

# *HAWKINS ELECTRICAL GUIDE · N<sup>o</sup> 10*

*WITH QUESTIONS ANSWERS AND ILLUSTRATIONS*

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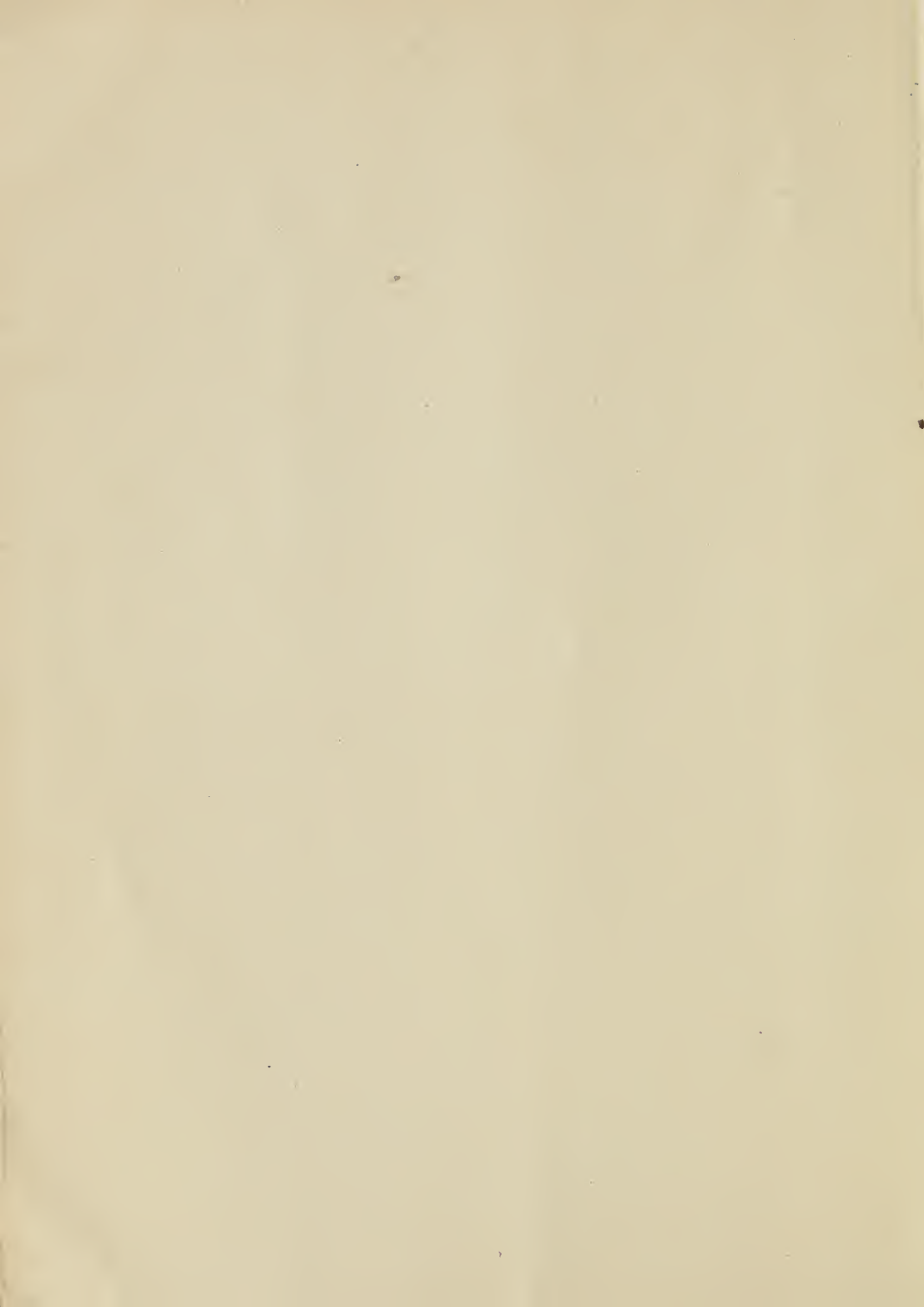


IN MEMORY OF


Milton Marshall



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**HAWKINS**  
**ELECTRICAL GUIDE**  
**NUMBER**  
**TEN**



**QUESTIONS**  
**ANSWERS**  
**&**  
**ILLUSTRATIONS**

A PROGRESSIVE COURSE OF STUDY  
FOR ENGINEERS, ELECTRICIANS, STUDENTS  
AND THOSE DESIRING TO ACQUIRE A  
WORKING KNOWLEDGE OF

**ELECTRICITY AND ITS APPLICATIONS**

A PRACTICAL TREATISE

by

**HAWKINS AND STAFF**



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## X RAYS - - - - - 3,227 to 3,242

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## CHAPTER LXXIV

## MOTION PICTURES

The subject of motion pictures may be included with propriety in a work on electricity because of the electric arc generally used for illumination and the auxiliary apparatus necessary for the proper working of the arc; in some installations the generating machinery being included, comprising an isolated plant.

While arc lighting has been treated at considerable length in the chapter on electric lighting, the special adaptation of the arc for moving picture machines is best explained in a separate chapter. For completeness, the subject of motion pictures is treated at length with respect both to its electrical and non-electrical features. With this in view, a comprehensive explanation of motion pictures is naturally given in the order of the outline below which is followed in part.

- |                            |   |
|----------------------------|---|
| 1. Optics;                 | 9. Projection;                              |
| 2. The film;               | 10. Reproducing the pictures on the screen; |
| 3. Motion picture cameras; | 11. Stage effects;                          |
| 4. Taking the pictures;    | 12. Motion picture theatres;                |
| 5. Developing;             | 13. Theatre lighting;                       |
| 6. The electric arc;       | 14. Installation;                           |
| 7. Auxiliary apparatus;    | 15. Operation;                              |
| 8. Motion picture machine; | 16. Care and repair.                        |

**Optics.**—By definition, *that part of physics which deals with the property of light is known as optics.*

### Ques. What is light?

Ans. Various hypotheses have been made, the most important of which are the emission or corpuscular theory, and the undulatory or wave theory.

**The emission theory** assumes that luminous bodies emit, in all directions, an imponderable substance which consists of molecules of an extreme degree of tenuity. These are propagated in right lines with an almost infinite velocity. Penetrating into the eye, they act on the retina and produce a sensation which is called *vision*.

**The undulatory theory** assumes that all bodies, as well as the celestial spaces are filled with an extremely subtle elastic medium,

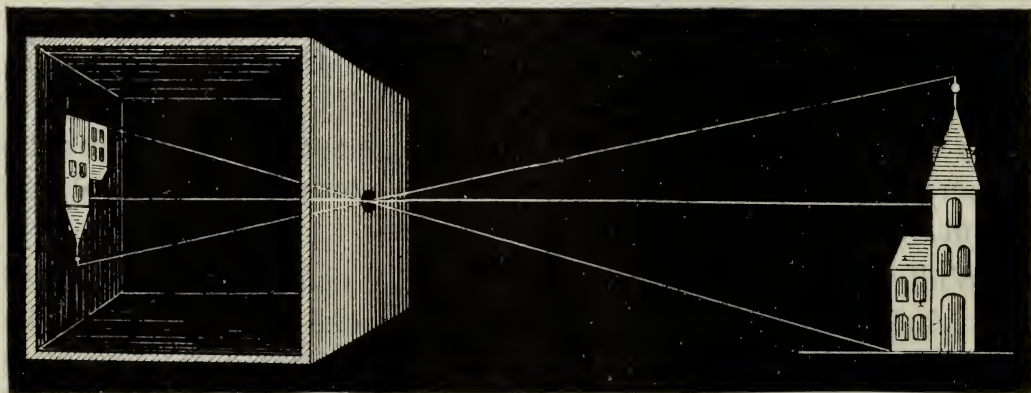


FIG. 3,762.—Images produced by small apertures showing the crossing of luminous rays at the aperture causing inversion of the image.

called the luminiferous ether, the luminosity of a body being due to an infinitely rapid vibratory motion of its molecules, which, when communicated to the ether, is propagated in all directions in the form of spherical waves, and this vibratory motion, being thus transmitted to the retina, produces the sensation called *vision*.

### Ques. What is an image?

Ans. An image is the appearance of an object at a place where no object exists.

**Ques. What is the difference between a real and a virtual image?**

Ans. A real image is formed when the rays *actually* meet; a virtual image is formed when the rays only *appear* to meet.



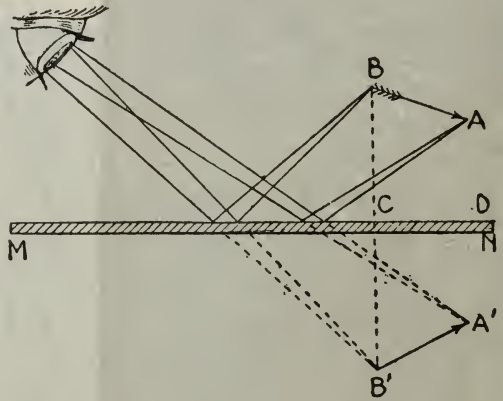
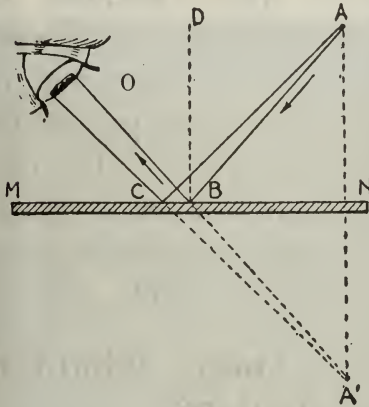
**Ques. What is a mirror?**

**Ans.** A polished surface which reflects objects placed before it.

According to their shape, mirrors are called plane, concave, convex, spherical, parabolic, conical, etc.

**Ques. What kind of image is seen in a plane mirror?**

**Ans.** A virtual image.

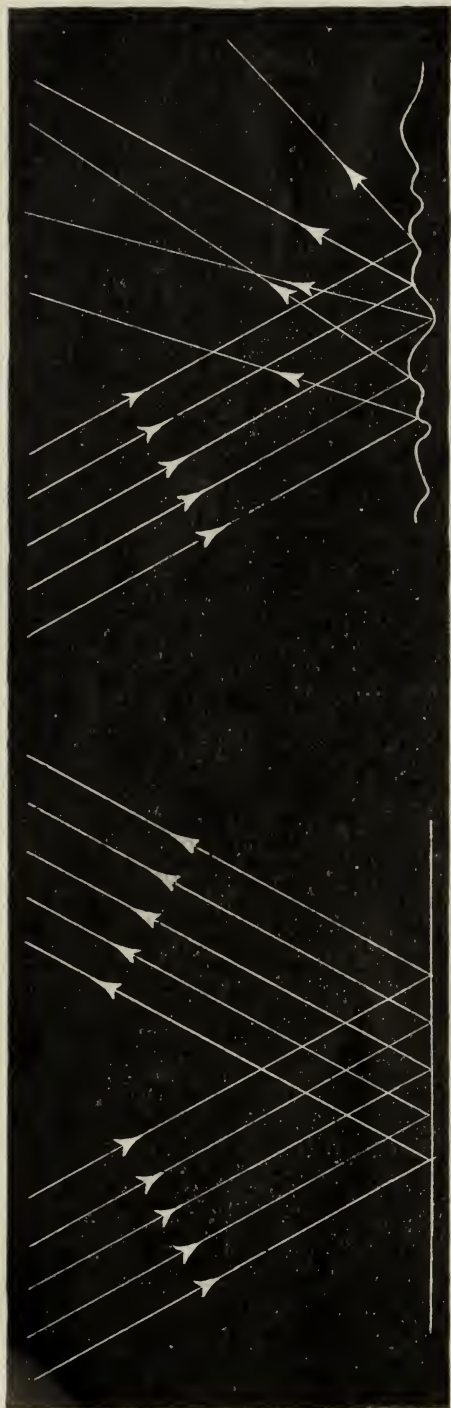


**FIGS. 3,763 and 3,764.**—Formation of images by plane mirrors. The determination of the position and size of image resolves itself into investigating the images of a series of point. **CASE I.** *Single point A placed in front of a plane mirror*, as in fig. 3,763. Any ray AB, incident from this point on the mirror is reflected in the direction BO, making the angle of reflection DBO equal to the angle of incidence DBA. If a perpendicular AN, be let fall from the point A over the mirror, and if the ray OB, be prolonged below the mirror until it meets this perpendicular in the point A', two triangles are formed, ABN and BNA', which are equal, for they have the side BN common to both, and the angles ANB, ABN, equal to the angles A'NB, A'BN; for the angles ANB and A'NB are right angles, and the angles ABN and A'BN are each equal to the angle OBM. From the equality of these triangles, it follows that A'N is equal to AN; that is, that any ray AB, takes such a direction after being reflected, that its prolongation below the mirror cuts the perpendicular AA' in the point A', which is at the same distance from the mirror as the point A. This applies also to the case of any other ray from the point A, as AC. It follows, that all rays from the point A, reflected from the mirror, follow after reflection, the same direction as if they had all proceeded from the point A'. The eye is deceived, and sees the point A at A', as if it were really situated at A'. Hence, in plane mirrors, *the image of any point is formed behind the mirror at a distance equal to that of the given point, and on the perpendicular let fall from this point on the mirror.* **CASE II:** *Object AB placed in front of the mirror*, as in fig. 3,764. The image of any object will be obtained by constructing the image of each of its points, or at least, of those which are sufficient to determine its form. Fig. 3,764 shows how the image A'B' of any object AB is formed.

**Ques. How are images produced by small apertures?**

**Ans.** When luminous rays, which pass through a small aperture into a dark chamber, are received upon a screen, they form





**Figs. 3,765 and 3,766.**—Reflection from polished and unpolished surfaces. The difference between a smooth (polished) and a rough (unpolished) reflecting surface is here greatly exaggerated. In both cases the law of reflection for each ray of light is precisely the same, that is, the *angle of incidence is equal to the angle of reflection*. In the first case all portions of the reflecting surface are parallel to one another, and therefore reflect in the same direction all the rays which fall upon them from a given direction; in the second case, the elements of the surface are turned in a great variety of way and hence the reflected rays pass off in every direction. Even the smoothest surfaces which can be made diffuse light to a slight extent.

images of external objects as shown in fig. 3,762.

**Ques.** Why are these images inverted?

**Ans.** Because the luminous rays proceeding from external objects, and penetrating into the chamber, cross one another in passing the aperture as shown in fig. 3,762.

**Ques.** What is reflection?

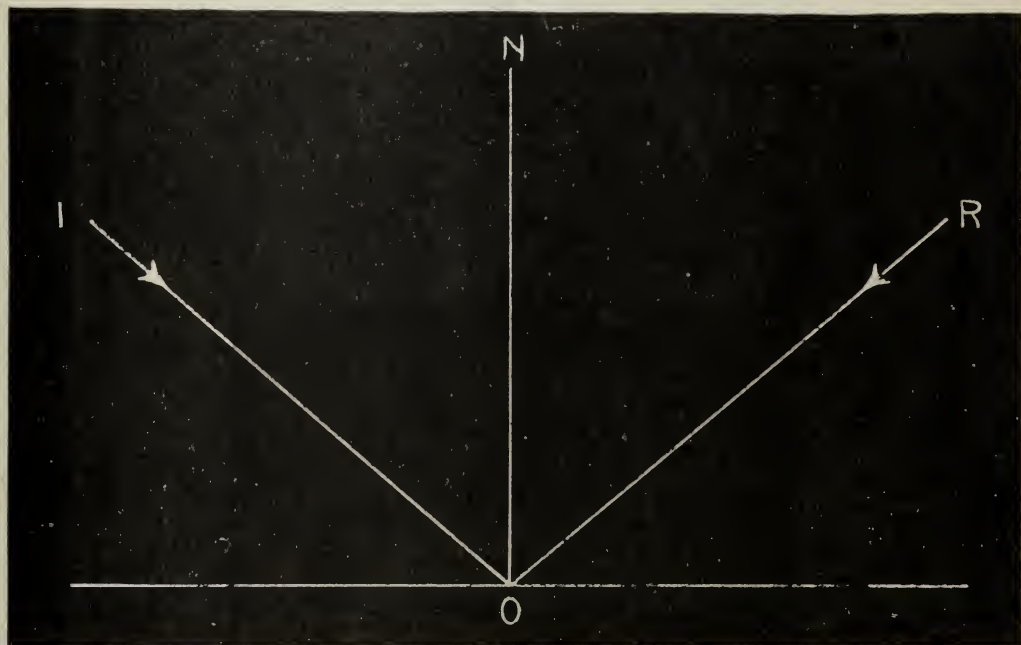
**Ans.** The change of direction experienced by a ray of light, or of other radiant energy, when it strikes a surface and is thrown back or reflected, as shown in fig. 3,767.

**Laws of Reflection.**—When a ray of light meets a polished surface, it is reflected according to the two following laws:

1. The angle of reflection is equal to the angle of incidence.
2. The incident and the reflected rays are both in the same plane which is perpendicular to the reflecting surface.

**Ques.** Describe a spherical mirror.

**Ans.** If a segment were cut from a hollow sphere and the surfaces were silvered or polished, each side of the segment would be a spherical mirror.



**FIG. 3,767.**—Angles of incidence and reflection. **LAW:** *the angle of reflection is equal to the angle of incidence.* The ray  $IO$  is called the incident ray;  $OR$ , reflected ray; angle  $ION$ , angle of incidence; angle  $NOR$ , angle of reflection;  $NO$ , normal or perpendicular to the reflecting surface.

The inner side is a *concave* spherical mirror, and the outer side, a *convex* spherical mirror.

**Ques.** What is the focus of a curved mirror?

**Ans.** A point where the reflected rays meet or tend to meet if produced either backward or forward.

There is a real or principal focus, a virtual focus, and conjugate foci. The principal and the conjugate foci are always on the same

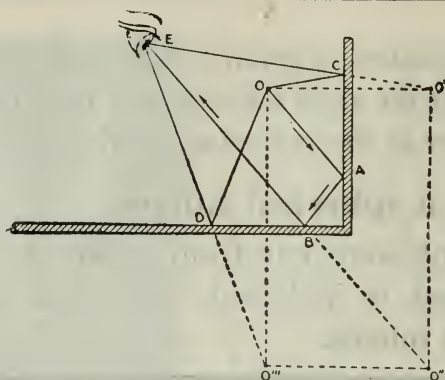


FIG. 3,768.—Multi-image formed by two mirrors. When an object is placed between two plane mirrors, which form an angle with each other, either right or acute, images of the object are formed, the number of which increases with the inclination of the mirrors. If they be at right angles to each other, three images are seen, arranged as represented in the figure. The rays OC and OD from the point O, after a single reflection, give the one, an image  $O'$ , and the other an image  $O''$ , while the ray OA, which has undergone two reflections at A and B, gives the third image  $O'''$ . When the angle of the mirror is  $60^\circ$ , five images are produced, and seven if it be  $45^\circ$ . The number of image continues to increase in proportion as the angle diminishes, and when it is zero (mirrors parallel), the number of image is infinite. *In general*, if two mirrors be inclined to each other, the number of image they produce is equal to the number of times the angle between them is contained in  $360$ .

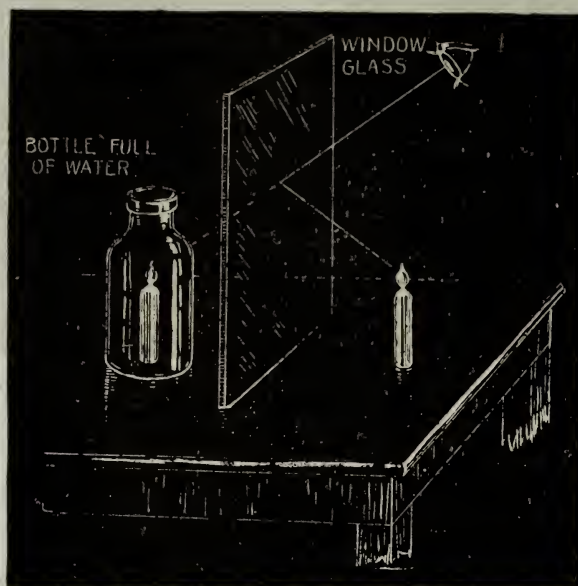


FIG. 3,769.—Position of image in a plain mirror. Let a candle be placed exactly as far in front of a pane of window glass as a bottle full of water is behind it, both objects being on a perpendicular drawn through the glass. The candle will appear to be burning inside the water. This experiment explains a large number of familiar optical illusions, such as "the figure suspended in mid-air," "bust of person without trunk," "stage ghost," etc. In the last case the illusion is produced by causing the audience to look at the actors obliquely through a sheet of very clear plate glass, the edges of which are concealed by draperies. Images of strongly illuminated figures at one side appear to the audience to be in the midst of the actors.



side of the mirror as the luminous point, while the virtual focus is always on the other side of the mirror. The distinction between these various foci is illustrated in the accompanying cuts.

### Ques. What is a parabolic mirror?

Ans. A concave mirror whose surface is generated by the revolution of the arc of a parabola AC about its axis AB as in fig. 3,770.

### Ques. What is avoided by the use of parabolic mirrors?

Ans. Spherical aberration.

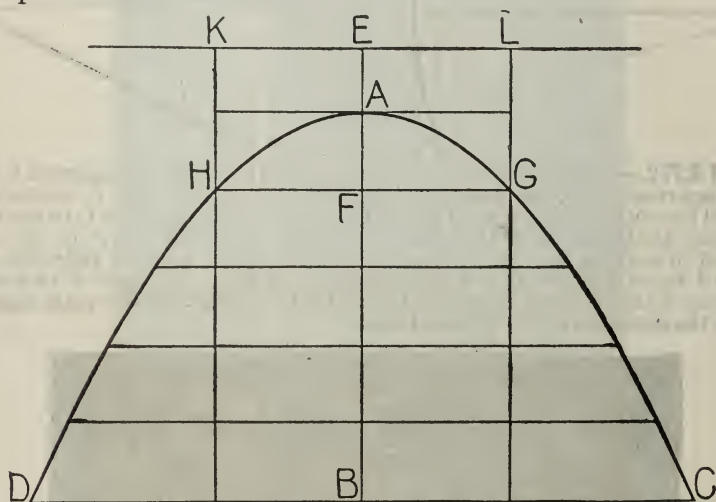


FIG. 3,770.—The parabola. A parabola DAC is a curve such that every point in the curve is equally distant from the directrix KL and the focus F. The focus lies in the axis AB, drawn from the vertex or head of the curve A, so as to divide the figure into two equal parts. The vertex A, is equidistant from the directrix and the focus or  $AE = AF$ . Any line parallel to the axis is a diameter. A straight line, as HG or DC, drawn across the figure at right angles to the axis is a double ordinate, and either half of it is an ordinate. The ordinate to the axis HFG drawn through the focus, is called the parameter of the axis. A segment of the axis, reckoned from the vertex, is an abscissa of the axis, and it is an abscissa of the ordinate drawn from the base of the abscissa. Thus AB is an abscissa of the ordinate BC. Abscissæ of a parabola are as the square of their ordinates.

### Ques. What is refraction?

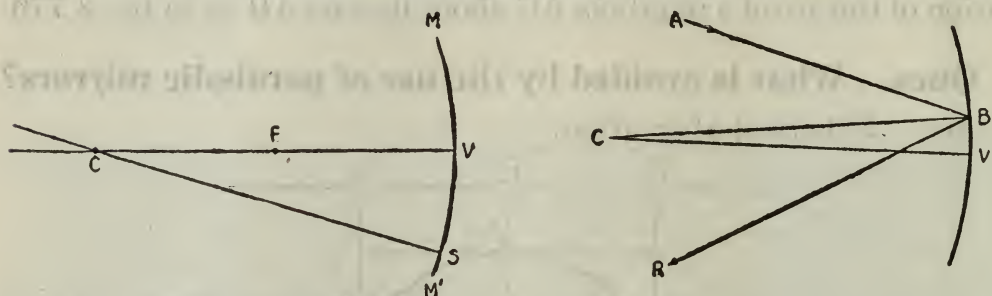
Ans. The change of direction which a ray of light undergoes upon entering obliquely a medium of different density from that through which it has been passing, as in fig. 3,773.

If the incident ray be perpendicular to the surface separating the two media, it is not bent, but continues its course in a right line.

According as the refracted ray approaches or deviates from the normal, the second medium is said to be more or less *refracting*, or *refracting* than the first.

Mathematical analysis shows that the direction of refraction depends on the relative velocity of light in the two media.

**Ques.** Define the index of refraction, or refractive index.



FIGS. 3,771 and 3,772.—Concave spherical mirror; definitions. In the diagram V is the vertex; MM', the aperture; CV, the principal axis; CS, a secondary axis; C, center of curvature; F, principal focus (midway between V and C). Any line drawn from C to the mirror will be perpendicular to the mirror at that point. This line then will always be the normal which will be used in making the angle of incidence equal to the angle of reflection. Now in fig. 3,772, if AB be an incident ray of light, the angle ABC is the *angle of incidence*. To find the direction of the reflected ray draw BR so that the angle CBR equals angle ABC, then will BR be the direction of the reflected ray.

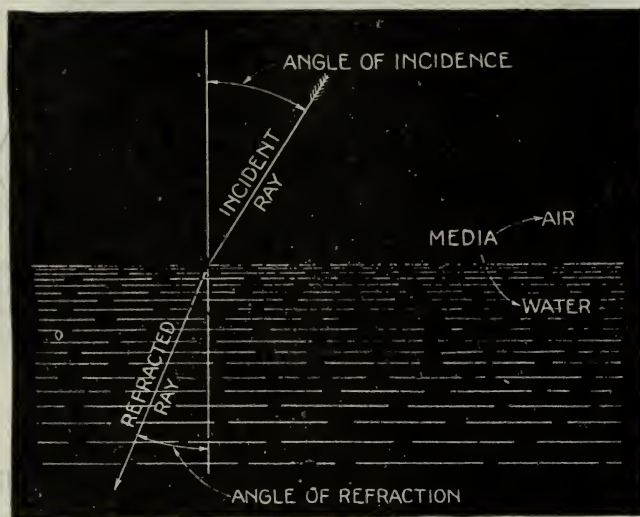


FIG. 3,773.—Diagram illustrating refraction definitions. All the light which falls on a refracting surface does not completely pass into it; one part is reflected and scattered, while the other penetrates into the medium. According to the *undulatory theory*, the more highly refracting media is that in which the velocity of propagation is least. In uncrystallized media, such as air, liquids, ordinary glass, the luminous ray is singly refracted; but in certain crystallized bodies, such as Iceland spar, selenite, etc., the incident ray gives rise to two refracted rays. The latter phenomenon is called *double refraction*.

Ans. It is the ratio between the sines of the incident and refracted angles.

It varies with the media, for instance from air to glass it is  $\frac{3}{2}$ ; from air to water,  $\frac{4}{3}$ .

Indices of a few common substances are as follows: alcohol 1.36; crown glass 1.53; turpentine 1.47; diamond 1.67; flint glass 2.47.



FIG. 3,774.—Experiment illustrating multi-image in ordinary mirror. Let the flame of a candle be observed very obliquely in an ordinary mirror. From four to ten images of the flame may be seen arranged in a row, as here shown. The second image of the series will be by far the most brilliant.

**Laws of Refraction.**—When a luminous ray is refracted in passing from one medium into another of different refractive power the following laws obtain:

1. *Light is refracted whenever it passes obliquely from one medium to another of different optical density;*
2. *The index of refraction for a given substance is a constant quantity whatever be the angle of incidence;*



3. The refracted ray lies in the plane of the incident ray and the normal;

4. Light rays are bent toward the normal when they enter a more refractive medium, and from the normal when they enter a less refractive medium.

**Ques. Define the critical angle.**

**Ans.** In fig. 3,775, let CD be a surface separating two transparent media, the lower one being the denser of the two (as air

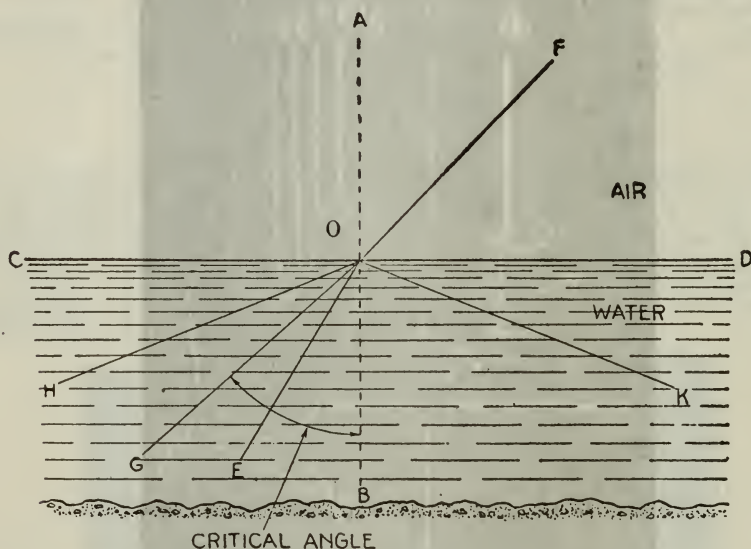


FIG.—3,775.—Diagram illustrating the **critical angle** or that angle between the incident ray and the perpendicular drawn to the surface in the medium of smaller velocity at the point at which total reflection begins to occur; the diagram is explained in the accompanying text,

and water). If a ray EO strike the surface it will be bent away from the normal AOB, along the line OF, in accordance with the law of refraction  $\sin AOF = \mu \sin EOB$ . If now the angle EOB be increased, AOF will go on increasing until  $\sin AOF = 1$ , and the refracted ray passes along OD; in this case the ray in the dense medium makes an angle BOG with the normal such

**NOTE.—Effect produced by refraction.** Bodies immersed in a medium more highly refracting than air appear nearer the surface of this medium, but they appear to be more distant if immersed in a less refracting medium. A stick plunged obliquely into water appears bent, the immersed part appearing raised. Owing to refraction stars are visible even when they are below the horizon.

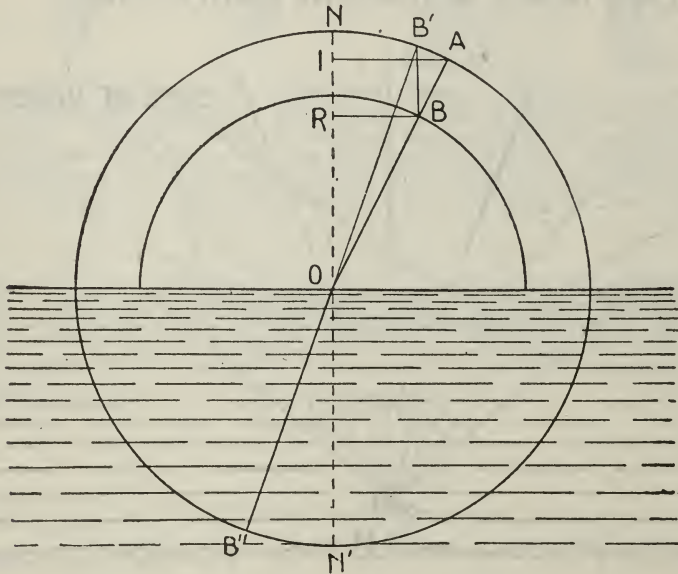


that  $\mu \sin \text{BOG} = 1$ , from which,  $\sin \text{BOG} = 1 \div \mu$ . This angle BOG is the *critical angle*.

The critical angle varies with the nature of the substance: thus, for water and air, it is about  $48.5^\circ$ ; for crown glass,  $42.5^\circ$ ; for flint glass,  $38.6^\circ$ ; for diamond,  $23.7^\circ$ .

**Ques.** What is total reflection?

**Ans.** When the angle of incidence is greater than the critical



**FIG 3,776.**—Construction of refracted ray. Let AO be a ray of light passing through air and entering water at O. The index is  $\frac{4}{3}$ . Draw two circles with centers at O and with radii whose lengths are as 4 : 3. Draw AI and BR perpendicular to the normal NN'. Since AO : BO = 4 : 3, then AI : BR = 4 : 3. Hence if AI be the sine of the angle of incidence, BR is the sine of the angle of refraction. If then, BB' be drawn parallel to the normal, and a straight ruler be placed on the points B' and O, the line OB', the refracted ray may be drawn.

angle, none of the light will emerge into the adjacent medium, but all will be reflected; this is called total reflection.

Total reflection can take place only when light traveling in any medium meets another medium in which the speed is greater.

**Ques.** How do external objects appear to an eye under water?

Ans. They appear to lie within a cone whose angle is  $97^\circ$ , as explained in fig. 3,777.

**Lenses.**—A lens may be defined as, *a piece of glass or other transparent substance with one or both sides curved.* Both sides may be curved, or one curved and the other flat.

The **object** of a lens is to **change** the direction of rays of light, and thus magnify objects, or otherwise modify vision.

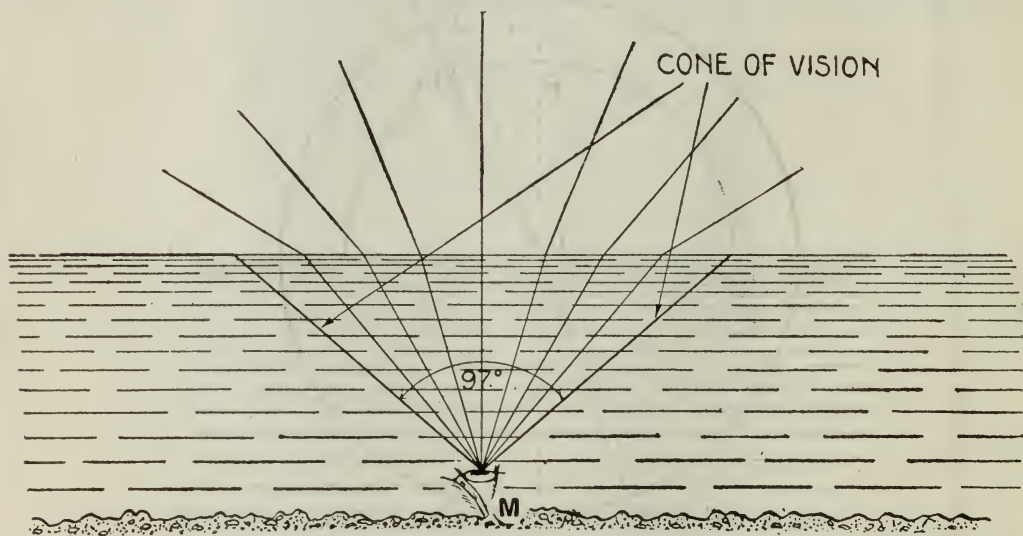


FIG. 3,777.—Appearance of external objects to an eye under water. Since the critical angle for water is  $48\frac{1}{2}^\circ$ , an eye located at M will see objects above the water as though located within a cone whose angle is  $2 \times 48\frac{1}{2}^\circ = 97^\circ$ . The reason for this is because if the eye look toward the surface at an angle greater than  $48\frac{1}{2}^\circ$  it can see nothing but the reflection from the bottom of the water.

There are various kinds of lens and they may be classed as:

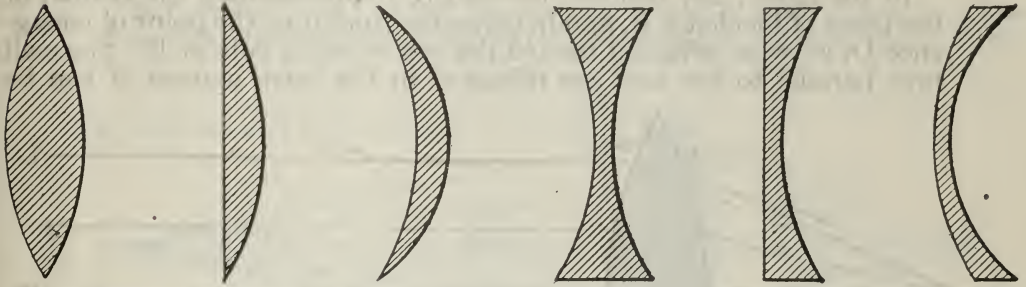
1. Convex.

- a. double convex;
- b. plano convex;
- c. concavo convex.

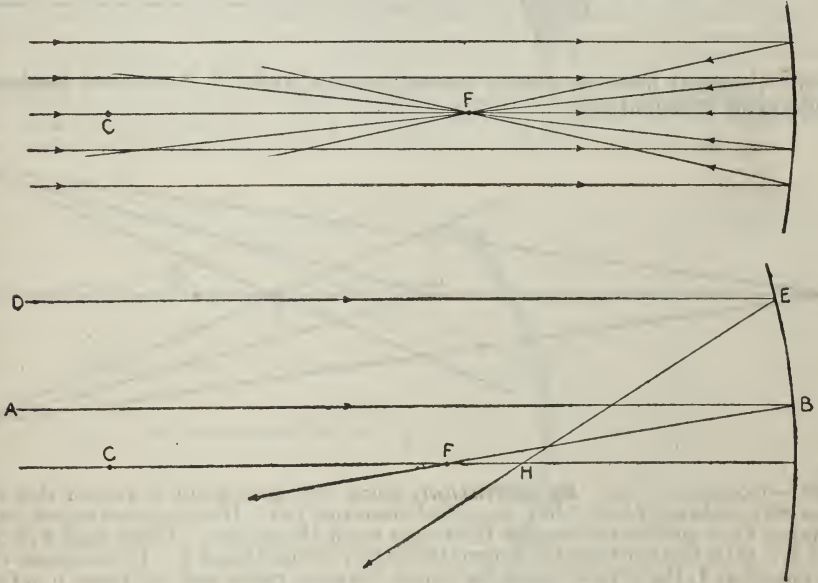
2. Concave.

- a. double concave;
- b. plano concave;
- c. convexo concave.

These various types of lens are illustrated in figs. 3,778 to 3,783, which give a better idea of the numerous combinations of curved and plane surface than is obtained by definition.



FIGS. 3,778 to 3,783.—Various lenses. *The first three* are thicker at the center than at the borders, and are called *converging*; *the second three*, which are thinner at the center are called *diverging*. In lenses whose two surfaces are spherical, the centers of these surfaces are called centers of curvature, and the right line which passes through these two centers is the principal axis. In a plano-concave or plano-convex lens, the principal axis is the perpendicular let fall from the center of curvature of the spherical face on the plane face.



FIGS. 3,784 and 3,785.—The principal focus. *By definition*, it is, that point where all the rays **parallel** to the principal axis meet after reflection, as, for instance, the rays from a source of light at an infinite distance from the mirror. The sun is so far distant that its rays are practically parallel. When they are reflected upon a concave mirror they are reflected to the principal focus *F*; forming a point of intense light and heat.

**Foci in Double Convex Lenses.**—*The focus of a lens is the point where the refracted rays, or their prolongations meet.* Double convex lenses have both real and virtual foci, like concave mirrors.



**Principal Foci.**—Fig. 3,786 shows the case in which the luminous rays which fall on the lens are parallel to its principal axis.

In the figure, any incident ray as LB, in approaching the normal of the point of incidence B, and in diverging from it at the point of emergence D, is twice refracted toward the axis which it cuts at F. Since all rays parallel to the axis are refracted in the same manner it can be

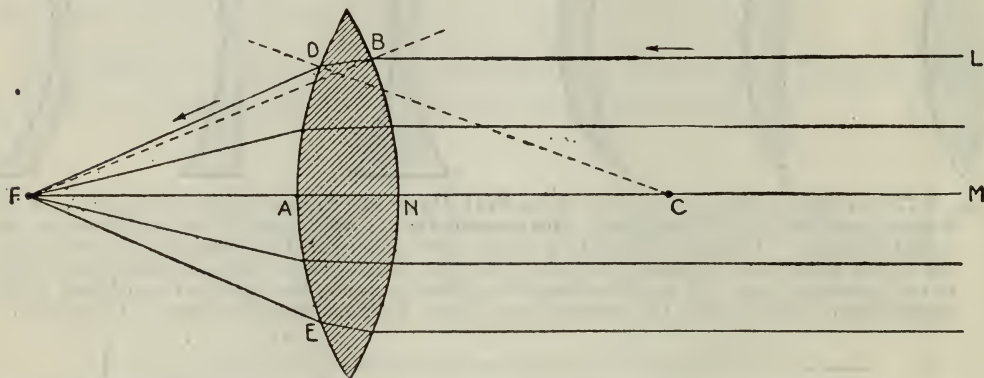


FIG. 3,786.—Principal focus in double convex lens. CASE I: Rays from luminous source parallel to the principal axis.

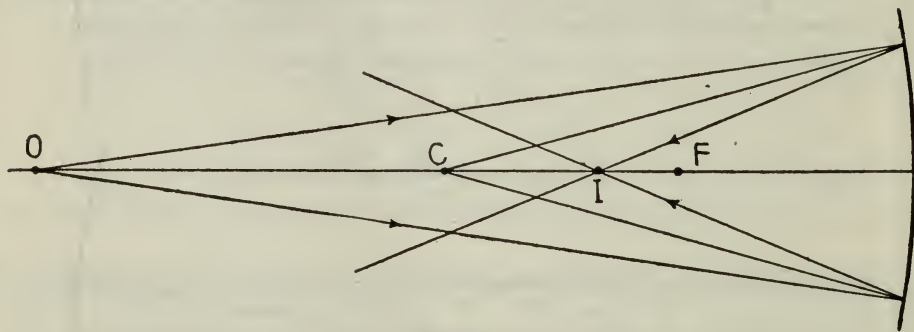


FIG. 3,787.—Conjugate foci. **By definition**, when two points are so related that object and image may exchange places, they are called *conjugate foci*. If a luminous object be placed at the point O, it projects divergent light rays upon the mirror. These rays will focus at a point I, a little further from the mirror than the principal focus F. If the source of light be now placed at I, the rays will pass back over the same paths and will come to a focus at O; the points I and O thus related to each other are called *conjugate foci*. Concave mirrors make divergent rays less divergent, parallel or convergent; parallel rays, convergent; convergent rays more convergent.

shown by calculation that they all pass very nearly through the point F, so long as the arc DE does not exceed  $10^\circ$  to  $12^\circ$ . This point is the principal focus and the distance FA, the principal focal distance.

Fig. 3,788 shows the case in which the luminous source is outside the principal focus, but so near that all incident rays form a divergent pencil.

**Virtual Foci.**—A double convex lens has a *virtual focus* when the luminous object is placed between the lens and the principal focus, as shown in fig. 3,790.

In this case the incident rays make with the normal greater angles than those made with the rays FI from the principal focus. Accordingly,

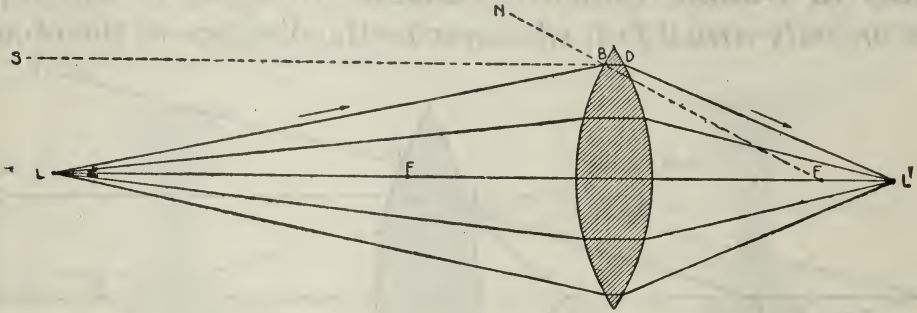


FIG. 3,788.—**Principal focus** in double curve lenses. CASE II: *Divergent rays from luminous source.* In the figure the luminous source being at L, by comparing the path of a diverging ray LB, with that of a ray, SB, parallel to the axis, the former is found to make with the normal, an angle LBN, greater than the angle SBN, hence, after traversing the lens, the ray cuts the axis at a point L', which is more distant than the principal focus F. As all rays from the point L intersect approximately in the same point L', this latter is the conjugate focus of the point L. This term has the same meaning here as in the case of mirrors, and expresses the relation existing between the two points L and L', which is of such a nature that, if the luminous point be moved to L', the focus passes to L.

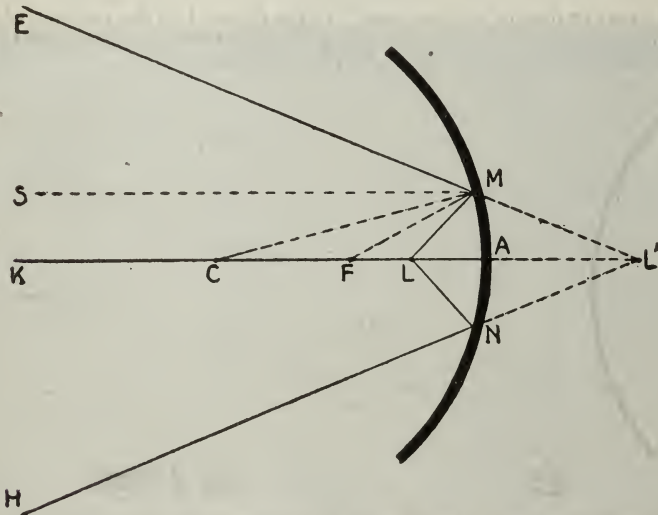


FIG. 3,789.—**The virtual focus.** If a source of light be placed at L, between the principal focus F, and the mirror, any ray LM emitted from L, makes with the normal CM, an angle of incidence LMC, greater than FMC. The angle of reflection must be greater than CMS, and therefore the reflected ray ME diverges from the axis AK. This is also the case with all rays from the point L, and hence these rays do not intersect, thus forming no conjugate focus. If they be regarded as being prolonged on the other side of the mirror, their prolongations will intersect in a point L', on the axis, giving the same effect to the eye as though the rays were emitted from the point L', this point being called the *virtual focus*.

when the former rays emerge, they move farther from the axis than the latter, and form a diverging pencil HK, GM. These rays cannot produce a real focus, but their prolongations intersect in some point  $L'$ , on the axis, and this point is the virtual focus of the point L.

**Foci in Double Concave Lenses.**—In lenses of this form, *there are only virtual foci*, whatever be the distance of the object.

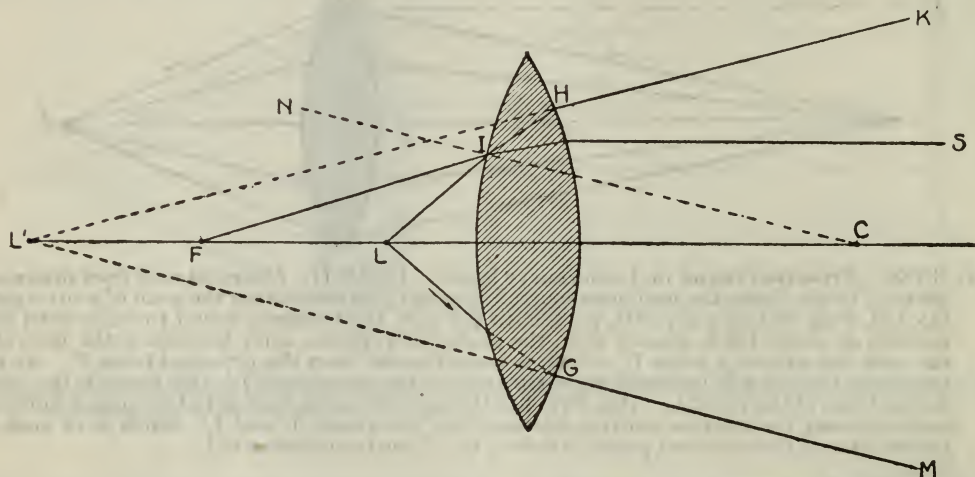


FIG. 3,790.—Virtual focus in double convex lens. In the figure,  $L$  is the position of the luminous source between the principal focus and the lens;  $F$  is the principal focus, and  $L'$ , the virtual focus corresponding to the position  $L$  of the luminous source.

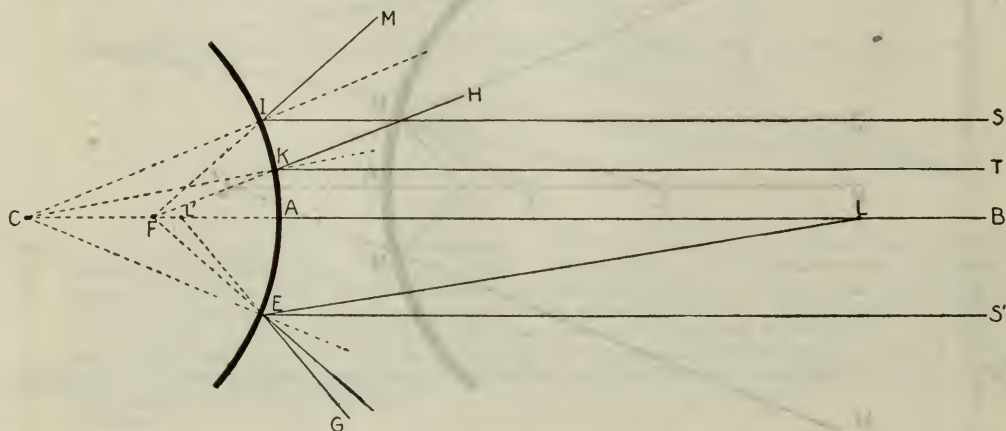


FIG. 3,791.—Foci of convex mirrors. This type of mirror has only virtual foci. Let  $SI$ , and  $TK$  be rays parallel to the principal axis of a convex mirror. These rays, after reflection, take the diverging directions  $IM$ ,  $KH$ , which, when continued, meet at a point  $F$ , which is the *principal virtual focus*. In the triangle  $CKF$ , it may be shown, in the same manner as with concave mirrors, that the point  $F$  is approximately the center of the radius of curvature  $CA$ . If the incident luminous rays, instead of being parallel to the axis, proceed from a point  $L$ , situated on the axis at a finite distance, a virtual focus will be formed at a point  $L'$ , between the principal virtual focus and the mirror.



In fig. 3,792 let  $SS'$  be any pencil of ray parallel to the axis. Any ray  $SI$  is refracted at the point of incidence  $I$ , and approaches the normal  $CI$ . At the point of emergence it is also refracted, but diverges from the normal  $GC'$ , so that it is twice refracted in a direction which moves it from the axis  $CC'$ . Since the same conditions obtain for every other ray,  $S'KMN$ , it follows that the rays, after traversing the lens, form a diverging pencil,  $GHMN$ . Hence, there is no real focus, but the prolongations of these rays cut one another in a point  $F$ , which is the principal virtual focus.

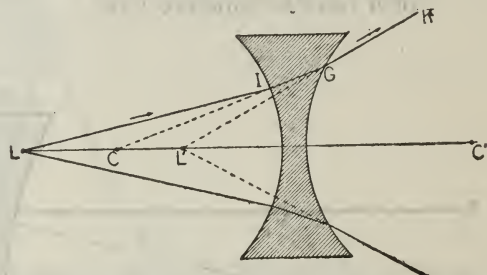
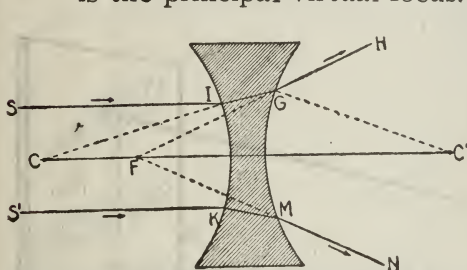


FIG. 3,792.—Virtual focus in double concave lens. CASE I: *Parallel incident rays.*

FIG. 3,793.—Virtual focus in double concave lens. CASE II: *Divergent incident rays.* In this case where the rays radiate from a point  $L$  on the axis, it is found by the same construction that a virtual focus is formed at  $L'$ , which is between the principal focus and the lens.

**Experimental Determination of the Principal Focus of Lenses.**—To determine the principal focus of a convex lens, it

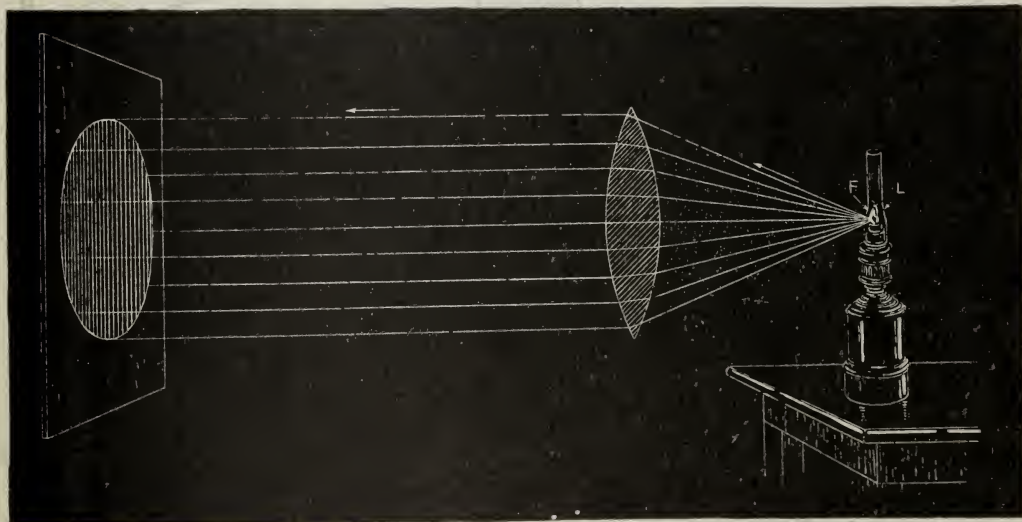


FIG. 3,794.—Effect of placing luminous source at the principal focus of a double convex lens. As the point of light comes near the lens, the convergence of the emergent rays decreases, and the conjugate focus  $L'$  (fig. 3,788) becomes more distant. When the source of light  $L$  coincides with the principal focus  $F$ , as shown above, the conjugate focus is at an infinite distance, that is to say, the emergent rays are parallel. When this condition obtains, the intensity of light decreases slowly, thus, a small lamp can illuminate considerable distance.



may be exposed to the sun's rays so that they are "parallel" to its axis. The emergent pencil being received on a ground glass screen, the point to which the rays converge or the principal focus is readily seen.

Fig. 3,795 shows the experimental determination of the principal focus of a double concave lens.

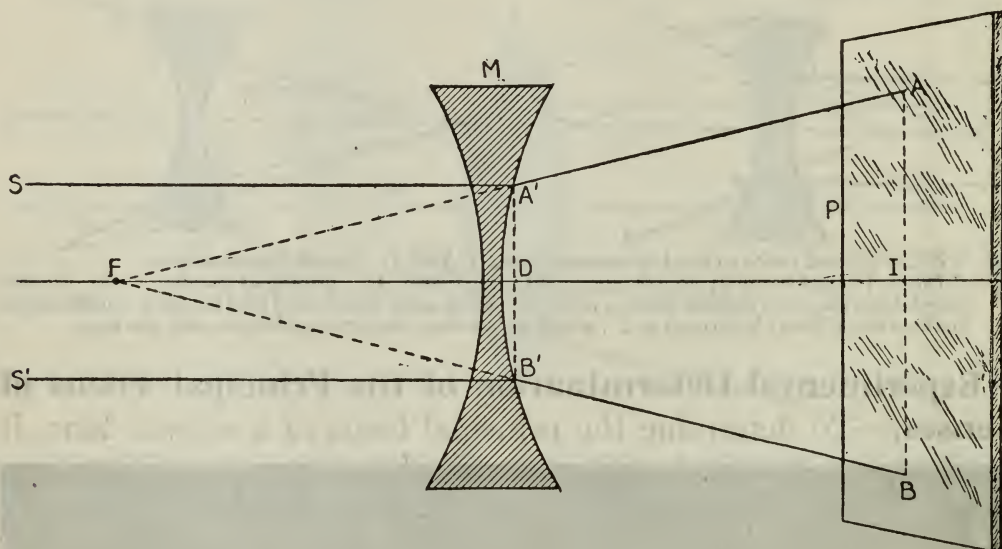


FIG. 3,795.—Experimental determination of the principal focus of a double concave lens. The face AB is covered with an opaque substance, such as lamp black, two small apertures, A and B, being left in the same principal section and at an equal distance from the axis. A pencil of sunlight is then received on the other face, and the screen P, which receives the emergent rays, is moved toward or away from the lens until A and B, the spots of light from the small apertures, are distant from each other by twice  $A'B'$ . The distance DI is then equal to the focal distance FD, because the triangles  $FA'B'$  and  $FAB$  are similar.

**Optical Center; Secondary Axis.**—In or near every lens there is a point called the optical center, which is located on the axis, and which has the property that *any luminous ray passing through it experiences no angular deviation*, that is to say, the emergent ray is parallel to the incident ray. The existence of this point is demonstrated as in fig. 3,796.

By definition, a secondary axis is *any right line* (as  $PP'$ , fig. 3,797), *which passes through the optical center of a lens without passing through the centers of curvature*. From this property of the optical center, every

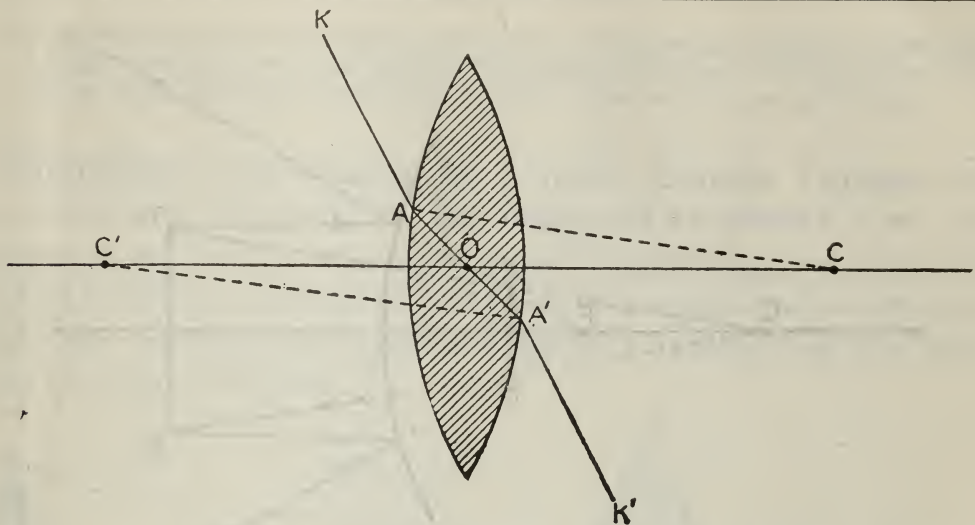


FIG. 3,796.—**Optical center.** Let two parallel radii of curvature  $CA$  and  $C'A'$  be drawn to the two surfaces of a double convex lens. Since the two plane elements of the lens  $A$  and  $A'$  are parallel, as being perpendicular to two parallel right lines, it is evident that the refracted ray  $AA'$  is propagated in a medium with parallel faces. Hence a ray  $KA$ , which reaches  $A$  at such an inclination that after refraction it takes the direction  $AA'$ , will emerge parallel to its first direction. The point  $O$  at which the right line cuts the axis is therefore the optical center. The position of this point may be determined from the case in which the curvature of the two faces is the same, which is the usual condition, by observing that the triangles  $COA$  and  $C'O'A'$  are equal, and therefore that  $OC = OC'$ , which gives the point  $O$ . If the curvatures be unequal, the triangles  $COA$  and  $C'O'A'$  are similar, and either  $CO$  or  $C'O$  may be found, and therefore also the point  $O$ . In double concave or concavo-convex lenses, the optical center may be determined by the same construction. In lenses with a plane face, this point is at the intersection of the axis by the curved face.

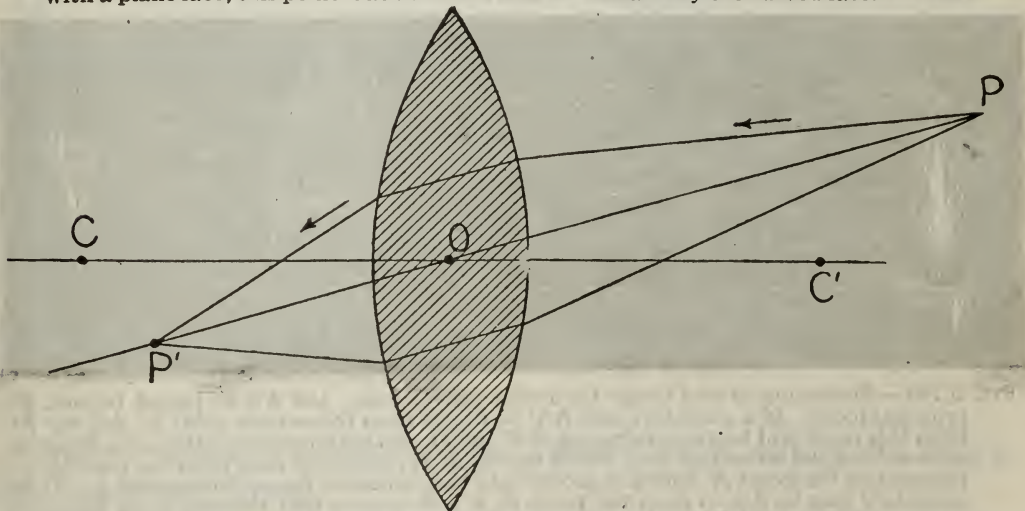


FIG. 3,797.—**Secondary axis.** This is any right line passing through the optical center, but not through the centers of curvature. Rays emitted from a point  $P$  on the secondary axis  $PP'$  nearly converge to a center point  $P'$  on the axis  $PP'$ , and according as the distance from the point  $P$  to the lens is greater or less than the principal focal distance, the focus thus formed will be conjugate or virtual. The formation of image is in accordance with this principle.

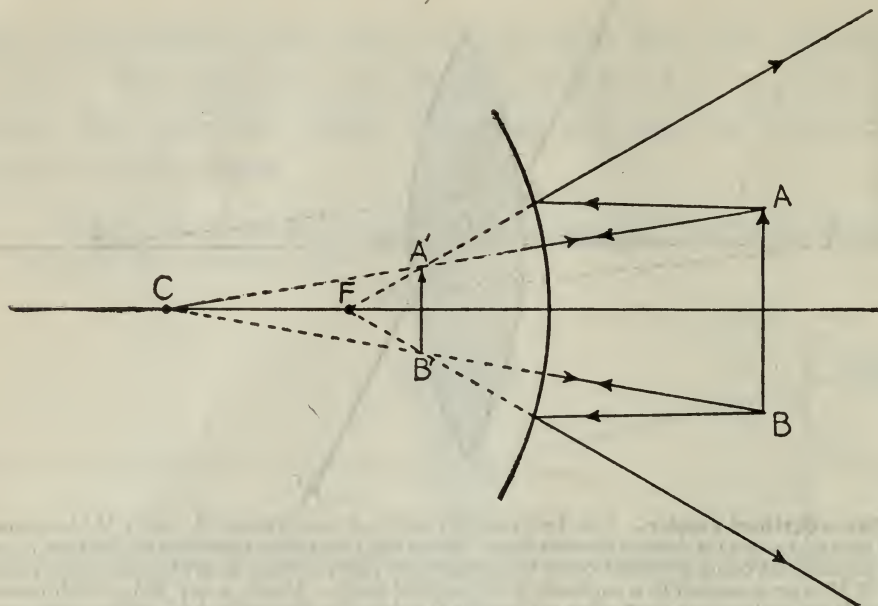


FIG. 3,789.—Image in convex mirror. Let  $AB$  be the object; draw two lines from  $A$ , and two from  $B$ , to the convex side of the mirror. Draw lines from  $C$  through these points. These lines are the normals. Construct the angles of reflection and extend the rays until they meet. It is found in this case that the image  $A'B'$  is virtual, erect, smaller than the object, and located on the opposite side of the mirror. *The effect of a convex mirror is to make convergent rays less convergent, parallel, or divergent; parallel rays, divergent, and divergent rays, more divergent. In general, the concave mirror tends to collect the rays, and the convex mirror tends to scatter them.*

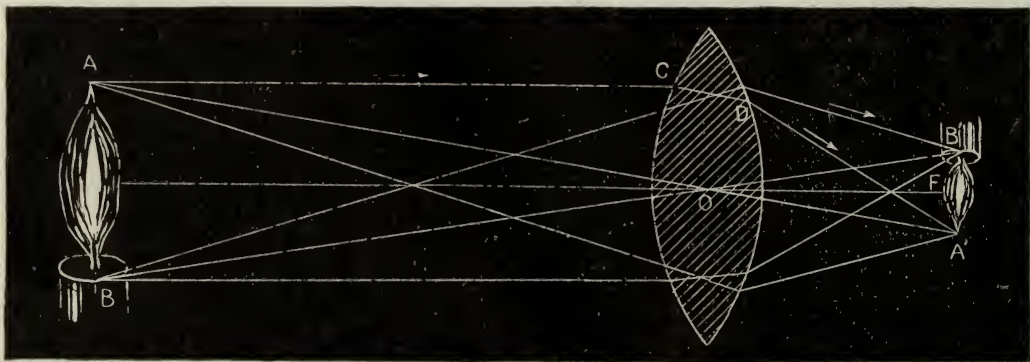


FIG. 3,799.—Formation of real image by double convex lens. Let  $AB$  be placed beyond the principal focus. If a secondary axis  $AA'$  be drawn from the outside point  $A$ , any ray  $AC$  from this point will be twice refracted at  $C$  and  $D$ , and both turning in the same direction, approaching the secondary axis, which it cuts at  $A'$ , the other rays from the point  $A$  will intersect in the point  $A'$  which is accordingly the conjugate focus of the point  $A$ . If the secondary axis be drawn from the point  $B$ , it will be seen that the rays from this point intersect in the point  $B'$ , and as the points between  $A$  and  $B$  have their foci between  $A'$  and  $B'$ , a real and inverted image of  $AB$  will be formed at  $A'B'$ . To see this image it may be received on a white screen, on which it will be depicted, so the eye may be placed in the path of the rays emerging from it. Again, if  $A'B'$  were the luminous object, its image would be formed at  $AB$ .



secondary axis represents a luminous rectilinear ray passing from this point because, from the slight thickness of the lens, it may be assumed that rays passing through the optical center are on a right line.

**Formation of Images by Double Convex Lenses.**—In lenses as well as in mirrors, **the image of an object is the collection of the foci of its several point.** Accordingly images furnished by lenses are real or virtual in the same case as the foci, and their construction resolves itself into determining the position of a series of point.

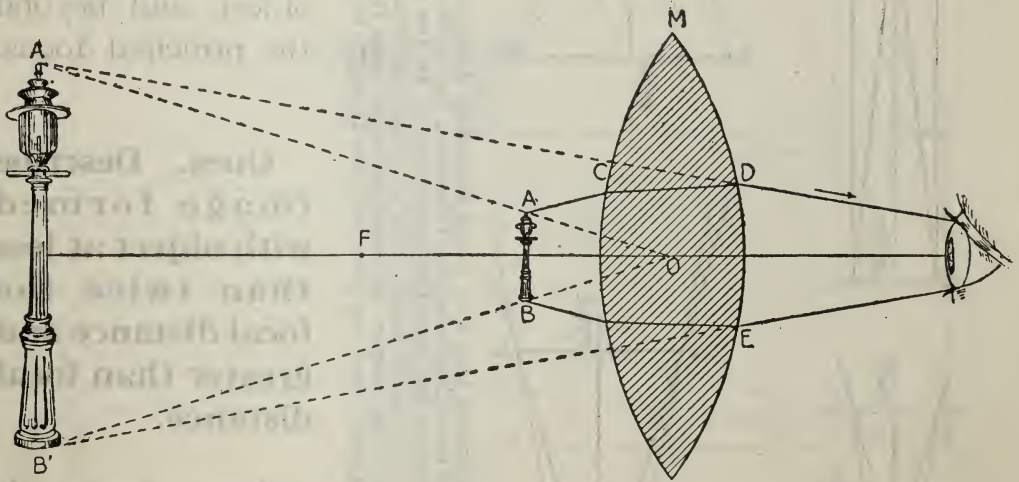


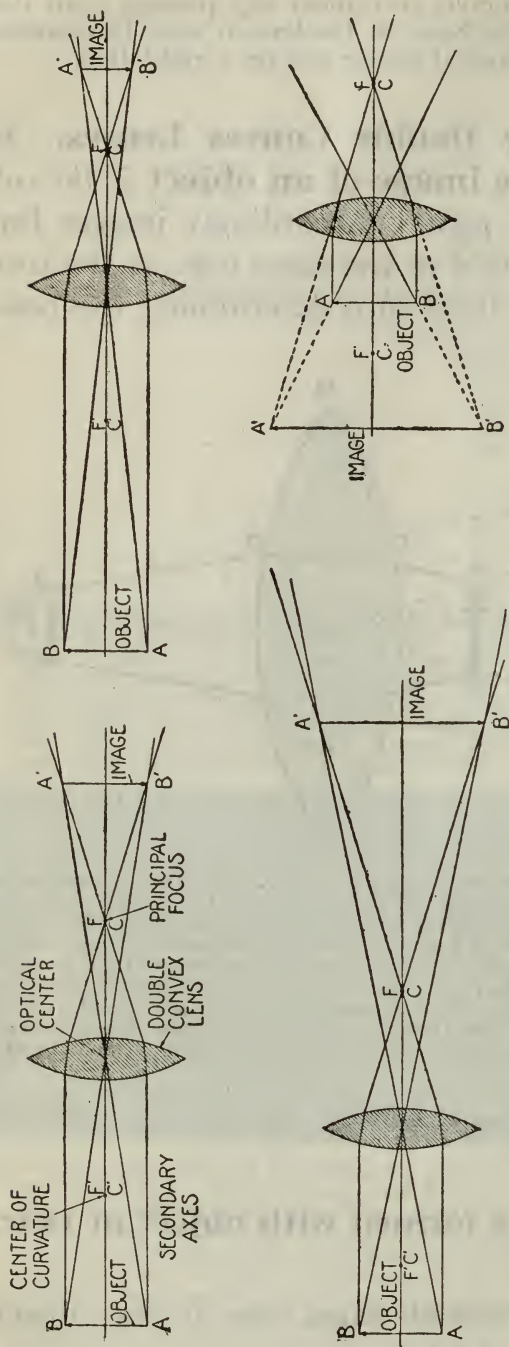
FIG. 3,800.—Formation of virtual image by double convex lens; object AB, placed between the lens and its principal focus. If a secondary axis  $OA'$  be drawn from the point A, every ray AC, after having been twice refracted, diverges from this axis on emerging, since the point A is at a less distance than the principal focal distance, this ray, continued in an opposite direction, will cut the axis  $OA'$  in the point  $A'$ , which is the virtual focus of the point A. Tracing the secondary axis of the point B, it will be found in the same manner, that the virtual focus of this point is formed at  $B'$ . There is, therefore, an image of AB at  $A'B'$ . This is a virtual image; it is erect and larger than the object. The magnifying power is greater in proportion as the lens is more convex, and the object nearer the principal focus.

Fig. 3,799 shows the formation of a real image, and fig. 3,800, the formation of a virtual image.

**Ques.** Describe the image formed with object at twice the focal distance.

**Ans.** The image is real, inverted, same size as the object, and at the same distance from the lens.





FIGS. 3,801 to 3,804.—Images formed by double convex lens with object at various distances from the lens. Fig. 3,801, object at twice the focal distance; fig. 3,802, object more than twice focal distance; fig. 3,803, object at a distance less than twice the focal distance; fig. 3,804, object at a distance less than the focal distance. **In the construction** of these figures, two rays from any point are all that are needed to locate the image. The two most convenient are, one parallel to the principal axis and the other through the optical center. The former will, after refraction, pass through the principal focus, which in cases here considered is at the center of curvature, and the latter will pass through the lens without change of direction.

**Ques.** Describe image formed with object at more than twice focal distance.

**Ans.** The image is real, inverted, smaller than the object, and beyond the principal focus.

**Ques.** Describe image formed with object at less than twice the focal distance and greater than focal distance.

**Ans.** Image is real, inverted, larger than the object, and more than twice the focal distance from the lens.

When the object is at the principal focus, the rays after passing through the lens will be parallel, and no image will be formed.

**Ques.** Describe image formed when the object is between the principal focus and the lens.

**Ans.** The image is virtual, erect and larger than the object.

In this case the rays are made less divergent but not convergent.

**Formation of Images by Double Concave Lenses.**—These lenses like convex mirrors give *only virtual images*, whatever be the distance of the object.

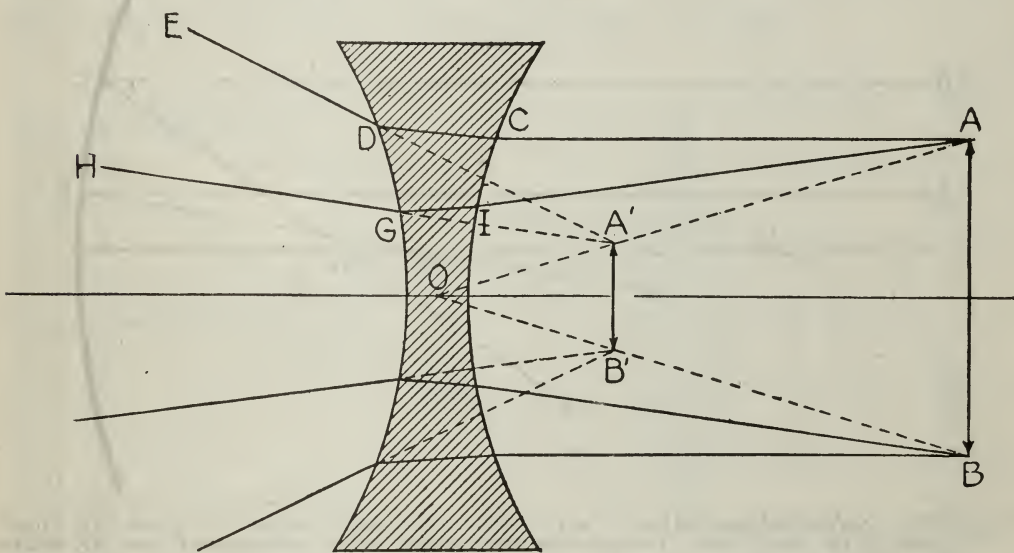


FIG. 3,805.—Formation of virtual image in double concave lens; no real image is formed with this type of lens. Let  $AB$  be an object placed in front of the lens. If the secondary axis  $AO$  be drawn from the point  $A$ , all rays  $AC, AI$ , etc., from this point are twice refracted in the same direction, diverging from the axis  $AO$ , so that the eye receiving the emergent rays  $DE$  and  $GH$ , supposes them to proceed from the point where their prolongations cut the secondary axis  $AO$  in the point  $A'$ . Similarly, drawing a secondary axis from the point  $B$ , the rays from this point form a pencil of divergent rays, the directions of which, prolonged, intersect in  $B'$ . Accordingly the eye sees at  $A'B'$ , a virtual image of  $AB$ , which is *always erect, and smaller than the object*.

**Ques.** How are rays affected by double concave lenses?

**Ans.** Diverging rays are always made more divergent.

**Ques.** Describe the image formed.

**Ans.** It is virtual, erect, and smaller than the object.

**Formulae Relating to Lenses.**—In all these lenses the relations between the distances of the image and object, principal focus, also radii of curvature, the refractive index, etc., may be expressed by a formula.

If O be distance of the object from the lens, I the distance of the image, and F, the principal focal distance, then

$$\frac{1}{O} + \frac{1}{I} = \frac{1}{F} \dots\dots\dots (1)$$

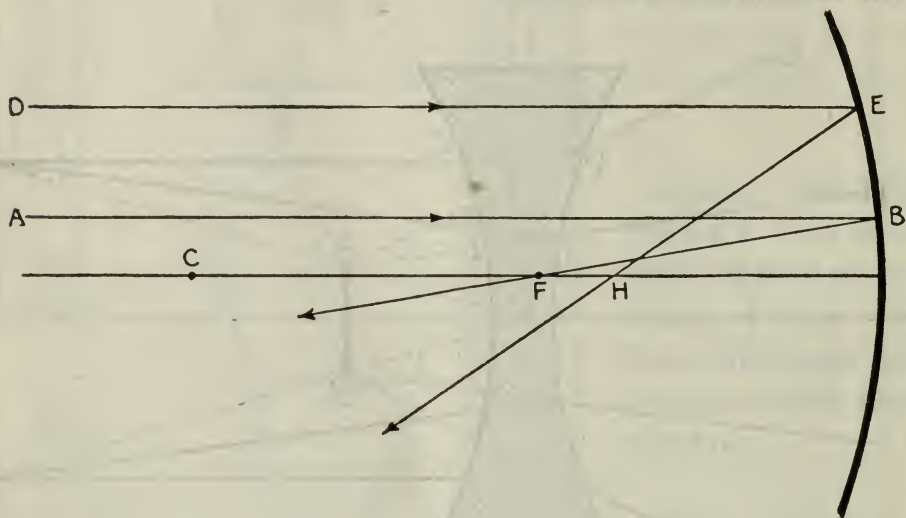


FIG. 3,806.—**Spherical aberration.** The reflected rays of concave spherical mirrors do not meet at exactly the same point. For instance, the ray AB, will be reflected to F, but DE will be reflected to H, a point closer to the mirror. This is called *spherical aberration*. It has been observed that the reflected rays only pass through a single point when the aperture of the mirror does not exceed 8 or 10 degrees. A larger aperture causes spherical aberration, producing a lack of "sharpness." Every reflected ray cuts the one next to it, and their points of intersection form in space a curved surface which is called the *caustic by reflection*. **By experiment**, when the light of a candle is reflected from the inside of a tea cup or a glass tumbler, a section of the **caustic surface** can be seen by partly filling the cup or tumbler with milk. Spherical aberration may be avoided by the use of a parabolic mirror. The point C is the center of curvature.

From the equation it is seen that if any two of the distances are given the other can be found. Thus solving (1).

$$\frac{1}{I} = \frac{1}{F} - \frac{1}{O} \dots\dots\dots (2)$$

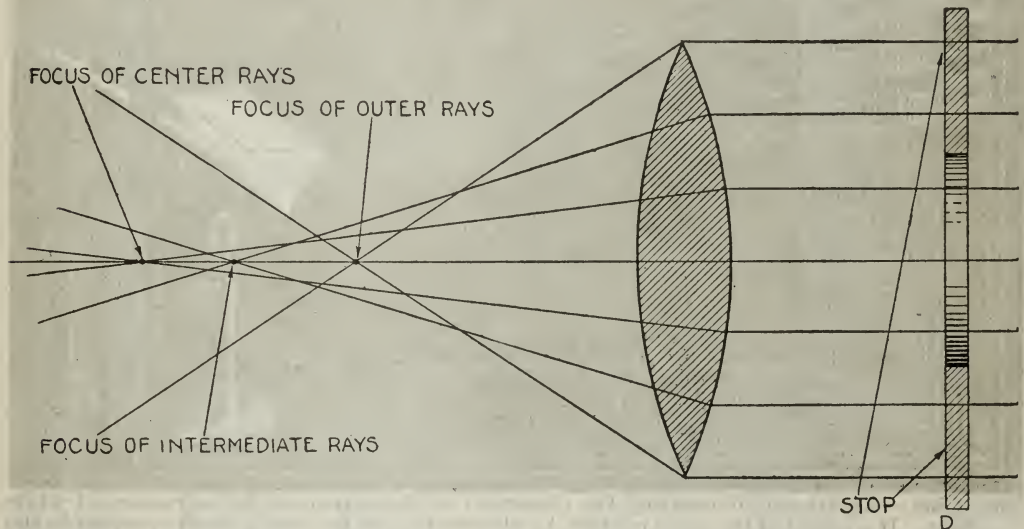
$$\frac{1}{O} = \frac{1}{F} - \frac{1}{I} \dots\dots\dots (3)$$



**Spherical Aberration; Caustics.**—The assumption that rays emitted from a single point intersect also after refracting in a single point is virtually correct with a lens whose aperture, that is, the angle obtained by joining the edges to the principal focus, does not exceed  $10^\circ$  or  $12^\circ$ .

**Ques.** What is the effect of a larger aperture?

**Ans.** The rays which traverse the lens near the edge are refracted to a point F on the principal axis nearer the lens than the focus of the rays G which pass near the axis.



**FIG. 3,807.—Effect of spherical aberration:** it produces a lack of sharpness and definition of an image. If a ground glass screen be placed exactly in the focus of a lens, the image of an object will be sharply defined in the center but indistinct at the edges, and if sharp at the edges, it will be indistinct at the center. This effect is very objectionable, especially in photographic lenses. To avoid this, a disc D with a hole in the center is placed concentric with the principal axis of the lens, thus only the central part of the lens is used.

That is to say, the rays farther from the principal axis are refracted more than those near this axis.

**Ques.** What ill effect is due to spherical aberration?

**Ans.** The image is slightly blurred.

**Ques.** How may this be avoided?



Ans. By means of a "stop," that is to say, a disc with a small hole in it placed in the path of light, as shown in fig. 3,807.

**Ques.** What name is given to the luminous surfaces produced by the intersecting of the refracted rays?

Ans. Caustics by refraction.

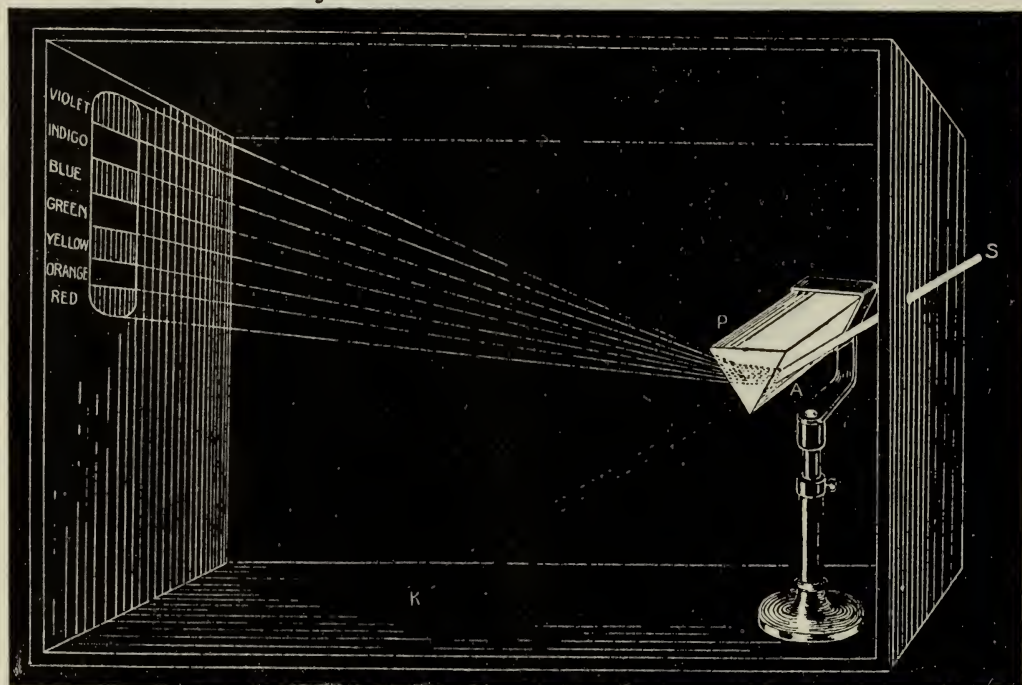


FIG. 3,808.—Experiment illustrating the dispersion or decomposition by refraction of white light. If a pencil of the sun's rays SA be allowed to pass through a small aperture in the window shutter of a dark chamber, this pencil tends to form a round and colorless image of the sun at K, but if a flint glass prism arranged horizontally, be interposed in its path, the beam, on emerging from the prism, becomes refracted toward its base, and produces on a distant screen a vertical band rounded at the ends, colored in all the tints of the rainbow, which is called the solar spectrum. In this spectrum there is virtually an infinity of different tint, which merge into each other, but it is customary to distinguish seven principal colors, viz: violet, indigo, blue, green, yellow, orange, red; they are arranged in this order in the spectrum, the violet being the most refrangible, and the red the least. They do not all occupy an equal extent in the spectrum, violet having the greatest extent, and orange the least.

**Chromatic Aberration.**—When white light is passed through a spherical lens, *both refraction and dispersion occur.*

This causes a separation of the white light into its various colors and causes images to have colored edges. This defect which is most observable in condensing lenses is due to the unequal refrangibility of the simple colors, and is called chromatic aberration.

**Ques.** What is white light?

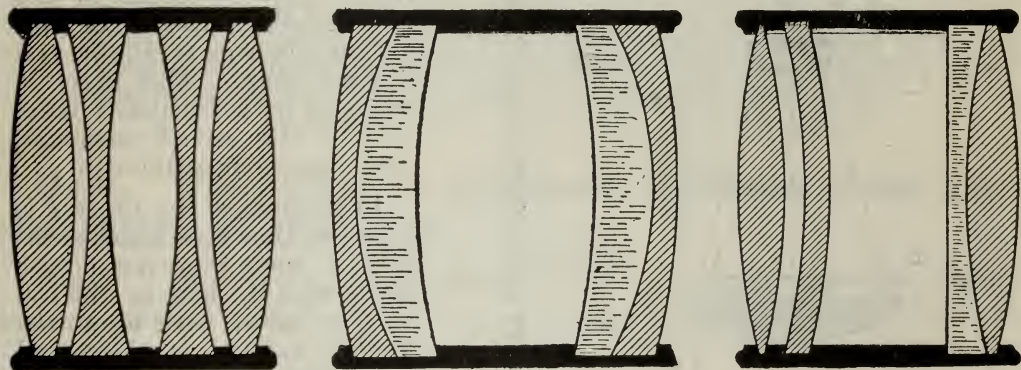
**Ans.** The light from the sun, the electric arc, etc.

**Ques.** What is dispersion?

**Ans.** The decomposition of white light into several kinds of light as shown in fig. 3,808.



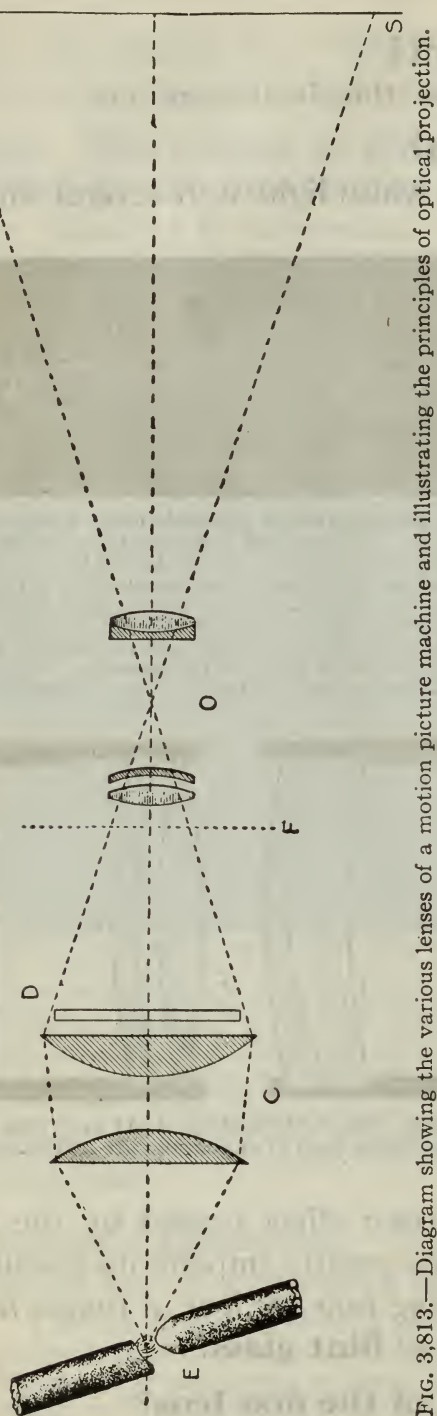
**FIG. 3,809.**—Achromatic lens, consisting of a combination of a double convex lens of crown glass, and a double concave lens of flint glass. Whenever it is desired to project especially good pictures upon a screen, lenses are often combined as shown in the figure. Here M indicates the line through the principal axis, at which the red rays reflected by the double convex lens would strike, and S, the line where the violet rays would be projected. The addition of the double concave lens brings the red and violet together again at G. A combination of two such lenses F H, placed the proper distance apart and the surfaces properly proportioned, may be made to combine any two of the colors of the spectrum. Accordingly even with these connected lenses there is always some coloring on the screen, although hardly noticeable.



**FIGS. 3,810 to 3,812.**—Various achromatic lenses. Fig. 3,810 and fig. 3,811 are types usually used in photography, and fig. 3,812, a combination used in motion picture and stereopticon projection.

**Achromatic Lenses.**—The color effect caused by the chromatic aberration of a simple lens greatly impairs its usefulness. *This may be overcome by combining into one lens, a convex lens of crown glass and a concave lens of flint glass.*

**Ques.** What is the action of the first lens?



Ans. It produces both bending and dispersion.

**Ques.** What is accomplished by the second lens?

Ans. It almost completely overcomes the dispersion without entirely overcoming the bending.

**Principles of Optical Projection.**—The process is almost the reverse of ordinary photography.

For instance in photographing a scene by means of the photographic objective or lens, a reduced image is obtained on ground glass. This glass is replaced by a sensitized plate, and by the use of chemicals the image is fixed thereon.

In projection the process is reversed, that is, a transparent slide is made from the picture made with the lens, or the roll of film taken with a motion picture camera is developed and used in the projection lantern or "motion picture machine" as it is usually called.

By means of a condensed light these are strongly illuminated, and with an objective lens, an enlarged image is projected upon the screen; this screen image corresponding to the real objects photographed.



The principles of optical projection for both lantern slide and motion picture apparatus will readily be understood from the diagram fig. 3,813.

At E is an electric light or other suitable illuminant the light from which is caught up by the condensing lenses or condenser C; this condenser is an arrangement of lenses so constructed as firstly, to gather up as great a volume of light as possible and secondly, to concentrate the light which it gathers at the center or diaphragm plane of the objective when the objective is located at the proper distance from the slide or film, which distance is determined by the focal length of the objective.

The slide or film should be placed at such a point that the entire area of the opening is fully illuminated, and it should also be placed so that the greatest number of light ray possible should pass through it. Taking into consideration the fact that the opening in the mat in the lantern slide is  $2\frac{3}{4} \times 3$  inches and in the motion picture film is  $1\frac{1}{16} \times 1\frac{15}{16}$  inches, it will at once be evident that the slide must be placed at the point D in the diagram in order that its entire area be covered, and the moving picture film must be located at the point F, in order that it may take in the greatest number of light ray.

Proceeding from the slide or film, the light passes through the objective O, where the rays cross and the object is therefore reversed; by means of the objective, the object is also imaged or delineated upon the screen S, the degree of sharpness or flatness of the image depends upon the optical connection of the lens.

**Ques.** What must be the relative positions of the arc, condenser and objective?

**Ans.** They must be so placed that an image of the light source will be formed at the diaphragm of the objective.

Under these conditions all light coming from the condenser is utilized and the image on the screen is at its brightest.

**Ques.** What provision should be made where lantern slide and motion picture films are to be used interchangeably?

**Ans.** Since the opening in the slide mat is approximately three times that of the moving picture film, it is therefore necessary

to have a lens for lantern slides about three times the focal length of that of the lens used for films.

*It should be noted* that it is possible to match the size of the image in *one dimension only* (either width or height) because the two openings are not proportionate in size; **accordingly, it is necessary in ordering lenses to specify whether the images are to be the same height or width.**

**How to Select a Lens.**—The lens is probably the most important consideration in projection work, for on its selection depend the quality and size of the image on the screen. Not

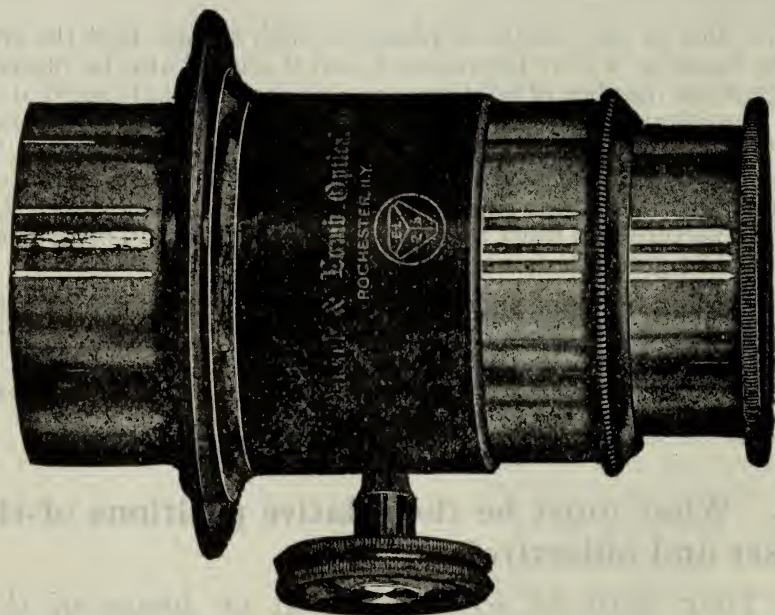


FIG. 3,814.—Bausch & Lomb standard projection lens. *It consists of two combinations fitted into a cell and mounted in a brass tube which slides through a brass tube or sleeve. The focusing is by rack and prism, as shown. Connection is made for spherical and achromatic aberration. Equivalent focus  $2\frac{1}{2}$  to 32 inches, and back focus  $1\frac{3}{4}$  to 30 inches; corresponding diameter of lenses  $1\frac{1}{8}$  to  $2\frac{1}{16}$ .*

the lens mounting, nor even the diameter of the lens itself, but ***its equivalent focus***, and *distance from the screen*, determine the size of the image.

**Ques.** At a given distance how does the size of the image on the screen vary with the focal length?

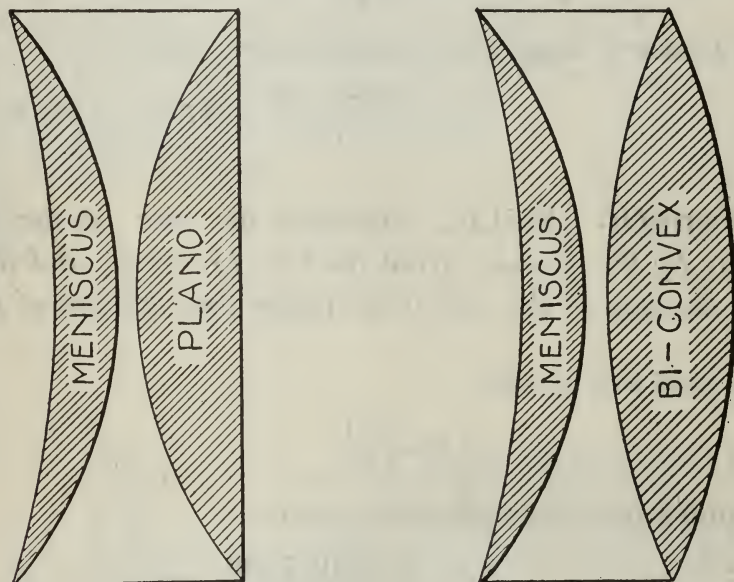


Ans. The greater the focal length the smaller the image.

Accordingly short focus lenses give large images.

**Ques. What precaution should be taken in selecting a lens?**

Ans. The lens should not be of such short focus that the magnification will be so great as to sacrifice definition and perspective when viewed by an observer near the screen.



FIGS. 3,815 and 3,816.—Two forms of condenser. Owing to its form, the meniscus condenser will intercept and utilize a larger percentage of light ray from the arc than the plano, which means that more light will be transmitted to the film, when a meniscus condenser is used. The meniscus, however, because of being closer to the heat of the arc, is more liable to breakage. A combination consisting of one meniscus, and one bi-convex condenser is recommended.

**Ques. What kind of picture is most desirable?\***

Ans. Brilliant pictures of medium size.

**Ques. How should the projection distance be measured?**

Ans. From the slide or film to the screen.

The accompanying tables show the size of image obtained with lenses of different focal length at varying distances. Other sizes, focal lengths and distances can be computed as follows:



**Size of Image.** RULE: *Multiply the difference between the distance from the lens to screen and the focal length of the objective, by the size of the slide and divide the product by the focal length.*

EXAMPLE.—Let  $L$  be the projection distance, 40 feet or 480 inches;  $S$ , the slide mat 3 inches;  $F$ , the focus of the lens 12 inches. The formula for size of image, is

$$d = \frac{S (L - F)}{F}$$

where  $d$  = size of image substituting the given data

$$d = \frac{3 (480 - 12)}{12} = 117 \text{ ins. or } 9\frac{3}{4} \text{ ft.}$$

**Focal Length.** RULE: *Multiply the size of the slide or film opening by the distance from the lens to screen, and divide the product by the sum of the size of the image and the size of the slide.*

Expressed as a formula

$$F = \frac{S \times L}{d + S}$$

substituting the values previously given

$$F = \frac{3 \times 480}{117 + 3} = \frac{1,440}{120} = 12 \text{ ins.}$$

**Distance from Slide to Screen.** RULE: *Multiply the sum of the size of the image and size of slide mat, by the focal length, and divide this product by the size of the slide mat.*

Expressed as a formula

$$L = \frac{F (d + S)}{S}$$

substituting the values previously given

$$L = \frac{12 (117 + 3)}{3} = 480 \text{ ins., or } 40 \text{ ft.}$$

**Table showing size of screen image when lantern-slides are projected.**

Size of Mat opening  $2\frac{3}{4} \times 3$  inches

Equiv. focus Inches	15 ft.	20 ft.	25 ft.	30 ft.	35 ft.	40 ft.	45 ft.	50 ft.	60 ft.	70 ft.	80 ft.	90 ft.	100 ft.
5	8.0	10.8	13.5	16.3	19.0								
5½	8.8	11.8	14.8	17.8	20.8								
6	7.3	9.8	12.3	14.8	17.3	19.8							
6½	7.9	10.7	13.4	16.1	18.8	21.6							
7	8.6	8.9	11.2	13.5	15.8	18.1	20.4						
7½	7.3	9.8	12.3	14.8	17.3	19.8	22.3						
8	6.1	8.2	10.4	12.5	14.6	16.7	18.8						
8½	6.7	9.0	11.3	13.6	15.9	18.2	20.5						
9	5.7	7.6	9.6	11.6	13.5	15.5	17.5	19.4					
9½	6.2	8.3	10.5	12.6	14.8	16.9	19.0	21.2					
10	5.3	7.1	8.9	10.8	12.6	14.4	16.3	18.1					
10½	5.8	7.8	9.8	11.8	13.8	15.8	17.8	19.8					
11	6.6	8.4	10.1	11.8	13.5	15.2	17.0	20.4					
11½	7.3	9.1	11.0	12.9	14.8	16.6	18.5	22.3					
12	6.2	7.9	9.5	11.1	12.7	14.3	16.0	19.2					
12½	6.8	8.6	10.3	12.1	13.9	15.6	17.4	20.9					
13	5.9	7.4	8.9	10.5	12.0	13.5	15.1	18.1	21.1				
13½	6.4	8.1	9.8	11.4	13.1	14.8	16.4	19.6	23.1				
14	5.6	7.0	8.5	9.9	11.4	12.8	14.2	17.1	20.0				
14½	6.1	7.6	9.2	10.8	12.4	14.0	15.5	18.7	21.9				
15	5.3	6.8	8.0	9.4	10.8	12.2	13.5	16.3	19.0	21.8			
15½	5.8	7.3	8.8	10.3	11.8	13.3	14.8	17.8	20.8	23.8			
16	5.5	6.8	7.8	8.9	10.1	11.2	12.3	13.5	15.8	18.1	20.4		
16½	6.0	7.3	8.5	9.8	11.0	12.3	13.6	17.3	19.8	22.3			
17	5.6	6.6	7.6	8.6	9.6	10.6	11.6	13.5	15.5	17.5	19.4		
17½	6.2	7.3	8.3	9.4	10.5	11.6	12.8	14.8	16.9	19.0	21.2		
18	5.8	6.8	7.5	8.4	9.4	10.4	11.4	13.5	15.2	17.0			
18½	6.3	7.3	8.2	9.1	10.1	11.0	12.0	14.8	18.8	18.5			
19	5.1	5.9	6.6	7.4	8.2	9.0	10.5	12.0	13.5	15.1			
19½	5.6	6.4	7.3	8.1	9.0	10.0	11.4	13.1	14.9	16.4			
20	5.3	6.0	6.8	7.6	8.4	9.2	10.6	12.2	13.8				
20½	5.8	6.5	7.3	8.0	8.8	9.6	11.0	12.8	14.8	16.8			
21	5.4	6.0	6.7	7.4	8.1	8.8	10.3	11.8	13.3	14.8			
21½	5.9	6.6	7.3	8.0	8.7	9.4	10.9	12.4	13.9				
22	5.5	6.2	6.9	7.6	8.3	9.0	10.5	12.0	13.5				
22½	6.0	6.7	7.4	8.1	8.8	9.5	11.0	12.5	14.0				
23	5.6	6.3	7.0	7.7	8.4	9.1	10.6	12.1	13.6				
23½	6.1	6.8	7.5	8.2	8.9	9.6	11.1	12.6	14.1				
24	5.7	6.4	7.1	7.8	8.5	9.2	10.7	12.2	13.7				

**EXAMPLE:** With a lens of 10-inch focus at a distance of 20 ft. the screen image will be 5.3 x 5.8; at 25 ft., 6.6 x 7.3; at 30 ft., 8.0 x 8.8; at 50 ft., 13.5 x 14.8 etc.

**Table showing size of screen image when moving picture films are projected.**

Size of Mat opening  $1\frac{1}{8} \times 1\frac{3}{8}$  inch

Equiv. focus Inches	15 ft.	20 ft.	25 ft.	30 ft.	35 ft.	40 ft.	45 ft.	50 ft.	60 ft.	70 ft.	80 ft.	90 ft.	100 ft.
2½	4.8	6.4	8.0	9.6	11.3	12.9	14.5	16.1					
2½	6.5	8.7	11.0	13.2	15.4	17.6	19.8	22.0					
3	5.4	6.8	8.2	9.6	10.9	12.3	13.7	16.4					
3½	7.4	9.3	11.2	13.1	14.9	16.8	18.7	22.4					
4	4.5	5.7	6.8	8.0	9.1	10.3	11.4	13.7	16.0				
4½	6.2	7.7	9.3	10.9	12.4	14.0	15.6	18.7	21.8				
5	4.8	5.8	6.8	7.8	8.8	9.8	11.7	13.7	15.7				
5½	6.6	8.0	9.3	10.6	12.0	13.3	16.0	18.7	21.4				
6	4.2	5.1	6.0	6.8	7.7	8.5	10.3	12.0	13.7	15.4			
6½	5.8	7.0	8.1	9.3	10.5	11.6	14.0	16.3	18.7	21.0			
7	4.5	5.3	6.2	6.8	7.7	8.4	10.6	12.2	13.7	15.4			
7½	6.2	7.2	8.4	9.3	10.5	12.4	14.5	16.6	18.7	21.0			
8	4.8	5.4	6.1	6.8	7.6	8.2	9.6	10.9	12.3	13.7			
8½	6.5	7.4	8.4	9.3	11.2	13.0	14.9	16.8	18.7				
9	4.3	4.9	5.6	6.2	7.4	8.7	9.9	11.2	12.4				
9½	5.9	6.7	7.6	8.4	10.2	11.9	13.6	15.3	17.0				
10	4.5	5.1	5.7	6.8	8.0	9.1	10.3	11.4					
10½	6.2	7.0	7.7	9.3	10.9	12.4	14.0	15.6					
11	4.7	5.2	6.3	7.3	8.4	9.6	10.6						
11½	6.4	7.1	8.6	10.0	11.4	13.0	14.5						
12	4.4	4.9	5.8	6.8	7.8	8.8	9.8						
12½	6.0	6.6	8.0	9.3	10.6	12.0	13.3						
13	4.5	5.4	6.4	7.3	8.2	9.1							
13½	6.2	7.4	8.7	10.0	11.2	12.3							
14	5.1	6.0	6.8	7.7	8.5								
14½	7.0	8.1	9.3	10.5	11.6								

**EXAMPLE:** With a lens of 5½ inch focus at a distance of 35 ft. the screen image will be 4.3 x 5.9; at 40 ft., 4.9 x 6.7; at 45 ft., 5.6 x 7.6 etc.

**Motion Picture Machines.**—The term motion picture machine is the proper name of the apparatus used in projecting motion picture film upon a screen; the use of such expressions as projector, graphoscope, etc., should be avoided.

The function of a moving picture machine, as stated, is to project motion pictures upon a screen, in distinction from a motion picture camera used for motion picture photography. Some of the "coined expressions" are both ill advisedly and erroneously used.

A motion picture machine may be said to consist of:

1. An optical system, comprising

a. Source of light;

b. Lens { condenser;  
objective.

2. Intermittent film feed system, comprising

a. Upper reel;

b. Upper steady feed sprocket;

c. Steady drum;

d. Film gate;

e. Intermittent sprocket;

f. Intermittent movement;

g. Shutter;

h. Lower steady feed sprocket;

i. Lower reel;

j. Lower reel drive;

k. Operating crank and drive;

l. Numerous presser rollers.

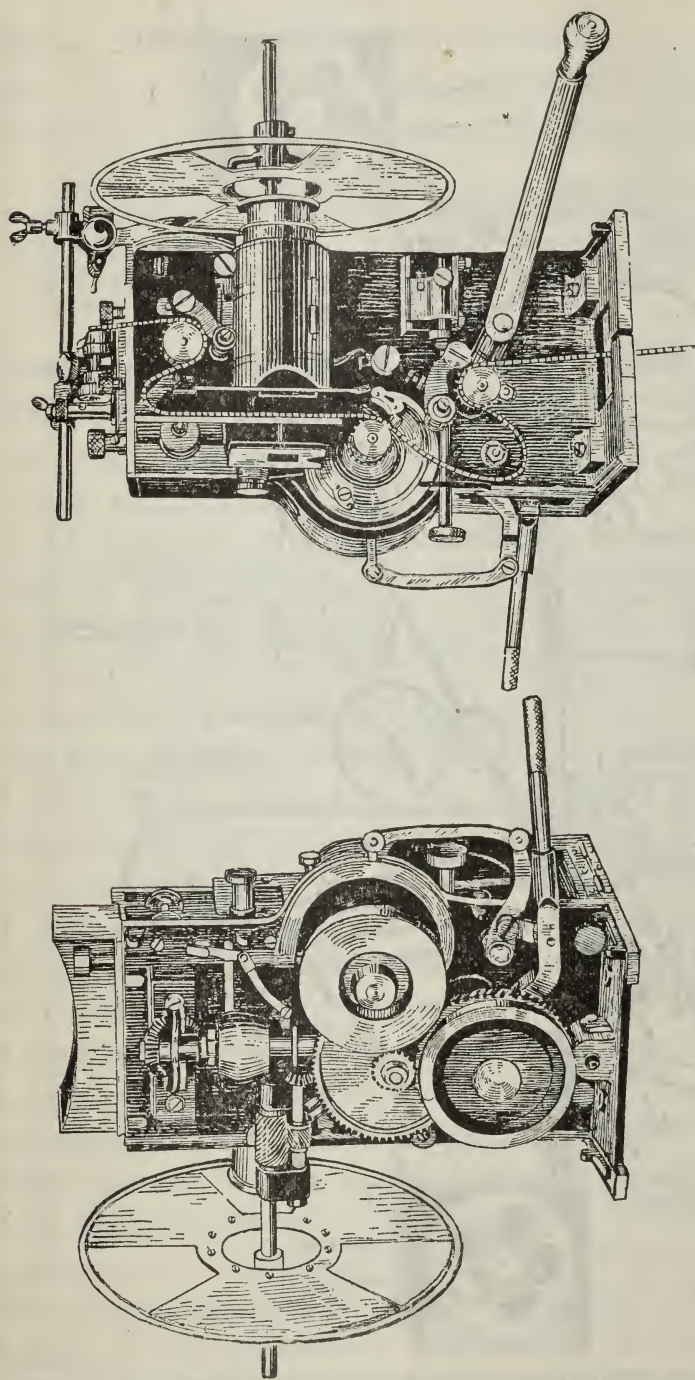
Besides these various essential parts, safety devices such as, fire shutter, fire valves, film shields, etc., are provided.

The elementary moving picture machine shown in fig. 3,819 is so drawn that every part can be seen; it does not represent any particular machine but is intended to give a clear idea of how the film is fed across the film gate intermittently and the synchronous operation of the shutter whereby the light is cut off from the screen during each movement of the film, with alternate "on" intervals while the film is at rest.

**Ques.** Upon what property of vision is moving picture projection based?

**Ans.** Upon the "*persistence of vision.*"





FIGS. 3,817 and 3,818.—Simplex motion picture machine. Fig. 3,817 shows the right side with film covers and upper magazine fire valve removed from the top. The valve consists of one large steel roller and two smaller ones which are set at an angle of 45 degrees. They bear against the film top and bottom, and protect the reel from fire. Fig. 3,817 shows also the revolving shutter and shutter mechanism. The three wing shutter shown is used with direct current, but on A. C. circuits of 60 cycles or less a two wing shutter is recommended as it does not intercept the light periods in step with the alternation of the arc. A three wing shutter used with alternating current is liable to get into synchronism with the alternations of the arc and cause a wavy effect in the light similar to a bad flicker. The shutter may be set during operation by turning the knurled knob located alongside the framing handle, thus avoiding ghosts or white streaks. Fig. 3,818 shows right side of machine with fireproof covers removed; it also shows clearly the path of the film through the machine.

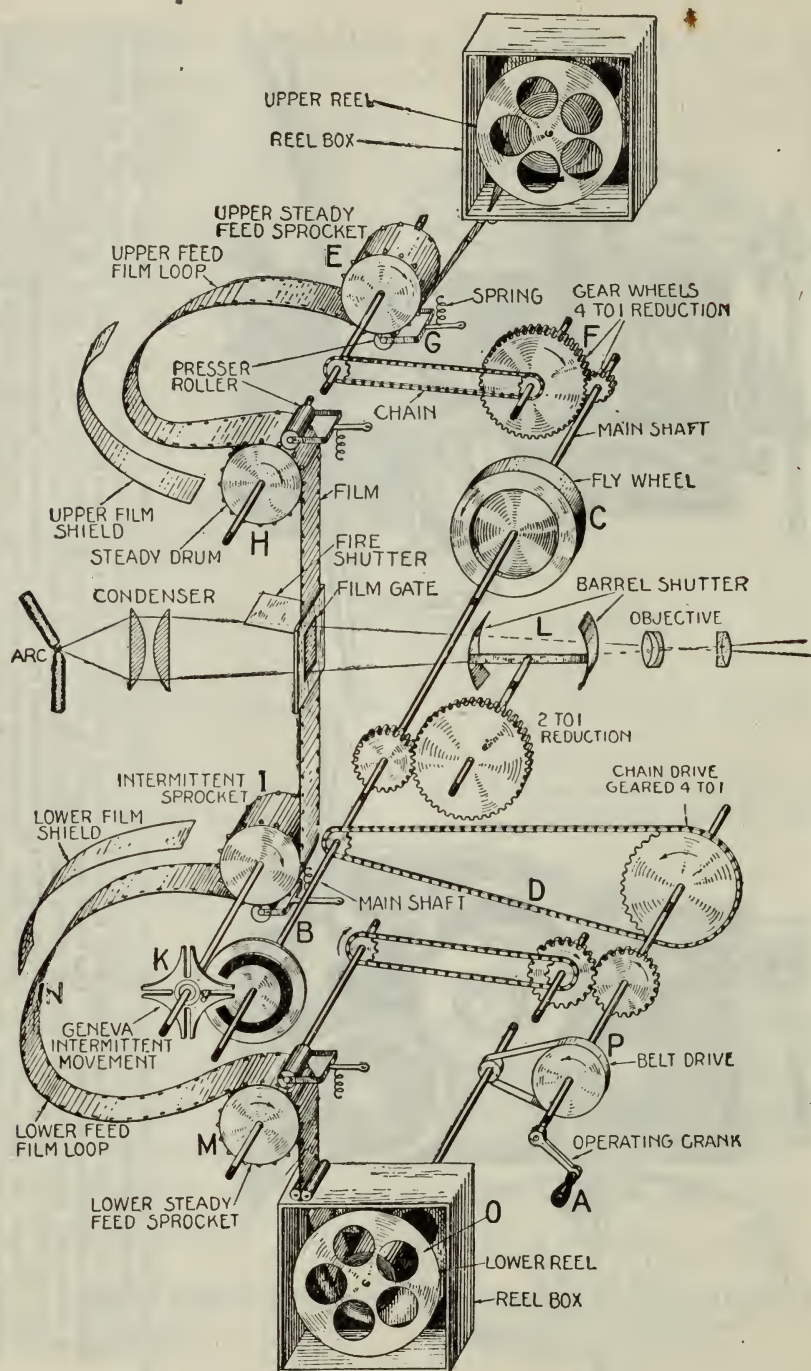


FIG. 3,819.—Elementary moving picture machine without case, showing essential parts.



**Ques. Define persistence of vision.**

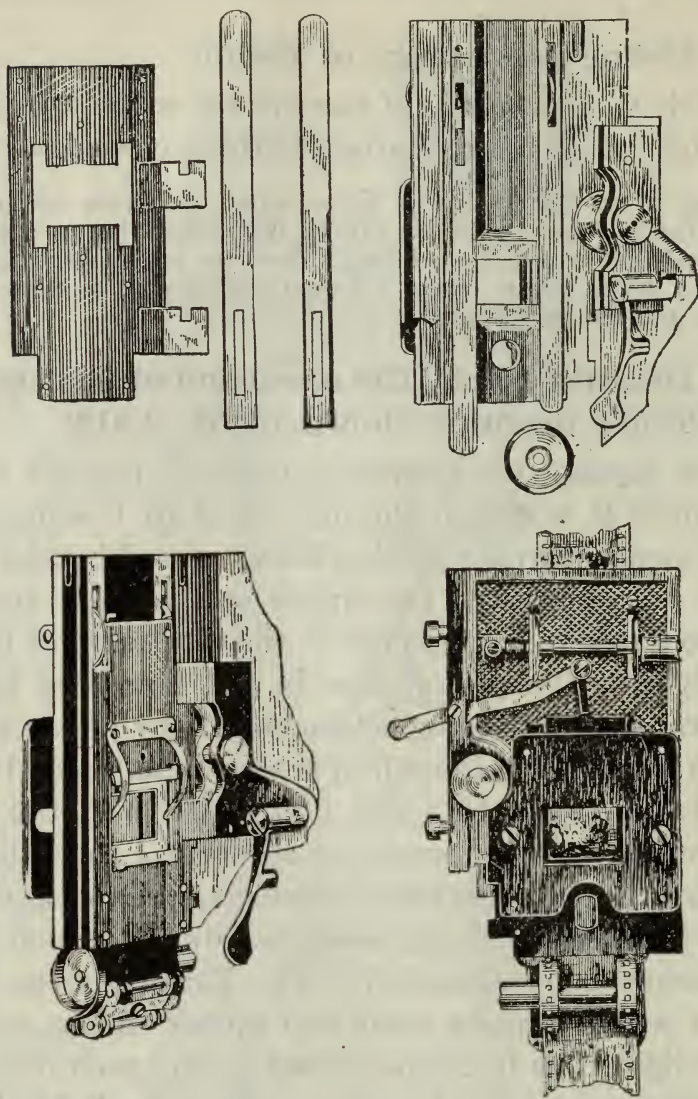
**Ans.** It is that property of the eye by which vision remains or *persists* for a short interval after the thing viewed has vanished.

Owing to the persistence of vision, when two views are seen with an interval of not more than one fiftieth of a second between the two, the eye blends the two and accordingly does not appreciate the interval of darkness which has occurred between the two, as is demonstrated in moving picture projection.

**Ques. Describe briefly the operation of the elementary motion picture machine shown in fig. 3,819.**

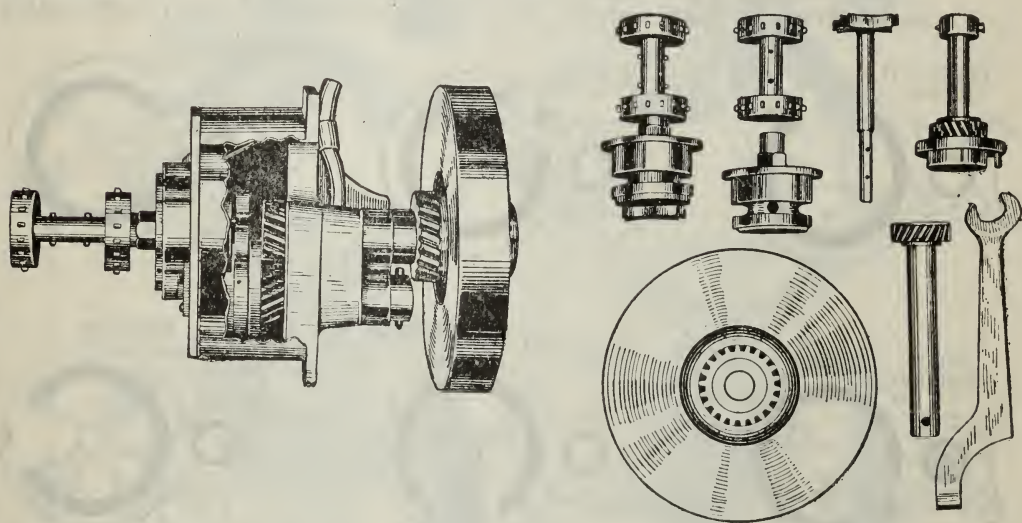
**Ans.** By turning the operating crank A, counter clockwise, the main shaft B, is driven through the 4 to 1 reduction chain drive D, a steady turning motion being caused by the fly wheel C, this in turn operates the upper steady feed sprocket E, through the 4 to 1 reduction gear F, thus the teeth of E sprocket which mesh with the perforations in the film, feed the film at a constant rate, the film being held against E by pressure roller G. A film loop or length of loose film is thus maintained between E and the steady drum H. The film is fed past the film gate intermittently by the intermittent sprocket I, operated by the Geneva movement K, the latter producing a quick quarter turn of I, followed by a relatively long rest during which the main shaft B, makes one revolution. The barrel shutter L, by a 2 to 1 gear with the main shaft and proper timing, operates to cut off the light rays from the screen during each movement of the intermittent sprocket I, and to admit the light during the intervals that I remains stationary. The synchronous operation of the intermittent sprocket and the shutter is very clearly shown in the diagram. A lower steady feed sprocket M, which operates at the same speed as the upper sprocket E, maintains a lower feed film loop N, and feeds the film to the lower reel O. Because of the increasing diameter of the roll of film due to winding the film on reel O, the velocity of rotation of O must be





FIGS. 3,820 to 3,826.—Construction details of Simplex film gate. It is made of machine steel, the lugs securing the gate to the holder being electrically welded. Fig. 3,820 represents milled surfaces. The film trap shoes (figs. 3,820, 3,825), are of steel ground on both sides and beveled (fig. 3,820) to permit sliding into the dove tail slots (fig. 3,823). The lateral guide rollers (fig. 3,824 and 3,826) are of steel hardened and ground; the film cannot pass the guide rollers unless it be set between the two. If it should not be, it automatically rights itself. The distance between the rollers is adjustable by a set collar (fig. 3,826). The gate (fig. 3,825) is opened for threading by a light inward pressure on a thimble (fig. 3,826), and is closed by releasing the film trap door trip lever (fig. 3,825). Thus, in threading, there are only two operations: one to open, and one to close the gate. The intermittent sprocket tension shoe is made of ten pieces of hardened tool steel. The two inside shoes are offset and do not touch the film. The cooling plate (fig. 3,826) is made of two pieces of sheet steel separated  $\frac{1}{4}$  inch, which arrests the heat by radiation and protects the fire shutter and aperture side of the film trap. The air space between the film trap is  $\frac{1}{2}$  inch.

allowed to vary; this is accomplished by means of the belt drive P, the belt permitting slippage below the maximum speed. *It should be carefully noted that the total revolutions made by each of the three sprockets E, I, and M, is the same, the only difference being that the motion of E and M is constant while that of I is intermittent.*



FIGS. 3,827 to 3,835.—Construction details of an intermittent sprocket and intermittent movement. Fig. 3,827, intermittent sprocket and intermittent movement with case broken to show interior; figs. 3,828 to 3,835, parts. The intermittent movement is of the Geneva type arranged to run in oil. The case is in two pieces, consisting of box and screw cover, as shown in fig. 3,827. "Framing" of the film is accomplished by advancing or retarding the intermittent movement by a device for turning the intermittent box forward or backward. The revolving shutter synchronizes automatically by a cam system.

**Ques.** What is the object of the upper and lower feed loops.

**Ans.** To lessen the inertia of the film by reducing the length of film subject to the sudden intermittent motion.

**Ques.** What duties are performed by the film gate?

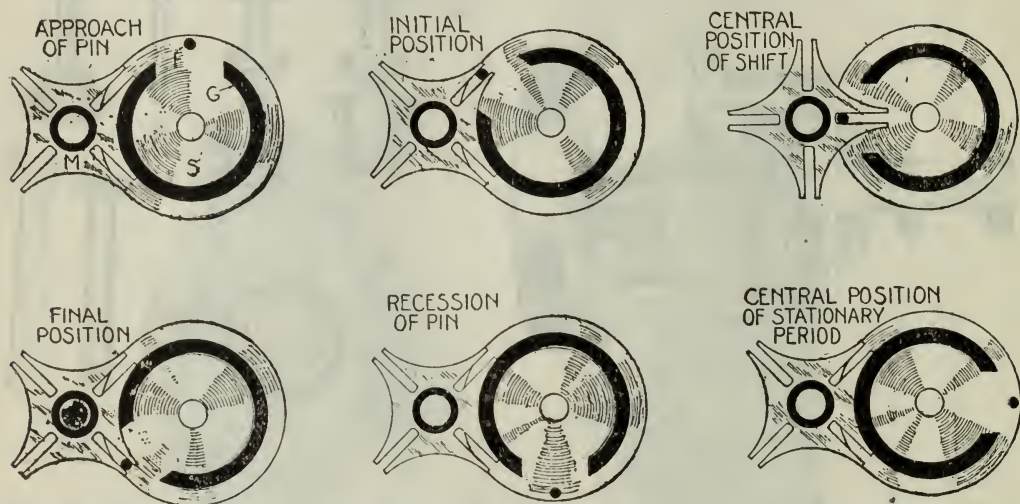
**Ans.** It guides the film so as to prevent any lateral motion,



flattens the film, and by frictional resistance, prevents the momentum of the film causing any up and down vibration.

**The Intermittent Movement.**—Various devices have been introduced for producing the intermittent movement necessary in projecting motion pictures. The movement consists essentially of an intermittent sprocket and intermittent gear.

The sprocket is a cylinder with teeth at each end, or for very light construction, it may consist of two hubs provided with teeth and



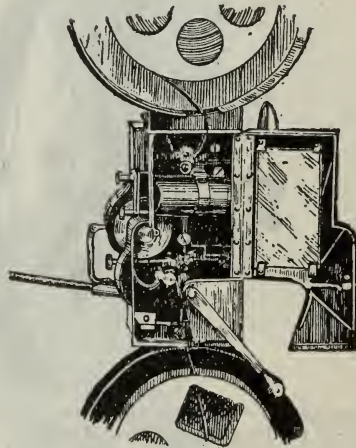
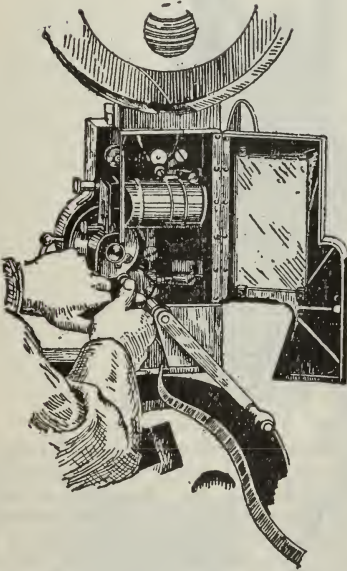
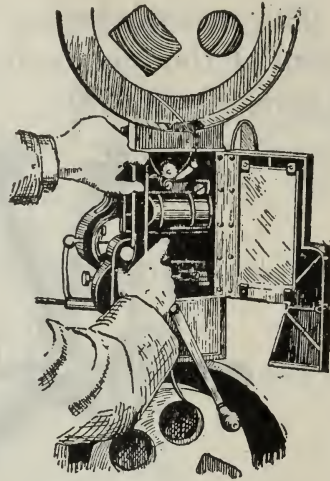
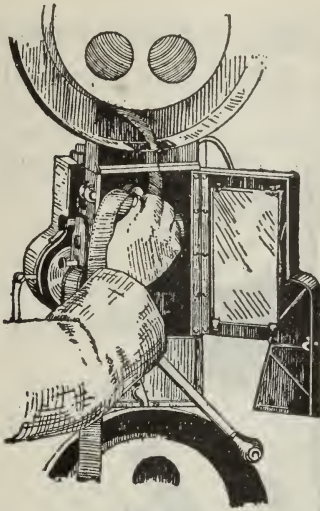
FIGS. 3,836 to 3,841.—Diagrams showing progressively the operations of the Geneva intermittent movement. Fig. 3,836, approach of pin; fig. 3,837, initial position or beginning of the movement; fig. 3,838, mid-position; fig. 3,839, final position or end of the movement; fig. 3,840, recession of the pin; fig. 3,841, mid-position of stationary period. The Geneva movement consists of a maltese cross M and a disc S provided with a pin F and circular guide G. *In operation*, the pin disc S is in continuous motion and the pin is so located that it enters one slot of the cross M and carries it along with it, thus causing one-quarter revolution. The circular guide G is cut away sufficiently to allow the cross to make a quarter revolution, but when it registers with the cross it holds the latter securely until the pin rotates around to the next slot.

properly spaced on a shaft to take the film. The teeth mesh with perforations of the film and thus secure a positive movement.

Of the various intermittent movements, the Geneva is extensively used and easily understood. Its operation is shown progressively in figs. 3,836 to 3,841.

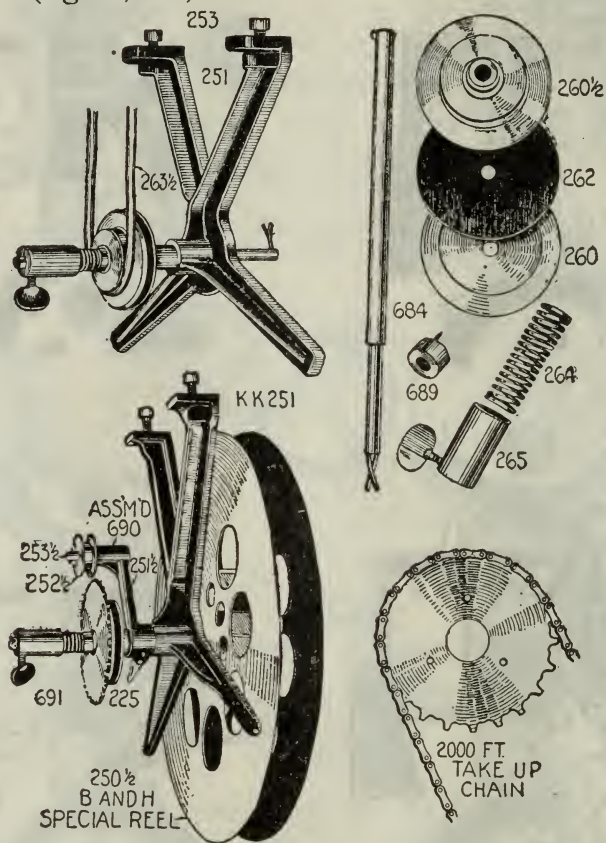
**Ques.** What is the nature of the Geneva intermittent motion?





FIGS. 3,842 to 3,845.—“Threading” a typical motion picture machine. Fig. 3,842 illustrates the method of threading the film through the film trap by forming the upper loop with the second finger of the left hand and gripping the film below the intermittent sprocket with the first finger. Fig. 3,843 illustrates how the film is threaded through the film trap by forming the upper loop with the second finger of the left hand and gripping the film below the intermittent sprocket with the first and third fingers of the right hand and closing the film gate by tripping the film trip lever with second finger. Fig. 3,844 illustrates the method of forming the lower loop, threading the film over the lower feed sprocket and closing the lower feed sprocket roll arm by a downward pressure with the first finger of the right hand. The film is then inserted through the fire valve by means of the slot in the base of the mechanism and is then fastened on to the lower reel so as to rewind to the right. Fig. 3,845 shows the machine completely threaded from the top reel to the feed sprocket through the film trap and on to the lower feed sprocket and the take up reel.

Ans. The motion begins slowly, (fig. 3,837), accelerates to a maximum at the mid position (fig. 3,838) and gradually slows down to zero (fig. 3,839).



**FIGS. 3,846 TO 3,855.**—Simplex take up device. Fig. 3,846 belt drive for small reels; fig. 3,854, chain drive for large reels; figs. 3,847 to 3,853, parts. The take up is the equivalent of the belt drive P, fig. 3,819, that is, it performs the same function, viz.: to rotate at variable speed the lower reel upon which the film is wound. Instead of securing the variable speed by belt slippage, a friction disc clutch is provided. Part 260 is the driving side of the disc and is directly connected to the take up shaft 684. The leather friction washer 262 is 3" diameter by  $\frac{1}{4}$ " thick; it operates between friction disc 260 and pulley 260 $\frac{1}{2}$ . The driving pulley 260 $\frac{1}{2}$ , driven by belt 263 $\frac{1}{2}$ , is forced to bear against leather washer 262 by spring 264, which is kept in place by a thimble and set screw 265.

**Ques.** Describe a variation in construction details.

Ans. Instead of only one pin on the disc, there are sometimes two.

**Ques.** How may the relative periods of rest and motion be varied?



Ans. By making the disc large in proportion to the cross.

The interval of movement can be reduced as much as desired in proportion to the interval of rest, but the characteristic features of starting and stopping the film gradually will be lost directly in proportion as the ratio between disc and cross sizes is increased.

**Ques.** How is the Geneva movement sometimes arranged in construction?

Ans. Provision is sometimes made for the movement to be run in oil.

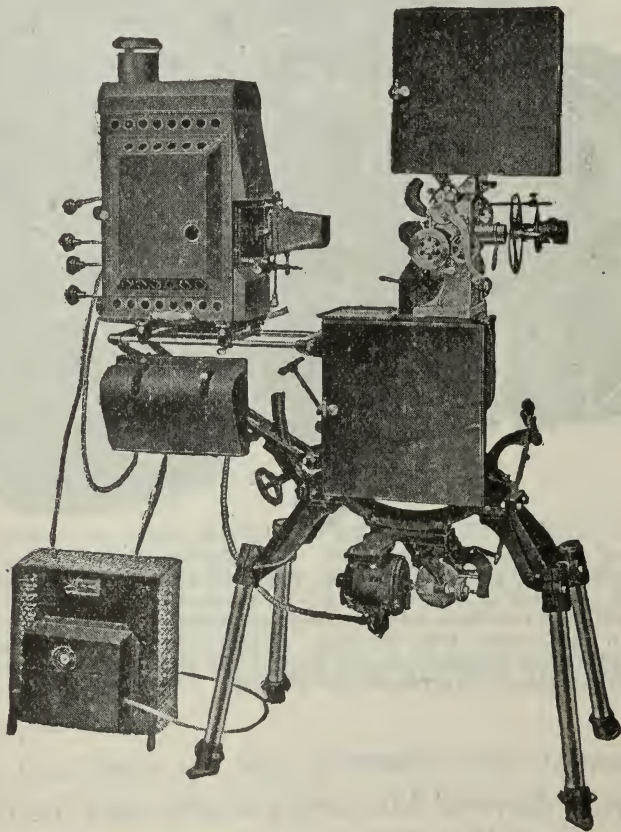


FIG. 3,856.—Power's motion picture machine or Cameragraph; view showing lamp house and machine with covers removed, exposing mechanism.



**Illumination for Motion Picture Projection.**—Both gas and electricity are used to produce illumination for motion picture projection. The electric arc is universally employed wherever electric current is available, but in many rural districts where

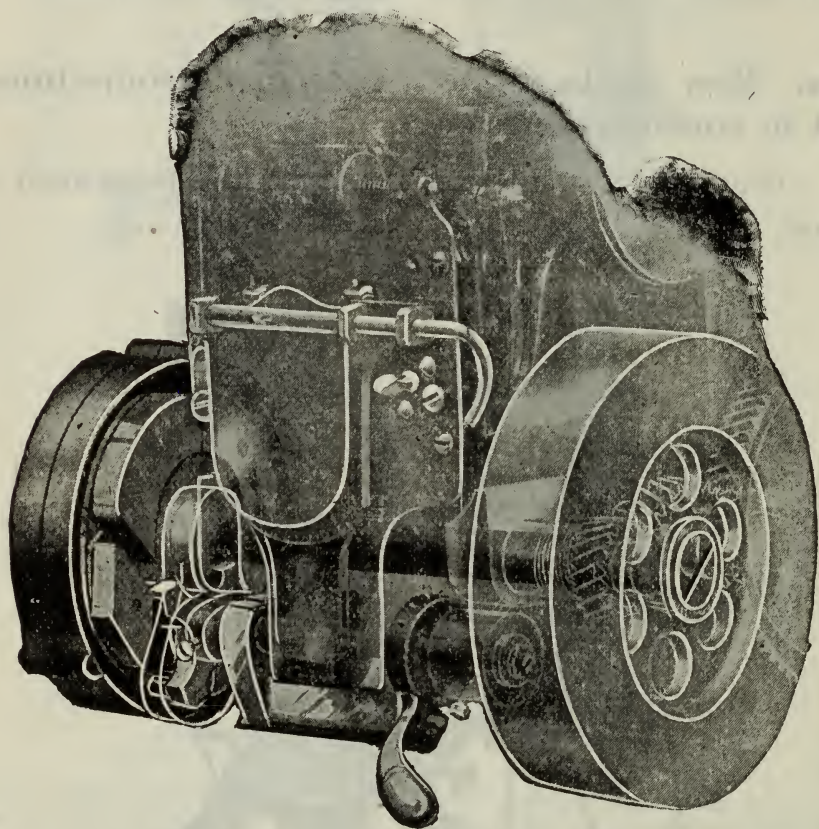


FIG. 3,857.—Powers' intermittent movement. The driving element is a diamond-shaped revolving surface which projects from the disc, the latter being attached to the main spindle or shaft. A locking ring for the driven element is also formed on the face of the disc in such relation to the diamond that the driven element passes from engagement with the diamond to engagement with the ring. The driven element consists of a cross as shown with intermittent sprocket spindle formed out of a block of drop forged tool steel. The intermittent movement is arranged to run in oil.

electricity cannot be obtained, gas is used and gives satisfactory results. Several kinds of gas are used for illumination.

Burners for use with these gases are shown in the accompanying cuts, also some types of generator or gas making outfit.

**The Electric Arc.**—The subject of electric arcs has been presented at length in Guide No. 9, and it is only necessary to treat here of its special adaptation to optical projection.

The only modification of the ordinary arc required to adapt it for use in the optical lantern is to make it as much one sided as possible, that is to say, to so arrange it that *as much of the light as possible will be thrown toward the condensers.*

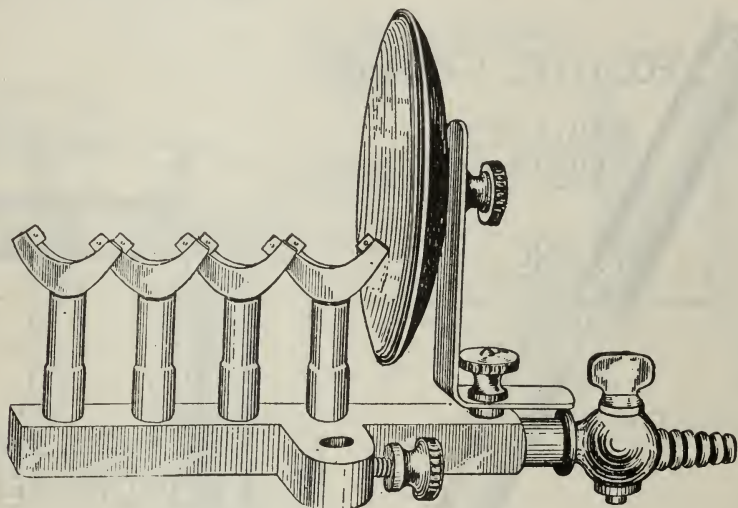


FIG. 3,858.—Challenge multi-tip acetylene burner. It has eight tips set in pairs at an angle. The gas comes from each set at an upward and inward angle, meeting to form one flame.

**Ques.** What kind of current is used for the arc?

**Ans.** Either direct or alternating

**Ques.** How is the direct current arc connected?

**Ans.** The positive pole is connected to the upper carbon of the lamp and the negative pole to the lower carbon.

**Ques.** How are the carbons adjusted for direct current motion picture arc?

**Ans.** The carbons are placed end to end in a straight line except that the axis of the lower one is slightly in advance of that of the upper one as in fig. 3,859. To bring the maximum light upon the condensers the carbon must be inclined about  $25^{\circ}$ .

If inclined too much, the end of the lower carbon will throw a shadow upon the condenser; if not enough, the maximum light is not projected upon the condenser.

**Ques. How are carbons adjusted for direct current stereopticon arc?**

**Ans.** The carbons are set at right angles, positive carbon horizontal, and negative carbon vertical, as in fig. 3,860.

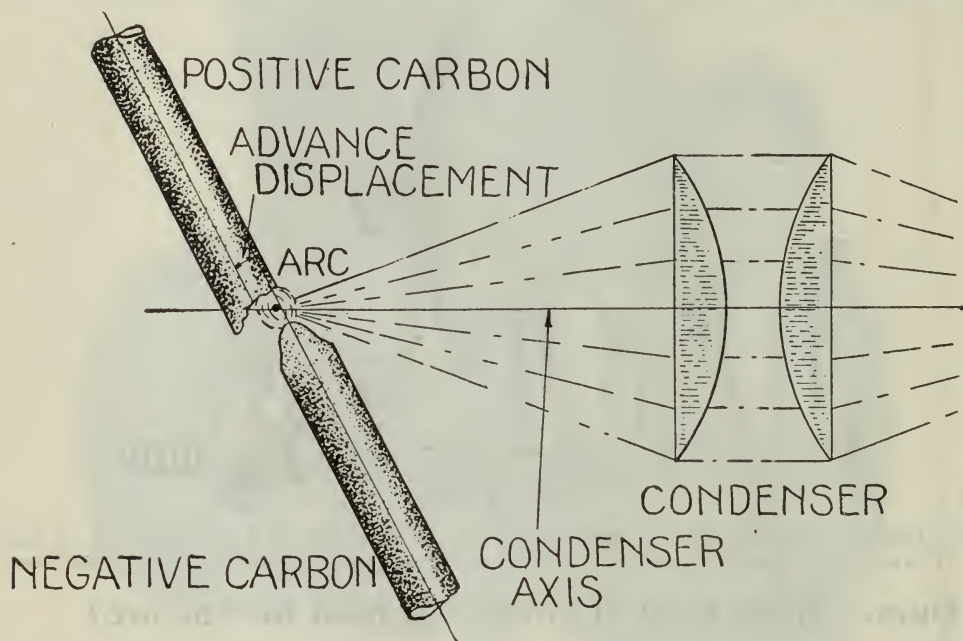


FIG. 3,859.—Motion picture arc for direct current. *The advance displacement*, say  $\frac{1}{8}$  inch, causes the upper carbon to burn with a diagonal end containing the brilliant crater and the light is accordingly thrown toward the condenser.

That is to say, the positive carbon is set in the axis of the condenser with the negative carbon at right angles.

**Ques. What troubles are encountered with alternating current arcs?**

**Ans.** Two craters are formed and if the light from both is to be used, a very careful setting and adjustment is necessary to avoid poor illumination and a double spot at the center of the screen.



**Ques.** What kind of carbon should be used for alternating current arcs?

**Ans.** Cored carbons.

**Ques.** For angular settings, how does the angle of carbon vary?

**Ans.** It varies with the amount of current used, and the size and quality of the carbon.

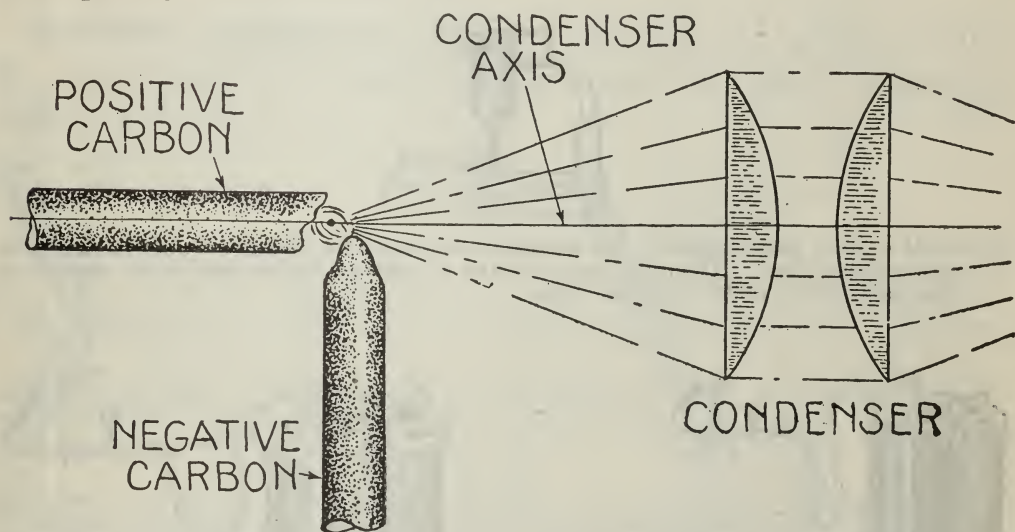


FIG. 3,860.—Stereopticon arc for direct current. *This setting* does not give as brilliant an arc as fig. 3,859, when a long arc is used, but for a short arc the carbons become so near that an arc of more brilliancy than fig. 3,859 is obtained.

**Ques.** In operation how is the proper angle secured?

**Ans.** By varying the angle, that is “rocking” the carbons while watching the screen till the best illumination is secured.

**Ques.** How is the light centered?

**Ans.** By moving the arc in a direction opposite to that in which it is desired to move the bright spot on the screen.

**Ques.** Describe the lamp adjustments.

**Ans.** There are four adjustments: 1, vertical, 2, lateral, 3, focusing, and 4, feed.

**Ques. How is the arc started or "struck?"**

Ans. Bring the carbons together by turning the proper knob, then reverse and draw them apart until the proper arc is secured.

**Ques. What is a proper arc?**

Ans. An arc of medium length.

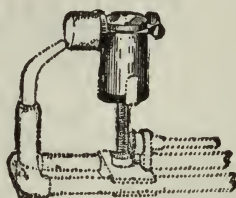
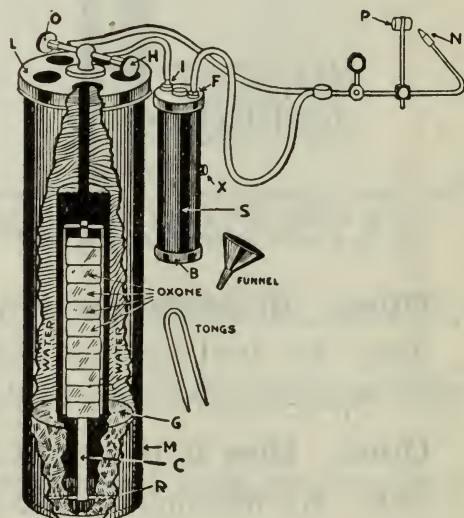
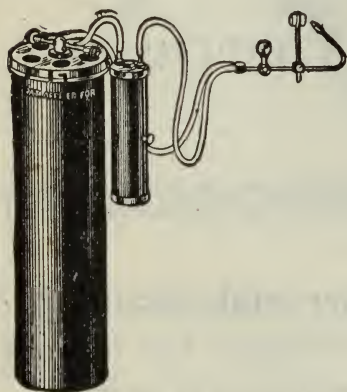


FIG. 3,861.—Fulco pastil adapter. By means of this device the Guil pastil may be used with any calcium burner. The main portion of the adapter is a hollow shell which serves as a receptacle for the pastil when not in use.



FIGS. 3,862 to 3,865.—The Economic calcium light; makes its own gas automatically from oxone and ether. Fig. 3,863 shows section view of interior of outfit. The parts are: M, main tank; L, cover for tank; G, gas bell or chamber; C, container for holding charge of oxone; R, wire rod for supporting container in position; O, needle valve controlling flow of oxygen gas direct to burner; H, needle valve controlling flow of gas through saturator S which causes ether vapor (hydro-carbon gas) to flow to burner; S, saturator; I, inlet connecting with nipple of needle valve H; F, filler plug; X, overflow; B, bottom cap of saturator; P, pastil; N, nozzle of burner.

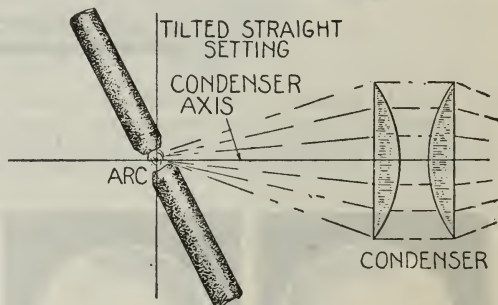
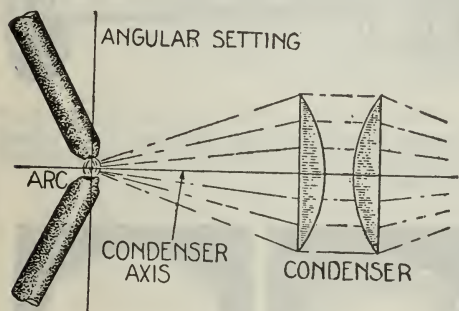
**Ques.** What are the characteristics of a long arc?

**Ans.** The crater is at less than maximum brilliancy and the current is reduced.

**Ques.** How is the feeding of the carbon gauged?

**Ans.** By observation through the peep hole in the lamp house, or by the sound produced by the arc.

**Auxiliary Apparatus.**—Various devices are necessary for the proper and safe control of the electric arc used in motion picture projection.



**FIG. 3,866.**—Arc setting for alternating current arc with cored carbons. When cored carbons are used, the crater will form in the end of the core, keeping in the center of the carbon pencil, and the vapor of the soft core will hold the arc between alternations. Without cored carbons, an alternating current arc has a tendency to run to the nearer edges of the carbons with loss of brilliancy upon the condensers.

**FIG. 3,867.**—Tilted straight setting for alternating current arc carbons. The lower carbon is placed a little ahead of the upper carbon. This tends to draw the crater of the upper carbon forward, thus improving the light on the condenser, but if the carbons be tilted too much the lower carbon will obstruct light from the lower part of the lens. The carbons must be in perfect alignment in a vertical plane, passing through the arc and axis of condenser.

Each installation will require proper fuses and switches in accordance with the Underwriters' regulations.

Rheostats are required with direct current to regulate the voltage so as to obtain best results with the arc. Rheostats should never be used on alternating current circuits for permanent installation as they are very wasteful in comparison with transformers.

On alternating current circuits when it is considered that the hand feed arc lamp used requires only about 30 to 35 volts, while the alternating current is supplied at from 104 to 250 volts, it is obvious that there is a large percentage of current wasted unless a transformer having a proper transformation ratio be used.



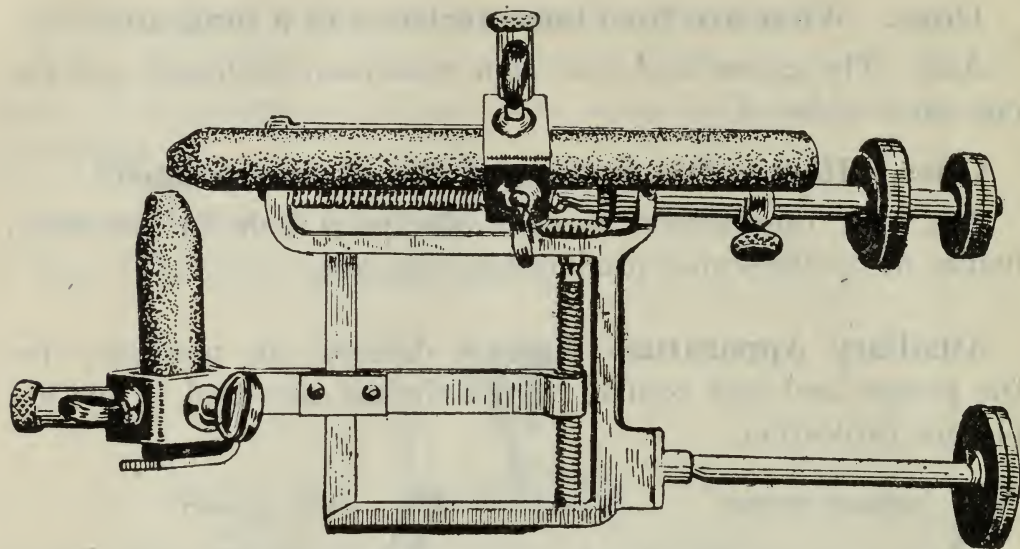
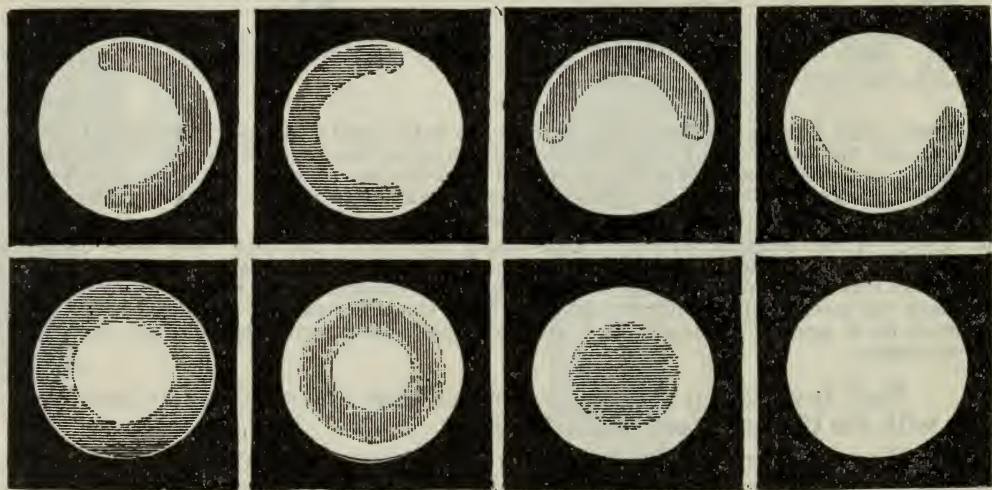


FIG. 3,868.—Ninety degree or right angle arc lamp. With the  $90^\circ$  setting, the arc can be kept nearer in line with the center of the lenses for a greater length of time, without re-adjusting the carbons, because of the horizontal carbon being placed in line with the principal optical axis and fed directly toward the center of the condenser.



FIGS. 3,869 to 3,876.—Bausch & Lomb diagrams illustrating the results of defective centering, that is, the shadows produced. **Successful results** in projection **depend largely** upon the correct adjustment of the lamp, which must throw a brilliantly illuminated circle upon the screen. After the objective is focused, as will be evidenced by a sharp, clear image on the screen, remove slide and slide holder, and examine the illuminated circle. If the light be centered and the lamp correctly adjusted, the circle will be entirely free from coloration or shadows. In figs. 3,869 and 3,870, the crater needs to be properly adjusted laterally, it being as shown too far to the right or left; figs. 3,871 and 3,872, show the crater too high or too low; in figs. 3,873 to 3,875, it is too near or too far from the condenser; fig. 3,876 shows it to be in correct position, the field being entirely clear.

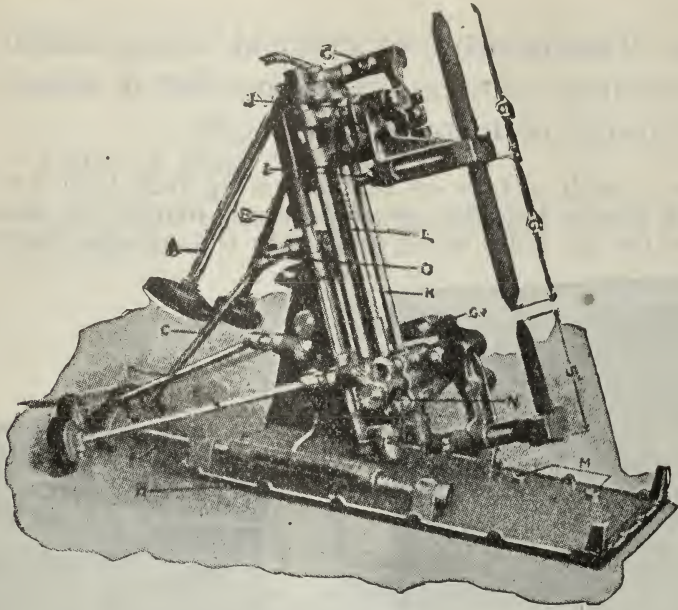


FIG. 3,877.—Simplex arc lamp. The carbon holders are furnished to accommodate carbons of  $\frac{1}{8}$ " to  $\frac{3}{4}$ " diameter and 12" upper and 6" lower in length, carrying capacity 75 amperes. There are eight adjustments, six being accessible from the back of the lamp house; and two, to alter the angle of the carbon, from the inside. The lamp can be withdrawn from the back of the lamp house, so that all parts are readily accessible.

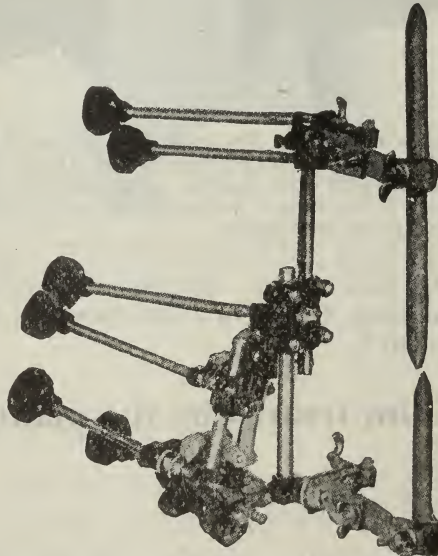
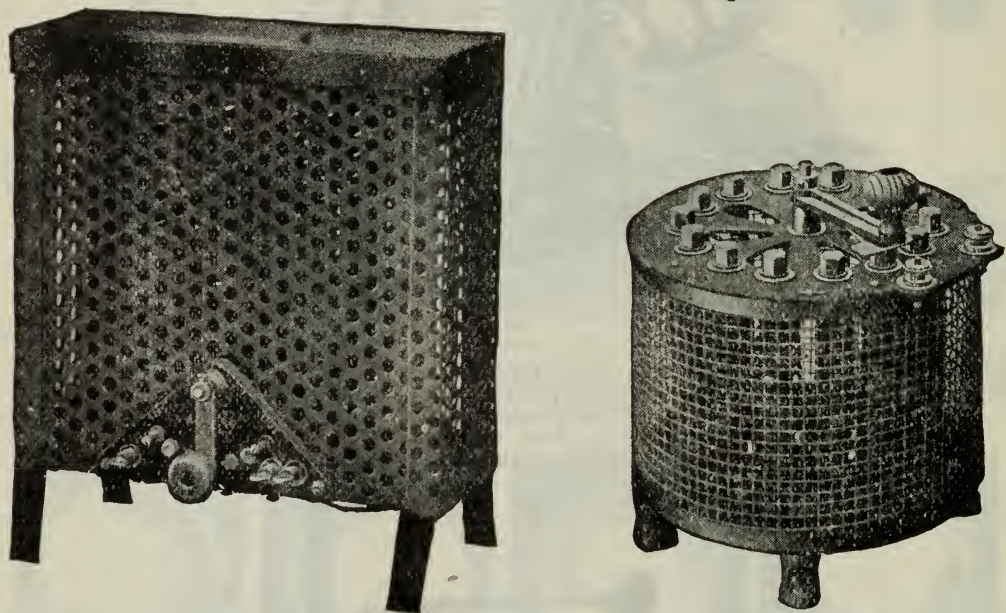


FIG. 3,878. Powers' arc lamp. Carrying capacity 100 amperes. All adjustments are accomplished from the outside of the lamp house. Carbon range from  $\frac{3}{8}$ " to  $\frac{3}{4}$ " in diameter, 6" length for lower and 12" length for upper carbon. The carbon may be placed at any angle desired, and can be moved independently of each other, forward, backward and sideways, or the whole lamp can be swung forward or backward, laterally, and up and down.



**The Film.**—This is made of celluloid, being similar to the film used in ordinary cameras, excepting that it comes in long strips, one thousand or more feet in length.

The size of each picture on the film is  $1\frac{1}{16}$  inch high by  $1\frac{5}{16}$  inch wide. The film is  $1\frac{3}{8}$  wide which leaves a margin on each side of the pictures for the holes which mesh with the sprocket teeth. These



FIGS. 3,879 and 3,880.—Powers' rheostats. The type shown in fig. 3,879 is designed for use on 110 volt circuits and will carry 25 amperes without overheating. The coils are so supported that any of them may be replaced when desired. Adjustment is effected by means of a lever switch. Fig. 3,880 shows Underwriters' pattern rheostat of 25 amperes capacity. It is designed for 110 volts and is not adjustable.

holes are about  $\frac{3}{16}$  inch apart. At present there is no standard as to the spacing of the holes, but as in other lines, the makers will sooner or later adopt a standard.

**Ques.** How is film treated by the manufacturer before shipment?

**Ans.** It is treated with glycerine.

This keeps the film pliable, and delays drying out.

**Ques.** What precaution should be taken with film?



Ans. Because of its inflammable character it must always be kept in fire proof enclosures.

**Ques. How is film repaired?**

Ans. Usually by cutting out the defective part and splicing the ends together.

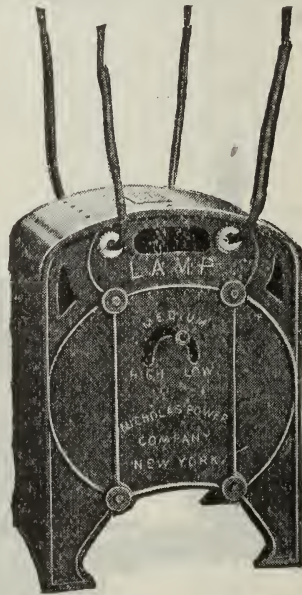
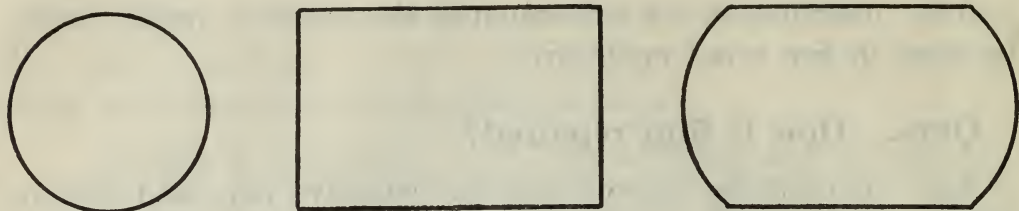


FIG. 3,881.—Powers' multi-tap transformer. It is without casing and is mounted on heavy legs which support it several inches above the floor. The numerous leads are properly marked as shown, to distinguish them.

**Ques. How is a splice made?**

Ans. Cut one end on the line between pictures and cut the other end with a quarter picture on; thus in cutting a film there will be three quarters of a picture cut out, a picture and three quarters, etc. Moisten the gelatine on the quarter picture and scrape it clean, also scrape the celluloid side of the other end



FIGS. 3,882 to 3,884.—Various film perforations. These are called: fig. 3,882, round; fig. 3,883, square; fig. 3,884, barrel. The square and barrel holes seem to be more durable than the round hole. The shape of the holes should correspond to the shape of the sprocket teeth. A standard perforation is four pairs of holes per picture, each hole being approximately  $\frac{1}{16} \times \frac{3}{32}$ , spaced along the edges of the film  $\frac{3}{16}$  inch apart, making four holes at each edge for a  $\frac{3}{4}$  inch motion picture image.

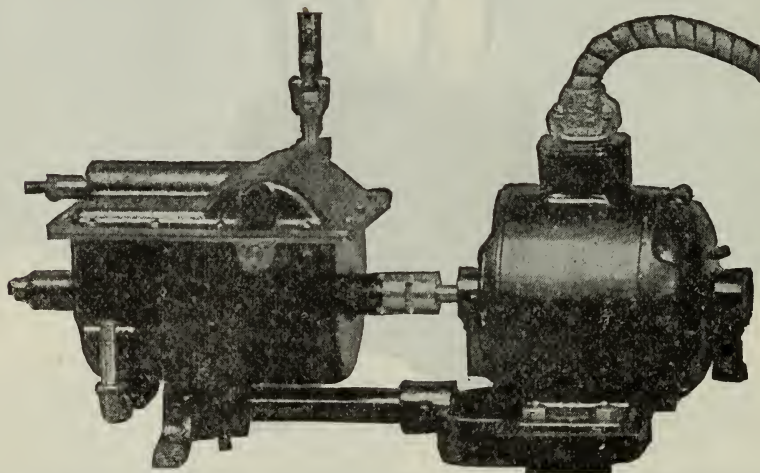


FIG. 3,885.—The arc controller or device designed to control the rate of feed of the carbons of an arc lamp, with the object of maintaining at all times a predetermined size of arc. **It consists** of the controller proper, direct coupled to a fractional horse power motor. There are two shafts, primary and secondary. The former, which is direct coupled to the motor, carries governor parts, and rotates constantly at the motor speed. The secondary, to which the telescope rod is geared, remains idle until the speed of the primary shaft exceeds the point of adjustment. The adjustment for any preferable size of arc is made with a brass adjusting nut upon a rod projecting from the cover of the controller. The inner end of the rod is connected through a heavy wire spring to a pawl, the function of which is to "step in" and transmit the power to the primary, through differential gearing to the secondary shaft, at the slightest tendency of the arc to become wider than the predetermined size adjusted for. The installation of the arc controller does not interfere with any of the lamp adjustments already provided. The operator may trim as he pleases, and feed by hand if he choose, by loosening a thumb screw at the feed handle gearing. Having loosened the thumb screw and trimmed the lamp, the operator strikes the arc by hand and makes the original and only feeding adjustment, by parting the carbons to the size of arc that he wishes to maintain; he then tightens thumb screw, and sets adjusting nut at the controller so that feeds do not occur below that size; the controller will then feed the carbons to that certain size of arc without further attention. To increase size of arc, tighten adjusting nut; to decrease size, loosen nut.

clean. Spread cement on the cleaned quarter picture space and fit it on the back of the other end, sticking the two ends together with the picture lines matching and the sprocket holes matching. Cut either through a sprocket hole or midway between sprocket holes straight across the film.

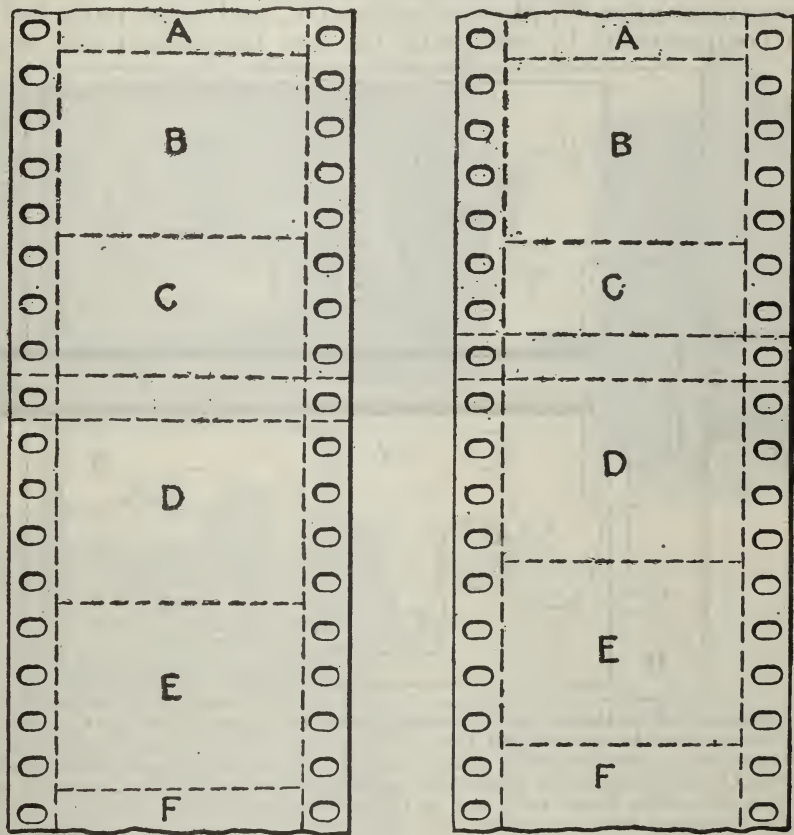


FIG. 3,886.—Splice, in frame. The picture C has four holes at the side, just as have the pictures A, B, D, E, etc., and when that film is passed through the film gate and intermittent mechanism, the framing will be preserved, because mechanically the film is the same in distribution of pictures and of sprocket holes as though no splice had been made. The difference is found in the "jump" of the pictures when one or more pictures have been omitted, but the "frame" will not be disturbed as the splice passes.

FIG. 3,887.—Splice out of frame. The picture C has but three holes at the side. Hence, when the picture B is pulled out of the film window and C is pulled in, the intermittent sprocket pulling down four holes will pull into the film window the three-quarter picture C, and also the top quarter of the whole picture D. At the next shift, the intermittent sprocket pulls down another four holes, pulling into the film window the remaining three-quarters of D, and the top quarter of E, etc. This continues until the operator notices the screen and frames with his lever. This is called a splice "out of frame" because the splice throws the picture out of frame in passing.



**Motion Picture Cameras.**—Apparatus for taking motion pictures differs in many ways from ordinary cameras. Fig. 3,888 is a diagram showing the essential parts of a motion picture camera.

There are three compartments: 1, a front compartment U containing a rotating shutter N, pin mechanism OP, and other parts not shown; 2, a compartment V, containing the film mechanism and magazines,

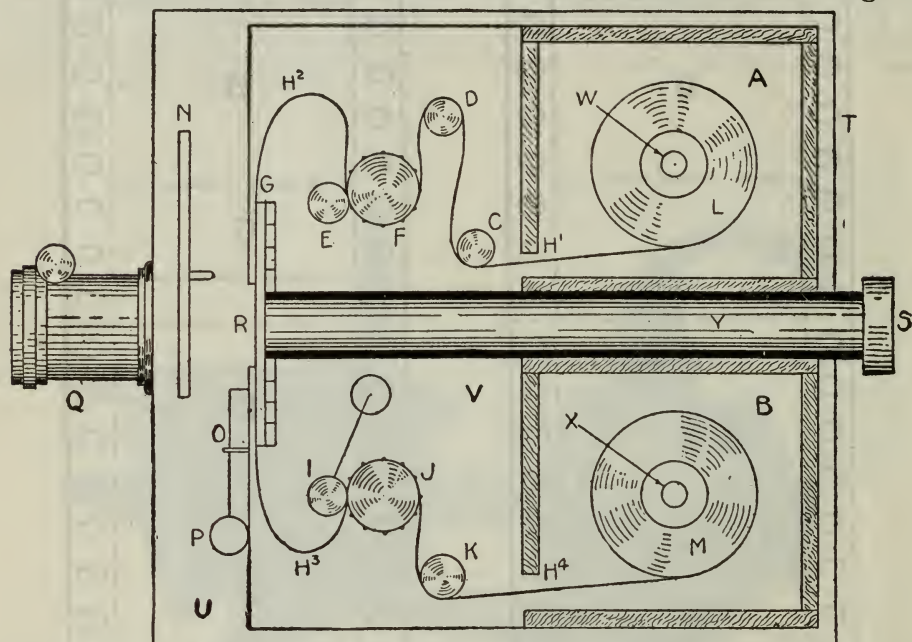


FIG. 3,888.—Diagram of motion picture camera showing the essential parts. Cameras are built for various numbers of picture per turn of the crank; four, six, and eight are common. An eight picture camera should be run at a speed of almost one hundred turns per minute. To operate at this speed, get a watch ticking 300 ticks per minute and learn to count one, two, three; one, two, three, etc., just as fast as the watch ticks, turning the crank one revolution for every one, two, three counted; that is to say, one revolution per every three ticks of the watch.

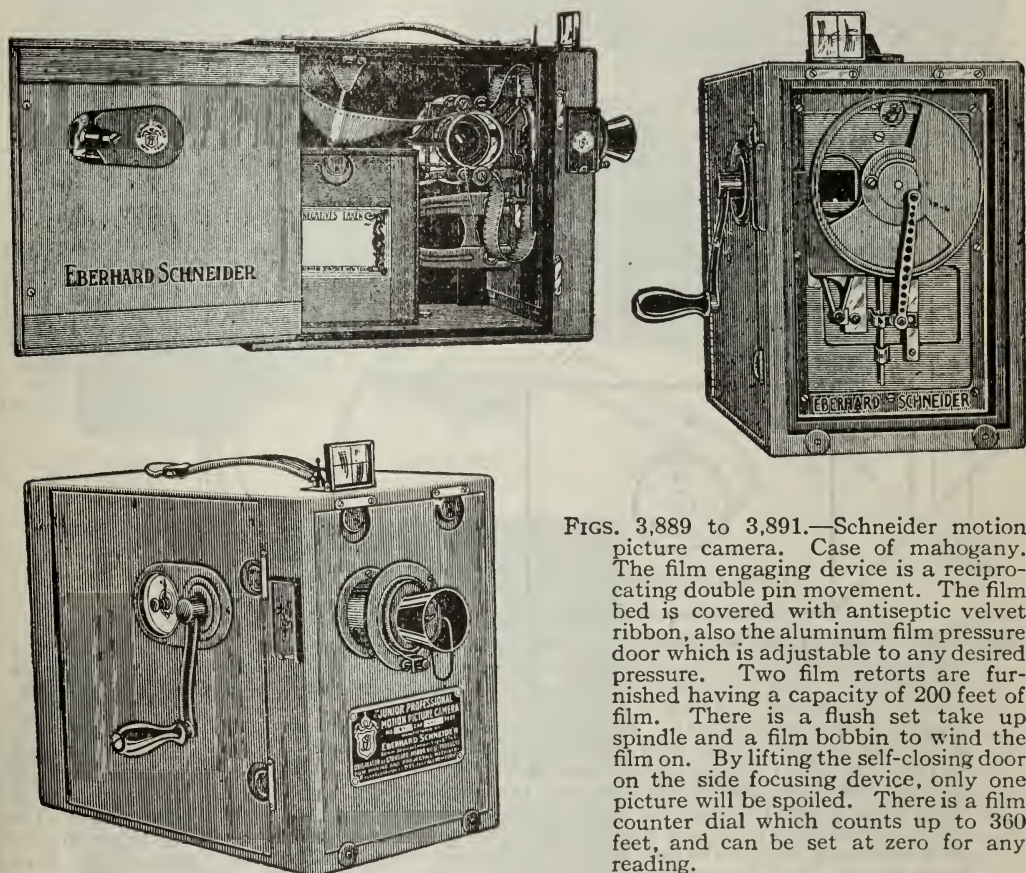
and 3, a compartment on the opposite side containing mechanism communicating with the spools in the magazines, with the sprocket wheels, and the points in the first compartment.

The two magazines A, B, consisting of light boxes, fit into the back portion, and carry reels, W, X, on which the film is wound.

**In operation,** the roll of unexposed film L, which passes out of a small aperture H¹ at the corner of the top magazine A, around guide rollers C, D, engages by its perforations with the sprocket wheel F, to which it is kept by the roller E. The film forms a loop at H² and passes downward through the guide grooves made in the gate G.

Continuing, it passes out past the bottom of the gate, forming a second loop  $H^3$ , and then passes between a spring roller I and sprocket J, under the guide roller K, and enters at  $H^4$  the lower magazine B when it is wound up on the bobbin X.

The sprocket wheels rotate continuously drawing the film from the supply at L and taking it up at M.



FIGS. 3,889 to 3,891.—Schneider motion picture camera. Case of mahogany. The film engaging device is a reciprocating double pin movement. The film bed is covered with antiseptic velvet ribbon, also the aluminum film pressure door which is adjustable to any desired pressure. Two film retorts are furnished having a capacity of 200 feet of film. There is a flush set take up spindle and a film bobbin to wind the film on. By lifting the self-closing door on the side focusing device, only one picture will be spoiled. There is a film counter dial which counts up to 360 feet, and can be set at zero for any reading.

The motion of the film in the gate G, however, is intermittent. During the period of rest, a surplus loop of film forms at  $H^2$ , which is then pulled down through the gate by the action of the pin O, engaging with the perforations.

The whole mechanism is so arranged and geared together that, while the film is being shifted, the light is excluded from the lens, and admitted during the stationary periods.



A long tube V extends through the center of the camera, and is provided with a detachable cap at S. This tube forms the sight hole for inspecting the image on the film, prior to exposure.

The gate G is a kind of hinged door with an aperture in it, and its function is to keep the film flat and vertical during exposure and also to act as a channel or guide.

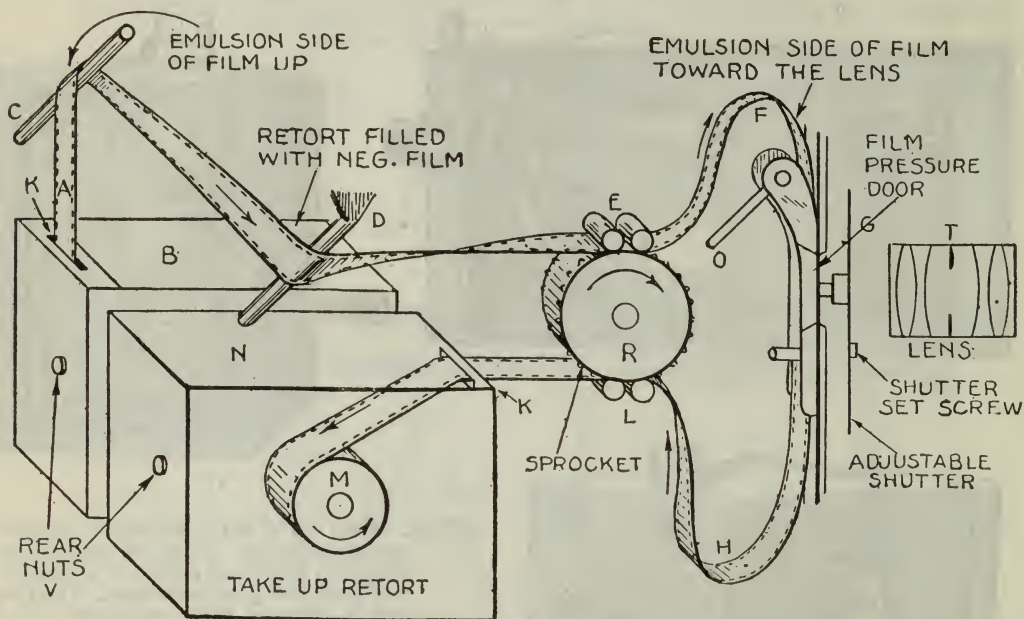
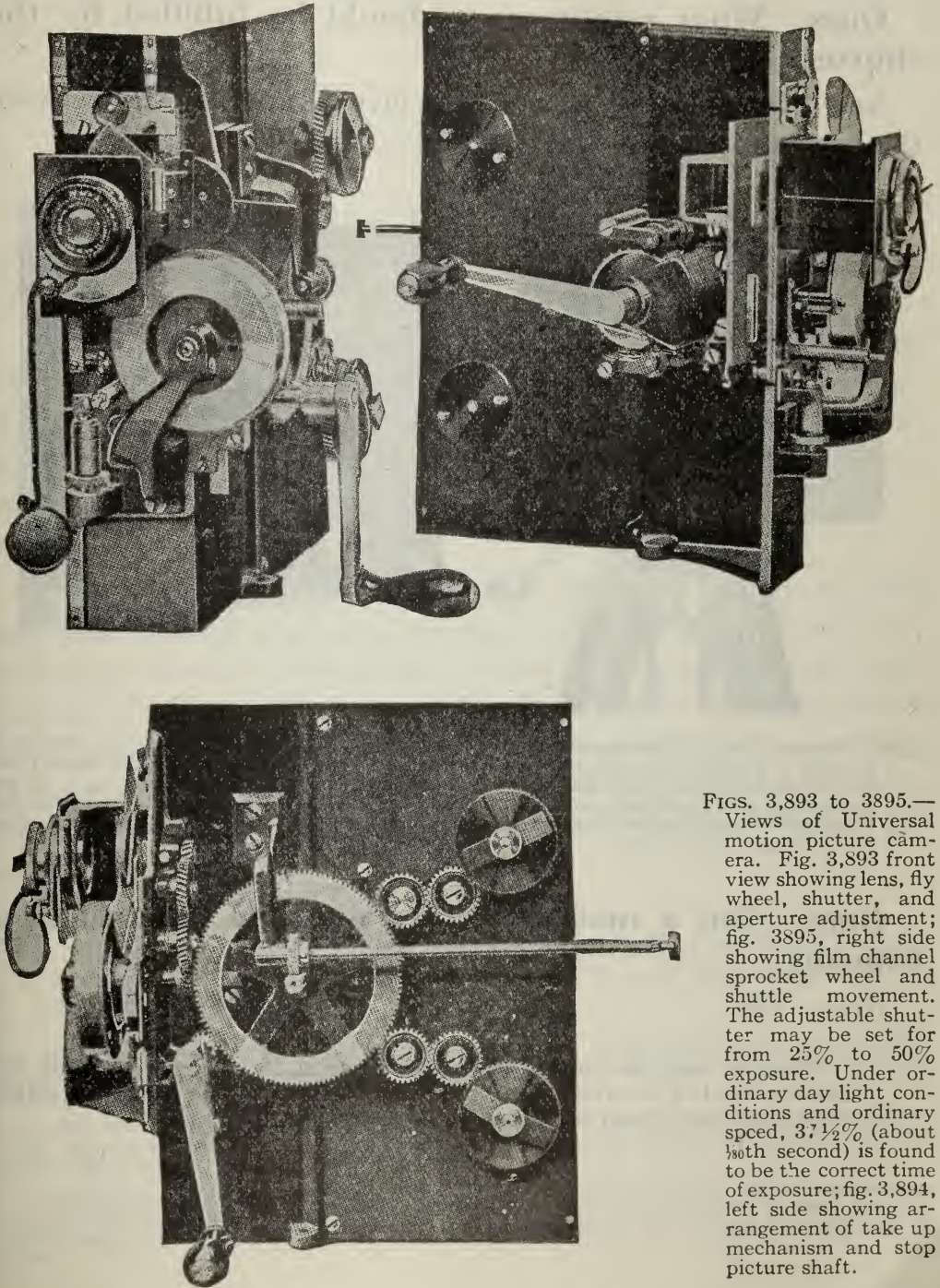


FIG. 3,892.—How to use the Schneider camera. Open the doors on both sides of the camera by opening locks, fill retort B in dark room with perforated, sensitive negative film A of reliable manufacture, close cover and secure retort B, with nut, screw V into the camera box; lead film A through film gate K of retort B in a way that the emulsion side of film will be **up** in passing over guide roller C. Now lead the film under guide roller D so the emulsion side of the film will lay against this roller D, then lead the film over the sprocket R under the two film pressure rollers E and be sure that the teeth engage the holes in the film and not between the holes, also make sure that the film lays straight over the large sprocket R make a few turns of the sprocket to obtain more slack of film, lift pressure door G with the ring finger of right hand and place the film straight into the aperture track, leave enough slack for loop F and let the door go, but make sure that the door presses on the film. Now leave enough slack for under loop H and pass the film between sprocket and pressure rollers L through retort gate K on to bobbin M of retort N. Make another turn of sprocket R and see that the film is guided properly between all members and that the loops are there and that bobbin M takes up the film. Place the cover on retort N and fasten same into the rear wall by rear nuts V, close all camera doors and **set the film counter to zero**. The camera has either a fixed or an adjustable focus lens (the latter preferred) either lens has a diaphragm. The camera can be focused for either the inside or outside.

**After taking a subject**, the operator presses a button, and in so doing punches a hole in the film at a point just above the gate, thus indicating the end of the subject and beginning of the next subject.



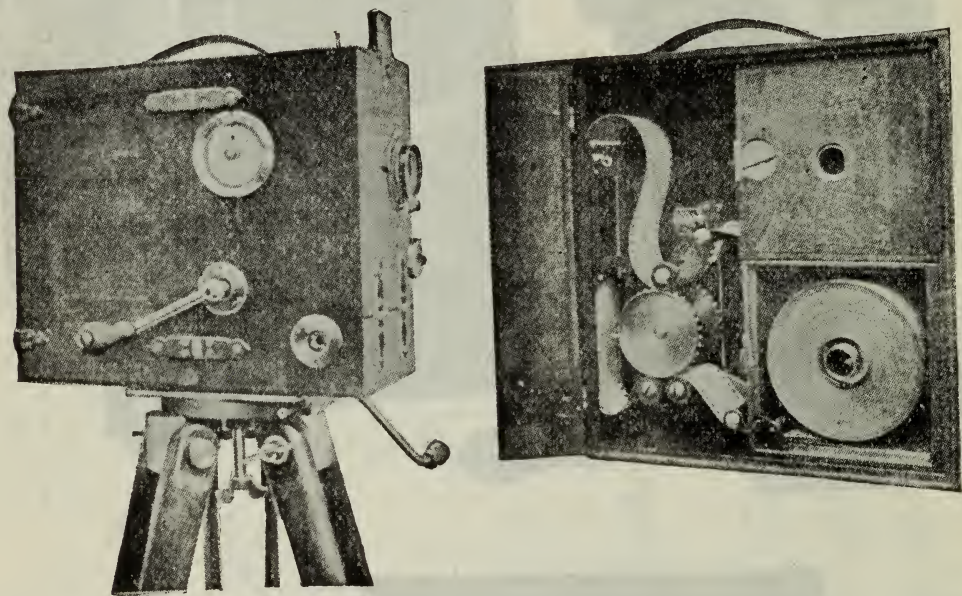


FIGS. 3,893 to 3,895.—

Views of Universal motion picture camera. Fig. 3,893 front view showing lens, fly wheel, shutter, and aperture adjustment; fig. 3,895, right side showing film channel sprocket wheel and shuttle movement. The adjustable shutter may be set for from 25% to 50% exposure. Under ordinary day light conditions and ordinary speed,  $37\frac{1}{2}\%$  (about  $\frac{1}{80}$ th second) is found to be the correct time of exposure; fig. 3,894, left side showing arrangement of take up mechanism and stop picture shaft.

**Ques.** What requirement should be fulfilled by the shutter?

**Ans.** It should be adjustable to give a variable ratio between the open time and closed time.



FIGS. 3,896 and 3,897.—Exterior and interior views of Angelus motion picture camera. The frame is made of pressed steel with table bronze bearings, claw movement is of the finger type, counterbalanced, and feeds film forward or backward equally well. Take up is of the pulley type with spring belt and adjustable tension; takes up in both directions, forward or backward. Punch or film marker is placed on one side so as to notch edge of film instead of punching hole in center.

**Ques.** Can a motion picture machine be used as a camera?

**Ans.** Yes.

Pictures may be taken by constructing a light tight box for the motion head of the machine. Such an arrangement is, however, rather bulky in comparison to a regular motion picture camera.



## CHAPTER LXXV

## GAS ENGINE IGNITION

Most treatises on ignition begin with an explanation of electrical principles and considerable space is thus taken up, which, if confined to the main subject, would be of greater value to the reader, assuming that he either has an elementary knowledge of electricity, or that he will acquire this knowledge elsewhere.

The author especially recommends that the reader at least acquaint himself with fundamental electrical principles before taking up the study of ignition, so that he can, with greater ease, become familiar with the working principles of the multiplicity of ignition apparatus now in use. This preliminary knowledge may be obtained by consulting the preceding Guides, however, for convenience, a summary or condensed outline of elementary electricity is here given.

**Electricity.**—The name electricity is applied to an invisible agent known only by the effects which it produces, and the various ways in which it manifests itself.

Electrical *currents* are said to flow through *conductors*. These offer more or less *resistance* to the flow, depending on the material. Copper wire is generally used as it offers little resistance to the flow of the current.

The current must have pressure to overcome the resistance of the conductor and flow. This pressure is called *voltage* caused by what is known as *difference of pressure* between the source and terminal.

An electric current has often been compared to water flowing through a pipe. The pressure under which the current flows is measured in *volts* and the quantity that passes in *amperes*. The resistance with which the current meets in flowing along the conductor is measured in *ohms*.



The flow of the current is proportional to the voltage and inversely proportional to the resistance. The latter depends upon the material, length and diameter of the conductor.

Since the current will always flow along the path of least resistance it must be so guarded that there will be no leakage. Hence to prevent leakage, wires are *insulated*, that is, covered by wrapping them with cotton or silk thread or other non-conducting materials. If the insulation be not effective, the current may leak, and so return to the source without doing its work. This is known as a *short circuit*.

The conductor which receives the current from the source is called the *lead* and the one by which it flows back, the *return*.

When wires are used for both lead and return, it is called a *metallic circuit*; when the metal of the engine is used for the return, it is called a *grounded circuit*, the term originating in telegraphy, where the earth is used for the return.

In ignition diagrams, then, the expression "to ground" means *to the metal of the engine*.

An electric current may do work of various kinds, but the one property which makes it available for ignition is the fact that whenever its motion is stopped by interposing a resistance, the energy of its flow is converted into heat. In practice this is accomplished in two ways: 1, by suddenly breaking a circuit; 2, by placing in the circuit a permanent *air gap* which the current must jump. In either case, the intense heat caused by the enormous resistance interposed, produces a spark which is utilized to ignite the charge. The first method is known as the *make and break* or *low tension* and the second, the *jump spark* or *high tension*.

An electric current is said to be: 1, *direct*, when it is of unvarying direction; 2, *alternating*, when it flows rapidly to and fro in opposite directions; 3, *primary*, when it comes directly from the source; 4, *secondary*, when the voltage and amperage of a primary current have been changed by an *induction coil*.

A current is spoken of as *low tension*, or *high tension*, according as the voltage is low or high.

A **high tension current** is capable of forcing its way against considerable resistance, whereas, a **low tension current** must have its path made easy. A continuous metal path is an easy one, but an interruption in the metal, as, the permanent air gap of a spark plug, is difficult to bridge, because air is a very poor conductor. Air is such a poor conductor that it is usually, though erroneously, spoken of as a *non-conductor*; it is properly an insulator.

The low tension current is only able to produce a spark when parts are provided in the path, so arranged that they may be in contact and then suddenly separated. The low tension current will, as the separation occurs, tear off very small metallic particles and use these as a bridge to keep the path complete. Such a bridge is called an *arc*, the heat of which is used for ignition.

**Magnetism.**—The ancients applied the word "magnet," *magnes lapes*, to certain hard black stones which possess the property of attracting small pieces of iron, and as discovered later, to have the still more remarkable property of pointing north and south when hung up by a string; at this time the magnet received the name *lodestone*. The automobile word *magneto* is derived, as may easily be understood, from the word *magnet*.

Magnets have two opposite kinds of magnetism or magnetic poles, which attract or repel each other in much the same way as would two opposite kinds of electrification.

One of these kinds of magnetism has a tendency to move toward the north and the other, toward the south.

The two regions, in which the magnetic property is strongest, are called the *poles*. In a long shaped magnet it resides in the ends, while all around the magnet half way between the poles there is no attraction at all. The poles of a magnet are usually spoken of as *north pole* and *south pole*.

When a current of electricity passes through a wire, a certain change is produced in the surrounding space producing what is known as a *magnetic field*.

If the wire be insulated with a covering and coiled around a soft iron rod, it becomes an electromagnet having a north and south pole, *so long as the current continues to flow*. The magnetic strength increases with the number of turn of the coil, for each turn adds its magnetic field to that of the other turns.

**Induction.**—If a second coil of wire be wound around the coil of an electromagnet, but not touching it, an *induced current* is produced in this second coil by what is known as *induction*, each time the current in the inside coil begins or ceases flowing. The inside coil is called the *primary winding* and the outside coil the *secondary winding*. Similarly, the current passing through the inside coil is called the *primary current* and that in the outside coil the *secondary* or *induced current*.

It has been found that by varying the ratio of the number of turn in the two coils, the ratio of voltage of the two currents is changed approximately proportionately. That is, if the primary winding be composed of ten turns and the secondary, of one hundred, the voltage of the secondary current is increased approximately ten times that of the primary. This principle is employed to produce the extremely high tension current necessary with the jump spark method of ignition.

**Methods of Producing Electricity.**—Currents are produced by, 1, chemical, and 2, mechanical means. In the first method, two dissimilar metals such as copper and zinc called *electrodes* are immersed in an exciting fluid or *dielectric*. When the electrodes are connected at their terminals by a wire or conductor, a chemical action takes place, producing a current which flows in the external circuit from the copper to the zinc. This device is called a *cell*, and the combination of two or more of them connected so as to form a unit, is known as a *battery*.

The word battery is frequently used *incorrectly* for a single cell. That terminal of the copper electrode from which the current flows is called a *plus* or *positive pole* and the zinc electrode terminal a *negative pole*. It should be carefully noted, however, that the copper electrode itself is negative and the zinc electrode, positive.

Cells are said to be *primary* or *secondary* according as they generate a current of themselves or first require to be charged from an external source, storing up a current supply which is afterwards yielded in the reverse direction to that of the charging current.

There are two methods of producing an electric current by mechanical means, 1, by a *dynamo*, and 2, by a *magneto*. A dynamo has an *electromagnet* which is known as a *field magnet* to produce a *magnetic field* and an armature which when revolved in the magnetic field develops electric current. A magneto has a permanent magnet to produce the magnetic field and an armature which is usually arranged to revolve between the poles of the magnet.

The basic principles upon which dynamos and magnetos operate are the same.

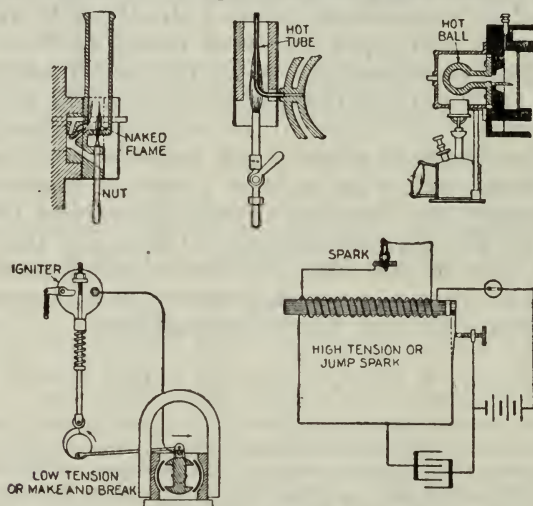
Magnetos are divided into two classes, 1, *low tension*, and 2, *high tension* according as they generate a current of low or high voltage. Low tension magnetos are used for make and break ignition and the high tension type for the jump spark system. There are numerous so called high tension magnetos on the market each consisting of a low tension magneto in combination with a secondary induction coil used to produce a high tension spark.

**Ignition.**—A thorough knowledge of ignition is of prime importance to any operator of a gas engine, whether it be stationary, marine, or automobile type. Many of the troubles still encountered, notwithstanding numerous improvements, have arisen from failure of the ignition system to perform its proper function. The engine may operate with an imperfect



fuel mixture, if the ignition system be in working order, but any defect in the latter will in nearly every case cause the engine to misfire or stop.

Numerous devices have been tried to fire the charge in gas engines. In the early days, a flame behind a shutter was used, the latter being opened at the proper moment. Sometimes the flame was blown out by a too violent explosion, so this method gave way to a porcelain tube that was kept at white heat by an interior flame. Tube being subject to breakage, spongy platinum, heated by compression, was next tried and found to work, if not too moist from watery vapor in the gas mixture, or if the engine speed were not too high. Electricity is now universally used. Hence, in order to gain an understanding of ignition principles,



FIGS. 3,898 to 3,902.—Various methods of ignition. Fig. 3,898, naked flame; fig. 3,899, hot tube; fig. 3,900, hot ball; fig. 3,901, low tension electric or make and break; fig. 3,902, high tension electric or jump spark.

it is necessary to have at least an elementary knowledge of electricity, as previously mentioned, and because of which, the preceding electrical introduction will be found of value.

**Methods of Ignition.**—The charge in the cylinder of a gas engine may be ignited in several ways, as

1. By means of a naked flame;
2. By means of a highly heated metallic surface;
3. By an electric spark;
4. By the heat of very high compression.



The naked flame is practically obsolete, and the hot surface or hot tube is used to a very limited extent, except in the case of some types of oil engine. Many builders of standard engine, however, are prepared to furnish hot tube ignition.

**Point of Ignition.**—The “timing” or selection of the point of the stroke at which ignition shall take place is an important factor in the application of any method.

Obviously the amount of “advance,” that is to say, the pre-dead center angular position of the crank selected for firing the charge, will vary in different types of engine and in the same engine under different

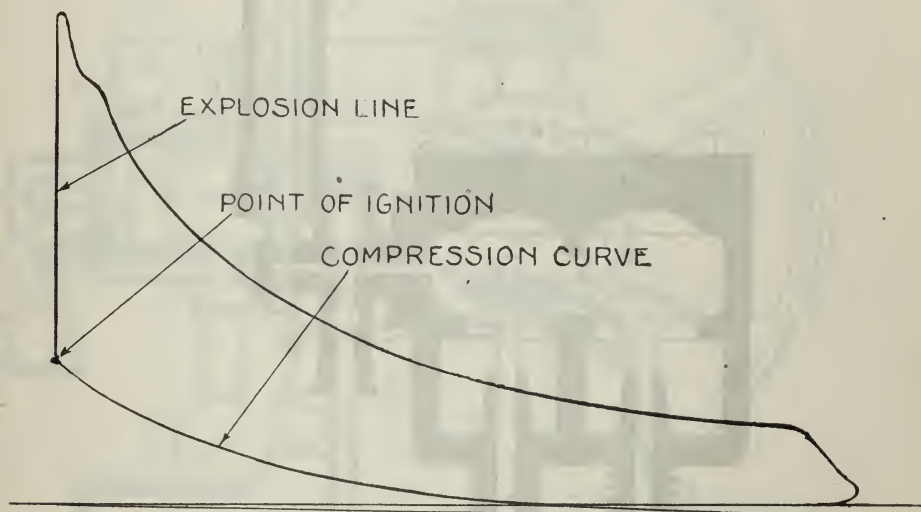


FIG. 3,903.—Indicator card for gas engine illustrating the “*point of ignition*”. It will be noted that compression continued to the end of the stroke, before the compression curve made an abrupt change into a nearly vertical line, the point of ignition, that is, the piston position at the instant of the spark, the nearly vertical “explosion” line with the high peak coming almost to a point, denotes a strong mixture and a quick explosion.

running conditions; thus, noting that there is an appreciable time interval between the spark and the maximum pressure of combustion, it is clear that the spark should be advanced more for an engine running at high speed than for one running at low speed.

**Ques.** In general how much should the spark be advanced?

**Ans.** As much as possible, consistent with smooth running and economy.

### Ques. Why?

Ans. In order that the temperature at release, that is to say, when exhaust begins, should not be high enough to injure the exhaust valves.

If more attention were paid to this, especially by automobilists, there would not be the need for such frequent grinding of the exhaust valves.

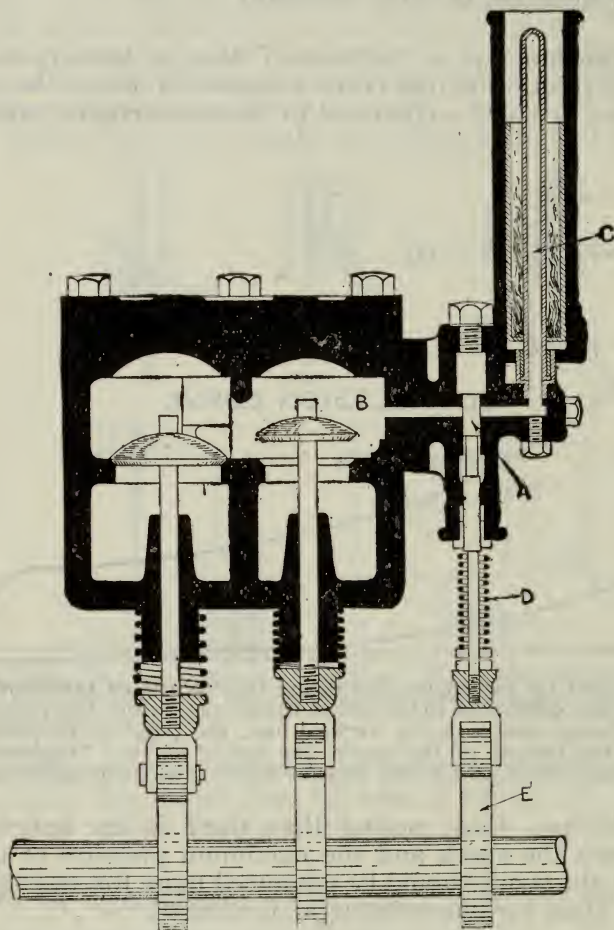


FIG. 3,904.—Sectional view through valves of engine showing hot tube method of ignition. This is a modification of the method described in the accompanying text and is more exact and satisfactory. *In construction*, a valve A, commonly called the timing valve, is provided, and which is interposed between the admission valve chamber B (communicating with the clearance space of the cylinder) and the interior of the hot tube C. This valve is normally held closed by the spring D. When the piston reaches its inner dead point at the end of the compression stroke, a cam E, on the secondary shaft, opens the valve and allows a portion of the compressed charge to pass into the hot tube where it ignites. The timing valve is held open throughout the power and exhaust strokes, thus permitting the products of combustion to be carried out of the tube with the exhaust.

**Hot Tube Ignition.**—This method consists of a short tube of metal or porcelain which is maintained at a dull red heat by contact with a gas flame, and which is attached to the engine cylinder in such a manner that a portion of the explosive charge is forced into it, this, being ignited by contact with the hot walls of the tube, ignites the whole charge.

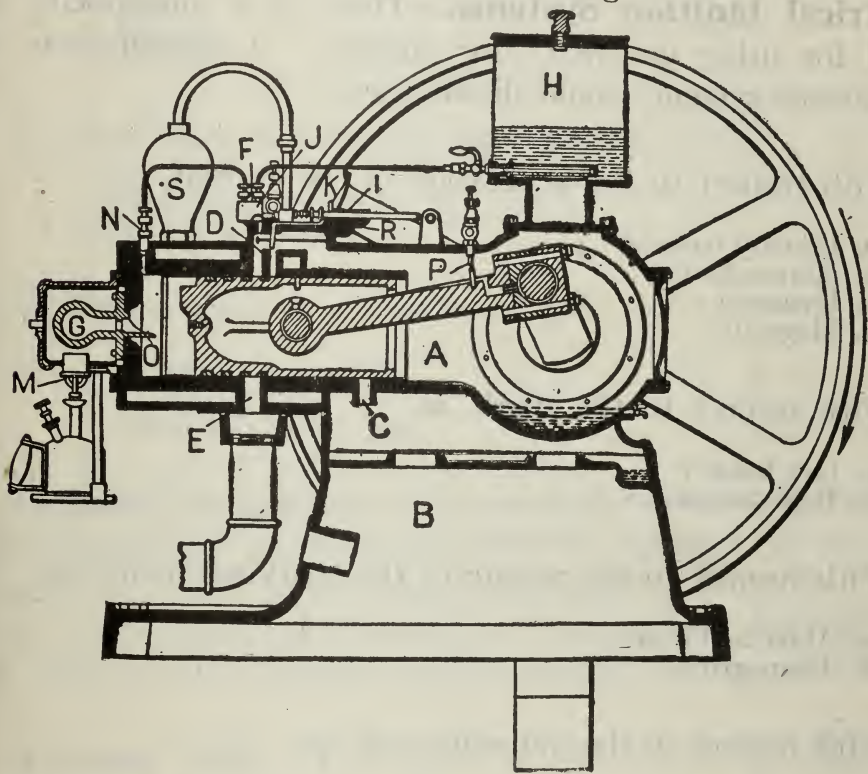


FIG. 3,905.—Meitz and Weiss two cycle oil engine with hot ball igniter. *In operation*, air is drawn into the closed crank chamber A, from the interior of the base B, through the part C, in the lower part of the cylinder. On the outward stroke of the piston, this air is compressed, and the opening of a port D, by the piston, allows the air, together with the steam generated in the water jacket, to pass into the combustion space of the cylinder. At the same time, the exhaust port E, having been overrun, and thus opened by the piston, discharges the products of combustion of the previous charge into the exhaust pipe. The fuel is injected into the cylinder by the pump F, and mixes with the air and steam previously admitted from the crank chamber, so that on the compression stroke, the charge is automatically ignited by contact with the heated walls of the hollow igniter ball G. This ball, made of cast iron, is located in the projection attached to the cylinder head, as shown. A charge is compressed at every revolution of the crank shaft, and compressed by the piston into the compression space of the cylinder and the interior of the igniter ball where it is ignited. *Before starting*, the igniter ball is heated for a few minutes by a small oil burner M. The oil jet from the injection nozzle N, strikes the projection O, extending from the igniter ball and is sprayed, vaporized and mixed with the air and steam in the compression space. The igniter ball is maintained at a dull red heat by the heat of the explosives.



In the ordinary arrangement, the time of ignition depends upon the degree of compression. The products of combustion remain in the tube and mix with the succeeding fresh charge, so that varying degrees of compression cause ignition at different points of the piston stroke or cycle of operation. Under these conditions, the moment of ignition becomes later and later as the amount of compression decreases, until the compression becomes so weak as to produce failure to ignite.

**Electrical Ignition Systems.**—There is a multiplicity of method for using electricity for ignition. A classification of these various system, would divide them

1. With respect to the generation of the current, as
  - a. Primary battery;
  - b. Storage battery;
  - c. Dynamo;
  - d. Magneto.
2. With respect to the spark, as
  - a. Low tension;
  - b. High tension.
3. With respect to the nature of the sparking device, as
  - a. Make and break;
  - b. Jump spark.
4. With respect to the induction coil, as
  - a. Primary coil;
  - b. Secondary coil { multi-coil;  
single coil (*synchronous ignition*).
5. With respect to the primary circuit control, as
  - a. Contact maker;
  - b. Contact breaker;
  - c. Mechanical vibrator;
  - d. Magnetic vibrator { individual vibrator;  
master vibrator.

6. With respect to the magneto, as
  - a. Low tension;
  - b. So called high tension;
  - c. True high tension.
7. With respect to extra or duplicate apparatus, as
  - a. Dual;
  - b. Duplex;
  - c. Double.
8. With respect to circuit arrangement, as
  - a. One wire (grounded);
  - b. Two wire (metallic).
9. With respect to special spark plug construction, as
  - a. Magnetic spark plug;
  - b. Coil spark plug;
  - c. Multi-point spark plug.

**Current for Ignition.**—The electric current used for igniting the charge may be produced either by chemical, or mechanical means, or it may be generated mechanically and stored chemically. The apparatus required for these various methods consist of primary and secondary cells, dynamos and magnetos.

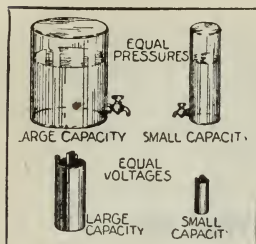
**Primary Cells.**—Two types of cell are in general use for ignition, namely, liquid cells and the so called dry cells.

Liquid cells are used extensively for stationary engines and for some classes of marine work.

In purchasing a set of wet cell, the following points should be noted:

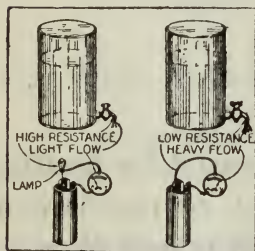
1. They should be substantial and constructed so that the chemicals will not creep over the edge of the jar or evaporate;
2. They should be slop proof and all renewals required should be easily obtainable.

When space allows and first cost is not of great importance, wet cells give excellent service. The advantage of these cells is that they give



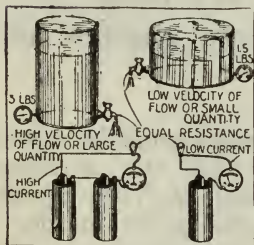
FIGS. 3,906 to 3,909.—*Hydraulic analogy of capacity.* Figs. 3,906 and 3,907 show two tanks of water of different sizes (capacities). The head of water is the same in each and consequently the pressure in the stop cock is the same in each, irrespective of the fact that they are of different capacities. The two dry cells shown have the same voltage even though they are of different size. The difference in size, however, means that they contain different amounts of electricity. The voltage of a dry cell does not depend on its size. It is about 1.5 volts

FIGS. 3,910 to 3,913.—*Hydraulic analogy of pressure.* Fig. 3,910 shows three tanks connected in *series*. The total head and therefore, the pressure on the stop cock is three times that of a single tank. When three cells are connected in *series*, as in fig. 3,911, the terminal voltage is increased three times, in a like manner. Fig. 3,912 shows three tanks connected in parallel. Here the pressure is the same as if there were only one tank. When three cells are connected in *parallel*, as in fig. 3,913, the *voltage* remains the same as that of a single cell.



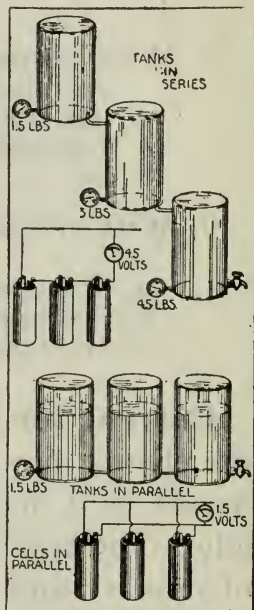
FIGS. 3,914 to 3,917.—*Hydraulic analogy of resistance.* Figs. 3,914 and 3,915 show two tanks, having equal depths of water, and consequently equal pressures in the discharge cocks. The left tank has a small cock (*high resistance*) and the other has a large cock (*low resistance*). It is obvious that the flow from the first will be less than the flow from the second. In an analogous manner it may be seen that the two dry cell circuits have equal voltages

applied and that the circuit of high resistance, (fig. 3,916), permits less current to flow than does the circuit of low resistance, fig. 3,917. It is apparent that both these conditions show the current to depend on the voltage and resistance, in accordance with Ohm's law.



FIGS. 3,918 to 3,921.—*Hydraulic analogy of current.* Figs. 3,918 and 3,919 show two tanks with discharge cocks of the same size (*equal resistances*). Obviously the higher pressure in tank fig. 3,918 will cause a greater flow through its cock than will the low pressure in tank, fig. 3,919. The analogous electrical condition is shown in figs. 3,920 and 3,921. Assuming the *internal* resistance of each cell to be zero and each circuit to have an equal external resistance, the current in fig. 3,920 will be two times stronger than in fig. 3,921. **It should be noted** that in an actual circuit the *internal* resistance of the cells must be considered. Thus, an ammeter connected across the end terminals of the cells in figs. 3,920

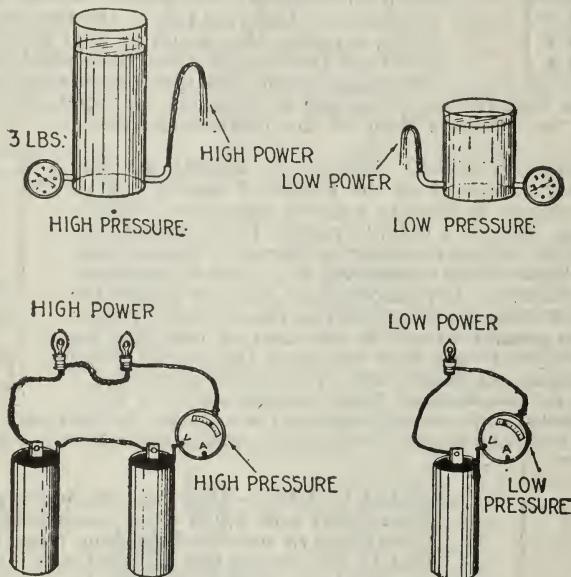
and 3,921 will give the same reading because the internal resistance of a battery of cells in series increases in proportion to the number of cell.





constant current, moreover the liquid or electrolyte may be renewed so that it is not necessary to buy a new battery when it becomes exhausted.

**“Dry” Cells.**—The so called dry cell consists usually of a carbon and zinc element immersed in moistened salts.



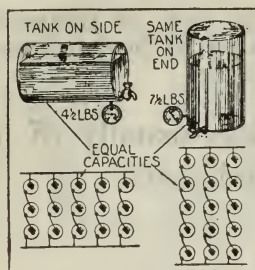
FIGS. 3,922 to 3,925.—*Hydraulic analogy of power.* Figs. 3,922 and 3,923 show two tanks with equal flows at different pressures. In both, the same number of pound of water is discharged per second, but in the high pressure tank this amount is lifted higher than in the low pressure tank, and consequently the first jet has more *power*, because it raises the same amount of water higher in the same time. Power, accordingly, increases with pressure, as well as with flow. The electrical case is analogous. In fig. 3,924, the circuit has 3 volts applied to two  $1\frac{1}{2}$  ohm lamps, thus, according to Ohm's law, one ampere is flowing. Fig. 3,925 shows a circuit having  $1\frac{1}{2}$  volts applied to one  $1\frac{1}{2}$  ohm lamp so that here also one ampere is flowing. The candle power, however, of the two lamps in fig. 3,924 is two times that of the lamp in fig. 3,925.

For full description of dry cell and points relating to same, see Guide No. 1.

Since the gasoline engine has come into prominence and the demand for an efficient, reliable and inexpensive source of current supply has been created, the dry cell has been brought to a high state of efficiency.

An ammeter test should be made of each dry cell before purchasing. The ignition size cell should test at least 25 amperes; to avoid waste of current, make the ammeter test as quickly as possible.

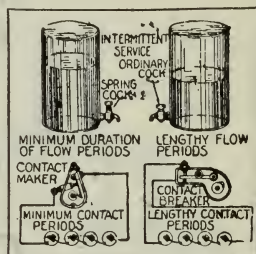
**Points Relating to Primary Cells.**—In order to obtain satisfactory results in battery systems of ignition, the following suggestions should be carefully noted and followed:



same way, if the batteries be discharged to the same end point, more unavailable energy will remain in the left-hand than in the right-hand battery.

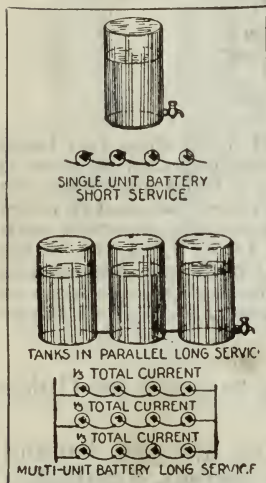
FIGS. 3,930 to 3,933.—*Hydraulic analogy of useful service.*

Service is usually expressed as the length of time a cell or battery will continue to operate a given apparatus, that is until the voltage falls to a definite value. It is evident that with a lower cut off voltage more current can be obtained, just as lowering the limit of the water level in a tank allows more water to be withdrawn. It is also evident that the lighter the flow from a given tank, the longer will be the service. This is true to an even greater extent in the case of dry cells on account of the characteristic that the lower the current drain the greater becomes the useful life. The length of service is increased, then, for two reasons; first, because energy is withdrawn more slowly, and second, because the capacity is increased. Thus, if the current drain be cut in half, the length of the service will be considerably increased.



FIGS. 3,934 to 3,937.—*Hydraulic analogy of parallel connection.*

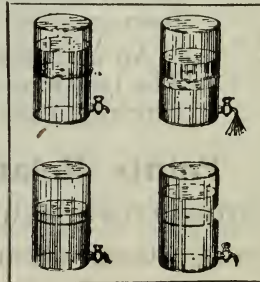
Figs. 3,934 and 3,936 show conditions of a single tank, and three tanks in parallel, furnishing equal flows. It is apparent that in the case of the parallel tanks, each is furnishing only one-third the total flow, while the single tank has to furnish it all. The parallel connection for dry cells has the same effect of dividing the current, giving triple the length of service.



FIGS. 3,938 to 3,941.—*Hydraulic analogy of recuperation.*

The power of recuperation and some other phenomena may be illustrated by an analogy in the form of such a tank as is shown in fig. 3,938, containing an internal diaphragm pierced by a small hole. When the tank is in the condition of fig. 3,938, with no water flowing, the pressure on the stop cock is due to the head of water all the way to the top level. This corresponds to the *open circuit voltage* of a cell. When, however, the stop cock is opened, as in fig. 3,939 and water flows out of the lower compartment faster than it can flow in from the upper, the pressure immediately drops just as the voltage of a cell drops under a heavy current drain. The greater the flow the

less of the total water in the tank that can be used before the lower (useful) compartment becomes exhausted. With a lighter flow more opportunity would be afforded to use water from the upper tank, thus *increasing* the effective *capacity*. If now the flow be stopped, the tank will "recuperate" to the condition of fig. 3,940, so that it can once more be used, but the "initial pressure" will be less than formerly and the recuperation after a second discharge will not be as rapid as before. Finally, when the upper compartment is emptied the recuperative power fails altogether and the tank becomes "dead." In the case of *very light flow* from the lower chamber, as in fig. 3,941, the recuperation may be able to keep up with the discharge in which case the initial and working pressures remain approximately equal.



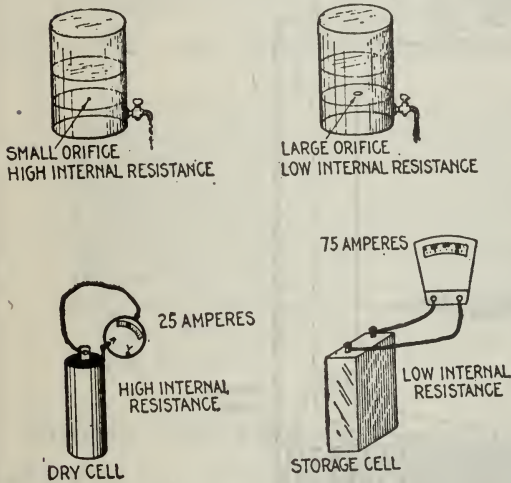


1. In connecting up cells the terminals and connecting wires should be scrupulously clean and bright, using sand paper or a scraper if necessary. All terminal nuts should be screwed down tightly so as to make a firm connection and reduce the resistance of the joint to a minimum.

2. Batteries consisting of two or more series connected units should not be used with series parallel connection except in case of emergency because the units are never of exactly the same voltage, hence the storage set tends to discharge through the weaker.

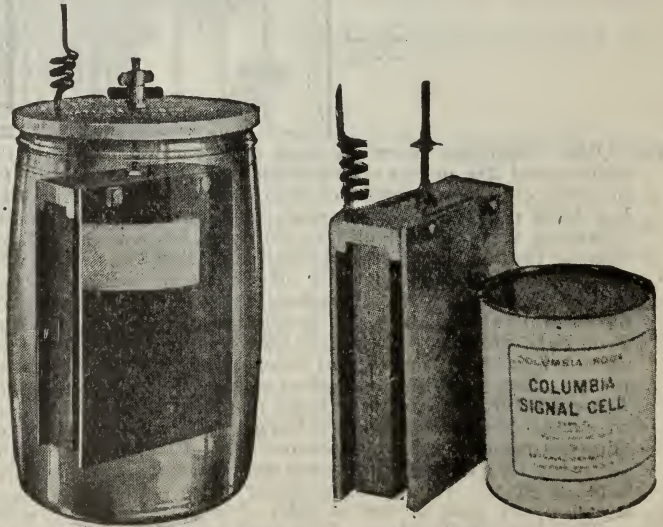
3. Never use more cells than necessary, because an excess of current will flow, thus reducing the life of the battery.

4. In general four dry cells are sufficient for automobile ignition, and six for marine ignition.



FIGS. 3,942 to 3,945.—*Hydraulic analogy of internal resistance.* Figs. 3,942 and 3,943 show two tanks (cells) both having discharge pipes (external circuits) of practically no resistance. The internal resistances of the tanks are represented by a large and small orifice through which the tanks must discharge. It is evident that the flow in one case will be high, and in the other case low, corresponding to initial currents of cells of low and high internal resistances. It is certain that on ordinary work either of these tanks would give equally good service if the flow required be less than the initial flow of the high resistance tank. This is true of dry cells. The required drain in any kind of work is less than the lowest initial current; hence, a low current cell may give just as good or better service results than a very high current cell.

FIGS. 3,946 and 3,947.—Columbia R. S. A. signal cell, type 72. It conforms to the R. R. S. A. specifications for copper oxide, zinc and soda primary battery. The cell is self-oiling and does not require the shipping or handling of any oil. A protecting layer of oil automatically forms on the surface of the solution within a comparatively short time after the element is immersed. A sand blasted space on jar is provided for record. Although primarily designed for signal work the cell is also satisfactory for gas engine ignition.





5. Weak dry cells can be strengthened by removing the paper jacket and punching the metal caps full of small hole, then placing in a weak solution of sal-ammoniac, allowing the cells to absorb all they will take up. Do this only in emergency; if the holes be closed by soldering, the cells will last longer.

6. Extra service may be obtained by two run down series connected units by connecting them in series parallel.

7. Extra service may be obtained by closer adjustment of the vibrator coil or reducing the distance between the spark plug points.

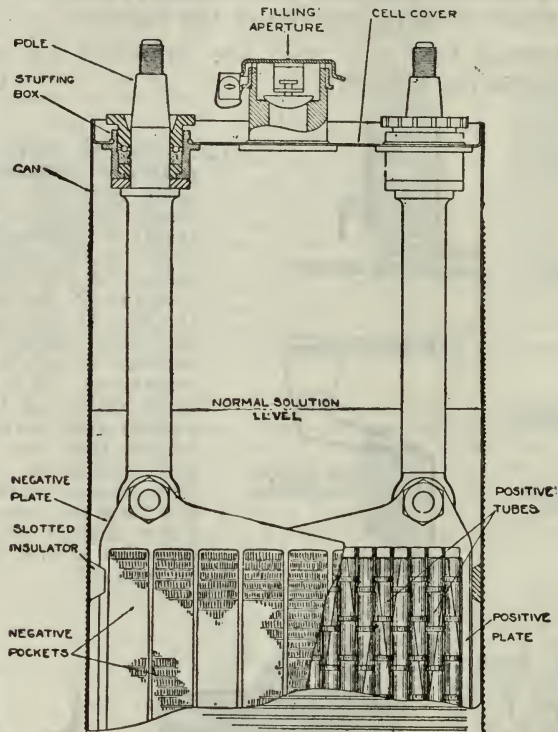


FIG. 3,948.—Sectional view showing construction of Edison cell. The solution should be maintained  $2\frac{3}{4}$  inches above plates. If solution level be low in any cell, hold battery out of service until renewal solution can be obtained. **Normal charge.** After battery has been practically discharged, the normal charge is for seven hours at normal rate. Charging resistance should be adjusted from time to time to keep current normal. If this be impracticable, set resistance so that current is about 50 per cent. above normal at the start. It should taper off by rise in battery voltage so that the average current will be at normal rate. If battery be only half discharged, recharge for half of seven hours at normal rate; if only one quarter discharged, charge for a quarter of seven hours, etc. **Low rate charge.** To secure best results on five hour or eight hour discharge, charge at not less than the normal rate. If, however, the cells be discharged at a very low rate, a charging rate lower than normal can be used with satisfactory results. **Ampere hour meter.** An ampere hour meter, if used, should be set to recharge 25 per cent. in excess of discharge. **Discharge rate.** The size of cell used should be such that the continuous discharge does not exceed 25 per cent. above normal rate. **Water.** Replenish cells with distilled water as frequently as is necessary to keep solution level above tops of plate. When adding water do so before charging. **Changing solution.** After about every nine or ten months of continuous daily service, test solution with hydrometer after a full charge. If it read below about 1.160, the solution should be changed.

**Secondary Cells.**—A second chemical means of producing electricity for ignition is the *storage battery* which consists of two or more secondary cells contained in a carrying case or box usually of wood or hard rubber. A secondary cell is made up of a positive and a negative set of plate (usually of lead) immersed in an electrolyte of dilute sulphuric acid. The plates are spaced apart by insulating separators. The proportion of acid to water is about one part acid to three and one-half parts water. In preparing the electrolyte, acid should always be added to the water—*not water to acid*.

In passing an electric current through a cell, the plates undergo a chemical change; when this is complete the cell is said to be *charged*. A quantity of electricity has been stored in the cell, hence the name, *storage battery*. The cell after being charged will deliver a current in a reverse direction because during the discharge a reverse chemical action takes place which causes the plates to resume their original condition. When fully charged the positive plates are coated with peroxide of lead and are brown in color and the negative plates gray.

For a very extended treatment of the subject of storage batteries see Guide No. 4

**Points Relating to Secondary Batteries.**—Many storage batteries are ruined after short service by neglect or ignorance in caring for them; accordingly, the following items should be carefully noted.

1. The water in the electrolyte evaporates but the acid never does.
2. Keep plates well covered with electrolyte.
3. To replace loss by evaporation *add only distilled water*, or *clean rain water which has been collected in a non-metallic vessel*. The water must positively be chemically pure or the battery will be ruined within a short time.
4. The battery capacity is rated in *ampere hours*. Thus a fifty ampere hour battery means that with full charge it will give an ampere for 50 hours.
5. *Never test a storage battery with an ammeter*. The internal resistance of battery being very low, a very large current flows on short circuit, hence, an ordinary pocket ammeter would probably be injured—use a volt meter and take readings while the battery is delivering current, not when the circuit is open.
6. The capacity of a battery is independent of its voltage.



7. Don't take it for granted that the wiring on automobile lighting and starting systems is of large enough size to carry current of a short circuited storage battery without excessive heating—such short circuit in the vicinity of a leaking carburetter is not to be recommended (though only so called "gasoline" be used), especially in the case of makeshift rigs installed by amateurs.

8. Except for stationary service, keep battery securely fastened in place.

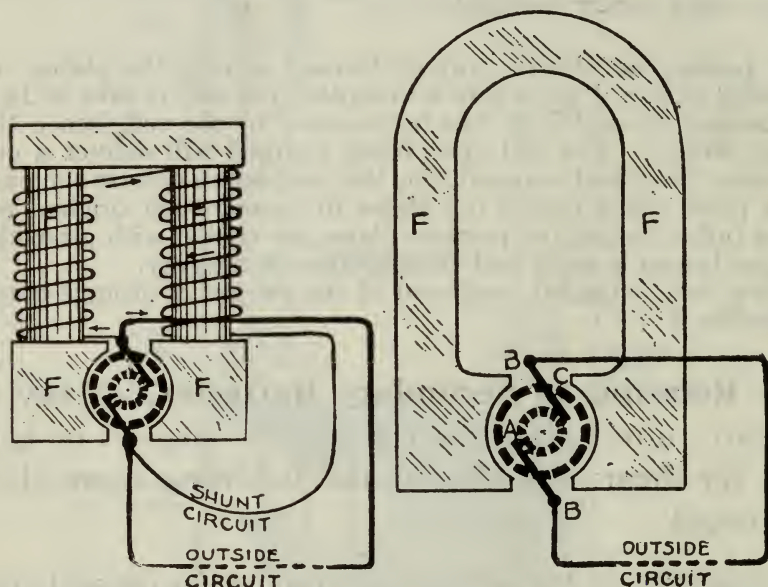
9. Keep battery and interior of battery compartment wiped clean and dry.

10. Do not permit an open flame near the battery

11. Keep terminals and connections coated with vaseline or grease.

12. Test specific gravity of each cell regularly with a hydrometer.

13. When all cells are in good order the gravity will test about the same (within 25 degrees) in all.



FIGS. 3,949 and 3,950.—Circuit diagrams to illustrate the difference between a dynamo and a magneto. The former has its field magnets FF magnetized by means of a small current flowing around a shunt circuit. In a magneto the field magnets are permanently magnetized. The strength of the magnetic field of a magneto is constant while that of a dynamo varies with the output, hence, a magneto may be run at a widely varying speed and meet ignition requirements, but a dynamo must have its speed maintained approximately constant to keep the voltage within limits.

14. A dead battery tests 1,150; when fully charged 1,275 to 1,300.

15. A battery which is to stand idle should be fully charged.

16. A battery should not remain idle for more than six months without recharging.

17. Disconnect the leads from an idle battery to avoid any slight leak in the external circuit.

18. Many batteries are ruined by entrusting their care to incompetent garage men.



**Mechanical Generators.**—The two methods of producing a current by mechanical means are by the use of dynamos or magnetos.

**Ques.** How does a dynamo differ from a magneto?

**Ans.** Chiefly in that the dynamo has field magnets of soft iron or mild steel, wound with wire through which circulates the whole, or a portion of the current generated by the machine;

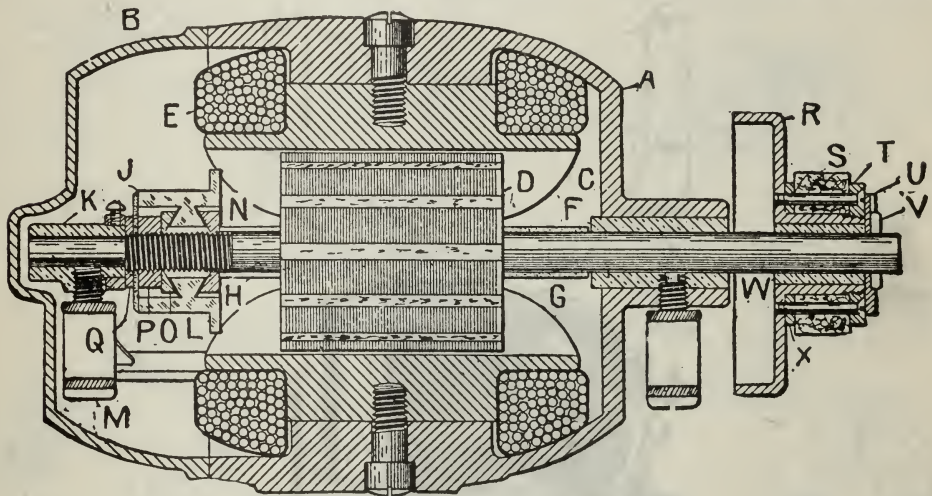


FIG. 3,951.—Sectional diagram of the Apple igniting dynamo. The parts shown are: A, cast iron body containing the moving parts; B, the hinged lid of the body; C, the one pole piece of one of the field magnets; F, brass bearing of the armature spindle; G and H, fibre tubes surrounding the spindle; K, brass spider supporting the spindle; L, commutator; M, wick feed oil cup; N, beveled nut supporting the commutator; O, P, Q, supports of the commutator; R, the driving disc; S, lever friction pinion. This machine can generate a direct current at 8 volts at a speed of between 1,000 and 1,200 revolutions per minute. It is provided with a simple centrifugal governor that automatically interrupts the driving connections when a certain speed has been exceeded.

whereas, a magneto has field magnets constructed of steel and permanently magnetized, no part of the current adding to the magnetism.

The circuit diagrams, figs. 3,949 and 3,950, illustrate this difference. In the dynamo the field magnets FF are magnetized by means of a small current flowing around a shunt circuit; that is, a certain amount of current is taken from the system and used to magnetize the field. The remainder of the current generated is used in the outside circuit.

**Dynamos.**—The field magnets of a dynamo increase in strength as the current which passes around them increases.

Moreover, as the magnetic strength increases, the voltage of the generated current also becomes stronger. Hence, it is evident that a dynamo is not self-regulating, and if run at too high speed is liable to be overheated or even burned out in its effort to furnish a current beyond its capabilities, on account of this faculty of automatically strengthening its own fields.

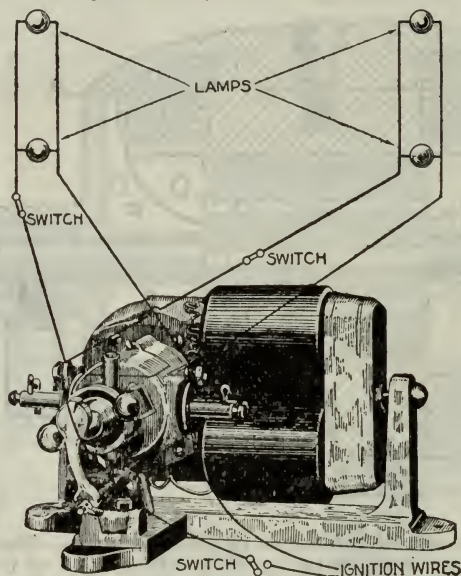


FIG. 3,952.—Motsinger "Auto Sparker" friction drive dynamo. The small friction pulley gives sufficient speed to ignite the charge when engine is turned slowly as in cranking. After the engine is under motion, the governor on the shaft of the dynamo limits its speed, so as not to obtain an excessive voltage. This is accomplished by mounting the dynamo on its base so that it can oscillate on an axis, the small friction wheel making and breaking contact with the engine fly wheel. *In operation*, when normal speed is exceeded, the governor weights fly out and draw the friction wheel away from the fly wheel, one spring serving the double purpose of pushing the friction pulley against the fly wheel and acting as a tension on the governor. By increasing or diminishing the tension on the governor spring by means of a thumb nut provided for the purpose, the speed of the dynamo may be increased or diminished, which in turn increases or diminishes the volume of current and size of spark. By screwing up on this thumb nut the position of the dynamo is not changed, but the contact of the pulley and tension of the governor are increased. Thus, by adjusting the thumb nut, the size of the spark may be regulated at will.

**Ques.** Describe the friction drive for a dynamo.

**Ans.** In this form of drive, motion is transmitted through a very small wheel in frictional contact with the fly wheel of the engine.



This frictional wheel is small enough to run the dynamo at full speed when the engine is turned slowly, as in cranking. As the engine speed increases, the governor acts, and maintains the speed of the dynamo unchanged.

**Ques.** How is a dynamo generally used?

Ans. In connection with a storage battery, the current for ignition being supplied by the battery, which, in turn, is con-

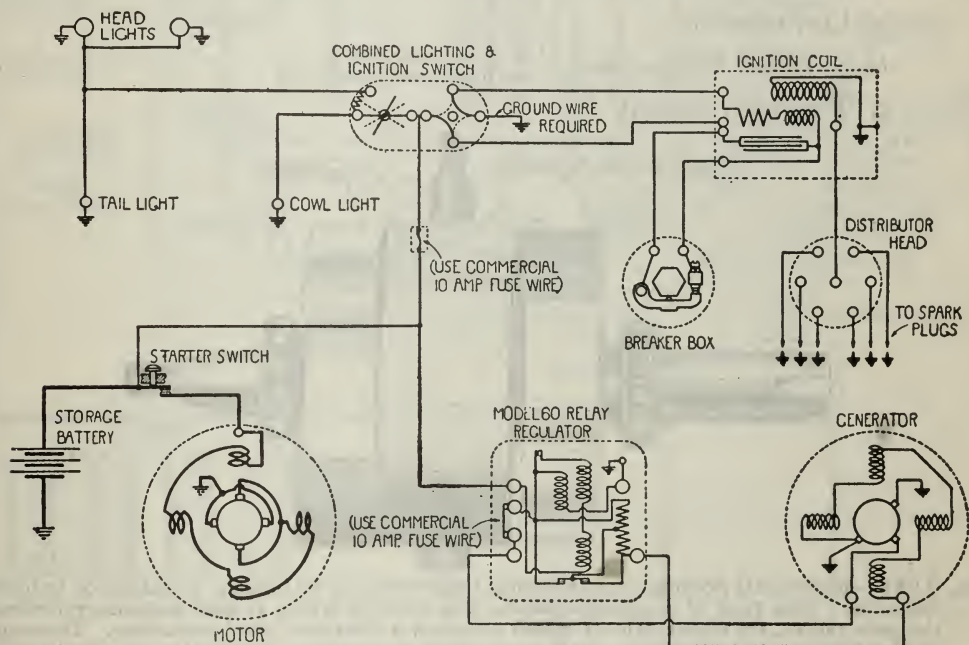


FIG. 3,953.—Wiring diagram of Remy ignition, lighting and starting system as installed on Oakland automobiles. The 6 volt dynamo is a four pole shunt wound machine driven at  $1\frac{1}{2}$  crank speed. A discriminating cut out controls its connection with the battery in charging. The ignition distributor which is a part of the dynamo distributes the high tension current to the cylinders in proper sequence. The interrupter contact points are made of silver.

stantly charged by the dynamo to replace the energy drawn from the battery.

A discriminating cut out or reverse current circuit breaker (erroneously called relay) disconnects the dynamo from the battery when the voltage of the former becomes equal to, or less than that of the latter and this prevents the battery discharging through the dynamo.



**Magnetos.**—There are many types of magneto in use for ignition. They may be classified,

1. With respect to the armature, as
  - a. Stationary;
  - b. Oscillating;
  - c. Rotating.
2. With respect to the kind of current generated, as
  - a. Low tension;
  - b. So called high tension { with separate coil;  
with self-contained coil.
  - c. True high tension.

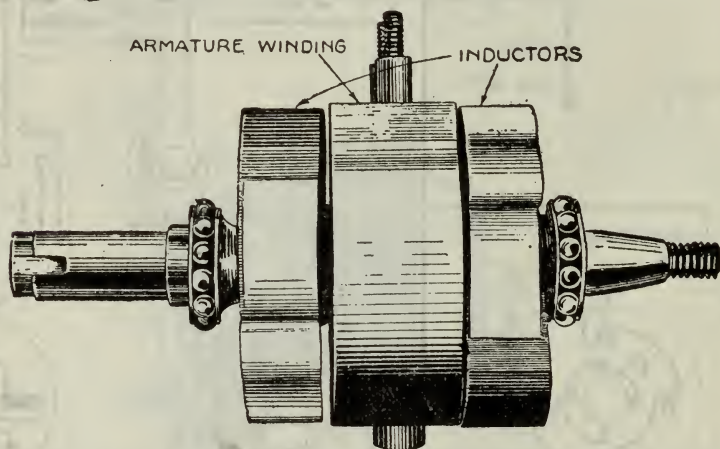


FIG. 3,954.—Remy ball bearing shaft showing inductors and stationary armature of inductor magneto. This type of magneto consists of a winding which is held stationary between the pole pieces, on either side of which revolves a *laminated steel inductor*. Inasmuch as the winding is held rigidly stationary, such construction eliminates all revolving or moving wires, all sliding or wiping contacts, collector rings, etc. This design permits of rugged electrical, as well as mechanical, construction. **In operation**, at each half turn of the inductor shaft, the direction of flow of the lines of force through the winding is reversed, producing in the winding two electrical impulses for each complete revolution. The stationary winding is directly connected through the magneto circuit breaker with the primary of the secondary coil used with the magneto. The timing of the spark is accomplished by shifting the circuit breaker around the inductor shaft, to which is attached the circuit breaker cam. The timing range is 35 degrees.

**Inductor Magnetos.**—In this class of magneto, the armature is fixed so that it does not revolve and is located with the sector shaped heads of the core at right angles to the line joining the field poles. This position of the core furnishes the least magnetically conducting path. An annular space between the

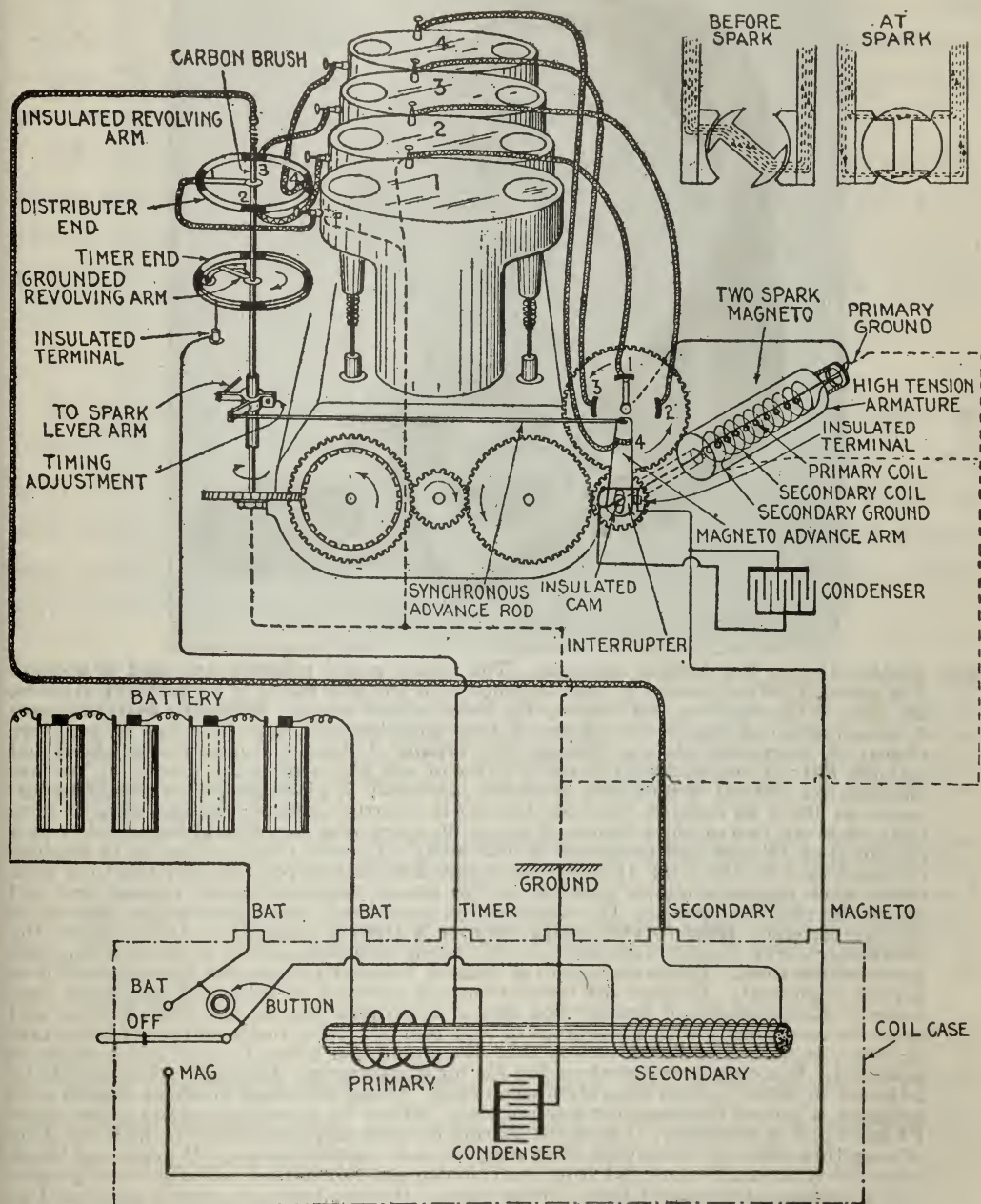


FIG. 3,955 TO 3,957.—Double ignition consisting of a two spark high tension magneto system, and a battery synchronous ignition system with engine driven distributor. Fig. 3,955 elementary diagram of connections; fig. 3,956, position of magneto armature just before time of spark; fig. 3,957, position of armature at time of spark.



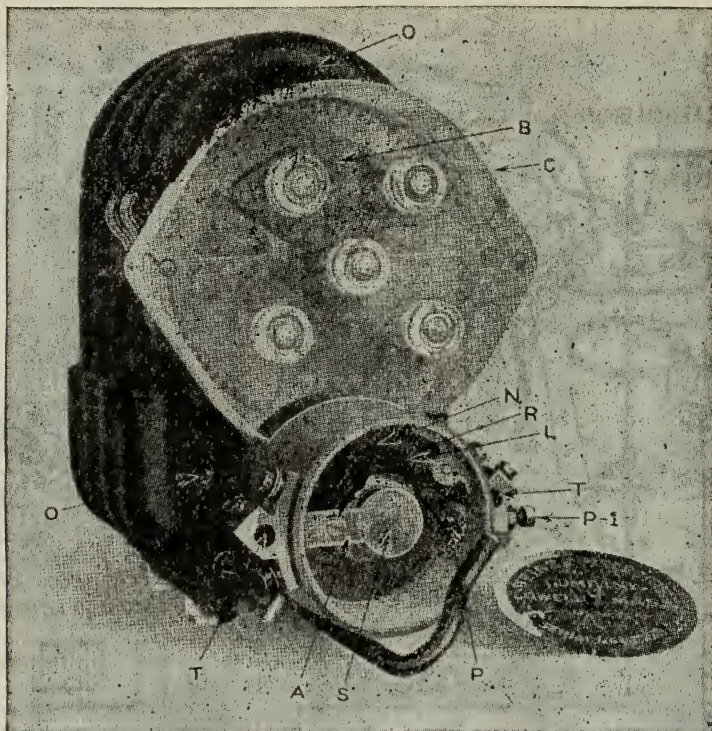


FIG. 3,956.—Heinze low tension magneto. The reason round magnets are used is because it is claimed better contact is thus obtained with the pole pieces or by carefully grinding the ends of the magnets and reaming the holes in pole pieces. **Magneto instructions:** 1, Keep interior of breaker box **clean**; 2, keep phosphor bronze studs on end of armature **clean**; 3, keep steel plate in breaker box **clean**; 4, keep platinum points **clean** and surfaces **flat**; 5, use nothing but **emery paper or fine file** on platinum points; 6, be sure all leads are **soldered** in terminals or **rigidly connected**; 7, platinum points should be adjusted to .02 of an inch; 8, lubricate bearing in interrupter lever with one drop of very light oil every two or three thousand miles; 9, spark plug gap should be adjusted to a minimum of .02 inch and maximum of .025 inch; 10, connect dry cells so as to produce not more than 3 or 4 volts; 11, never leave switch on battery point for any length of time either when engine is idle or running, as this causes excessive battery current and will injure the platinum points; 12, magnetos are considered running clockwise looking at the driving end. **How to efficiently operate a Heinze magneto.** In the figure the distributor cover C, and brush arm A, are shown semi-transparent so as to distinguish parts behind them. Be sure magneto is securely fastened to base and driving shaft is in perfect alignment. Be sure **all** connections are soldered or otherwise positively connected. Keep interior of breaker box clean. Keep phosphor bronze studs S clean and lubricate occasionally with a few drops of very thin oil. Keep inside surface of brush arm A, clean, as studs S make contact on this. Keep platinum points P, clean and surfaces of same flat. Use only emery cloth or fine file for this purpose. Platinum points should be adjusted to .02 of an inch separation when open. Gauge furnished on small wrench with magneto is proper thickness for this purpose. Adjust by turning platinum point screw P1 in or out as necessary. Lubricate bearing in make and break lever L, with one drop of very thin oil every two weeks when magneto is in continuous use. If make and break lever roll R, should become flat from wear, loosen nut N, and turn roll slightly to present a new surface to cam, and then tighten again. Be sure leads are rigidly connected in terminals TT. Leads must be long enough to allow free movement of breaker box. Remove distributor cover C occasionally and wipe out interior of same, also clean off any carbon dust or dirt from distributor brush B. Magneto bearings should be lubricated by oiling at OOO every week when magneto is in continuous use. Two or three drops are enough at a time. There is one oiler at rear end which does not show in cut.



armature and the field poles is provided for the rotation of an *inductor*. This consists of two diametrically opposite cylindrical segments of soft iron supported and carried by a shaft located at the center of the circle described by the segments.

The magnetic condition of the armature core depends entirely upon the position of the inductor. The latter is arranged, 1, to revolve continuously with a gear drive from the engine, or 2, to rotate to and fro through a small arc by link connection to the half time shaft.

**Low Tension Magnetos.**—Generators of this class may be used to supply a current of low voltage for, 1, make and break ignition or for, 2, high tension ignition with induction coils or coil spark plugs. A low tension magneto has an armature winding consisting of about 150 to 200 turns of fairly thick wire, covered with a double layer of insulating material.

One end of the winding is grounded to the armature core and the other, brought to a single insulated terminal. When this terminal is connected to any metal part of the magneto or engine (since the latter is in metallic contact with the base of the magneto), the circuit is complete. The wiring therefore is very simple, which is one of the advantages of the system.

The "live end" of the armature winding is brought out by means of a metallic rod passing lengthways through the shaft of the armature; a hard rubber bushing is provided as insulation between the shaft and the rod. The live end of the winding is located at one end of the armature shaft, from which the current flows to an insulated terminal by means of a metal contact which is pressed against the revolving rod by a spring.

**High Tension Magnetos.**—These are *erroneously* divided into three classes, viz: 1, those in which the induction secondary wiring is wound directly on the armature; 2, those having a secondary induction coil contained within the magneto, and 3, those having the coil in a separate box usually placed on the dash.

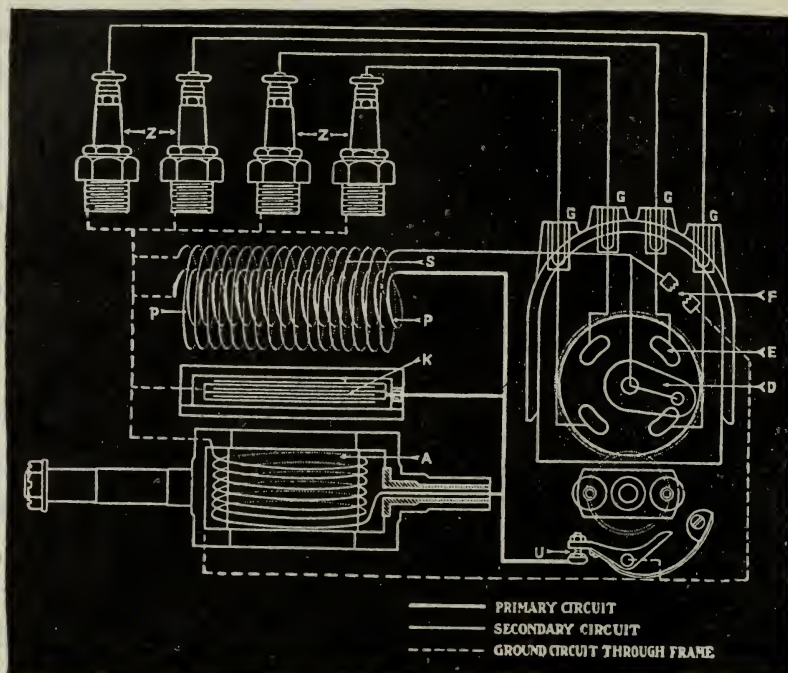


FIG. 3,959.—Circuit diagram of a magneto with self contained coil. A is the armature winding; P, primary of transformer; S, secondary of transformer; D, distributing brush carrier; E, contact segments; F, safety spark gap; G, terminals to plugs; U, interrupter; Z, spark plugs. **In operation**, alternating current flows from the armature having two points of maximum pressure in each armature revolution. As the current leaves the armature, it is offered two paths: 1, the shorter through the interrupter U to the ground, and 2, the longer through the primary P of the induction coil to the ground. A third path through the condenser K is only apparently available; it is obstructed by the refusal of the condenser to permit the passage of the current, as the condenser will merely absorb a certain amount of current at the proper moment, that is at the instant of the opening of the interrupter. The interrupter being closed the greater part of the time, allows the primary current to avail itself of the short path it offers. At the instant at which the greatest current intensity exists in the armature, the interrupter is opened mechanically so that the primary current has no choice but must take the path through the primary P of the induction coil. A certain amount of current is at this instant also absorbed by the condenser K. This sudden rush of current into the primary P of the induction coil, induces a high tension current in the secondary winding S of the coil which has sufficient pressure to bridge the air gap of the spark plug. The sharper the rush of current into the primary winding P, the more easily will the necessary intensity of current for a jump spark be induced in the secondary winding S. **The distribution of the current** in proper sequence to the various engine cylinders is accomplished as follows: the high tension current induced in the secondary S of the induction coil is delivered to a distributing brush carrier D that rotates in the magneto at half the speed of the crank shaft of the engine. This brush carrier slides over insulated metal segments E—there being one for each cylinder. Each of these segments E connects with one of the terminal sockets that are connected by cable with the spark plugs as shown. **At the instant of interruption** of the primary current, the distributing brush is in contact with one of the metal segments E and so completes a circuit to that spark plug connected with this segment. Should the circuit between the terminal G and its spark plug be broken, or the resistance of the spark plug be too great to permit a spark to jump, then the current might rise to an intensity sufficient to destroy the induction coil. To prevent this what is known as a safety spark gap is introduced. This will allow the current to rise only to a certain maximum, after which discharges will take place through this gap. **In construction** the spark discharges over this gap are visible through a small glass window conveniently located.



The first mentioned type constitutes the only real high tension magnetos.

**Ques.** How does a magneto deliver current to the cylinders in proper sequence?

**Ans.** By means of a self-contained distributor.

**Ques.** Describe briefly a so called high tension magneto with self-contained coil.

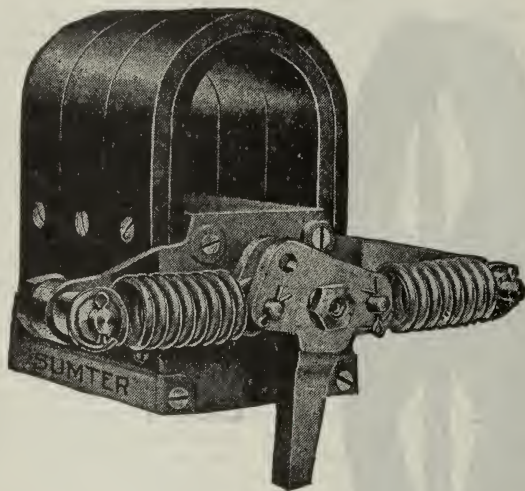


FIG. 3,960.—Sumter low tension oscillating magneto. In this type the armature does not revolve continuously but oscillates back and forth through an angle of about 90°.

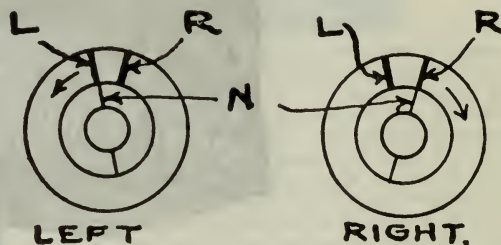
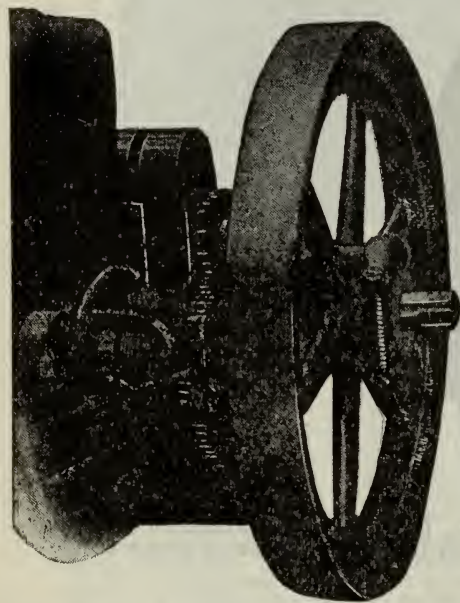
**Ans.** The essential features are a low tension armature arranged to revolve in a permanent magnet field and provided with interrupter, secondary coil, condenser, and distributor. The construction and operation of this type magneto is clearly shown in fig. 3,959.

**Synchronous Drive for Magnetos.**—Ignition magnetos are generally constructed to deliver an alternating current, that is,



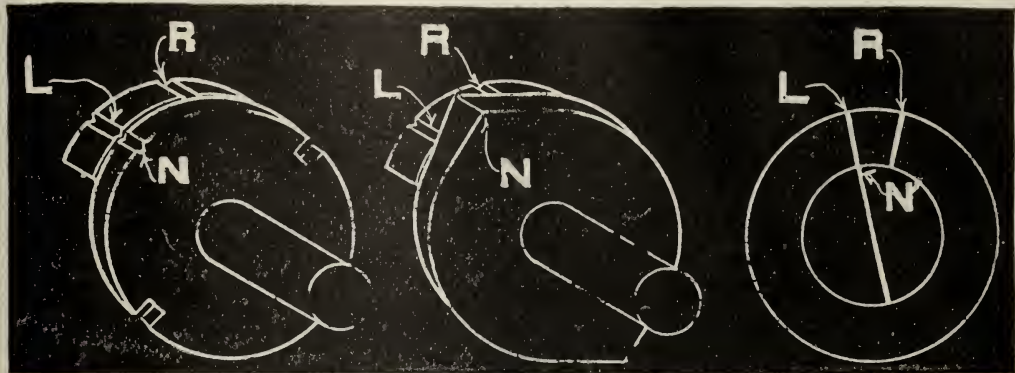
a current consisting of a succession of regularly alternating electrical impulses, varying in intensity from a plus maximum to a negative maximum, and separated by points of zero pressure depending upon the armature position with respect to the field.

Hence, it is necessary that the generator, unless geared to run at high speed, should be driven **synchronously**, that is, at a speed in a definite rate to that of the engine, in order that the periods when a spark is desired shall coincide with the periods when sufficient voltage is being developed, as otherwise the sparking periods might occur with a zero point of electrical generation, and no spark would be produced.



FIGS. 3,961 and 3,962.—Sumter low tension magneto installed on stationary engine, and marking on the ends of shaft and bearing for timing. *To time*, turn engine over in *running* direction until igniter snaps; be careful not to turn past this point. With gear on magneto shaft, turn the magneto in *running* direction until timing mark N on the shaft is in line with mark L, if rotation be left hand, or R, if rotation be right hand. Now mesh the gears, *without moving the timing*; this is accomplished by a proper location of the keyway in the magneto gear in relation to a marked tooth on same. The teeth on the engine driving gear meshing with marked tooth on magneto gear should also be marked, and after this marking is once determined all keyways may be cut in proper relation to the marked tooth, thus making all magnetos on the same type of engine interchangeable. These magnetos are usually driven at engine speed, but may be driven at other speeds.

To meet these conditions, the drive must be positive and may consist of either toothed wheel gears or chain and sprocket; the former is more desirable, since, with a chain and sprocket drive, there is sufficient



FIGS. 3,963 to 3,965.—Timing Sumter low tension magnetos. Type "Imp" is timed as in figs. 3,963 and 3,964, the end of shaft and bearings being marked as in fig. 3,965. All other Sumter magnetos are timed as shown in figs. 3,963 or 3,964. Some machines have the notched disc as per fig. 3,963; others, the pointed disc, fig. 3,964. In either case, the timing is exactly the same. With the pointed disc, use the point to time with instead of the notch. **Speed:** On single cylinder 2 and 4 cycle engines, magnetos may be run at engine speed, or  $1\frac{1}{4}$ ,  $1\frac{1}{2}$ ,  $1\frac{3}{4}$ , or twice engine speed. In the majority of cases, engine speed is most desirable, although other speeds result in reversing the current through igniter points, preventing pitting, which is advantageous. On two and four cylinder, 4 cycle engines, run magneto at engine speed. Three cylinders, at  $1\frac{1}{2}$  times engine speed. **For fixed ignition**, turn the engine in the direction in which it runs until the igniter snaps. *Do not turn past this point.* Observe the setting disc on the magneto shaft, and so mesh the magneto driving gear with gear on engine that either *small* notch N (see cut) is exactly in line with the mark R on the end plate if rotation be right hand, or L, if rotation be left hand, looking at magneto from gear end. Where timing discs have points like fig. 3,964 set either point in line with the proper mark. **For variable ignition**, where the range is not excessive, place the spark lever in the starting position, and then time the magneto as described above. Some engine builders prefer to reverse this order, giving the best spark for the advance or running position, although for *starting on magneto* it is preferable in most cases to use the best spark for starting. These are matters which have to be tested out by the manufacturer, and the engine dealer and user should be particular not to change the speed or method of timing on the engine as originally furnished. When magneto is properly timed, it is necessary to secure the magneto gear against slipping. The gear should be marked and keyway cut to register with keyway in armature shaft. As the keyway is the same in all armature shafts, the gears may also be keyed and marked alike, and by simply meshing the marked tooth on magneto gear with marked tooth on driving gear, the correct timing will be obtained without the necessity of setting each magneto. The driving gear should be so meshed that there is a very small amount of play. Otherwise, destructive wear of magneto bearings will take place. The amount of play is sometimes provided for by the engine manufacturer, by adjusting collars in the magneto bracket, or is easily accomplished by shimming either the magneto itself or the bracket. **In old engines**, when checking timing, it is best to note that the magneto marks line up when the piston is in the proper firing position, as it is possible that the igniter may have gotten out of time with the piston through wear. If so, the igniter should be properly adjusted, so that it will snap in time with the magneto. Sometimes the magneto is suspected of being out of time, when as a matter of fact it is the igniter. Igniters should be so adjusted that the points remain *closed* as much as possible, and open only to make a spark. This not only keeps the points from getting dirty, but also gives the magneto time to "build up" and produce its maximum current.

NOTE.—**Sumter reversing attachment.** Many marine engines are reversed "on the spark," and to accomplish this, a special attachment is necessary. **This consists of** a collar on magneto shaft carrying the gear and having a pin engaging a cutaway shoulder on the collar. This arrangement allows sufficient lost motion between the gear and collar so that, when the engine is reversed, the magneto is brought in time with the snapping of the igniter.



lost motion when the chain is loose enough for smooth running to prevent the accurate timing of the spark.

The friction gear drive or belt and pulley are alike objectionable, from the fact that no slipping or variation is permissible. While some recent forms of high tension magneto are advertised to operate **asyn-chronously**, that is, not speeded in definite ratio to the engine, the common types are so made that the spark shall occur in the cylinder at precisely the moment the magneto armature is at a certain point in its rotation. If, therefore, this condition be not strictly observed, the spark will be of defective intensity.

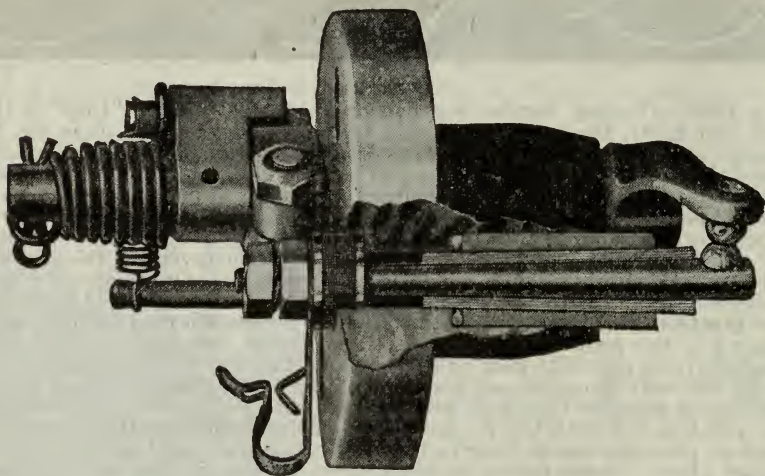


FIG. 3,966.—Sumter electrode for make and break ignition. *In construction*, the stem is insulated with rolled mica, which does not have any upturned edges in the combustion chamber. The taper arrangement makes it impossible to loosen or pull out the insulation. A copper gasket inside the igniter casting makes a gas tight joint. The stem is long enough to take care of igniter castings of various thickness, and the superfluous portion may be cut off.

**Ignition Systems.**—There are two systems in general use for igniting the charge by electricity:

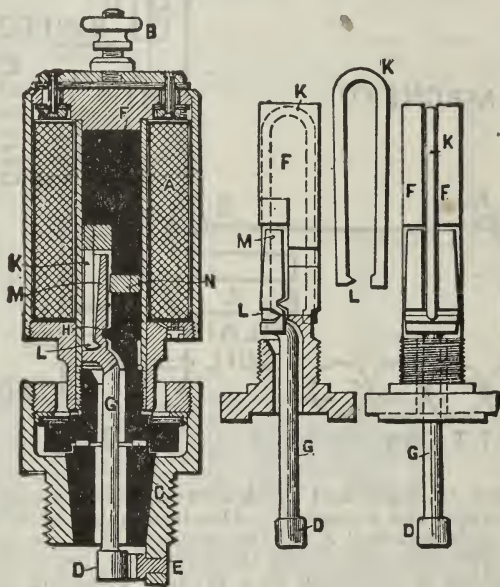
1. The low tension or *make and break*.
2. The high tension or *jump spark*.

**Ques.** What are the characteristic features of each system?

**Ans.** The low tension system is electrically simple and mechanically complex, while the high tension system is electrically complicated and mechanically simple.



**Low Tension Ignition.**—In this system there is a device known as an *igniter*, placed in the combustion space of the engine cylinder. This consists of two electrodes, one of which is stationery and the other movable. The stationary electrode is insulated, while the other, having an arm within the cylinder and placed conveniently near, is capable of being moved from the outside so that the arm comes into contact with the stationary electrode and separates from the latter with great rapidity.



FIGS. 3,967 to 3,970.—Bosch magnetic spark plug. This consists of a coil A having one end connected to a terminal B, and the other to the plug casing C. A spark is produced when a separation takes place between the moving contact D and the stationary contact E. Within the plug is a metal core F and a swinging lever G, which lever pivots on the projection H which is a part of the core F. K shows a portion of a hair-pin spring, the end L of which rests in a recess within the lever G, the ordinary tension of the spring tending to hold the lower end of the lever G carrying the contact D against the stationary contact piece E.

This sudden breaking of the circuit produces an electric arc or *primary spark* caused by the inductance—that is, by the “inertia” or tendency of the current to continue flowing after the separation of the contact points.

The current may be derived from either a primary battery, storage battery, or low tension magneto.

**Ques.** Name the elements in a low tension circuit.

**Ans.** 1, a source of current supply consisting of either a primary battery, storage battery, or low tension magneto, 2, a primary induction coil when a battery is used, 3, an igniter,

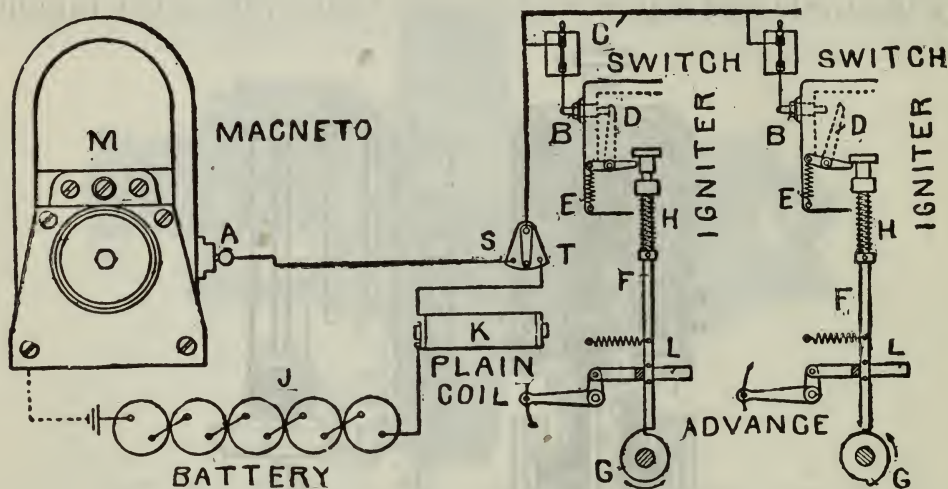


FIG. 3,971.—Low tension or make and break system. Two sources of current supply are provided: a dry battery and a magneto. One terminal of both the battery and magneto is grounded; the other terminal A, of the magneto M, is connected to the point S, of a two way switch. The cells comprising the battery J, are connected in series and the terminal not grounded is connected to a primary induction coil K, and thence to the point T of the two way switch. By moving the arm of this switch to the right or left, current may be had from the battery or magneto respectively. A conductor C, connects the third point of the switch to the stationary or insulated electrode of each igniter, a single throw switch being placed at each igniter which allows either or both cylinders to be thrown out of the circuit at will. The movable electrodes and metal of the engine furnishes the ground return to the battery and magneto. On a multi-cylinder engine it is evident that no other contact can be made at the moment of break in one cylinder since the current would then flow through any other igniter that might be in contact instead of producing a spark at the break. The operation of the make and break system is as follows: *Starting, say on the battery*, the arm of the two way switch is turned upon point T. The movable electrode D, of the first cylinder being in contact with the insulated electrode B, by the spring E, the current will flow from the battery J through the coil K, thence through the two way switch and the single throw switch to the insulated electrode B. The movable electrode D, being in contact with the insulated electrode B, the current returns to the battery through D and the metal of the engine, thus completing the circuit. As the cam G revolves in the direction indicated by the arrow, its nose passes from under the lower end of F, the latter drops with great rapidity by the action of spring H and in so doing a shoulder at the upper end of F, strikes the external arm of D a blow causing the contact point of D to be *quickly snapped* apart from B, producing an arc which ignites the charge. This cycle of operations is repeated by the ignition mechanism of each cylinder in rotation.



4, a switch for breaking the circuit, and an additional switch to alternate between the battery and the magneto when both means of furnishing the current are provided, and 5, connecting wires, as shown in fig. 3,971.

**Ques.** How is the spark produced in the low tension system?

**Ans.** The sudden breaking of the circuit by the quick separation of the electrodes produces an electric arc or **primary**

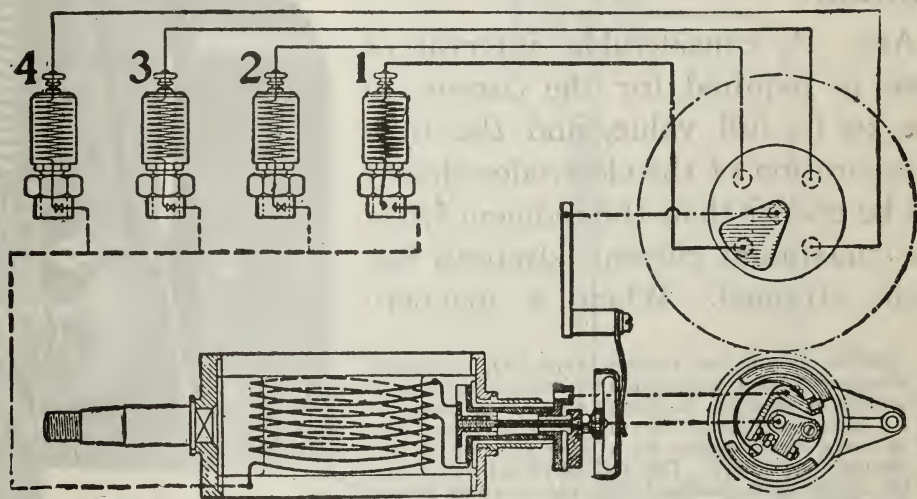


FIG. 3,972.—Wiring diagram of a low tension system with magnetic spark plugs. A portion of the wiring of the magneto armature is short circuited by the platinum points of the interrupter, and when the circuit is broken the resulting armature reaction has the effect of raising the armature voltage sufficiently to operate the plugs.

**spark** caused by the **inductance**—that is, by the “inertia” or tendency of the current to continue flowing after the separation of the contact points.

**Ques.** What is the object of the primary induction coil?

**Ans.** To intensify the spark.

When a magneto is used, a coil is not necessary, as the armature winding serves the same purpose. A magneto furnishing either direct



or alternating current may be used; the voltage will depend on the armature speed and the strength of the magnets.

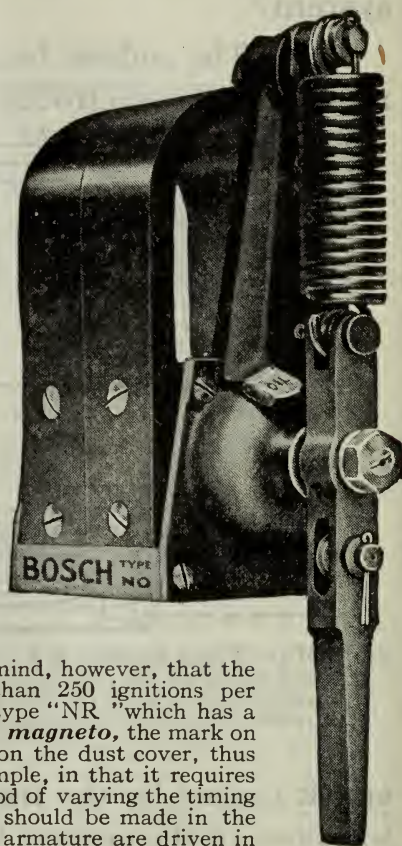
**Ques.** What is used for the electrode contact points?

**Ans.** Iridium or platinum, as these metals resist the oxidizing effect of electricity and heat better than others.

**Ques.** What is the action of the current in low tension ignition?

**Ans.** A considerable interval of time is required for the current to rise to its full value, and the time of separation of the electrodes should not be sooner than the moment when the maximum current strength has been attained. When a magneto

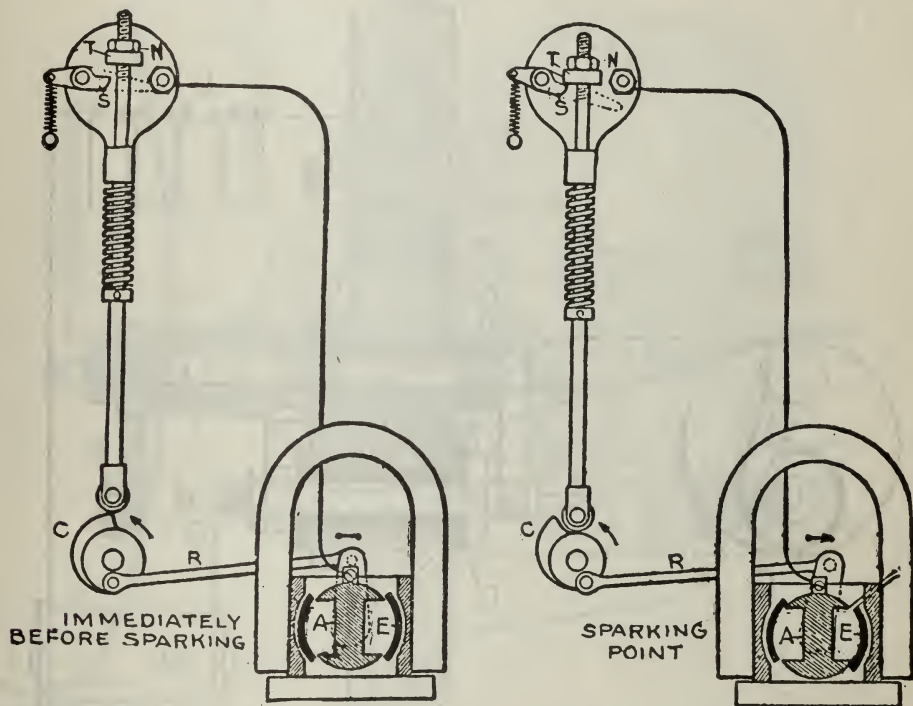
**FIG. 3,973.**—Bosch low tension, type NO, oscillating magneto used in connection with mechanical make and break igniters. A current wave being produced by each oscillation of the armature, it is necessary to drive the magneto in a fixed relation to the engine crank shaft. The magneto trip lever should be mechanically connected to the movable igniter on the engine, as in this way only can proper synchronism be obtained. It should be borne in mind, however, that the type "NO" cannot be used at speeds greater than 250 ignitions per minute, and where a greater speed is desired, the type "NR" which has a rotating armature, should be used. *In timing the magneto*, the mark on the armature should register with the proper mark on the dust cover, thus making the timing for either rotation extremely simple, in that it requires no disassembling of the instrument. Since no method of varying the timing of the spark is provided, arrangements to this end should be made in the tripping mechanism, and since the igniter and the armature are driven in synchronism by the trip lever, the instrument is always operated at its point of maximum efficiency regardless of whether the spark be retarded or advanced. In order to obtain proper results, the trip lever should be deflected through an angle of 30 degrees before it is released, and, since the spark is produced by spring action rather than directly through the speed of the engine and therefore is independent of the latter, no battery is necessary for starting, and in ordinary cases one turn of the fly wheel will be sufficient, provided, of course, that a proper gas mixture be present.



is used, the current strength increases with the speed, hence the contact interval can be shorter at high speeds than when a battery is used.

**Ques.** In low tension ignition, what is necessary in order to produce a good spark?

**Ans.** The "**break**" or separation of the contact points of the igniter should take place with **extreme rapidity**, that is, the spring H (fig. 3,971) should be sufficiently strong to cause the shoulder or rod F, when it falls, to strike the igniter arm a decided blow, thus quickly snapping apart the contact points.



**FIGS. 3,974 and 3,975.**—Low tension ignition system with inductor magneto. Fig. 3,974, position immediately before sparking; fig. 3,975, position immediately after sparking. **In construction**, the cam which operates the make and break igniter has a link connection to the inductor crank of the magneto which gives an oscillating motion to the inductor. The connection is such that at the instant of "break" the inductor cuts through the greatest number of magnetic line. **In operation**, the cam C, on the half time shaft, makes a contact just before sparking, and immediately breaks it again by permitting the hammer T to fall on the cam S. A spark is produced at the instant of break of contact at N. The winding of the armature A has one end grounded through the base of the magneto, the current returning through the engine to the point S; the other end of the winding is led through an insulated post to the nut N by which it is connected with a stud brought through the cylinder wall, where a wiper, indicated by dotted outline, normally rests against it by means of a spring.

**Ques.** State some disadvantages of low tension ignition.



Ans. Mechanical complication, excessive noise, wear of the igniter points, and possible leakage through the igniter.

**Ques.** For what service is low tension ignition especially suited?

Ans. For marine service especially in open, off shore fishing boats, such as Cape Cod dories, Sea Bright skiffs, etc.

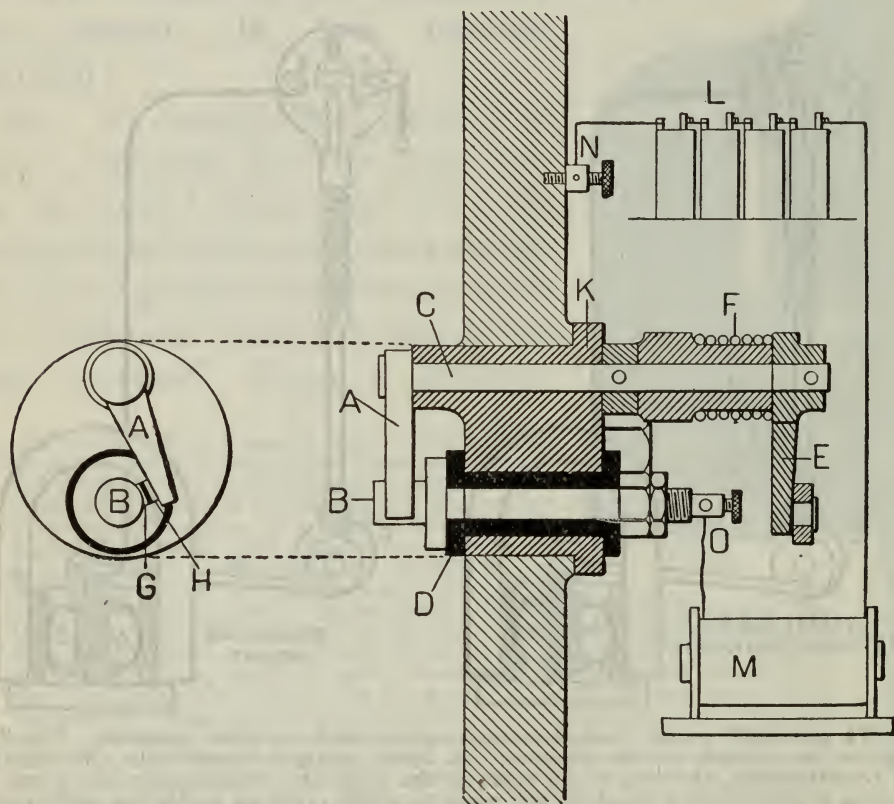
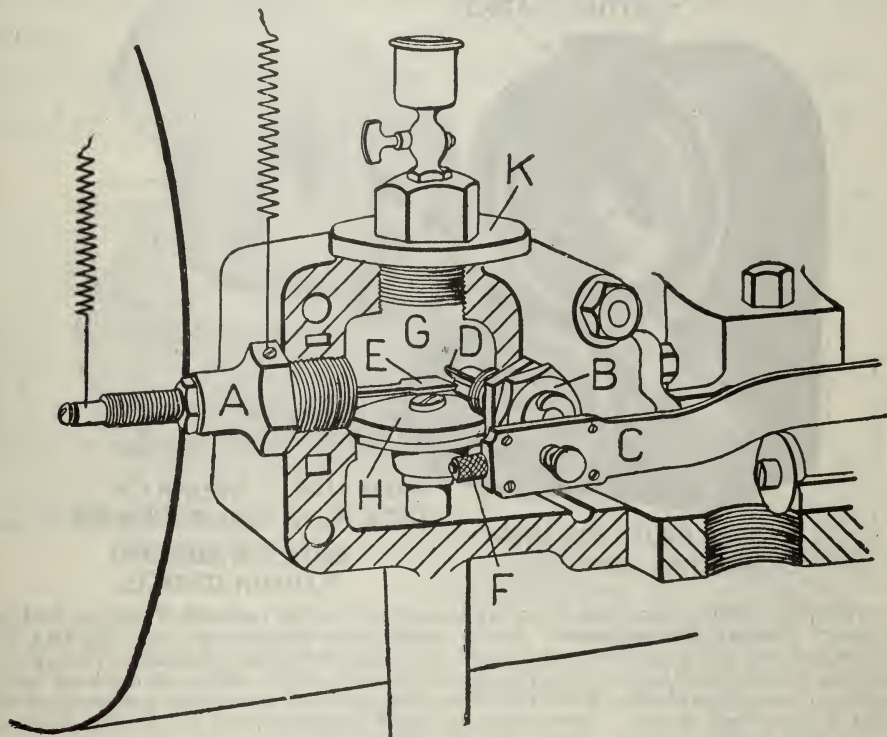


FIG. 3,976.—Hammer break igniter. *It consists of* two metallic terminals A and B. The terminal A is mounted on a movable shaft C, while B is stationary and *insulated* from the cylinder wall by the lava bushing D. A suitable cam rod, attached to the crank E, provides the means for rocking the terminal A, so as to bring it in contact with the terminal B, and then *quickly separate* the terminals to produce the spark. The helical spring F, provides a semiflexible connection between the shaft C, and the crank E. The contact points of the two terminals are tipped with two small pieces of platinum G and H, and both terminals are mounted in the removable plug K, which is usually inserted through the wall of the cylinder head, so that the igniter points extend into the compression space of the cylinder. In the circuit is a battery L, and primary spark coil M. *In operation*, when the igniter terminals are brought together, the circuit is closed through the battery and the spark coil, and when the terminals are *quickly separated*, the self induction of the coil causes an electric arc between the igniter terminals which ignites the charge.



**Ignition with Inductor Magneto.**—In this system of low tension ignition, the current is furnished by a magneto having a stationary armature and a rotating inductor as before described.

The inductor is arranged to either revolve continuously or to oscillate through a small arc. An example of the latter type for low tension ignition is shown in figs. 3,974 and 3,975 which illustrates the Simms-Bosch system.

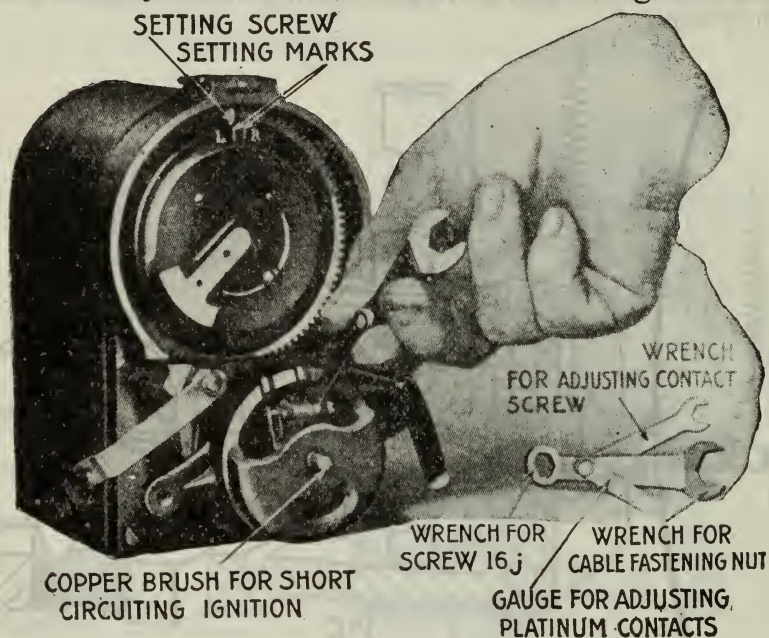


**FIG. 3,977.**—Wipe contact igniter. *It consists of two independent electrodes, the stationary electrode A, and the movable electrode B. The igniter is located in the inlet chamber G, directly over the head of the admission valve H, and either one of the electrodes can be reached for inspection or removal independently by removing the cap K. In operation, when B is revolved by the motion of the igniter rod C, the revolving blade D, is brought into contact with the spring E, at each rotation and produces the spark. A feature of this type of igniter is that the wiping contact prevents the accumulation of burnt carbon on the contact surfaces and this serves to reduce the resistance of the closed circuit. It is subject however to wear of the contact surface, and breakage of the spring. In adjusting the timing can be changed during operation by turning thumb screw F, on the end of the igniter rod, advancing or retarding the arc.*

**Low Tension or Make and Break Igniters.**—These devices may be divided into two general types according to the manner

of separating the terminals, that is to say, according to the method of break, as hammer break, and wipe contact (figs. 3,976 and 3,977.)

**High Tension Ignition.**—In this method of producing a spark, a device called a *spark plug* is employed. It consists of two stationary electrodes, one of which is grounded to the



FIGS. 3,978 and 3,979.—Eisemann type G4 magneto showing method of timing and special wrench. **Timing the magneto:** As the spark occurs when the primary circuit is broken by the opening of the platinum contacts in the make and break mechanism, it is necessary that the magneto will be so timed that at full retard position of the timing lever body, the platinum contacts will open when the respective piston of the engine has reached the top point on the firing stroke. Turn engine by hand until piston of No. 1 cylinder is on the upper dead center; remove distributor plate from magneto and turn the driving axle of the armature until the setting mark on the distributor disc is in line with the setting screw as shown. (For clockwise rotation use mark R, for counter clockwise, use mark L). With the armature in this position, the platinum contacts are just opening, and the metal insert of the distributor disc is in connection with carbon for No. 1 cylinder. The driving medium must now be fixed to the armature axle without disturbing the position of the latter, and the cables connected to the spark plugs.

**NOTE.—Primary Induction Coils.** When an electric current flows along a coiled conductor, an inductive effect is produced which opposes any rapid change in the current strength. This principle is employed in low tension ignition to intensify the spark when a battery forms the current source. The device which accomplishes this effect is known as a *primary induction coil* and consists of a long iron core wound with a considerable length of low resistance copper wire, the length of the core and the number of turns of the insulated winding determining the efficiency. The current passing through the winding magnetizes the soft iron, and a self-induced current is generated. When the circuit is broken, the magnetic reactance tends to continue the flow of current, despite the break in the circuit, and occasions a spark of great heat and brilliancy. *The spark occurs at the moment of breaking the circuit, not at the moment of making.*



engine cylinder and the other insulated. The points of the electrodes are permanently separated from each other by about  $\frac{1}{32}$  of an inch, the space between the points being known as an *air gap*. This space offers so much resistance to the flow of an electric current that a very high pressure is required to cause the current to burst through the air gap and produce a spark, hence the term "high tension ignition," meaning *high pressure* ignition.

Since the spark jumps from one electrode to the other, this method of igniting the charge is also known as the *jump spark*

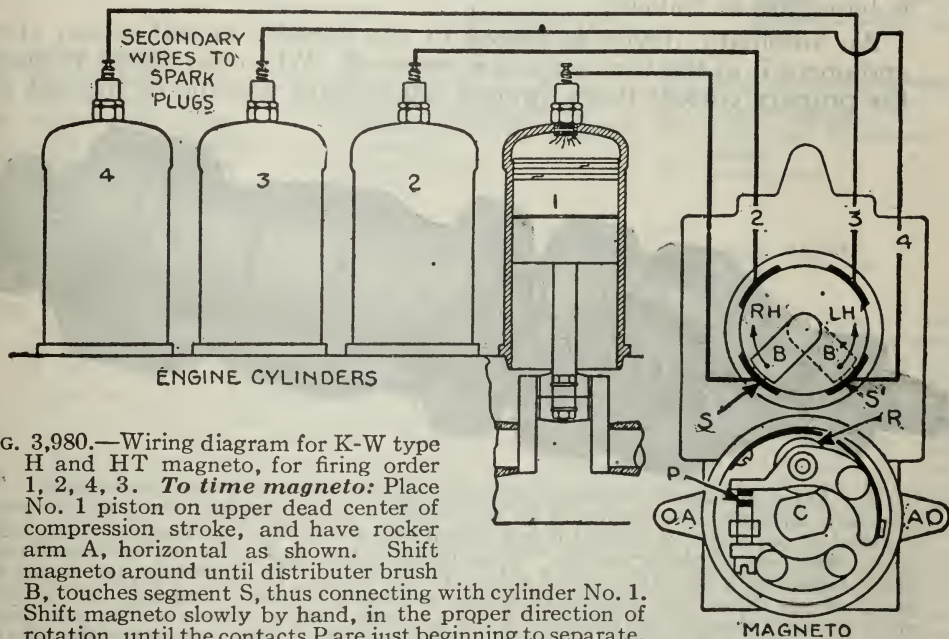


FIG. 3,980.—Wiring diagram for K-W type H and HT magneto, for firing order 1, 2, 4, 3. **To time magneto:** Place No. 1 piston on upper dead center of compression stroke, and have rocker arm A, horizontal as shown. Shift magneto around until distributor brush B, touches segment S, thus connecting with cylinder No. 1. Shift magneto slowly by hand, in the proper direction of rotation, until the contacts P are just beginning to separate.

At this point secure magneto shaft to gear or coupling with set screws. When one cylinder is timed, proceed to connect the others as follows: Ascertain the firing order of the engine, then crank engine slowly and connect plug cable from next cylinder that fires to distributor segment No. 2 and so on until all the plug cables are connected. The secondary connections on the hard rubber distributor block are numbered in consecutive order, 1, 2, 3, 4, etc. These numbers do not refer to the engine cylinders, and it is necessary to determine the order in which the cylinders fire and connect secondary cables accordingly. Replace parts on the magneto and start the engine to test the setting. See that all nuts and connections are tight, also that retainer spring has been replaced. There should be a tendency for the engine to kick back slightly when starting, and if it do not, advance magneto until it does kick slightly. To advance, shift coupling against direction of rotation. To retard, shift coupling with direction of rotation. Shift slightly each time until correct position is obtained. Pin magneto shaft to gear or coupling with taper pin, do not depend on a set screw, as it will surely work loose in time.



system. The spark itself is properly described by the prefix *high tension* or *secondary*.

In the production of the spark two distinct circuits are necessary; 1, a low tension or *primary* circuit and 2, a high tension or *secondary* circuit. The current which flows through the low tension circuit is called the *primary current* and that which it *induces* in the high tension circuit, the *secondary current*.

In order to obtain the high pressure required to produce a spark, a device known as a *secondary induction coil* is used which transforms the primary current of low voltage and high amperage into a secondary current of high voltage and low amperage, that is, the quantity of the current is decreased and its pressure increased.

The general principles upon which high tension or jump spark ignition is based are as follows:

An automatic device is placed in the primary circuit which closes and opens it at the time a spark is required. When the circuit is closed, the primary current flows through the primary winding of the coil and

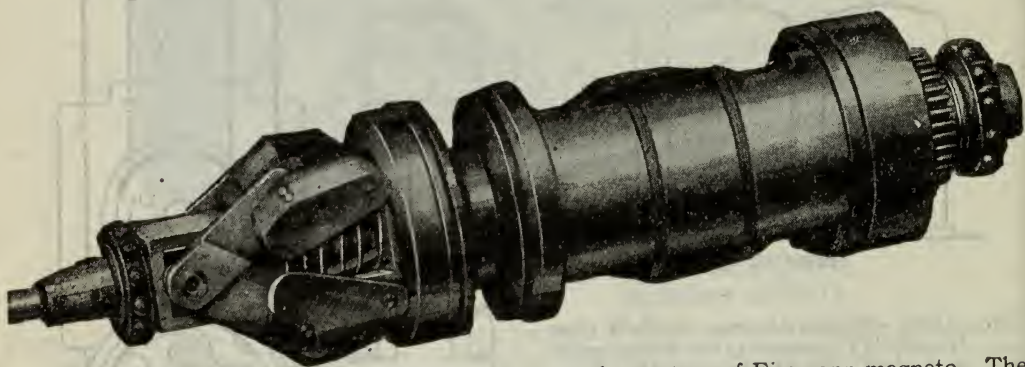
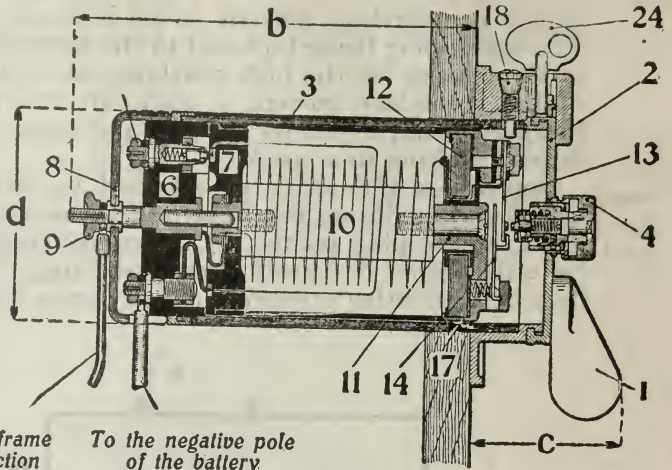
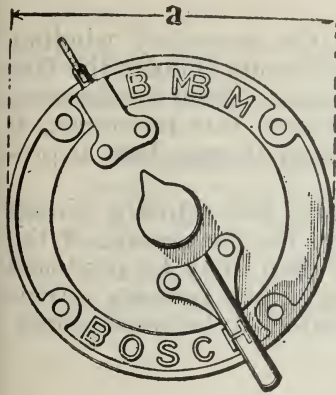


FIG. 3,981.—Automatic spark advance mechanism and armature of Eisemann magneto. The automatic advance is accomplished by the action of centrifugal force on a pair of weight attached at one end to a sleeve through which runs the shaft of the magneto, and hinged at the other end of the armature. Along the armature shaft, run two helicoidal ridges which engage with similarly shaped splines in the sleeve. *In operation*, the rotation of the armature causes the weights to spread and exert a longitudinal pull on the sleeve which in turn changes the position of the armature with reference to the pole pieces. Thus, the moment of greatest induction is advanced or retarded and with it the break in the primary circuit, for the segments (or cams) which left the circuit breaker and cause the break in the primary circuit are *fixed* in the correct position and thus the break occurs only at the moment when the current in the winding is strongest. On other magnetos it is the segments or cams that are moved forward or back as the case may be. To apply the automatic control principle to any engine, there have been produced spindles of varying pitches; spindles that will give 19, 25, 38, 45 and 60 degrees advance. For use in connection with these spindles, there are sixteen different springs. With these parts, in connection with the governor mechanism, 160 advance curves can be produced. By varying the length of the stop on the bronze nut, more may be obtained. Many engines require a great deal of advance, others will not permit of more than 20 to 25 degrees. It is necessary to take into consideration the size and shape of the combustion chamber, the compression, the position of the spark plugs and the speed of the motor. It is also universally acknowledged that an engine of high compression will give a quicker burning mixture and will not require, or in some cases, stand, as early a spark as one of lower compression.



1. Switch handle.
2. Movable cover.
3. Coil housing.
4. Starting press button.
6. Fixed connection plate.
7. Movable switch plate.
8. Cable cover.

- To the frame Connection  
To the negative pole of the battery
9. Milled edged nut.
  10. Iron core.
  11. Plate carrying the starting arrangement and the condenser.
  12. Condenser.
  13. Contact spring.
  14. Vibrator.

15. } Auxiliary contact breaker.
16. }
17. Vibrator spring.
18. Stop screw for switch handle.
24. Locking key.

<u>Dimensions</u>	a = 105 mm
	b = 135 "
	b = 50 "
	d = 71 "

## Horizontal Coil Type "C".

**FIGS. 3,982 and 3,983.**—Bosch type C horizontal secondary coil. **In construction,** a movable brass cover 2 carries the switch handle 1, and is attached to the cylindrical coil housing 3 by means of a bayonet joint. The press button used for starting projects from the center of the cover. A pin set on the coil end plate engages an opening in the cover, which causes the coil and cover to move together. The switch contacts being located on the other end plate of the coil, this permits the operation of the switch by the movement of the cover. **Switch positions:** Four positions are provided, 1, O, off, 2, B, battery, 3, MB, magneto and battery, 4, M, magneto. The base of the coil housing is formed by the stationary switch plate 6, and the contacts carried on it register with the contacts of the movable switch plate 7. The partial rotation of the coil by the movement of the cover plate causes the different switch contacts to engage. The coil body consists of a cylindrical iron core 10, upon which are wound the primary and secondary windings; the former consists of a few layers of heavy wire, and the latter of many layers of fine wire. One end of the primary winding is connected to a segment on switch plate 7, while the other end leads to the vibrator, from whence it passes to ground. The iron core 10; carries the condenser 12, and to it is screwed the end plate 11 that supports the starting device. The parts of the starting device are the brass button 4, the contact spring 13, and the vibrator blade 14. When the switch handle is turned to either of the battery positions, a pressure on button 4, will complete the primary circuit by causing the contact pin to touch the platinum point carried on spring 13. This contact will be in parallel with the primary timer, and the current will flow from the blade 14, to the end plate 11, to the iron core 10, and by binding post 9, to ground. **Lock:** The coil is provided with a key lock, which may be operated only when the coil is in the "Off" position. This prevents the unauthorized use of the engine, and by making it impossible to lock the switch in any of the operative positions, renders unlikely that the switch will be left unintentionally on one of the battery positions to the injury of the battery. **Battery voltage:** The coils are wound for a current of six volts, and a six volt, sixty ampere hour storage battery is recommended. If it be necessary to use dry cells, ten should be provided for a 4 cylinder system, and twelve for 6 cylinders, connected in series parallel. They should be divided into two groups of five or six cells each; the cells of each group should be connected in series, and the groups connected together in parallel.



causes a secondary current to be induced in the secondary winding. The spark plug being included in the secondary circuit opposes the flow of the current by the high resistance of its air gap. Since the pressure of the secondary current is sufficient to overcome this resistance, it flows or "jumps" across the gap and in so doing, intense heat is produced resulting in a spark.

Sometimes the spark is obtained by keeping the primary circuit closed except during the brief interval necessary for the passage of the spark at the plug points. A secondary spark, then, may be produced by either open or closed circuit working, that is, the primary circuit may be kept either opened or closed during the intervals between sparks.

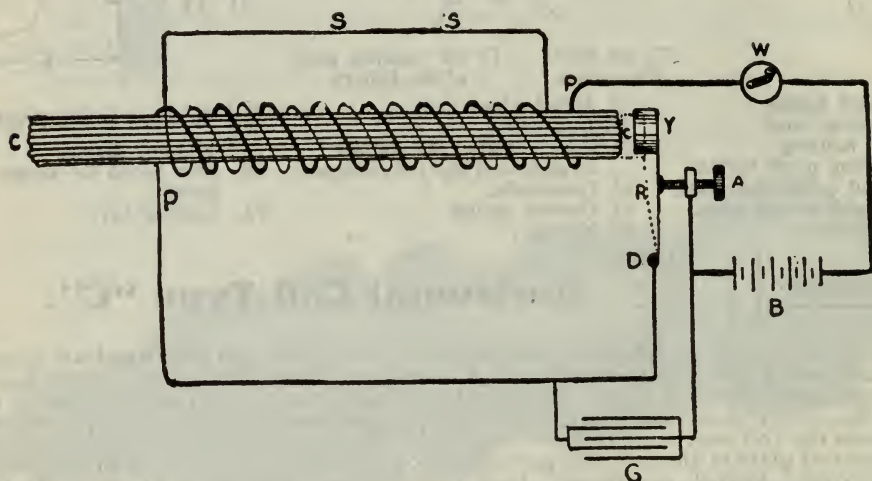


FIG. 3,984.—Diagram of a secondary, vibrator type induction coil. *The parts are as follows:* A, contact screw; B, battery; C, core; D, vibrator terminal; G, condenser; P, primary winding; S, secondary winding; W, switch; Y, vibrator. *In operation*, when the switch is closed, the following cycle of action takes place: *a*, the primary current flows and magnetizes core; *b*, magnetized core attracts the vibrator and breaks primary circuit; *c*, the magnetism vanishes, inducing a momentary high tension current in the secondary winding, producing a spark at the air gap; *d*, magnetic attraction of the core having ceased, vibrator spring re-establishes contact; *e*, primary circuit is again completed and the cycle begins anew.

The automatic device which controls the primary current to produce a spark by the first method is called a *contact maker*, and by the second method, a *contact breaker*. A closed primary circuit with a contact breaker is used to advantage on small engines run at very high speed as it allows time for the magnetism or magnetic flux in the core of the coil to attain a density sufficient to produce a good spark. The word *timer* is usually applied to any device which controls the primary current, when it controls both the primary and secondary currents, as in *synchronous ignition*, it is called a *distributor*. Before explaining the different systems of high tension ignition the several devices used, such as induction coils, spark plugs, etc., will be described in some detail.



Among the various devices used in high tension ignition the following are of importance and the function and construction of each should be clearly understood.

**Secondary Induction Coils.**—In order to obtain the high voltage necessary to produce a secondary (jump) spark, a secondary induction coil is used: it is a species of transformer and transforms the primary low tension current into a secondary high tension current. It consists essentially of four main parts: 1, an iron core; 2, primary winding, 3, secondary winding, and 4, condenser.

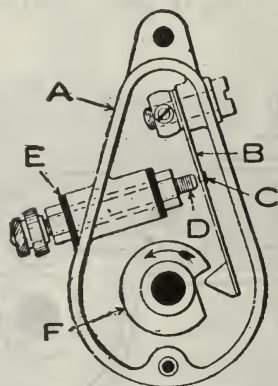


FIG. 3,985.—Contact maker and mechanical vibrator. The case, A, is usually attached to the gear box of the engine; B, is the vibrator blade; C, a platinum contact point; D, an insulated adjusting screw; E, a bushing with insulation; F, the operating cam. As this cam revolves the weight on the end of blade, B, drops into the recess on the cam causing the blade to vibrate and make a number of contacts with D, thus producing a series of sparks when in operation.

**Timers.**—These devices are simply revolving switches operated by the engine and so adjusted that the primary circuit is made and broken in proper sequence with the engine cycle, so that the spark may occur at the proper point with respect to the crank position. A timer is geared to revolve at one half engine speed for a four cycle engine, and at engine speed for a two cycle engine. *The distinction between timers and distributors should be carefully noted, to avoid the usual erroneous use of these terms.*

**Special Forms of Timer.**—In order to meet certain conditions of operation, special timer construction is sometimes used, giving rise to types of timer which are known as:

1. Contact makers;
2. Mechanical vibrators, or *tremblers*;
3. Contact breakers;
4. Interrupters.

A *contact maker* keeps the circuit **closed** for only a short interval, whereas, a *contact breaker* keeps the circuit **open** for only a short interval. A contact breaker is intended to meet the conditions of extreme high speed, that is, by keeping the primary circuit closed except during the brief interval necessary for the passage of the spark, sufficient time is given for the magnetic flux of the core of the magnet to attain a sufficient density to induce a secondary current of the required strength.

An interrupter is virtually a contact maker located on a magneto and forming a part of the latter machine.

**Distributers.**—When one secondary coil only is used with a multi-cylinder engine as in synchronous ignition, a device called a distributor is a necessary part of the system. Its use is to direct the discharge of a single coil to the spark plug of each cylinder in rotation. A distributor

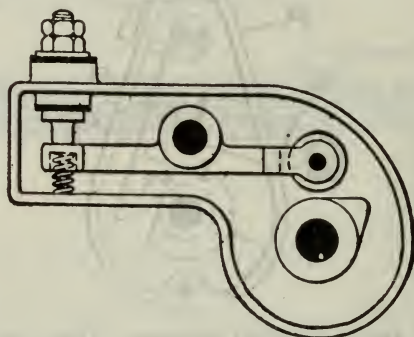


FIG. 3,986.—Contact breaker. This device keeps the circuit closed at all times except during the brief interval necessary for the passage of the spark at the plug points. It is used to advantage on engines running at very high speeds, as it allows time for the magnetic flux in the core of the coil to attain a density sufficient to produce a good spark.

consists of a timer for the primary current, and a similar device for the secondary current working synchronously, that is, in step with the timer and which switches the secondary current to the various spark plugs in the proper order of firing.

In other words, a distributor is a combination of two timing devices working in unison with each other; one makes and breaks the primary

NOTE.—*The primary element of a distributor* contains as many stationary contacts as there are cylinders and a revolving arm or *rotor* which in its revolution touches each of the stationary contact so that the primary circuit is made and broken once for each cylinder during one revolution of the arm. *The secondary element* is above and concentric with the primary part. It has a rotor and the same number of stationary contact as the primary element; the parts of both elements are arranged symmetrically with each other and are contained in a compact cylindrical casing. A shaft geared to the engine operates both the primary and secondary rotors. The primary rotor is in metallic contact with the shaft and forms with it and the engine a ground return for the primary circuit. The secondary rotor is carefully insulated. All the primary stationary contacts are connected to one common terminal which receives the primary lead. A binding post is provided for each of the secondary stationary contacts and one for the secondary rotor. These binding posts are usually placed on the top part of the casing.



circuit, while the other makes and breaks the secondary circuit and in so doing distributes the current to the several cylinders in correct sequence.

**Spark Plugs.**—In all high tension ignition systems a *permanent air gap* is placed in the secondary circuit across which the current must jump to produce a spark. The device by which this permanent air gap is maintained is called a *spark plug*. There are several varieties

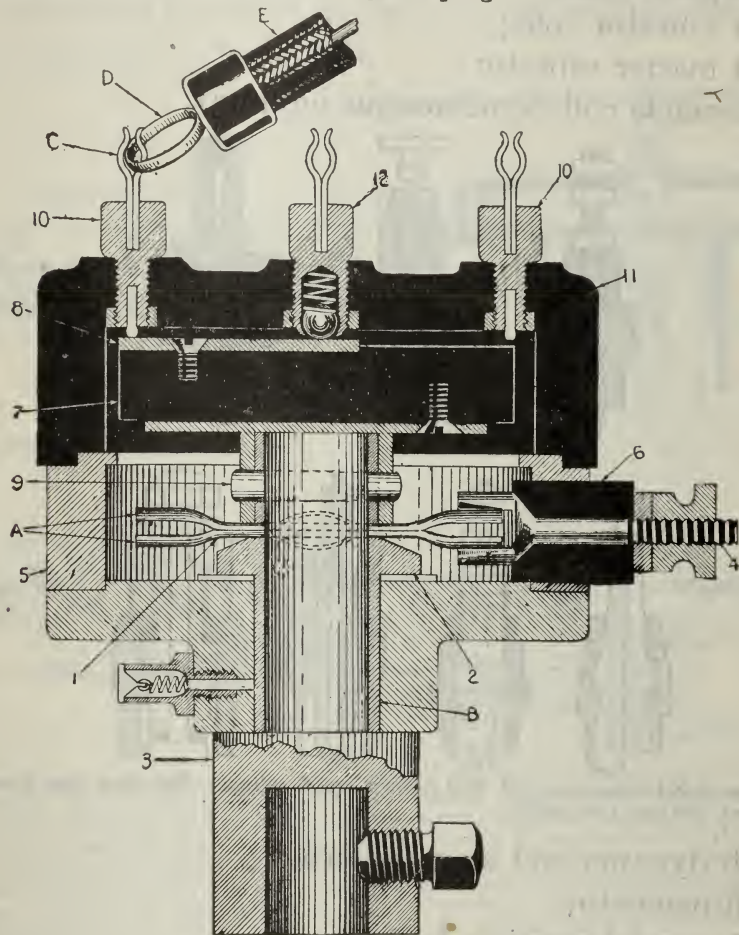


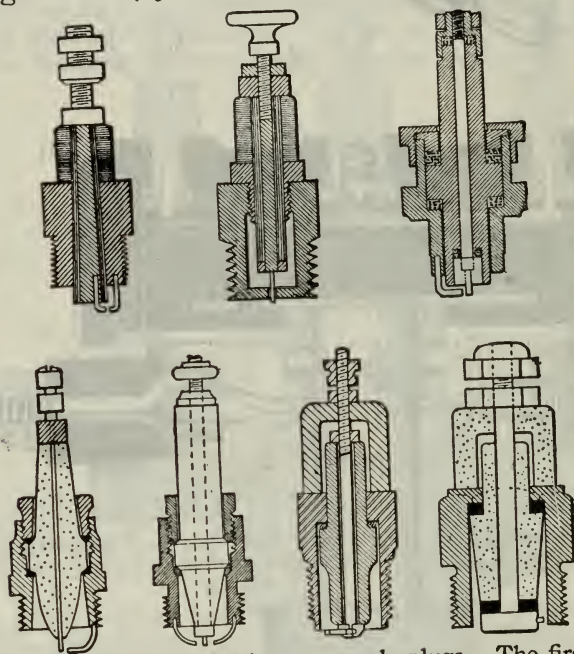
FIG. 3,987.—Sectional view of the Pittsfield distributor. In this device several revolving contacts are employed instead of one; these consist of a double spring making sliding contact at the portions, A. **The parts are:** 1, contact springs; 2, shaft; 3, bushing; 4, stationary terminal; 5, timer ring; 6, stationary contact insulation; 7, distributor plate; 8, secondary revolving contact segment; 9, taper pin; 10, secondary stationary terminals; 11, casing; 12, secondary terminal for lead to coil; B, slide bearing; C, hook; D, eye; E, secondary cable. The principles of distributor operations are plainly shown in fig. 3,998.

of spark plug, of which the following are extensively used: 1, *primary*, or magnetic make and break plugs, 2, *secondary*, or jump spark plugs, including plain and special forms such as coil plugs.



**Various High Tension Ignition Systems.**—There are a number of satisfactory method for producing a secondary or high tension spark, such as ingition

1. With plain coils;
2. With vibrator coils;
3. With master vibrator;
4. With single coil (synchronous ignition);



FIGS. 3,988 to 3,994.—Sections of well known spark plugs. The first five have porcelain insulation; the last two, mica.

5. With dynamo and storage battery;
6. With magneto;
7. With special igniting devices.

**NOTE.—Sparking pressure.** A current of very high voltage is required to produce a secondary or jump spark on account of the great resistance of the air gap and compression pressure which oppose the current flow. The required voltage will depend on the length of the air gap and, the intensity of the pressure inside the cylinder. For ordinary spark plugs in air the sparking pressure will vary from about 3,000 to 5,000 volts according to the length of the gap, but to produce a spark in an engine cylinder where the mixture has been compressed to four or five times the atmospheric pressure, will require from 10,000 to 20,000 volts. **When a spark plug will not work,** the electrodes and insulating material should be thoroughly cleaned with fine sandpaper and the distance between the points adjusted to about one thirty-second of an inch, or the thickness of a ten cent silver piece. If the battery be weak, the gap may be made smaller.

**Ignition with Plain Coils.**—The first high tension system to attain popularity was the single spark system using a plain coil and contact maker. This being the simplest method of producing a secondary spark, it will serve to illustrate the several principles involved in jump spark or high tension ignition, as explained in fig. 3,995.

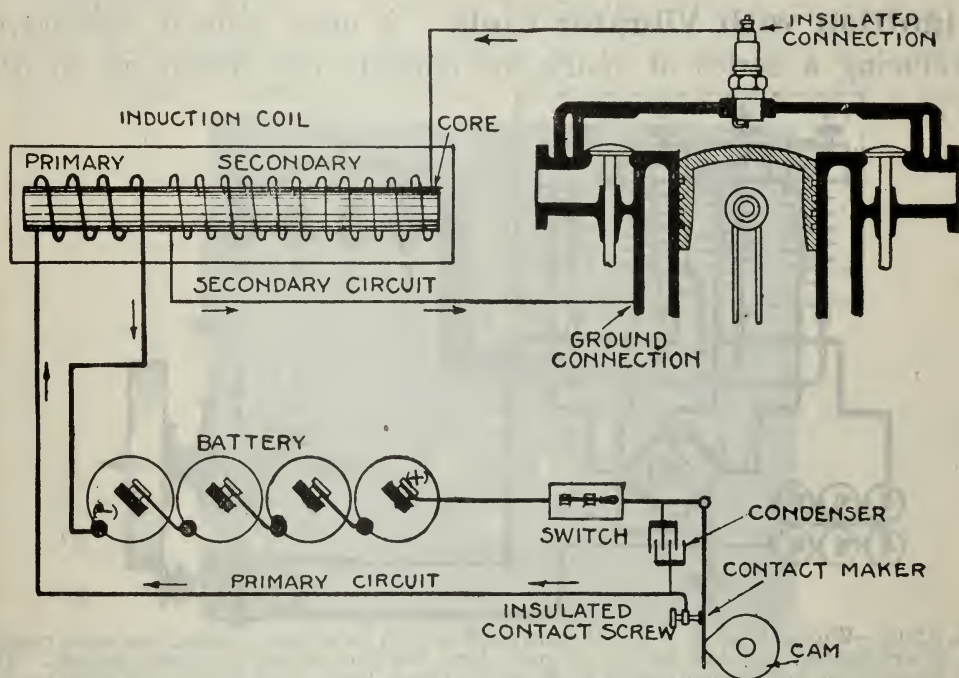


FIG. 3,995.—Diagram illustrating the principles of high tension or jump spark ignition. The nose of the cam in revolving engages the contact maker which completes the primary circuit and allows current to flow from the battery through the primary winding of the coil; this magnetizes the core. The primary circuit is now broken by the action of the cam and magnetic changes take place in the coil which induce a momentary high tension current in the secondary circuit. The great pressure of this current forces it across the air gap of the spark plug and as it bridges the gap a spark is produced. The arrows indicate the paths of the currents. At break, the primary current is "slowed down" by the condenser, thus preventing an arc between contact breaker contacts.

**Ignition with Mechanical Vibrators.**—The view held by some that a series of spark closely following each other is more effective for ignition than a single spark, led first to the introduction of the mechanical vibrator. This system employs a plain coil and is identical with the one just described with the



exception that in place of the make or break timing device, a mechanical vibrator is used which gives a succession of spark for firing each charge.

As the rotor of the timer revolves, it touches each of the stationary contact and in so doing, the above cycle is repeated for each cylinder in the order of firing, as wired.

**Ignition with Vibrator Coils.**—A more refined method of producing a series of spark for igniting the charge is by the

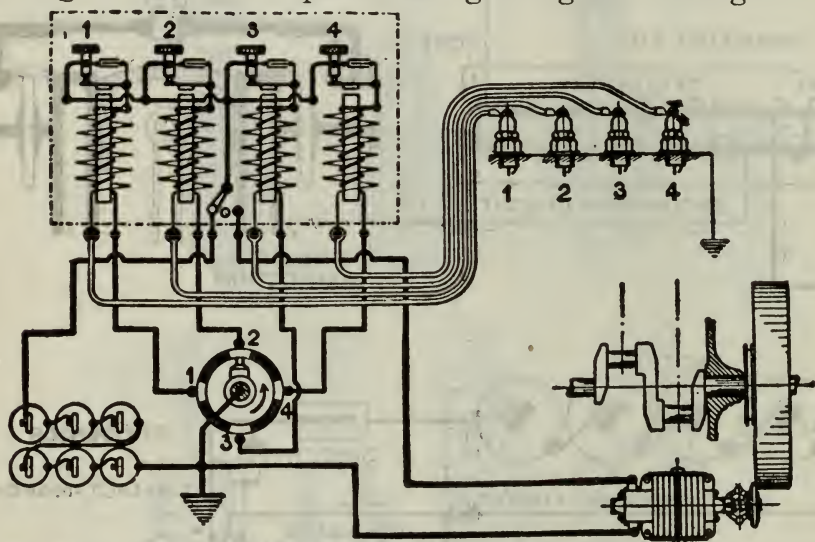


FIG. 3,996.—Wiring diagram of a dual jump spark system for a four cylinder, four cycle engine. A dry battery and low tension magneto form the two sources of current supply. The primary, or low tension circuit is shown by heavy lines, the secondary or high tension circuit by fine lines, and the leads to spark plugs by the double lines. The dotted rectangle represents the outline of a four unit dash coil. **In the coil connections** it should be noted that the adjustable contact screw of each vibrator is connected by a common wire terminating at the two way switch; also, in each unit one end of the secondary winding is connected to that end of the primary, leading to the vibrator blade. These common connections simplify the external wiring, as otherwise there would be four binding posts for each unit. The two way switch just referred to permits the current supply to be taken from either of two sources, such as a battery and a magneto. Current is supplied by the battery when the switch is in the position shown in the figure. By turning the switch to the right, a current from the magneto will be furnished. With the battery in the circuit and the timer in the position shown, **the operation is as follows:** Current flows from the positive terminal of the battery, to the switch, thence, to the contact screw of coil number two. From here, it flows through the vibrator blade, primary winding of the coil timer and the metal of the engine, and returns to the battery. The primary circuit is alternately opened and closed with great rapidity by the vibrator so long as the rotor of the timer is in contact with terminal 2. During this interval, a series of high tension current is induced in the secondary circuit, producing a series of spark. The current which flows through the secondary winding is in a direction opposite to that of the primary current. At each interruption of the primary current, an induced high tension current flows through the secondary winding, to the spark plug, across the gap, producing a spark and returns through the metal of the engine, timer, and back to the coil.



use of a vibrator coil. The magnetic vibrator is a marked improvement on the mechanically operated device as it vibrates with greater rapidity and is capable of delicate adjustment. This system which is extensively used is illustrated in fig. 3,996, which is a wiring diagram for a four cylinder engine.

**Ignition with a Master Vibrator.**—In a multi-unit coil there is a vibrator for each unit, all of which may be operated by a single or master vibrator. The advantage of such a system

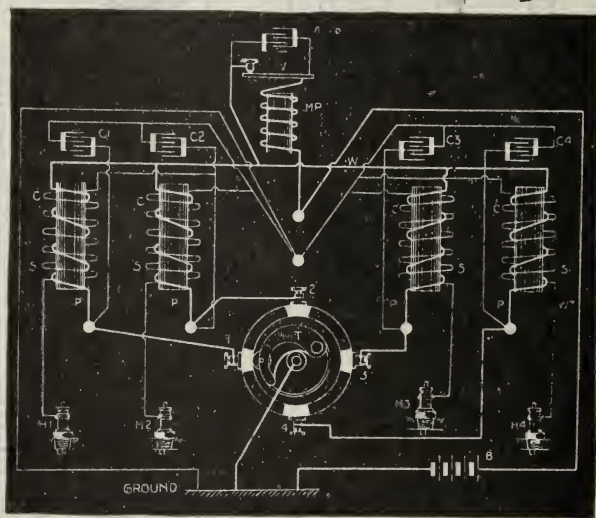


FIG. 3,997.—Circuit diagram of a master vibrator coil. B, is the battery; C, the unit coils; C1, C2, etc., the condensers; P, the primary windings and S, the secondary windings; H1, H2, etc., the spark plugs; T, the timer; MP, the master primary; V, the vibrator; W, the common primary connection; 1, 2, etc., the stationary contacts of the timer. The primary windings are all united in parallel at the top by a wire W, and with the lower ends connecting respectively with the segments of the timer T. The primary winding MP which operates the vibrator V is in series with this winding, the wire WT connecting from the battery and passing directly through the master primary MP. The four condensers, C1, C2, C3 and C4, are in parallel with the primary windings. Each of the secondary windings S connects direct to the spark plugs, designated respectively H1, H2, H3 and H4.

is that there is but one vibrator to keep in adjustment, since this vibrator serves for all the cylinders; whereas, with one for each unit, all have to be kept in adjustment and the difficulty of keeping the several adjustments is a considerable factor. The diagram, fig. 3,997, illustrates the circuit and operation of a master vibrator.

**Synchronous Ignition.**—This system employs a distributor and a single coil for a number of cylinder. It is called “synchronous” for the following reason: when a multi-cylinder engine has a coil unit for each cylinder, it requires the adjustment of several vibrators. Now, the time required by the vibrator to act is variable with the adjustment and with slight differences

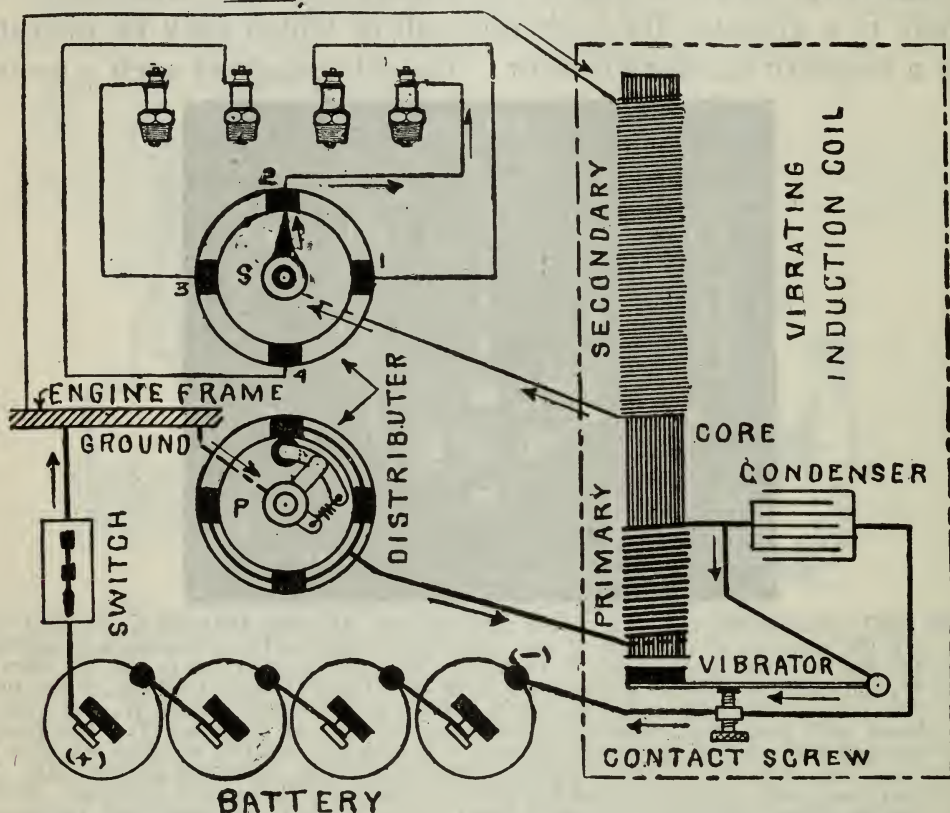


FIG. 3,998.—Diagram illustrating the principles of synchronous ignition. For clearness the primary and secondary elements of both the coil and the distributor are shown separated. When the primary rotor of the distributor completes the primary circuit, current from the battery flows and the vibrator operates, making and breaking the current with great frequency. A high tension current, made up of a series of impulses, is induced in the secondary circuit and distributed by the rotor arm during its revolution to the several cylinders in the proper order of firing. Each secondary segment of the distributor being wired to one of the spark plugs, the rotor during its revolution brings each plug into the secondary circuit in the order indicated in the diagram. As shown, the secondary rotor is in contact with segment number two which causes the induced current to flow from the secondary winding, through the distributor. One end of the secondary winding is usually connected to one end of the primary winding instead of making a separate connection to the metal of the engine. This simplifies the wiring by having one common ground connection.



in construction, hence, of the several vibrators, perhaps no two will act in exactly the same time. Consequently, though in the ordinary multi-unit coil system, the closing of the primary circuits may occur at exactly corresponding moments for all cylinders, the production of the spark will be more or less "out," owing to the variation in the "lag" of the different vibrator.

With a distributor and single coil, the lag is the same for all the cylinders, hence, the application of the word *synchronous*.

Fig. 3,998 is a wiring diagram showing the connections of a synchronous system; for clearness, the two windings of the coil are shown separated from each other and for the same reason also the primary and secondary elements of the distributor are separated.

**Magneto Ignition.**—There are numerous types of magneto used for igniting purposes. In the several systems, therefore, different methods of wiring are required. In the true high tension and the self-contained types where the coil and condenser are a part of the magneto, the number of external connection is less than with those having the coil in a separate box.

In starting an engine equipped solely with a magneto, it is necessary to turn the crank much faster than when a battery is used, because the armature must be turned at a certain speed to generate the required current. Due to the refinement of design this factor has been reduced and most magnetos will give a spark sufficient for ignition even if the armature be revolved quite slowly.

To secure satisfactory ignition with a magneto it is very essential that the various joints of the primary circuit be kept in perfect condition,

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NOTE.—In connecting up batteries and coils it is recommended that the vibrator screws be made "positive," so that whatever platinum is carried away by the arc may be taken from the screw and deposited upon the contact point of the vibrator. The theory is that the screw is cheaper and easier to replace than is the vibrator, and that, with this arrangement, the vibrator point builds up rather than wears away, requiring only the smoothing off of the extra metal deposited upon it to keep it in condition.

NOTE.—The very slight wear produced upon vibrators operated from non-synchronous alternating current magnetos from which the current is in each direction for one-half of the time, in the aggregate, is well known. Hence, when a battery is used, if the operator would periodically change the direction of the current flow by reversing the two battery wires connecting the one which has gone to the positive pole, to the negative and vice versa, he will find that the wear of the vibrator points is reduced to a minimum.



that is to say: all terminals should be clean, bright, and firmly connected.

*The interrupter contacts should be kept **clean** and **true*** using a fine file to square the surface, so that the entire surface of one contact will touch the other.

The two brushes leading to armature coil must be kept clean, free of oil and springs adjusted to secure good contact.

Most operators pay too little attention to the secondary circuit contacts. These also should be kept clean, true, and springs properly adjusted.

When an engine will not start on the magneto or requires unusually rapid spinning to effect ignition, it is a strong indication that the primary and secondary contacts are not in proper condition.

When a magneto ignition system fails, the trouble is almost always due to faulty condition of the contacts.

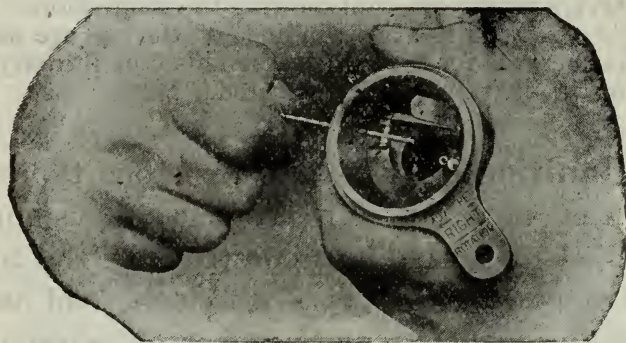


FIG. 3,999.—Filing slot for cleaning platinum contacts of Connecticut magneto interrupter. The cup holding the interrupter or primary circuit breaker may be withdrawn from its housing. The slot serves as a guide for a small flat file for cleaning and squaring the contact points. By means of an adjustable gauge furnished with the magneto, the correct opening of the contact points may be determined. The interrupter is provided with a single roller bearing against the cam pins, thus insuring accurate timing at any speed and unaffected by centrifugal force. The advance lever can be connected at either side of the magneto as the interrupter housing is reversible. The cams are renewable by a half turn with a screw driver.

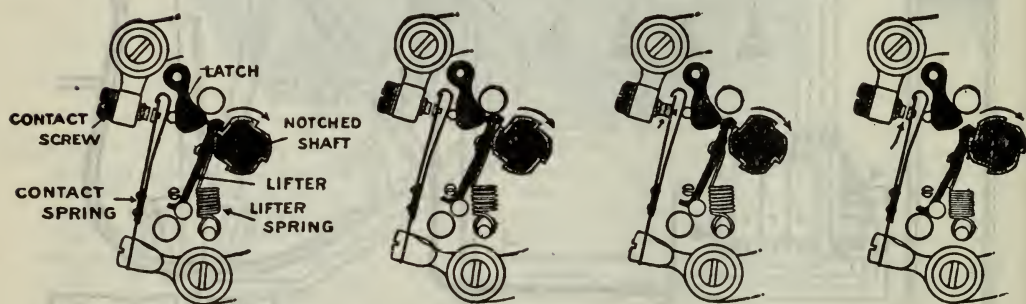
**Dual Ignition.**—As defined, a dual ignition system is *one having two separate current sources with **some parts** of the ignition apparatus in common.* Most magneto systems are examples of dual ignition, that is the distributor which forms a part of the magneto is used to distribute the current from either the magneto or a battery. Thus, if a short circuit occur in the armature, by turning a switch, current may be *furnished* by the battery and *distributed* by the magneto. Moreover, because of the difficulty of cranking an engine fast enough to start on the magneto,





several seekers after battery economy with coil ignition to develop and place on the market devices in which a single break in the primary circuit is caused mechanically at each instant at which it is desired to ignite the charge within the engine cylinders.

These "single-break" coil systems embody, in their most highly developed forms, a single plain coil, a secondary timing device for the induced high tension current and a timer or circuit breaker which causes a sharp break in the circuit of the primary coil winding each time an ignition spark is required. After the coil itself, the circuit breaker is the chief component of single coil systems with distributor, designed to produce but one spark per ignition. Upon it depends the effectiveness



FIGS. 4,001 to 4,004.—Principle of the Atwater-Kent ignition system. The so called "unisarker" consists of a notched shaft, one notch for each cylinder, which rotates at one-half the engine speed, a lifter or trigger which is pulled forward by the rotation of the shaft and a spring which pulls the lifter back to its original position. A hardened steel latch and a pair of contact point complete the device. The figures show the operation of the contact maker very clearly. It will be noted that in fig. 4,001 the lifter is being pulled forward by the notched shaft. When pulled forward as far as the shaft will carry it fig. 4,002, the lifter is suddenly pulled back by the recoil of the lifter spring. In returning, it strikes against the latch, throwing this against the contact spring and closing the contact for a very brief instant—too quickly for the eye to follow the movement (fig. 4,003). Fig 4,004 shows the lifter ready to be pulled forward by the next notch. Note that the circuit is closed only an instant preceding the spark. No current can flow at any other time, not even if the switch be left "On" when the engine is not running. Note that no matter how slow or how fast the shaft is turning, the lifter spring will always pull the lifter back at exactly the same speed, so that the operation of the contact, and therefore the spark, will always be the same, no matter how fast or how slow the engine be running. The contact points are adjustable only for normal wear. By means of the distributor, which forms the upper part of the unisarker, the high tension current from the coil is conveyed by the rotating distributor block, which seats on the end of the unisarker, to each of the four spark plug terminals in the order of firing.



of the spark, and in some measure also the current consumed in the coil in producing it.

In consideration of battery economy, it is necessary that the circuit breaker make only a sufficiently long contact to secure the proper building up of the magnetic field about the coil windings, before the occurrence of the break. Because of this, it is usual to so set the adjustable point of the breaker that the contact duration is the minimum with which a proper igniting spark can be secured. The author objects to primary battery systems, except on some single cylinder engines, because the current is of constantly decreasing strength and batteries of short life, necessitating frequent renewal.

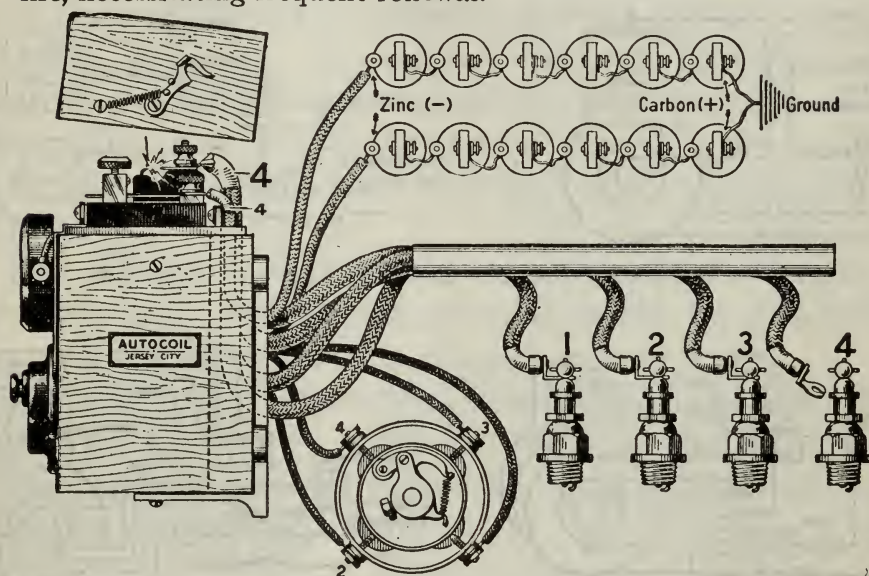
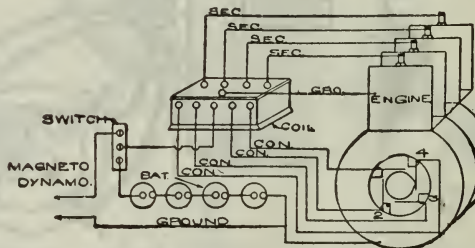
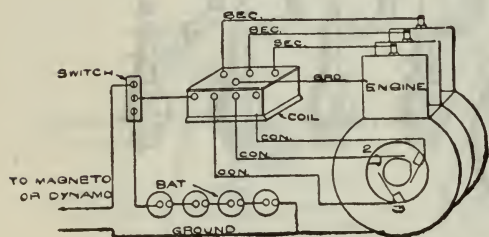
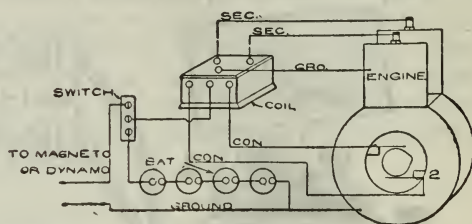
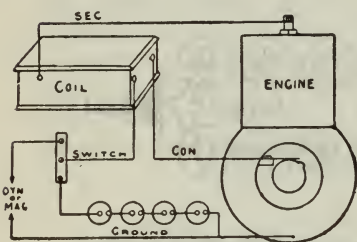
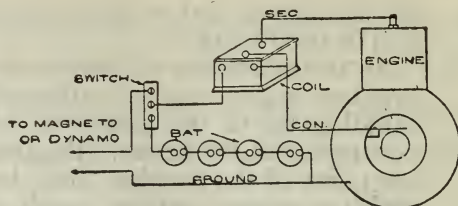
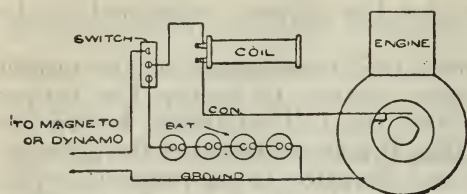


FIG. 4,005.—Auto coil wiring diagram showing coil box and connections. The picture shows clearly how to bring the battery, timer and plug wires to the coil. The wires can enter through the middle back or from the bottom of the coil box, through holes provided for the purpose. It is important to connect the zinc or (—) battery wires to coil, the carbon or (+) wires being connected to ground or frame of engine. It is also important to shave or pare back the braid on the secondary or high tension wires as shown in picture. If the braid be connected to any metallic portion of the wire or terminal clip, there will be a noticeable leak on damp days, as the oil in the braid sooner or later dies out, and the braid quickly absorbs moisture, and moist braid will cause the high tension current to escape to the frame of the engine.

**Ignition Troubles.**—To successfully cope with ignition troubles there are two requisites: 1, a thorough knowledge of the system used, and 2, a well ordered course of procedure in looking for the cause of the trouble.

In many ignition systems the chief difficulty encountered in the location of defects arises from the fact that faults in different



FIGS. 4,006 to 4,011.—Knoblock coil wiring diagrams. Fig. 4,006, connections for make and break engine, showing battery, magneto and double switch. If magneto be not installed, use a single switch in place of the double switch; Fig. 4,007, connections for single cylinder jump spark engine using either vibrator or non-vibrator coil; fig. 4,008, connections for jump spark coil with three terminals; fig. 4,009, connections for two cylinder jump spark coil; fig. 4,010, connections for three cylinder jump spark coil; fig. 4,011, connections for four cylinder jump spark coil.

**NOTE.—How to adjust a vibrating coil.** Good coils, when properly adjusted, consume about one-quarter to one-half ampere for each engine cylinder. By screwing down the points too close, the current consumption may be greatly increased to the detriment of the mileage and without any advantage. Therefore, it is advisable to see that the coil is adjusted so as to take no more current than is necessary. To do this connect an ammeter in the place usually left for a connection on a coil, or insert the ammeter in the battery connection, so that the current flows from the battery through the ammeter to the coil. Place a piece of paper under all but one of the vibrator points with the engine running. Adjust this point until the current taken by its cylinder is a minimum, without, however, any tendency to miss explosions. If the engine will not run with only one cylinder working, the current taken by each contact point may be determined by blocking this one point off with a piece of paper and noting the change in the current that this causes. Adjust the point and try this again, until the lowest current consumption on which the engine will run properly is obtained. The proper voltage for a battery in most cases is 6 volts.



portions of the circuit sometimes make themselves manifest by the same symptoms. If each defect had its individual symptom, locating the trouble would be comparatively easy, but, as it is, it is sometimes quite difficult to find the defective parts. In general, the following method, should be adopted to locate ignition troubles:

1. The source of current supply should be examined; if a battery, each cell should be tested separately, and any one found to be weak, removed. If a magneto be used, it should be disconnected, and the armature turned by hand; in case the field magnets have not lost their proper strength, the armature should turn perceptibly hard during certain portions of each revolution.

2. The primary circuit should be examined for breaks; all connections made bright and secured firmly by the binding screws, and the timer contacts cleaned.

3. The spark plug points should be cleaned and the air gap made the proper length—about one thirty-second of an inch.

4. The vibrator contacts should be made flat and clean, and the vibrator properly adjusted.

**Testing the Spark Plug.**—The spark plug should be unscrewed and placed on the cylinder without disconnecting the wire to the insulated electrode: the body of the plug only should touch the metal of the cylinder. On cranking the engine the spark should be "fat" if everything be in good condition; if a weak spark be produced it may be due to either a loose terminal, run down battery, or badly adjusted vibrator. When no spark can be obtained the entire system must be examined and tested, beginning at the battery.

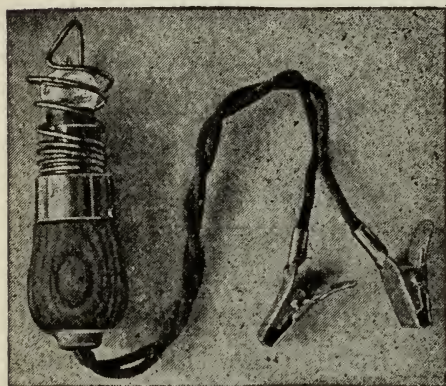
**Plug Testing in Multi-Cylinder Engines.**—All nuts are removed from the plug, leaving the high tension wires in place. After starting the engine, all wires are grounded except one, thus running the engine on one cylinder. In case there be no misfiring after testing at various engine speeds, it can be taken for granted that the plug is sound. The remaining plugs are tested in the same manner. When a multi-unit coil is used, a faulty plug may be located by holding down all the vibrator blades but one, so that only one spark plug operates. Running each cylinder separately by this means, it can easily be ascertained



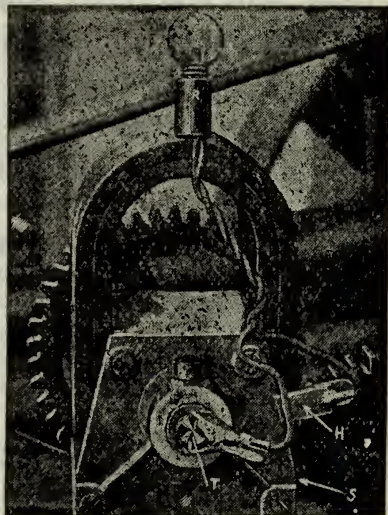
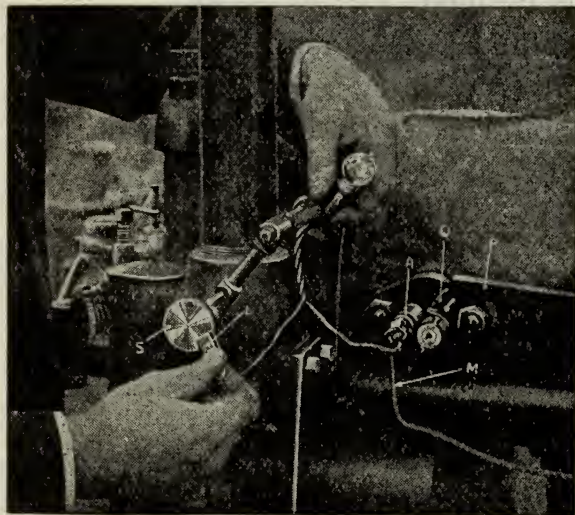
which plug is defective. Some coils are provided with little knobs for cutting out cylinders in the manner just described.

**Complete Break in the Wiring.**—The engine is placed upon the sparking point, the primary switch closed, and the two terminals of the suspected wire touched with a test wire. A current indicates a break.

**Partial Break in the Wiring.**—A partial break, or one held together by the insulation, may sometimes be located by bending the wire sharply at successive points along its length, the engine being at the sparking point and the switch closed as before.



**Primary Short Circuits.**—The primary wires should be disconnected from the coil, leaving the ends out of contact with anything. There is a short circuit if on touching the switch points momentarily a spark appear. A short circuit may sometimes be overcome by clearing all wires of contact with metallic bodies, and pulling each wire away from the others which were formerly in contact with it.



FIGS. 4,012 and 4,014.—Sumter testing device for testing low tension circuits. To test magneto, snap the clips on terminals after disconnecting it from circuit. The condition of magneto is evidenced by the brilliancy of lamp. To test a make and break ignitor, snap one clip on insulated terminal and the other on the engine frame. A little practice enables the conditions to be determined by noting the varying brilliancy of the lamp.

**Secondary Short Circuits.**—The secondary lead from the spark plug should be disconnected. Under this condition the high tension current may sometimes be heard or seen discharging from the secondary

wire to some metallic portion of the car. Water in contact with the secondary wire will sometimes cause a short circuit unless the insulation be of the best quality.

**The Primary Switch.**—This portion of the primary circuit sometimes causes trouble by making poor contact. This is generally due to the deterioration of the spring portion of the metal, which gradually loses its resiliency. Snap switches sometimes fail through the weakening of the springs which hold them in the "on" or "off" position. The contacts of a switch should be kept in good condition.

**Primary Connections.**—All binding posts and their connections should be clean and bright. The wires should be firmly secured to the binding posts, as a loose connection in the primary circuit is often the cause of irregular misfiring or the stopping of the engine.

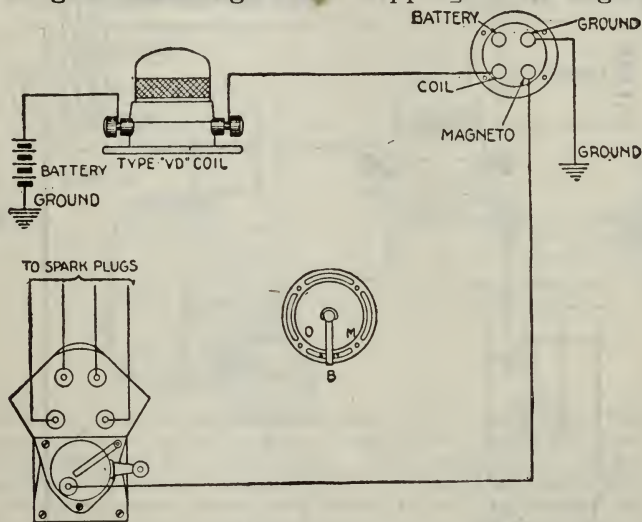


FIG. 4,015.—Bosch vibrating duplex ignition; arrangement when employing battery of a grounded lighting or starting system, or separate battery for ignition.

**NOTE.—Bosch vibrating duplex ignition.** In the operation of this system the arrangement is such that, while the magneto circuit is independent and complete in itself, the battery circuit includes both the coil and the magneto. With the switch in the battery position, the battery and coil are in series with the primary winding of the magneto armature, and the current for the battery supplements that generated by the magneto. Thus there is induced in the secondary winding of the magneto armature, a very powerful current, which, on account of vibration action of the coil appears not as a single spark but as a series of sparks, the current is distributed in the usual way by the magneto distributor. The battery side is not intended to be used as a separate ignition system, but merely as an auxiliary to the magneto to insure positive starting when conditions are not of the best. The battery and coil are used in connection with the magneto only when starting, while for regular running the magneto operates as an independent ignition system. The coil is designed to operate over a range of from eight to sixteen volts, so that cars provided with a storage battery for lighting, starting, or other purposes, if within the voltages mentioned, can employ the same battery for the Bosch vibrating duplex system. If only a 6 volt storage battery be provided, this can be utilized in connection with the system by adding three dry cells in series with the storage battery. Where no storage battery is available, or where it is desired to keep the ignition battery separate from the starting or lighting battery, dry cells alone may be used to operate the system; in such case it is advisable that the battery consist of eight or ten dry cells (preferably ten), connected in series.



**Vibration.**—Since the wires are subject to constant vibration, a number of strand of fine wire is better than a single heavy wire, as the latter is more liable to be broken. In securing the wire to a binding post, care should be taken that all the strands are bound.

**Timers.**—These may give trouble by: 1, presence of dirt, 2, loose contacts, or 3, division of the spark; this latter effect is sometimes caused by metallic particles wearing off the revolving part forming a path so that the spark passes from the revolving part to more than one contact segment.

**Coils.**—The part of a coil which requires most frequent attention is the vibrator. The contact points are subject to deterioration on account of the small spark always present between the points when the coil is in operation. In time, the points become corroded and

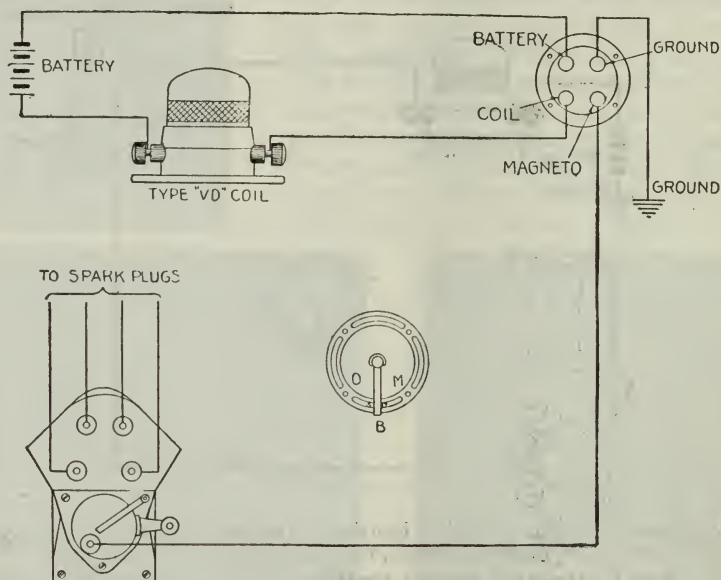


FIG. 4,016.—Bosc vibrating duplex ignition; arrangement when employing battery of an ungrounded lighting or starting system.

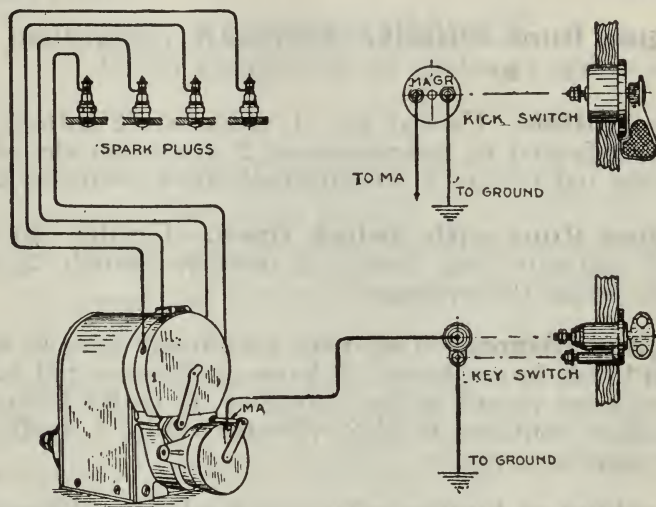
burned, and therefore require to be resurfaced by smoothing with a fine file. A faulty connection to the condenser is at once shown by large sparks at the vibrator points. Any repairs to a coil, aside from the vibrator, should be done by an expert, as the construction is very delicate.

**Igniters.**—In make and break ignition, a failure to get a spark, especially with a weak battery, is frequently due to the tappet spring. This spring must be quite stiff so as to cause the break to take place with considerable rapidity; **the more rapid the break, the better is the quality of the spark.** The contact points of the igniter electrodes are subject to corrosion and wear. When they become pitted the contact surfaces should be filed smooth.



**Spark Plugs.**—Repeated failure to start when the coil vibrator operates, indicates a faulty spark plug. A rich gasoline mixture often leaves a carbon deposit, and being a partial conductor short circuits the plug. The porcelain insulation, on account of its brittleness, may crack inside the sleeve, allowing a spark to pass there instead of at the gap. Mica insulation sometimes becomes saturated with oil, causing the layers to separate, permitting a short circuit.

**Engine Misfires and Finally Stops.**—This may be due to exhaustion of the battery, and is indicated by a weak spark and very faint vibrator action.



FIGS. 4,017 and 4018.—Wiring diagram of Eisemann type G4 magneto. **Troubles and remedies.**

If the engine misfire or refuse to start, it should be found out first whether the trouble lie in the magneto or in the spark plugs. The latter should be examined first, as they are the most frequent cause of trouble. If the missing be in one cylinder only, or in different cylinders, the corresponding spark plug should be examined to see that the gap be not too large. This gap between the electrodes should be approximately  $\frac{1}{32}$  of an inch. Also the spark plug may be short circuited through carbon, or the insulation may be cracked. Cleaning with gasoline or replacing is the remedy. The wiring should be very carefully examined and checked in accordance with the firing order of the engine. If cables be cracked or worn, they should be replaced. Clean same with gasoline until the contact surface appears quite white, or if pitted use a fine file—a manicure file will serve the purpose very well—but file very carefully, so that the surfaces will remain square to each other. The correct gap of the contact points is  $\frac{1}{64}$ " and in no case should it be more than  $\frac{1}{32}$ ". As these contacts wear away in time, they should be regulated by giving the adjustable screw "U" a forward turn, care being taken to securely tighten the lock nut "V". This can be accomplished without removing the timing lever or make and break mechanism, as shown in figs. 3,978 and 3,979. The cut also shows the combination wrench which is furnished with each magneto and which includes a gauge for the regulation of the gap between the platinum contacts ( $\frac{1}{64}$ "). If the platinum contact riveted to the contact spring "17m", or that of the adjustable screw "U" should be worn down entirely, it would necessitate a change of either or both. When the adjustable screw "U" is replaced or adjusted, care must be taken that the lock nut is securely tightened in place. If after following these instructions, the engine still refuse to start, the magneto should then be tested by removing the distributor plate and resting a screw driver on the gear casing holding same about  $\frac{1}{8}$ " from the collector ring. Then, if upon rotating the armature, a spark jump across the  $\frac{1}{8}$ " gap, it shows that the trouble does not lie in the magneto. but in some other part of the engine, possibly the carburetter. If a spark *do not* jump across the  $\frac{1}{8}$ " gap previously mentioned, the magneto should be examined by an expert.

**Engine Suddenly Stops.**—This is generally caused by a broken wire or loose switch which does not stay closed. In the case of a single cylinder, the broken wire may be either in the primary or secondary circuit; if a multi-cylinder engine, the break is in the primary circuit.

**Engine Does Not Start.**—Usually caused by: 1, primary switch not closed, 2, battery weak or exhausted, 3, entire or partial break in wire, 4, loose terminal, 5, moisture on spark plug, 6, fouled plug, 7, spark too far retarded or advanced, or 8, too slow cranking with magneto ignition.

**Engine Runs Fitfully.**—Frequently results from a partial break in the wiring, especially in the primary circuit.

**Pre-ignition.**—Caused by: 1, some small particle in the cylinder becoming heated to incandescence, 2, the electrodes of the spark plug becoming red hot, or 3, intermittent short circuit in the primary.

**Engine Runs with Switch Open.**—Usually caused by: 1, overheated engine or plug points, 2, defective switch, 3, an incandescent particle inside the cylinder.

**Engine Misfires.**—This may be caused by: 1, weak battery, 2, partial break in conductor, 3, loose or disconnected terminal, 4, intermittent short circuit in the secondary, 5, faulty action of either timer or vibrator contacts, 6, bent vibrator blade, 7, faulty spark plug, or 8, air gap too large.

**Knocking of Engine.**—Too much advance of the spark sometimes produces this effect.

**Knocking in the Cylinder.**—The form of unusual noise commonly described as "knocking" consists of a regular and continuous tapping in the cylinder, which is so unlike any sound usual and normal to operation, that, once heard, it cannot be mistaken. Too much advance of the spark sometimes produces this result. As mentioned by numerous authorities, the placing of the spark plug in the exact center of the combustion space occasions a peculiarly sharp knock, which may be stopped by advancing or retarding the spark from the one point of trouble. This explanation of the trouble is questioned by others, and is probably over rated.

**Knocking in Cylinder when Ascending Hills.**—*Carbonized cylinder.*

**Loss of Power Without Misfires.**—This may be due to badly adjusted coil contacts, poor spark, or incorrect timing.

**Explosions in the Muffler.**—These are usually caused by misfiring, partially charged storage battery, or by one cylinder not working.



## CHAPTER LXXVI

**SELF-STARTERS AND LIGHTING SYSTEMS  
FOR AUTOMOBILES**

In summing up the merits of the gas engine as a prime mover, there is one inherent defect that cannot be overlooked—the fact that, on account of the nature of its cycle of operation, it is not self-starting. It must be turned by some external force until the proper mixture has been drawn into the cylinder; compressed and ignited before it will start, unless perchance an unignited mixture be left in the cylinder and the piston be in the proper position; then by igniting the unburned charge the engine will usually start.

**Classes of Starter.**—The engine starting mechanism requires deep thought and engineering skill to properly apply it to an automobile, that is, making it an integral part of the car, preferably a part of the engine mechanism.

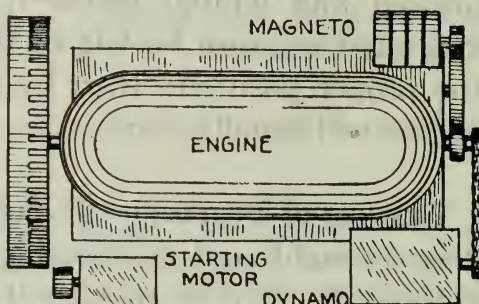
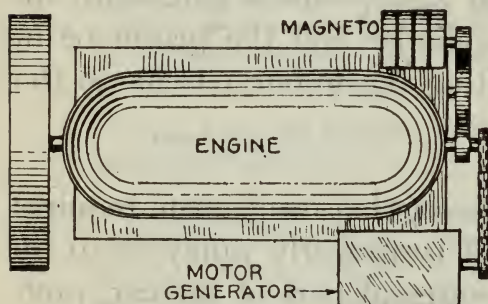
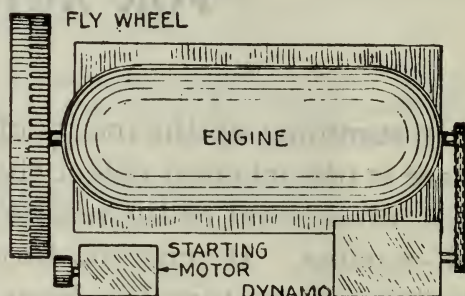
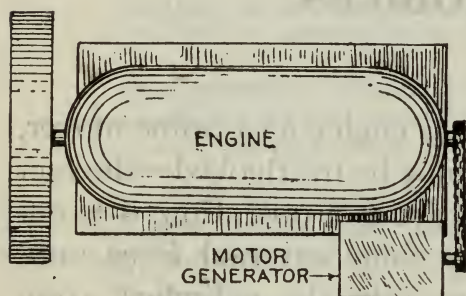
The various starting systems are classed, according to the kind of power used, as: 1, mechanical; 2, compressed air; 3, gas; and 4, electric.

The employment of electricity for starting has the advantage of also supplying current for lighting and ignition as well, and this has led to the development of systems involving various combinations. It would seem, therefore, that electricity would be universally used for starters, save for the fact that there are some objections, such as high cost, maintenance, and the considerable mechanism necessary, that offset more or less the advantages accruing from its threefold uses.



**Classes of Electric Starter.**—There are numerous electric starting systems, and they may be classified according to the methods of obtaining current for starting and ignition, and the power element of the starter, as:

1. One unit systems;
2. Two unit systems;
3. Three unit systems.



FIGS. 4,019 to 4,022.—Classes of starter systems. Fig. 4,019, one unit system; fig. 4,020, two unit system; fig. 4,021 so called two unit system; fig. 4,022, so called three unit system.

These several systems comprise respectively:

1. A motor-dynamo;
2. A motor and a dynamo;
3. A motor, a dynamo, and magneto all separate.

**NOTE.**—There are two classes of two unit systems as explained on page 2,802; a two unit system and a so called two unit system. There is some confusion in classification, chiefly because of the close relationship between the starter lighting and ignition systems. *One unit* properly indicates a system with a motor generator and *two unit*, a system with motor and dynamo separate.

**Electric Starters Require a Storage Battery.**—In any electric system a storage battery is always necessary; for, in order to crank a gasoline engine there must be some source of electrical energy from which the cranking motor may draw its supply of electricity. Without it there would be no electric cranking

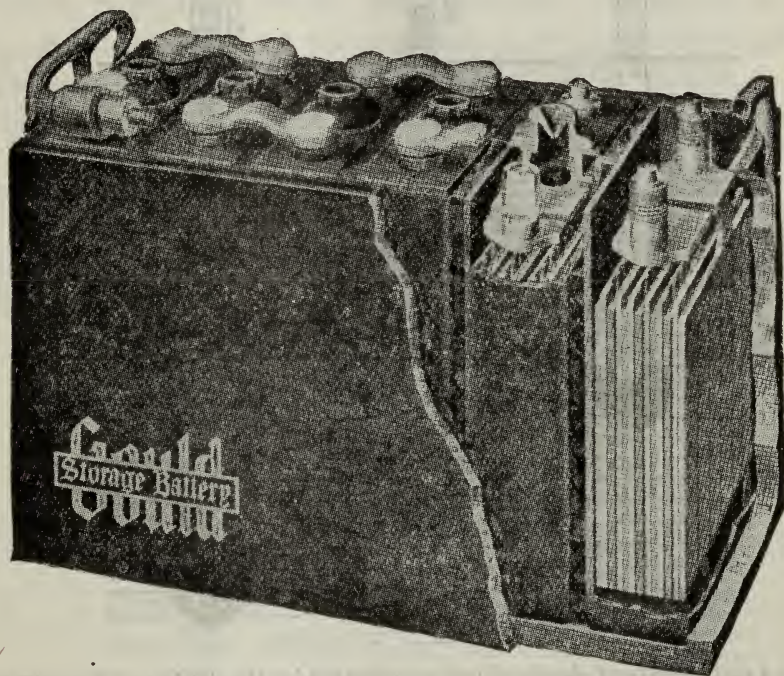
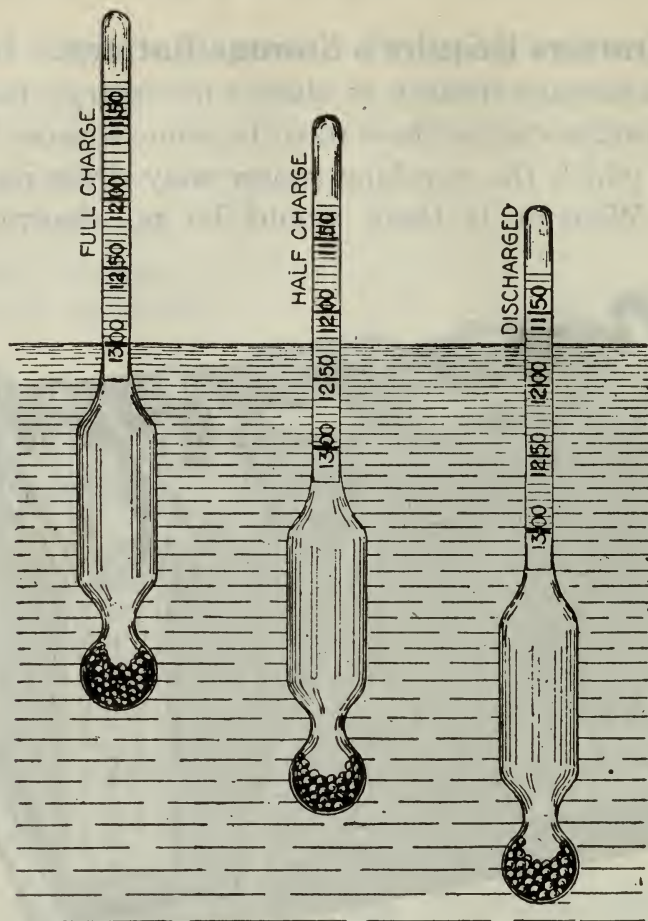


FIG. 4,023—Gould type B storage battery for starting and lighting systems. Plates  $4\frac{1}{8} \times 5\frac{1}{2}$ ; 7 to 15 plates per cell. Battery units for 6, 8, 12, 16, 18 and 24 volts.

devices. The first function, therefore, which the storage battery serves is to supply electricity for starting purposes.

**NOTE.**—The oxide battery plates are of the grid type. The grid is made of a stiff lead alloy which supports the active material in the form of a series of vertical strip held between the grid bars and locked in place by horizontal surface ribs which are staggered on the opposite sides. After the grids are cast, they are "pasted" with oxides of lead made into a paste of special composition which sets in drying like cement. The plates then go through an electric chemical process which converts the material of the positives into brown peroxide of lead and that of the negatives into gray spongy lead. Both the positive and negative plates are provided with lugs and in assembly the positives and negatives are separated by wood separators ribbed on the side against the positive. A positive and negative group, together with the separators constitute an *element*. A rubber jar of special composition is used as a cell container. The plates rest on stiff ribs or bridges in the bottom of the jar.





FIGS. 4,024 to 4,026.—State of charge of cell as indicated by the density of the solution. Fig. 4,024, cell fully charged; fig. 4,025, cell about half charged; fig. 4,026, cell almost discharged.

**How to test with hydrometer:** Remove vent caps from the cells. To use hydrometer, squeeze the rubber bulb, then insert the end of the rubber tube in the cell and well below the surface of the liquid; slowly release bulb, drawing the solution into the glass chamber until the hydrometer floats freely. Note the point at which the hydrometer stem emerges from the solution. Then slowly withdraw the tube from the solution and squeeze the bulb to return the solution in the hydrometer set to the cell. The point at which the hydrometer stem emerges from the solution denotes the density thereof. When the cells are in good condition the density of the solution denotes the state of charge thereof. The readings for various conditions of charge are 1,300, 1,225, and 1,150 for full, half, and no charge respectively. **In taking readings,** to prevent the hydrometer sticking to the side of the barrel, it should be held in a vertical position, the reading being taken at the surface of the electrolyte when *there is no compression on the bulb.* **In reading the gravity** of the different cells, it is customary to begin with the cell at the positive end. **When readings have been taken** be careful to replace the electrolyte into the same cell from which it was taken. Failure to do this often leads to trouble, that is, electrolyte is often taken out of one cell, the gravity noted and the electrolyte put back into another cell. The result is that the amount of electrolyte taken out of the first cell is eventually replaced with water, leaving the electrolyte weaker; whereas the electrolyte which was taken out and put into another cell would make the electrolyte of that cell stronger, resulting in irregularity in the different cells.



When the car comes from the manufacturer, the storage battery will be filled with electricity, and it must be kept charged. If a dynamo be provided on the car, this may serve to charge the battery whenever the car is in use. Unless such a generator be supplied, it will be necessary to periodically recharge the battery.

Batteries designed solely for ignition or lighting are not capable of taking care of the sudden and large demand for current to operate a starter.

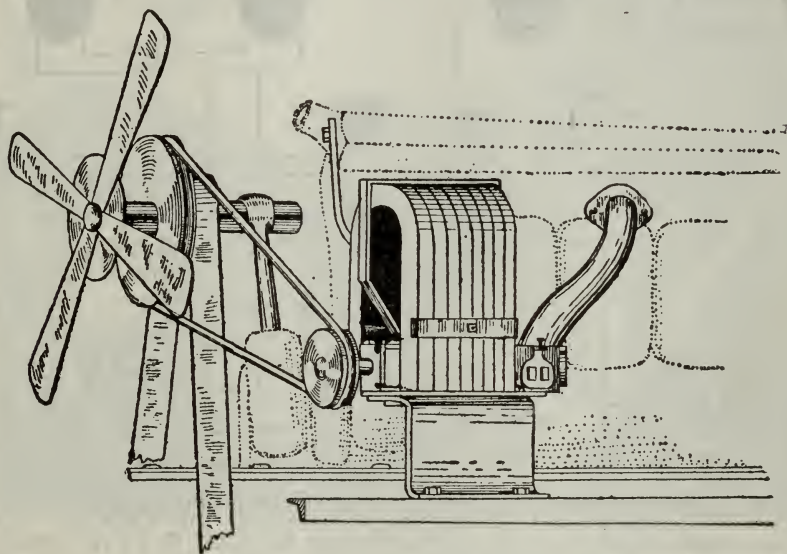


FIG. 4,027.—Holtzer-Cabot lighting magneto as installed on model T Ford car. It must be driven from the fan pulley. A special fan with magneto pulley is furnished with the magneto. The battery is mounted under rear seat on right side; the usual running board mounting is not recommended. A 60 ampere hour storage battery, if fully charged, will operate the side and tail lamps (6 candle power total) for approximately 50 hours, or the head and tail lamps (34 candle power) for approximately 10 hours. Turn off head lights when car is standing.

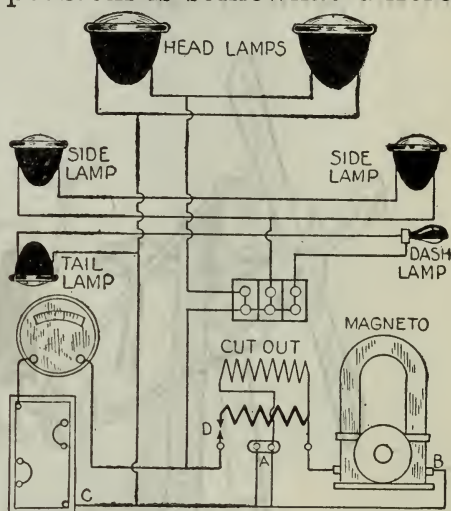
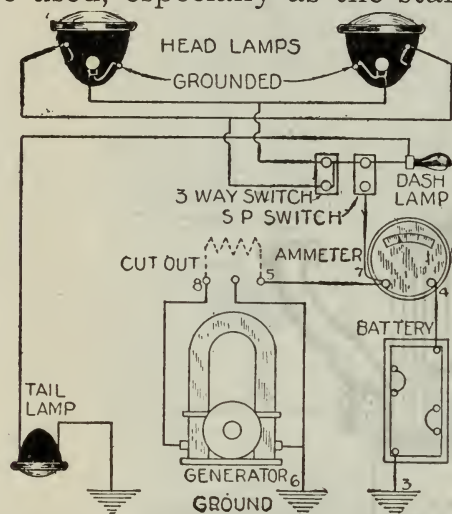
**Ques.** What is the principal difference in storage batteries intended for ignition, lighting, and starting?

**Ans.** Capacity.

The ignition battery is inapplicable to either lighting or starting duty. Just as the lighting battery lacks capacity for starting purposes, so does the one used for ignition purposes, only that the latter is lacking in a greater degree than the former.

The construction of the ignition battery prohibits its use for starting purposes; however, there is little difference in the construction of lighting and starting batteries, hence a large lighting battery may be used for starting.

**Choice of Voltage.**—In designing starters there are several conditions to be considered in determining what voltage shall be used, especially as the starter problem is somewhat different



FIGS. 4,028 and 4,029.—Holtzer-Cabot lighting magneto outfit installation, views showing location of switch, ammeter, cut out and their connections. Fig. 4,028, one wire system as applied to double bulb or turn down head lamps: fig. 4,229, two wire system, suitable also as a general guide for motor boat wiring.

from the ignition and lighting requirements as to voltage, and one battery is generally employed for all.

The pressure used on the different lighting and ignition systems is six volts, and were it not for the problem of cranking, there probably would not be any reason to change.

**NOTE.**—The essential requirement for rapid discharging is large plate area per ampere discharged. This is just what is accomplished by the use of thin plates; for when two plates replace one, the effective area is doubled. In practice this doubling of area is accompanied by the reduction in thickness of plate, in order to keep the size of the battery about the same as before. It also has an important bearing on the discharge rate which may be obtained from a battery, and also the capacity or length of time that the battery will give this discharge. The gain is due to the shortening of the distance which the electrolyte has to travel to reach the center of the plate.



**Ques. What is the advantage of low voltage?**

Ans. The circuits are easily protected from electrical leakage. Low pressure lamps are manufactured with less difficulty than those designed for higher pressure.

**Voltage of Units.**—The weight of six volt batteries is less than that of the higher voltage type. Were it not for these considerations, starting motors would be designed for high pressure,

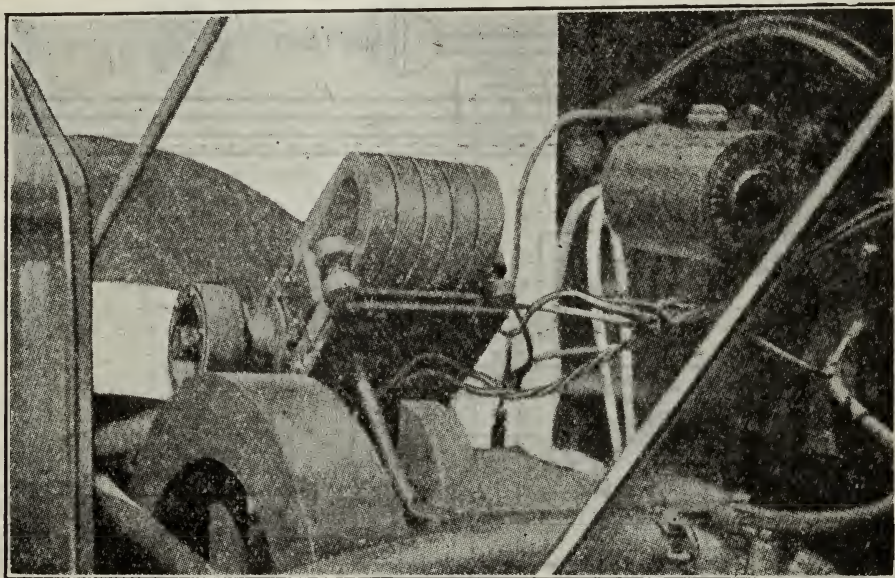


FIG. 4,030.—Method of driving a generator direct from engine fly wheel by friction pulley with spring or cushion base; the latter relieves the stress on the shaft from excessive vibration. The governor regulates the speed of the machine and prevents burning out of the lamps. The illustration shows a K-W magneto installed on an early Maxwell car.

as they are smaller and consequently lighter. High voltage for the motor does not necessarily mean high voltage for the dynamo and lights.

There are three general combinations:

1. All one voltage, either 6, 12, 16, or 18 volts;
2. Generating and starting at 12, 16, or 18 volts, and lighting at 6, 8, and 16 volts respectively.
3. Generating and lighting at 6 volts, and starting at 24 or 30 volts.



**One Unit Systems.**—The term “one unit” as applied to an electric starting system means that there is a motor and dynamo combined in one machine, or motor dynamo, as it is called, the dynamo furnishing current for the starter, and for charging the storage battery.

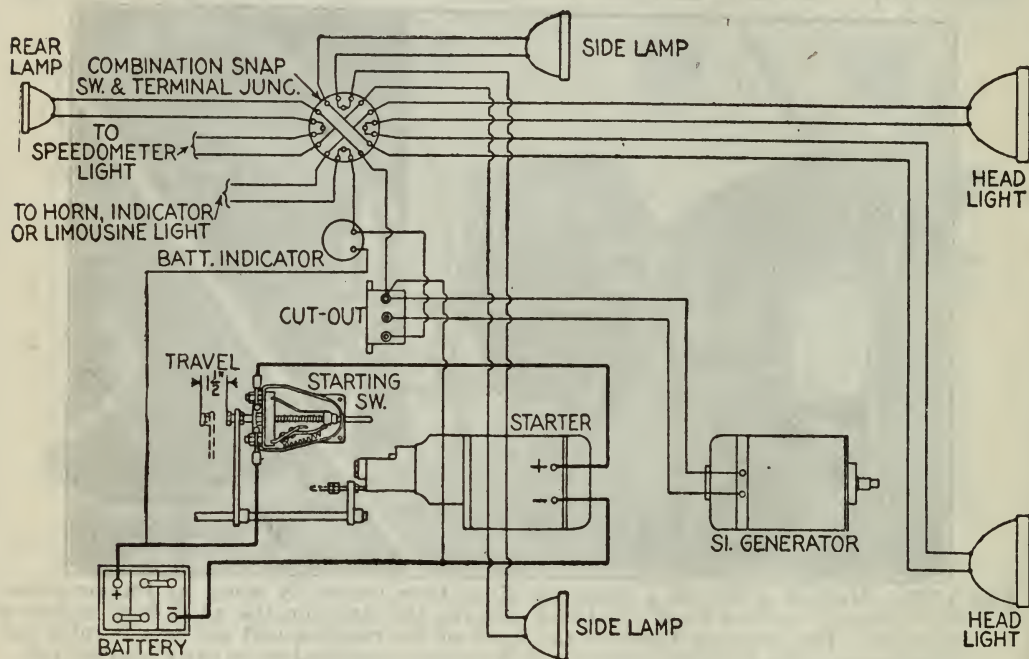
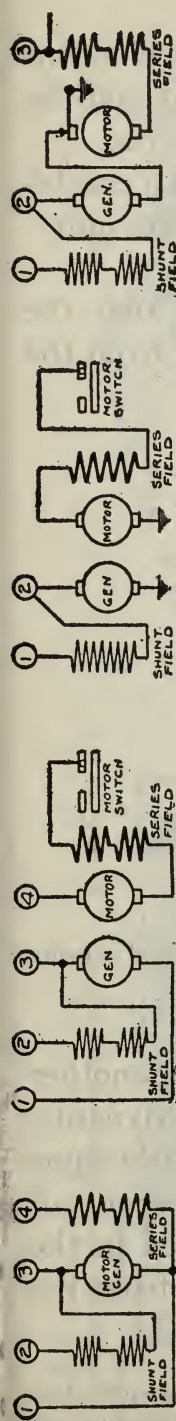


FIG. 4,031.—Wiring diagram of Deaco single unit starting and lighting system. Heavy lines indicate No. 4 B. & S. stranded cable. Medium lines from motor generator and starting switch to combination snap switch and terminal junction indicate No. 10 B. & S. gauge duplex wire. Fine lines in lamp circuit indicate No. 12 B. & S. gauge duplex wire.

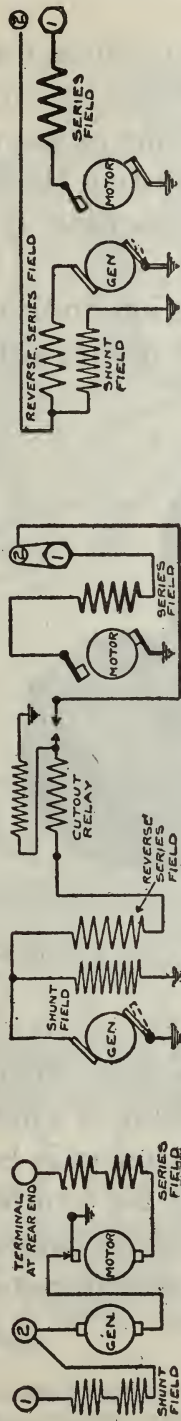
**NOTE.**—An example of the one unit arrangement is the Electro system, which has a combined motor and dynamo, the latter furnishing current for starting ignition and lighting. It is necessary to arrange the motor with a short driving shaft integral with the motor case, driven either through the timing gears or silent chain and connecting to the starter with an Oldham coupling. The motor dynamo is always in operation. When turning below 380 revolutions per minute it is a motor, and when turning above that rate, a dynamo. The compound differential winding takes care of the output from the generator. No discriminating cut out or reverse current circuit breaker is provided to disconnect the battery from the motor dynamo entirely at very low speeds. Instead of this, the ignition switch breaks the line between the battery and generator when the engine is stopped by cutting off the ignition. The system operates on 24 volts, but charges the battery at six volts. The amperage drawn by the 24 volt motor when turning over the gasoline engine varies with the size of the motor as in all systems. The gear reduction between the motor dynamo and the engine is twenty-five to one when starting but changes automatically to a direct drive when the engine starts running.



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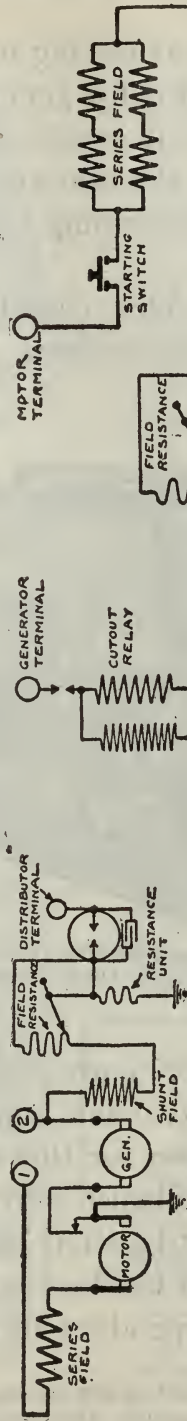
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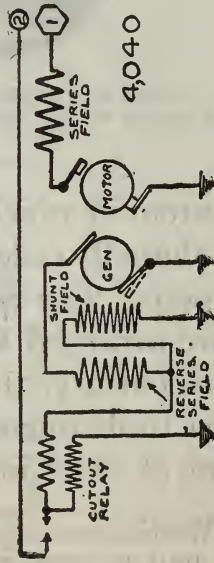
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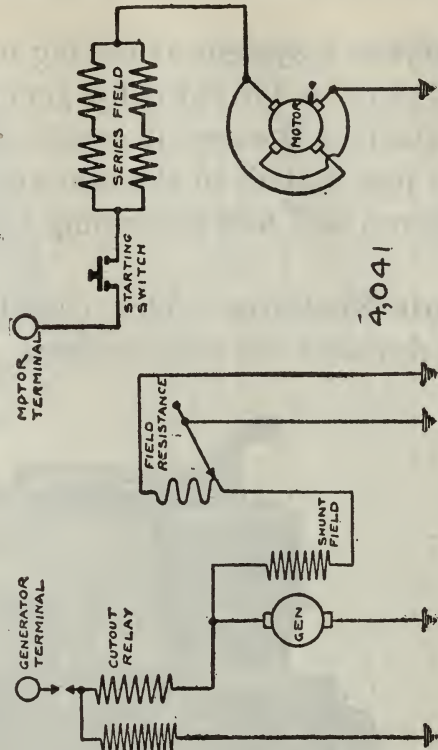
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4,039



4,040



4,041

Figs. 4,032 to 4,041.—Internal circuits of motors, generators, and motor generators in Delco Systems (Phillips and Copland diagrams). Fig. 4,032, 1912 Cadillac, 1913 Cole, Hudson, Oakland and Oldsmobile. Fig. 4,033, 1913 Cadillac and Packard 13-38. Fig. 4,034, Buick 14-54, 55, Oldsmobile 6-54, Oakland 43, 48, 62, Cole 4-40, 4-50, 6-60, Moon 4-42, 6-50. Fig. 4,035, 1914 Cadillac. Fig. 4,036, 1914 Hudson 6-54. Fig. 4,037, 1914 Buick 24, 25, 36, 37, Cartecar 7, Paterson, Oakland 36, Hudson 6-40. Fig. 4,038, 1915 Buick, 24, 25, Cartecar-9. Fig. 4,039 Buick 36, 37, 54, 55, Cadillac 8, Cole 6-50, Hudson 6-40, Moon 6-40, 6-60, Oakland 37, 49, Oldsmobile 42, Paterson and Westcott Model U. Fig. 4,040, 1915 Westcott 4. Fig. 4,041, 1915 Cole 8.



In classifying a system as having one or more units, it means that the apparatus provided for generating the current and the motor for starting the engine consists of one or more parts.

Thus, as just stated, in the one unit system there is a combination dynamo and motor forming one machine, or "one unit."

**Two Unit Systems.**—This classification indicates that the motor and dynamo are separate units, as distinguished from the

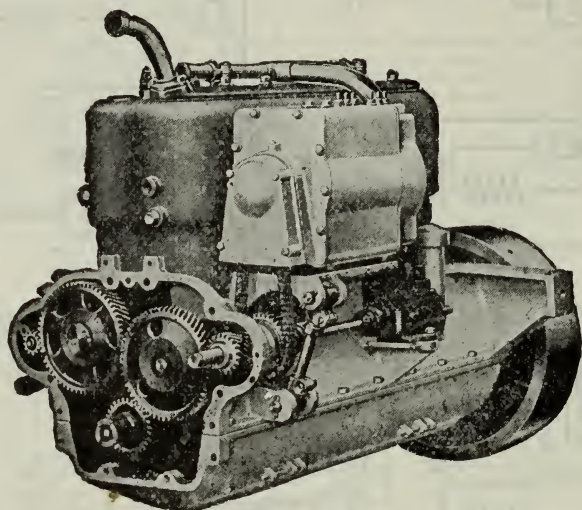
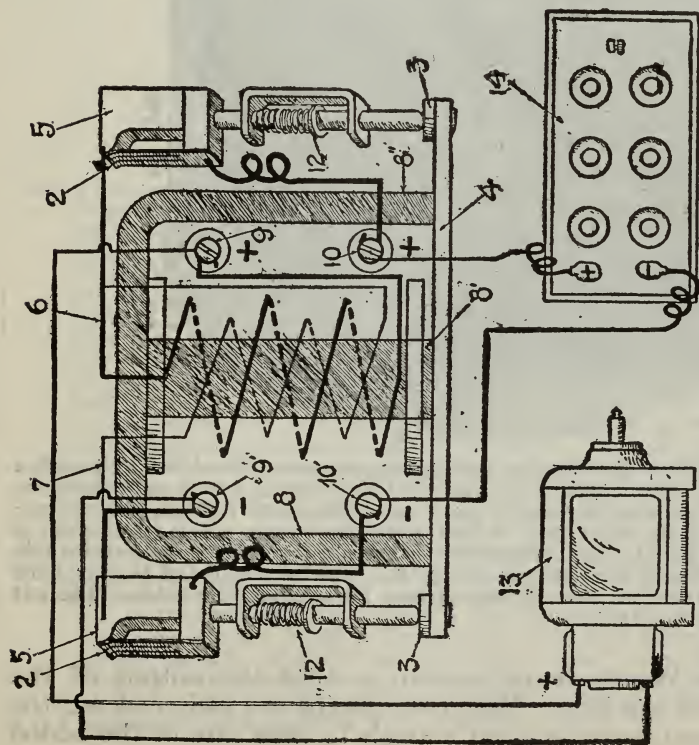


FIG. 4,042.—Entz single unit starting and lighting system. View showing mounting of motor generator on engine and so called silent chain drive.

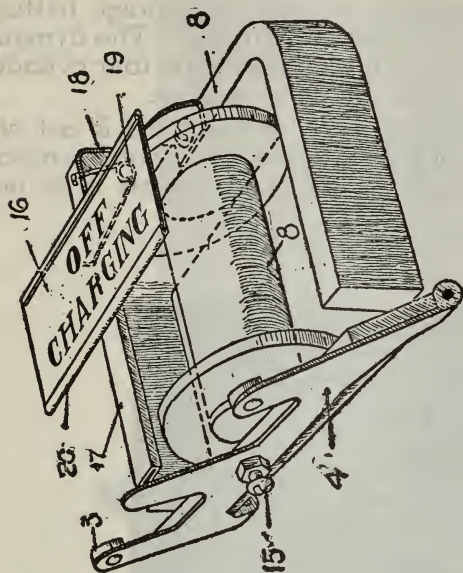
one unit system in which they are combined. There is another system, ill advisedly called two unit, consisting of a motor dynamo, and a magneto. The reason for this confusion is because some dynamos are arranged to furnish current for ignition when not charging the battery, thus ignition has to be considered in the classification to distinguish the last mentioned system from the arrangement of three independent units.

The Westinghouse system is an example of the first mentioned class of two unit systems in which the cranking motor and dynamo are





FIGS. 4,043 and 4,044.—Leece-Neville two unit electric starting and lighting system. Breaker contacts 1, 2 and 5 are shown closed as when the generator is charging the battery. Indicating target omitted for the sake of clearness. The electric generating and storage plant commences operation as soon as the engine starts by generating current in the generator. This first current flows from the generator 8 until the energy is sufficient to attract and close the armature 4. This action closes the charging contacts 1, 2, and 5, when the bulk of the current flows through the heavy wire winding 6, to the battery and the energy is there stored for use in cranking, lighting, etc. When the armature closes it also operates the indicating target and shows the word "charging" on the face of circuit breaker to the operator. When the generator stops running, the magnet 8 is no longer energized and springs 12 push the armature back and open the charging contacts 1, 2 and 5, thus breaking the electric connection between generator and battery on both the positive and negative sides. At the same time spring 19 operates the indicating target to show "off" on the circuit breaker to the operator. The indicating target shows the word "off" in the little window of its case when generator is not charging, and when the generator is "charging," this word is shown instead of "off." The wiring diagram shows the generator connected through the circuit breaker to the storage battery and the battery connected to the motor through the motor switch and the lamps through the lighting switch. Standard 6 volt lamps are used in connection with the 12 volt battery by connecting them thereto by a three wire system. All the lamps are connected on one side through the lighting switch to a central terminal on the battery and on the other side one-half of the lamps are connected to the positive pole of the battery and the other half of the lamps are connected to the negative pole. Thus the 12 volt battery is divided into two 6 volt batteries for lighting without in any way interfering with its being charged by the generator at 12 volts or discharged through the motor at 12 volts.



separate machines. The latter not only charges the storage battery but also furnishes direct a supply of current for ignition. The dynamo is of the slow speed type and turns at crank shaft speed on four cylinder engines and  $1\frac{1}{2}$  crank shaft speed on six cylinder engines.

The battery circuit is cut in above 10 miles an hour and is cut out below 7 miles per hour. This difference prevents the switch cutting in and cutting out continuously when the speed of the car is at one particular point.

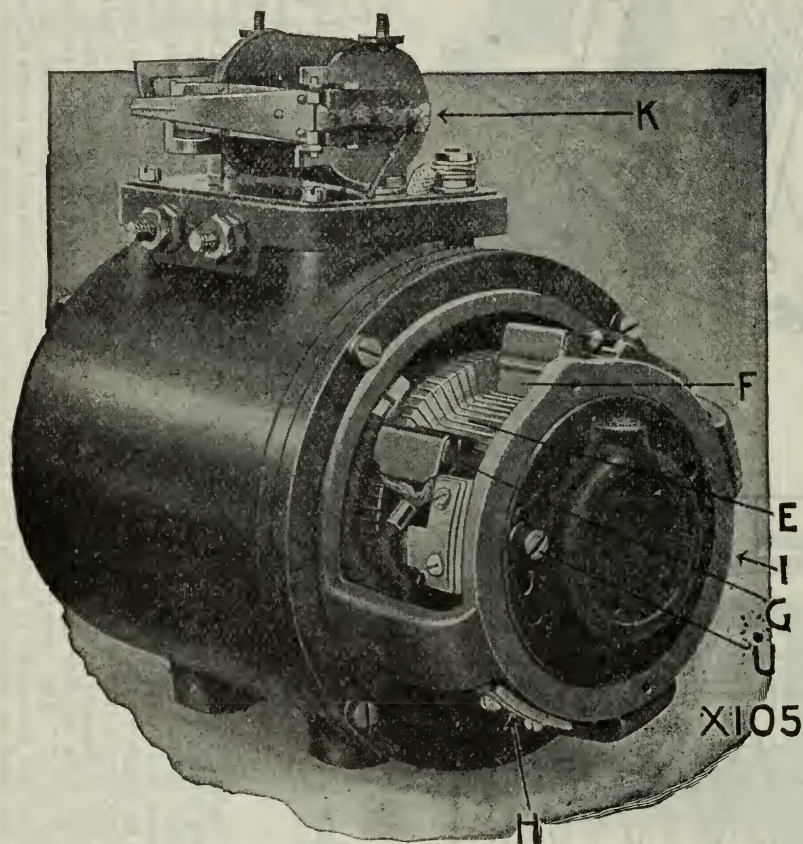


FIG. 4,045.—Wagner dynamo of two unit starting and lighting system. The drive is through a train of gear or equivalent. The windings and internal connections are of such character that no regulating devices are required except a cut out. *In construction*, the commutator E and brushes F, G, H, and I, are located under the cover which in this cut is removed. The brushes H and I collect the current from the commutator and furnish this current for charging the battery through the cut out K. The brushes F and G collect the current from the commutator and furnish this current for exciting the fields. The cut out K is shown in detail in fig. 4,046.

A feature of the Westinghouse system is that the output of the generator varies with the load. When the lamps are switched on, the output of the dynamo becomes great enough to take care of the added



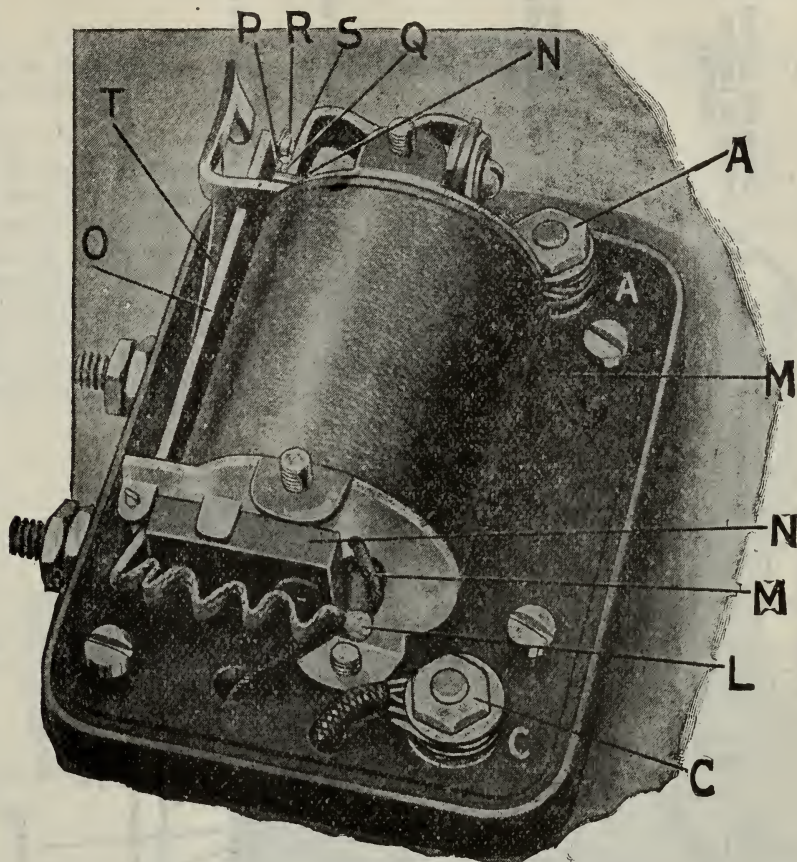


FIG. 4,016.—Wagner cut out of two unit starting and lighting system. *It consists of* two magnet coils L and M, wound on an iron core N, which attracts and repels an iron lever O. At the end of O are two main contact points P and Q at which the contact between the dynamo and battery is made and broken. There are also supplied two auxiliary contact points R and S which are for the purpose of minimizing sparking at the main contact points P and Q. The coil M called the *shunt coil* is connected directly across the two brushes H and I, and therefore the full dynamo voltage is impressed across the ends of this coil. The coil L, called the *series coil*, is connected in series with the battery and dynamo and therefore this coil carries the charging current when the battery is being charged. **In operation**, when the engine is started, the dynamo is driven by the engine and it, therefore, increases and decreases in speed with the engine. When the engine is speeded up, the dynamo follows with corresponding increase in speed and the voltage of the dynamo rises as the speed increases. As soon as the dynamo voltage gets to a point above the voltage of the battery, which is approximately six volts, the coil M pulls the iron lever O toward the magnet core, thereby closing the contact at the points P and Q-R and S. As soon as this contact is made, the dynamo is connected to the battery, and a charging current will flow from the dynamo to the battery through the series coil L, which is in series with the dynamo and battery. The dynamo continues to charge as long as these contact points P and Q-R and S remain together, but when the engine speed is decreased, so that the dynamo voltage falls below the battery voltage, the battery will discharge through the dynamo and therefore through the coil L. This discharge current, being in the opposite direction from the charging current, will neutralize the effect of coil M and allow the spring T to pull lever O away from the magnet core, thereby opening the contact at the points P and Q-R and S. As soon as these contacts open, the battery is off charge. The engine speed at which this relay closes corresponds to a car speed of 7 to 10 miles per hour.



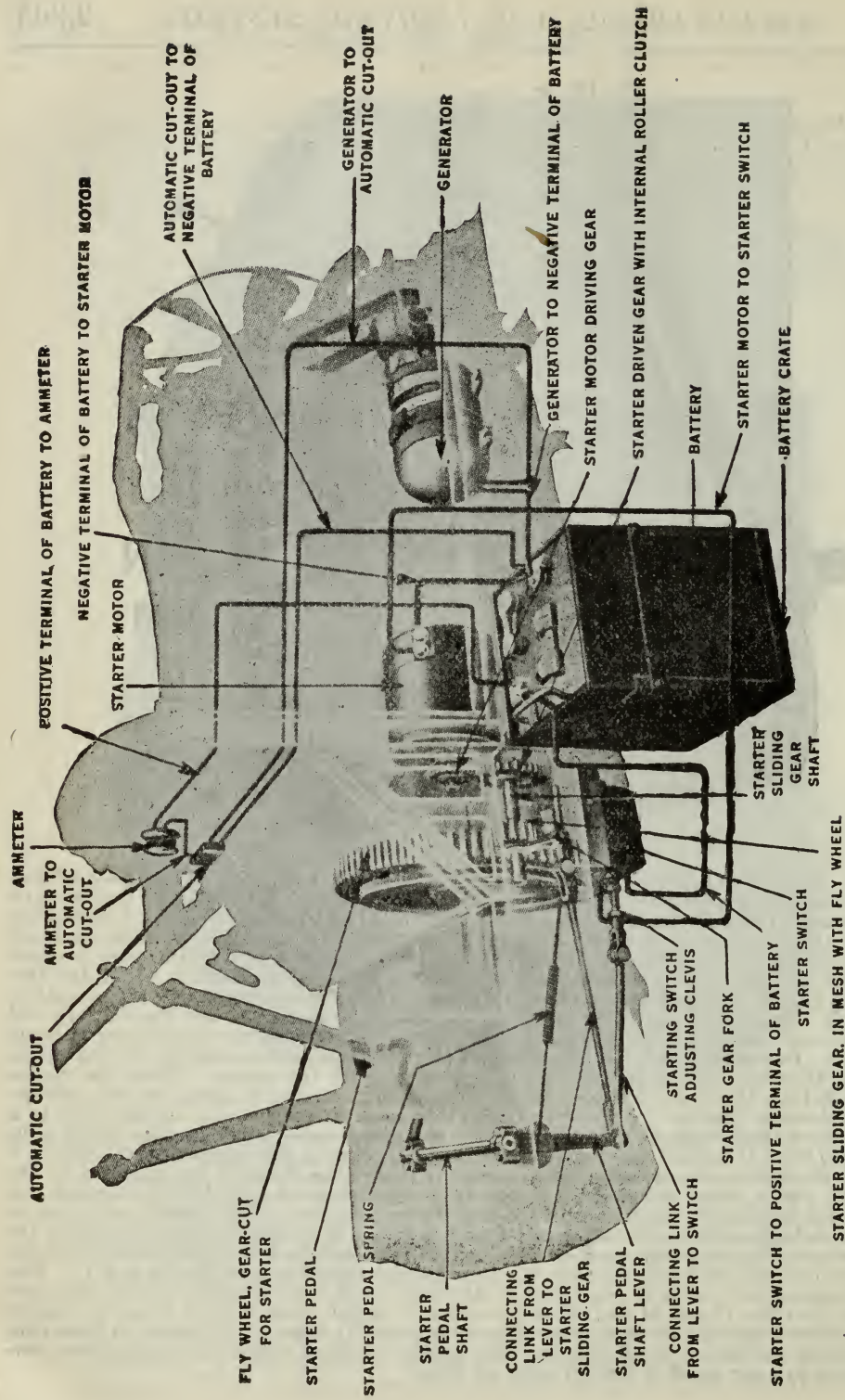
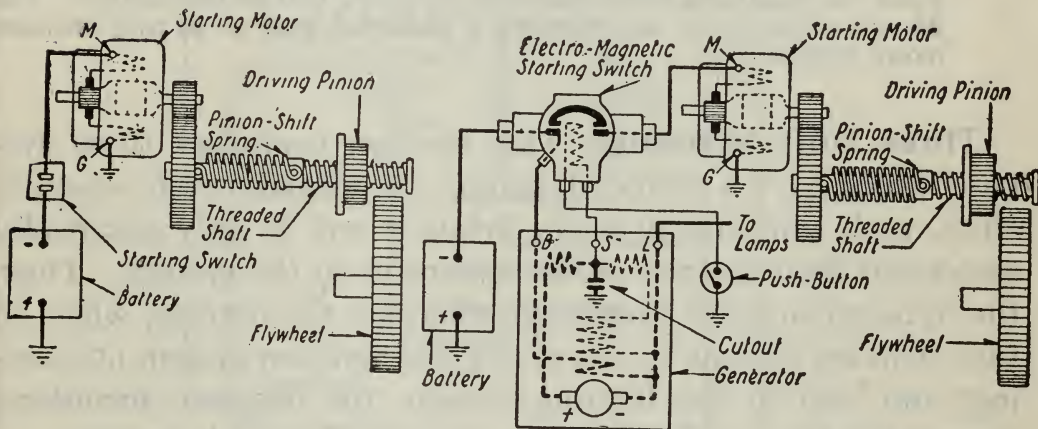


FIG. 4,047.—Gray and Davis self-starter as installed on the Lozier car, storage battery, discriminating cut out, motor and resistance switch.

This is a two-unit system, and comprises a dynamo,

load. This is accomplished by having the battery current go through a series field on its way to the lamps, thus assisting instead of bucking or neutralizing the shunt field.

The reduction between the motor and the engine varies between ten to one and twenty-two to one. The amperage on the jump or when the starting switch is thrown in depends on the resistance opposed to revolving the engine, but will in the average case of a large four or small six cylinder motor be 200 on the jump and about 80 for a running amperage. The motor is series wound and is generally geared to the fly wheel; it is operated by a switch which throws the gears into engagement for starting, by first meshing them and then spinning the engine. The motor is automatically thrown out of engagement when the engine operates under its own power.



FIGS. 4,048 and 4,049.—Diagrams of Westinghouse electrical and mechanical connections of double reduction motor and switch for automatic screw pinion shaft. Fig. 4,048, with hand or foot operated starting switch; fig. 4,049, with electro magnetically operated starting switch controlled by push button. In the figures, when the starting switch is closed, the full battery voltage is impressed on the motor, and it starts immediately. The pinion, when the motor is at rest, is within the screw shift housing and entirely away from the flywheel gear. The threaded shaft is connected to the reduction gear shaft by a spring which thus forms a flexible coupling. As the load is not large enough to compress the spring when the motor starts, the threaded shaft is immediately revolved by the spring in released position. The pinion moves out on its shaft by virtue of the revolving threads, until it reaches the flywheel. If the teeth of the pinion and flywheel meet instead of meshing, the spring allows the pinion to revolve until it meshes with the flywheel. When the pinion is fully meshed into the flywheel teeth, the spring compresses and the pinion is then revolved by the motor as through a continuous shaft, turning the engine over. When the engine fires and the flywheel peripheral speed continuously exceeds that of the driving pinion, it forces the latter out of mesh, and it is returned to its original position in the screw shaft housing. During the periods immediately after the engine has passed over any one of the points of maximum compression, the spring offers an elastic cushion between the flywheel and the reduction gear so that the pinion will not be thrown out of mesh.



The "Aplco" is a so called two unit system in which the motor and the dynamo are contained in one unit and the magneto forms the second unit. The make of the magneto is optional and is separate and distinct from the lighting and cranking systems.

A widely different voltage is used in the cranking motor and the dynamo. The former operates at 24 volts (except in one instance, where 30 volts are used), while the latter operates at  $6\frac{1}{2}$  volts.

The dynamo is of the low speed type, being driven at crank shaft speed by chain or any other suitable means. It furnishes current for the battery above a car speed of eight miles an hour and charges the battery until it becomes fully charged, when it is automatically switched off, and does not charge the battery again until the latter drops below a point which can be fixed to suit the ideas of the manufacturer.

A discriminating circuit breaker or reverse current cut out operates when the voltage of the dynamo drops below that of the battery. The 24 volt series motor acts through a reduction gear of 40 to 1 between motor and engine.

**Three Unit Systems.**—This division comprises those systems which have a motor, dynamo, and magneto each separate. Here, each unit has a single function and is only electrically associated with the rest of the apparatus in the system. Thus, the dynamo supplies current for charging the battery, which in turn delivers current to the motor and ignition system at starting, and also to the lighting system, the magneto furnishing current for the ignition system, when the engine is running.

In the manufacture of three unit systems, some make the entire outfit, others manufacturing only motor and dynamo, leaving it optional as to the make of magneto employed.

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**NOTE.**—The following description of the **Disco** will serve as an example of the three unit system. The motor and dynamo are both of the same size, each operating at 12 volts. The aluminum cases are interchangeable for each unit, the entire difference being in the windings, which are simple series on the motor and compound on the dynamo. The dynamo does not come into action until the speed of the engine has reached the point at which the car is traveling seven miles per hour. Below this point a cut out switch prevents any connection between the storage battery and the dynamo, and eliminates any possibility of a discharge to the generator. Below seven miles an hour the lighting current is drawn from the battery, which may be in any size desired over an 80 ampere hour capacity. The upper limit to the charging point is about 25 miles an hour. Above this the dynamo is again cut out and has no connection with the storage battery. The motor generally is mounted so as to drive through teeth cut on the periphery on the flywheel, or it may be mounted on the one end of the engine or the gear set. A roller clutch is used which cuts out the motor as soon as the engine starts.



The term three unit system applies only to "starting, lighting and ignition systems," as distinguished from "starting and lighting systems."

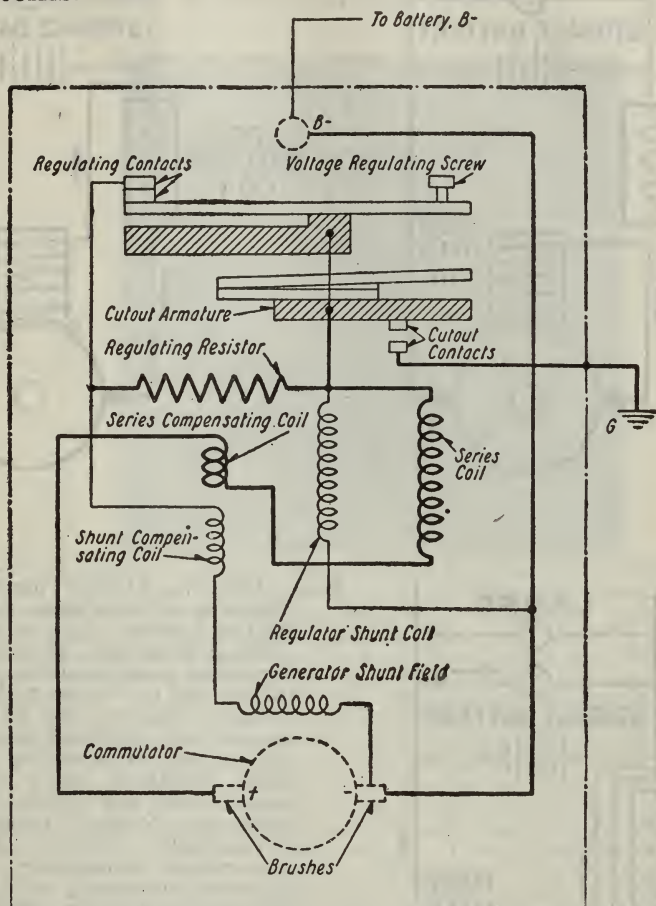
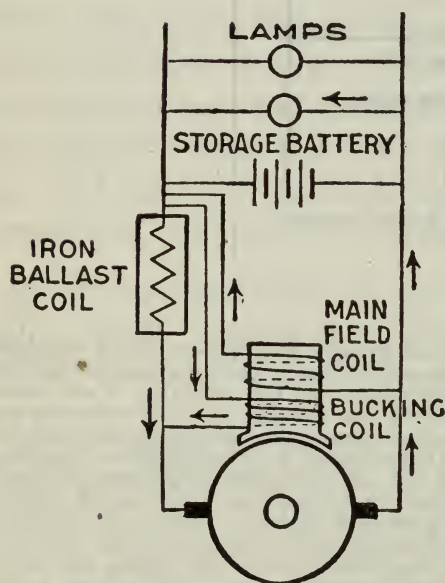
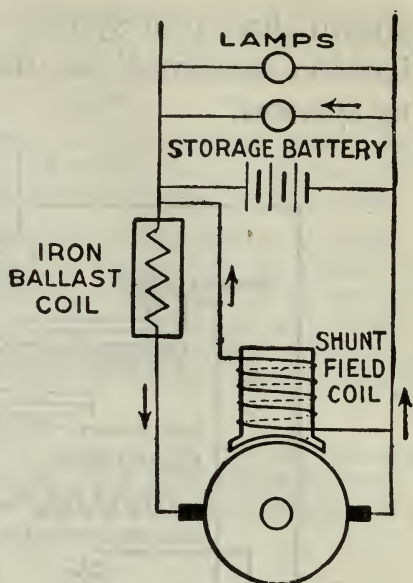
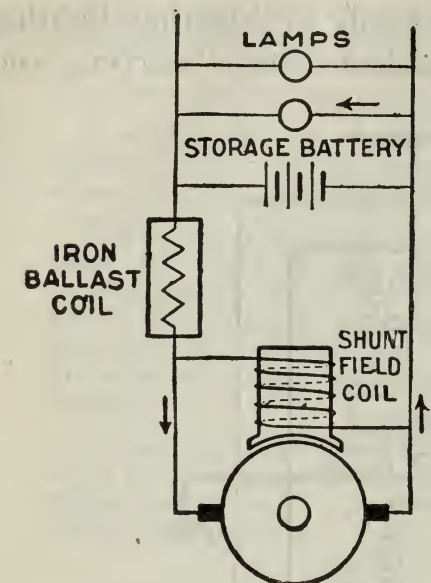


FIG. 4,050.—Diagram of connections of Westinghouse dynamo with self-contained regulator. The regulator performs two functions: 1, that of a cut out, and 2, that of a voltage regulator. Each function is performed by its individual element but the operation of the second function depends upon that of the first. When the dynamo is being operated at a speed below the predetermined "cut in" speed, the contacts of the cut out are open, and *vice versa*. The cut in speed varies from five to ten miles per hour on high gear, depending upon the gear ratio and wheel diameter of the car. **For voltage regulation**, the shunt fields of the dynamo are so designed that a voltage in excess of normal would be regularly generated when dynamo is operated at high speed and no load. This excess voltage is prevented and the voltage is held constant by the automatic voltage regulator. When the dynamo is operating below cut in speed, the regulator contacts are closed, and remain closed till there is a voltage in excess of the predetermined value. This voltage is fixed by the setting of the voltage regulating screw. When, due to increased speed of dynamo, the voltage tends to exceed the value for which the regulator is set, the regulating contact open, opening the direct shunt field circuit and cutting in the regulating resistance. This causes a momentary drop in voltage so that the contacts close again. This opening and closing of the contacts is repeated so rapidly as to be imperceptible to the eye, and holds the voltage constant.



FIGS. 4,051 to 4,053.—Thermal method of obtaining self-regulation in the Rushmore lighting system. As a current of constant volume is desired, it follows that self-regulation must be produced by change in the volume of current rather than in the voltage. The first clue to the solution of the problem was found in a peculiar property by iron, of increasing greatly in electrical resistance at a certain critical temperature just below the red heat. Below this "critical" point the resistance is practically constant. At and beyond the critical temperature, the resistance increases enormously with each degree of temperature increase. Starting from this peculiar property of iron, the next thing was to employ it correctly. The primitive method would have been to insert a thin coil of iron wire directly in the circuit and simply waste the surplus energy at higher speeds in heat as shown in fig. 4,051. This however, would have given very imperfect regulation, besides necessitating a heavy and clumsy machine, since the shunt field winding would receive the full voltage normal to the speed at any moment. To keep down the strength of the current in the

shunt field coil one terminal of the latter may be connected beyond the iron "ballast" coil instead of between that and the armature and the "ballast" coil as in fig. 4,052. With this arrangement better results are obtained, but, as the field excitation remains constant, an excessive voltage will still be generated at high speeds. To counteract this, a bucking coil is added, as shown in fig. 4,053, which reduces the field excitation.



**Methods of Control.**—In any electric system where there is a dynamo and a storage battery, two control elements are necessary for the proper working of the system:

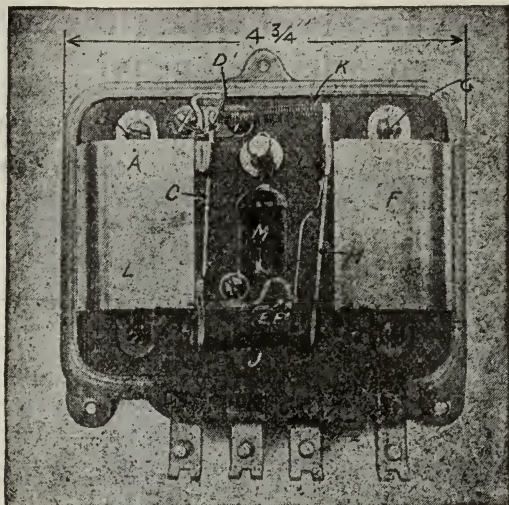


FIG. 4,054.—Ward Leonard automatic controller for automatically regulating the charging of the battery. When the car speed becomes approximately seven miles per hour, the dynamo armature will give a voltage sufficient to charge the batteries. The circuit between the dynamo and the batteries is normally open, but when the voltage of the dynamo becomes proper for charging, the coil A on the magnet core B, magnetizes the core sufficiently to attract the arm C. This arm moves toward the core B and thus two spark proof points D D' are brought together, establishing the circuit between the battery and the dynamo, and the dynamo begins to charge the batteries. In a dynamo the dynamo voltage increases with the speed unless a method of controlling it be adopted. The dynamo should charge at about seven miles per hour, but it is desirable that when the car runs at a much higher speed, as 15 to 60 miles per hour, the dynamo voltage shall not increase. If allowed to increase, such an excessive dynamo voltage would tend to cause sparking at the brushes, excess current and consequent trouble at the commutator and excessive wear and heating of the bearings. It would also cause an excessive amount of current to flow through the battery. To prevent this, the strength of the dynamo field, and consequently the output of the dynamo, is made dependent on the touching of the two points E E'. The coil F on the magnet core G carries the armature current, and if this current become a certain amount (usually in practice 10 amperes) the core becomes sufficiently magnetized to attract the finger H. This separates the contacts E E' and a resistance M is inserted in the field circuit, weakening it. This causes the amperes flowing through the battery to decrease. When the current decreases to a predetermined amount (say 9 amperes), the coil F does not magnetize the core G enough to overcome the pull of the spring J. The spring J pulls together the points E E', the full field strength is restored and the current tends to increase. Under operating conditions, the finger H vibrates so rapidly as to keep the current constant. As a result the dynamo will never charge above a predetermined amount (10 amperes), no matter how high the speed of the car, but at all speeds greater than a predetermined speed (about 15 miles per hour in practice), the dynamo will charge at a varying rate, which has a maximum of 10 amperes and a minimum of 9 amperes. In case the engine speed become so low that the dynamo cannot charge the battery, the magnetism caused by the coil A is weakened so that the spring K pulls the contacts D D' apart. Thus the circuit between the dynamo and battery is opened when the dynamo speed is too low for the dynamo to charge. The auxiliary series coil L on core B acts to insure the perfect demagnetization of the core B on reversal of current.



1. Means for preventing reversal of current when the dynamo is charging the battery;
2. Means for limiting the dynamo voltage.

**Ques.** When dynamo is charging the battery and the engine is slowed down, what happens?

**Ans.** Reducing the speed reduces the pressure induced in the dynamo armature, hence, in slowing down beyond a certain

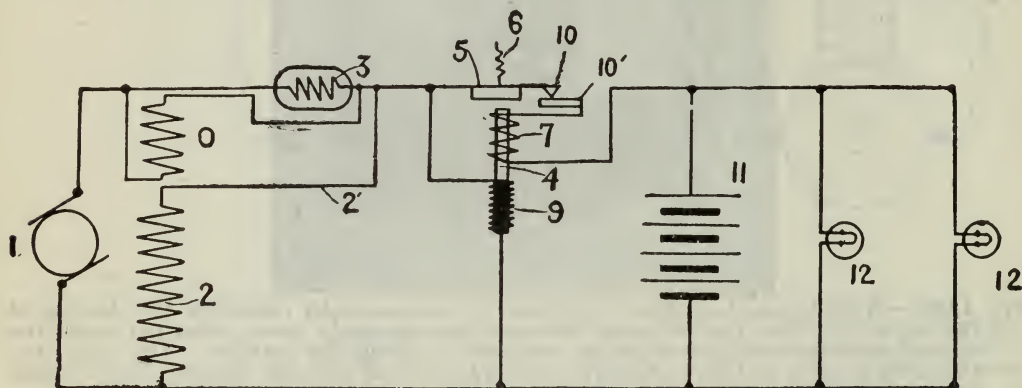


FIG. 4,055.—Diagram showing circuit connection of Rushmore dynamo with automatic cut out. The construction of the cut out is shown on fig. 4,056. The shunt field coil is connected beyond the ballast coil so that it receives current at all times at the constant voltage of the battery, and another winding is added to the field. This is what electricians call a "bucking" coil, that is a coil so connected as to *oppose* the main shunt field coil. This bucking coil, the effect of which is to reduce the field excitation, is connected as a shunt across the iron ballast coil. Its resistance is considerably greater than that of the ballast coil when the latter is cold or only warm, so that at low engine speeds practically all of the current generated passes directly to the battery and lamps and the machine acts as a simple unhampered shunt dynamo. However, the iron wire will allow only a certain number of ampere to pass, after which it suddenly increases in resistance, so that any excess current cannot pass, but must go through the field bucking coil which thus, only at high speeds, comes into action and chokes down the dynamo excitation. It will thus be seen that the output of the dynamo may be adjusted to any value desired by simply employing an iron wire of suitable diameter in the ballast coil. At car speeds below 15 miles an hour, the dynamo acts as a simple uncontrolled shunt wound machine, while at the higher speeds, owing to the counter effect of the bucking coil, the resultant excitation is less than the excitation due to the main shunt field coil alone. In order to keep the current in the main shunt field coil as nearly constant as possible, it is connected at a point beyond the ballast coil instead of directly across the brushes; then it does not feel the fluctuations of voltage at the brushes. The effect of controlling the bucking coil by the current output is to produce an approximately constant current at the higher speeds. The voltage is determined by the storage battery, and is simply the voltage required to force the specified current against the reverse pressure, plus the small internal resistance of the battery. Assuming the battery to be in good condition, the dynamo voltage will be slightly in excess of the open circuit voltage of the battery, from about  $6\frac{1}{4}$  to  $6\frac{1}{2}$  volts, depending upon the state of charge. The battery is necessary to control the voltage of any automobile lighting dynamo, and must never be disconnected therefrom while the dynamo is in use,

point, the pressure induced in the armature will become less than the battery pressure against which it must force the current in charging, and accordingly, unless some automatic device be provided to break the circuit when such condition obtains, the current will reverse and flow out of the battery.

**Ques.** What is the automatic device called?

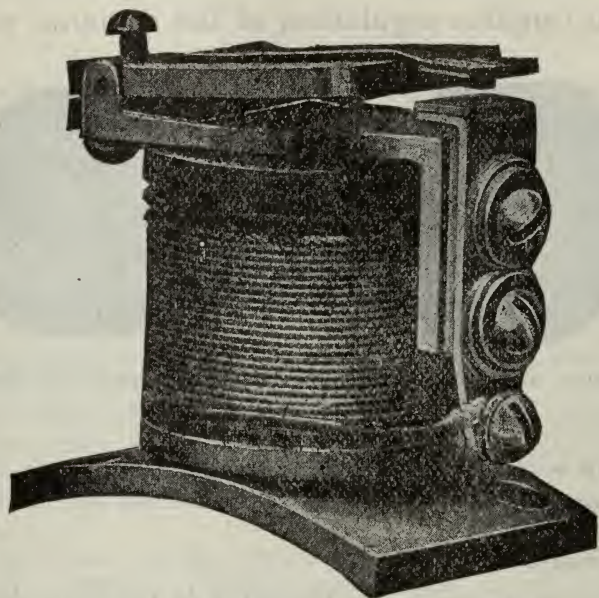


FIG. 4,056.—Automatic cut out as used for Rushmore electric car lighting system.

**Ans.** It is properly called a discriminating cut out or reverse current circuit breaker, and *erroneously* a relay.

**Ques.** Describe a discriminating cut out.

**Ans.** It consists of an electromagnet connected in the dynamo circuit, which, when the dynamo generates sufficient pressure to charge the battery, will attract an armature and close the circuit between the dynamo and battery, and which will also open the circuit when the battery pressure becomes greater than that induced in the dynamo.



**Ques.** What requirement is essential in charging a battery?

**Ans.** The voltage of the dynamo must not exceed a certain maximum, so that the charging rates do not become higher than that proper for the battery.

**Ques.** How is this condition obtained?

**Ans.** By automatic regulation of the dynamo voltage.

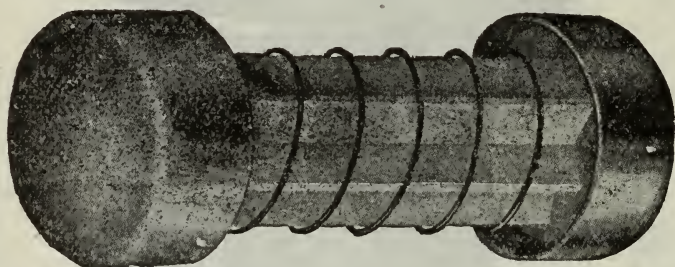


FIG. 4,057.—Rushmore ballast coil with cover removed to show the iron wire; illustration full size.

There are several ways of effecting this regulation:

1. Mechanically;
2. Electrically;
3. Thermally.

These several methods are illustrated in the accompanying cuts.

An example of mechanical control is the Gray & Davis system, where a clutch and centrifugal governor are used.

The Ward-Leonard has electromagnet control, and in the Westinghouse there are two electrical fields, which oppose one another as the speed of the dynamo increases.

The Rushmore system furnishes an example of thermal control.



## CHAPTER LXXVII

# ELECTRIC VEHICLES

The term *electric vehicle*, is generally applied to a great variety of either passenger or freight carrying machines which are propelled by electric energy supplied usually from storage batteries, and in some cases from dynamos direct connected to gas engines; the latter type, however, does not include gas electric combinations used on some electric railroads.

The principal types of electric vehicle which are commercially successful at the present time are:

1. Electric automobiles, represented by various types of roadster, coupe, phaeton, cab, etc., suitable for the use of physicians, business men and others, in city service.

2. Electric trucks and vans for moving merchandise, and for delivering purposes.

3. Gasoline-electric trucks, which represent an attempt to overcome the lack of flexibility of internal combustion engine by combining it with a dynamo and storage battery.

**Electricity as a Motive Power.**—Vehicles propelled by electric motors, whose energy is derived from secondary batteries, are preferred by some on account of the combined advantages in point of cleanliness, safety and ease of manipulation. When well constructed and well cared for, they are also less liable to get out of order from ordinary causes. Among their disadvantages, however, may be mentioned the fact that the storage battery must be periodically recharged from some primary electrical source, which fact greatly reduces their sphere of efficient operation.

Since electric vehicles are not the prevailing type, charging stations are in some localities few and far between which would make it impossible under these conditions to make an extended tour from the base of supplies. This difficulty cannot be overcome by carrying an extra battery since the additional weight would curtail the speed and carrying power of the vehicle.

It is impracticable to propel a vehicle by a battery of primary cell, since such a battery of sufficient power would have little, if any, advantage in point of endurance over secondary cells, and when once exhausted must be entirely replaced.

**Light Electric Vehicles.**—These are of various types, such as roadsters, victorias, phaetons, runabouts and coupes, and are

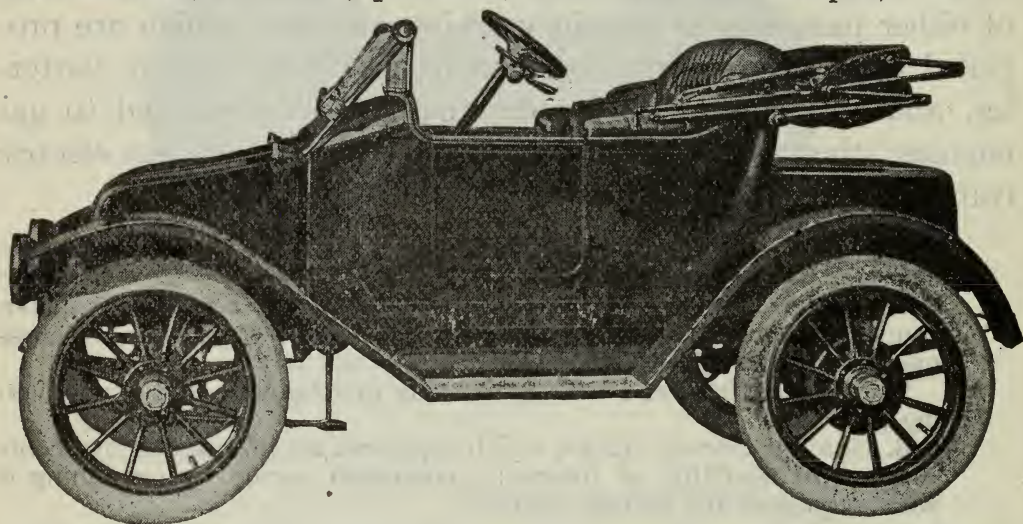


FIG. 4,058.—Baker electric roadster. The general specifications are as follows: frame, pressed steel; wheel base, 88 ins.; tread, 50 ins.; steering mechanism, two types, one with wheel steer, the other with lever steer; controller, continuous torque type, six speeds forward and three reverse; springs, semi-elliptic and full elliptic rear; battery, 34 cells, 13 MV thin plate Exide, standard; tires, 32×4 special electric pneumatic front and rear or 34×4 cushion front and rear; brakes, two sets of internal expanding on rear wheels, operated independently by two foot pedals; body aluminum, with side doors, open top, nickel and black metal finishings throughout; painting, body black, blue, green, or maroon panels, striping to match; upholstery, blue, green, or maroon leathers, or imported broadcloths, standard; fenders, full skirted metal curved fenders; equipment, two head lamps, two side lamps, tail lamp, side and storm curtains; volt ammeter and shaft odometer, full kit of tools, special adjustable clear vision wind shield, electric horn.

equipped with batteries which have a capacity ranging from 75 to 100 miles per charge, with controller arrangements for providing speeds varying from 6 to 25 miles per hour. In these cases the number of cell in each battery may vary from 10 to 30 according



to the make and number of plate in each cell. The number of plate in each cell may vary to suit special conditions.

**Electric Trucks for City Service.**—Under certain traffic conditions and surface requirements, the superior mobility of the gasoline engine truck effects a saving in drivers sufficient to compensate for the higher maintenance charges, but when the number

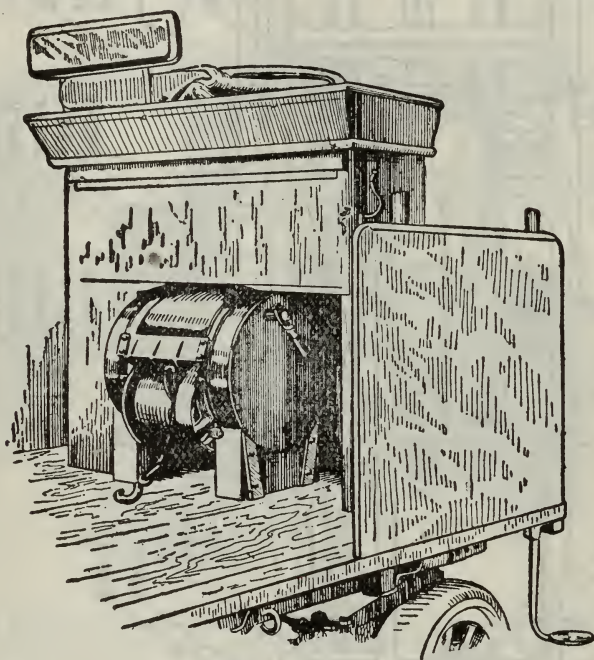


FIG. 4,059.—View of front portion of electric truck showing electric winch which provides mechanical means for loading or unloading, consequently reducing the time necessary for this performance, especially in the case of bulky and heavy articles, thus in some instances increasing the total utility of the machine and operator.

of active truck is the same in each case, the electric truck is sometimes the more economical.

The gasoline engine truck has the advantage in all classes of service requiring a greater mileage than that which is conveniently obtainable with the electric truck, but the greater portion of city delivery service is well within the limits of the safe operative mileage radius of the electric truck built at the present time.

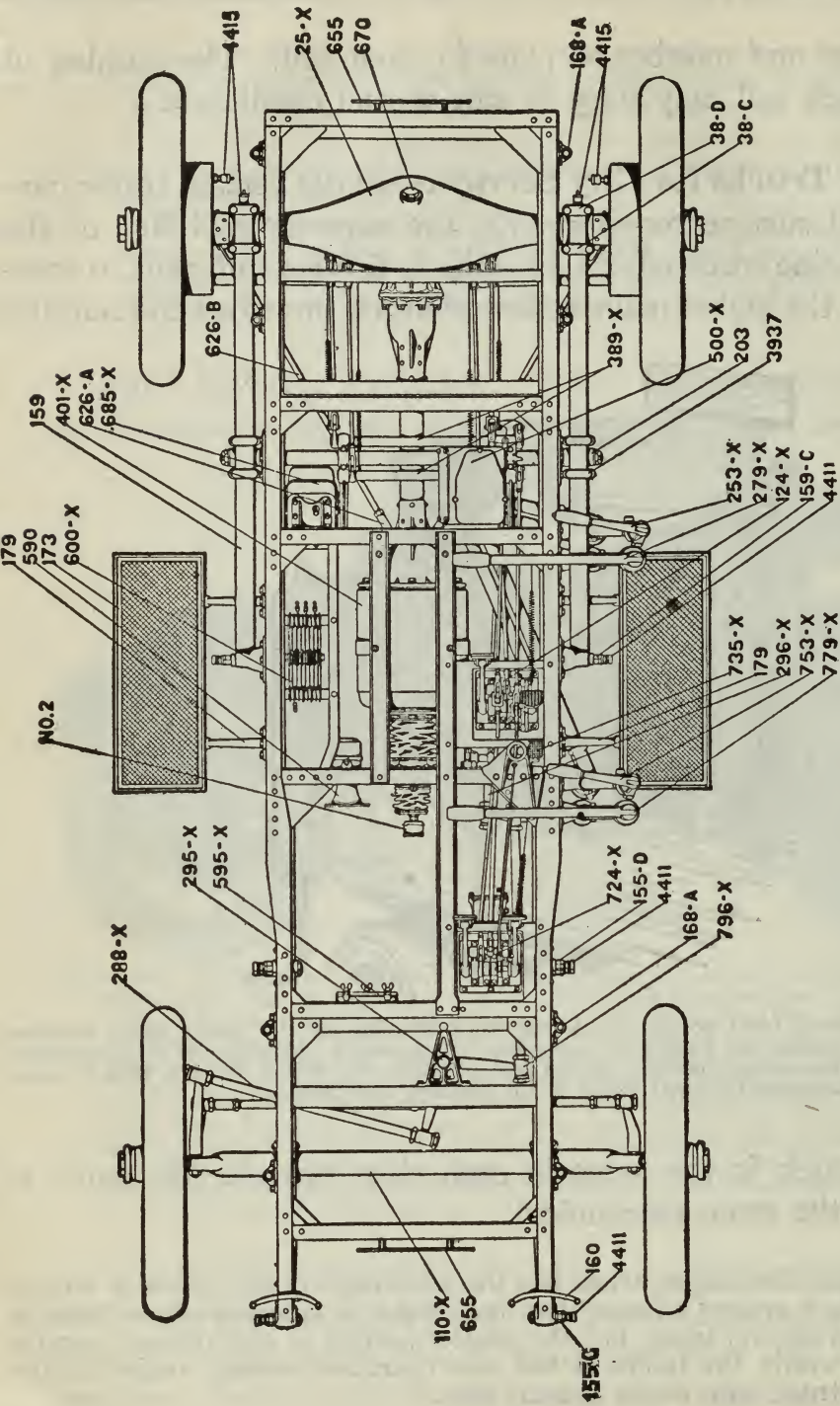


FIG. 4.060.—Plan view of Baker electric chassis. The parts are: 25-X, rear axle; 38-C, rear spring yoke front; 38-D, rear spring yoke rear; 110-X, front axle; 124-X, front levers, rear; 155-C, front spring bolt, front; 155-D, front spring bolt, rear; 159, rear spring; 159-C, rear spring bracket; 160, head lamp bracket; 168-A, fender bracket; 173, step pad; 179, step bracket; 203, rear spring seat, center; 253-X, rear control mast; 279-X, steering mast, rear; 288-X, lower steering rod, bell crank to spindle; 295-X, bell crank; 296-X, lower steering rod, mast to mast; 389-X, brake shaft; 401-X, motor; 500-X, controller; 590, horn; 595-X, fuse box; 600-X, resistance; 626-A, brace rod clevis; 626-B, brace rod; 655, license bracket; 670, oil inlet; 685-X, contactor; 724-X, foot levers, front; 735-X, interlock; 753-X, front control mast; 779-X, steering mast, front; 796-X, lower steering rod, mast to bell crank; 3,937, rear spring clip; 4,411, 4,415, No. 2 grease cups.



**Gasoline-Electric Vehicles.**—The principal disadvantage of the gas engine for self-propelled vehicles is its lack of flexibility; while on the other hand, the principal disadvantage of the electric vehicle operated by means of storage batteries is its lack of mobility. It is evident that the short coming in each case can be overcome only by combining the gas engine with a dynamo connected to a storage battery, for supplying the power required by the electric motors.

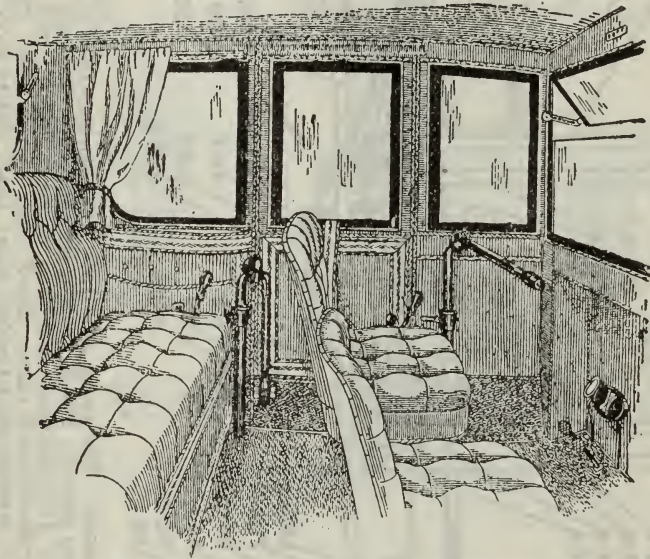


FIG. 4,061.—Interior Waverly front and rear drive electric brougham. The seating arrangement of this type of electric duplicates that of the Waverly front drive four with the addition of separate steering and controlling levers, and a separate set of brake pedal at the left of the rear seat. The car in this way gains the advantage of dual driving systems, a feature sometimes desired.

Such a combination will operate at practically constant speed at all loads, as the dynamo with the storage battery serves to furnish the necessary overload, or consumes that portion of the energy which is not needed. Furthermore, the transmission will be entirely electrical and will possess the simplicity and flexibility of electric control; while the use of a motor will allow the attainment of various speeds by series-parallel combinations.

Vehicles of this type are built in the form of omnibuses, surface cars and trucks for city service and freight and passenger cars for interurban railway service. The arrangement appears better adapted to the latter service, than for propelling pleasure vehicles.

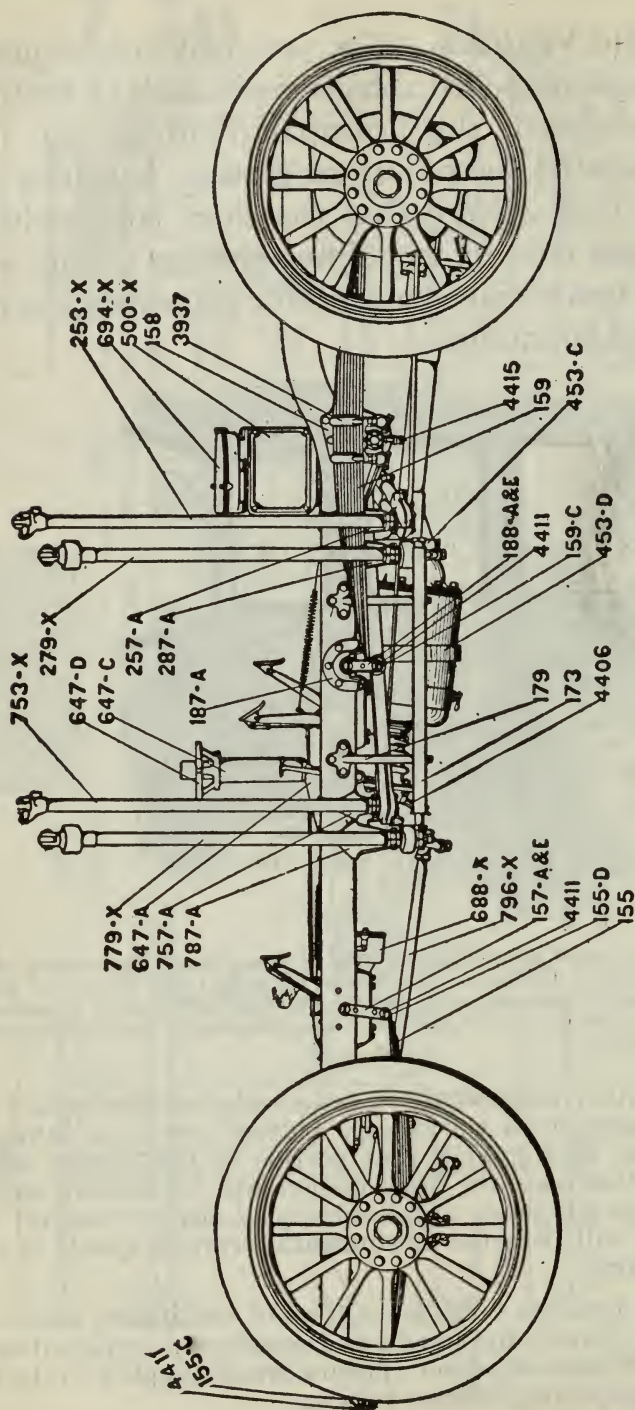
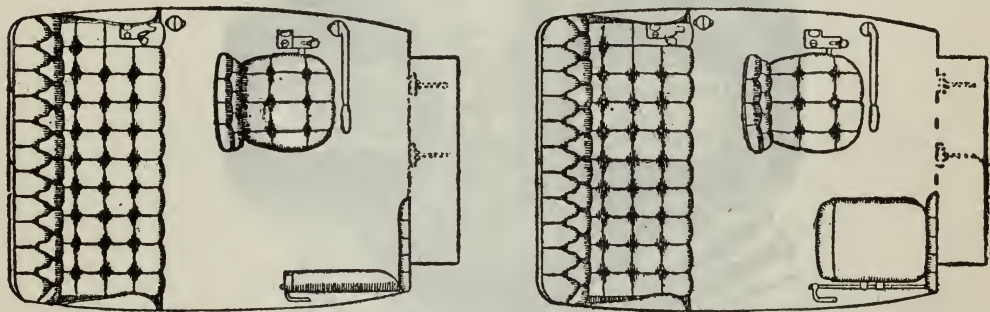


FIG. 4.062.—Side view of Baker electric chassis. The parts are: 155, front spring; 155-C, front spring bolt, front; 155-D, front spring bolt rear; 157-A, front spring shackle; 157-E, front spring shackle lock plate; 158, rear spring bracket center; 159, rear spring; 159-C, rear spring bolt; 173, step pad; 179, step bracket; 187-A, front hanger for rear spring; 188-A, rear spring shackle; 188-E, rear spring shackle lock plate; 253-X, rear control mast; 257-A, rear control mast bracket, lower; 279-X, steering mast, rear; 287-A, steering mast bracket, rear; 453-C, safety loop, short; 453-D, safety loop, long; 500-X, controller; 647-A, seat pedestal bracket, left; 647-C, seat pedestal tube, left; 647-D, seat pedestal stop cup; 688-X, opening switch; 694-X, closing switch; 753-X, front control mast; 757-A, front control mast bracket, lower; 779-X, steering mast, front; 787-A, steering mast bracket, front; 796-X, lower steering rod, mast to bell crank; 3,937, rear spring clip, 4,406, 4,411, 4,415, grease cups.



**Electric Vehicle Essentials.**—The three essential features which convert a vehicle into an electric automobile are the battery, the motor and the system of transmitting power from the motor to the propelling wheels.

In order to move a body from one point to another, it is necessary to apply power to overcome the various opposing forces that always exist. In putting any body, say a carriage, into motion, the effect of its weight, called inertia, opposes the force producing the motion. Inertia requires an application of



FIGS. 4,063 and 4,064.—Waverly alternative seating arrangements.

force directly proportional to the rate at which the vehicle is accelerated. Besides this, there are several forces which are active not only on starting and increasing the speed, but when a uniform motion has been attained. These forces are: 1, wind pressure; 2, internal friction of tires; 3, losses in the various moving parts; 4, electrical losses in battery; 5, electrical losses in wiring and motor; 6, gravity in ascending hills.

All these forces which are met when the vehicle is under motion absorb more or less power, and, as in an electric machine the quantity of energy that can be stored is limited, it is of the greatest importance that the designing engineer should bear in mind the vital necessity of cutting down these opposing forces as much as he possibly can.

**Wind Pressure.**—The resistance of the air encountered by a vehicle at normal speed is not a very serious matter, but with an increase of speed or with a head wind, the loss becomes quite large and racing cars are built with the idea in view of reducing the area exposed to the wind and so shaping the exposed parts that the machine will cut its way through with the smallest amount of retardation.

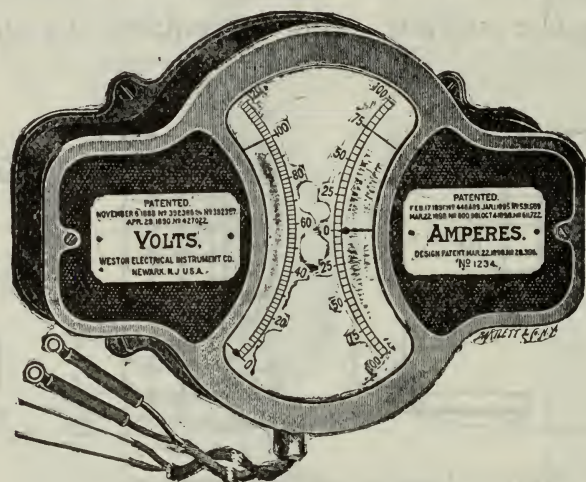


FIG. 4,065.—Weston volt ammeter of the type used on electric vehicles. In some types, the index is side by side instead of end to end.

**Tire Friction.**—The most important loss, perhaps, and one that is least understood is the effect of tires.

It is clear that the portion of any tire which is in contact with the earth must be flattened, but in order to do this, not only must some other parts of the outer surface of the tire assume a deformed shape by creeping, but there must be a change in the relative position of the internal particles. If the tire be a double tube, pneumatic, the inner tube will rub against the casing and the casing will have more or less play against its fastening.

In every pneumatic tire, besides the rubber composition there must be a certain amount of tough cotton fabric which gives the entire structure its strength. In most tires of standard make this material is inserted in the shape of canvas fairly closely woven and quite stiff. In these tires the elasticity of the rubber is restrained and controlled by this



cloth, and it is readily seen that there is but little of the power of flattening or adapting itself to the road that would be possible by the same tire were rubber used alone.

Thread and cord fabric tires have been developed with the intention of retaining the strength of the cotton and at the same time permit of more freedom of motion than canvas will allow. The idea is to use independent threads or cords and surround them with rubber. The one layer of such threads being wound in the direction of the thread on a right hand screw and the next layer at right angles to these. The action of all the threads will then resemble very much a strip of loosely woven cloth cut bias.

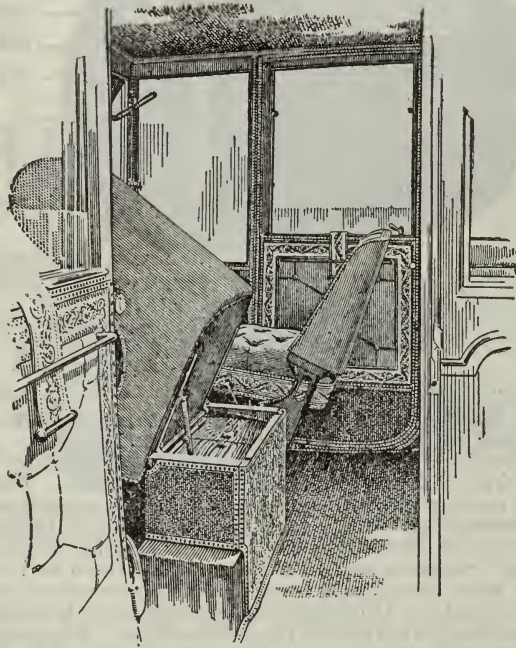
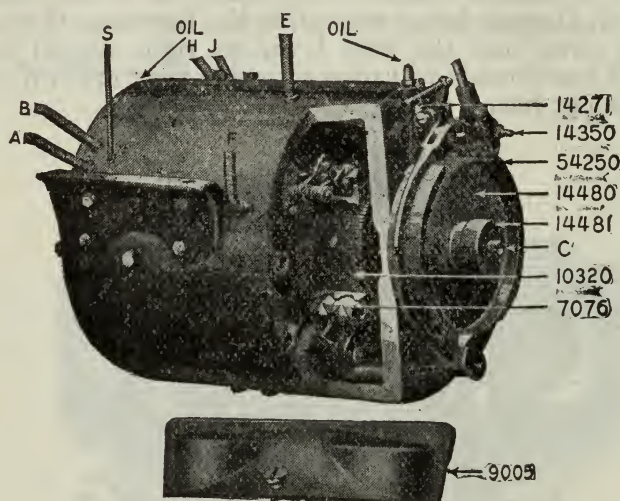


FIG. 4,066.—Interior of Borland electric. The driving seat is tilted forward to show the means of ready access to controller through the box-like base beneath the seat.

There are losses in the electric motor, controller and wiring which in importance rank next to tire losses; besides the design of the motor should be such that outside of the question of its own efficiency its propelling power should be so regulated that the maximum distance may be covered on a single charge.

In the design of electric vehicle the object of the builders should be to attain the greatest possible mileage consistent with durability; also lightness, combined with strength and efficiency in every part. To this end manganese bronze, aluminum, seamless tubing and drop-forged steel are the materials that are largely used.

**Motors for Electric Vehicles.**—These are of the enclosed type of construction, which of necessity they must be, in order to protect them from dust, etc., in their exposed positions under the car. They are designed for heavy overloads.



**FIG. 4,067.**—Rauch and Lang electric vehicle motor. *Instructions for care of motor:* The two oil covers lead to the ball bearings in the motor yokes. A good grade of light cylinder oil is recommended for these bearings. The commutator, 10,320, should be at all times kept clean, free from any gummy or gritty substance. The carbon brushes 7,076 should make perfect contact with the surface of the commutator and should be replaced with new ones when worn out. These brushes are originally  $1\frac{5}{8}$  inches long and should be replaced with new ones as soon as the measurement is reduced to  $1\frac{1}{4}$  inches. It is safer to replace these brushes often, rather than allow them to become too short. Very serious damage may result from using brushes that are too short or ones that make poor contact with the commutator. Brushes that are too short or that are making poor contact will pit, burn and blacken the surface of the commutator. Replacement of brushes should be made only by an experienced person. The motor leads are lead out of motor through insulated holes. These holes, lettered J, H, B, A, S, E and F correspond to the letter contacts on the controller into which they are connected. The motor brake may be adjusted for wear by means of the winged nut 14,350. Clearance between brake jaws and wheel may be adjusted by means of the screw 14,271. To remove brake wheel from armature shaft, take the  $\frac{5}{16}$  screw C out of the cap 14,481. A  $\frac{1}{2}$  inch, 12 pitch bolt, 3 inches or longer, or a cap screw may then be screwed through the threads in the cap and up against the end of the armature shaft. Continue to turn this screw and the pulley will be drawn off the shaft.

When a vehicle is started or its speed increased, a certain amount of energy is absorbed to produce this acceleration. The total amount of energy required is in proportion to the total weight and to the square of the velocity, so that to double the



weight of a vehicle means doubling the power required for starting, and doubling the velocity means four times the power. Accordingly, to meet these conditions, especially when starting under severe conditions, as on a sandy road, or in ascending a hill, the electric vehicle motor is constructed for a 200% or more overload.

As stated by one manufacturer, a motor for a two passenger runabout rated at  $2\frac{1}{2}$  horse power consumes 6,800 watts in ascending an 11 per

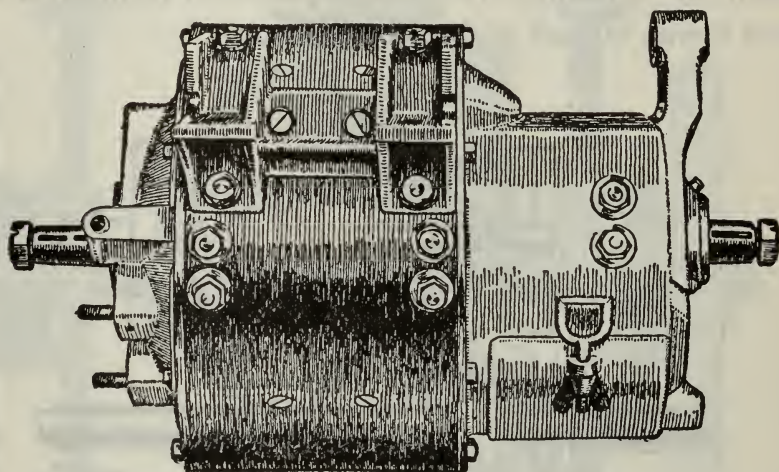


FIG. 4,068.—Waverly 80 volt motor. *In construction* it is series wound medium speed. The armature rotates on ball bearings; four poles are used.

cent. grade at 7 miles per hour, although no more than 360 watts are required to propel the vehicle on an even asphalt roadway at  $8\frac{1}{2}$  miles per hour. These figures represent an effective power range of between  $\frac{1}{2}$  horse power and over 9 horse power.

There seems to be some uncertainty as to the precise power rating of vehicle motors, but, as a matter of fact, they are wound to develop the highest constant power output at the highest voltage used, with a high overload capacity for short spurts, as in hill climbing, etc.

**Ques.** What objectionable feature should be avoided in electric vehicle design?

**Ans.** Very quick acceleration, because a vehicle, constructed

with this feature, not only gives the passenger an unpleasant jerk, but puts a heavy overdraft on the battery.

**Ques.** What are the considerations with respect to friction in the bearings?

**Ans.** Since the amount of power lost by friction in the bearings requires that much more power to be carried by the vehicle, in order to attain the desired mileage or speed, it is very essential to reduce frictional losses to a minimum by using approved forms of ball and roller bearing.

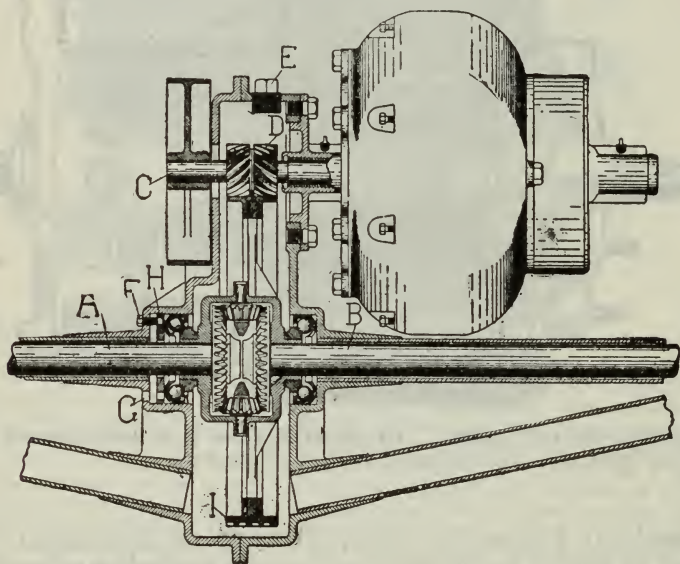


FIG. 4,069.—Diagram of a single motor attached to rear axle through "herringbone" single reducing gears. A, is the left hand section of the divided rear axle; B, the right hand section of the rear axle; C, the brake drum; D, the spiral pinion on the motor shaft driving the worm gear, I, on the differential; E, plug for greasing gears; F, set screw for locking ball race; G, slot for wrench to adjust threaded ring, H, against ball bearings.

**The Drive or Transmission.**—Because of the relatively high speed of the motor as compared with that of the rear wheels of the car, a system of gearing is necessary between the motor and rear axle to obtain the necessary velocity reduction. Moreover, in some cases, other gears must be provided so that



the power may be applied to the rear shaft when the motor shaft and rear shaft are at right angles to each other.

There are several forms of drive, as by

1. Herringbone gear;
2. Chain gear;
3. Worm gear.

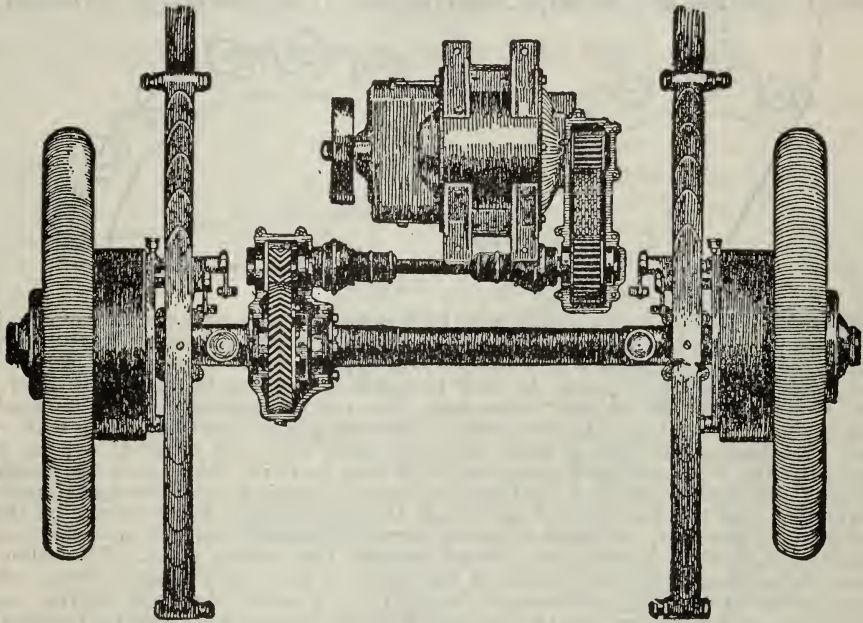


FIG. 4,070.—Waverly double reduction gear or combination herringbone gear and "silent" chain. *In construction* the motor shaft is parallel to the intermediate or jack shaft and drive shaft. Two universal joints are used, so as to give freedom of motion in any direction. The motor weight is above the springs. The first reduction is by the silent chain enclosed in a casing at end of motor; the second reduction is through the herringbone gear in the axle.

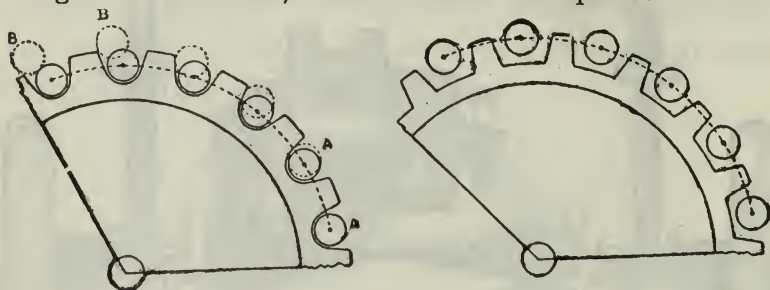
**Herringbone Drive.**—This type of drive gear is extensively used.

The method of attaching a single motor to the rear axle through herringbone single reducing gears is shown in fig. 4,069. A and B, are the two sections of the divided rear axle. The spiral pinion D on the motor shaft drives the worm gear I, on the differential. C represents the brake drum; E, the plug for greasing gears; F, the set screw for locking ball race; and G, the slot for wrench for adjusting threaded ring H, against the ball bearings.

The advantages of this sort of drive are its freedom from noise, its simplicity and durability owing to the parts being enclosed.

**Chain Drive.**—This form of drive is desirable for heavy service, as on very large trucks. It is a noisy and dirty mode of power transmission, and when not enclosed is subject to rapid wear.

In chain drives there is more or less elongation of the chain due to the wear of the rivets and bearings or to stretch of the material. To guard against the latter, chain makers use special material of high



FIGS. 4,071 and 4,072.—Diagrams showing the behavior of a chain on a sprocket of equal pitch, and on one of properly unequal pitch. The following quotation from an English authority explains the action: "A chain can never be in true pitch with its sprocket. A pair of spur gears tend, to a certain extent, to wear into a good running fit with each other, but a chain, if made to fit its sprocket when new, does not continue do to so a moment after being made, as wear at once throws it out. This being so, it must be put up with, and involves the consequence that a chain can only drive with one tooth at a time, supplemented by any frictional 'bite' the other links may have on the base of the tooth interspaces. If the chain be made to fit these accurately (taking a roller chain for illustration), it is obvious that the least stretch will cause the rollers AA to begin to ride on the teeth as at BB. If, however, the teeth be made narrow compared with the spaces between the rollers, a considerable stretch may occur without this taking place. The roller interspaces, then, should be long, to permit the teeth to have some play in them, while retaining sufficient strength, as shown in fig. 4,072. In order that the driving sprocket may receive each incoming link of the chain without its having to slide up the tooth face, it should be of a somewhat longer pitch than its chain, the result being that the bottom tooth takes the drive, this being permitted by the tooth play shown in fig. 4,072. This difference, of course, gradually disappears as the chain stretches. The back wheel sprocket, on the other hand, should take the drive with its topmost tooth, and hence should be of slightly less pitch than the chain, but as the pitch of the latter constantly increases, it may be originally of the same pitch. The only remaining point with regard to design, and one which the owner of a car may easily ensure, is that the number of teeth in the sprockets should be prime to that of the links in the chain."

tensile strength, but if, for any reason, a link elongates unduly, it should be replaced at once, as one long link will eventually ruin a chain. Such elongation sometimes results from a sudden application of the load.

To prevent undue interference between the chain and sprocket as the result of elongation, the sprockets are not cut to fit the chain accurately but with a certain amount of pitch line clearance.

**Ques.** State a very objectionable feature of chain drives?

**Ans.** The chain sometimes climbs the sprocket teeth.



**Ques.** What is the cause of this?

**Ans.** Considerable wear or too little clearance.

If a sprocket were cut without clearance, an elongated chain would climb the teeth and the latter would exert a wedging effect, thus subjecting the chain to excessive strains. **In design** the amount of clearance should be as large as is consistent with the proper strength of the teeth.

**Ques.** Under what conditions should a chain operate?

**Ans.** It should work in oil, in a dust tight case.

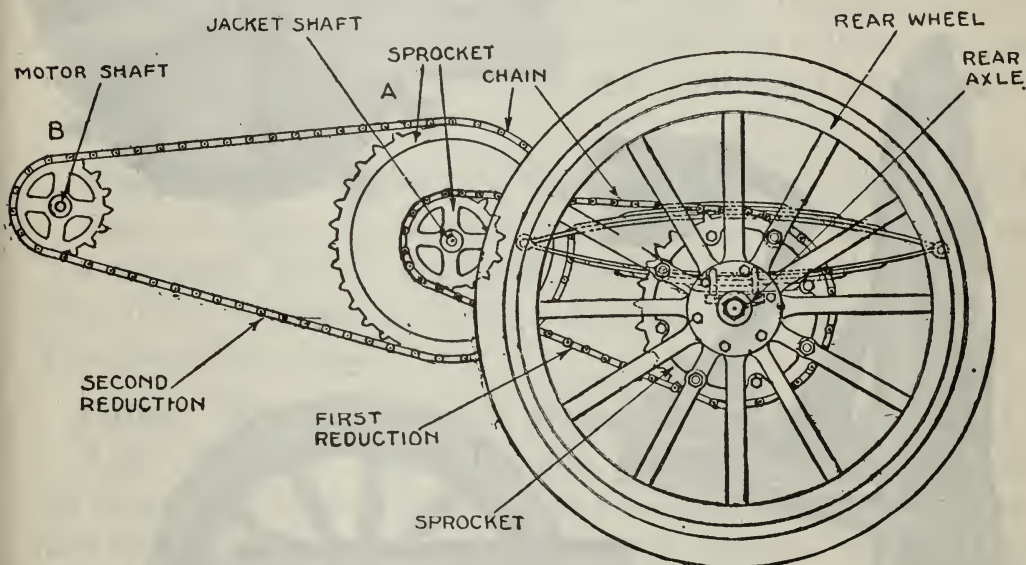


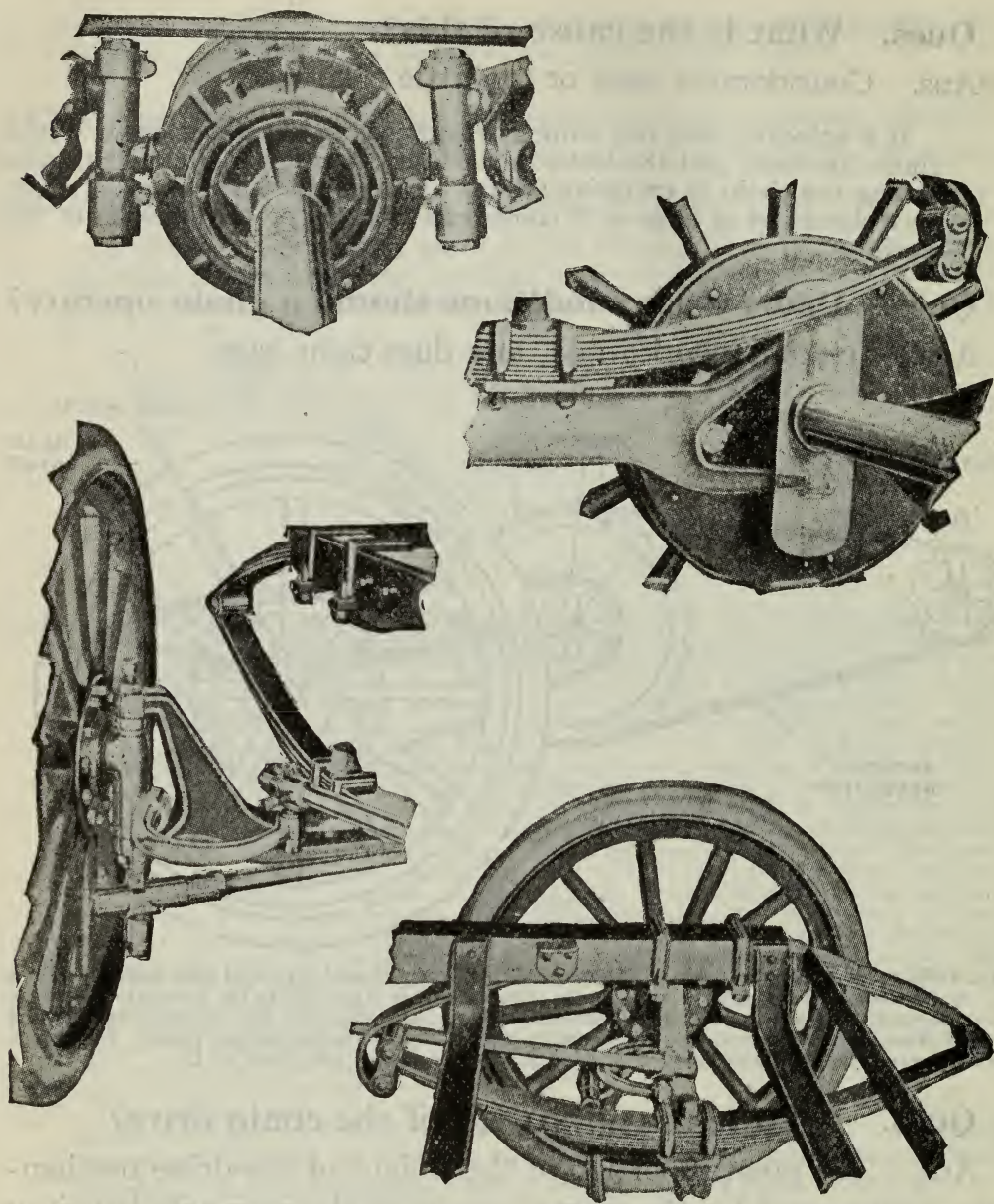
FIG. 4,073.—Double chain drive. The rear axle is of the "dead" type and each rear wheel has a sprocket with which the chains mesh. The jack shaft is parallel to the rear axle and upon the maintenance of parallelism between the two axles depends the satisfactory working of the chain. The cut illustrates single and double reduction chain drive. For single reduction the motor would be located at A, and for double reduction, at B.

**Ques.** What is the advantage of the chain drive?

**Ans.** The greater portion of the weight of the drive mechanism is supported by the frame instead of the rear axle housing; it is thus cushioned from shocks due to uneven road.

**Ques.** What two kinds of chain are used?

**Ans.** Block chain and roller chain.



FIGS. 4,074 TO 4,077.—Details of Wood's electric vehicle construction. Fig. 4,074, **motor suspension** showing detail of the hangers between which the motor is suspended; fig. 4,075, **radius rod connection**, showing phantom view of radius rod and how attached to rear axle housing. Also mounting of rear spring or radius rod forward to rear axle; fig. 4,076, **steering knuckle**, showing connections and half of front spring; fig. 4,077, **front spring** showing full elliptic design and method of attaching springs to main chassis frame.



**Ques. Describe a block chain.**

Ans. A block chain is made of a series of block, properly shaped to fit the teeth of the sprocket, each joined to similar blocks before and after by side links bolted through the body of the block.

**Ques. Describe a roller chain.**

Ans. A roller chain is composed of a series of roller, known as center blocks, joined by side links. Each roller rotates on a hollow core which is turned to smaller diameter at either end, to fit a perforated side piece joining the rollers into pairs. The side links are set over these side pieces and bolted in place through the cores.

**Ques. How do the two types compare in operation?**

Ans. A block chain with generous slack is liable to meet the sprocket with a continual clapping, which at high speed, becomes a continuous rattle. A roller chain is comparatively free from the trouble.

**Ques. What causes the snap and rattle of a chain?**

Ans. The fact that even with the best designed sprocket, as each tooth in turn passes out of engagement with the chain, the next roller must be drawn forward through an appreciable distance before engaging a tooth. This action not only produces the noise, but it is a factor in waste of driving power.

**Ques. What attention should chains receive to maintain a proper working condition?**

Ans. The principal points to be observed in the use and care of sprocket driving chains are: 1, to maintain the proper tension in order to avoid "whipping"—which, particularly with a long one, is liable to result in snapping of the chain,—and, at best, involves a loss of driving efficiency. The chain should not be drawn too tight, lest a similar disaster result. Some slack

must always be allowed, 2, two sprockets should always be kept in alignment. In the case of a double chain drive, from a counter shaft parallel to the rear axle, care should be exercised to maintain the parallelism, even preferring a somewhat loose chain to a tight one that strains the countershaft, 3, if a link show signs of elongation, it should be

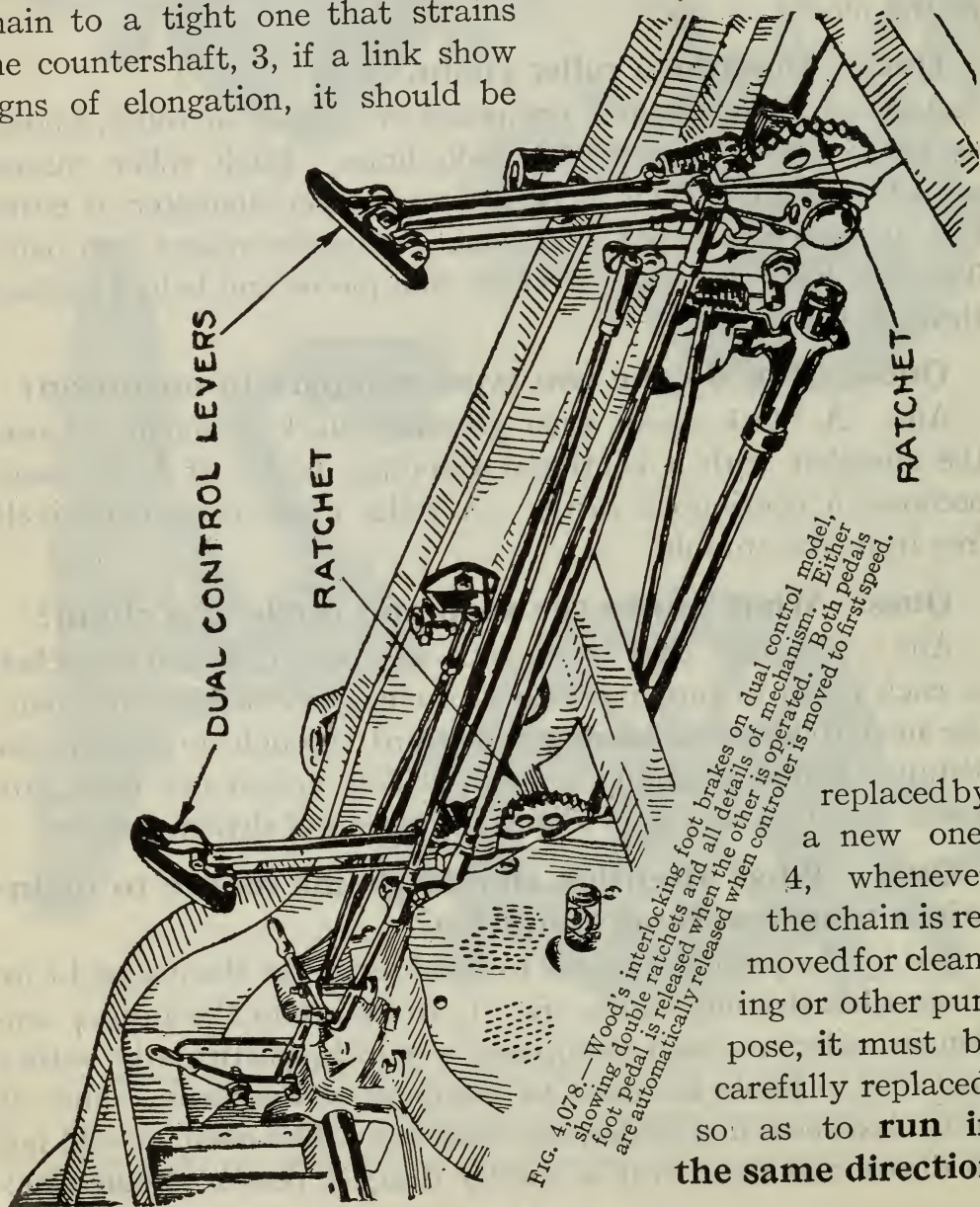


FIG. 4,078.—Wood's interlocking foot brakes on dual control model, showing double ratchets and all details of mechanism. Either foot pedal is released when the other is operated. Both pedals are automatically released when controller is moved to first speed.

replaced by a new one, 4, whenever the chain is removed for cleaning or other purpose, it must be carefully replaced, so as to **run in the same direction**



as formerly, and **with the same side up**. The chain should never be turned around, or its direction between the sprockets reversed, 5, a new chain should not be put on a much worn sprocket, 6, a chain should be frequently cleaned and rubbed with graphite, because the chief difficulty involved in the use of driving chains is the liability to clog and grind with sand, dust, and other abrasives, and 7, after steady use for a more or less extended period, the chain should be removed and cleaned throughout.

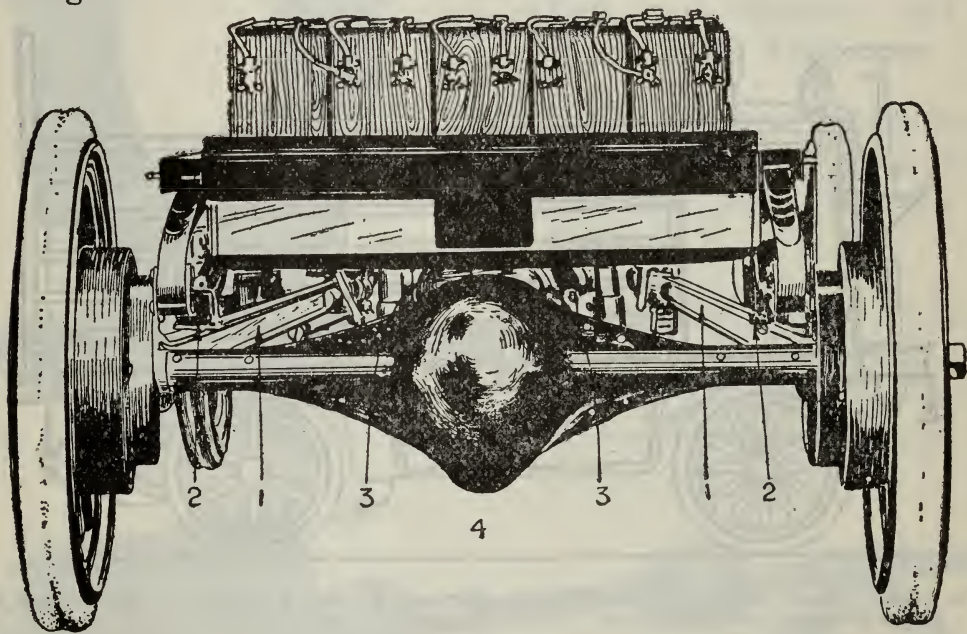


FIG. 4,079.—Rear view of Wood's chassis with battery showing the following **features of construction**: 1, radius rods extending from rear axle to sub-chassis frame; 2, rear springs rest on radius rods, instead of on rear axle; 3, motor, showing ball and socket spring suspension; 4, worm drive, showing location of worm below rear axle.

**Ques.** How may a chain be best cleaned?

**Ans.** After removing it from the sprockets, cleanse first in boiling water, then in gasoline, in order to remove all grease and dirt. The common practice is next to boil the chain for about half an hour in mutton tallow, which is thereby permitted to penetrate all the chinks between rolling surfaces forming an

excellent inside lubricant. After boiling, the chain is hung up until thoroughly cool, at which time the tallow is hardened. It may then be wiped off clean and treated with a preparation of graphite, or a graphite alcohol solution on its inner surface.

Some authorities recommend that the chain, after it is cleaned in boiling water and gasoline, should be soaked, first, in melted paraffin for an hour at least, and then in a mixture of melted mutton tallow and graphite. After each soaking, it is dried and wiped clean. With either process, a daily application of graphite is desirable.

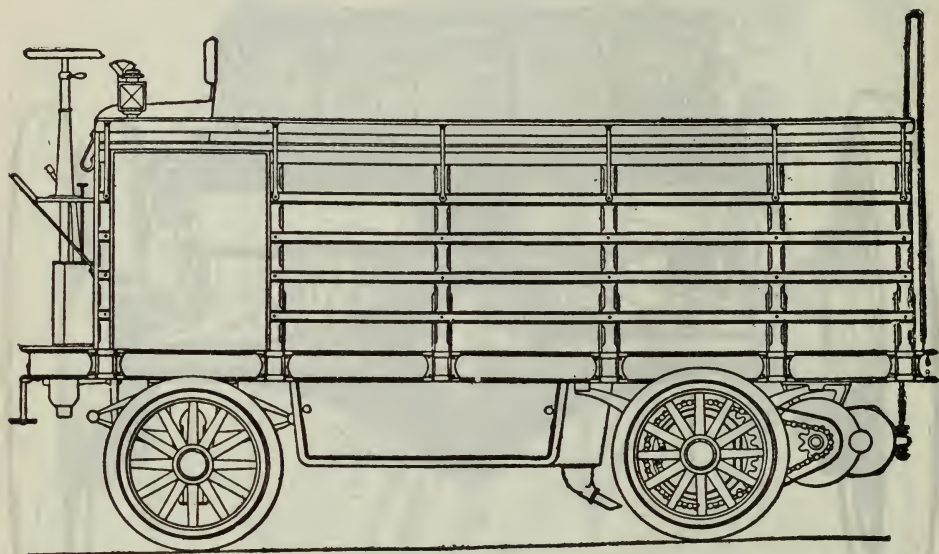


FIG. 4,080.—Chain and sprocket double reduction gear for heavy trucks. As here shown, the motor is hung above the springs, missing the jars of travel.

**Ques.** Is it necessary that both chains be of equal tightness?

**Ans.** No; the differential gear on the jack shaft will counteract this and cause each chain to do its share of the driving.

**Ques.** What adjustment is important with a chain drive?

**Ans.** The jack shaft and rear axle should be made parallel



by adjusting the radius rods to secure the proper engagement of the chain with the sprockets.

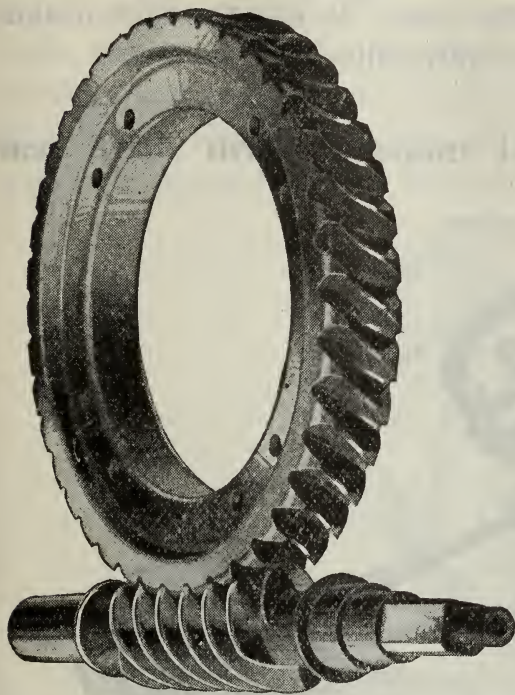


FIG. 4,081.—Baker R and L worm and gear.

**Combination Chain and Gear Drive.**—For very heavy trucks where a considerable reduction in speed is required between the motor and wheels, a double reduction is sometimes used as shown in fig. 4,080.

The motor is usually hung above the springs, thus being protected from the jars of travel.

There are several forms of double reduction using light high speed motors by means of various combinations of

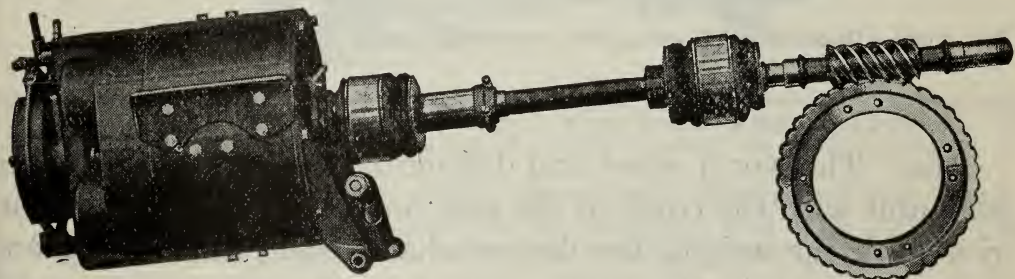


FIG. 4,082.—Baker R and L motor, propeller shaft, universal joints, worm and gear. This is the straight type top mounted worm drive.

gear and chain, with silent, roller chains or herringbone gears for the first reduction, and single or double roller chains, bevel gears or herringbone gears for the second reduction.

**Worm Drive.**—This is a very popular drive for trucks and pleasure cars propelled by electric motors, because of the very large reduction possible on single gear. It has the advantages of silence in operation and great durability.

**Ques.** Describe a typical modern worm drive rear axle construction.

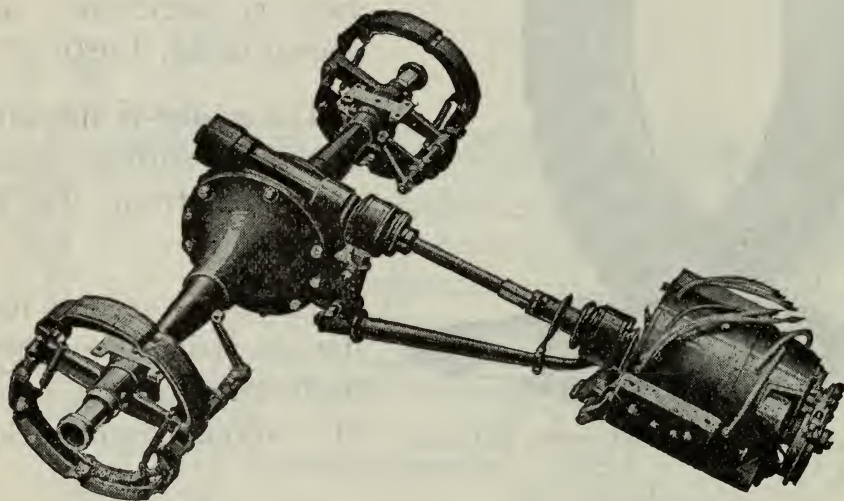


FIG. 4,083.—Baker R and L worm drive transmission unit.

**Ans.** The worm wheel and differential gearing are assembled as a unit with the cover of the axle housing. This housing carries all of the weight, the driving shafts being full floating and transmitting only the driving power to the wheels. A torque rod takes all driving and braking torsional strain, while two side radius rods relieve the rear springs of all tractive effort. Annular ball bearings are used to take the radial and thrust loads of the worm and wheel, while the road wheels run on conical roller bearings.



**Storage Batteries for Electric Vehicles.**—The storage battery has been modified in various ways to adapt it to automobile use, the problem being to secure the greatest specific energy with the least bulk and weight. Its efficiency, or the amount of electrical energy it will discharge in proportion to the amount it takes to charge it is also an important consideration. Average figures run between 70 and 90 per cent.

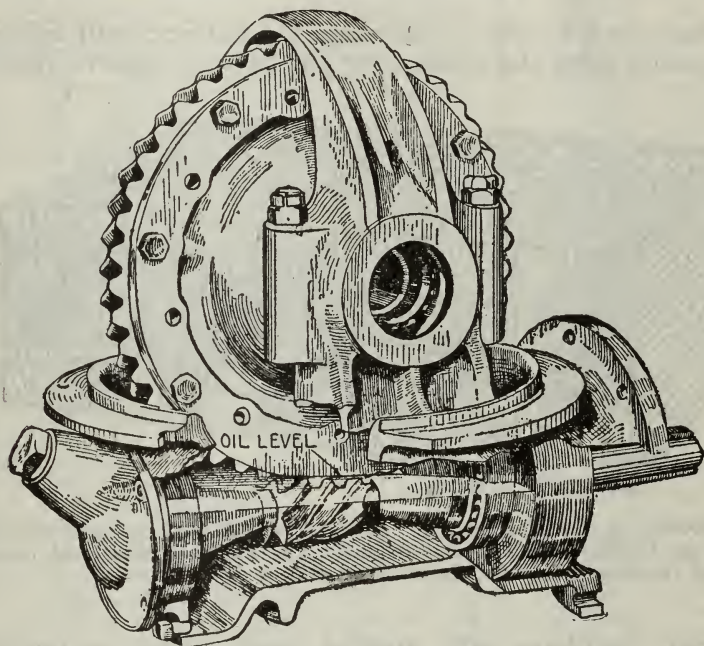


FIG. 4,084.—Lanchester type of worm drive as used on some electrics. An advantage claimed for this form of worm drive is the fact that mounting the worm below the ring gear permits it to be placed in a bath of oil, assuring constant and ample lubrication.

The storage batteries which have proved most successful in connection with electric vehicles are the lead sulphuric acid type, and the iron nickel battery, commonly known as the Edison battery.

**Ques.** What construction is employed to reduce the weight of battery for use in electric vehicles?

**Ans.** The plate surface is finely divided.

The following methods are those most common: scoring, grooving, laminating, casting, pressing and by the use of a lead wool.

The Faure, or pasted type plates are usually lighter and of higher capacity than the Plante, but have a tendency to shed the material for the grid thus making the battery useless.

**Mileage and Battery.**—If the proper mileage per charge be not obtained when all mechanical parts of the car are in good order, it is undoubtedly due to the battery being undercharged and not brought up to full voltage as indicated on the meter.

In this case it is best to discharge the battery until voltage indicates 1.8 per cell; open the hoods over the battery, remove plugs from cells

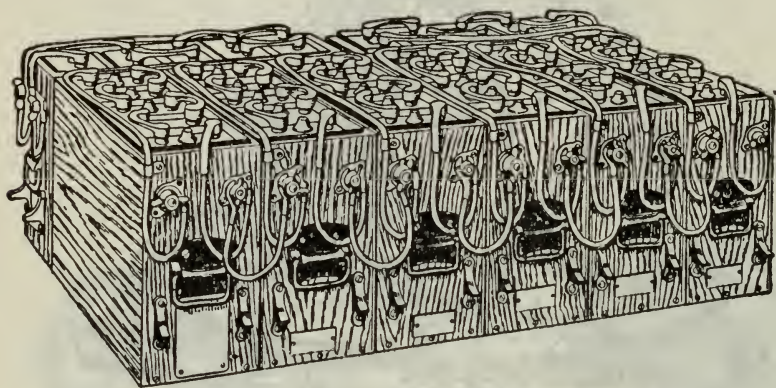


FIG. 4,085.—Waverly 42 cell lead battery. All battery cells are accessible from outside of car by raising the hoods. The battery compartments are lined with acid proof material to prevent acid reaching the paint, the running gear or other parts.

and cover the plates with *distilled* water to within one-half inch of the inside top cover. Charge the battery in the usual way until it reaches a maximum voltage as given on charging card, then charge four hours longer at the lowest rate shown on the card. Try battery; if this do not improve the mileage sufficiently, repeat the operation as before. If after repeating the operation three times, normal mileage be not obtained, and trouble be not found elsewhere the maker of the battery should be consulted at once.

**\* Points Relating to Storage Batteries.**—The following important directions should be carefully followed to obtain satisfactory service for a storage battery:

\* NOTE.—For a full treatment of the subject of storage batteries, see Guide No. 4.



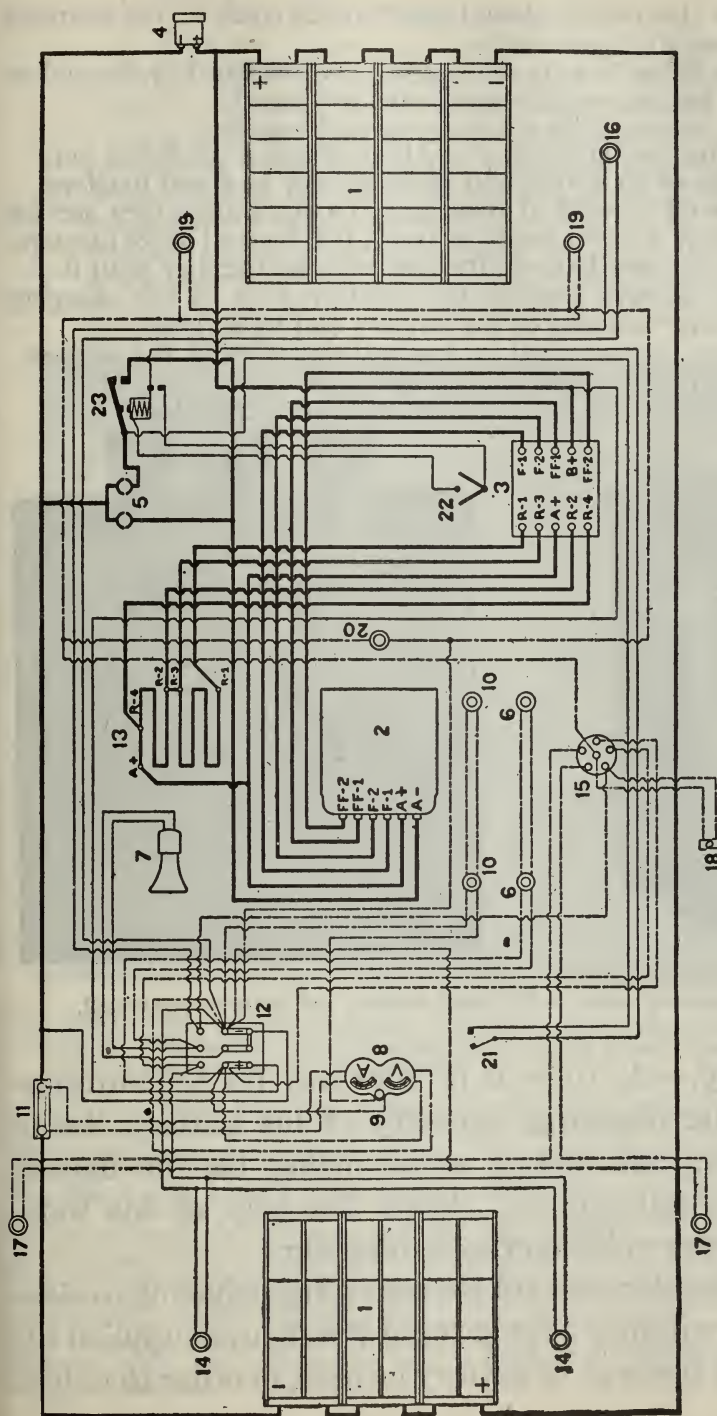


FIG. 4,086.—Wiring diagram of Baker electric. 1, batteries; 2, motor; 3, controller; 4, charging receptacle; 5, starting plug receptacle; 6, signal button; 7, horn; 8, volt ammeter; 9, meter light; 10, light switch; 11, shunt for volt ammeter; 12, fuse box; 13, resistance guides; 14, head light wires; 15, light switch; 16, tail light wires; 17, side light wires; 18, door jamb switch; 19, inside rear corner lights; 20, dome light; 21, opening switch; 22, closing switch; 23, contactor.

1. Keep the battery and connections clean.

2. Go over the same and see that they are bolted up tight.

3. If there be any low cells in the battery, attend to them at once.

4. Keep the electrolyte, or battery solution, at the proper height above the tops of the plates.

5. Keep the density of the electrolyte, or battery solution, at the proper point.

6. Do not charge at a rate that will make the cells exceed 100 degrees F. in temperature.

7. A battery can be ruined in three hours after it has been put in use by being left on charge at a high rate after it is full.

8. The user of the vehicle should keep careful track of the charging and, if possible, watch it personally.
9. In all cases follow strictly the instructions furnished by the maker.
10. Do not let battery stand completely discharged.
11. Do not let battery fully discharge in cold weather.
12. Do not let battery stand in a partly discharged condition long.
13. Do not go away on a visit and allow battery to stand inactive.
14. A battery must be worked constantly to get satisfactory service and when going away for two weeks or more, it is best to make arrangements to have the battery looked after by someone familiar with it.
15. In charging, always connect the positive wire of the charging source to the positive terminal of the battery and vice versa.
16. If the battery become dead, or lose mileage, consult the makers.
17. Charge battery in a warm room in winter.
18. In consulting the makers, be sure to give full particulars.

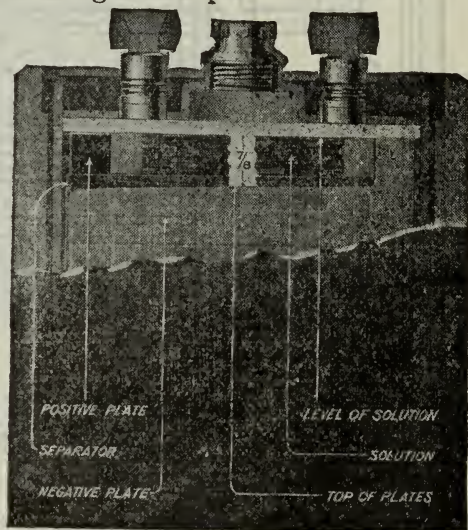
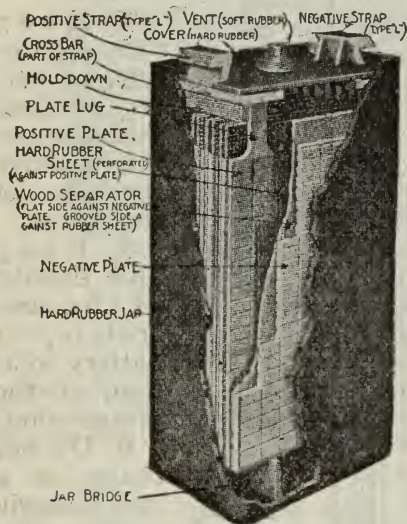


FIG. 4,079.—Gould cell showing parts.

FIG. 4,088.—Sectional view showing height to fill Gould starting and lighting type of cell.

**Battery Capacity.**—As there is no sure way for the automobilist to estimate the discharge capacity of his battery, he is obliged to base such calculations as he makes on the figures furnished by the manufacturers. With the help of his indicating instruments, the voltmeter and ammeter.

Apart from any considerations of efficiency, the driver of an electric carriage should carefully bear in mind the figures supplied by the manufacturers of the type of battery he uses, in order to judge:



1. How long the present charge will last;
2. Whether he be exceeding the normal rate of discharge, and thus contributing to the unnecessary waste of his battery and incurring other dangers that may involve unnecessary expense.

As a general rule the 1 hour discharge rate is four times that of the normal, or 8 hour discharge, and considerations of economy and prudence suggest that it should never be exceeded, if, indeed, it be ever employed. The 3 hour discharge, which is normally twice that of the 8 hour, is usually the highest that is prudent while the 4 hour discharge is the one most often employed for average high speed riding; batteries give only the 3 and 4 hour discharge rates in specifying the capacity of their products.

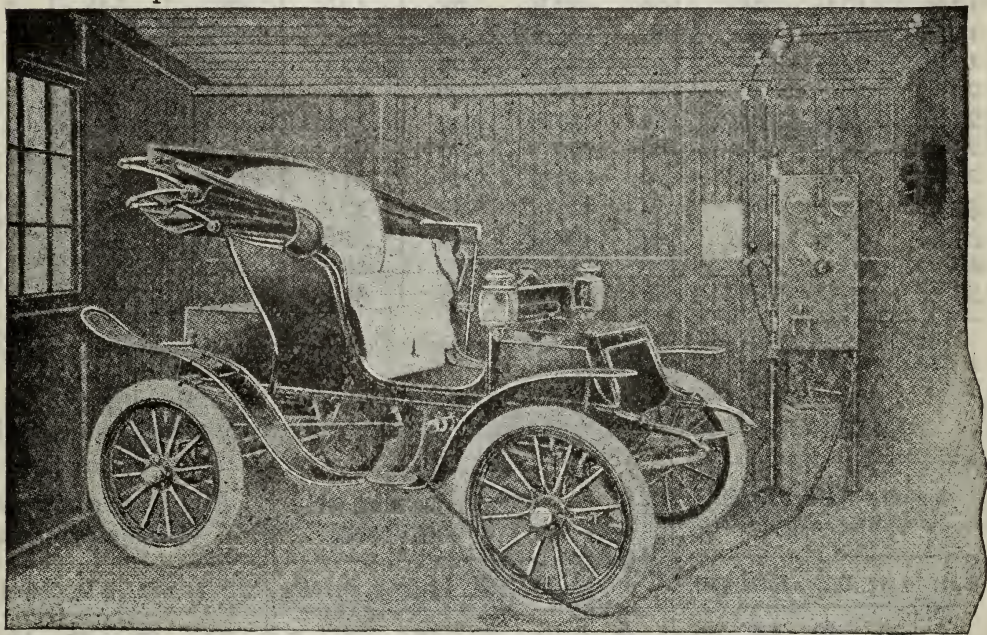


FIG. 4,089.—View showing Studebaker electric in home garage connected to rectifier charging outfit. The subject of rectifiers has been treated at such length in Guide No. 6, that no further explanation is here necessary.

**NOTE.—High Charging Rates.**—Occasionally it is desirable to charge a battery as quickly as possible, in order to save time, as when belated and far from home with an electric vehicle that has almost reached its limit. As a general rule, such a procedure should not be adopted unless the battery be thoroughly discharged. In charging a battery at a high rate, the danger to be avoided is the tendency of the cells to heat. A battery should never be charged at a high rate unless it be completely exhausted, since it is a fact that the rate of charge that it will absorb is dependent upon the amount of energy already absorbed. As shown in the table of high charging rates, the 96 ampere hour cell requires, for charging in three hours: For the first half hour, 70 amperes; for the second, 40 amperes; for the third, 30 amperes; for the fourth, 20 amperes, and during the last hour, 10 amperes. It may also be charged at the following rate in 45 minutes: 140 amperes for the first 20 minutes; 100 amperes for the next 5 minutes; 70 amperes for the next 5 minutes; 30 amperes for the next 10 minutes; 10 amperes for the last five minutes. This is the rate to be followed when the battery is completely discharged.

The following data on sizes suitable for automobile use will be found useful.

Discharge in Amperes Per Hour During			Ampere Hour Capacity When Discharged in			Normal Charging Rate	Outside Dimensions of Jar in Inches		
8 Hrs.	5 Hrs.	3 Hrs.	8 Hrs.	5 Hrs.	3 Hrs.		Height	Length	Width
6¼	8¾	12½	50	43¾	37½	6¼	10½	5¼	4¼
7½	10½	15	60	52½	45	7½	11	7⅞	4¾
8¾	12¼	17½	70	61¼	52½	8¾	12½	7⅞	4¾
10	14	20	80	70	60	10	12	6⅜	7
12½	17½	25	100	87½	75	12½	12	6⅜	7
15	21	30	120	105	90	15	12½	6⅜	7
17½	24½	35	140	122½	105	17½	12½	6⅜	7
20	28	40	160	140	120	20	12½	9⅞	5¾
22½	31½	45	180	157½	135	22½	12½	9	6½
25	35	50	200	175	150	25	12½	9	6½
27½	38½	55	220	192½	165	27½	12½	9	6½
30	42	60	240	210	180	30	12½	9	6½
37½	52½	75	300	262½	225	37½	12½	9⅞	7¾
45	63	90	360	315	270	45	12½	9	8⅝
52½	73½	105	420	367½	315	52½	12½	11⅞	8

NOTE.—The figures will vary for different rates largely due to the number of plate per jar and to other points of construction.

As given by a well known vehicle manufacturer, the following data on discharging and rapid charging of a given make of battery will be found typical:

Ampere Hour Capacity Discharged in—					Normal Charging Rate	Rate in Amperes for a 3 Hour Charge					Rate in Amperes for a 45 Minute Charge				
3 Hr.	4 Hr.	5 Hr.	6 Hr.	8 Hr.		½ Hr.	½ Hr.	½ Hr.	½ Hr.	1 Hr.	20 M.	5 M.	5 M.	10 M.	5 M.
34	38	40	42	48	6	36	20	16	10	5	72	52	36	16	5
45	50	53	55	64	8	48	28	20	16	7	96	68	48	20	7
66	73	78	81	96	12	70	40	30	20	10	140	100	70	30	10
112	124	132	137	160	20	128	68	52	32	17	238	170	119	51	17
140	155	165	171	200	25	150	86	62	42	21	300	214	150	64	21
168	186	198	206	240	30	178	102	76	50	26	356	254	178	76	26
196	217	231	240	280	35	208	118	90	60	30	420	300	210	90	30

NOTE.—It is customary to state the normal capacity of a cell in ampere hours, based upon the current which it will discharge at a constant rate for eight hours. Thus a cell which will discharge at 10 amperes for 8 hours *without the voltage falling below 1.75 per cell* is said to have a capacity of 80 ampere hours. It does not follow that 80 amperes would be secured if the cell were discharged in 1 hour. It is safe to say that not more than 40 amperes would be the result with this rapid discharge. *The ampere hour capacity decreases with the increase in current output.* Generally speaking, the voltage during discharge is an indication of the quantity of electricity remaining within the cell.



**Electric Vehicle Controllers.**—The form of controller adapted to electric vehicle use consists of a rotatable insulated cylinder carrying on its circumference a number of contact, arranged to make the desired connections with the terminals of the various apparatus in the circuit through a wide range of variation.

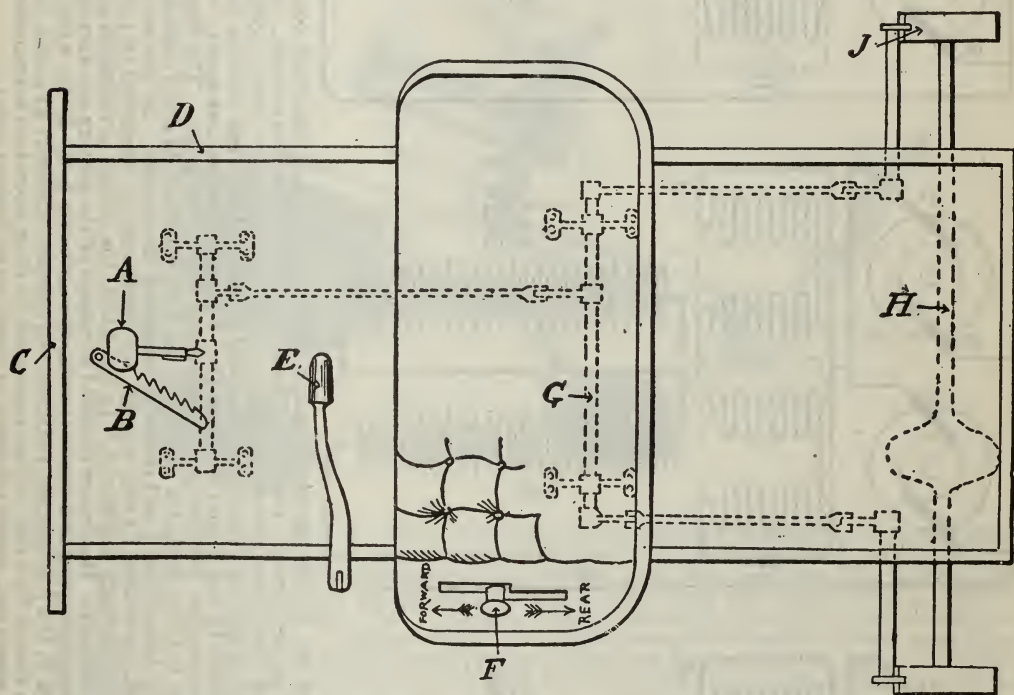
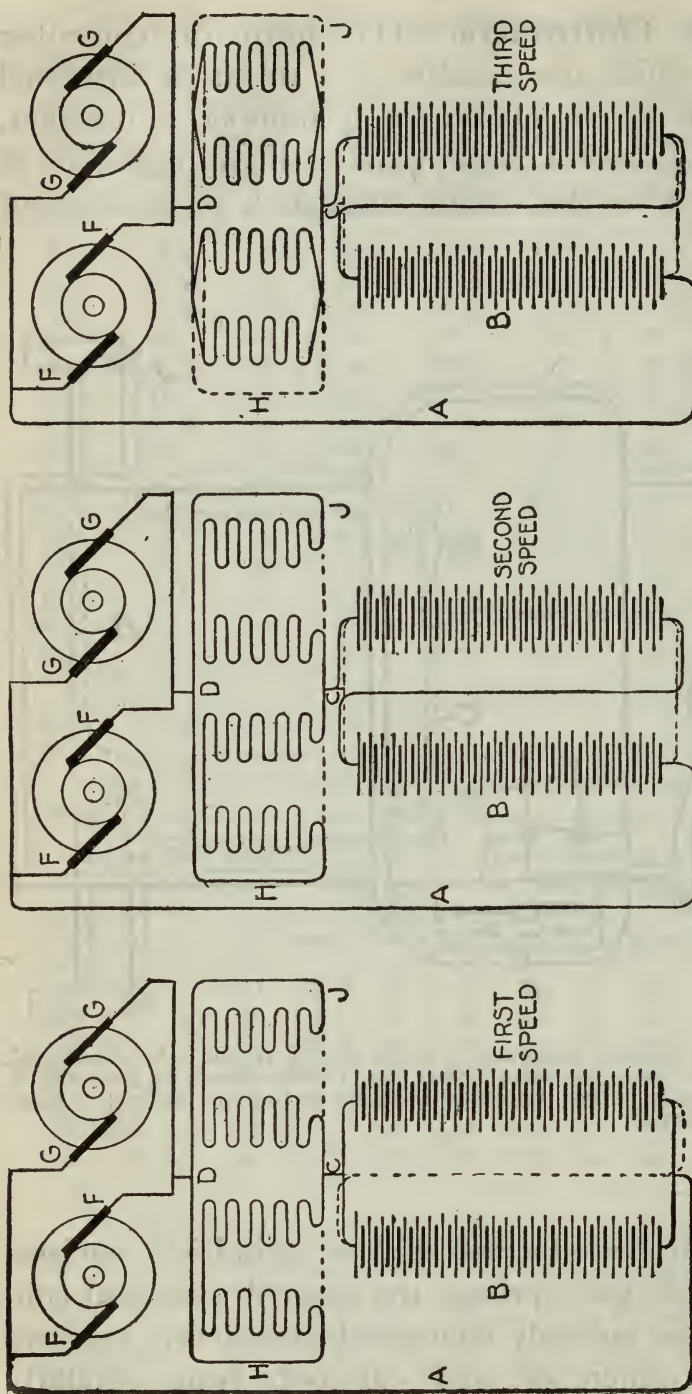


FIG. 4,090.—Diagram of the controlling apparatus of a light electric vehicle, A, brake pedal; B, ratchet retaining pedal in place, operated by left foot; C, dash board; D, body sill; E, steering handle; F, controller handle; G, rocker shaft for setting hub brakes; J, brake band on wheel hub; H, rear axle.

Some controllers are constructed with a cylindrical surface, upon which bear single leaf springs, the desired electrical connections being made by suitably connected conducting surfaces on the cylinder circumference, and cut outs being similarly

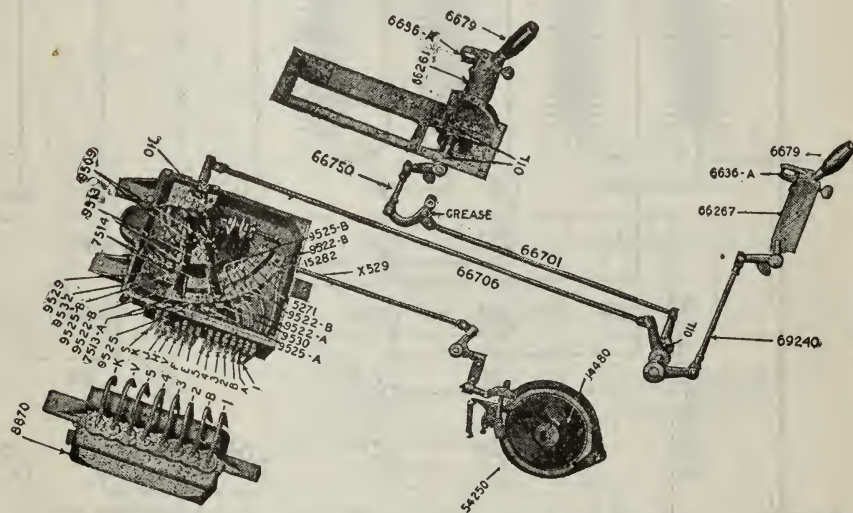


**FIGS. 4,091 TO 4,093.**—Diagrams of the circuit changing arrangements of a typical electrical vehicle. The full lines in these diagrams indicate the closed or active circuits; the dotted lines the open, or inactive circuits. As may be readily understood, the whole scheme of the circuit changing depends on employing several different circuit connections between battery and motor, which may be opened and closed, as desired. Here A and C are the lead wires between battery, B, and motor brushes, FF and GG, and the field windings H and J, and the wire D. Fig. 4,091 shows first speed; two units of the battery B are connected in parallel, which means that the voltage is reduced to the lowest point. The wire C, connected to the bridge between the positive poles of the battery, leads the current to the field windings, H and J, which, in this figure, are connected in series-parallel, which gives the lowest speed and power efficiency of the motors. By the wire, D, the current is carried to the brushes, FF and GG, which, according to this scheme, are permanently connected in parallel; the return path to the negative pole of the battery being through the wire A. In fig. 4,092, the circuit is varied so as to connect the two units, so as to give its highest pressure efficiency. But, since the field windings of the motors are also connected in series, or in series parallel, as in this case, the efficiency in speed and power is reduced nearly one-half. In fig. 4,093, the two units of the battery are connected in series, which, as in the former case, indicates the greatest efficiency in power output; but the field windings are connected in parallel, which means that the voltage generated by their operation is equivalent to the voltage of only one motor, with the result that the speed and power efficiency is raised to its highest point.



accomplished by insulating surfaces, bearing against the spring contacts at the desired points. This type of controller is one of the most usual forms for motor vehicle purposes.

As is obvious, it is possible to so arrange the electrical connections on the controller surfaces, that by proper contacts with the terminal springs, reversal of the motor may be accomplished. This is done in a number of controller, the reverse being accomplished at a definite notch on the quadrant of the shifting lever.



**FIGS. 4,094 and 4,095.—**Baker R and L selective dual controller, control handles, resistance and motor brake. **General care:** keep the plates 9,522-B and 9,525-B on the face of the controller and the shoes 7,513-A on the movable arm clean and free from burned and rough edges. The contact plates 9,522-B and 9,525-B and the shoes 7,513-A are the ones that become damaged first. They are removable and when badly worn may be replaced with new ones. **Instructions for adjustment of motor brake and controller to controller handle.** Set the controller arm fingers 9,513 in neutral position, as shown in cut, remove key from controller handle 66,267 and pull handle back to brake position and then push it forward to the stop, which is its neutral position. Have the driver's seat locked in forward running position and then the connecting rod 66,706 may be adjusted to such a length that the handle 66,267 and the controller arm fingers 9,513 will be in their respective neutral positions at the same time. After the above adjustments have been correctly made, the forward driver's seat should be turned to the position it will assume when car is to be operated from the rear seat and the length of the connection rod 66,750 adjusted to such a length that both controller arm fingers 9,513 and the rear controller handle 66,261 will be in their respective neutral positions at the same time. When these adjustments are correctly made the front driver's seat will turn freely from forward driving position to rear driving position at the time that both controller handles 66,267 and 66,261 are in their neutral positions. Adjust motor brake shoes for wear by means of the winged nut 14,350. Clearance of shoe is obtained by the adjusting screw 14,271. These adjustments should be such that the brake is perfectly free when controller arm fingers 9,513 are in their neutral position, as shown in cut. When brake is applied the top finger 9,513 will have traveled upward across the contact plate, 9,525-B, and just to the plate 9,529. The wires leading from the controlling resistance 18,870 are marked to correspond to the connectors on the side of the controller into which they are connected.

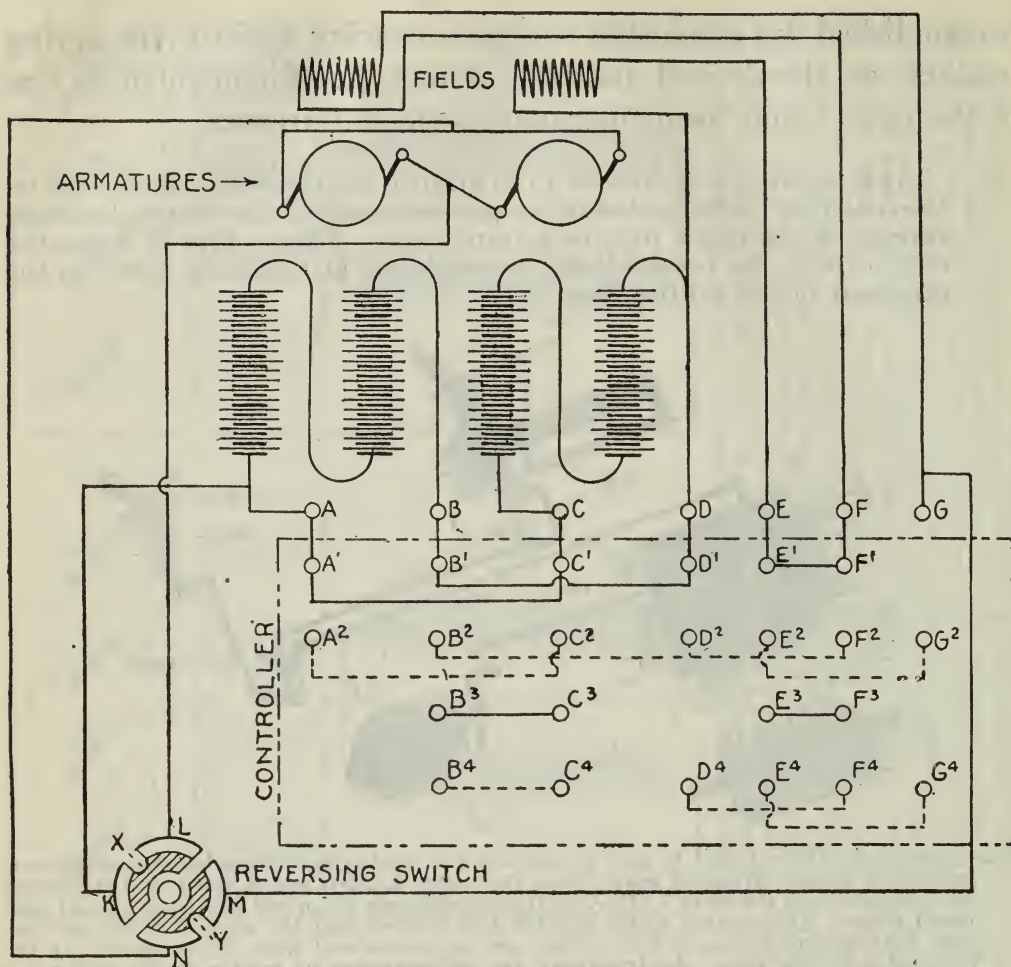
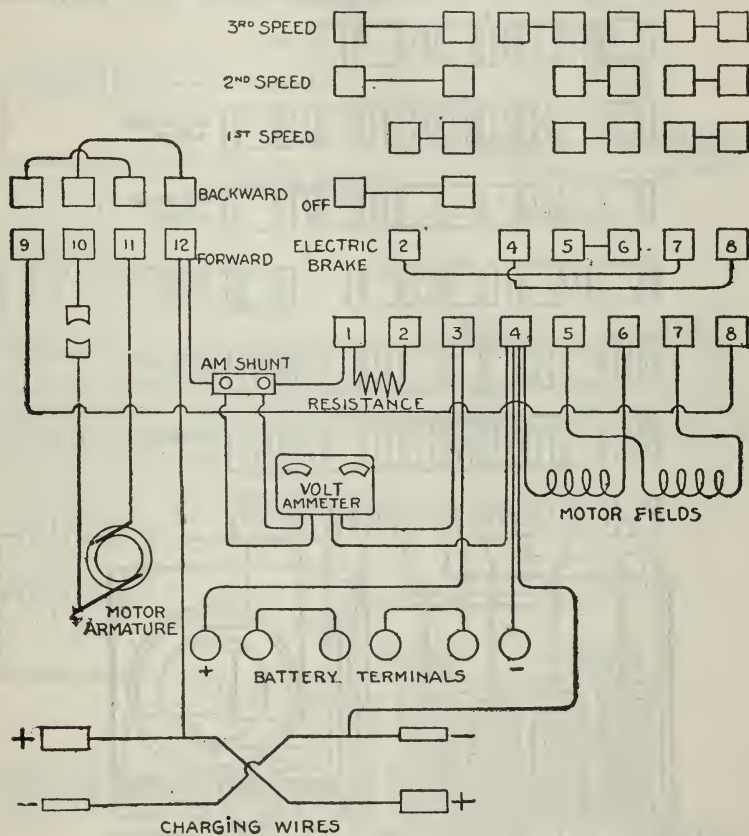


FIG. 4,096.—Diagram plan of the several parts of an electric vehicle driving circuit. The field windings and armatures are shown projected, the proper wiring connections being indicated. The periphery of the controller is laid out within the broken line rectangle, the contacts and connections through it for varying the circuits through four speeds being shown. **For first speed** the controller is rotated so that the row of terminal points, A, B, C, D, E, F, G, are brought into electrical contact with the row of terminal points, on the controller, A', B', C', D', E', F', G'; this connects the two unit battery in parallel and the field windings of the two motors in series. A further movement of the controller, bringing the points, A, B, C, etc., into contact with A<sup>2</sup>, B<sup>2</sup>, C<sup>2</sup>, etc., **gives second speed**, the batteries now being in parallel and the fields in series parallel. **For third speed**, the points B and C are brought into contact with B<sup>3</sup> and C<sup>3</sup>, and E and F with E<sup>3</sup> and F<sup>3</sup>, which means that the batteries are connected in series, and the fields in series. Similarly, for fourth speed, the points B and C are brought into contact with B<sup>4</sup> and C<sup>4</sup>, and D, E, F, G, with D<sup>4</sup>, E<sup>4</sup>, F<sup>4</sup>, G<sup>4</sup>, which means that the batteries are in series and the fields in parallel. The connections between the battery, the armature brushes, and the motor fields, are made as indicated through the rotary reversing switch by the terminals, K, L, M, N. The switch may effect the reversal of the motors by giving a quarter turn to its spindle, which means that the contacts of segment X, will be shifted from L and K to K and N, and the contacts of segment Y, shifted from M and N to L and M, thus reversing the direction of the current.



**Electric Vehicle Circuits.**—The methods employed to vary the speed and power output of an electric vehicle motor consist briefly in such variation of the electric circuits as will modify the pressure of the batteries on the one hand, and the operative efficiency of the motors on the other.



**FIG. 4,097.**—Diagram of controller connections of a one unit, one motor circuit, with variable fields.

The cells comprising the storage battery are so arranged as to form a number of unit, being so wired that by the use of a form of switch known as a controller, the connections may be varied from series to parallel, or the reverse, as desired. The same arrangement for varying the circuit connections is used for the field windings.

The wiring diagrams, figs. 4,091 to 4,093, show one arrangement. The dotted lines on each figure indicate the circuits that are cut out or open, and the full lines those that are active or closed.

**Ques.** How may the circuits be arranged with two batteries and two motors?

**Ans.** For this combination, as shown in figs. 4,102 to 4,104, it is possible to eliminate the resistance coil altogether and depend entirely upon the circuit shifting for regulating the

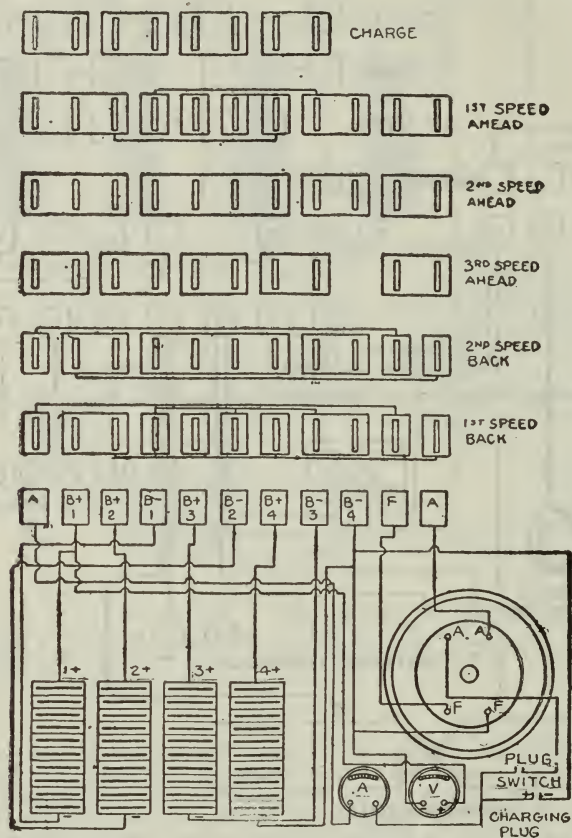
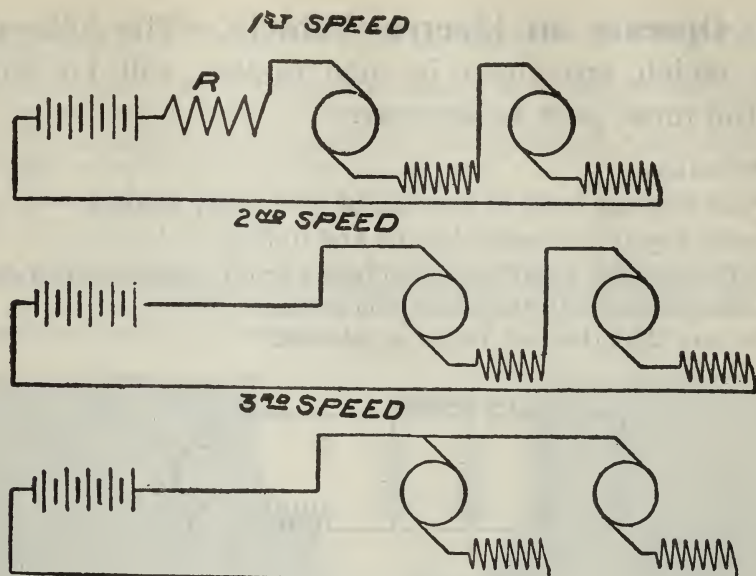


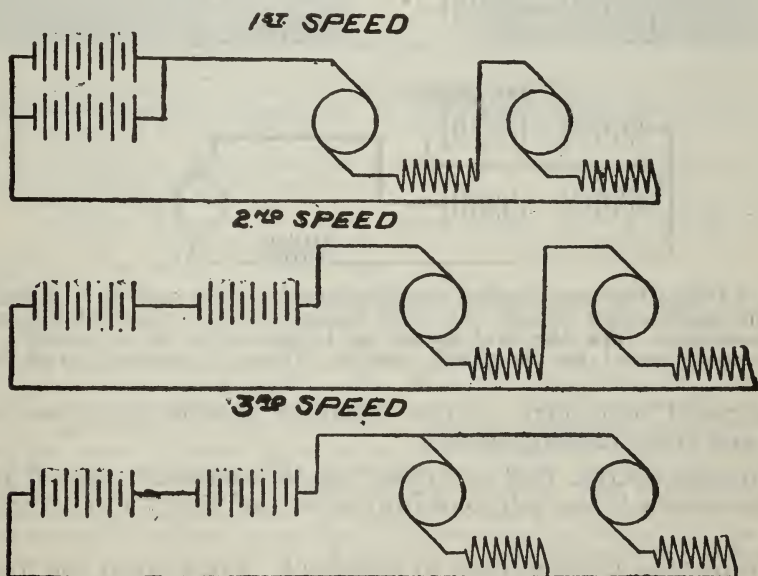
FIG. 4,098.—Diagram of controller connections of a four unit one motor circuit, with constant series connections for fields and armatures in forward and backward speeds.

voltage and power. Accordingly, *for the first speed* the batteries are connected in parallel, and the armatures and windings of the two motors in series. *For the second speed*, the series connections are adopted for both batteries and motors, while *for the third speed* the batteries are in series, with the motors in parallel.





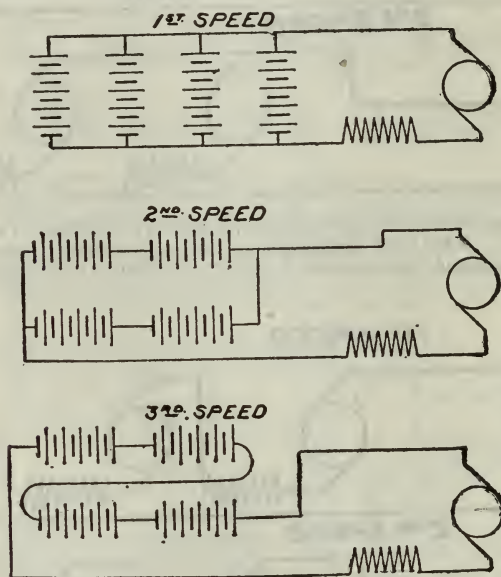
FIGS. 4,099 to 4,101.—Diagrams showing methods of speed changing in a typical one battery unit, two motor circuit. *The first speed* shows the two motors in series, with a resistance coil interposed; *the second*, the motors in series, without the resistance; *the third*, the motors in parallel.



FIGS. 4,102 to 4,104.—Diagram showing methods of speed changing in a two battery unit, two motor circuit, showing combinations for three speeds. *The first speed* is obtained with the battery units in parallel, and the motors in series; *the second*, with the battery units in series and the motors in series; *the third*, with the battery units in series and the motors in parallel.

**How to Operate an Electric Vehicle.**—The following instructions, which are given by one maker, will be found to apply for the most part to any car.

1. Be seated.
2. Place steering lever in position to give ready control.
3. Insert key in controller handle and unlock.
4. Pull controller handle back to brake or off position and raise slide.  
(This closes the circuit and electric is ready to move.)
5. Be sure that the foot brake is released.



FIGS. 4,105 to 4,107.—Diagrams showing combinations for three speeds in a typical four battery unit, single motor circuit. The only changes made in these circuits are in the battery connections. **For the first speed** the battery units are in parallel **for the second**, in series parallel, **for the third**, in series. The motor connections are not varied.

6. Forward movement of the controller handle gives two starting speeds and three running speeds.

7. To stop electric, pull controller handle backward past off position. First the electric brake will come into action and then a mechanical motor brake.

8. To reverse, bring electric to standstill. Press down the foot lever. Move controller handle forward same as when running forward. Two starting and one running speed will be obtained when backing.

9. To stop reversing, pull controller handle to extreme backward position. Take foot off reverse lever, which will automatically return



to forward position and electric is ready to be operated in a forward direction.

10. Steering: Push steering arm from you to turn to the left and pull steering arm toward you to turn to the right.

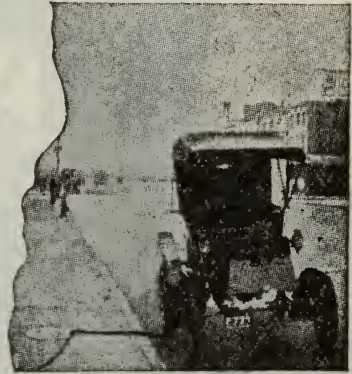
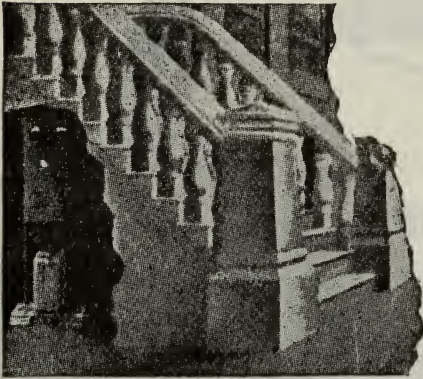
11. When leaving the electric, be sure to always force down slide of controller handle and take key out of lock.

12. Release foot brake before applying power.

13. To charge batteries:

*a.* Be sure that slide of controller handle is down and key out of lock.

*b.* Insert charging plug in socket at rear of electric and if the connections from the plug to the charging source be correct the ammeter should show reading below the zero on the scale.



FIGS. 4,108 and 4,109.—Charging an electric in front of city residence; fig. 4,108 shows mercury rectifier located in basement under steps. With this arrangement the car may be charged at the curb during idle hours of the day.

*c.* Follow the instructions for charging and care of battery that are furnished by the manufacturers of the battery.

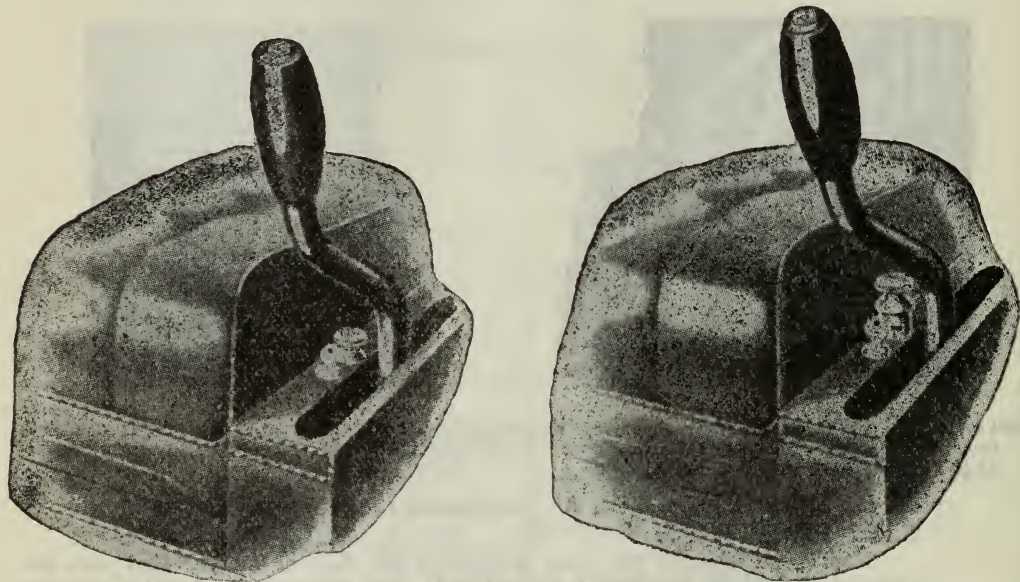
NOTE.—There are two push buttons in the floor of the car that may be operated by a slight pressure of the left foot. One increases the speed of the car and the other lights the meter lamp.

NOTE.—**Baker R and L motor and control.** The motor is designed to receive the combined voltage of all the cells in the battery, *i. e.*, the battery is at all times in series and as the voltage is 2 volts per cell, the running voltage of the models equipped with 41 cells would be 82 volts and on those models having 42 cells the voltage would be 84 volts. The object of this is to eliminate the usual troubles caused by all unbalanced conditions of the battery as when several sections are operated in parallel. **The first speed** includes a high resistance and is intended for starting duty alone. **The second speed** has less resistance and although intended to grade the starting is convenient for occasional use in congested districts, but too slow for ordinary running. **The next stop** cuts out all the resistance and the motor runs on the series fields alone, the two sections being in series. **The next or fourth speed** parallels the two sections of series field. **On the fifth speed** the series fields are in parallel with an external shunt resistance across them. This weakens the strength of the series fields and reduces the resistance of the circuit. **The sixth or highest speed** of the car is obtained by means of an **accelerator button** located in the floor of the car. Its action is that of a switch closing the circuit of a light shunt field on the motor. The direction of the flow of current in this field is such that its strength opposes that of a series, thus weakening it and producing an increase of speed on light running; but due to the differential action between the two, a very great dropping off in speed occurs when climbing a grade or traveling a heavy road. In this manner great driving power and low current consumption is obtained on the grades on the high speed.

**Electric Vehicle Troubles.**—In order to properly cope with the numerous disorders and mishaps likely to be encountered, the following points relating to troubles may be found helpful.

1. If vehicle run too slow, look for the following:

- a. Deflated tires.
- b. Slow tires, due to other makes having been substituted for those furnished by the manufacturer of the vehicle.
- c. Broken bearings in wheels, countershaft or motor.
- d. Shoes not making perfect contact on face of controller.



FIGS. 4,110 and 4,111 Broc control lever lock. Fig. 4,110, locked, safety plunger pushed down; fig. 4,111, ready to operate safety plunger raised. **To unlock**, insert and turn the key, move control lever back to power off position, and pull up safety plunger.

- e. Brushes not making perfect contact on commutator due to being too short, or commutator being dirty.
- f. Broken battery jar, solution having partly leaked out.
- g. Brakes rubbing when they are supposed to be thrown off.
- h. Battery exhausted.

2. If the current be higher than usual when running on the level, look for the following:

- a. Tight bearings.
- b. Brakes rubbing.
- c. Silent chains too tight.
- d. Front wheels out of alignment.
- e. Tires deflated.



3. If needle on ammeter vibrate more than usual, moving up and down very rapidly, look for the following:

- a.* Blackened commutator.
- b.* Commutator brushes worn too short.
- c.* Loose connections at battery terminals or at connections on controller.
- d.* Broken wire leading to meter.

4. If vehicle refuse to run, look for the following:

- a.* Broken jar in battery.
- b.* Broken connections between cells.

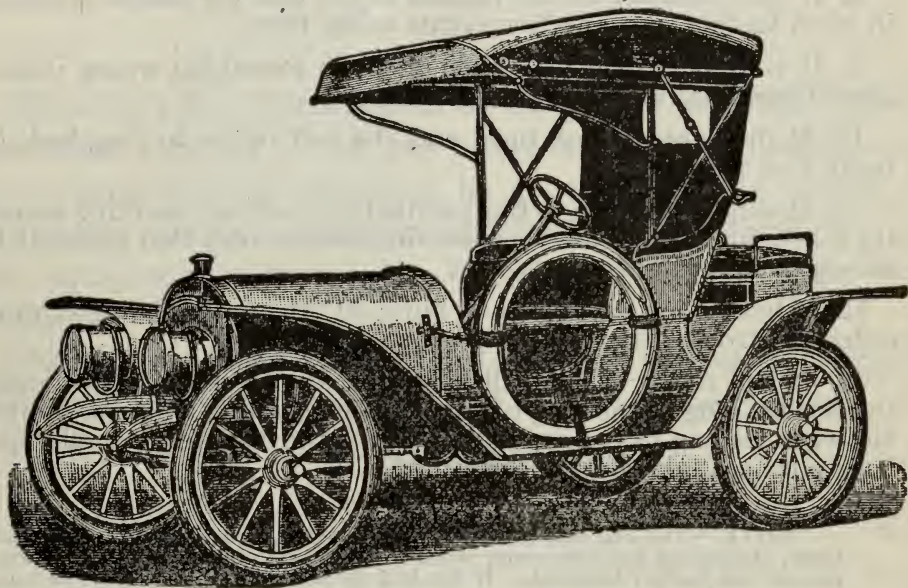


FIG. 4,112.—The Babcock electric roadster. This car is provided with a battery of forty two cells, which it is claimed, gives one hundred miles at seventeen miles per hour on one charge. The controller provides for five speeds forward and two reverse. The motor develops fifteen horse power, which will run the car over thirty miles per hour.

- c.* Broken terminals.
- d.* Open motor leads.
- e.* Broken connections on any part of vehicle.

5. In case vehicle do not run on any of the speeds, first examine those connections that are easiest to get at, viz:

- a.* Those at the end of the batteries.
- b.* The connecting straps, connecting one cell to another.
- c.* The wires going into the circuit closing switch.
- d.* The springs on the controller arm and the copper shoes. Be sure that they make contact with plates on the controller face.
- e.* See that there are no wires hanging loose, that appear to belong in the controller.
- f.* If the trouble be not found in some one of these points, it would be best to have an expert examine the machine.

6. If the usual graduation of speed be not obtained when running on the level, read carefully the instructions of maker relating to controller.

7. If ammeter on the vehicle do not register properly, look for the following:

- a. Broken or partly broken connections in the wire leading from meter to shunt block, under floor of carriage.
- b. The ammeter pointer sticking or working irregularly, due to dirt inside of ammeter, in which case it must go to the factory.

8. If the voltmeter do not register at all, look for broken connections in wires leading to connection points under floor.

9. If voltmeter read too high, there is something wrong inside; it should immediately be sent to the factory.

10. If the lights do not burn and the bell refuse to ring, look for a burnt fuse wire.

11. If one light refuse to burn while the others are working correctly, try a new lamp, or examine connecting theater plug that connects body wiring to chassis wiring.

12. If both side lights refuse to burn, all other lamps being in working order, the trouble is in the connector.

13. If bell refuse to ring, all lamps being in working order, examine the theater plug connecting body and chassis wiring and make sure that the wires leading to the switch contacts at bottom of controller handle have not been taken out or broken off.

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NOTE.—The bell can be tested by disconnecting from it the wires that are there, connecting two temporary wires to these same binding posts and touching these to the battery terminals. If the bell do not ring then it should be taken off and replaced with a new one or readjusted.

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NOTE.—No meter on an electric vehicle is infallible as the service is very hard and the adjustments liable to get loose; and, as the general instructions as to care of battery, especially in charging, are to charge until voltage reads a certain amount, it is of the highest importance that the meter should read correctly. As soon as any irregularities are noticed in its readings, have it examined immediately by an expert, or send it to the factory. When it is necessary to return it to the factory, be sure to send the shunt block with it, as this is part of the meter. Even if no irregularities be noticed it would be well to have the meter examined at the factory and recalibrated once every year.



## CHAPTER LXXVIII

# ELECTRIC ELEVATORS

Electricity has been found to be a very desirable power for operating elevators, and has some inherent advantages which has caused electric elevators to grow rapidly in public favor. Ordinarily electricity is easily obtained, and the flexibility of electric equipment allows it to be installed where little room is available.

There are numerous kinds of electric elevator to meet the various conditions of service, and they may be classed:

1. With respect to the current, as

- a.* Direct;
- b.* Alternating.

2. With respect to service, as

- a.* Passenger;
- b.* Freight.

3. With respect to the transmission, as

- a.* Drawn;
- b.* **Traction.**

4. With respect to the control, as

- |                            |                        |
|----------------------------|------------------------|
| <i>a.</i> Non-reversible;  | <i>f.</i> Full magnet; |
| <i>b.</i> Reversible;      | <i>g.</i> Push button; |
| <i>c.</i> Mechanical;      | <i>h.</i> One speed;   |
| <i>d.</i> Semi-mechanical; | <i>i.</i> Two speed,   |
| <i>e.</i> Semi-magnet;     |                        |

5. With respect to the location of the power unit, as
  - a. Over mounted (overhead);
  - b. Under mounted (basement).
6. With respect to the velocity ratio between motor and car, as
  - a. Direct drive;
  - b. 2:1 reduction;
  - c. Multi-reduction.
7. With respect to the transmission as
  - a. Belt driven;
  - b. Direct connected.
8. With respect to balancing the load, as
  - a. Counter-balanced;
  - b. Compensated.

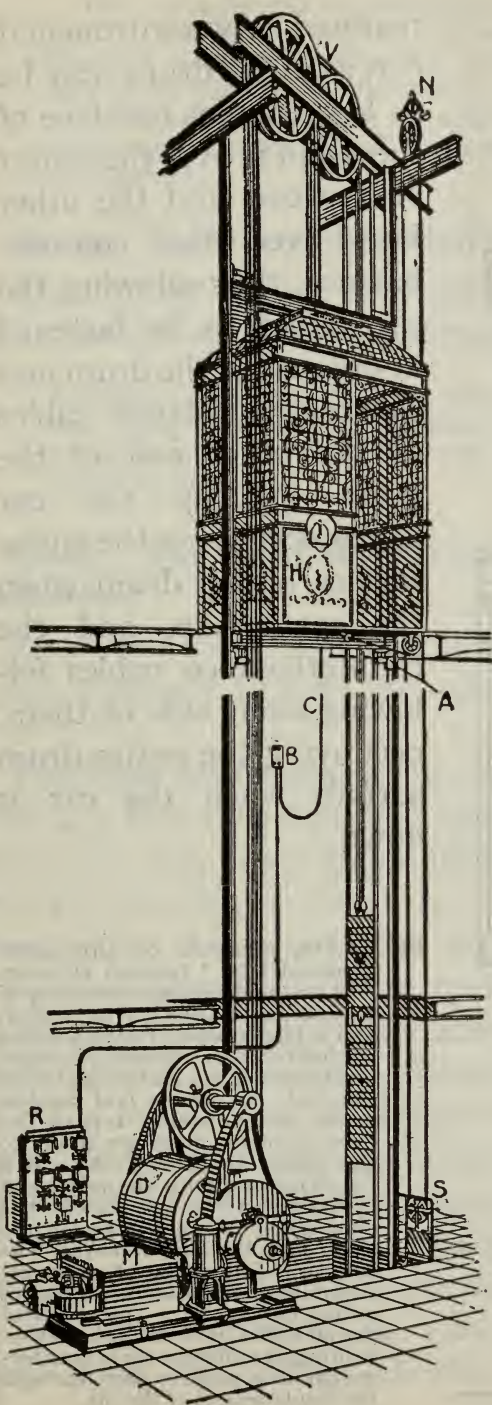
After describing the essential features of drum and traction elevators, the numerous devices comprising the mechanism, many common to both systems, will be treated in detail.

**Drum Elevators.**—The term “drum” applies to all elevators in which the cables leading from the car are **both fastened to and wound upon** a drum. The essential features consist of a drum operated through gearing, and to which is attached the cables which support the car.

Power, when applied to the driving gear, turning it in one direction, winds the cables upon the drum and causes the car to ascend, and when the power is reversed, the drum turns in the opposite direction, paying out the cables, and causing the car to descend.

The weight of the car is balanced by a counterweight, thus reducing the energy to be expended in operating the car. Automatic devices, to be described later, are used to insure the proper and safe control of the movements of the car.





**Ques.** How is the counter balance usually proportioned for drum elevators?

**Ans.** It is made heavy enough to balance the car with its average load.

**Ques.** Why?

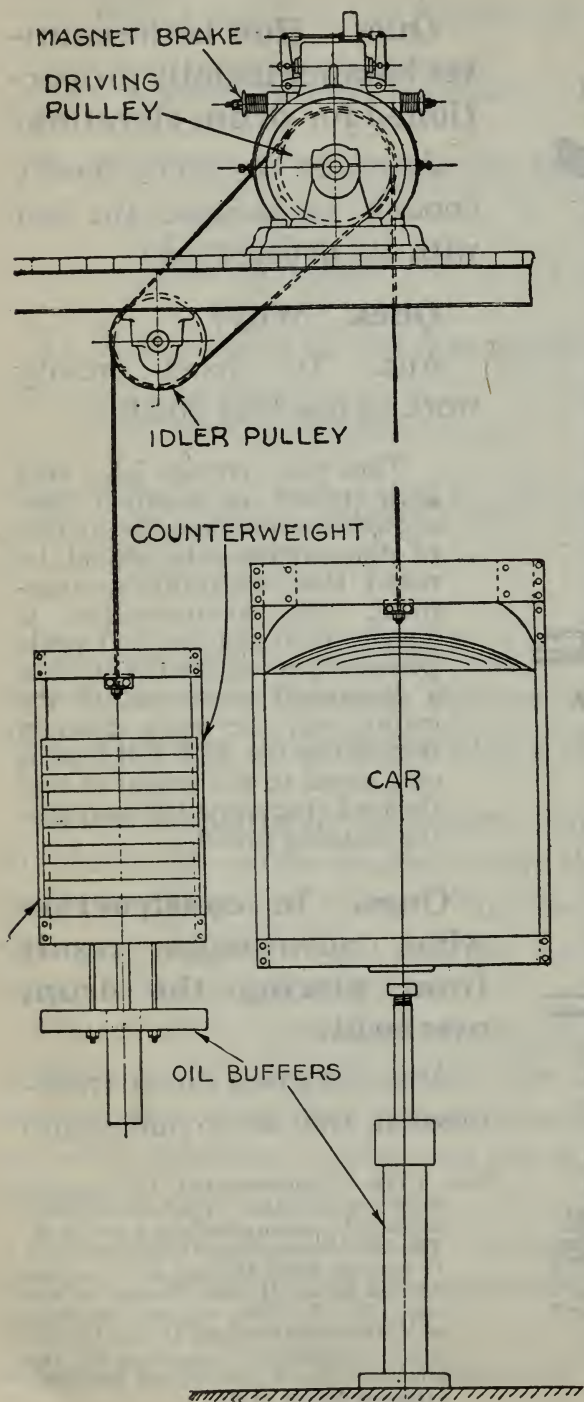
**Ans.** To avoid gravity work as much as possible.

Thus with average load, very little power is required—just enough to overcome the friction of the system. It should be noted that with this arrangement, the counterweight is heavier than the car, and while power will be required to produce a downward movement of the empty car, the work done in raising the car with full load is only equal to the weight of half the load (including friction) plus the distance raised.

**Ques.** In construction what advantages result from placing the drum overhead?

**Ans.** It gives direct transmission, that is, no pulleys are

**FIG. 4,113.**—Undermounted full magnet drum type elevator. The hoisting drum is driven by worm gear from a motor M. The flexible conductors being shown at C running from the car H to a connection block B, and thence to the controller R. The overhead sheaves at V, the counterweight U, and the car safety equipment consisting of the governor N, the idler S, and the guide gripping device at A.



required between drum and car, also the drum may be so located that one face of the drum is over the center of the car, and the other face over the counterbalance, thus allowing the car cables to be fastened at one end of the drum and the counterbalance cables at the other end of the drum grooves, the car cables occupying the entire surface of the drum when the car is up, and the counterbalance cables following along side of them, occupying the entire drum surface when the car is down.

FIG. 4,114.—Diagram of Otis over-mounted 1 to 1 traction elevator. The machine consists essentially of a motor, a traction driving pulley, and a magnetically released spring applied to brake, compactly grouped and mounted on a continuous heavy iron bed. The motor is of the slow speed shunt wound type. The drive from the armature spider to the pulley is effected through a flange integral with the spider and bolted directly to the pulley, thus eliminating torsional strains on the shaft and the use of keys. The control is full magnet, that is, the controller is actuated by a master switch in the car. The object of the oil buffer, is to act as a cushion in bringing either the car or counterweight to a positive stop through the displacement of the oil.



The arrangement of placing the machine or "engine" as it is called, that is, the power unit in the top of the elevator shaft, is peculiarly adapted to electric elevators, when the power is easily conveyed by electric conductors to the motor. The drum machine, whether over or under mounted is nearly always overbalanced as the saving in gravity work compensates for all friction and any extra first cost that might be received.

**Ques. State an objection to drum elevators.**

Ans. There is lack of absolute means of stopping the drum when the car or counterbalance gets to the top of the shaft.

Automatic safety devices are provided to shut off the power and apply the brake when the car is near its limit of travel. These devices are adjustable, can be removed, and may get out of order when neglected by those in charge.

**Ques. For what service are drum elevators not suited, and why?**

Ans. For very high lifts, because of the very large size of drum necessary to take the cables.

**Traction Elevators.**—This type of elevator derives its name from the fact that motion is obtained by means of the *traction*; that is to say, the friction existing between the driving pulley and the hoisting cables. In order to produce the necessary tension for this result, the hoisting cables, from one end of which is suspended the car, and at the other end, the counterweight, pass twice partially around the driving drum and only once around the idler, although frequently, before leading into the shaft, they are deflected by the idler in order to lead them plumb over the counterweight. This accounts for the necessity of having the same number of groove on each drum.

It should be noted that the grooves are straight for traction elevators and spiral for drum elevators.

The term "gearless" is sometimes ill advisedly applied to some form of traction elevator, meaning that the power is

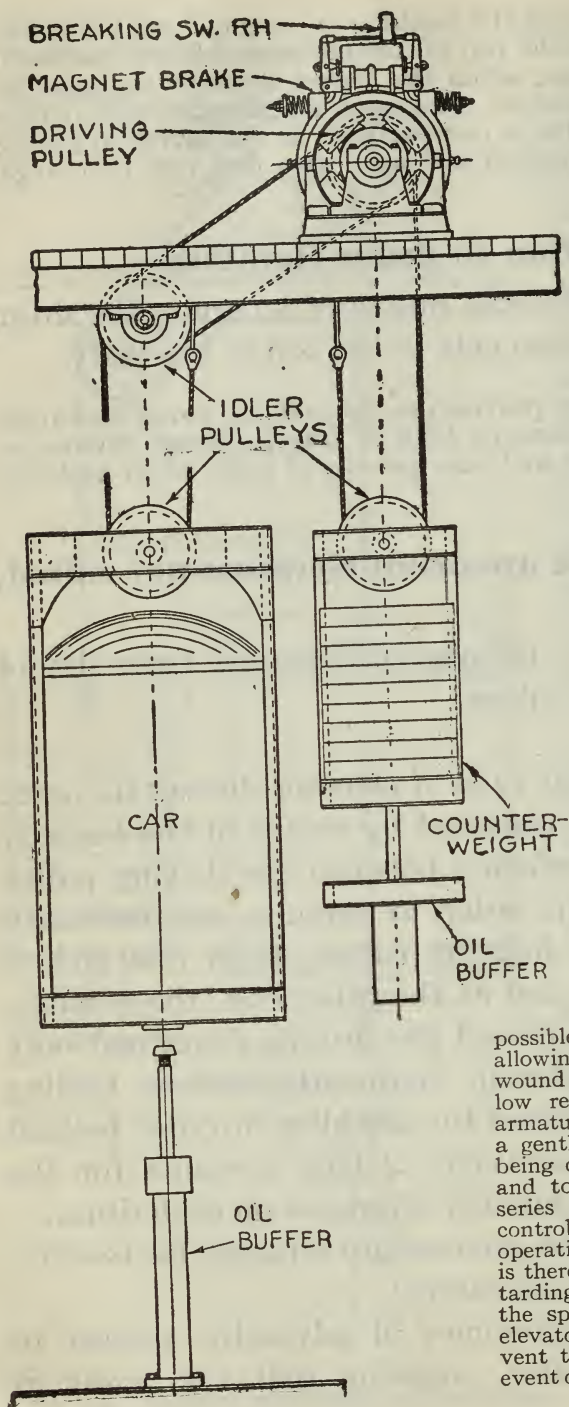


FIG. 4,115.—Diagram of Otis, over-mounted 2 to 1 traction elevator. This machine is similar in appearance to the standard drum machine, except that a multi-grooved driving pulley is mounted in place of the drum, and a non-vibrating idler leading pulley takes the place of the vibrating pulley necessary on the drum type. The car and the counter-balance weight hang directly from the driving pulley, one from either end of the cables in precisely the same manner as with the 1 to 1 drive, the necessary amount of traction being obtained by the extra turn of the cables resulting from passing around the idler pulley. The machine is equipped with a mechanically applied and electrically released double shoe brake. The shoes are applied against a pulley of ample diameter and width to dissipate any heat generated, which also serves as a coupling between the motor shaft and the worm shaft. The brake shoes, normally, are bearing against the pulley with a pressure corresponding to the compression of the two helical springs. When current is admitted to the solenoid brake magnet, and then only, the action of the springs for the time is overcome, so that the shoes are released. It will be seen, therefore, that the brake will apply with full force should a failure of current occur, resulting in an immediate stop of the elevator. The motor is compound wound and runs usually at about eight hundred revolutions per minute at full car speed and load. The series field is used only at starting to obtain a highly saturated field in the shortest possible time, and this is then short circuited, allowing the motor to run as a plain shunt wound type. In stopping, a comparatively low resistance field is thrown across the armature, providing a dynamic brake action and a gentle slowing down of the car, the brake being called upon only to effect the final stop and to hold the load at rest. Resistance in series with this *extra field* as it is called, is controlled by magnets which depend in their operation on the speed of the armature. It is therefore evident that the dynamic or retarding effect of the field is proportional to the speed; and therefore to the load in the elevator. Rope guards are provided to prevent the cables leaving their grooves in the event of either car or counterweight bottoming.

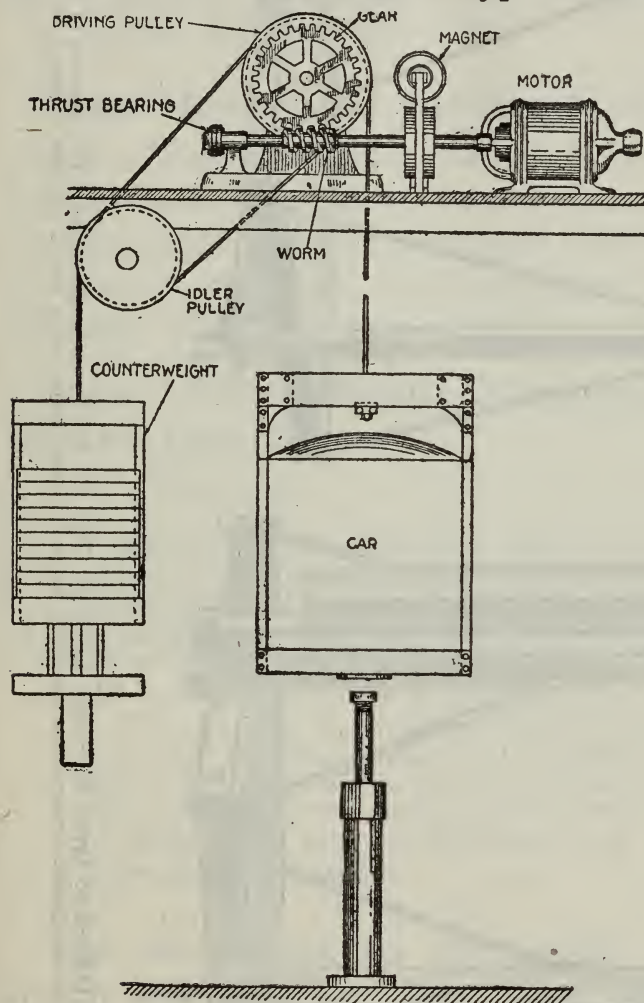


transmitted to the car without toothed gears; it is in fact, transmitted through cables and pulleys which is in fact a form of gear.

There are two forms of the so called gearless traction elevators: the 1 to 1 or direct drive type shown in fig. 4,114 and the

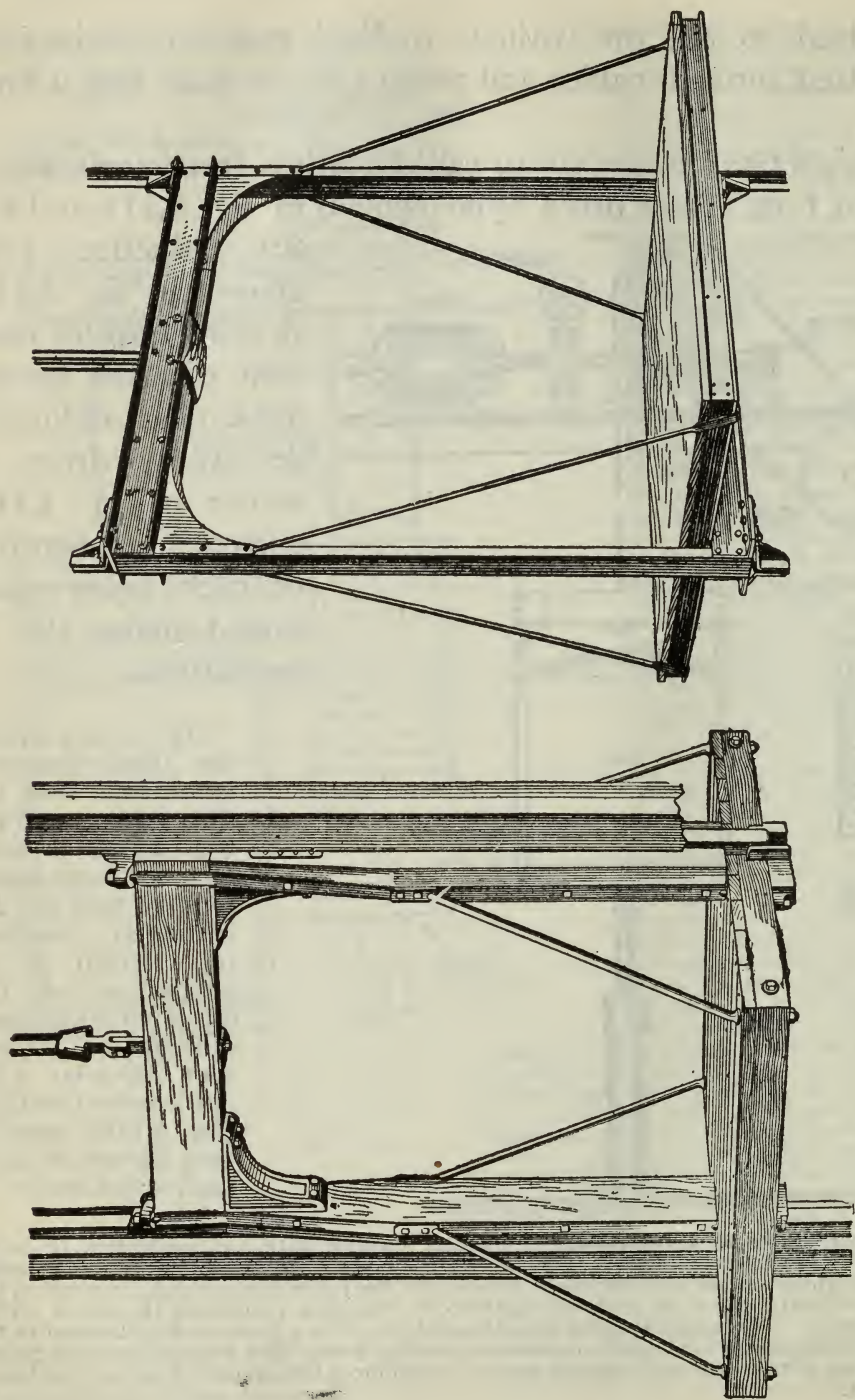
2:1 reduction type shown in fig. 4,115.

A third form of traction elevator known as a multi-reduction or worm drive is shown in fig. 4,116, the essential features of each being mentioned under the illustrations.



By comparing the three figures it is obvious that the direct drive machine (fig. 4,114) is suitable for high speed service; that the 2:1 reduction machine (fig. 4,115) is an adaptation of the direct drive type permitting of slower car speeds; the multi-reduction type (fig. 4,116), permitting the use of small high speed motor.

FIG. 4,116.—Diagram of an overmounted traction elevator with multi-reduction or worm drive. The traction feature is identical with fig. 4,115. Attached to the driving pulley is a gear which meshes with the worm underneath, the latter being direct connected to the motor. Clearly, the worm gives a large velocity reduction permitting the use of a high speed motor. The magnetic brake being located to act on a brake pulley attached to the fast revolving motor shaft gives considerable braking power light grip on the brake pulley. The action of the single worm gear is such as to require a thrust bearing, as later explained in detail.



FIGS. 4,117 and 4,118.—Two types of freight elevator. The all wood construction, fig. 4,117, because of fire risk, is not so desirable as the composite construction shown in fig. 4,118, the latter being made entirely of metal with exception of the floor boards.



The multi-reduction type of which fig. 4,116 shows one form permits the use of a small high speed motor for operating a slow or comparatively slow car. Because of the high velocity reduction ratio of the worm gear, it is self-locking, that is to say, although the worm and gear unit permits motion to be transmitted from the worm to the gear, no load that could be put on the car would be heavy enough to cause motion to be transmitted from the gear to the worm, thus no change of loading would cause the car to descend, and consequently no car locking device is required.

**Ques. State some advantages of traction elevators.**

**Ans.** The traction elevator may be used for lifts of any height, because it does not employ a winding drum whose size has to be considered; the compact and simple arrangement of parts permits of simplicity of installation and economy of space especially when over mounted.

**Ques. What difficulty is sometimes experienced with traction elevators?**

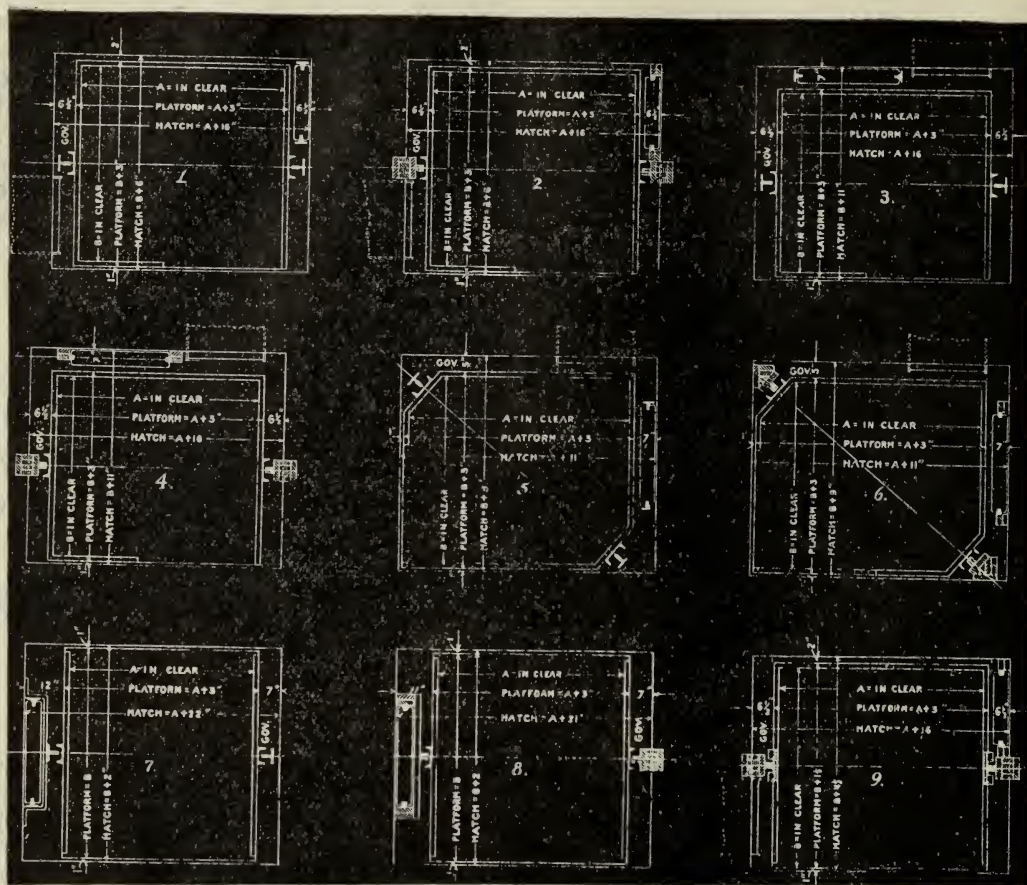
**Ans.** Slippage.

With all traction elevators, there is the danger of slippage of the cables on the driving drum, especially if the cables become greasy. This slippage is most noticeable when the operator endeavors to stop in descending with a heavy load, with the result that on high speed cars when attempting to make a quick stop, the car sometimes slides past the landing even to the extent of one or more stories.

The fact that the traction drive is not a positive drive is a safeguard for the reason that cable strains can never increase beyond a certain limit, well within the factor of safety of the cables and fastenings. This means that the danger of the car or weight dropping, as a result of being pulled into the overhead work, and thus breaking cables or fastenings, is eliminated.

**The Car.**—There are two general classes of elevator car: freight and passenger; these of course vary considerably in design.

Freight elevator cars are made of wood or iron, with iron braces and fixtures; their platforms are seldom enclosed, and their design is usually of the simplest nature. Cars intended for passenger service are enclosed by a cage of wood or iron—preferably of the latter material.



FIGS. 4,119 to 4,127.—Typical elevator car layouts as given by Warner Elevator Co., showing relative sizes of shaft and platform for both passenger and freight elevators, the width of entrance being the only difference. No. 1 side post, steel guides, machine and counterweight at side; No. 2 side post, wood guides, machine and counterweight at sides; No. 3 side post, steel guides, machine at back or overhead, counterweight at side; No. 4 side post, wood guides, machine back or overhead, counterweight at back; No. 5 corner post, steel guides, machine at back or overhead, counterweight at side; No. 6 corner post, wood guides, machine at back or overhead, counterweight at side; No. 7 side post, steel guides, machine overhead, weight at side; No. 8 side post, wood guides, machine overhead, weight at side; No. 9 side post, wood guides, machine and counterweight at sides. Layouts No. 1, 2 and 9 are to be preferred when machine is erected in basement. Layouts No. 3, 4, 7 and 8 are to be preferred with machine overhead. Height required above top floor when machine is placed in basement is 19 feet. Height required above top floor for overhead constructions is 23 feet. Pits must be made full size of shaft and should be 30 inches deep for speeds under 125 feet per minute, and 48 inches deep for greater speeds. Allow at least 7 feet by 11 feet for machine to permit free access to all parts.

NOTE.—In the construction of a freight elevator platform, oak timber can be recommended for all parts except head beam, which should be structural steel. In best work all joints are tenoned or bolted. Tension and brace rods effectually tie the frame together and prevent it getting out of shape. Structural brackets connect head beam with side pieces. Guide brackets at top and bottom of side frame have chilled faces which bear against hardwood guide strips. The platform is thus maintained in proper position and friction of guides reduced to a minimum.



In general, elevator cars should be constructed wholly of metal for safety in case of fire. Wrought iron grill work is largely employed for the sides and top of passenger cars, as it is not only fire proof but provides for ventilation and is ornamental in appearance, and at the same time substantial and of light weight.

In order to guide the car, two guide rails usually and preferably of iron are mounted vertically in the elevator shaft, and over these rails fit guide shoes that are fastened to the car. These guides are usually placed on opposite sides of the car, and in some instances at the diagonally opposite corners. In the former case the installation is said to be of the side post type, and in the latter case, of the corner post type.

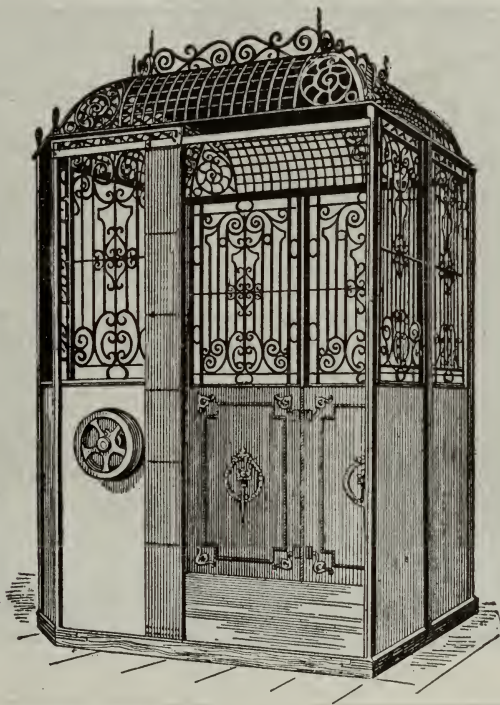


FIG. 4,128.—Typical modern passenger car. Wood or other combustible material is practically eliminated, and with the exception of the floor boards, the construction is all metal. Sheet metal is employed around the lower part and open metal grill work around the upper portion giving a well ventilated and light yet strong car.

Local conditions determine which type to adopt. The various details of car construction are shown in the accompanying cuts.

**The Shaft.**—The enclosure in which the elevator travels, called the shaft, and sometimes ill advisedly, the hatchway, should be enclosed with iron lattice work or grill work.

The walls should not be solid, because the solid enclosure acts as a chimney, in case of fire causing the fire to work upward from floor to floor, rendering escape by elevator impossible. A better lighted and ventilated shaft is also obtained with openwork construction of the shaft and of the doors or gates opening into it.

That portion of the shaft enclosure at each floor should be carried the full height of the opening between floor and ceiling in order to reduce the possibility of accident. When grill work is used for this portion of the enclosure, there should not be more space than one and one-half inches between the adjacent parts of the grill work to prevent objects being thrust through. Throughout the interior of the shaft there should be no projections.

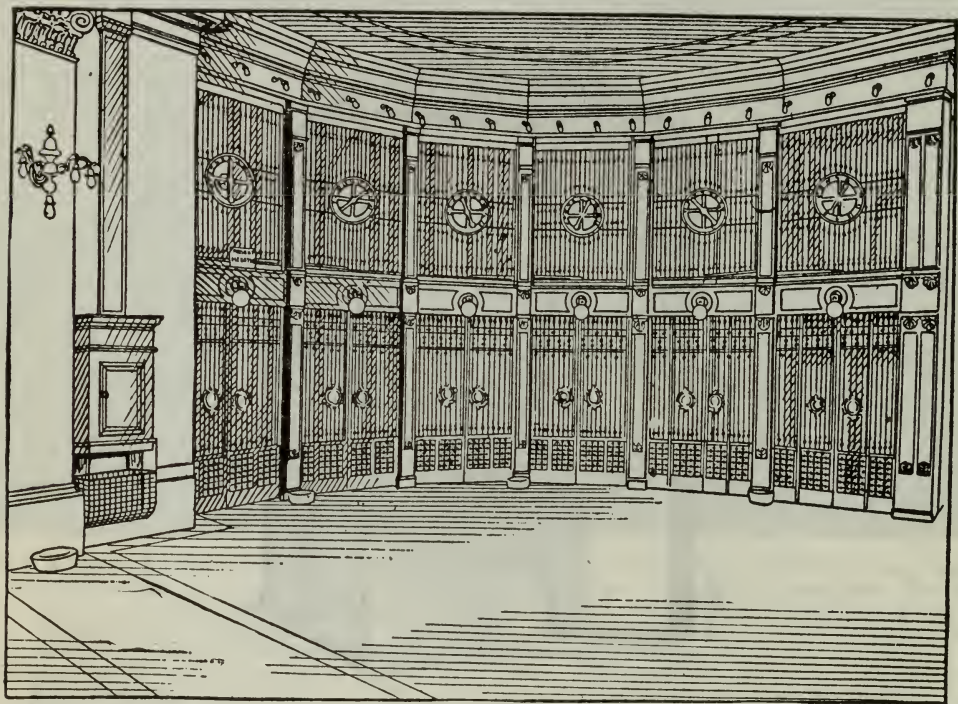


FIG. 4,129.—Semi-circular multi-shaft open iron work. With this grouping of the entrance to cars, the doors of all the cars can then readily be seen by a person entering the hall, and he can therefore ascertain at once which car to enter. This arrangement, however, should not be carried beyond the limits of a semi-circle, as the cars located in the extension are liable to be overlooked, and the efficiency of the system as a whole thus diminished.

In buildings where more than one elevator is installed, it is advisable to enclose each elevator shaft separately and have the stairways cut off from the elevator hallways. While this construction is not usually followed, the reduction in the fire risk that is otherwise present and the elimination of noises caused by the opening and closing of the elevator doors, commend it where the additional expense entailed is not prohibitive.



All doors and gates leading to the shaft at the various floors must be substantially made and locked or bolted on the shaft side so as to be opened only by the operator in the car.

When the car is at the lowest landing, it should rest on spiral springs called bumpers, or on oil bumpers, so as to relieve the tension on the hoisting cables. These bumpers interpose a yielding resistance to the car when settling to rest and thus often prevent severe shocks or jars. Below the lowest landing it is well to have the shaft constructed air tight as far as its walls are concerned, so that it will act as an air cushion in case a car fall into it and thus gradually bring the car to a stop.

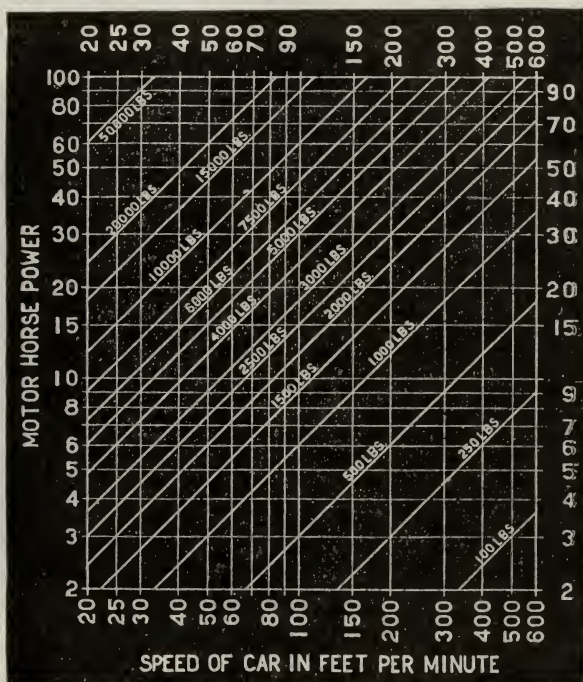


FIG. 4,130.—Elevator motor horse power diagram. Three factors determine the horse power of the motor that should be used, namely, the weight to be hoisted, the speed of travel and the efficiency of the elevator. In the diagram, the efficiency of the elevator is assumed to be 50 per cent. To determine the proper size motor to use in any case follow the diagonal line corresponding to the unbalanced load up to the point where it crosses the vertical line corresponding to the speed desired. The horizontal line at this point will indicate the horse power of motor required.

**Motors for Electric Elevators.**—In estimating the horse power required for an elevator motor, the load, speed and efficiency of the system must be considered. Since it is customary to counterbalance the weight of the car and part of the load this must be taken into account, that is, only the unbalanced

load is considered. Accordingly the horse power required may be obtained from the following formula:

$$\text{Horse power} = \frac{L \times S}{E \times 33,000}$$

in which

L = unbalanced load in pounds;

S = speed of elevator in feet per minute;

E = efficiency of the system generally taken at 50%.

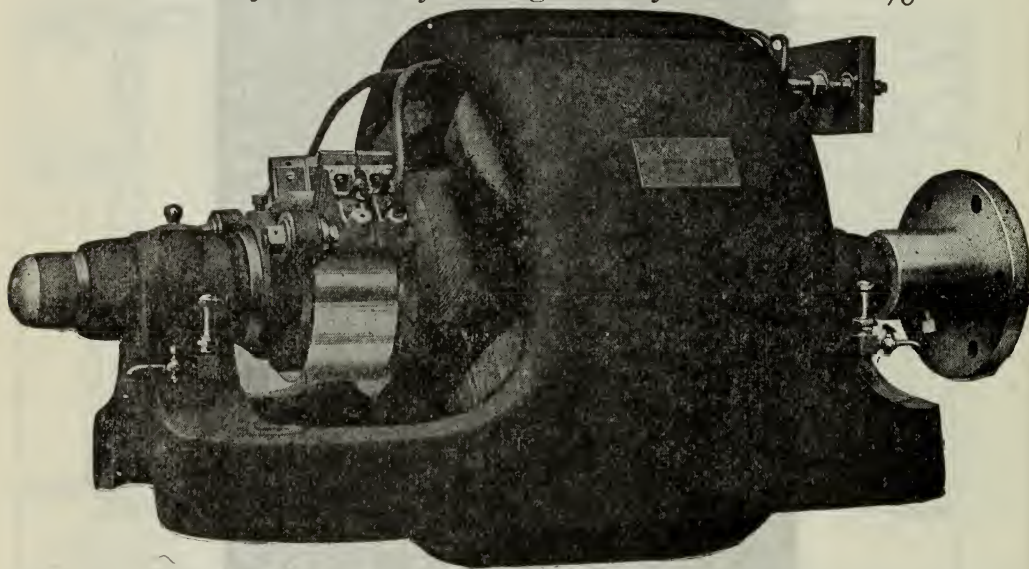


FIG. 4,131.—Warner direct current motor. It is compound wound, having heavy series field windings. The series windings are used for starting only, and are cut out of circuit as the motor attains its normal speed, in order to give the constant speed characteristic of the simple shunt motor. The standard motors up to 40 horse power are variable speed, and have a controllable range from 500 R.P.M. to 800 R.P.M. Another type of Warner direct current motor has interpoles; up to 30 horse power, the range is from 260 R.P.M. to 800 R.P.M., and 40 to 50 horse power the range is 200 R.P.M. to 600 R.P.M.

EXAMPLE.—What size motor will be required for an elevator to operate at a speed of 400 feet per minute with an unbalanced load of 2,000 lbs.?

Substituting the values in the formula,

$$\text{H. P.} = \frac{2,000 \times 400}{.5 \times 33,000} = 48$$

**Ques.** What kind of current is suitable for elevator motors?

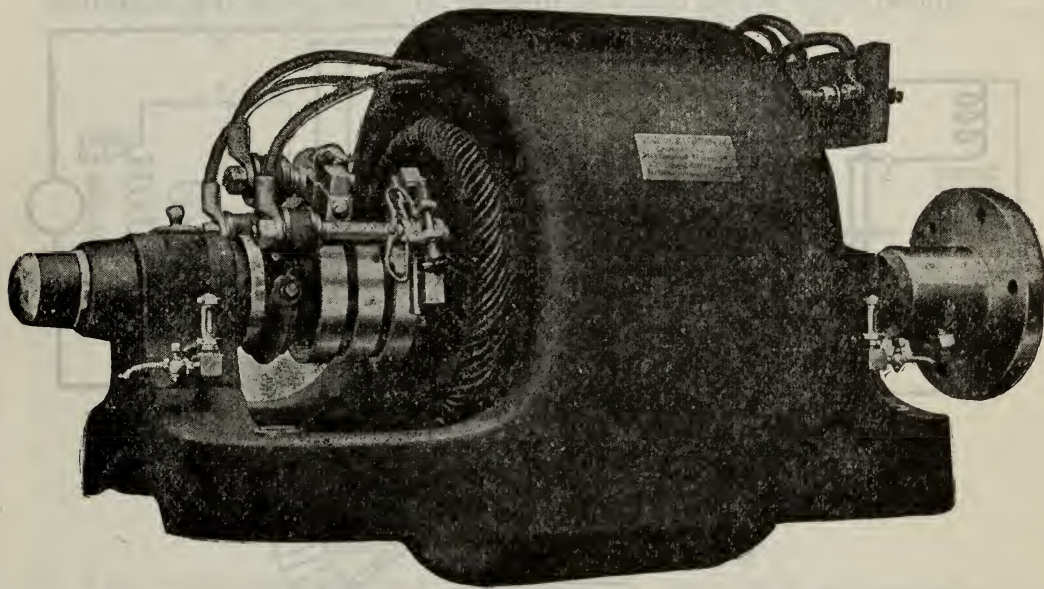
**Ans.** Either direct or alternating, preferably direct.



**Ques. Why?**

**Ans.** Principally, because of the high starting torque of the direct current motor.

The chief difficulty experienced with alternating current motors is this lack of ability to start under heavy loads, and for this reason proportionally larger sizes must be used, the increase in horse power required being fully 33 per cent.



**FIG. 4,132.**—Warner alternating current motor. It has a standard speed of 900 R.P.M. for 60 cycle circuits, and 750 R.P.M. for 25 cycle circuits, and is of the wound rotor, slip ring type. The slip ring type gives high torque with minimum starting current, and has practically a constant speed regardless of load. An interesting feature of the Warner motors is that the alternating and direct current motors are interchangeable. Thus, an elevator built for direct current can readily be changed to alternating current in cases of a change in power.

**Ques. Is the higher cost of the relatively larger size alternating current motor offset in any way?**

**Ans.** Besides giving a heavier starting torque, it furnishes an excess of power which enables the motor to run at full speed without such noticeable fluctuations with changes in load as would be the case with a smaller motor.

**Ques.** What type of direct current motor gives the best control?

**Ans.** The adjustable speed motor having a small percentage of compound winding.

The series winding is cut out by the controller at normal speed, but is necessary in starting, insuring a smooth quick start, besides being of value in the subsequent control of the motor.

About 10 to 15 per cent. series field winding give the best results. Where no speed control is provided by shunt field resistance, a compound wound motor is still desirable in order to obtain smooth acceleration.

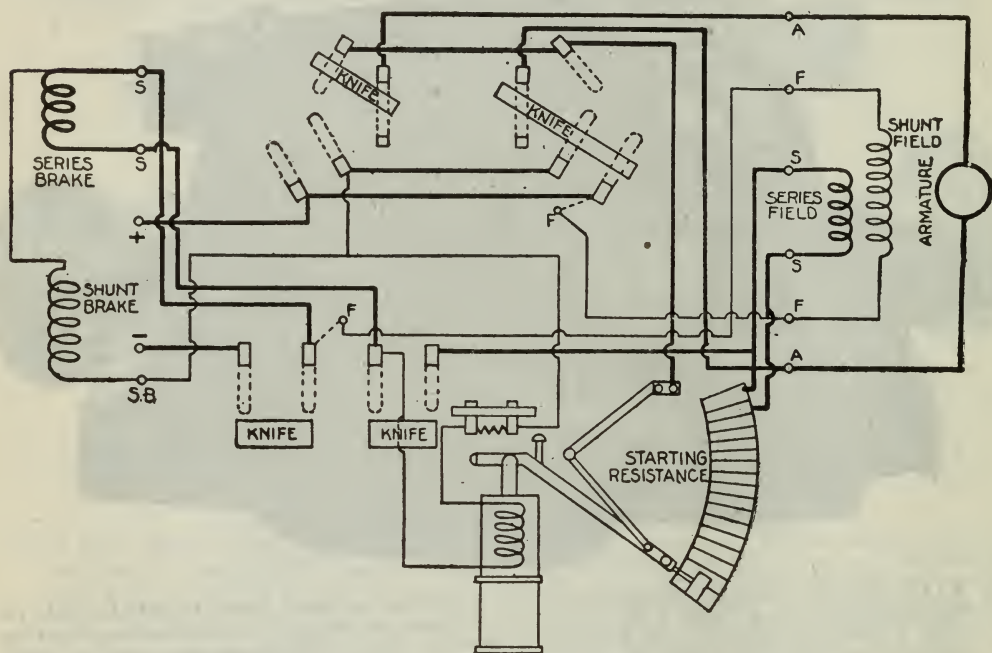


FIG. 4,133.—Diagram of A. B. See No. 4 mechanical controller.

**Ques.** For what service is the squirrel cage induction motor suited?

**Ans.** It should be used only for slow and constant speed freight elevators where the impairment of the line regulation, caused by the high starting currents, is not important.

The induction motor is being used more and more for driving elevators and while admirably adapted for some classes of elevator service, it



possesses certain definite limitations which should be taken into account when deciding on the type of motor to use.

It is not possible to vary the speed of the ordinary induction motor under all conditions of load, nor is it ever possible to employ with it the dynamic brake used with the direct current motor.

Accordingly, the use of alternating current motors is limited to slow speed elevators which may be slowed down and stopped by the mechanical brake alone.

Until such time as a variable speed alternating current motor is developed and placed on the market, the use of an induction motor with high speed passenger elevators should not be attempted. In addition, the high torque polyphase squirrel cage motor can be used where

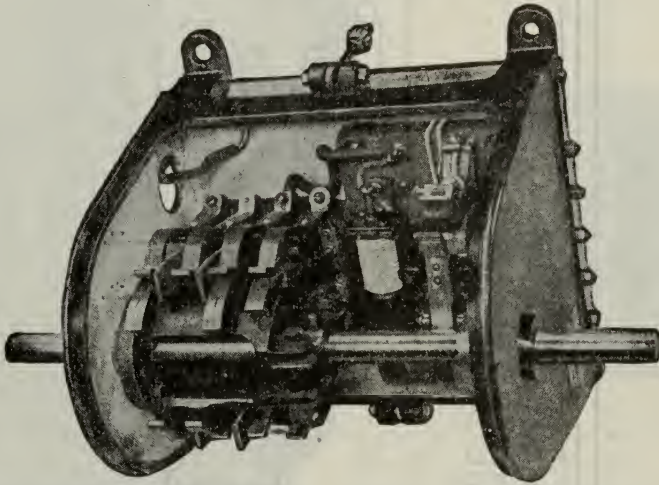


FIG. 4,134.—Cutler-Hammer direct current reversible single speed semi-mechanical controller for short lift sidewalk elevators. The equipment consists of a drum case containing the line and reverse switch and resistance switch, with a space at the back containing the armature starting resistance. Only a single step of starting resistance is provided, and one current relay. Accordingly, the motor is brought up to full speed in two steps, one according to the speed obtained with all resistance in circuit and the other to the speed obtained with all resistance short circuited. The motor is started, stopped and reversed by means of the drum switch which is usually connected directly to the hand cable. At the two limits of travel, the elevator may be stopped by buttons on the cable. All of the operating parts of this controller are enclosed in the drum case and are thus protected from dust and dirt. The space at the back of the frame containing the resistance is ventilated, but the resistance units themselves are of the enclosed, moisture proof type.

sufficient power and line capacity are obtainable, but the current inrushes limit the size of the motor in most cases to less than 20 horse power.

Elevator squirrel cage motors, when thrown across the line, should not take more than  $2\frac{1}{2}$  to 3 times the normal current.

**Ques.** What type of alternating current motor is suitable for elevators of higher speed?

**Ans.** Polyphase slip ring or external resistance motors.

This type of motor has a high starting torque and suitable secondary control can readily be provided that will insure a smooth acceleration. It will start smoothly under load and without requiring for acceleration more than 150 per cent. of normal current.

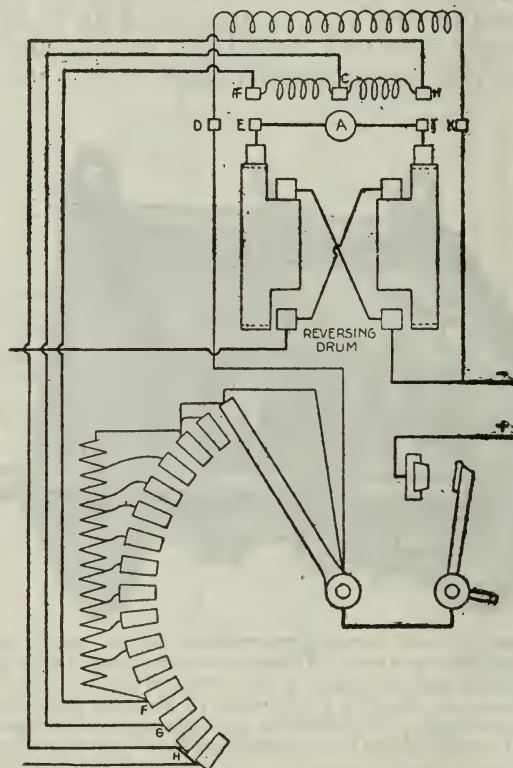


FIG. 4,135.—Diagram of Otis mechanical reversing control with type B reversing switch.

With this type of motor and the proper controlling device it is possible to secure a smooth start and to maintain a constant speed under varying loads. The polyphase, slip ring motor will not run away under conditions where the load tends to drive the motor, but, so far as operating characteristics are concerned, will approximate the performance of a shunt wound, direct current motor.

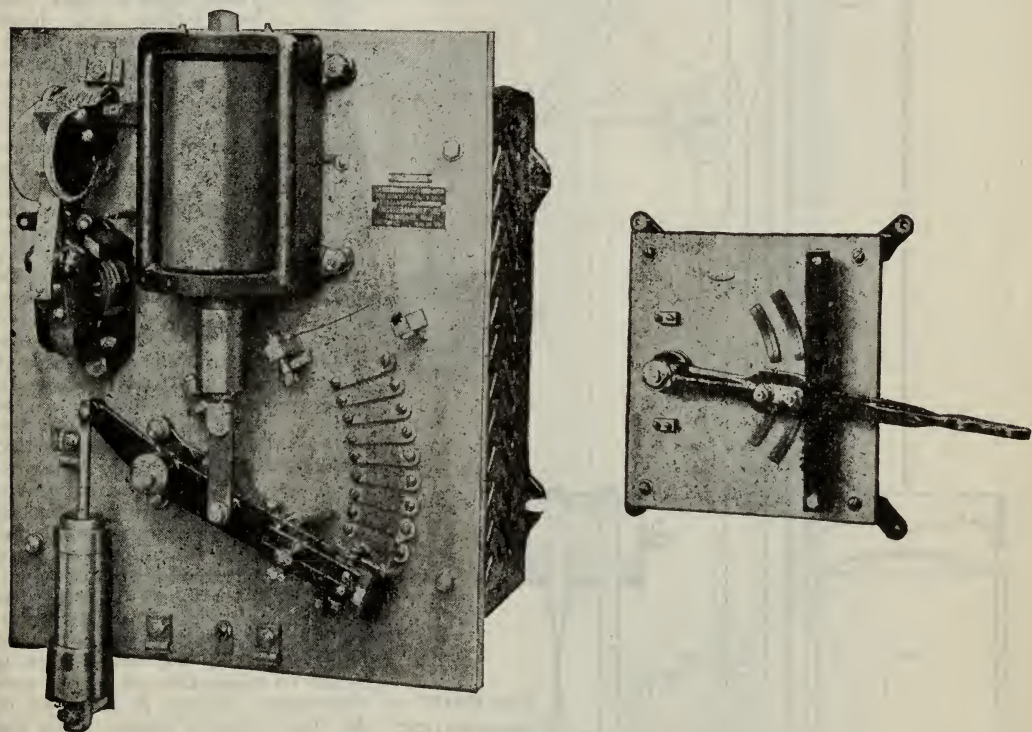
These motors may be used on two phase or three phase circuits having a frequency of not more than 60 cycles.



**Ques.** Are single phase motors suitable for elevator service?

**Ans.** Special elevator type of repulsion induction motors, which absolutely insure reversal of the motor, can be satisfactorily employed.

Standard split phase or standard repulsion induction motors are not suitable for elevator service.



**FIGS. 4,136 and 4,137.**—Cutler-Hammer direct current non-reversible single speed semi-magnet controller and belt switch for double belt freight elevators. The controller consists of a sliding contact type of self-starter, with main line clapper switch, and a separate belt switch which serves as a pilot switch for the self-starter. The belt switch is designed to be suitably connected to the belt shifting mechanism of the elevator so that the motor is started or stopped whenever the operator manipulates the lever that shifts the belt. The controller can also be operated by a separate hand cable connected to the belt switch only. By this arrangement the motor is started in advance of the elevator and is left running while the elevator is in service.

**Elevator Controller.**—This is a most important part of an elevator installation, as upon its proper working depends the safe and satisfactory working of the car. It performs a number of

function, such as releasing the brake, starting, accelerating, slowing, and quickly starting the car. The control may be classified:

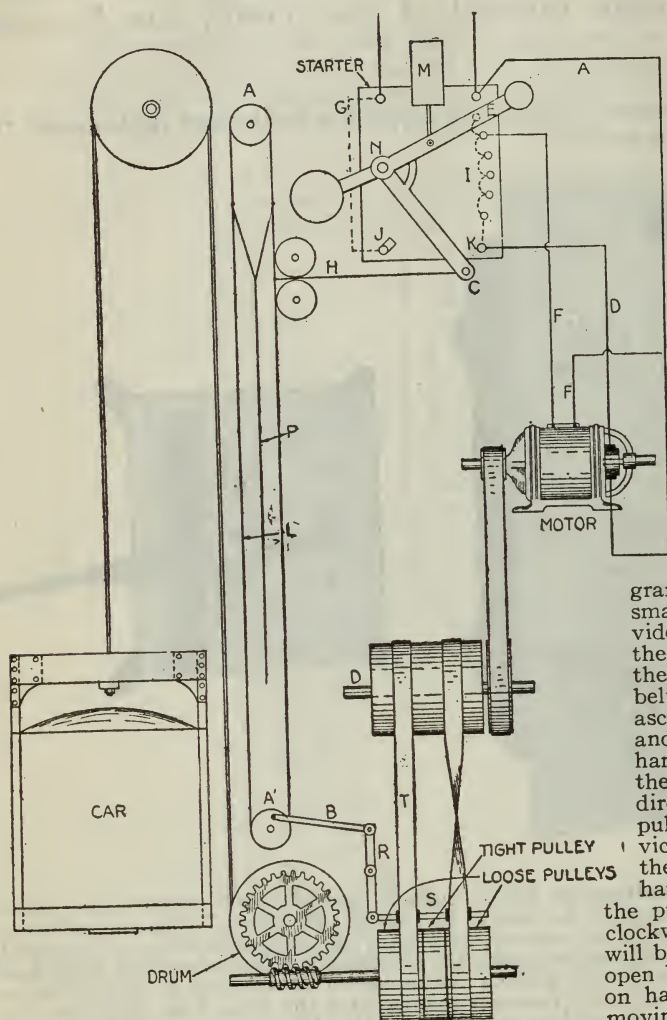


FIG. 4,138.—Continuous operating non-reversible full mechanical belt driven elevator control system. As shown the elevator machine is provided with a tight center pulley and loose pulleys on the two sides. The belts are shown on the loose pulleys, one being open and the other crossed. The countershaft carries a drum wide enough to allow for the side movement of the belts when one or the other is shifted upon the tight center pulley by the belt shifter S. To operate the elevator a hand rope is provided which runs up the elevator shaft at one side of the car from bottom to top of building. This rope is shown in the

diagram at L, and runs around two small pulleys AA'. Pulley A' is provided with a crank pin, which moves the connecting rod B and thus rocks the lever R, and thereby moves the belt shifter S. To cause the car to ascend, hand rope L is pulled down, and to make the car descend, the hand rope is pulled up. Accordingly, the lower pulley will rotate in one direction when the hand rope is pulled to make the car go up and vice versa. Pulley A is shown in the stop position, hence, when the hand rope is pulled down for up trip,

the pulley will turn in a counter-clockwise direction, and thus the belt will be moved to the right, bringing open belt into operation. Pulling up on hand rope rotates A clockwise, moving belt to left and bringing

cross belt into operation, thus causing car to descend. P is a stop rope and is connected with the two sides of the hand rope as shown and if pulled when car is in operation, will bring L to position shown, stopping the car. **In operation** when the hand rope L is pulled in either direction, H, draws C to the left and contacts with J, thus current passes through starting resistance I to motor armature through F, and reaches circuit branches off from upper end of I and reaches field coils through F, and reaches return wire through D and thus the opposite side of the circuit. When C is pulled to left, E gradually follows by gravity and dash pot control. The elevator machine is provided with a brake, actuated by the belt shifter S, applying brake when belts are in positions shown; when belt shifter is moved in either direction, brake is released.



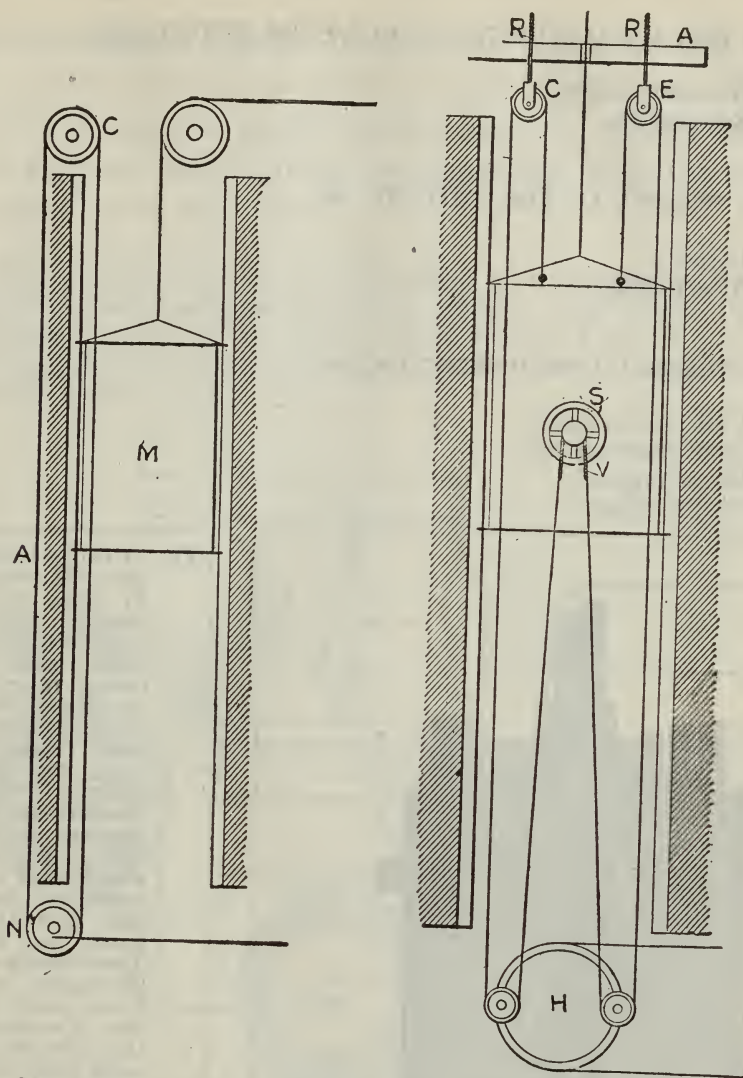


FIG. 4,139.—Mechanical control by shipper cable. *As shown*, an endless cable A, known as a shipper cable, is led up one side of the shaft and over a pulley C, down through the elevator car M, as shown, and around a pulley N connected to the switch or regulating apparatus at the motor. If, then, the operator in the car pull that portion of the shipper cable passing through the car, either up or down, he regulates the action of the motor and consequently of the car. For high speeds this style of control is not satisfactory.

FIG. 4,140.—Mechanical control by wheel; a method suitable for high speed cars. *As shown*, the ends of the shipper cables are fastened to the top of the car. The idlers C and E over which the cables pass are supplied by springs RR on a cross bar A which is fastened across the top of the shaft. A pulley H is placed at the bottom of the shaft, and a hand wheel S is used in the car for control, the shipper cable being roped around the pulleys as shown, that portion of the shipper cable near the hand wheel being replaced by a chain V which engages with a sprocket wheel mounted on the same shaft with the hand wheel. *In operation*, turning the control wheel to right or left causes a like movement of the pulley H, as is evident, thus transmitting the motion to the motor controller.

1. With respect to the rotation of the motor, as
  - a.* Non-reversible;
  - b.* Reversible.
2. With respect to the current, as
  - a.* Direct;
  - b.* Alternating.
3. With respect to construction, as
  - a.* Full mechanical;
  - b.* Semi-mechanical;
  - c.* Semi-magnet;
  - d.* Full magnet.

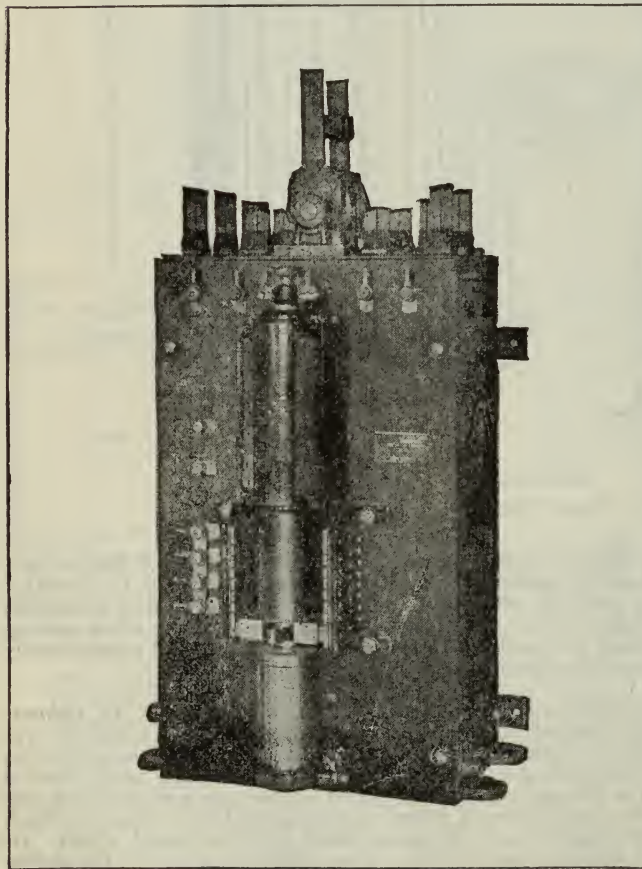


FIG. 4,141.—Cutler-Hammer (Schureman type F) direct current reversible single speed semi-mechanical controller with self-contained reverse switch for belted freight elevators controlled by a hand cable. In this type, the controller, reverse switch, and rheostat are mounted together as a single unit. The reverse switch is of the quick make and break type and cannot be left partly open or closed. The switch revolves 90 degrees each way from center to operate. The rheostat is of the solenoid operated cross head type with self-aligning contacts, the rate of acceleration being governed by a suction air dash pot. The piston is packed with soft leather, held in place by a compression spring and thereby forced gently against the wall of the dash pot. The rate of acceleration can be adjusted by means of a needle valve.



**Non-Reversible Controllers.**—The simplest way in which a motor can be installed to drive an elevator, is to arrange it so as to drive a counter shaft continuously, in which case the elevator is stopped and started by throwing belts on the tight or loose pulley as in fig. 4,138.

This system may be fully classified as a continuous operating non-reversible full mechanical control system. Obviously the term non-reversible refers to the motor which always runs in one direction as distinguished from motors which reverse their rotation to reverse the motion of the car.

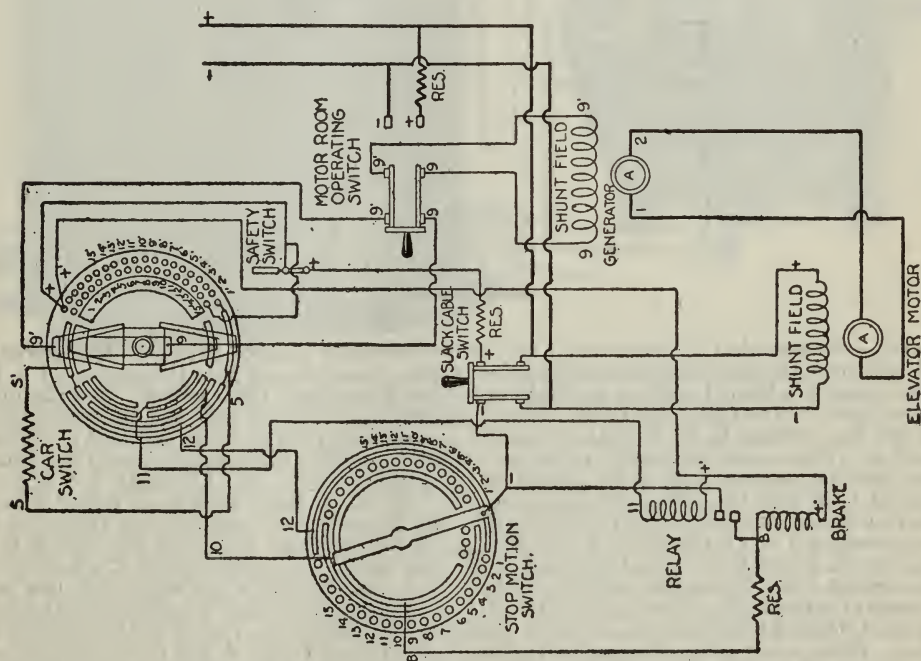
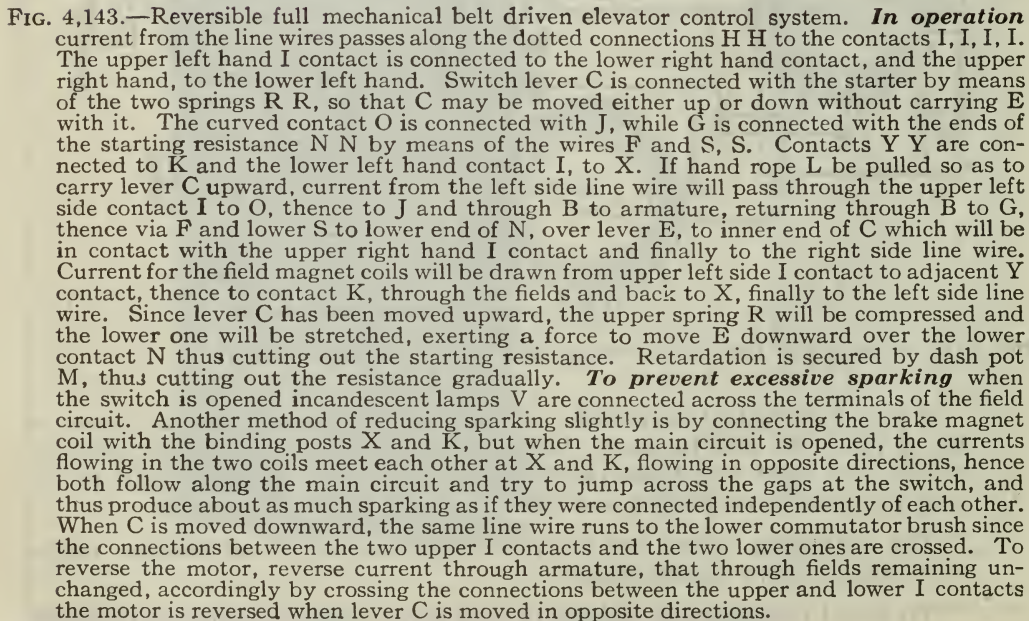


FIG. 4,142.—Diagram of Otis direct current field control (Leonard device).

A full mechanical reversible or "single belt" installation is shown in fig. 4,143. As will be seen, the principal difference in the mechanism is that the tight and loose pulleys are replaced by a single tight pulley and a reversible controller provided.

The foregoing types are simply combinations of an electric motor with a belt drive transmission.

To avoid the inherent defects of belt drive, and for economy of space,





the motor and winding mechanism are direct connected which is the form in most general use.

The distinction between the various classes of controller, known as non-reversible, reversible, mechanical, semi-mechanical, semi-magnet, full magnet, and push button is illustrated in the accompanying cuts.

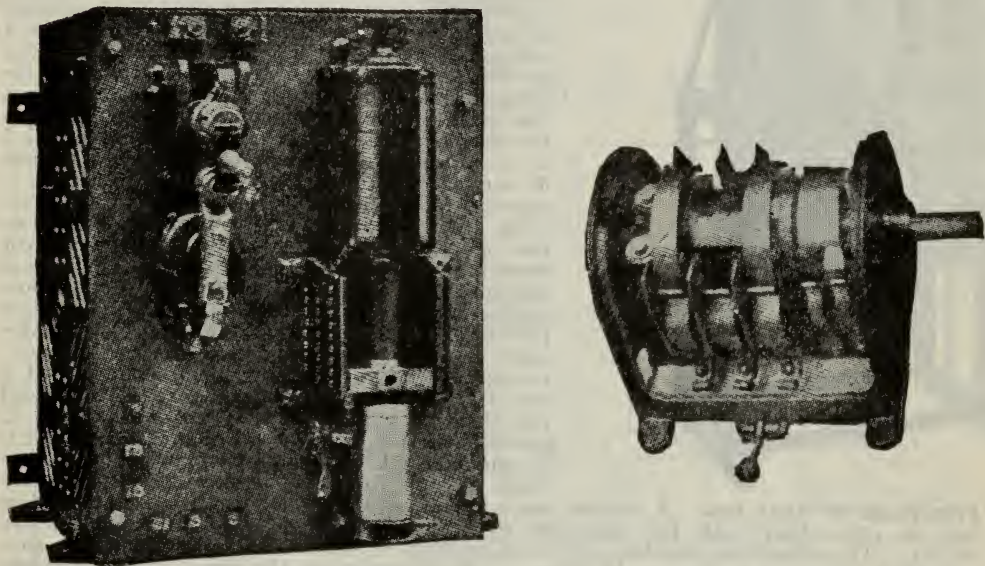


FIG. 4,144 and 4,145.—Cutler Hammer direct current reversible single speed semi-magnet controller with separate reverse switch for slow speed passenger or freight elevator. Fig. 4,144, self starting; fig. 4,145, Schureman type BR reverse switch. The controller consists of a sliding contact controller panel with main line magnetically operated clapper switch, and a separate drum reverse switch. The main clapper switch is controlled directly from the reverse switch by means of suitable auxiliary contacts, the action of the clapper switch being such that the motor circuit is always opened or closed with a snap. The main switch is so interlocked with the rheostat that the motor cannot be started or reversed until all starting resistance is in circuit, insuring smooth acceleration. The reverse switch is of the drum type designed for use with lever, wheel, or crank control, or may be operated by hand cable. The arrangement of contact is such that, although the reverse switch is of the slow break type without a centering spring, the motor circuit is opened at the clapper main switch, thereby eliminating destructive arcing on the reverse switch contacts. A mechanical connection may be made between the traveling nut of the winding drum and the reverse switch which will serve to throw the latter to the off position at either limit of travel. Limit switches may be used, however, and in many cases the use of shelf limit switches will obviate the necessity of installing the more expensive traveling nut device. Where shaft limit switches are used the hand cable is connected to the drum reverse switch only. Two single pole shaft limit switches should be installed, one at either limit of elevator travel. These can be arranged for operation by the car, or may be so installed that one switch is operated by the car and the other by the counterweight. The limit switches should be connected between the drum reverse switch and the controller panel so as to open the circuit of the main switch coil and stop the motor whenever the car arrives at the top or bottom of the shaft. With all semi-magnet controllers the mechanical brake is usually released by the operation of the hand cable. It is possible, however, to use a solenoid operated brake with these controllers by the addition of suitable contacts or relays to the controller. In connection with the hatchway limit switches a brake solenoid and slack cable switch should always be installed.

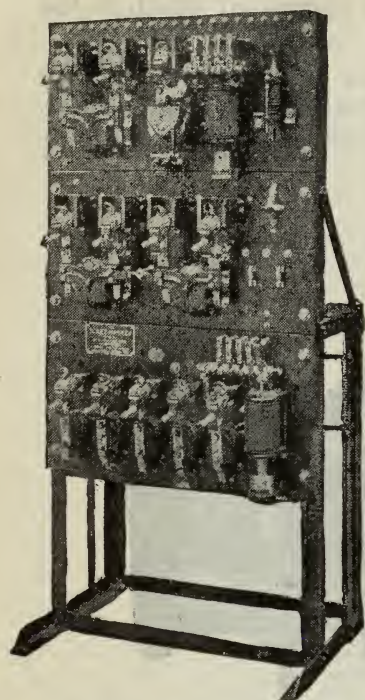


FIG. 4,146:—Cutler Hammer (Schureman type M) direct current reversible one or two speed with slow down full magnet controller for high speed passenger elevators. **Slow down.** This feature gives about one-quarter of the normal speed, the normal speed being for single speed equipment, the running speed, and for two speed equipment, the speed obtained with full field on the motor and all the armature resistance cut out of circuit. **Controller panel.** This is built in three sections in which the necessary armature resistance is mounted. The field and control resistances are mounted in a suitable frame on the back of the control panel. The field resistance has a wide range of adjustment so that the speed of the equipment can be regulated to the desired value. Suitable interlocks are supplied so that the main and reverse switches cannot be energized until all of the starting resistance is inserted in the armature circuit. Similar interlocks are supplied for giving proper sequence in the operation of the switches. **Apparatus on controller panel.** 1, double pole main line magnetically operated switch; 2, double pole magnetically operated direction switches; 1, single pole magnetically operated "slow down" or "dynamic brake" switch; 1, single pole "slow down" relay; 1, acceleration movement consisting of a set of crank switches operated by a solenoid and retarded by a dash pot; 1, try out switch; 2, control fuses; 1, double coil overload movement. In addition to the above, for two speed controllers there is one four step field weakening switch.

**Functions of switches.** A double pole main line switch breaks both sides of the line and in connection with the direction switches gives four breaks in the armature circuit. The direction switches are mechanically interlocked to prevent their simultaneous operation which would cause a short circuit on the line. These switches will automatically open on abnormal drop in voltage and stop the equipment. The slow down, or dynamic brake switch inserts armature shunt resistance in the slow down position and also keeps this resistance in circuit in the off position until the motor has practically stopped, thus giving a powerful dynamic braking effect. The slow down relay handles the accelerating solenoid current, thus eliminating the arcing on the car switch contacts, which would occur in case the accelerating solenoid was handled directly from the car switch. The time of cutting out the armature resistance is adjusted by means of a needle valve in the bottom of a large vacuum dash pot. The try out switch enables the attendant to run the car directly from the control panel without the necessity of getting into the car. The control fuses are used as a protection to the operating coils of the magnet switches and also afford additional protection to the elevator equipment in the case of grounds or short circuits in the operating cables. The double coil overload movement is arranged to stop the elevator in case of overload and can be automatically reset by throwing the car switch to the off position. This gives a reliable indication as to whether the car is overloaded and by having the resetting feature in the car switch, it is possible to set this overload within the closest limits. This device therefore possesses an advantage over the hand operated circuit breaker in that the operator is not compelled to go to the switchboard in case a slight overload occurs. The only thing necessary is to lighten the load on the elevator. With a manually operated circuit breaker the operator, under these conditions, invariably increases the current setting of the breaker when he goes to the panel to reset it and, in case of continued tripping, eventually ties the breaker in; thus eliminating the overload protection which the circuit breaker is designed to give. The four step field weakening switch which is used on two speed equipments is a weight closed switch controlled by an air dash pot. It is positive in action and is operative both when inserting and when cutting out the field resistance, insuring smooth acceleration and deceleration of the motor.



**Full Magnet Direct Current Controllers.**—A typical direct current control apparatus of the full magnet type consists of several slate panels, mounted on an angle iron frame with all the connections made on the back of the board.

The solenoid switches mounted on the slate panels are arranged to perform the following functions:

1. To disconnect in the off position both sides of the line from the armature, series field, resistance, and brake magnet.

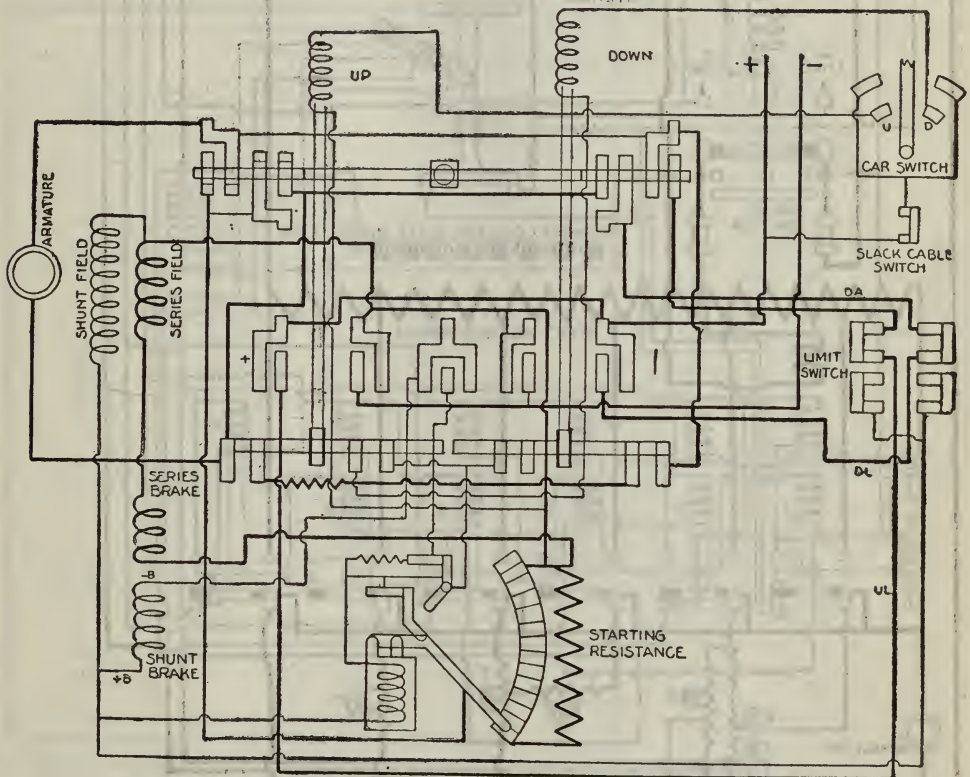


FIG. 4,147.—Diagram of A. B. See No. 4 magnet controller.

2. To accelerate the motor automatically by cutting out the armature starting resistance step by step, and also the series field with the last step of armature resistance (this by means of individual series relay control) giving smooth acceleration under all load conditions.

3. To control the speed of the elevator by cutting resistance in or out of the shunt field circuit of the motor, affording positive speed control under widely varying loads.

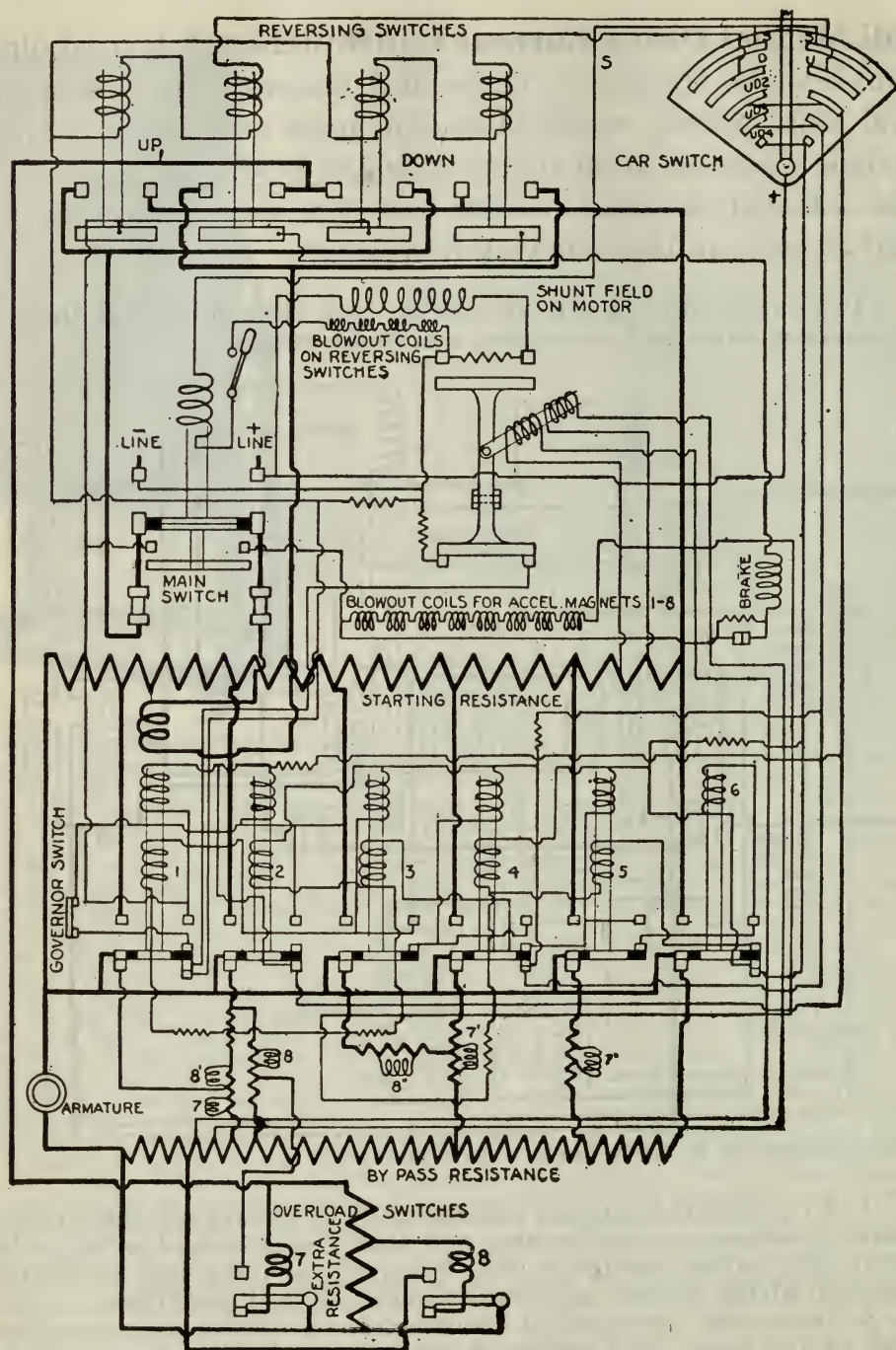


FIG. 4,148.—Diagram of A. B. See traction controller.



4. To bring the elevator quickly, but smoothly, from high to low speeds, regardless of load, making accurate stops at landings an easy matter.
5. To open the circuit to the motor should an overload current flow
6. To apply the dynamic brake in the off position.
7. To operate the elevator at normal speed from the switchboard for test purposes.

To these seven functions may be added, as a modification of the standard controller equipment:

8. To open the shunt field circuit in the off position of the controller

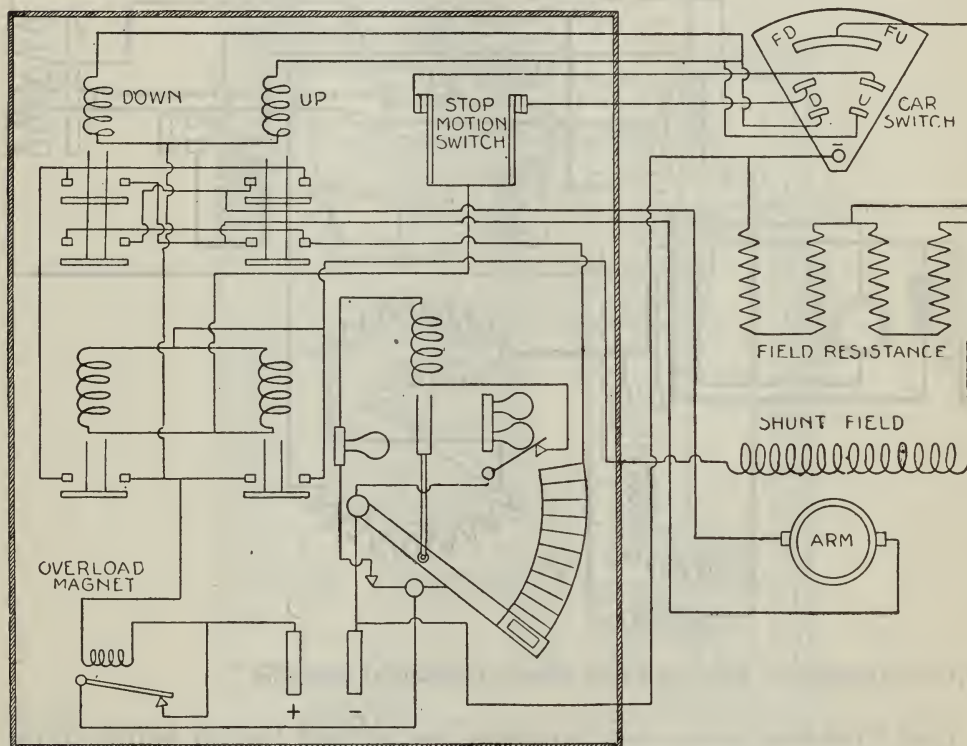


FIG. 4,149.—Diagram of Cutler-Hammer, two speed magnet controller.

**Ques.** How are excessive currents guarded against during the starting period?

**Ans.** The acceleration of the motor is governed by current relays so adjusted as to limit to a predetermined value the current taken by the motor.

Any tendency to overload the motor in starting is checked by the current relays which, whenever the current rises above a predetermined value, operate to prevent the cutting out of more resistance until the motor has properly accelerated and the surge of current, which follows the closing of each switch, has decreased.

In addition to the protection afforded by the current relays during the starting period, the motor is insured against overloads while running by an overload, or circuit breaker, relay which operates to open the circuit whenever an abnormal current flows. This circuit breaker relay is interlocked with the car switch in such a way that, should the motor be stopped by the action of the circuit breaker relay, the relay can be

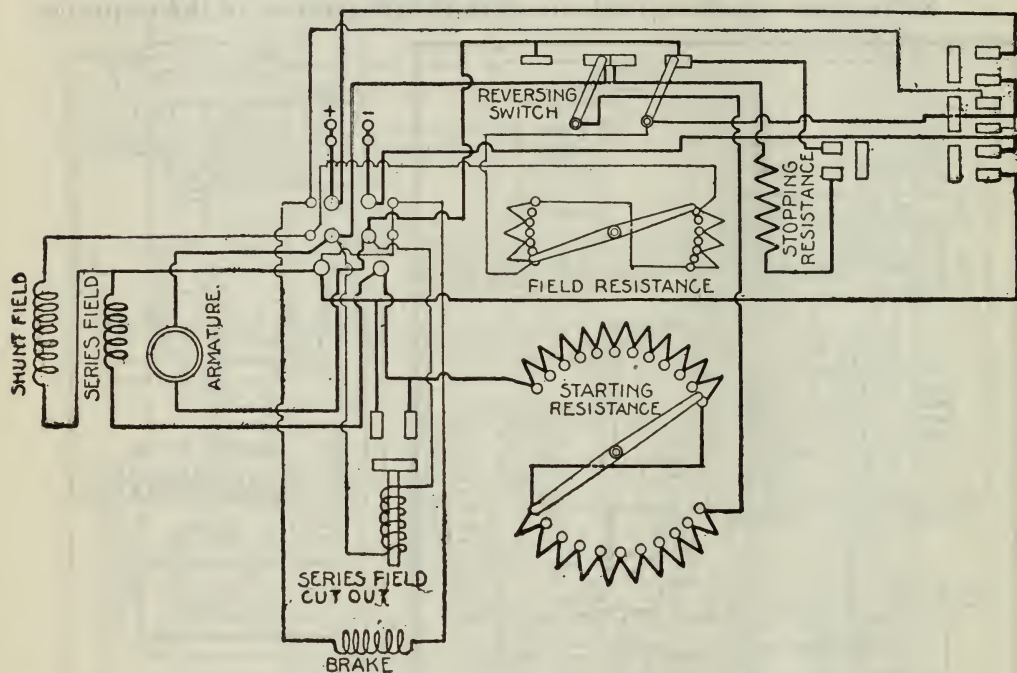


FIG. 4,150.—Diagram of Electron direct current mechanical controller

reset from the car by merely moving the lever of the car switch to the off position. This re-establishes the continuity of the circuit and it is then possible for the operator to start the car again in the usual manner.

### Ques. Describe the speed control.

Ans. The controller is arranged usually to give three speeds: 1, slow down speed, 2, normal speed, obtained by cutting out the armature resistance step by step, and 3, high speed, obtained by inserting resistance in the shunt field.



The slow down speed is not a running speed, but is only used for making accurate landings.

**Ques. What are the features of speed variation by shunt field resistance?**

**Ans.** It is positive at all loads in the elevator, even under conditions when the car, in descending, tends to drive the motor. It is also very economical

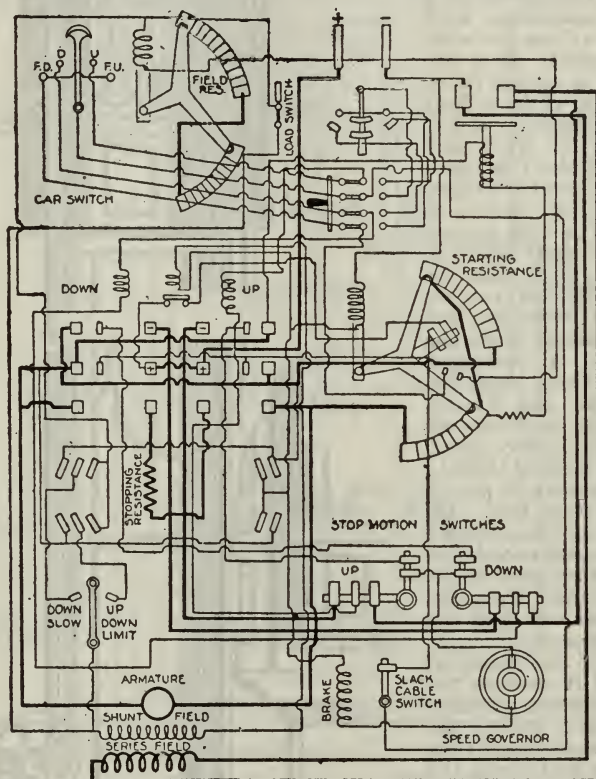


FIG. 4,151.—Diagram of Electron direct current two speed magnet controller.

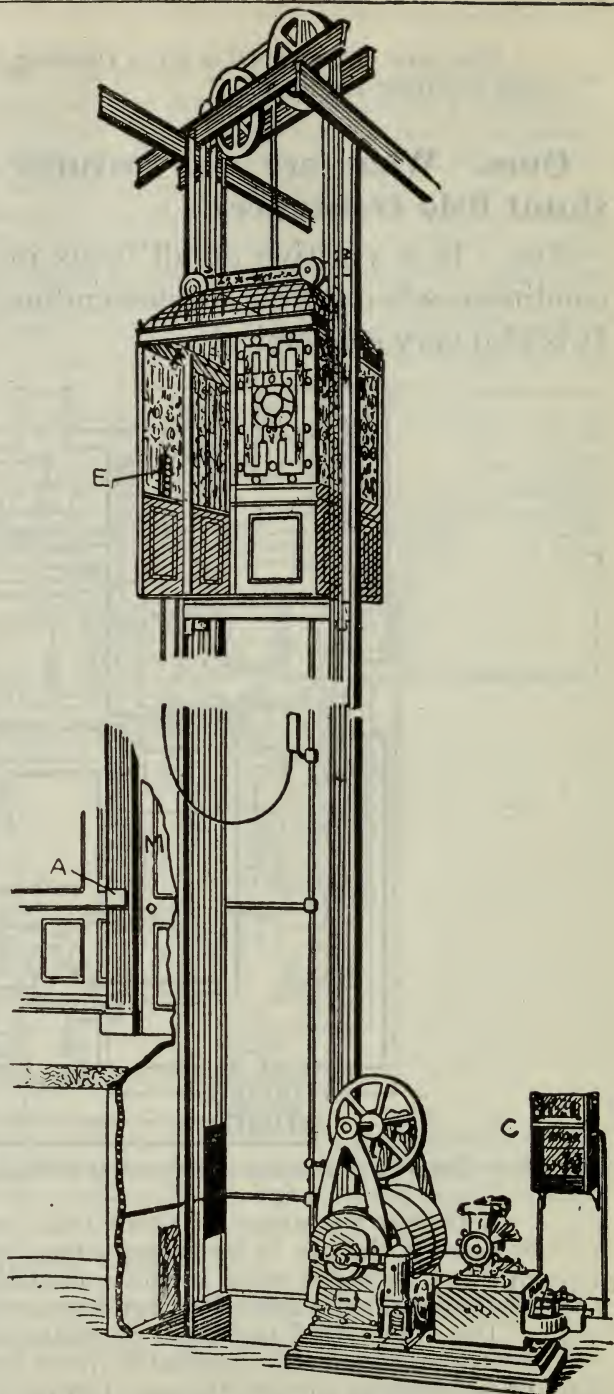
A further advantage of shunt field control is found in the fact that it permits the car to be slowed down, regardless of load, enabling the operator to make more accurate landings and rendering the operation of the automatic limit switches more certain.

The shunt field resistance is mounted directly on the back of the switchboard panel in a suitable frame and is arranged for a wide range of adjustment to vary the speed in case it is found necessary.

With the slow down control provided with some controllers the speed

FIG. 4,152.—Push button control.

In this system a series of push buttons are placed both in the hallway and in the car. In the hallway there is one button A at each floor to bring the car to that landing. In the car at E there is one button for each floor and also one for stopping the car at any point by cutting off the current. By means of a cut out device on the controller C the circuits to all push buttons are automatically opened after the car starts. It is therefore impossible for a second party to interfere with the movement of the car after it has been started. It is also impossible for a second party to start the car while it is at landing and a passenger is getting in or out, for while any door M to the shaft is open, the controlling circuit is broken. An automatic door fixture is generally used in this system for locking the shaft doors so that none of them can be opened until the car reaches the landing, and then only the door at the landing where the elevator stops. A passenger desiring to go from, say, the second floor to the fourth, would, if the car were not already at the second floor, push the hall button located there in the same manner as he would to ring an electric bell. He need not continue the pressure on the button, nor, in fact, on any of the buttons used in the system, for more than an instant. The car will then rise or descend, depending upon where it may be stationed at the time, until it reaches the second floor where it will stop and automatically unlock the shaft door. The passenger then steps in the car and closes the shaft door. Unless he close this door he will be unable to start the car. Wishing to go to the fourth floor he pushes the button in the car corresponding to that landing, and the car ascends, automatically stopping and unlocking the door at that floor as previously described for the second floor. A simple modification of the automatic system just described is used for dumbwaiters or freight elevators. In this case the car is controlled entirely from the landings.





of the car is reduced to approximately 30 per cent. of normal speed and from this slow speed it is very easy to make an accurate landing, the tendency of the car to coast being practically eliminated.

**Ques.** State an additional advantage of slow down control.

**Ans.** It reduces the speed of the car at the two limits of travel regardless of load, making it possible to set the brake and adjust the limit switches so that the car will be brought to a full stop

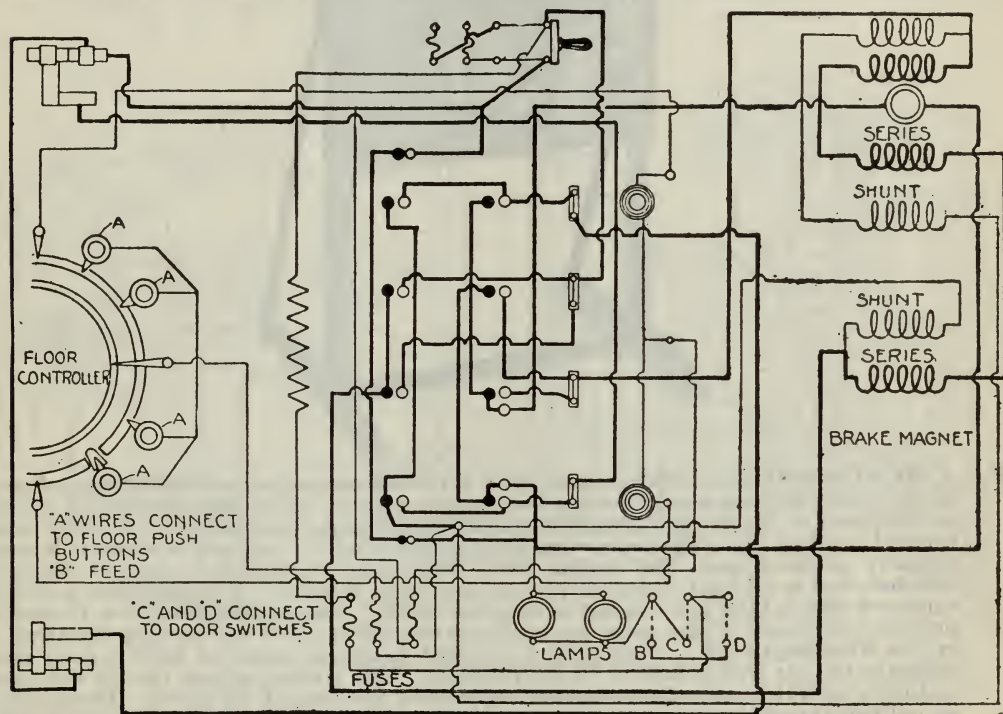


FIG. 4,153.—Diagram of Burdett and Roundtree push button controller for dumbwaiter.

at the last landing, instead of coasting past the limits when light or heavily loaded and hitting the bumpers at the top or bottom of the shaft.

**Ques.** When is the motor series field winding used?

**Ans.** It is used while accelerating, being cut out by the controller at normal speed.

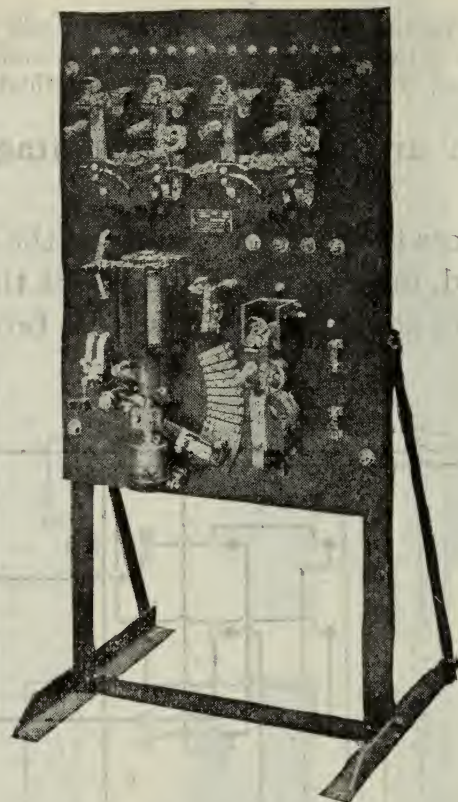


FIG. 4,154.—Cutler-Hammer (Schureman type K) direct current reversible single speed push button controller for passenger elevators or dumb waiters. The push buttons are located on the car or at various landings. The controller is of panel construction, all wiring being exposed on the back. The motor circuits are controlled by means of a single pole magnetically operated main line switch, two double pole magnetically operated direction switches, and a solenoid operated, pivoted arm type rheostat. The main line switch is equipped with a blow out magnet to suppress arcing. An electrical interlock is used to prevent the closure of the main line switch except when all of the starting resistance is in the armature circuit. Push button operated passenger elevators have a gang push switch in the car with a button for each landing. The pressing of any button will automatically send the car to the corresponding landing and bring it to a stop. There is also an individual push switch at each landing, which, when pressed, will automatically bring the car to that landing, provided that all the doors are closed and the car is not in use. An emergency stop switch is mounted in the car to bring the car to a stop at any time. Push button operated dumb waiters usually have a gang switch mounted at each landing so that the car can be brought from or sent to any other landing. Occasionally, however, installations are made in which a gang push switch is mounted at only one landing, from which the car is controlled, and an individual push switch is mounted at each of the other landings to send the car to the *control* landing, after it has been loaded or unloaded. A floor stop is used to determine the direction of travel and to bring the car to a stop when opposite the desired landing. On passenger elevators, an emergency stop device is used to bring the car to a stop at any time when the emergency stop button in the car is pressed. To prevent operation in case any of the doors be left open, a door safety switch is used; shaft limit switches and a slack cable switch should be used with these controllers to open the control circuit if the car should over travel or become stuck in the guides. When the motor is to be operated from a 500 volt circuit, a low voltage control circuit (115 or 230 volts) must be used. This circuit may be either direct current, or 25 or 60 cycle alternating current.



If the series field be heavy, the speed of the motor will increase very materially when the series winding is cut out, and it may be necessary to provide an extra switch on the controller in order to give smooth acceleration. This is apt to be the case with an old motor.

**Ques.** Name two types of resistance employed.

**Ans.** The armature starting resistance and the dynamic brake resistance.

These are of the cast metal grid form.

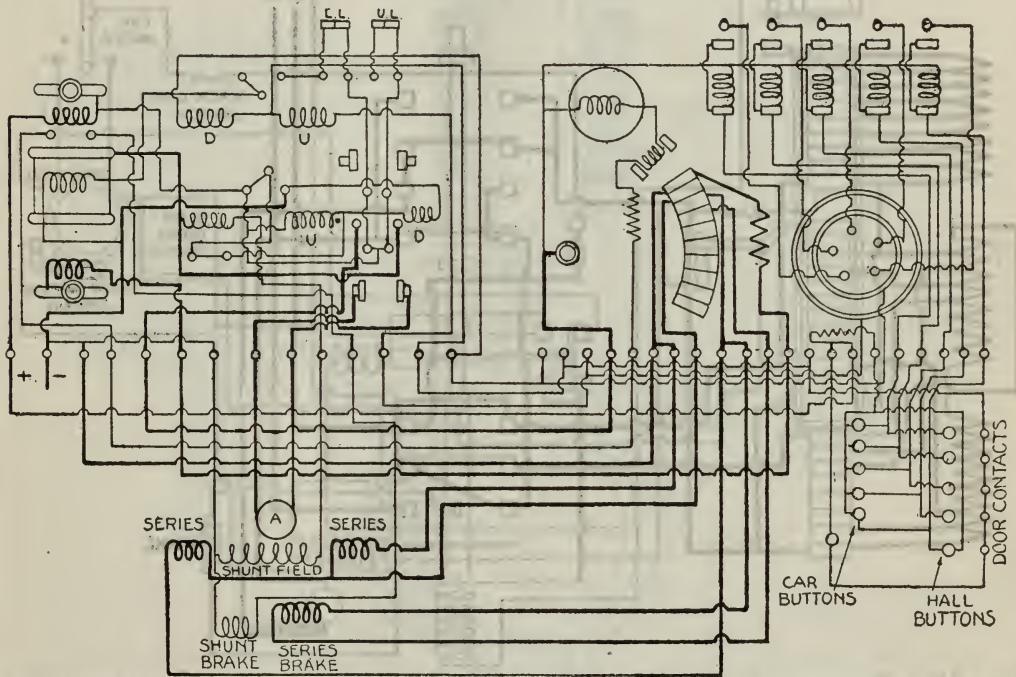


FIG. 4,155.—Diagram of Darrin automatic push button controller.

**Ques.** How is the armature resistance proportioned and why?

**Ans.** It is in proportion to the horse power output of the motor at normal speed in order to make the acceleration as smooth as possible and at the same time to reduce the amount of current taken from the line in starting.

**The Mechanical Brake.**—The proper functioning of the mechanical brake is rendered positive by disconnecting both terminals of the brake magnet winding from the line and from the motor armature in the off position of the controller. This makes it certain that no possible combination of grounds or short circuits can keep the brake magnet energized and the brake released when the car switch is thrown to the off position. So long as the brake mechanism is in good working order mechanically, the positive application of the brake is assured.

**The Dynamic Brake.**—Power for the operation of the dynamic brake switch is taken from the motor armature and the brake resistance is applied directly across the armature terminals.

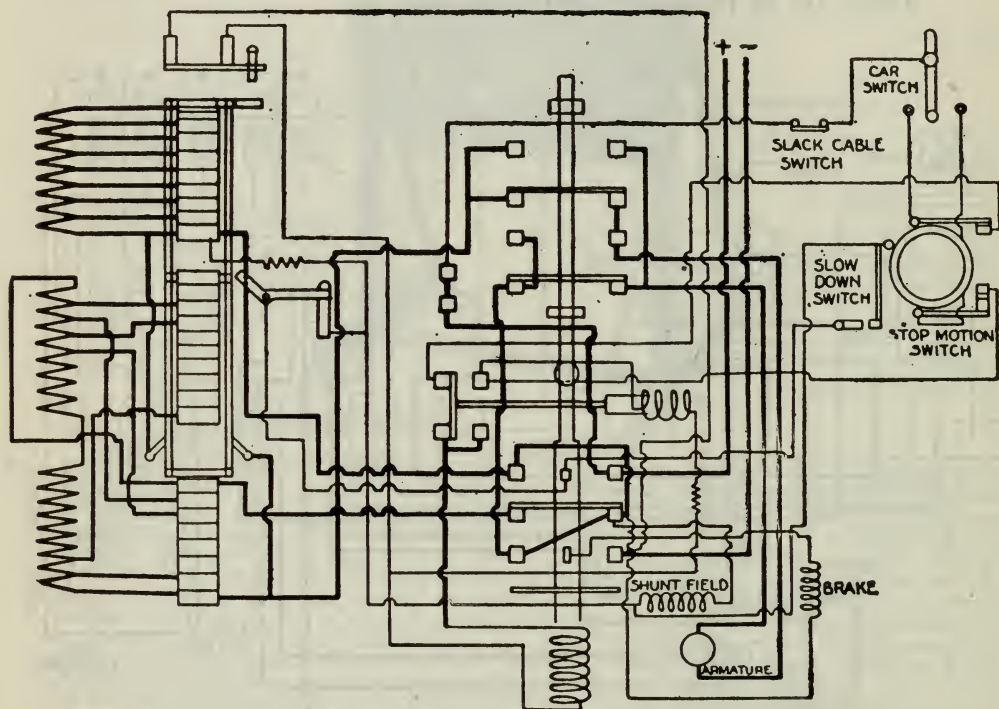


FIG. 4,156.—Diagram of National direct current type A, one speed gravity rheostat controller.

The application of this brake depends, therefore, not on the line voltage but solely on the motion of the armature.

In any form of elevator braking, mechanical or electric, the energy represented by the inertia of the moving parts must be dissipated in the form of heat in order to stop the motor.

In mechanical braking this energy is transformed into heat by the friction of the brake shoe; in electric braking it is transformed into heat by causing the motor to generate current and dissipating this energy in a resistance provided for that purpose—the dynamic brake



resistance. Accordingly, when the dynamic brake is used in connection with the mechanical brake, the effectiveness of the latter is increased since it is not called upon to arrest a full powered motor, but one which has already been deprived of a portion of its energy by having a resistance shunted across its armature terminals.

**The Try Out Switch.**—Operators are usually instructed to go to the switchboard every morning before entering the car and to test the operation of the elevator by means of a *try out switch*, so as to ascertain

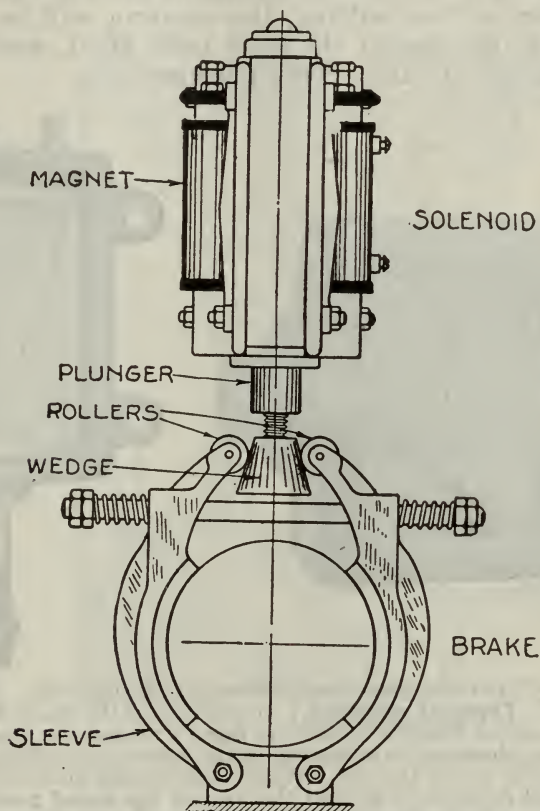


FIG. 4,157.—Typical arrangement of brake magnet having a wedge acting between rollers to release the brake.

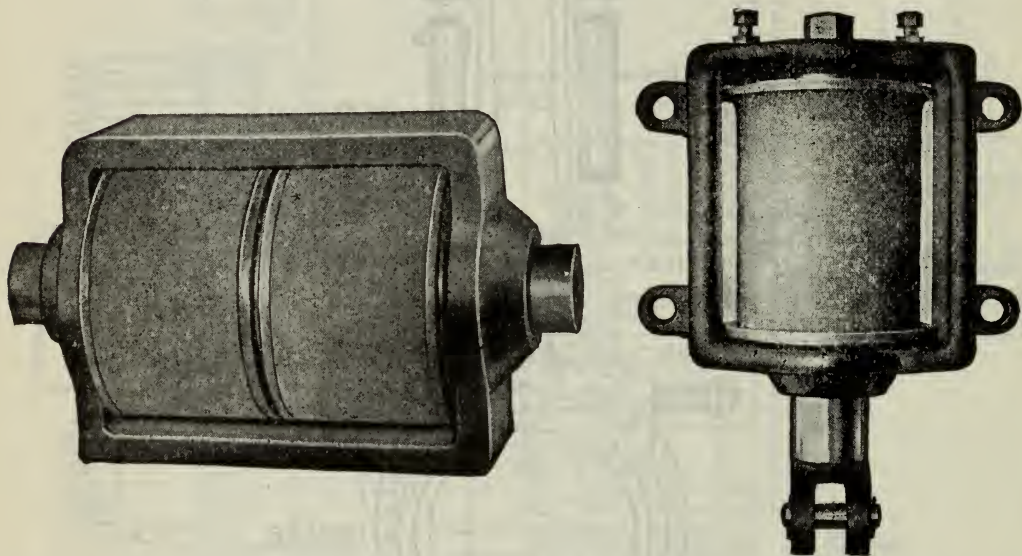
that every part of the installation is operating properly. In this way the car can be run up and down the shaft several times each morning, testing not only the control apparatus, but also the motor, limit switches, brake solenoids, etc.

**Ques.** Describe the try out switch.

**Ans.** It consists of a single lever normally locked in the central position, and in the position completing the circuit to the car switch.

It is, therefore, not possible to operate the elevator from the car while the try out switch is in use, this fact enabling the try out switch to be used also as a safeguard against the operation of the elevator while the regular operator is absent from the car.

**The Service Switch.**—It sometimes happens that the main line knife switch ordinarily used as a service switch cannot be so located that it may be conveniently opened at night, or at other times when the elevator is idle for considerable periods. This condition is frequently met with in over mounted installations, and unless some provision be made for opening the circuit to the motor from the car, or from one of the lower floors of the building, the operator will be obliged to leave the elevator at the top of the shaft each night, walking down stairs every evening and up stairs every morning.



FIGS. 4,158 and 4,159.—Cutler-Hammer direct current brake solenoids. Fig 4,158, short pull; fig. 4,159, long pull. **Types of winding.** In the case of the shunt wound solenoid, there is a single coil connected directly across the line to release the brake. The compound wound solenoid has a shunt and a series coil in the same frame. The shunt coil is wound for connection directly across the line. While contributing somewhat to the pull on the plunger, its principal function is to hold the load in the sealed position of the solenoid. The work of retracting the brake is performed principally by the series winding which is so connected as to be cut out of circuit when the motor is running, leaving the shunt winding in circuit to support the load. The brake will therefore be released whenever the circuit of the shunt winding is opened. Owing to the reduced self-induction, compound wound brake magnets are more rapid in action both in releasing and in applying the brake than plain shunt wound solenoids. This characteristic results in the preference being given to compound wound solenoids in all cases where quick starting and stopping is desirable.

**Ques.** Describe the operation of the service switch.

**Ans.** It remains closed normally while the elevator is in operation, not being connected in any way to the car switch or other speed regulating portion of the apparatus. Connection to the single pole service switch may be either through the safety switch, installed in the car,



or through any other suitable pilot switch installed on the landing at which the operator usually leaves the elevator for the night. The opening of the switch disconnects one side of the line from the controller switchboard, enabling the operator or janitor of the building to open the circuit to the motor without going to the main line switch. The service switch controls, from one set of contact, the continuity of both the armature and shunt field circuits. This arrangement is necessary for safety, so that it will not be possible to open or close the armature circuit without also opening or closing the shunt field circuit.

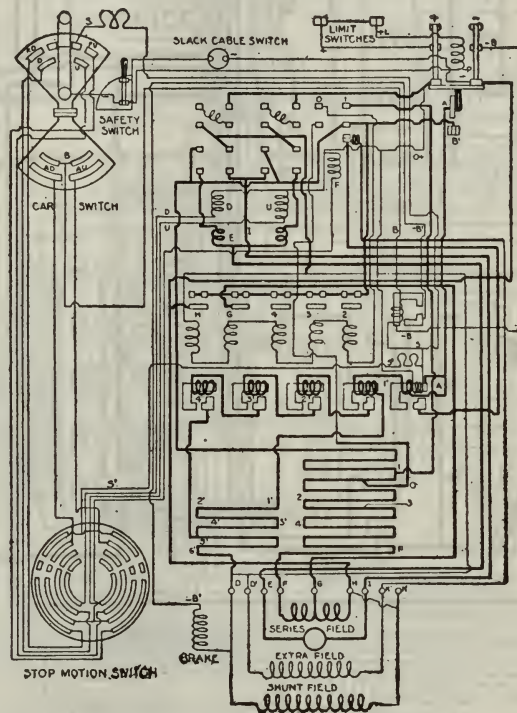


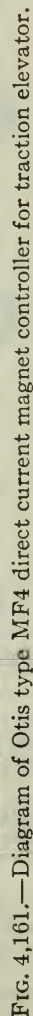
FIG. 4,160.—Diagram of Otis style B, direct current, two speed magnet controller.

Controllers in which the shunt field is always opened when the car switch is thrown to the off position are sometimes called for. This requirement can be met by the addition of relay circuits serving to open the service switch above described whenever the elevator comes to rest.

Unless there be some special reason for desiring this arrangement, however, it is generally advisable not to open the shunt field circuit except when the elevator service is shut down for the day, the reason for this being that some excitation of the shunt field is desirable while the elevator is in service in order to obtain the best results in speed control.

The amount of current saved by opening the shunt field momentarily during stops at landing is not very much, and any gain of this nature is more than offset by the larger armature current taken in starting under these conditions and the greater length of time which is required to bring the car up to full speed.

When the service is discontinued for the day there is then reason for wishing to open the circuit to the shunt field, and this is provided for by the service switch already described.





**Heavy Load Lifting Device.**—It is sometimes desired to have a high speed passenger elevator equipped so that it can be operated at a lower speed as a freight elevator for the purpose of lifting occasional heavy loads such as safes, etc. This has usually been accomplished in the past by means of back gearing, an arrangement which gives a slower speed to the car and a correspondingly greater lifting capacity. Such an arrangement however results in higher initial cost and requires a great deal of time and labor for throwing the back gears in and out. The same result can be accomplished electrically with the elimination of all back gearing. In changing over, the only operation required with this method is the closing or opening of a knife switch on the

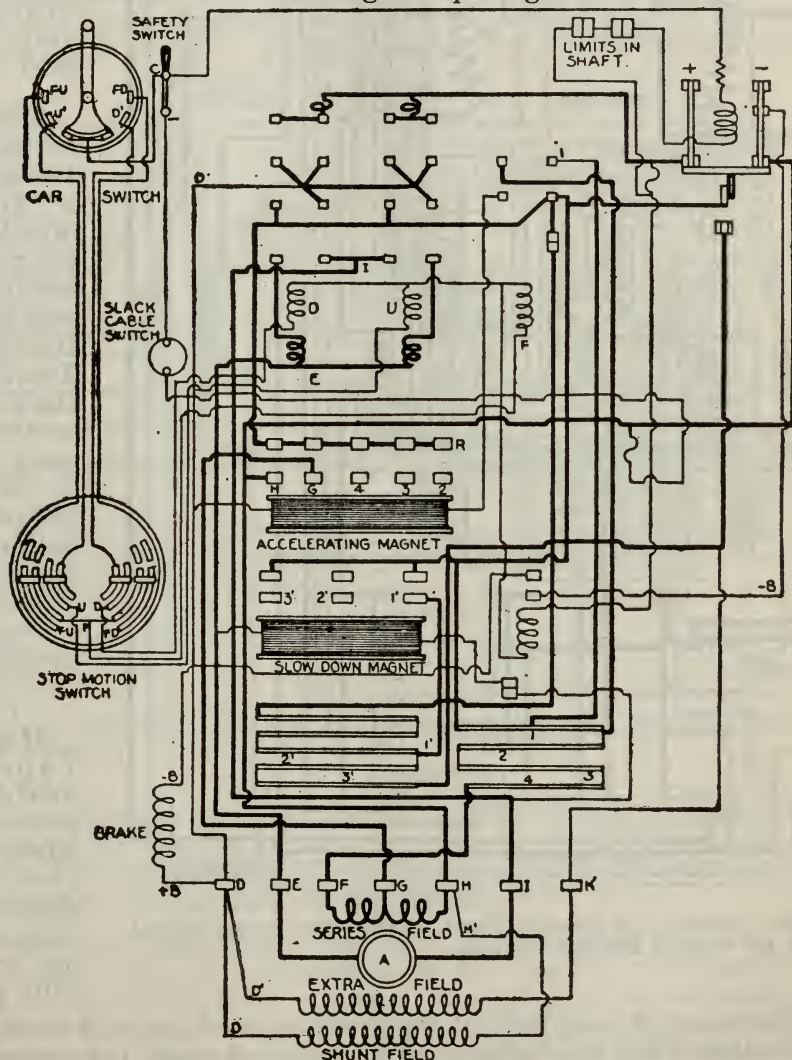


FIG. 4,162.—Diagram of Otis style GS direct current, two speed controller.

controller panel, this simple operation enabling one to lift approximately twice the normal load at half the normal speed.

In order to use this arrangement with a standard Cutler-Hammer controller it is necessary to have a motor with a 2 to 1 speed variation by shunt field resistance.

The knife switch referred to above rearranges the armature starting resistance and prevents the weakening of the shunt field. This also adjusts the series relays so that equally good conditions of acceleration are obtained in both methods of operation. The motor will not be worked above its rated capacity in either case.

**Machine Type Limit Switch.**—This switch is intended to insure the slowing down of the car from any speed not exceeding 300 feet per

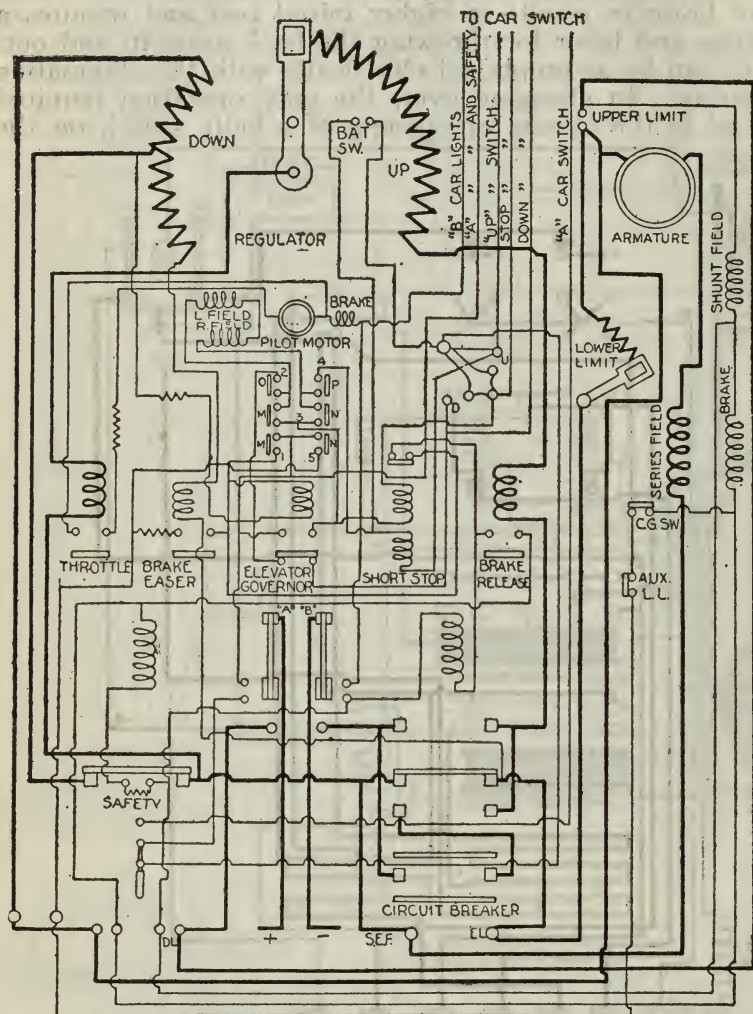


FIG. 4,163.—Diagram of Sprague direct current pilot motor controller for type A Sprague elevator.

minute, and its stoppage at the predetermined limits of elevator travel. The slow down is accomplished by means of single pole switches in the control circuit, while the complete stoppage of the car is brought



about by double pole switches which disconnect both sides of the lines from the control system, thus insuring that the motor will be stopped even under conditions which might otherwise tend to impair the control of the car, such for instance, as grounds or short circuits in some part of the control system.

Connections to the limit switches are so designed that after the car has been stopped automatically at either limit of elevator travel it is possible for the operator to start and immediately accelerate to full speed in the opposite direction.

**Shaft Limit Switches.**—In addition to the machine type limit switches just referred to, over travel switches should be installed in the elevator shaft as an extra precaution. These shaft limit switches

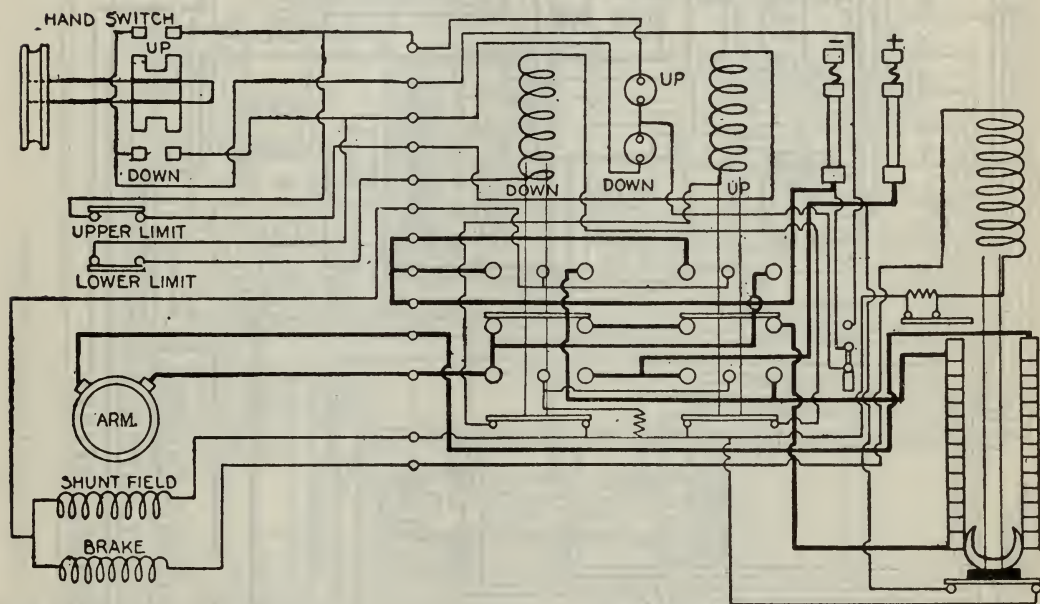


FIG. 4,164.—Diagram of Sprague direct current magnet controller for type T and Y Sprague sidewalk elevator.

are arranged to be operated by the car which, on passing a given point, opens the switch thus introducing an additional break in the control circuit and insuring the stopping of the elevator through the opening of the line and reverse switch.

Shaft limit switches, when used as over travel switches, should be so arranged that it is impossible for the operator to move the car after the switch has opened without first going to the elevator machine, thus insuring attention to the defect which caused the shaft limit switch to operate. These switches are sometimes installed alone in preference to the machine type of limit switch on drum type elevator machines.

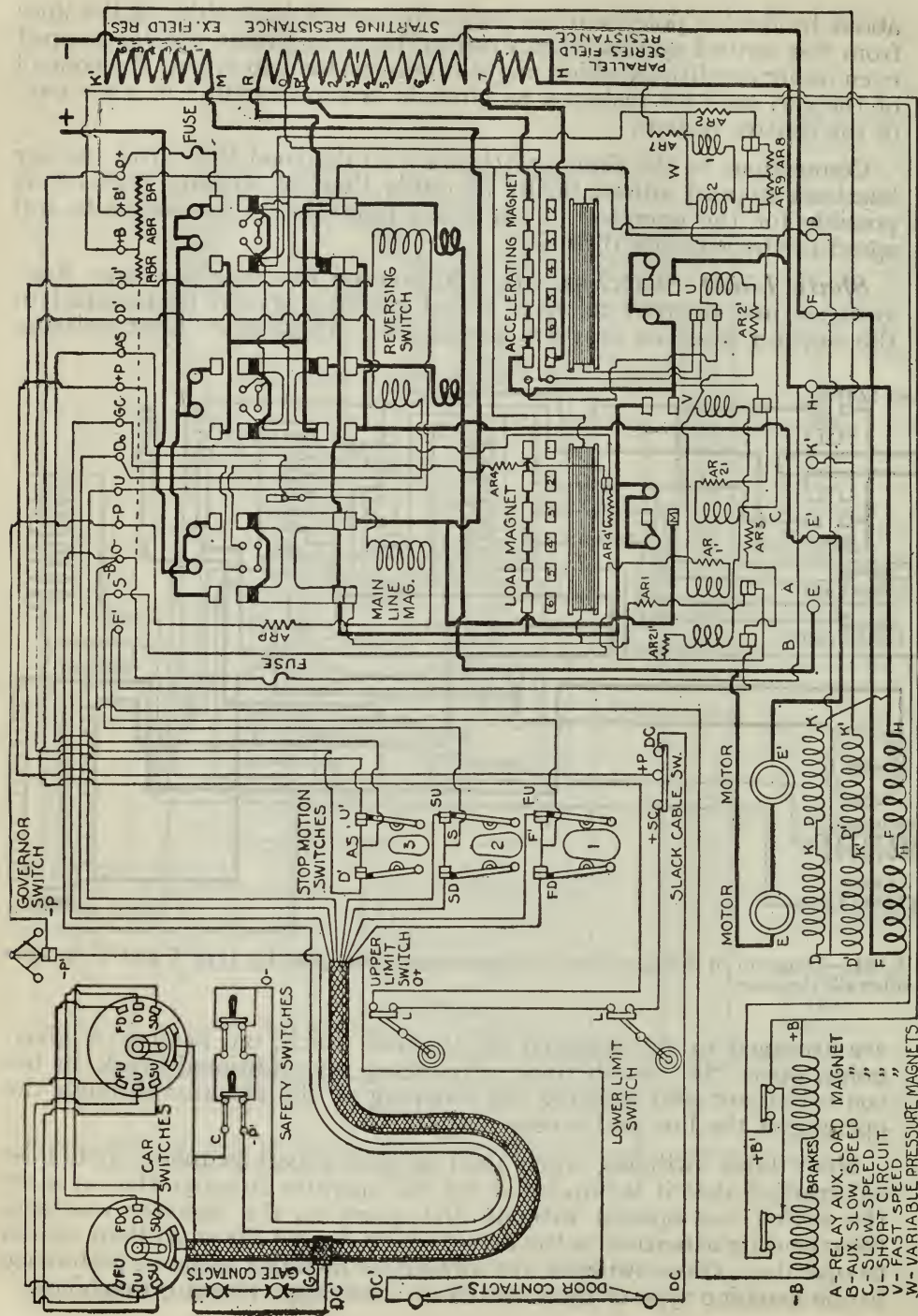


FIG. 4,105.—Diagram of Otis style 7 direct current duplex controller.



On traction type elevator machines they obviously have to be used for both the automatic limits and over travel. For automatically slowing down and stopping the car three single pole shaft switches at either limit of elevator travel should be used, making a total of six switches in all. One switch in each of the two sets of three is used to slow down the car while the other two operate in unison as a double pole switch to bring the car to a stand still.

In addition two single pole shaft limit switches should be used for protection against over travel.

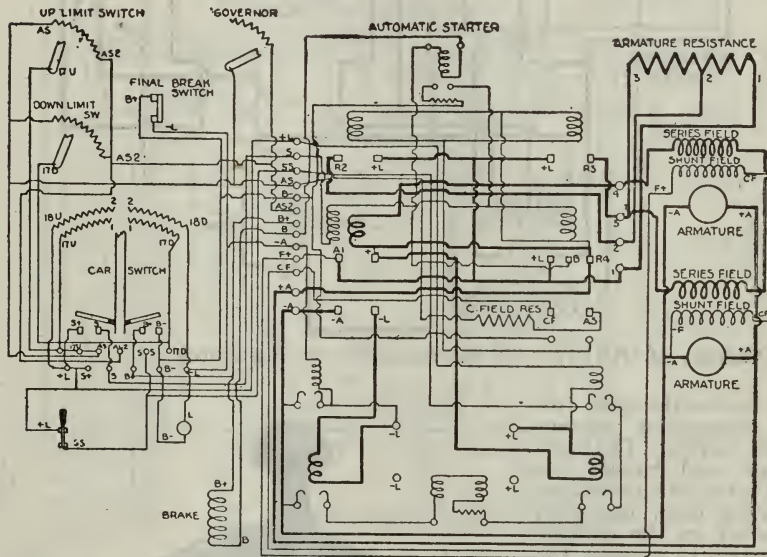


FIG. 4,166.—Diagram of Fraser direct current duplex motor controller.

Shaft limit switches may be installed so as to be operated either by the car or by the counter-weight, or by both.

**The Safety Switch.**—In order to insure the stopping of the elevator, even should some accident render the regular control from the car switch inoperative, a safety switch should be provided. This consists usually of a single pole switch enclosed in a cast iron box, the handle of the switch projecting through a slot in the enclosing case.

This safety switch is designed to be connected, by means of a separate three wire cable, to that part of the control circuit which is in the side of the line opposite to that in which the car switch is connected. The third wire in this cable is desirable as a spare. The opening of the safety

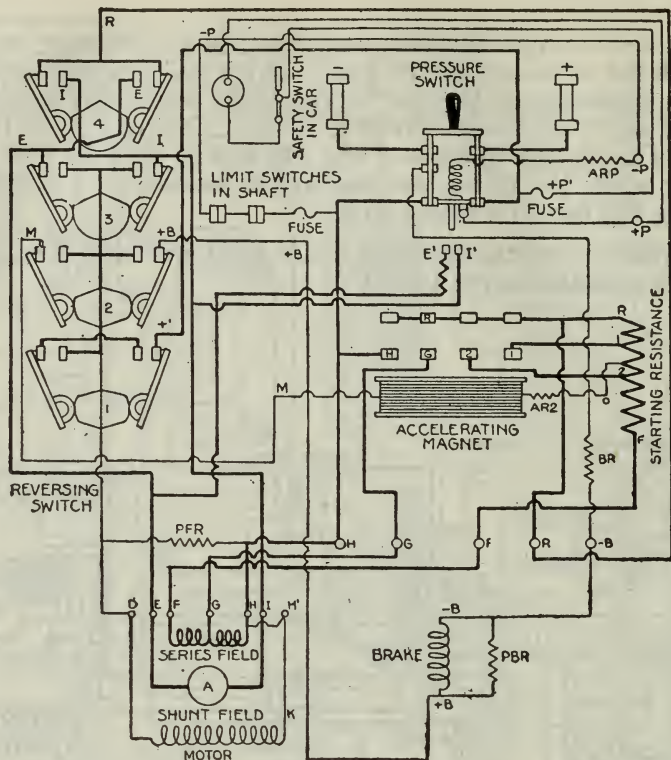
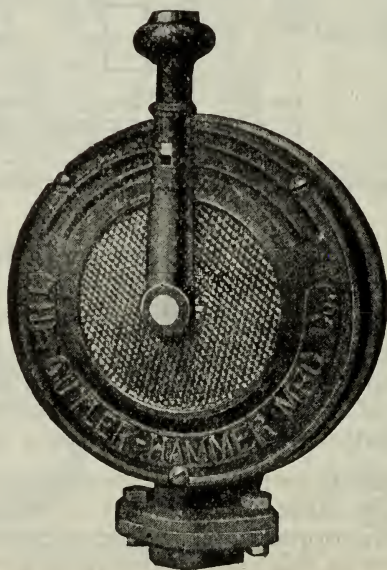


FIG. 4,167.—Diagram of Otis style 2H mechanical reversing switch.

FIG. 4,168. — Cutler-Hammer direct or alternating current elevator car switch. The operating lever and handle are mounted vertically on the front of the switch case, the lever being latched in the central, or off position to prevent the accidental starting of the elevator. **To release the latch** it is necessary to depress the button mounted in the top of the handle, this action occurring naturally when the operator places his hand on the lever to operate it. Should the operator remove his hand from the car switch while the elevator is in motion a centering spring throws the lever to the off position and brings the car to a standstill. This insures constant watchfulness on the part of the operator and serves also as a safeguard against accident should injury or illness befall the operator while the elevator is in motion.





switch will therefore entirely disconnect one side of the control system from the line, and this switch, in connection with the car switch, makes it impossible for any combination of ground or short circuit to prevent the operator stopping the car at will.

**Alternating Current Controllers.**—There are many types of alternating current controller, the best known being of the full magnet variety.

As previously stated alternating current motors should preferably be limited to moderate speeds, because it is not feasible

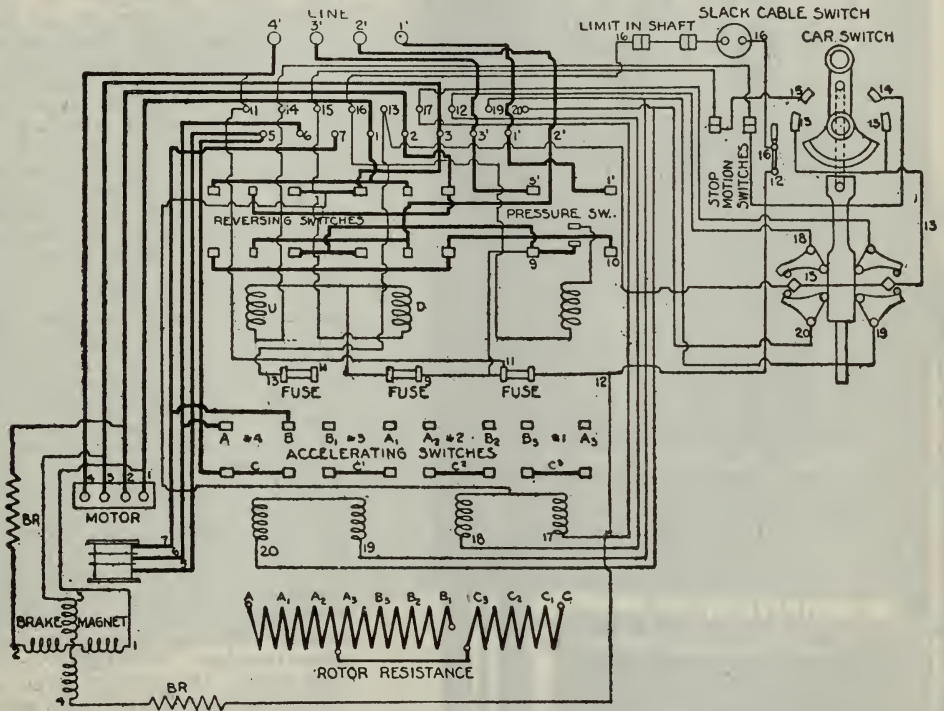


FIG. 4,169.—Diagram of Otis type VAS alternating current, two phase magnet controller.

to employ dynamic braking. This means that the car must be slowed down and stopped by the application of the solenoid brake alone, and the speed must therefore be one that will permit

**NOTE.**—Where old elevator equipments are being changed over to the full magnet system and the old motor is in such good condition that it is possible to use it with the new equipment, particular attention should be paid to the amount of speed variation that can be obtained from the old motor. Very few of the older elevator motors are designed for a wide range of speed variation by shunt field resistance.

this being done with safety and comfort under all the widely varying conditions met with in elevator service.

A typical alternating current full magnet controller consists of several slate panels mounted on an angle iron frame which serves also as a support for the resistance. Alternating current solenoid switches mounted on the face of the panel and

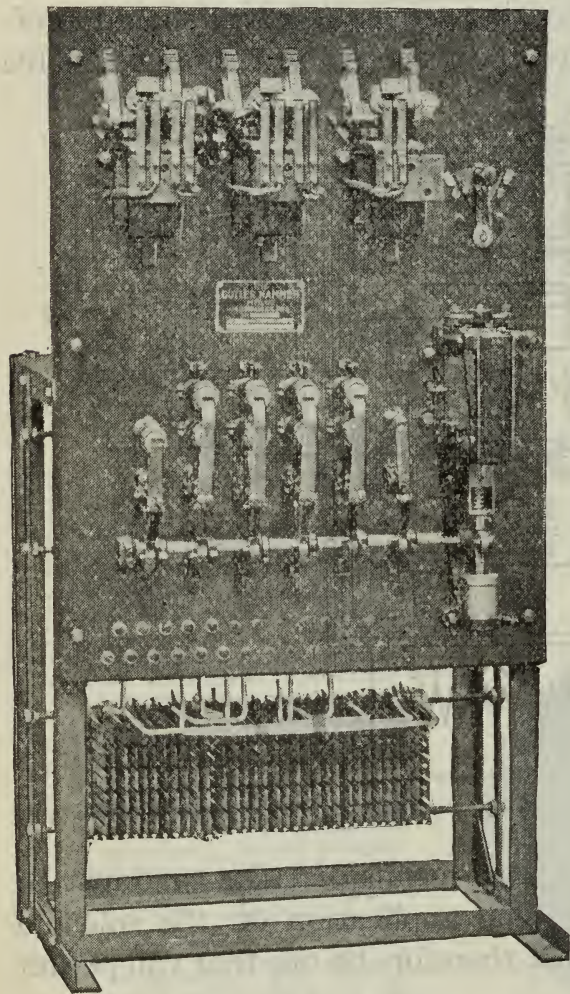


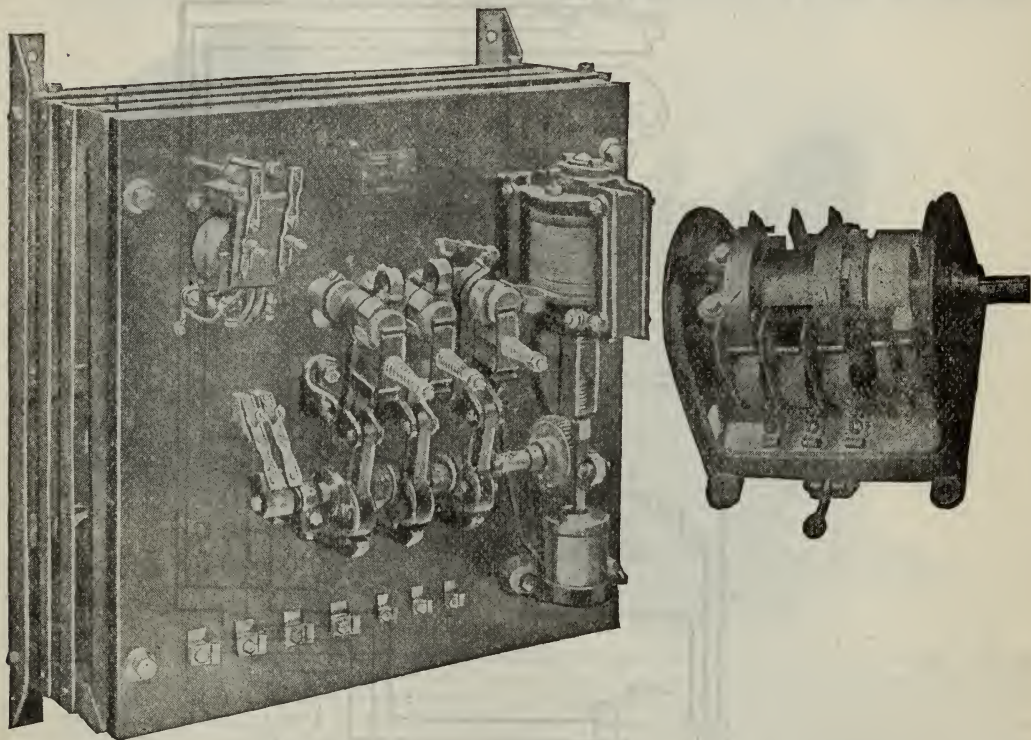
FIG. 4,170.—Cutler-Hammer, alternating current, reversible, single speed full magnet push button controller for slow speed passenger or freight elevators. It is suitable for two or three phase slip ring induction motors, 25 or 50 cycles, and also with self starting, single phase motors. The latter type motor should be provided with an interlocking connection to prevent quick reversals. Since there is no satisfactory and practicable method of reducing the speed of an alternating current motor under varying loads, the speed at which elevator cars may run when driven by such motors is limited and the problem is purely a matter of bringing the car to an easy and accurate stop. There are elevators driven by alternating current motors and operating satisfactorily at car speed of 275 to 300 feet per minute; however, in such cases the brake details have been worked out with extreme care so that a comparatively easy stop is made with widely varying loads, even for such a high speed. Ordinarily, however, it is not good practice to use alternating current elevator controllers for installation when the car speeds are likely to exceed 200 feet per minute. **In construction** of the controller here shown, the primary circuits are controlled by a double pole, solenoid operated main line switch and two double pole solenoid operated direction switches. The rheostat is of the solenoid operated crank acceleration type, retardation being effected by an adjustable vacuum dash pot. The starting resistance is of the cast grid type and is cut out in equal steps in each phase of the rotor winding, thereby keeping the

phases in balance at all times. The rheostat and the main line switch are so interlocked that it is impossible to make a quick reversal with the starting resistance cut out. A mechanical interlock is also provided between the two direction switches so that both cannot be closed at the same time. Test buttons mounted on the panel permit of the car being operated from the switchboard.



connected to the resistance (all connections being made at the back of the board) are arranged to perform the following functions:

1. To disconnect the primary wires from the motor and brake solenoid in the off position of the controller.
2. To accelerate the motor automatically by cutting the starting resistance out of the rotor circuit step by step (using series relay control) and giving smooth acceleration at all loads.
3. To operate the elevator from the switchboard for test purposes.



FIGS. 4,171 and 4,172.—Cutler-Hammer alternating current, reversible, single speed, semi-magnet controller with separate reverse switch for slow speed passenger or freight elevators operated by self-starting, single phase, special elevator type motors. Fig. 4,171, self-starter; fig. 4,172, reverse switch. **In construction**, the self-starter is of the crank acceleration type, using individual carbon contact levers for each step of resistance. The rate of accelerating is under control of a vacuum air dash pot. **In operation** the contacts in the drum reverse switch are not required to break the motor currents, but are used to reverse the motor connections. Auxiliary contacts in the switch, handle, and control circuit of the self-starter and the main circuits are made and broken on a special quick make crank switch actuated by the accelerating solenoid. The special motor which must be used is provided with an interlocking contact on the motor which is closed only after the motor has practically come to a standstill. Connection is made between this contact and the self-starter so as to insure reversal of the motor while running. The ordinary single phase, self-starting motor will not reverse from high speed unless this interlocking be provided. **Adaptation:** 25 to 60 cycles. Shaft limit switches may be installed in the elevator shaft if desired to stop the motor at the travel limits.

The secondary starting resistance is of the cast metal grid type and is mounted in a frame forming part of the switchboard support. Connections between grids and terminals and between the terminals and the various solenoid switches on the controller switchboard are usually made at the factory.

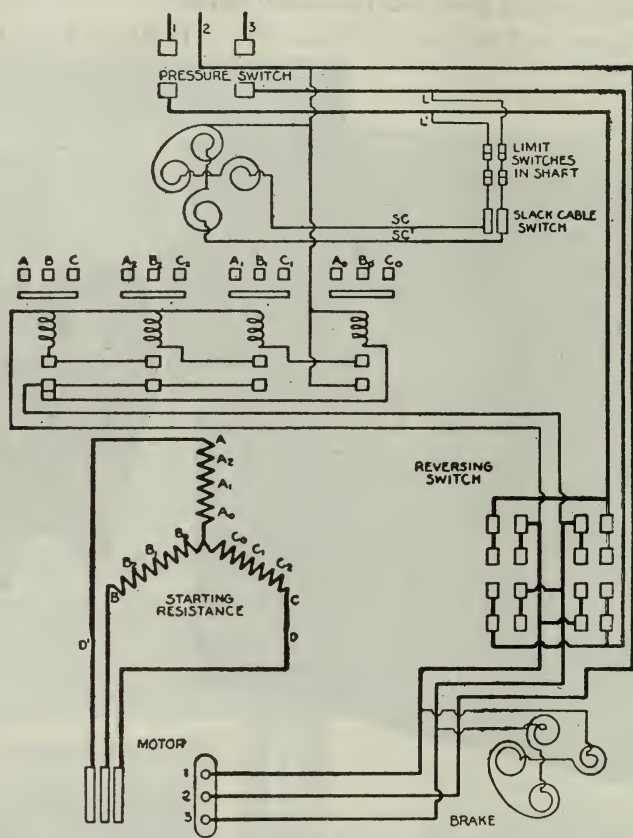


FIG. 4,173.—Diagram of Otis type alternating current two or three phase mechanical controller.

**Current Relay Acceleration.**—The acceleration of the motor is accomplished by a parallel solenoid self-starter with secondary starting resistance. A suitable number of double pole alternating current solenoid switch are used, these being so connected as to cut a section of resistance out of each of the three phases of the rotor circuit simultaneously, the rate of acceleration being governed automatically by a number of current relay in the rotor circuit. By suitable adjustment of these relays the starting current is limited to a predetermined maximum



**Ques.** What is the function of the relay?

**Ans.** It operates to lift and open the circuit to the succeeding switch when the starting current rises as each switch in turn is closed, thus preventing the cutting out of the next step of resistance until the motor has properly accelerated and the surge of current incident to the closing of the previous switch has died down.

**In construction** each circuit relay has three coils connected between its switch and the three phases of the rotor circuit. These relays govern the acceleration of the motor.

**Limit Switches.**—The automatic stopping of the car at the two limits of elevator travel, in the case of a drum type elevator machine,

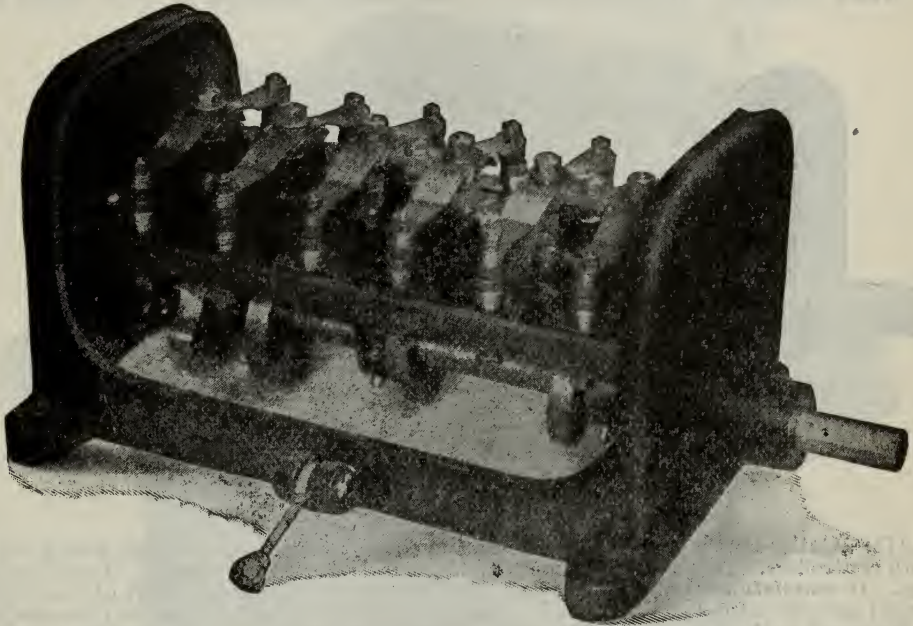


FIG. 4,174.—Cutler-Hammer direct or alternating current rotating cam limit switch for use with controllers in connection with the traveling nut mechanism of the winding drum machine. The limit switch is double pole, and in operating to stop the elevator, disconnects both sides of the control circuit from the line. **In installing** this type of limit switch the switch shaft is geared to the yoke of the traveling nut device on the winding machine, either by spur or bevel gearing. It is essential that a centering device be provided which will return the limit switch and the yoke of the traveling nut mechanism to the central position whenever the car moves away from either limit of its travel. The angular throw of the rotating cam limit switch is limited to approximately  $160^\circ$  on either side of the central position and it is necessary that the ratio of the gears between the traveling nut device and the limit switch be such that the elevator can be slowed down and stopped within this angular movement.

is usually accomplished by a limit switch of the rotating cam or traveling cam type. These switches are designed to open both sides of the control circuit to the solenoid switches on the controller switchboard, thus insuring the stopping of the car through the opening of the motor circuit.

Shaft limit switches may be used in place of the cam type limit switches, if desired, and should be used in the case of traction machines.

Two shaft limit switches should be used as over travel switches, in both cases, and should be so connected in the control circuit as to make it impossible for the operator to move the car in the reverse direction after over traveling without first going to the winding machine. This insures protection against phase reversal.

**The Brake Solenoid.**—This is designed to be connected directly to the motor terminals. When the circuit to the motor is closed, the solenoid is energized and the brake released. Upon the opening of the main line circuit (whether this be done intentionally in operating the elevator, or is the result of accident) the solenoid is de-energized and the brake applied. The operation of the brake solenoid is very rapid, and

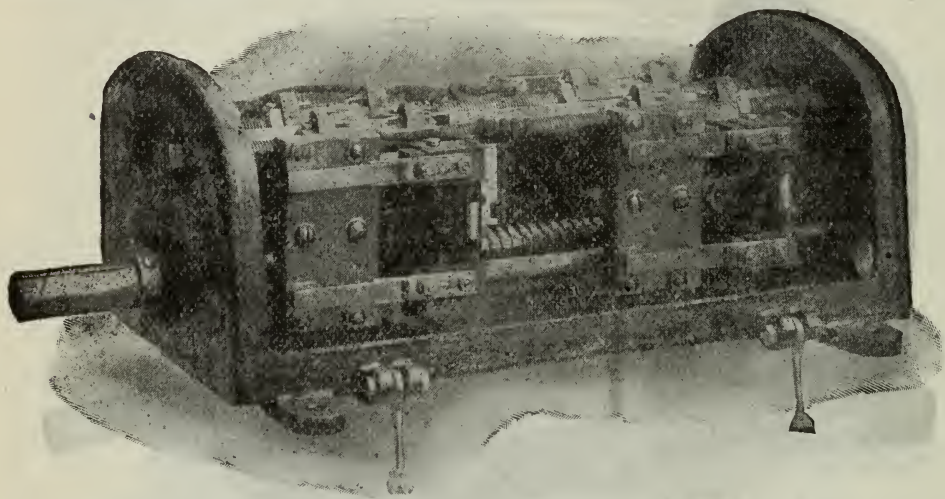


FIG. 4,175.—Cutler-Hammer direct or alternating current traveling cam limit switch for use with controllers. This switch has the traveling nut device incorporated in its own mechanism. **It consists of** a shaft (designed to be geared directly to the shaft of the winding drum) and threaded so as to drive a nut along its length as the car moves from one limit of its travel to the other. Double pole switches are mounted on rods parallel to the shaft of the limit switch, and adjustable on these rods with reference to the traveling cam. The cam itself follows the motion of the car, and as the latter approaches either limit of its travel, the cam trips out the switches, which in turn slow down the elevator and bring it to rest. The traveling cam limit switches may be mounted in any position but are preferably located above the drum shaft bearing so as to be out of the way of lubrication drippings. With both switches pointing inwardly the maximum number of turns that the shaft of the limit switch can make is 33, and the minimum 30. The best results will be obtained, however, when the switch is so geared to the winding drum that the number of turn made by the limit switch shaft for the full elevator travel is between 18 and 27, which is obtained with one switch pointing out, and one pointing in. With both switches pointing out, the range is from 7 turns to 20 turns of the limit switch shaft for the full elevator travel. The individual snap switches are reversible on their supporting rods, by reversing the corresponding cam at the same time.

the force applied to the brake considerable. It is recommended, therefore, that the parts of the brake mechanism used with these solenoids, be of rugged construction, a simple toggle or wedge mechanism being most desirable. It is desirable also that the brake itself be so



designed as to permit of a gradual, rather than a sudden braking effect, so as to avoid jarring the car by stopping it too quickly.

**The Transmission.**—The term “transmission,” as generally and erroneously used, denotes the system of gearing between the motor and drum; it properly includes the entire mechanism between the motor and car, that is, the gearing between motor and drum and the “final drive” or drum, cables and pulleys, for all

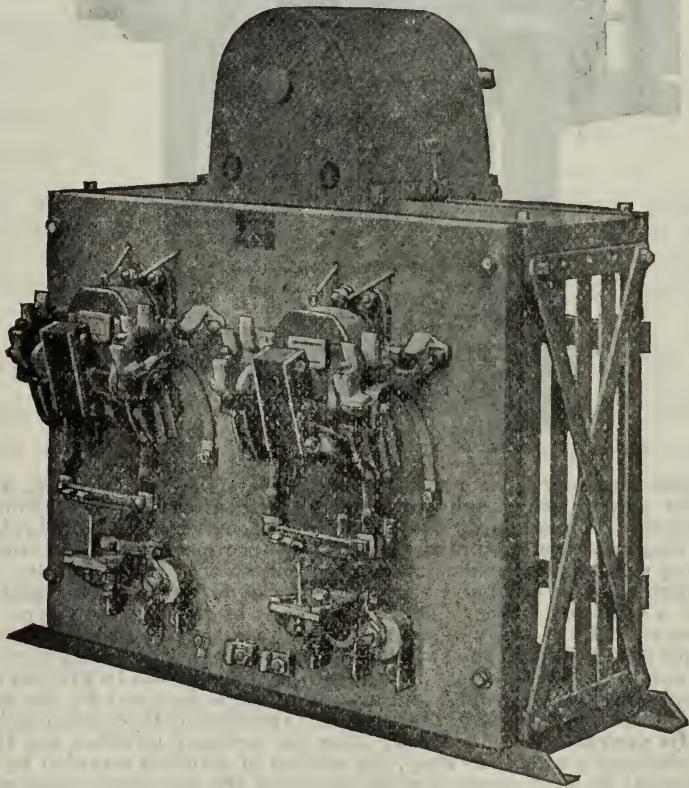


FIG. 4,176.—Cutler-Hammer alternating current, reversible, single speed, semi-mechanical controller with self-contained reverse switch for slow speed passenger or freight elevators; 25 to 60 cycle circuits with two or three phase slip ring induction motors where rated full load rotor circuit does not exceed 150 amperes per phase. *It consists of* a three pole drum type reverse switch and a secondary self-starter, the two being assembled on the same frame and inter-connected. The drum switch, which performs the functions of both line and reverse switch, controls the starting, stopping and reversing of the motor, and is designed to be suitably geared to the operating shaft of the elevator. As the reverse switch affords the only control over the line circuit, it is essential that the operating cable from the car be provided with a centering device. The acceleration of the motor is automatic and is accomplished by the secondary self-starter which is of the series relay type. Automatic stopping at the travel limits must be effected by the traveling nut device on the elevator machine.

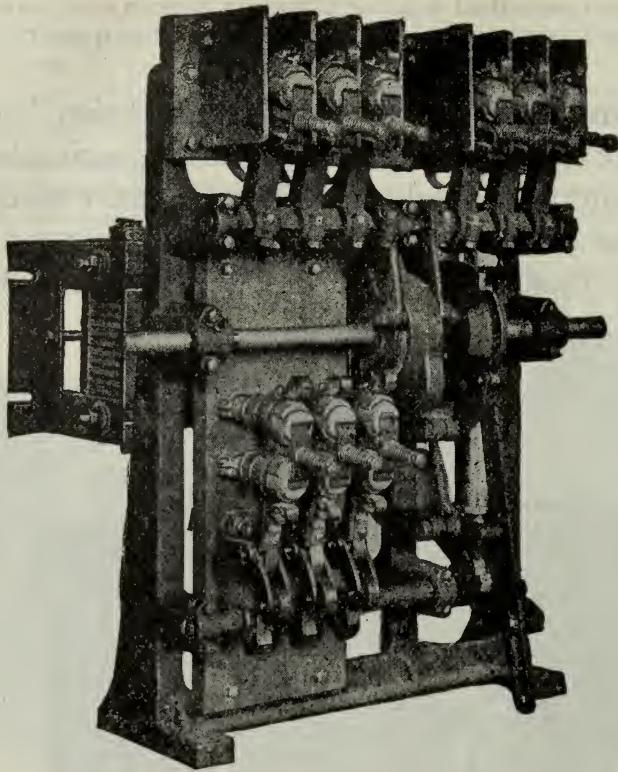


FIG. 4,177.—Cutler-Hammer alternating current, reversible, single speed, full mechanical controller for slow speed freight or passenger elevators; no electro-magnet or sliding contacts are used. It is primarily adapted for use in connection with polyphase alternating current slip ring induction motors and is arranged for rope or lever operation from the car. The operating shaft has an extension at each end so that the controller can be adapted for either right hand or left hand operation. **In construction** two separate panels are mounted on a cast iron frame. The resistance is of the cast grid type. The primary circuit is controlled by two sets of switch, each set consisting of three single pole switches, equipped with arcing shields, the switches being mounted on a square shaft and insulated. Each set is operated by a special internal cam, arranged so as to give an absolute knock out to the switches when opening, and also an absolute lock out for the second set when the first set is thrown in. Secondary resistance is cut out by three triple pole cam operated switches. **In operation**, immediately after the primary switches are thrown, a catch is released, allowing a weight to drop, the motion of which is retarded by a suction dash pot. The weight in turn drives a shaft on which the necessary cams are mounted for throwing in the secondary switches. The secondary resistance is cut out simultaneously in all three phases of the rotor circuit, thus insuring a balanced condition at all times. The secondary resistance is re-inserted upon the opening of the primary switches and a latching arrangement is also provided so as to prevent accidental operation of the controller, if the operating mechanism be not thrown to the central position. **In installing**, it is necessary to place heavy and substantial stops on the elevator machine so as to limit the angular throw of the controller operating shaft to 90 degrees from the central position in either direction of rotation. A notched star wheel gives an accurate indication of the "off" and "running" positions. Stops are provided on the controller in order to keep the parts in proper relation for shipment and to take care of excess overthrow of this shaft. They are not strong enough, however, to take the blow of the operating mechanism, and it is therefore necessary to provide stops of sufficient strength on the elevator machine.



these devices are used to *transmit* power from the motor to the car. The same mistake is made in the case of the automobile by ill advisedly using the word transmission to denote only the gear set, whereas it properly includes the entire system between the engine and rear axle, viz: clutch, gear set, propeller shaft, universal joints, bevel gear and differential.

Accordingly in the case of the elevator, the transmission consists of

1. Gearing between motor and drum;
2. Drum;
3. Cables;
4. Pulleys.

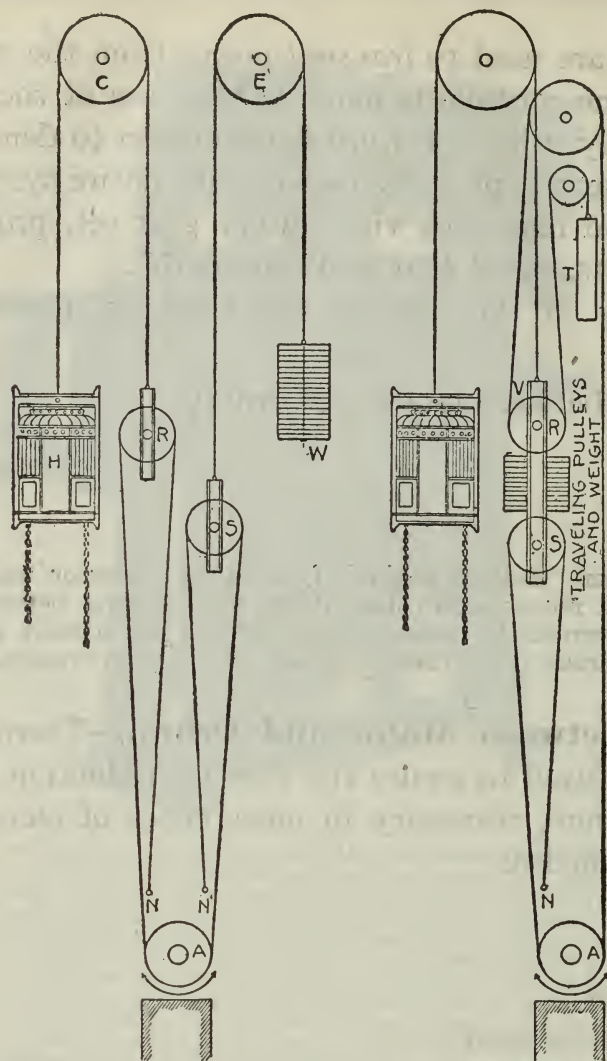
The term "electric engine" is used by elevator manufacturers to denote the motor, controller, drum and gearing between motor and drum. Presumably because these devices are usually incorporated in one unit, arises the erroneous usage of the term transmission.

**Gearing between Motor and Drum.**—There are several forms of gear used to secure the velocity reduction between the motor and drum, necessary in most types of elevator. These may be classified as

1. Belt;
2. Chain;
3. Spur gear;
4. Herringbone gear;
5. Worm and wheel gear.

**Belt Drive.**—In factories or other places where line shafting is kept running continuously elevators are sometimes driven from a countershaft, the latter being belted to the line shaft.

Very often the elevator machine is driven directly from the line shaft, and as the line shaft always runs in the same direction the only way in which the elevator machine can be reversed is by the use of two belts, one open and one crossed, as is done in the case of a metal planer in a machine shop; this form of elevator drive has already been described.



FIGS. 4,178 and 4,179.—Single motor traction drive with traveling pulleys. Fig. 4,178, primary form; fig. 4,179, modified form. This drive differs from the Fraser arrangement in that but one motor is used instead of two. The motor in this system runs at slow speed and, by means of the pulley A on the armature shaft, drives a set of cable, which passes under this pulley, thence over the traveling pulleys R and S, and has its free ends anchored at NN. The frames of the traveling pulleys are respectively connected by cables passing over the upper pulleys C and E with the car H and the counterweight W. **In the modified form**, the two traveling pulleys R and S are combined in a single frame V and a tension weight T is added as shown. **In operation**, the motor is controlled as usual from the car. It must be started to move the car and stopped to bring the car to rest. Both the car and counterweight move at half the peripheral speed of the driving pulley. If, however, the set of driving cable after passing over the pulley R and S be led under a pair of stationary pulley and then have their free ends connected respectively to the traveling frames R, and S, instead of anchored at the fixed points NN, the speed of the car and counterweight would be one-third the peripheral speed of the driving sheave. By further developing this plan, different ratios of car speed to motor speed can be obtained.



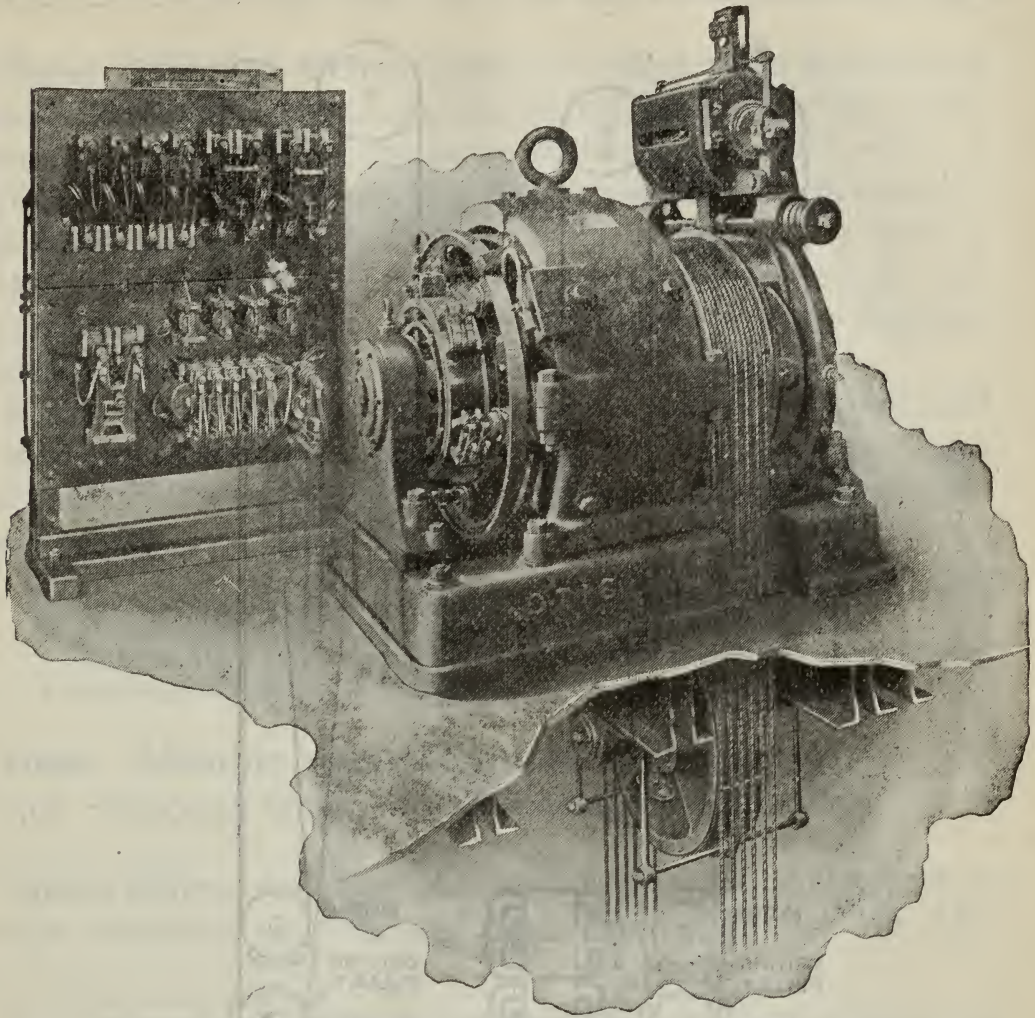
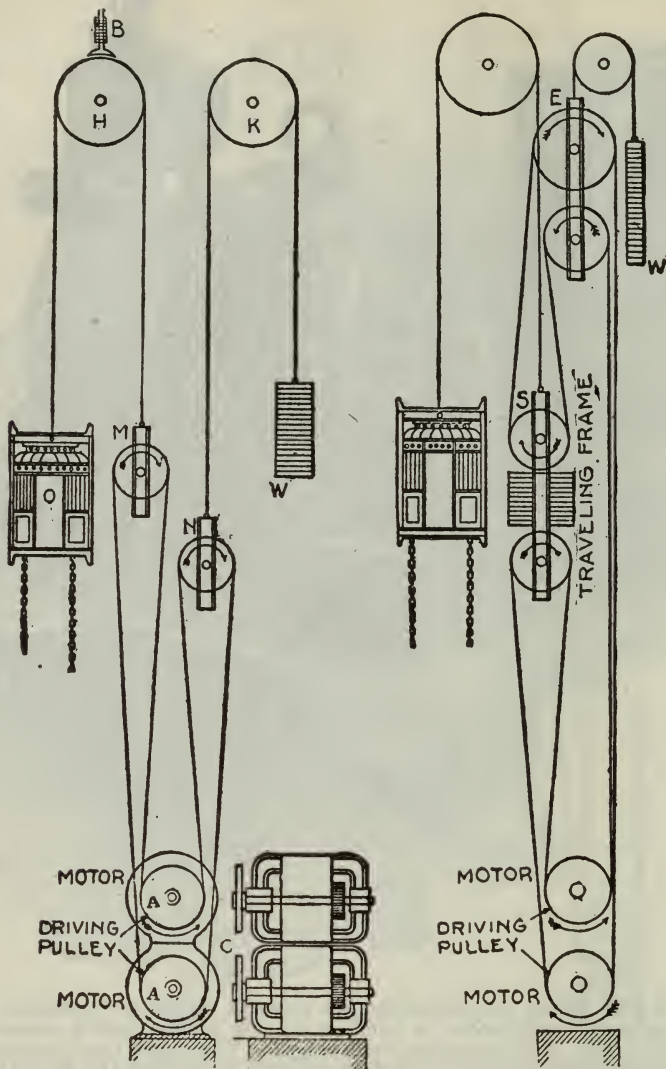


FIG. 4,180.—Otis 1 to 1 over mounted traction elevator machine, consisting essentially of a slow speed shunt wound motor, a traction driving pulley, and a magnetically released spring applied brake. Full magnet control is used. The motor is so governed as to prevent excessive speed regardless of load. Automatic slow down near the travel limits is secured, attained by two multi-arm switches located on the car, one for the up and one for the down motion. These switches are operated by cams in the shaft that open the contacts, one after the other, as the car approaches the limits of travel. This automatic feature being independent of the operator in the car, is effective even though the car operating device be left in the full speed position. The usual safety devices installed in connection with modern apparatus, are used with this type of elevator, including speed governors, wedge clamp safety devices for gripping the rails in case of the car attaining excessive speed, and pressure switches. One safeguard resulting from the arrangement and the method of driving the cables, is the decrease in traction which follows the bottoming of either the car or the counterweight on their oil buffers. This minimizes the lifting power of the motor, until normal conditions are resumed. Inasmuch as in any properly constructed elevator the roping is so arranged that the counterweight will rest on its oil buffer before the car reaches the overhead work, or vice versa, it therefore will be seen that the above mentioned decrease in tractive effort is a very valuable and effective safety feature inherent in this type of elevator.



FIGS. 4,181 and 4,182.—Fraser cable drive, designed to obviate the disadvantage of the large shaft space required for drum elevators in very high buildings, owing to the horizontal travel of the cables when winding. Fig. 4,181 primary form; fig. 4,182, modified form. **In the primary form**, the hoisting machine at C, consists of two motors, superimposed, each driving a set of endless cable by means of a pulley on its armature shaft. Two weighted sliding frames M and N, carrying pulleys, are driven by the endless cable. The frame M is connected to the car O by a cable passing over the upper pulley H, and the frame N is connected to the counterweight W by a cable passing over the upper pulley K. **In the modified form**, the traveling pulleys are combined in a single frame S, the tension on the endless cables being maintained by a weight W, acting on the pulleys in the frame E. **In operation**, when both motors are running at the same speed, and in opposite directions, the driving cables move without raising or lowering the car or counterweight. The motors, therefore, run continuously in the operation of the system regardless of whether the car be moving or standing still. A magnetic brake B, on the overhead pulley H, is operated when the car is to remain motionless, so as to prevent any slight variation in the speed of the



**Horse Power of Belts.**—There is considerable diversity of opinion in regard to the proper size of belt per horse power transmitted. If the working strain be 60 lbs. per inch of width, a belt one inch wide and traveling 550 ft. per minute will transmit one horse power; if the working strain be 30 lbs. per inch of width, a belt one inch wide traveling 1,100 ft. per minute will transmit one horse power. Numerous rules are given by different writers on belting which vary between these extremes.

A rule commonly used and one which can be recommended to give an amply large single belt for any service is: *a single belt one inch wide traveling 1,000 ft. per minute will transmit one horse power.*

This corresponds to a working strain of 33 pounds per inch of width. For double belts, twice the horse power may be transmitted.

Many writers give a safe practice for single belts in good condition, a working tension of 45 pounds per inch of width.

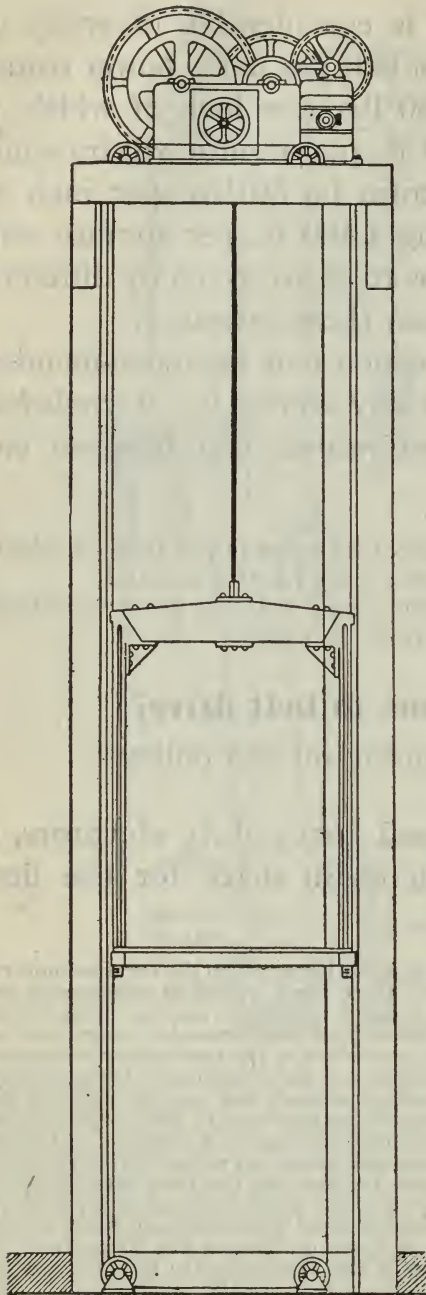
### **Ques. Mention some objections to belt drive?**

**Ans.** Slippage, breakage, and running off the pulleys.

**Chain Drive.**—On some slow speed heavy duty elevators, a double reduction gear is used with chain drive for the first

FIGS. 4,181 and 4,182.—Continued.

motors tending to move the car. When motion is to be imparted to the car, one motor is speeded up, and the other motor is slowed down, thus, there will be a difference in the heights of the two cable loops. This difference is taken up by the motion of the sliding frames which, in turn, transmit their motion to the car and counterweight, raising the one and lowering the other, or vice versa, depending upon which of the two motors be running the faster. The speed of the car in either case will be half the difference of the peripheral speeds of the driving pulleys. The motors are shunt wound, and run normally at 400 revolutions per minute. The speed of either motor can be increased to 520 revolutions per minute or diminished to 280 revolutions per minute by means of a rheostat in the car which introduces resistance in the field of one motor and cuts it out of the field of the other motor. With driving pulleys 19 inches in diameter, the operator can thus vary the speed of the car from zero to 600 feet per minute. Owing to the small diameter of the pulleys, a special kind of cable consisting of a steel wire core covered with manila or hemp is used to secure the requisite strength and flexibility. A diagram showing the connections for this system is given in fig. 4,166. The advantages of the Fraser type of elevator, besides small shaft space required for its operation, are rapid acceleration and quick stopping, and the ability to reverse from full speed in one direction to full speed in the opposite direction without producing excessive strains or shocks in the apparatus. To counterbalance these features are the first cost and the operating cost of the system, both of which are greater than for the drum type of elevator.



reduction and worm gear for the second reduction. There are various types of chain that may be used, such as link, roller, and the so called "silent" chain. The latter is extensively used because of its quiet operation, but has the objection that when the multiplicity of toothed bars of which it is composed, become worn, thus unduly elongating the pitch, it must be replaced with a new chain.

**Spur Gear Drive.**—This well-known method of transmitting power is extensively used in elevator practice. It is a "positive" drive, as distinguished from belt drive which is subject to slippage. For moderate speed motors or machines in which the speed reduction between the motor and drum is not too great, spur gearing is well suited.

Obviously, where great speed reduction is required, as in installation comprising a high speed motor and slow speed elevator it is not so well suited because of the large diameter of the drum gear required or the

FIG. 4,183.—Northern spur geared elevator machine for freight and foundry elevators. The frame for the hoisting mechanism is self contained. A slow speed motor is used. The machine can be either over or under mounted or below the ceiling of any story with the rope carried over the pulleys.



extra gears for double reduction necessary to obtain the necessary speed reduction. Clearly, such installations are best fitted with worm gear drive, as any speed reduction is easily obtained without the necessity of double reduction drive.

\*Prof. Harkness, as a result of his investigation on the strength of gear teeth, found that all the formulæ on the subject might be expressed in one of three forms, viz:

$$\text{horse power} = \text{CVPF} = \text{CVP}^2 = \text{CVP}^2\text{F}$$

in which C is a coefficient, V=velocity of the pitch line in feet per second, P=pitch in inches, and F=face of tooth in inches.

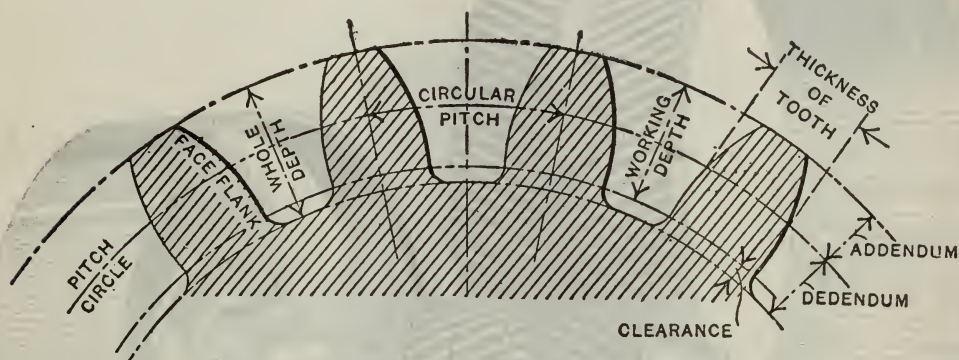


FIG. 4,184.—Gear tooth parts. **Systems of spur gearing.** Two systems of gear tooth are used for spur gears: the *cycloidal* and the *involute*. Of these, the involute system is the one more commonly used, especially for cut gearing. The standard involute gear tooth has a  $14\frac{1}{2}$  degree pressure angle, hence the rack meshing with gears cut according to this standard has straight sides inclined  $14\frac{1}{2}$  degrees from the vertical. **Definition:** *Circular pitch* is the distance from center to center of two adjacent teeth along the pitch circle. *Diametrical pitch* is a number found by dividing the number of teeth by the pitch diameter; that is, it gives the number of teeth for each inch of pitch diameter. **Internal spur gears.** The dimension of internal spur gears may be found by the same formulæ as those for external spur gears, except for the modification made necessary by the fact that the center distance in internal gearing is equal to the difference between the two pitch radii, instead of the sum. In addition, the term inside diameter takes the place of the outside diameter of external spur gearing. This diameter, of course, is the diameter of the hole in the blank before the teeth are cut. **In laying out** the shape of teeth for internal gearing, interferences are almost sure to be met with. The points of internal gear teeth must, therefore, be relieved to avoid interference with the flanks of the meshing teeth. **Interference occurs** also when the pinion has too nearly the same number of teeth as the gear. In this case there is a tendency for the points of the pinion and the gear teeth to strike as they roll into and out of engagement. To avoid this interference, the teeth must be cut by specially made cutters or shaped on a gear shaping machine.

NOTE.—The strength of gear teeth and the horse power that may be transmitted by them depend upon so many variable and uncertain factors that it is not surprising that the formulæ and rules given by different writers show a wide variation. In 1879 John H. Cooper (*Jour. Frank. Inst.*, July, 1879) found that there were then in existence about 48 well established rules for horse power and working strength, differing from each other in extreme cases about 500 per cent. In 1886 Prof. Wm. Harkness (*Proc. A. A. A. S.* 1886), from an examination of the bibliography of the subject, beginning in 1796, found that according to the constants and formulæ used by various authors, there were differences of 15 to 1 in the power which could be transmitted by a given pair of geared wheel.

From an examination of precedents he proposed the following formula for cast iron wheels:

$$\text{horse power} = \frac{.91 \text{ VPF}}{\sqrt{1+.65V}}$$

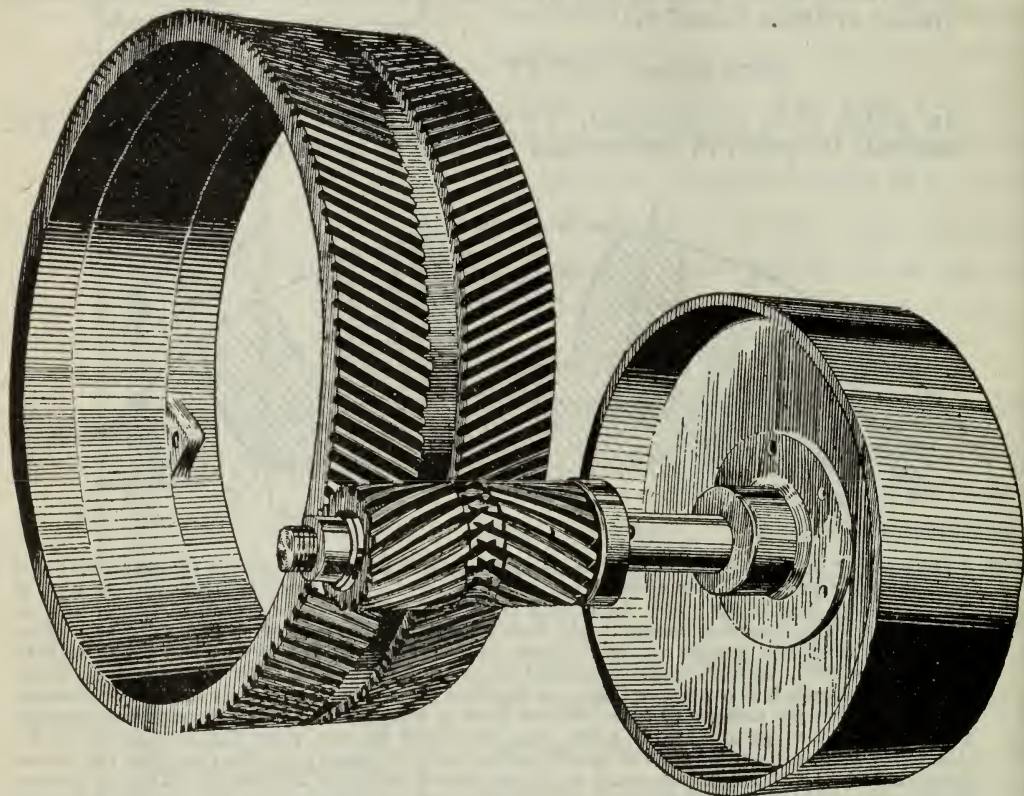


FIG. 4,185.—Gurney nerringbone gear, pinion, and brake pulley. The ratio between gears is about 5 or 7 to 1, and the teeth in gear and pinion converge from the center of its face outward at an angle of about 23 degrees. There is nothing new about this type of spur gear, as it has been in use for mill purposes for at least a century. It was originally designed to impart a smoother motion to the driven machines and also to give greater strength to the teeth, but until recently the only method of producing it was by casting and, of course, cast gears were not applicable to elevator service. The advantages of the herringbone gear are a minimum of friction as compared with the worm and worm gear; smoother running than with the teeth cut straight across the face; and greater strength due to the diagonal position of the teeth, which allows a greater number of teeth to be in mesh with the pinion at one time.

**Herringbone Gear Drive.**—This form of gear, sometimes called double helical tooth gear is a type in which right and left hand spiral teeth are both used.



The advantages of herringbone gears may be stated as follows: The action is continuous and smooth; there is no shock when the load is transferred from tooth to tooth, and therefore wear is practically eliminated; the bending action of the load on the teeth is less than with straight spur gearing; the gears work almost silently and without perceptible vibration; back lash is practically absent and herringbone gears can be used for high ratios and for great velocities.

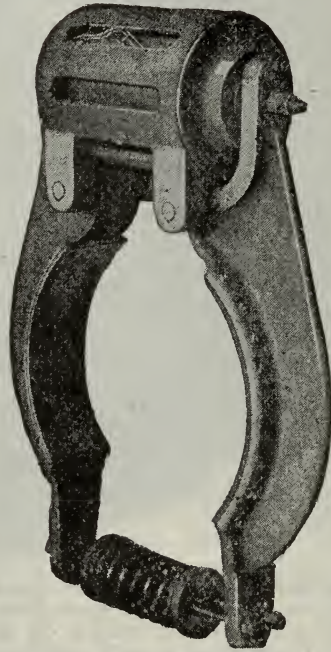


FIG. 4,186.—Detail of Kaestner and Hecht electric brakes. *In operation*, the brake is mechanically closed by the spring shown at the lower end, and electrically released by the solenoid at the top.

NOTE.—The fundamental principle of the action of herringbone gear teeth lies in the fact that all phases of engagement take place simultaneously for every position of pinion and gear, providing the relationship between pitch, width of face and angle of spiral is such that it insures a complete overlap of engagement. Since all the phases of engagement occur simultaneously, it is evident that the load is partly carried by tooth surfaces in sliding contact and partly by surfaces in rolling contact. The portions of the teeth farthest from the pitch line, which engage with sliding action, tend to wear away more rapidly than the portions nearest to the pitch line. The pitch line portion, however, is always carrying part of the load and the effect of wear at the ends of the teeth merely is to throw more load on the center portions, or in other words, there is a constant tendency to concentrate the load near the pitch line.

**Ques.** Describe the Wuest system of herringbone gears.

**Ans.** The right and left hand sides of the gears are stepped half a space apart and do not meet at a common apex at the center of the face, as in the usual type of herringbone gear.

This stepped form wears more evenly under extreme loads than the ordinary type.

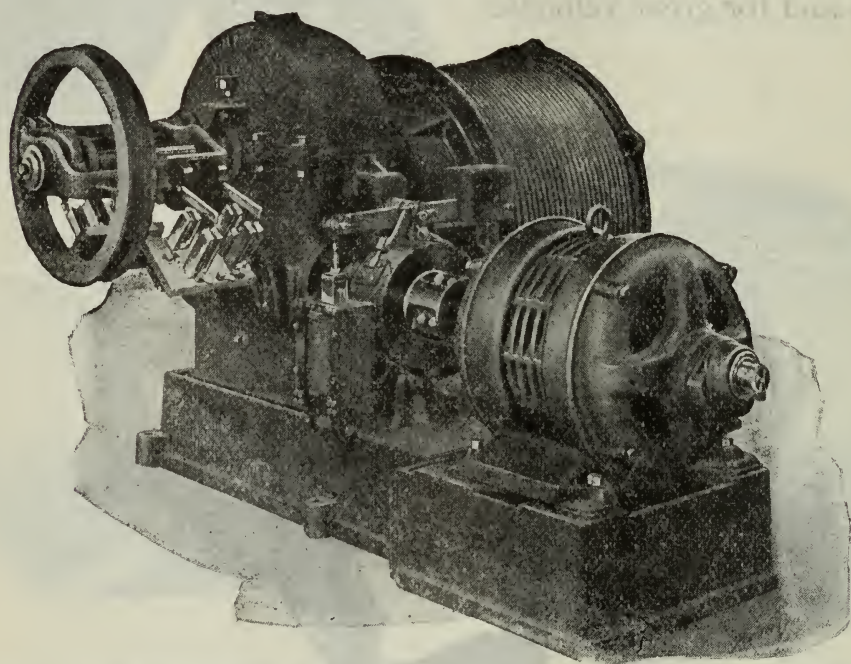


FIG. 4,187.—Albro-Clem internal geared electric elevator engine. This machine is sometimes furnished without internal gears, mounting the drum directly on the worm wheel shaft, using slightly higher pedestal and out board bearing on the drum. Either method being part of standard equipment. The internal geared machine is used for large capacity, slow speed elevators, while the omission of internal gears reduces the capacity and increases the car speed. This machine is built for either a. c. or d. c. current, using either electric or mechanical control in the car.

**Worm Gear Drive.**—This form of gear is very extensively used and is especially suited to slow speed elevators driven by high speed motors. A feature of worm gear drive is that it is self-locking because of the high velocity ratio, that is to say, no change in the loading of the car will produce movement.



**In construction** the gearing is enclosed in a cast iron box or casing which serves to protect the gears from dust and also to form a reservoir for oil used for lubrication. The worm is generally placed below the gear, in order that the worm may run in an oil bath. There are two kinds of gear:

1. Single gear;
2. Double or tandem gear.

**Ques. Describe the single gear.**

**Ans.** The worm is direct connected to the motor shaft, and in operation when it revolves, the spiral thread of the worm produces an endwise motion similar to that of a screw in a nut, but as the worm is prevented moving sidewise by a *thrust bearing*, it transmits motion to the teeth of the gear with which it meshes and causes it to revolve. This motion is transmitted to the drum which winds and unwinds the hoist cables.

**Ques. What is the undesirable feature of single worm drive?**

**Ans.** End thrust.

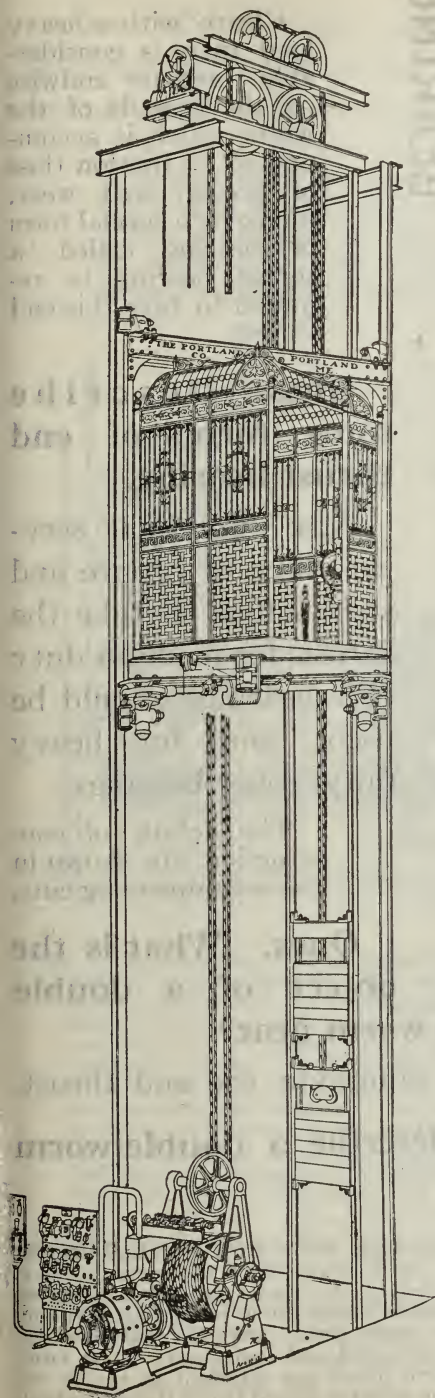
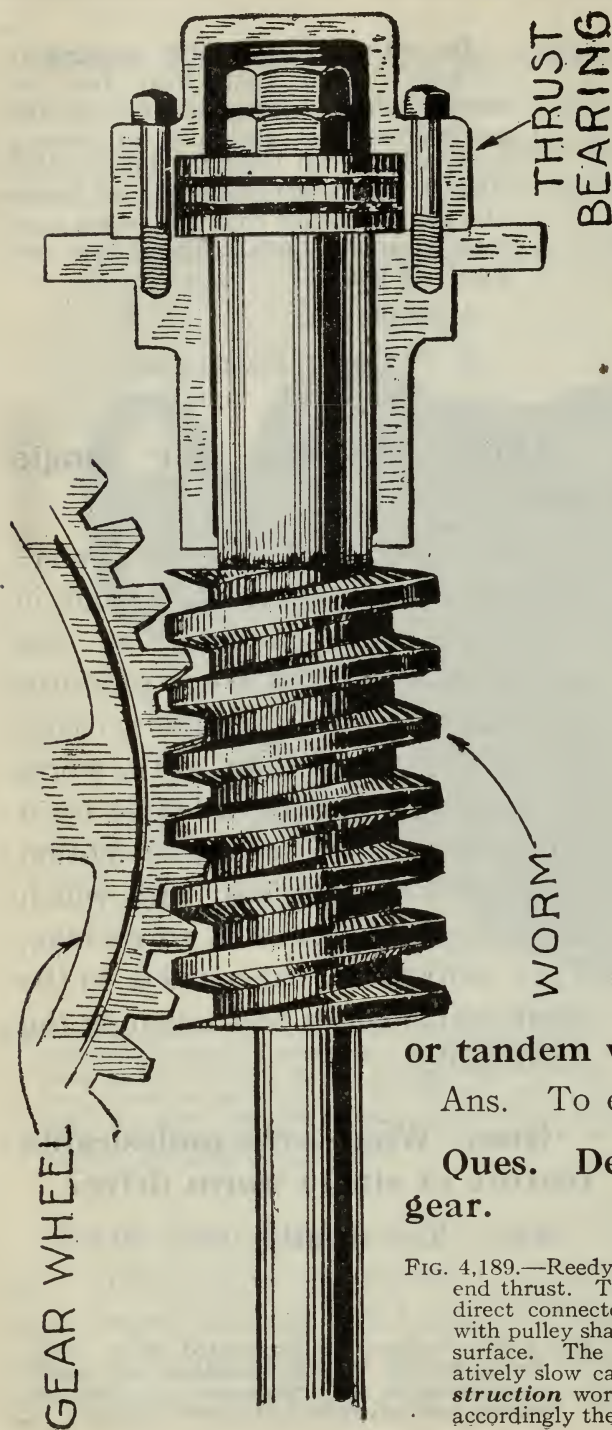


FIG. 4,188.—Portland undermounted worm drive drum elevator showing machine, car, shaft, counterweights, and arrangement of cables and pulleys, also controller and safety devices.



Clearly with a heavy load there is considerable pressure endwise on the threads of the worm which is accompanied by friction (loss of power) and wear, moreover a special form of bearing called a thrust bearing is required to take this end thrust.

**Ques. Describe some forms of end thrust bearing.**

**Ans.** For light service, discs of bronze and steel suffice to take the thrust; for medium duty ball bearings should be used; and for heavy duty, roller bearings.

The details of construction are shown in the accompanying cuts.

**Ques. What is the object of a double or tandem worm gear?**

**Ans.** To eliminate the end thrust.

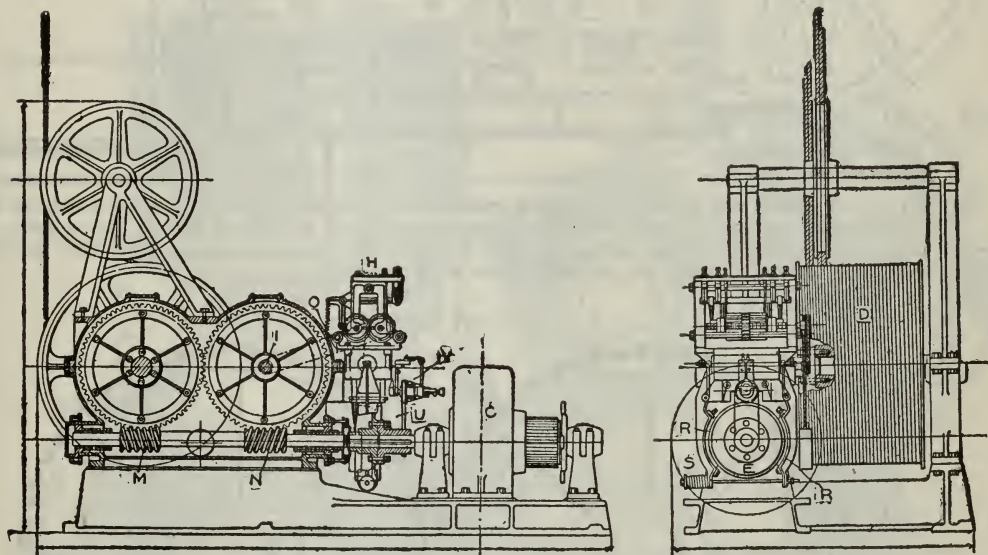
**Ques. Describe a double worm gear.**

**FIG. 4,189.**—Reedy single worm drive with ball bearing end thrust. The shaft on which the worm is cut is direct connected to the motor through a coupling with pulley shaped flange which is used as a braking surface. The single worm drive is suitable for relatively slow car speed and light loads. *In construction* worm drives are arranged to run in oil, accordingly the worm is placed below the gear wheel.



Ans. Two worms, usually forged solid to one shaft are employed; one, a right hand worm, and the other left hand. These worms mesh with two gears of equal size.

As originally designed by the inventors, the worm gears used were made with straight faces, the teeth being cut at the angle of the thread of the worm, and the gears were set so that they meshed together as in fig. 4,190 and 4,191. Later some makers used spur gears in addition to two worm wheels and bolted them together in pairs as in figure 4,192.



FIGS. 4,190 and 4,191.—Early design of tandem worm drive machinery in which the two gear wheels meshing with the two worms, mesh with each other. *In construction*, the gears are of bronze, cut on a spiral gear cutter, and the worms are a part of the steel worm shaft. The motor C is equipped with self-aligning, self-oiling bearings. Drum D is secured and driven by six coupling bolts fitted into a flange forged to the drum shaft. An electro-mechanical brake is used, the friction arms or shoes, RR, are made of cast iron, lined with cork formed to fit the brake wheel E. The pressure is applied by a spring S and released by energizing the magnet. The limit stop device is mounted on the brake magnet, and is driven by a sprocket chain O from the gear shaft I. The slack cable device consists of a balanced bar under the drum which acts upon the controller to stop the motor upon the slacking of the ropes. A centrifugal governor at V, driven by a belt U, from the worm shaft, applies the brake whenever the normal speed is exceeded. It will be noted that the casing around the worm drive forms a reservoir allowing the worms to run in oil, thus securing the most efficient lubrication.

The spur gears were enough larger in diameter than the worm gears to prevent the latter meshing.

Another and better construction is to use two spiral gears meshing together with the worms driving them.

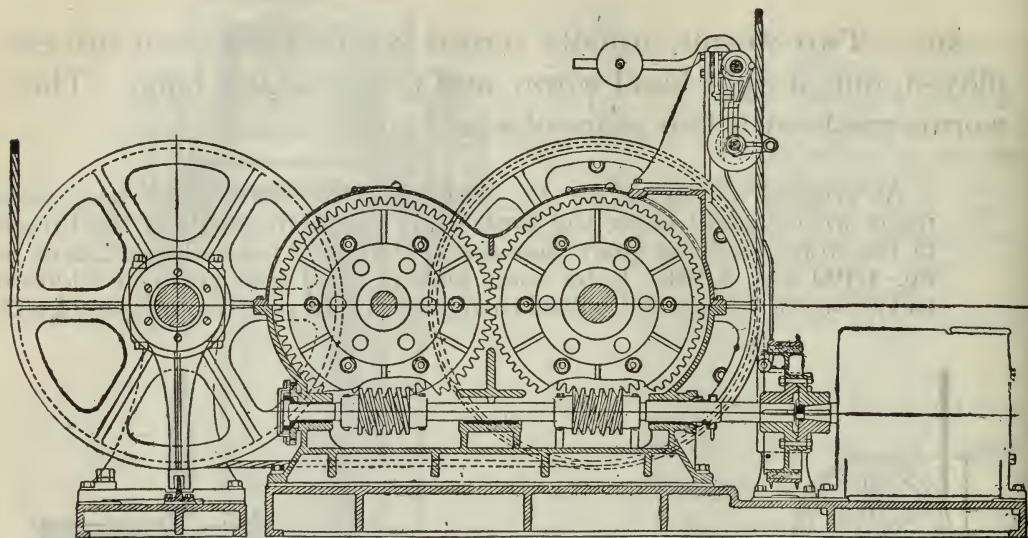


FIG. 4,192.—Tandem worm drive machine with independent concave face gears meshing with the worm as shown by the portions of the larger gears cut away above the worms. As shown, there are four gear wheels bolted together in pairs, the two larger ones meshing with each other, and the two smaller ones with the worms.

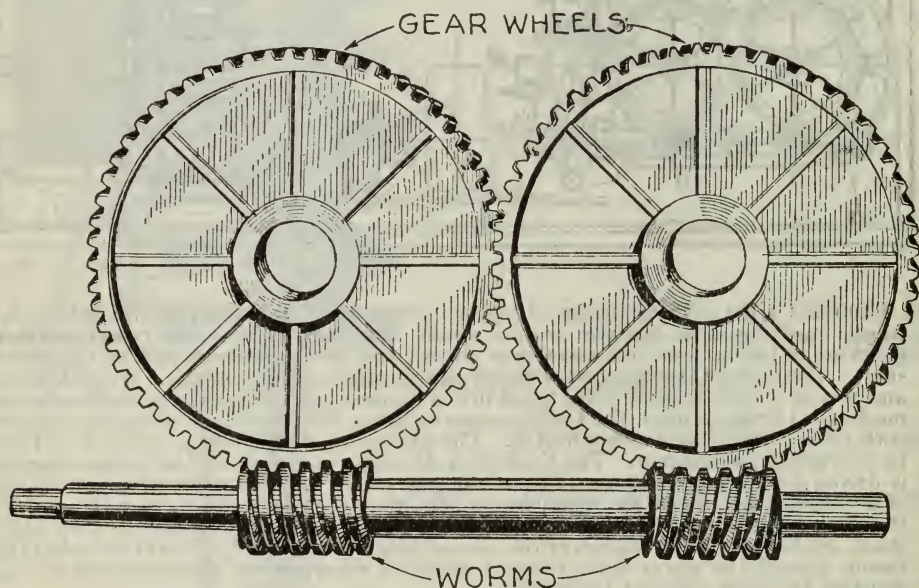


FIG. 4,193.—Reedy tandem worm drive. This type differs essentially from the single worm drive in that intermeshing right and left hand gears are used in place of the single gear. The use of the double gear has the advantage of dividing the pressure between the worm and gear so that greater loads and speeds are obtainable than are advisable with the single gear. The manner in which the gear wheels and worms intermesh produces, moreover, a three point contact which permits the gearing itself to compensate for any end thrust of the worm shaft, thus eliminating the necessity of thrust bearings.



### Double Reduction Worm and Internal Gear Drive.—

For very slow heavy duty freight elevators, operated by high speed motors, the excessive speed reduction necessary is best obtained by double reduction drive employing a combination of worm and internal spur gear.

The general arrangement is shown in fig. 4,194, in which the worm drives a large spur gear which has attached to its shaft a pinion meshing with the internal gear on the drum.

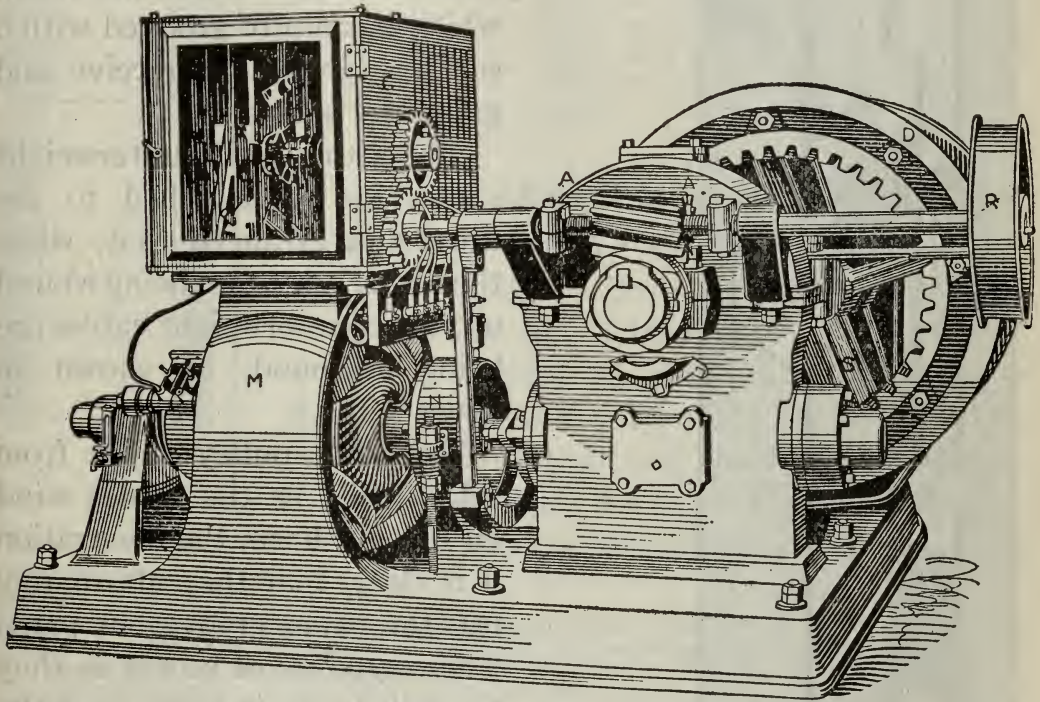


FIG. 4,194.—Warner internal spur gear freight elevator machine, fitted for mechanical control. The gear spider S and drum D are made in one casting with a heavy cast iron neck between them. On top, the motor M, is the controller box C, containing the switches and rheostat. N, is the brake, R, shipper pulley, and A A, the limit stop.

**Ques. Why is an internal gear used?**

**Ans.** In order that the drum will rotate in the same direction relative to the worm as in single reduction gear.

It is desirable that the drum in lifting the load should revolve so as to bring the thrust of the end of the worm shaft toward the back end of the gear case.

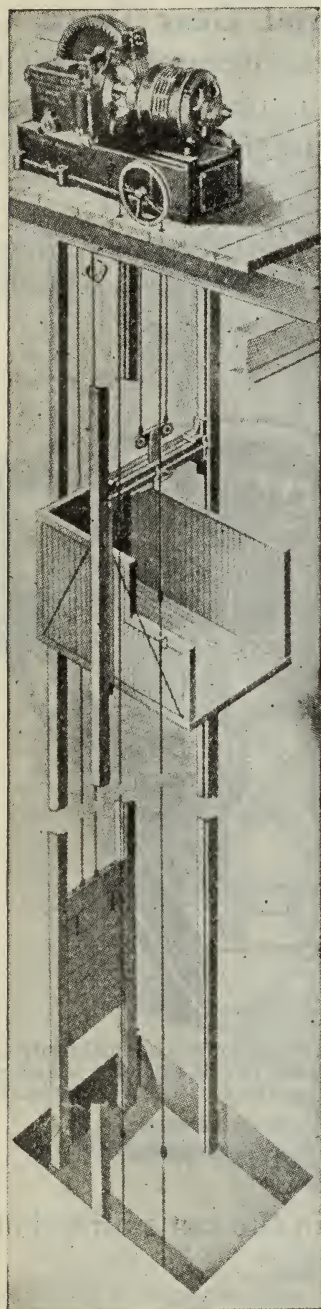


FIG. 4,195.—Albro-Clem internal gear worm drive freight elevator.

**Drums, Cables, Pulleys, Counterweights.**—These devices constitute that portion of the transmission that may be called the *final drive*.

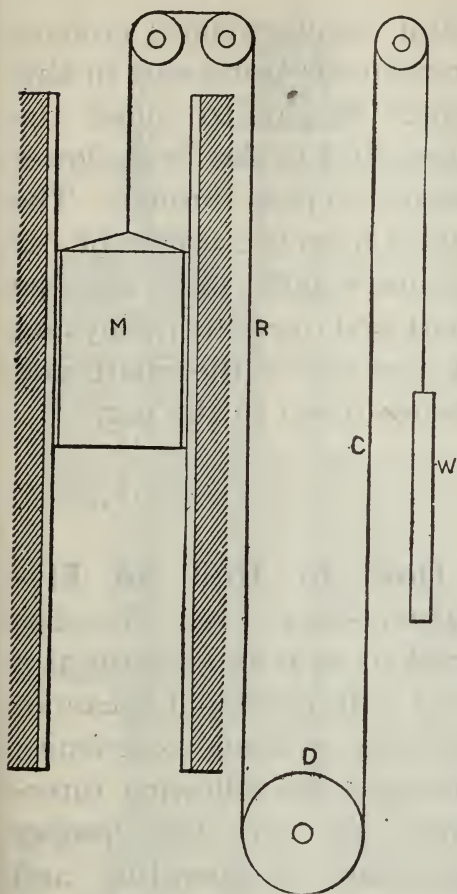
On winding drum machines, the lifting and counterweight cables are attached to the drum, which is spirally grooved with a concave groove to receive and guide the cables.

The lifting and counterweight cables are so attached to the drum and arranged that, while the lifting cables are being wound up, the counterweight cables are being unwound, as shown in figure 4,188.

The idler pulley slides from side to side as the cables wind on or off. From the illustration it is clear, that they alternately use the same grooves in pairs. These grooves or scores as they are called, are, in the case of the overhead type, so made, that they run from the end of the drum toward the center one grove on each side

**Ques.** In the case of the overhead type, how are the grooves or “scores” made?





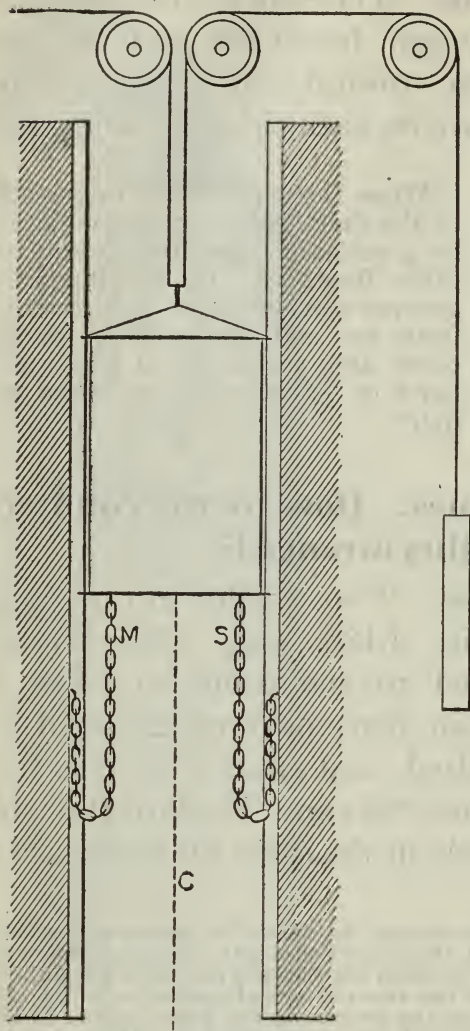
Ans. They are so arranged that they run from the ends of the drum toward the center, one groove on each side.

When the engine is set to one side of the shaft, either on a foundation or a suitable frame on one of the other floors of the building, the grooves run in pairs side by side from one end of the drum to the other and are made to lead right hand or left as the conditions require.

**Ques.** How are the counter-weights arranged?

Ans. Two weights are used, as in fig. 4,188, one, which is attached to the drum to offset a certain percentage of the load to be lifted, and another to counter-balance the car. The latter weight travels in the same runways as the

FIG. 4,196.—Usual method of proving the counterweight. As shown the counterweight W is joined to the drum D instead of to the car M, the connecting cable C, being wound around the drum in the opposite direction to that in which the hoisting rope R is wound, and anchored thereto. As the drum rotates, the two ropes or sets of rope move in opposite directions; the one set is therefore wound into the grooves on the drum left free by the unwinding of the other set. The counterbalance is generally given a weight equal to the weight of the car and its fixtures plus the weight of the average live load. When the average load is being carried by the car, the elevator is balanced, and the motor need then furnish only sufficient power to start the car and keep it moving against frictional resistances. With a live load in excess of the average, the motor will be required to furnish more power in raising the car and less power in lowering it. Thus, with a load in the car equal in weight to the maximum load, the power supplied by the motor on the up trip must be sufficient to raise the number of pound represented by the difference between the maximum load and the average load. On the down trip, however, the maximum load may be sufficient to lower the car without requiring any power from the motor. On the other hand, if the car be empty on the down trip, the motor must provide sufficient power to raise the weight of the counterbalance which, as previously stated, is generally equal to the weight of the car and its fixtures plus the weight of the average live load. In ordinary passenger service, the average load carried by an elevator is usually less than one-half the maximum load for which the car is designed, very often not more than one-third the maximum load.

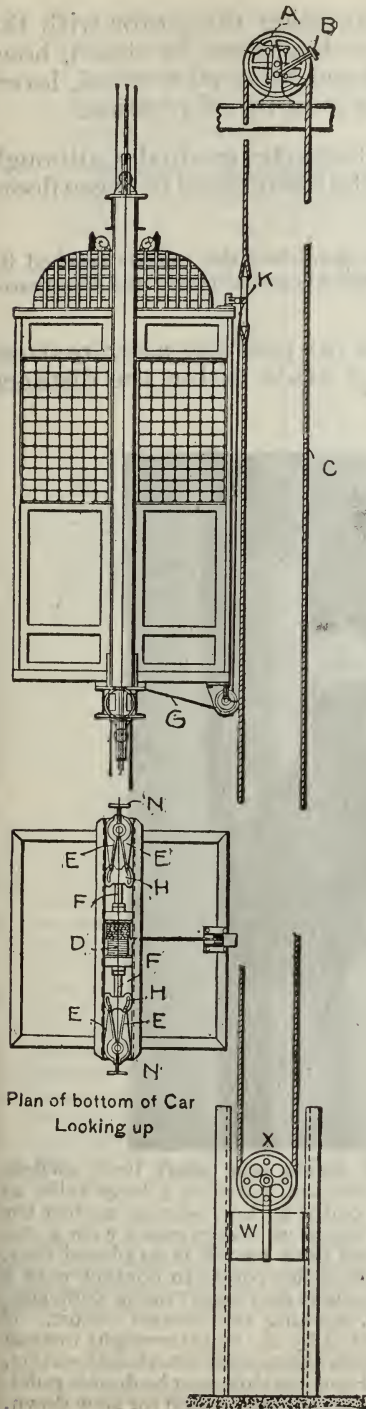


drum counterweight, grooves or channels being cast in this upper weight to allow the supporting cables for the lower weight to pass through. The cables from the upper or car counterweight pass up the shaft and over the pulleys set at the top of the shaft and thence down to the car.

**How to Run an Elevator.**—Any one who has tried to stop an elevator at a floor will agree that it cannot be done without experience; however, the following directions as to the proper procedure in operating and taking care of the plant will be found of value.

FIG. 4,197.—Compensating chains to counteract the varying factor introduced while the car is in motion by the changing length, and therefore changing weight, of the hoisting rope between the top of the car and its overhead pulley and also of the counterbalance cable between the counterweight and its overhead pulley. In installations where the cars make long trips, the weight of the ropes that ordinarily would have to be counterbalanced varies between wide limits. By the use of balancing chains hung from the bottom of the car, the problem is simply and effectually solved. These chains do not alter the total amount of power required per trip, but make the consumption of power nearer uniform throughout the trip. There may be but one balancing chain attached directly beneath the center of the car and allowed to hang all the way down the shaft as at C, or else two chains M and S, each of equal weight and about half the length of the chain C, may be attached to the bottom of the car and fastened at the middle of the shaft as shown, so that they hang in a loop in the shaft and travel up and down with the car. In either case the total weight of the balancing chain or chains must be equal to the weight of rope to be balanced. The chief objection to chains as compensators is the noise.





FIGS. 4,198 and 4,199.—Elevator safety consisting of wedges forced apart by right and left hand threads turned by a drum. This method gives a varying pressure which gradually increases as the drum turns, and consequently produces an increasing retardation of the motion of the car. The governor A, is bolted to the beams at the head of the shaft, and is connected by the ropes C and G with the drum D, shown in the plan of the bottom of the car, looking upward. The rope C passes over the governor wheel A, and around the wheel X, which latter carries a tension weight W, at the bottom of the shaft. Owing to the spring clip K on the car, this rope under normal conditions moves with the car. If, however, the speed of the car increase above the point at which the governor is set, the arm B of the governor flies out and grips the rope, preventing its further movement. As the car continues to descend, the spring clip K is forced to release its frictional hold on the rope C, which latter then causes the drum D to turn. A right and left hand nut inside of the drum D is thus turned, forcing apart the two screw shafts FF; these acting on the wedges HH and steel jaws EEEE cause the latter to grip the guide rails NN and gradually stop the car. The jaws may be released from the rails by turning the drum D in the opposite direction to that in which the rope rotated it.

Plan of bottom of Car  
Looking up

**Before Starting.**—The main switch connecting the motor with the supply circuit must be closed. This switch should not be closed, however, until it is positively known that the hand rope, pilot wheel, lever, or switch of the operating device in the car is in its off position.

**Starting.**—In all cases in order that a reasonable the acceleration must be

In starting, considerably more normal speed, and the more abrupt the stress in the various parts of the

**Stopping.**—An abrupt on the braking apparatus.

the car should be started gradually, although average speed be maintained between floors rapid.

power is required than after the car has reached its start the greater this abnormal power and the greater equipment.

stopping of the car produces a severe stress If the stops be made within the distance

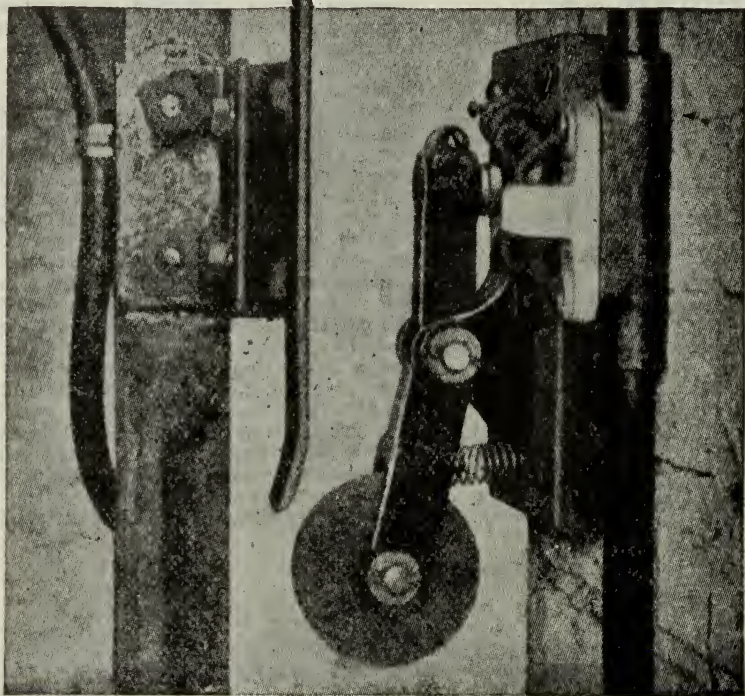


FIG. 4,200.—Cutler-Hammer direct or alternating current single pole shaft limit switch.

**It consists of** a slate base on which is mounted a pivoted arm carrying a large roller at one end and a carbon contact button at the other. A coiled spring, bearing against the roller end of the pivoted arm tends to keep the carbon button in close contact with a stationary carbon contact. When mounted in the shaft, the limit switch is so placed that, should the car fail to stop before reaching the switch, the roller comes in contact with a cam surface on the car and is forced back a little, this slight movement being sufficient, however, to raise the opposite end of the pivoted arm, opening the control circuit. If preferred, the switch can be so placed that it will be operated by the counterweight instead of by the car. Where shaft limits are used throughout as in the case of traction elevators, ordinarily one shaft limit is used for slow down, two for final stop (as this must be double pole). For speeds over 300 feet per minute, additional limit switches should be used for slow down.



that the operator can see the landing at which he aims, the best results will be obtained for moderate speed cars. This allows the operator about eight feet in which to bring the car to a stop from full speed. A skillful operator can readily do this, but an unskillful one may require a much longer distance.

**Sudden Reversal.**—On account of the waste of power and the strain on the apparatus, it is advisable not to suddenly reverse the direction of travel of the car; also, to bring the floor of the car on a level with the landing at the first stop, not run past and then back up, or stop too soon and thus have to start and stop again.

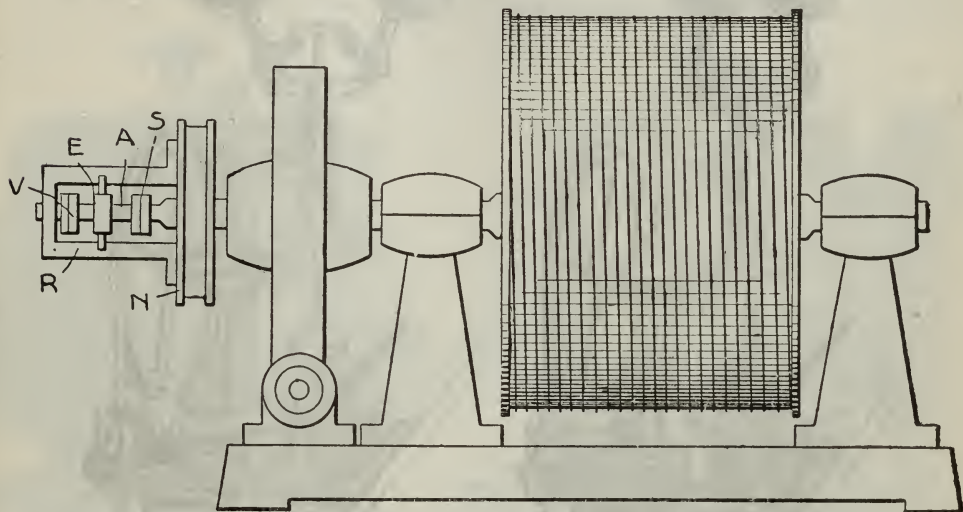


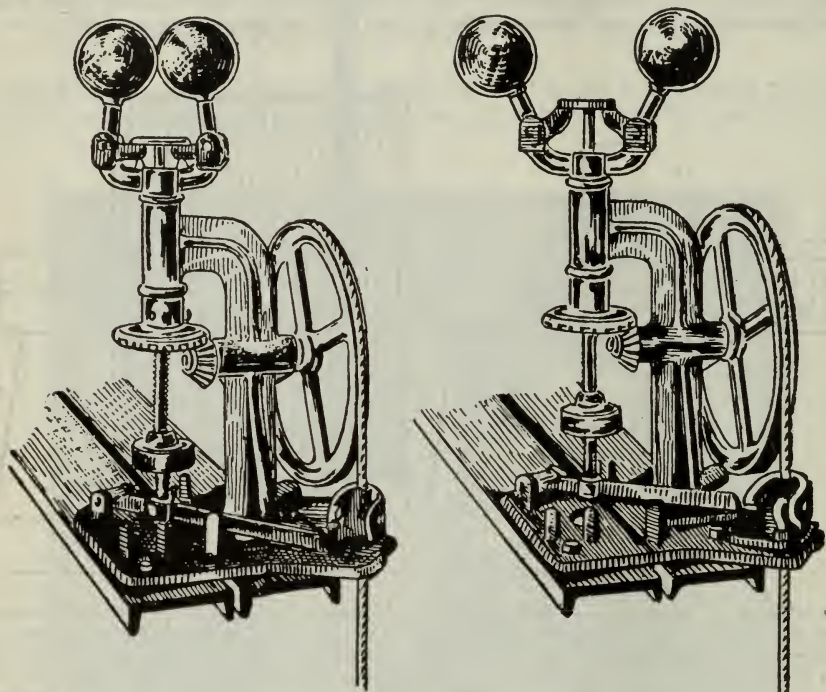
FIG. 4,201.—Machine limit stop or safety device placed on the machine to prevent over travel in case the stops on the shipper rope become inactive by the breaking of the rope. **It consists of** a threaded extension A on the drum shaft upon which a traveling nut E moves in a fixed ratio to the movement of the car. The shipper rope pulley N is on that portion of the drum shaft which is not threaded, and carries a bracket R that extends over the threaded portion. Owing to two lugs on the nut E which fit in slots in the bracket, the nut can move only parallel with the shaft when the drum rotates unless the shipper rope sheave N moves also. On each side of the nut E there are claws that engage with similar claws on the inner sides of the nuts V and S when E and V or E and S come together. Check nuts on the outer sides of the nuts V and S securely clamp the latter to the drum shaft, so that when the nut E engages either with V or S it will, by means of the bracket S, shift the shipper rope sheave N, thus cutting off the current from the motor and applying the brake. If the nuts V and S be located on the threaded portion of the shaft so that contact is made between them and the nut E when the car reaches its limits of travel, the operation of the device will stop the car automatically at both these points.

By giving attention to these points, not only will the power used, and therefore the operating expense be reduced, but the useful life of the motor starter contacts will be prolonged. These contacts suffer most from the sparking and flashing produced by switching off the current when the motor has just started or while it is running very slowly.

**Motor Starter Contacts.**—These contacts should always be kept smooth and bright. A piece of fine sand paper rubbed over them is the

best means of producing the desired result. After sand papering, the loose particles should be blown out with a bellows.

The bearings and cams of the motor starter should be kept clean and well oiled, and if a dash pot be provided to prevent the contact arm moving over the contacts faster than is necessary to secure the proper acceleration of the motor, this should be adjusted so that the arm will descend in from five to seven seconds.



FIGS. 4,202 and 4,203.—Gurney centrifugal safety governor. Fig. 4,202, governor under normal operating conditions; fig. 4,203, governor in operation through car exceeding a predetermined speed. The governor is located at the top of the shaft and directly connected to the car safety. *When the car exceeds a predetermined speed*, for which the centrifugal governor is adjusted, the car safety is automatically brought into action, gradually stopping the car and locking it securely to the guides by a powerful gripping pressure. Non-corrosive metal is used for the operating parts of this device, insuring its being in working condition at all times. There are no springs in the governor to assist or retard the action of the balls.

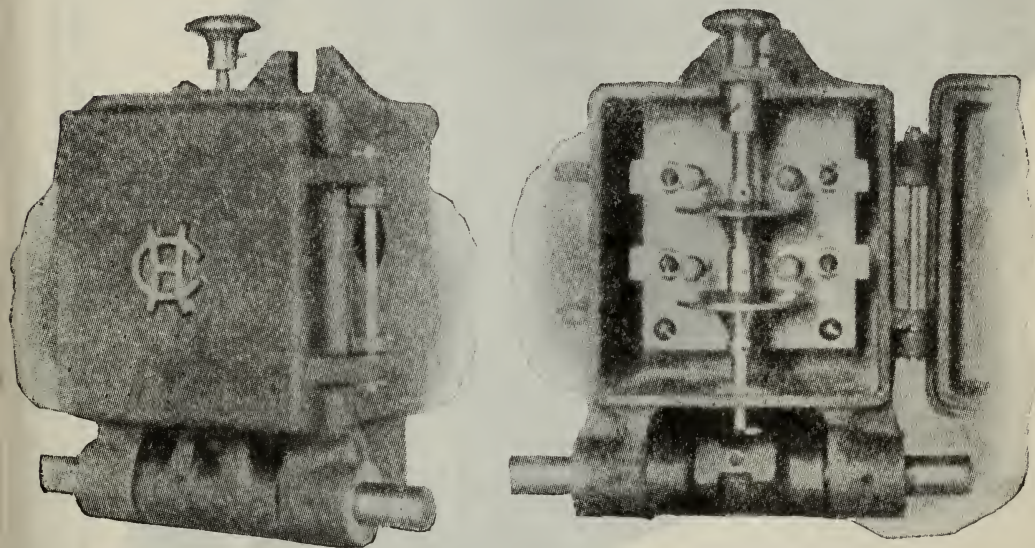
As the retarding action of the dash pot may be overcome by gravity, a spring, magnetic attraction, or by the motion imparted from the motor, the shafting, or the elevator machine, the method of adjustment will depend upon which form of motor starter be used.

**Caution in Adjusting.**—An important point to remember in connection with the cleaning, oiling, or adjusting of the motor starter,



and in fact in connection with the cleaning, oiling, or adjusting of any parts of the elevator equipment, is to open the main switch connecting the motor to the supply circuit before commencing these operations; this will tend to prevent accidents of an electrical or a mechanical nature.

**Car Stops.**—If, in the operation of an elevator, the car stop for some unknown reason, the operator should at once shift his controlling device in the car to the off position. If, then, upon shifting the controlling device again to start, the car refuse to move in either direction, some one of the following occurrences has probably taken place: It may be that the car or counter weight has met with some obstruction and the slack cable device has operated; that there is a poor contact in the switch or connections; that the fuse or circuit breaker has opened the



FIGS. 4,204 and 4,205.—Cutler-Hammer direct or alternating current double pole slack cable switch for use with controllers. Fig. 4,204, case closed; fig. 4,205, open. **In construction** the switch is enclosed in a cast iron case from which projects a shaft designed for attachment to the slack cable arm of the winding machine. **In operation** should the cable become slack, the movement of the slack cable arm through an angle of a few degrees in either direction serves to trip the switch, opening both sides of the line to the control system and stopping the car. The slack cable switch cannot be automatically reset, but after having tripped out must be reset by hand, thus compelling the operator to go to the source of the trouble before the elevator can be again operated.

motor circuit; or that the current has been turned off the supply wires. In any case, the motor should be examined before starting, to see that no damage has been done to it.

**Car Stops between Landings.**—When this happens, owing to a failure in supply of power, an effort should be made to have the main switch opened, the brake released, and the worm shaft turned either by pulling on the brake pulley or with a wrench on the end of the armature shaft so as to bring the car to a floor landing and allow the passengers to get out.



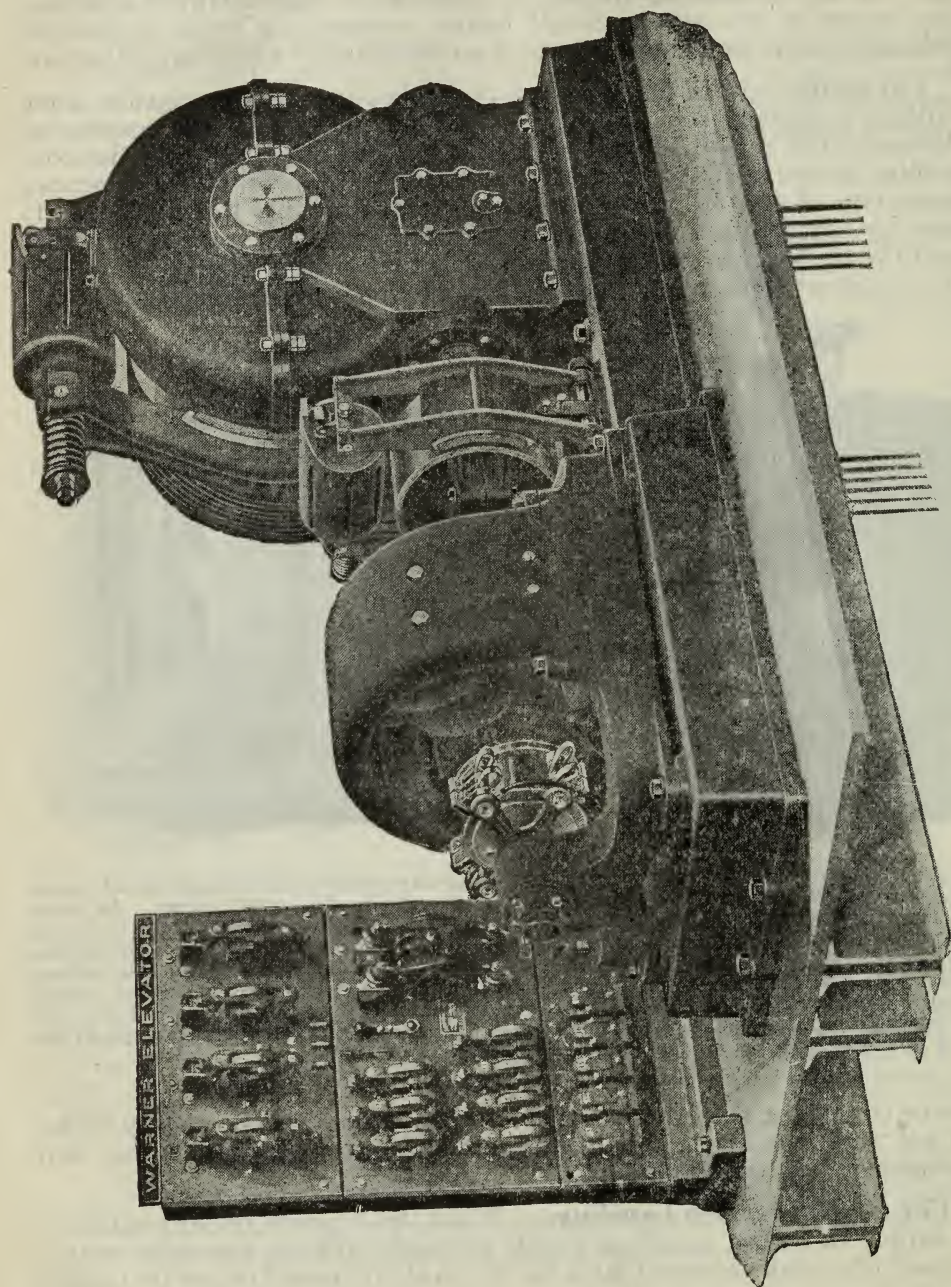


FIG. 4,206.—Warner worm drive over mounted traction elevator machine with control board; for speeds up to 600 feet per minute. The largest machines are ball bearing throughout. The motor is of the interpole type. The switches have metal contacts, except the pressure switch, which has copper and carbon contacts.



In some elevator motors, the free end of the armature shaft is purposely made square to facilitate turning the shaft with a wrench as just mentioned.

**Car Beyond Control.**—If the operator find he has lost control of the car and cannot stop it, he should not become frightened but allow it to make the full run, relying on the limit stops to automatically bring the car to a standstill at either end of its travel.

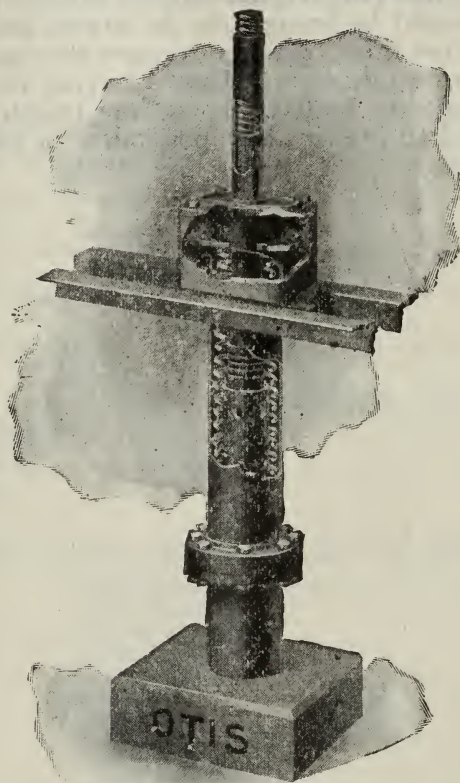


FIG. 4,207.—Otis spring return oil buffer or cushion. These are placed in the shaft one under the car and one under the counterweight, and are arranged to bring either the car or the counterweight to a positive stop, through the telescoping of the buffer—this occurring at a carefully calculated rate of speed, which is regulated by the escape of oil from one chamber of the buffer to another.

**Limit Stops.**—The operator should not rely on the limit stops to make a top or bottom landing, but should operate the controlling device in the car as he would to make any intermediate landing. It is advisable, however, to test the adjustment of the limit stops and determine if they remain in proper working order by trying them once daily by means of the car.

**Caution While Car is in Motion.**—The operator should never leave his car while it is in motion, and he in turn should never allow a passenger to enter or leave until the car has stopped at a landing.

The majority of elevator accidents have resulted from carelessness in observing this simple rule, showing that more attention should be given it by operators than heretofore has been the custom. As the operator opens the doors at a landing he should call out "up" or "down," depending upon the direction in which the car is making the trip, and while he should allow ample time for passengers to reach the car from wherever they may be standing, it may be necessary in certain cases to add, "step lively, please."

**Leaving Car for the Night.**—When the elevator is left for the night, the car should be brought to the lowest landing and allowed to remain there. Care must be taken to open the main switch connecting the motor to the supply circuit, before leaving the premises. In fact, whenever the car is to be left idle for any length of time, this switch should be opened to prevent any possibility of the motor starting up and causing damage.



## CHAPTER LXXIX

## ELECTRIC CRANES

By definition, a crane is *a machine for lifting, lowering and moving a load in a horizontal direction*, as distinguished from a hoist which simply lifts and lowers a load.

The numerous and diverse conditions of service require a multiplicity of type, and accordingly cranes may be classified:

1 With respect to the motive power, as

- a. Steam;
- b. Pneumatic;
- c. Hydraulic;
- d. **Electric.**

2. With respect to the character of the horizontal motion, as

- a. Rotary
  - { swing cranes;
  - { jib cranes;
  - { column cranes;
  - { pillar cranes;
  - { pillar jib cranes;
  - { derrick cranes;
  - { walking cranes;
  - { locomotive cranes.

- b. Rectilinear
  - { bridge cranes;
  - { tram cranes;
  - { traveling cranes;
  - { gantry cranes.

- c. Combination rotary and rectilinear.

In addition to these, there are some miscellaneous types known as

- 1. Sheer legs;
- 2. Transporters;
- 3. Telfers
  - { cableways;
  - { mono-rail systems.

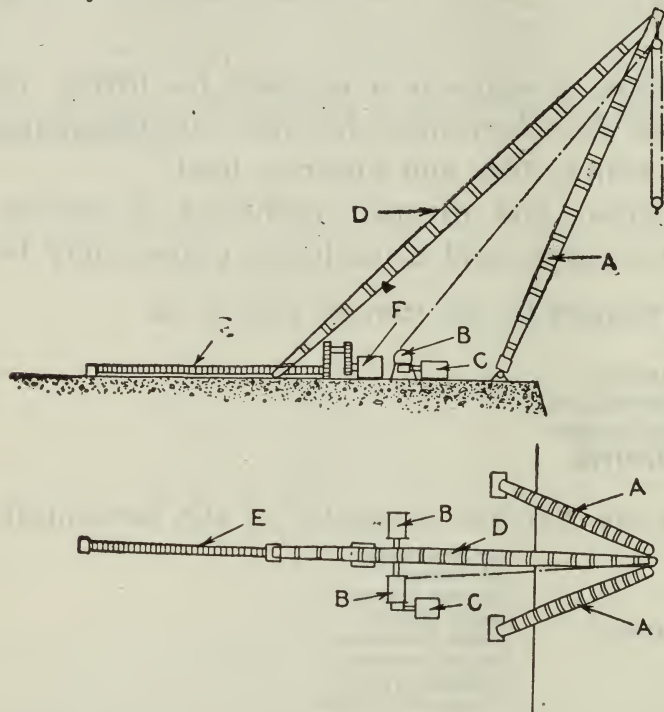
The following definitions of the various type show the inherent features of each:

**Swinging cranes.**—Having rotation, but no trolley motion.

**Jib cranes.**—Having rotation and a trolley traveling on the jib.

**Column cranes.**—Identical with the jib cranes, but rotating around a fixed column (which usually supports a floor above).

**Pillar cranes.**—Having rotation only, the pillar or column being supported entirely from the foundation.



FIGS. 4,208 and 4,209.—Sheer legs. This is a type of lifting appliance used for handling extremely heavy loads such as ship's boilers and heavy guns. The load rope passes over a pulley at the head of the legs A and is led to the winding drum B, which is driven by the motor C. The bottom of the back leg D is traversed by a screw E, driven by the motor F so as to traverse the load in or out. Occasionally a second hoisting drum and motor are provided to handle light loads at quick speeds. It will be noted that with this type of crane, loads can only be picked up and deposited along a horizontal line which is a continuation of the center line of the screw.

**Pillar jib cranes.**—Identical with the last, except in having a jib and trolley motion.

**Derrick cranes.**—Identical with jib cranes, except that the head of the mast is held in position by guy rods or stiff legs, instead of by attachment to a roof or ceiling.



**Walking cranes.**—Consisting of a pillar or jib crane mounted on wheels and arranged to travel longitudinally upon one or more rails.

**Locomotive cranes.**—Consisting of a pillar crane mounted on a truck, and provided with power capable of propelling and rotating the crane, and of hoisting and lowering the load.

**Bridge cranes.**—Having a fixed bridge spanning an opening and a trolley moving across the bridge.

**Tram cranes.**—Consisting of a truck, or short bridge traveling longitudinally on overhead rails, and without trolley motion.

**Traveling cranes.**—Consisting of a bridge moving longitudinally on overhead tracks, and a trolley moving transversely on the bridge.

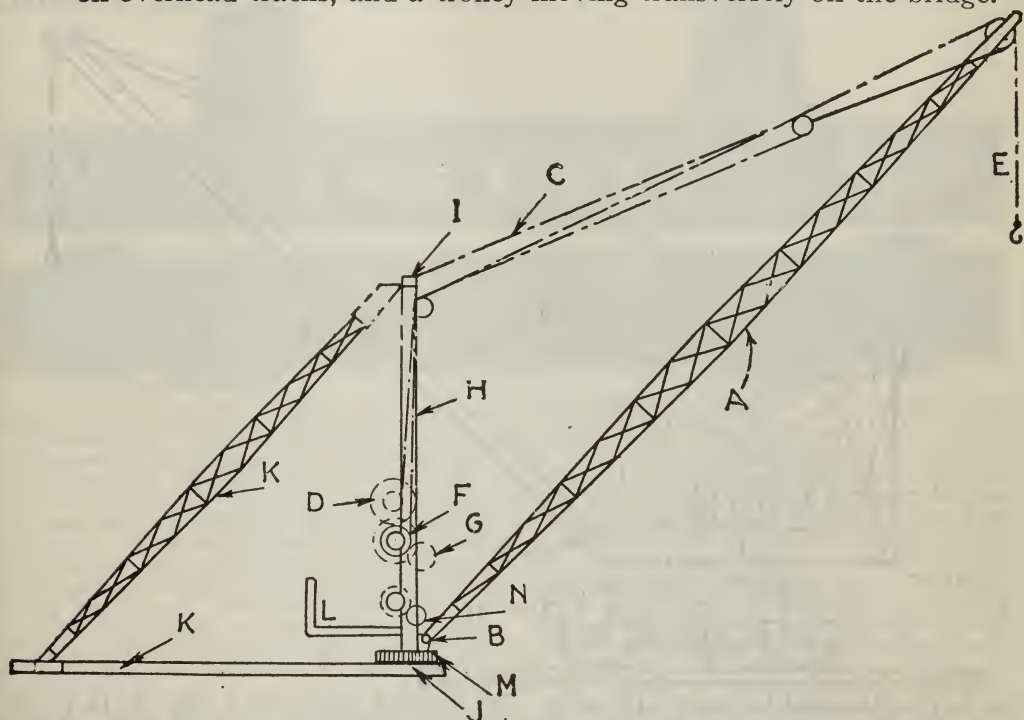


FIG. 4,210.—Electric derrick crane. The load hangs from the end of the jib A, which is supported by the pin B, and rope C, which leads to the jibbing drum D, by which the jib can be lowered. The load rope E, is led to the drum F. Drums D and F are driven by motor G. A clutch is provided by which the drum D may be put in or out of gear with drum F. When D is out of gear, the drum F is used to lift or lower the load. When the two drums are clutched together they run in opposite directions, so that when drum D is hoisting the jib, drum F pays out the load rope, and vice versa. Thus, whether the jib is being lifted or lowered, the load remains steady, and simply runs in or out in a horizontal line. The jib and the motors and gearing are carried by the vertical mast H, which turns in bearings I J in the framing K. The driver's platform L is also attached to the mast, and the various controlling switches and levers are placed on this platform. To slew the mast and jib, a toothed wheel M is fastened to the framing and gearing. With this is provided a pinion, the shaft of which is carried in bearings on the mast, and is driven by the slewing motor N. This type of crane will serve an area having a radius equal to the maximum horizontal radius of the jib, and forming a segment of a circle embracing an arc of rather less than 270 degrees.

**Gantry cranes.**—The same as a traveling crane except that the bridge member is supported on structural legs of suitable height, which are provided with wheels and suitable gearing, so that the crane may be propelled bodily along the tracks which are on the ground.

**Rotary bridge cranes.**—Combining rotary and rectilinear movements and consisting of a bridge pivoted at one end to a central pier or post, and supported at the other end on a circular track, provided with a trolley moving transversely on the bridge.

**Essentials of Rotary Cranes.**—In this type of crane, the construction is such as will permit the load to be lifted, lowered,

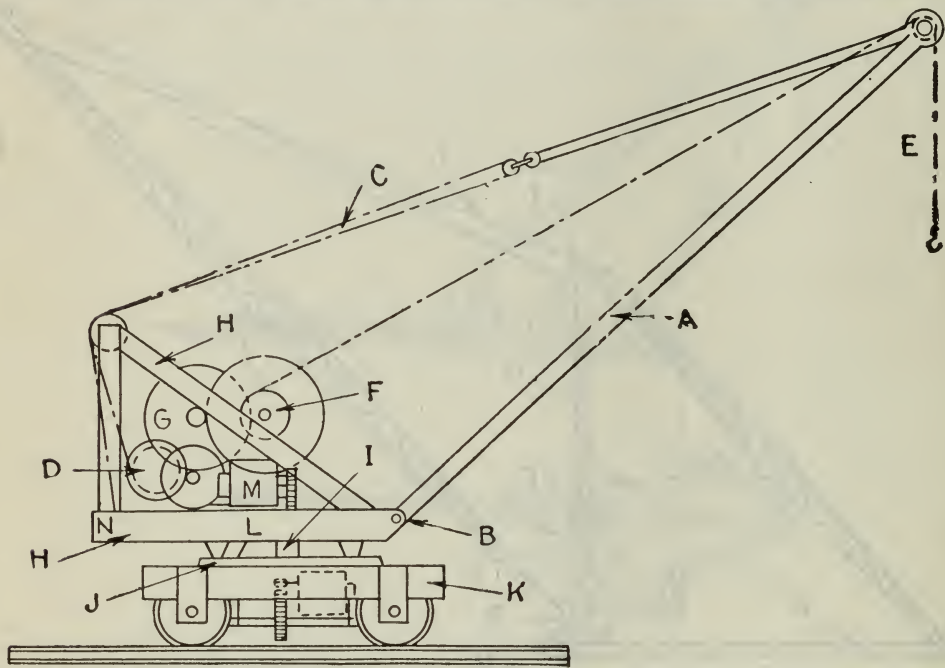


FIG. 4,211.—Electrical locomotive jib crane. The essential parts are: A, jib; B, jib pivot; C, rope gear serving as a brace for jib, and which controls the radial position of jib; D, jib shifting drum; E, hoisting rope leading from hook; F, hoisting drum; G, hoisting drum; H, framing; I, pin; J, turning or slewing wheel; K, truck; L, pinion; M, turning and propelling motor.

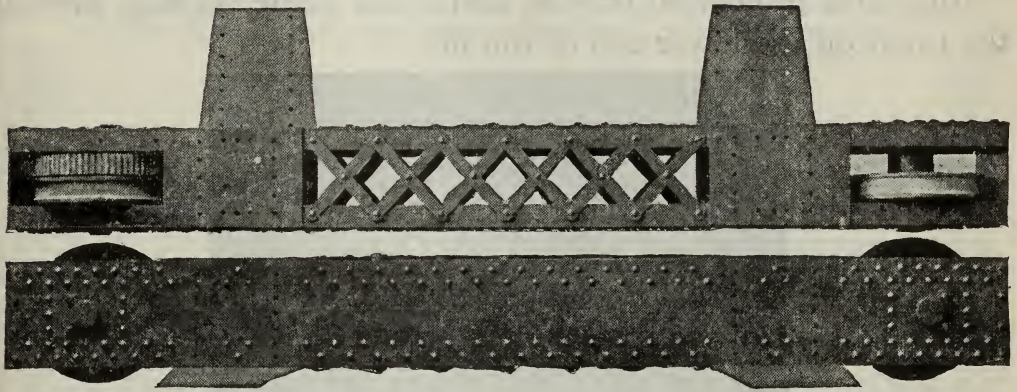
and moved radially. An example of rotary crane is shown in fig. 4,211, which illustrates the essential features of a locomotive jib crane.

As shown in the figure, the hook, which engages the load, hangs from the end of the jib A, which is supported by the piece B, and rope C, which leads to the drum D. By winding in or paying out the rope



C, the radius of the jib in the horizontal plane can be increased or diminished.

The rope for hoisting the load is brought over a pulley at the head of the jib and led to the drum F. Drums D and F are usually arranged to be driven from one motor G, clutches being so arranged that when the motor is in gear with the one drum, it is out of gear with the other. The jib and hoisting gear are carried by the framing H, which turns upon the pin I, the turning or slewing being accomplished by means of the wheel J, which is secured to the platform of the truck K and pinion L (carried by bearings in the framing H), which is driven by the motor M.



FIGS. 4,212 and 4,213.—Niles crane construction: bridge ends or trucks. The bridge ends are built up of plates and angles, as illustrated, or of heavy steel channels or I beams, depending upon the type and capacity of the crane. Heavy gusset plates connect the girders and bridge ends, and prevent the girders getting out of square. All connection holes are drilled and reamed after the parts are assembled and squared. In best construction, finished body bound bolts with lock washers are used for connecting these parts. The truck wheels are bronze bushed, extra heavy, and double flanged, the treads being accurately finished to equal diameters. They revolve on turned steel axles of large diameter, which are fitted in bored holes in the reinforced bridge ends and securely held by key plates. This construction gives large bearing surfaces and extremely low bearing pressure values, ensuring minimum wear. Bronze washers are provided between the hubs of the truck wheels and the web plates. The truck wheel gears have teeth cut from solid stock and are forced by hydraulic pressure on the hub of the truck wheels and keyed. The bridge ends extend beyond the wheel and are capped at the ends with a removable steel plate, provision being made for attaching wooden bumper blocks, which prevent the wheels and gears of two cranes coming in contact when several cranes are on the same runway. The truck wheels may be easily removed by taking off the steel caps, jacking up the bridge ends just enough to remove the weight from the wheel, withdrawing the axle and rolling the wheel out. Lubrication of the truck wheels is provided by internal oiling through the center of the axle. The bridge drive shaft is carried at the ends by self-oiling cap bearings, so located as to eliminate overhung gears or pinions.

It is usual for the framing to be capable of making a complete circle. The motor M is also used to drive the truck along the rails.

A vertical shaft driven from this motor passes through the pin I, and drives one or both of the axles by means of bevel gear. Clutches are provided so that the motor M may be used for slewing or traveling.

The load is balanced by the weight N. A foot plate for the operator is provided on the framing just in front of the balance weight, and the controllers and clutch levers are within easy reach.

**Ques. What area is served by a locomotive jib crane?**

Ans. It is equal to twice the maximum radius of the jib, and a length depending on the length of track laid.

**Ques. What is the effective radius of the jib?**

Ans. Its projection on the horizontal plane passing through the pivot on the lower end of the jib.

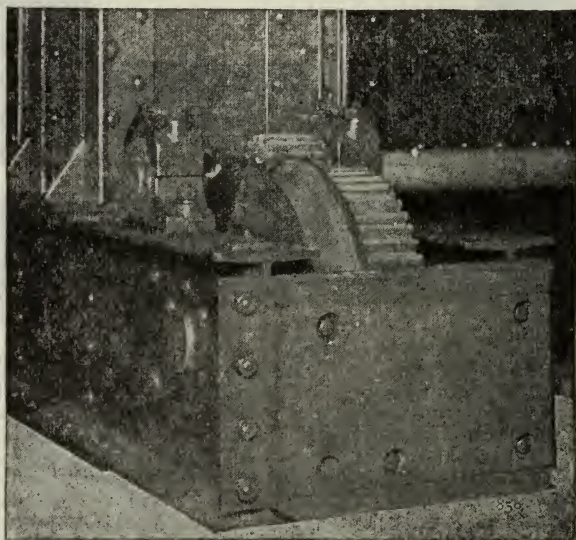


FIG. 4,214.—Niles crane construction: Bridge end trucks showing the two bearings for bridge drive shaft and the steel plate with bumper block at end of truck.

**Ques. What is the most economical position of the inclined brace in a jib crane?**

Ans. The position in which the inclined brace intersects the jib at a distance from the mast equal to  $\frac{4}{5}$  of the effective radius of the jib.

**Essentials of Rectilinear Cranes.**—This form of crane differs from the preceding type in that the load is moved linearly



instead of radially. The essential features of rectilinear cranes are shown in fig. 4,215, which illustrates a rectilinear crane of the traveling type.

In construction a pair of cross girder AA, known as the bridge, are supported on the end carriages BB. The wheels of the end carriages run on rails mounted on elevated structures or *gantries* CC. The purpose of the crane is to lift, transport, and deposit loads anywhere within an area a little less than the width between the gantries and of a length depending on the length of the gantries. Rails are laid on the cross girders AA, and a crab or trolley runs on these rails.

The trolley has two motions, each driven by its own motor.

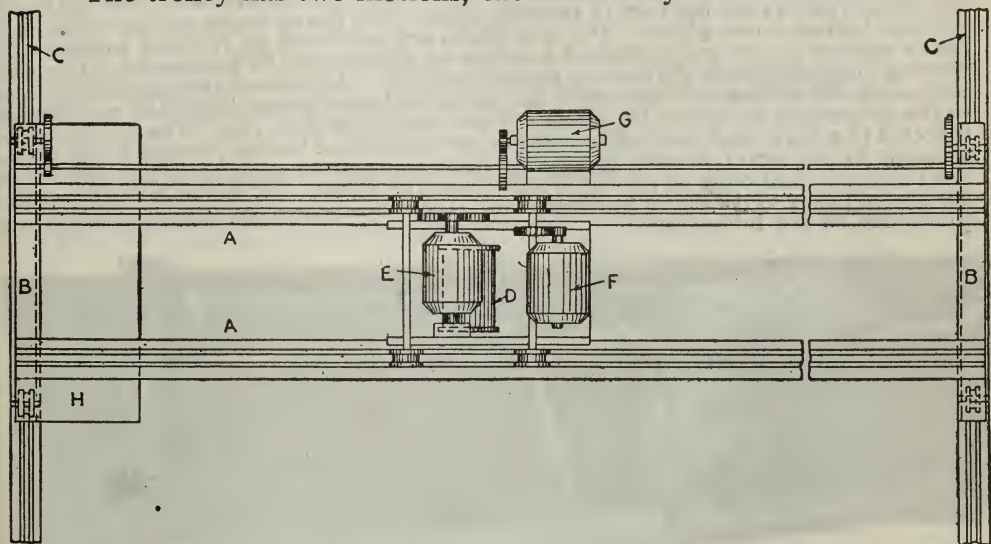


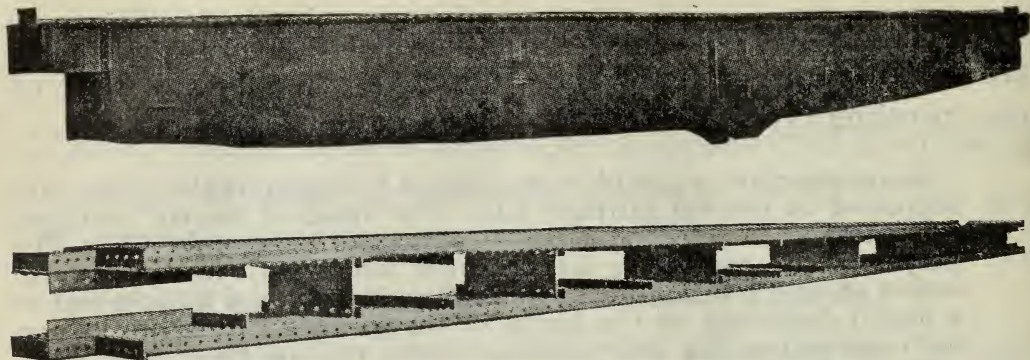
FIG. 4,215.—Electric traveling crane. The parts are: AA, cross girders known as the *bridge*; BB, end carriages; CC, elevated track structure or *gantries*; D, hoisting drum; E, hoisting motor; F, transverse propelling motor; G, longitudinal propelling motor; H, cage or operator's platform.

The hoisting motion, for lifting and lowering the load, consists of the drum D, driven through suitable gearing by the motor E.

To traverse the crab along the cross girders, the motor F drives one pair of wheel through gearing.

For the purpose of traveling the crane along the gantry, the motor G is mounted at the center of one of the cross girders, and from each end of the motor, a shaft is led to drive one wheel in each of the end carriages.

**Ques.** What is the object of mounting the traveling motor at the center of the cross girders?



FIGS. 4,216 and 4,217.—Niles crane construction: Box section bridge girders. The standard box section girders are built up of two web plates, four heavy angles and universal mill top and bottom cover plates. The web plates are reinforced at frequent intervals by heavy vertical angles and connected together by diaphragms to prevent vibration and skewing diagonally when the crane is started suddenly. All holes in the angles and plates composing the girders are laid out to templates, and after being assembled, are reamed to the proper size to receive the rivets without the use of drift pins. The bridge motor is bolted in a horizontal position to a heavy structural steel bracket, riveted to the girder adjacent to one set of vertical angles and diaphragm plates connecting the web plates described above, in order to prevent distortion of the girders. At the ends of the girders are placed heavy vertical and horizontal angles which reinforce the webs and serve as a connection to the bridge ends.

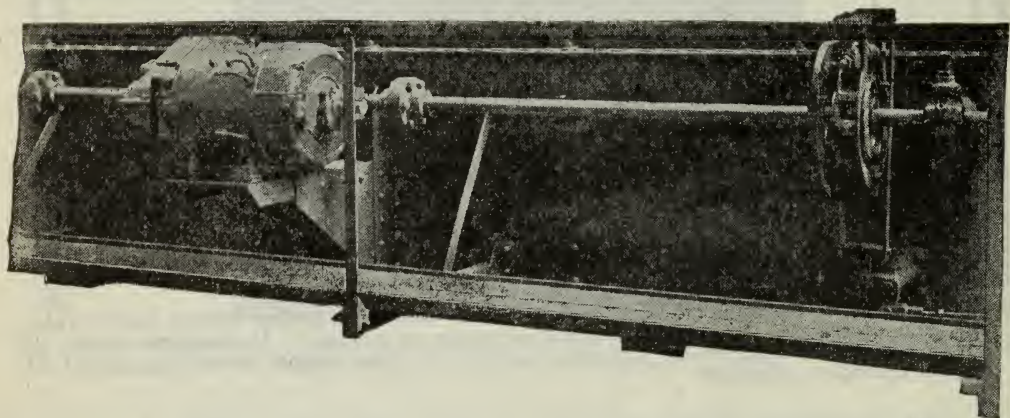


FIG. 4,218.—Niles crane construction: Bridge drive for box section girders. The web plates of the box section girders are reinforced by heavy stiffening angles, placed near the bridge drive motor and are connected by diaphragms, preventing distortion of the girders by motor or gears. The bridge motor is bolted in a horizontal position to a heavy structural steel bracket riveted to the girder. The motor gear and pinion are enclosed and run in self-oiling bearings. The cross shaft is of extra heavy steel and is sufficiently strong to skid the truck wheels with the crane fully loaded, thereby preventing distortion in the shaft due to careless handling. The shaft is supported at uniform intervals by adjustable split babbitted bearings which can be removed without disturbing any other part. They have oil reservoirs and are provided with wick feed lubrication. The truck wheels are extra heavy with double flanges, the treads being accurately machined or ground to equal diameters. A powerful foot brake of the post type is provided, operated by a foot lever conveniently located in the cage. The brake is simple in construction and extremely powerful in action. A substantial platform with angle iron hand rail extends along the girder on the bridge drive side, providing easy access to the bridge motor, gears and bearings.



Ans. To obtain an equal amount of twist in both parts of the shafting, so as to avoid cross wind.

**Ques. What is the cage?**

Ans. A platform or housing for the operator, and containing the control devices.

**Ques. Where is it located?**

Ans. It is attached to the bridge at H, fig. 4,215. This position gives the operator a clear view of the hoisting operations.

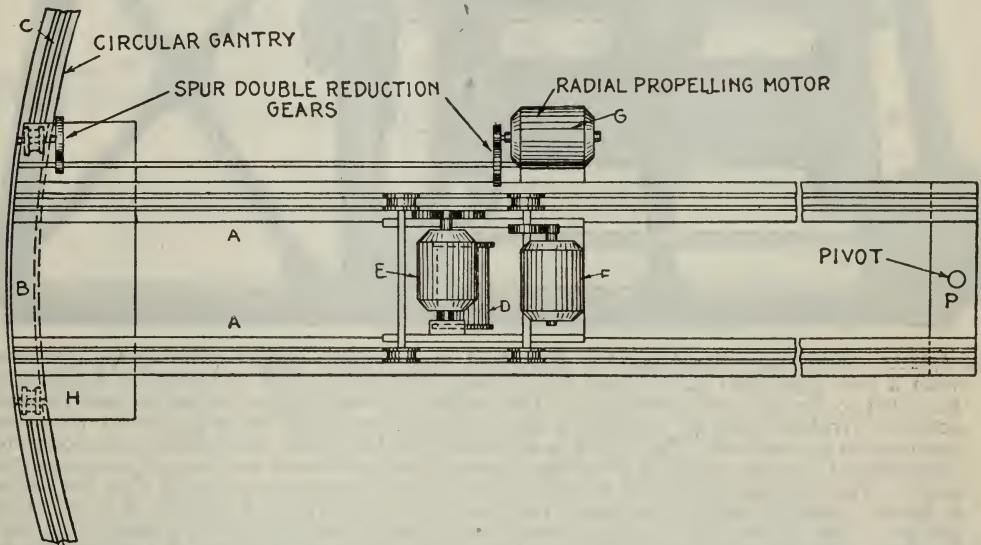


FIG. 4,219.—Electric combined rotary and rectilinear crane. *In construction* most of the parts are identical with those of fig. 4,215, and the letters on these parts are the same for each figure. This type differs from fig. 4,215, in the replacement of one gantry by a pivot P, and the other straight gantry by a circular gantry which may be either an arc or a complete circle as desired.

## Essentials of Combined Rotary and Rectilinear Cranes.

—A modification of the traveling crane, which combines the functions of the two classes, rotary and rectilinear, consists in pivoting one end of the bridge of a traveling crane and supporting the other end on a circular gantry as shown in fig. 4,219.

The illustration shows the most of the mechanism to be identical with that of the traveling crane.

One end of the bridge is pivoted at P and at the other end, a section of the circular gantry is shown.

In construction the circular gantry may continue all the way around or only for a short arc, as may be desired. The figure clearly shows that the rotary motion is obtained by operating motor G, and the rectilinear motion, by motor F, while hoisting and lowering is effected by motor E.

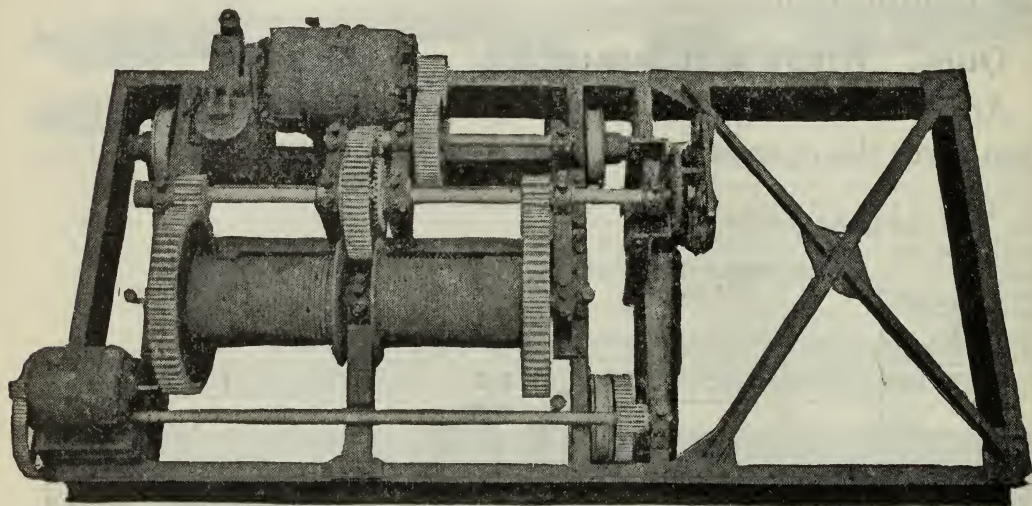


FIG. 4,220.—Niles crane construction: Standard grab bucket trolley suitable for operation with a two rope grab bucket, one rope being attached to bail of bucket and the other attached to the opening mechanism. The trolley framing consists of heavy steel channels securely riveted together, making a self-contained and rigid construction to which the mechanism is attached. The trolley is of the double drum type, each drum being operated independently of the other or in unison through the medium of one train of compensating gears. The hoisting drums are finished all over, and have grooves cut so that the bucket is lifted vertically without twisting, and the load is distributed equally to both bridge girders. The bearings in the drums are bronze bushed and revolve on a steel drum shaft in which allowance has been made for all bending strains and in which all torsional strains have been eliminated. The steel drum gears are forced directly on to the drums and keyed. All shafts run in self-oiling cap bearings with removable bushings. Any shaft may be removed without interfering with any other. One drum is fitted with a powerful foot brake of the post type, perfectly balanced and positively withheld from contact with the brake wheel, except when applied by the operator for the purpose of opening the bucket. The brake is operated by a foot lever conveniently located in the cage. The bucket is held by two sets of rope, the tension in which is always equalized through the compensating gears, avoiding the possibility of slack ropes and insuring the retention of the bucket by one of the ropes should the other break. The hoisting mechanism is controlled by powerful brakes, preventing the dropping of the bucket or running down by gravity under any condition of service. Hoisting, lowering, opening or closing the bucket is under the complete control of the operator at all times. The opening of the bucket or dumping of the load is by the simple application of the foot brake. When the open bucket comes in contact with the material to be handled, the controller is moved to the hoisting position. This closes and thereby fills the bucket, which, without further manipulation, is hoisted to the desired dumping point. The mechanism is always in position to repeat the operation, insuring, by its simplicity, high speed of operation with moderate speed of mechanism. Clutches or other parts liable to excessive wear are eliminated. Regularly built with direct or alternating current motors, which are bolted directly to the steel frame.



**Essentials of Transporters.**—By definition a transporter is a *lifting and transporting machine designed to carry loads between two fixed points*. It is used chiefly for handling comparatively light loads at quick speeds and employed largely for the conveyance of materials such as coal in bulk. For the latter service it is provided with an automatic grab instead of a hook. Fig. 4,221 shows the essential features.

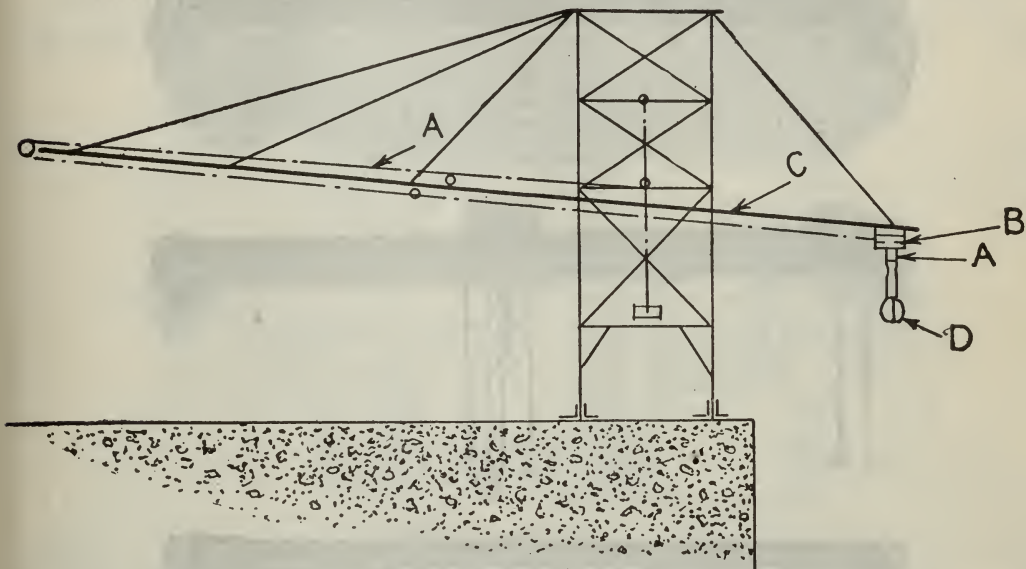


FIG. 4,221.—Electric transporter. The parts are: A, load rope; B, carriage; C, beam; D, grab.

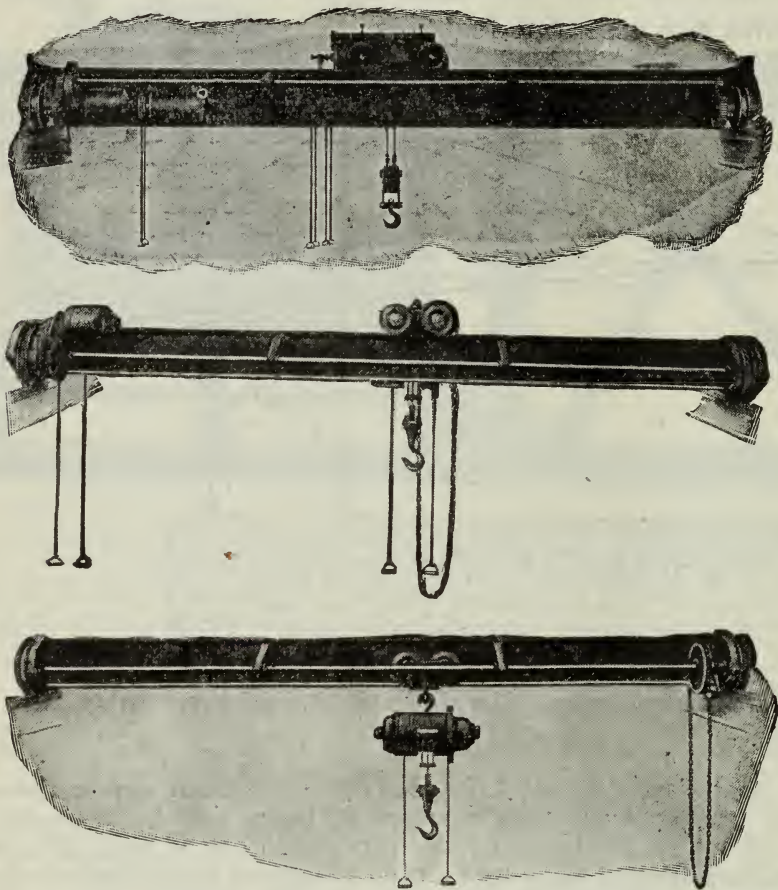
In operation, the grab being full, the electrically driven drum winds in the load rope A. The carriage B, being held by a trigger at the bottom end of the beam C, the winding in of the rope lifts the grab. When it is heaved right up to the carriage, it locks itself to it, and at the same time lets go the trigger.

The carriage is pulled along the beam, but as the rope is now single purchase, the carriage is pulled along at double the speed at which the load was hoisted.

On arriving at the top end, the carriage is held by a trigger and the grab is freed from the carriage. The motor is now reversed, and the grab, after being lowered a given distance, discharges its contents. The motor is again reversed, thus hoisting the grab up to the carriage, to which it locks itself and frees the trigger.

On reversing the motor, the carriage runs down the beam, and at the bottom end is caught by the trigger, while the grab is released and continues to run down till it plunges into the material, thus completing the cycle.

**Ques.** How long does a complete cycle take in this type of apparatus?



FIGS. 4,222 to 4,224.—Northern low junior and express type electric crane, floor controlled.  
Figs. 4,222 and 4,223 showing over mounted trolley; fig. 4,224, under mounted trolley.

**Ans.** From one-half to one minute.

**Ques.** What is the grab load?

**Ans.** From one to one and one-half tons.



**Crane Motors.**—For driving the traveling, traversing, and slewing motions of crane, series wound motors of a generally similar type to those used for electric traction give satisfactory results, this work being in fact a simple class of electric traction. The driving of the hoisting motion presents a more difficult problem, for though it is easy to lift the load up, it is not always so easy to get it down again in a satisfactory manner.

**Automatic Electro-magnetic Brakes.**—It is customary to fit the hoisting motion with an electro-magnetic brake. This

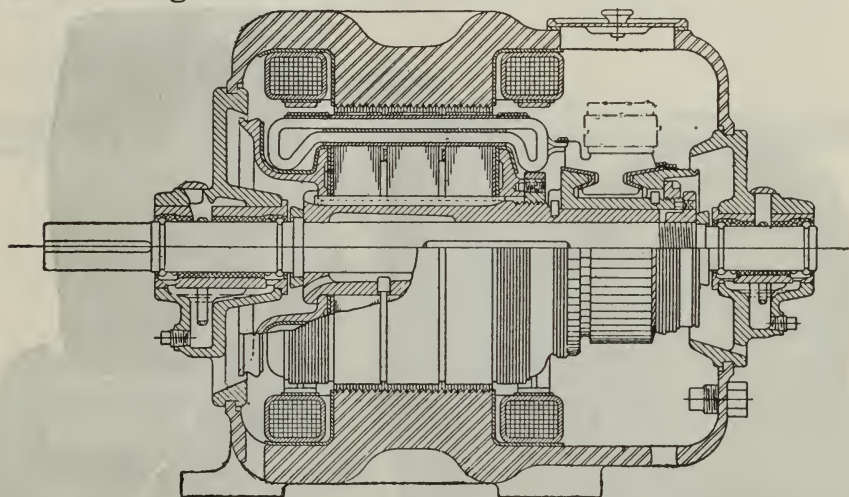


FIG. 4,225.—Sectional view of Shaw type Z Crane motor. The frames are of cast steel split diagonally and when assembled with bearings completely enclose the armature. The motor has four salient poles cast integral with the frame and so shaped that the field coils can easily be put in place. The brake is attached to the lower half of the frame so that the motor can be taken apart without disturbing it except that the band must be removed by taking out the two pins holding same.

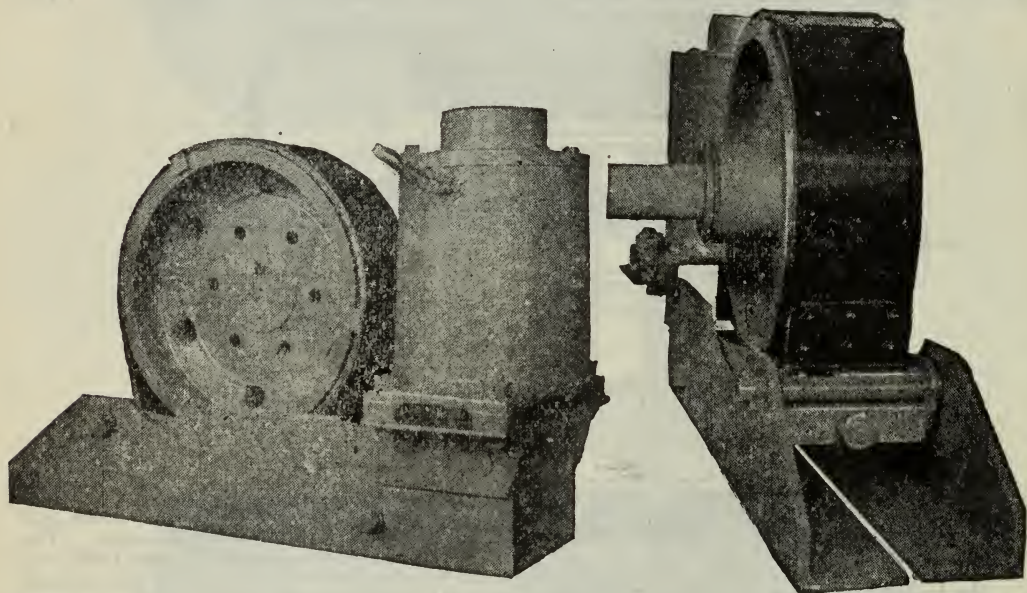
may consist of a band brake which is normally kept on by a spring or weight and released by an ironclad solenoid, or it may be a disc brake in which the discs are normally pressed together by a spring, an electro-magnet being provided to pull back the pressure plate and release the discs.

The coil of the solenoid or electro-magnet is in circuit with the hoisting motor, so that when current is switched on to the motor, the brake is released, and when it is switched off, the brake is applied. This makes an excellent safety device, but

as it can only be off or full on, it cannot be used to regulate the descent of the load when lowering.

In cases where the driver has access to the gear, as in locomotive jib cranes and derricks, an addition may be made to the electro-magnetic brake in the form of a hand or foot release lever, by which the brake can be released or its pressure regulated. Loads are then hoisted by the motor, and are allowed to run down by their own weight, the speed of descent being regulated by the brake.

Where the driver operates the gear from a distance, the arrangement just described is not practicable, and some automatic or electrically controlled arrangement must be used to check the speed of descent of the load.



FIGS. 4,226 and 4,227.—Niles crane construction: Electric brake. It is of the ironclad solenoid type and is fitted with a removable brake band which engages almost the entire circumference of a turned and balanced wheel. The band is of special steel and lined with a renewable friction wearing surface. The brake is equally effective in either direction. The brake is always on when there is no current flowing through the motor and is always off when motor is running.

**Automatic Mechanical Brake.**—A common arrangement is the automatic mechanical brake. The brake is usually of the disc type, and is arranged to allow the gear to run freely in the direction of hoisting, but holds it from running in the opposite direction, being applied by a screw, or it can be arranged to be operated automatically by the load.



The brake is released by running the motor in the direction for lowering. As the motor releases the brake, the load tends to put it on again; consequently the speed of descent depends upon the speed of the motor, and this can, of course, be regulated by the driver by means of the controller.

**Eddy Current Brake.**—This type of brake is only used to a limited extent. It consists of a wheel, generally of copper or

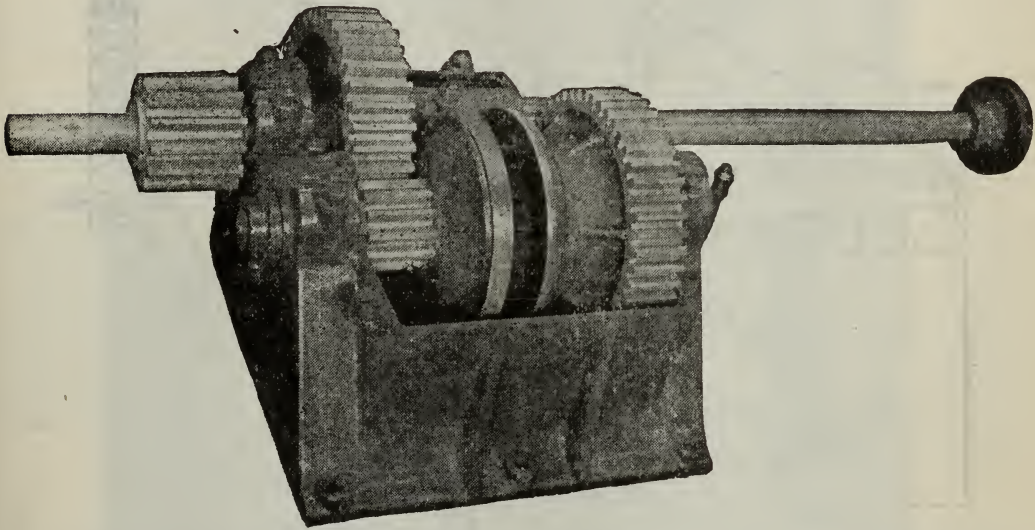


FIG. 4,228.—Niles crane construction: Mechanical load brake. It is of the double disc type with hard bronze wearing surfaces. It is automatic in action and self-contained, all thrusts being taken up within itself. The brake will not permit the load to run down unless the motor is revolved by power in the lowering direction. The brake, together with the intermediate steel gears, runs enclosed in a case, making a self-contained unit, insuring perfect accessibility, ideal lubrication and protection from dust and mechanical injury. The turned steel shafts revolve in self-oiling cap bearings, fitted with removable bronze bushings, the caps being attached by through bolts.

other metal of low electrical resistance, which is arranged to rotate between the poles of an electromagnet. The wheel is driven by the descending load, and eddy currents are generated in it, which give rise to a retarding torque. The eddy currents and the consequent torque are regulated by varying the strength of the magnet by means of a regulating switch and resistance.

**Rheostatic Brake.**—For this form of braking, the controller is provided with several positions on the lowering side, called *brake points*. In these positions the controller alters the connections of the motor to those of a series dynamo, so that it generates current when driven by the descending load, the

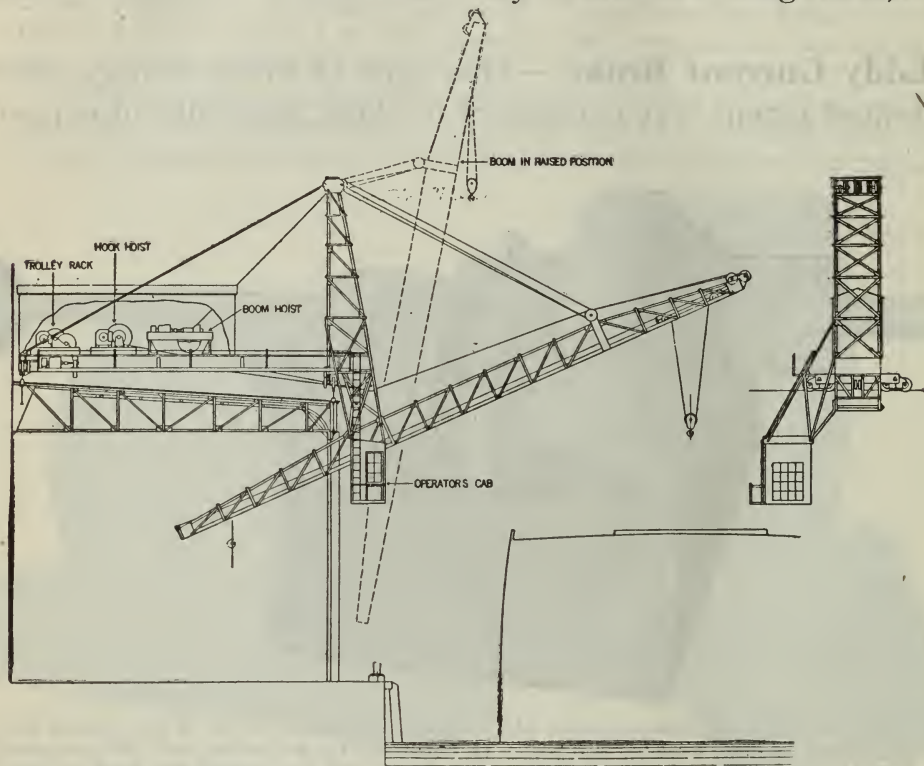


FIG. 4,229.—Shaw overhead wharf crane. The handling of freight at a marine terminal presents two distinct but closely related problems: the loading and unloading of ships and the distribution of freight on the pier. The crane here shown is designed for such service and travels on tracks carried above the roof of the shed. The boom, when in working position, stands with the outer end extending over the ship and the inner end projecting through the doorway into the shed. The usual working angle is 24 to 30 degrees from the horizontal, but this angle can be varied as the height of the boat and other conditions may require. A trolley, comprising merely a light frame with the necessary pulleys and wheels, from which the hoisting block hangs, travels out and in from one end of the boom to the other. When the crane is not in service the boom can be raised to a nearly vertical position, in which position the lower end is withdrawn from the shed and the upper end is removed from over the ship. The shed doors can then be closed, the crane can be moved to another location, and ships can sail or dock without interference with the crane boom. This crane is adapted especially to those terminals in which a railroad track is extended along the edge of the pier. Having no supports outside of the railroad track, the space is clear, so that long material, such as poles, railroad rails and structural steel, can be handled between ships and cars without swiveling. The shed should have a height sufficient to give clearance for handling freight over the sides of the largest ships entering the port when floating light at high tide or river stage. A capacity of 6,000 pounds is considered suitable for most terminals, but this, as well as other details, can be varied to suit local conditions.



energy being absorbed by the controller resistance. The speed of lowering is regulated by varying the resistance.

**Regenerative Control.**—Instead of a series motor, a shunt wound motor may be used to drive the hoisting motion. A shunt motor has the advantage that its speed can be efficiently

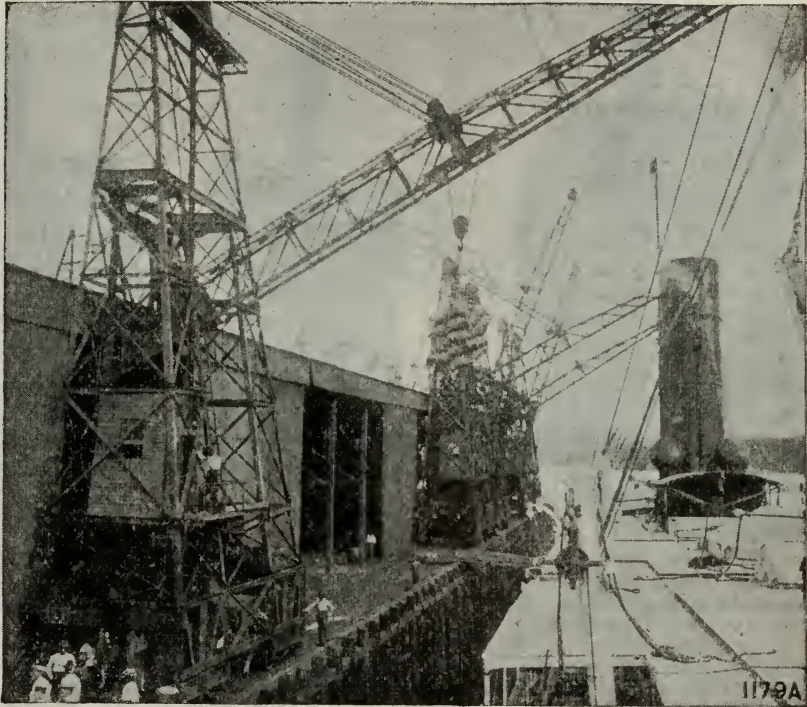
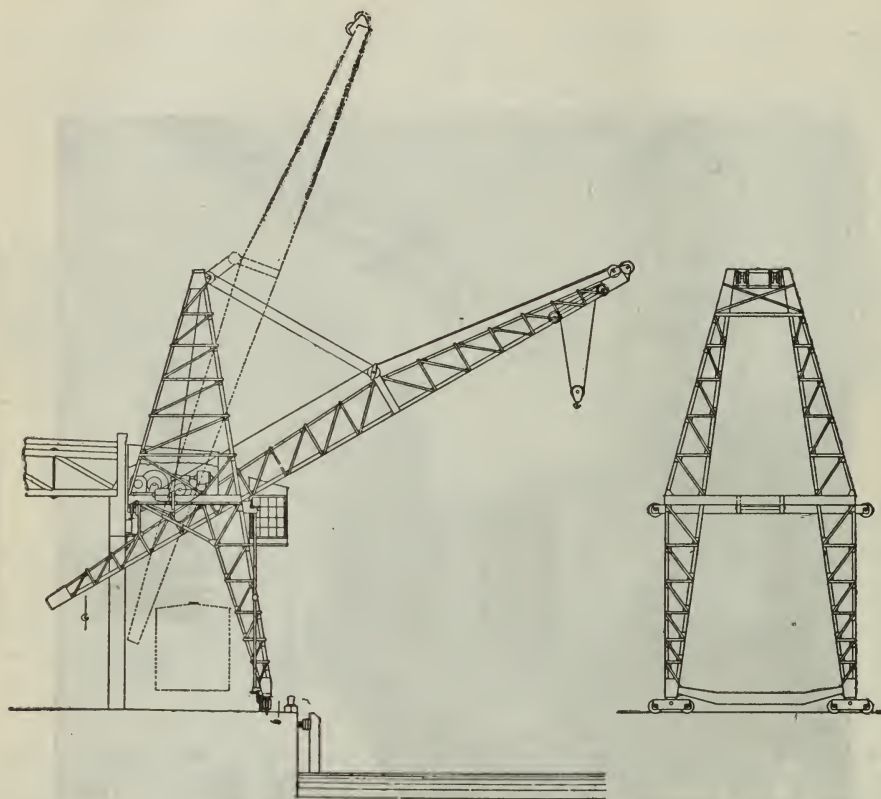


FIG. 4,230.—Shaw gantry wharf cranes as installed for the Panama R. R. Co., Laboca (now Balboa) Panama. These cranes have sloping booms, the upper ends of which are brought over the holds of vessels and the lower ends of which are then within the sheds. This construction permits freight being carried to and fro between ship's hold and inside of shed at a single handling. It carries the freight in a straight line and avoids moving a great mass of structural work or machinery whenever a piece of freight is moved. When it is desired to move the crane along the wharf, the boom is raised to a nearly vertical position. It then clears both the ship's rigging and the columns carrying the shed roof. In its most recent development, the sloping boom wharf crane runs, not on the wharf, but on the shed roof, thus leaving the deck of the wharf entirely free from obstruction.

**NOTE.—Cost of Cranes.** The cost of cranes depends to so great an extent upon the design, motor equipment, etc., that no reliable average figures can be given. As a rough approximation, the cost of a hand operated traveling crane may be taken at from about 5 to 7 cents per pound of total crane weight and the cost of an electric traveling crane at from about 10 to 13 cents per pound of total crane weight.

regulated over a fairly wide range by inserting resistance in its field circuit. By this means considerable variation of speed in lifting and lowering may be obtained without the necessity of having variable speed gear in the hoisting train, and when lowering, the shunt motor, if overhauled by a load, becomes a

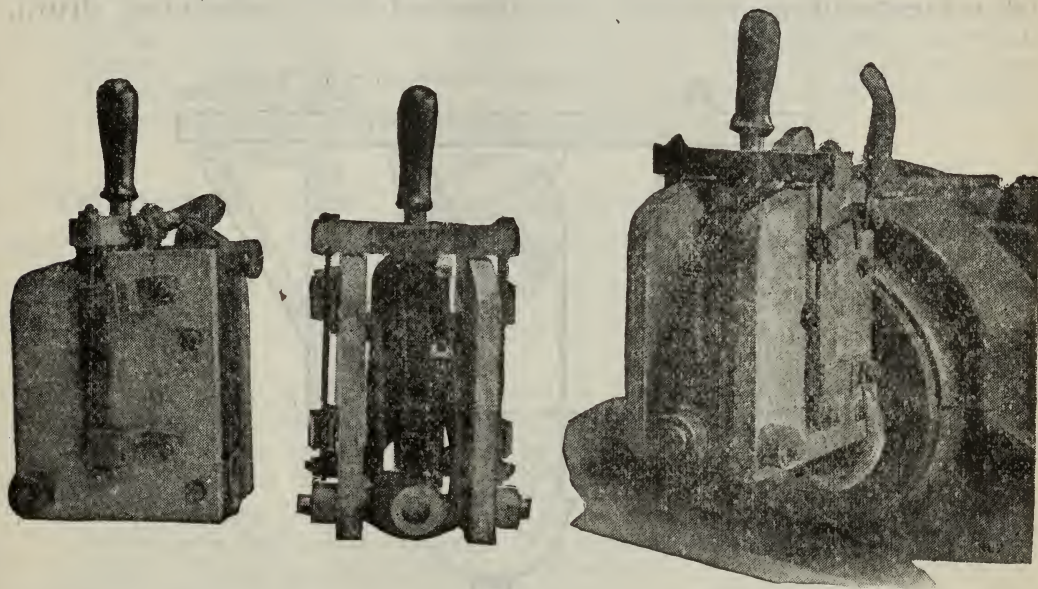


FIGS. 4,231 and 4,232.—Shaw half gantry wharf crane suitable for piers on which the sheds are set so far back that it is not practical to reach the ship from overhead tracks. This crane has the same boom and operating machinery as the overhead type shown in fig. 4,229, but travels on one elevated track carried by the building columns and one surface track at the edge of the pier. Such a crane gives the same advantages of direct and rapid handling, but not the unobstructed pier. The leg of the gantry is formed with an opening to allow the freight to pass through. This opening can be made wide enough to permit long material, such as railroad rails, to pass from boat to cars or vice versa without swiveling.

dynamo and feeds current back to the circuit, thus automatically controlling the speed of lowering. This system has been in use to a limited extent for some years.



**Collector Gear.**—To convey current from the mains to the moving crane a collector gear, generally similar to that used for electric tramway work, is employed. For overhead cranes copper wires about one-quarter to three-eighths inches diameter are stretched along the gantry, being supported at the ends by globe strain insulators. Trolley wheels or slides, mounted on the end carriage, make contact with these wires.



**FIGS. 4,233 to 4,235.**—Niles crane construction: Contact type limit switch. It consists of a worm wheel with machined teeth actuated by a turned steel worm which is attached directly to the hoisting drum shaft. The body of the switch has heavy soapstone sides between which are located the worm and wheel. The switch blades are of heavy hard drawn copper with ample carrying capacity; the blades are arranged for easy examination and cleaning. The release mechanism is operated by a positive stop on the worm wheel with a by pass attachment which prevents damage to the switch by over hoisting. The switch blades are of a quick break type operated by a powerful spring. When the switch is open the motor cannot be operated until the switch is set by hand, after which the hook can be hoisted to the maximum height in the danger zone. When the hook is out of the danger zone, the release stop is automatically reset.

From trolley wheels or slides, insulated cables are led to the switches and controllers, and to another set of trolley wires on the cross girders. Contact with these wires are made by sliders or trolley wheels on the crab, from which cables are led to the motors.

For locomotive jib cranes overhead or underground collector gear is used, similar to that used for tramway cars. As derrick cranes only swing backwards and forwards through a portion of a circle, collector

gear is not necessary. Connection from the supply mains to the moving part of the crane can be satisfactorily made by means of flexible armoured cable.

**Controllers.**—The class of controller most commonly used for crane work is that known as the drum, or tramway type. In these controllers the wires and cables are brought to a series of fixed contact, usually arranged in a straight line. A series of corresponding contact are attached to a revolving drum,

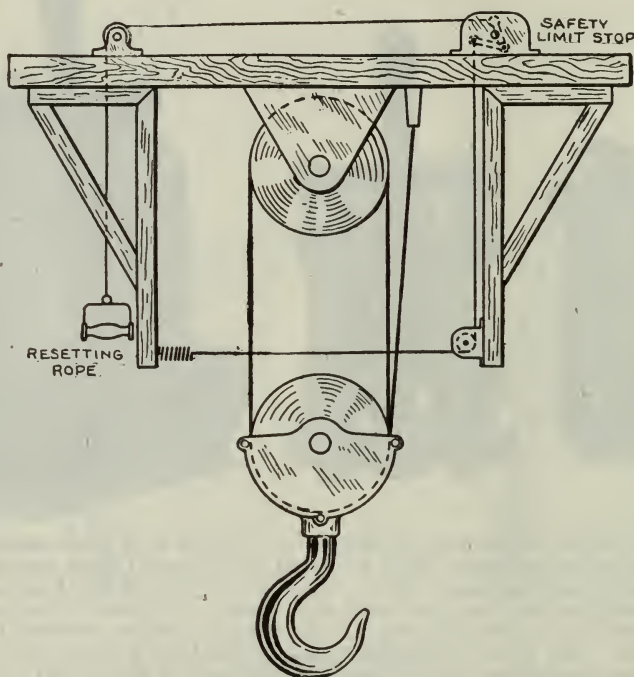


FIG. 4,236.—Diagram showing method of mounting the Palmer safety limit stop. It is not geared to the hoist nor operated by a traveling nut. Instead, a trip rope is used, one end of which is attached to a latch lever inside the enclosing case of the device while the other end, after passing through a pulley, is secured to a fixed support. The trip rope is passed through the hoisting ropes so that the hoist block cannot fail to come in contact with it at the upper limit of travel. Further upward movement of the hoist block causes a spring to trip the latch lever of the limit stop, open the motor circuit, establish a dynamic braking action and bring the motor promptly to rest. When the hoist block strikes the trip rope it is promptly stopped. It cannot be raised further, but can be lowered by simply throwing the controller lever to the reverse position. Resetting of the limit stop device is accomplished by means of the simple arrangement as shown.

the various combinations of connection for hoisting, lowering, etc., being obtained by rotating this drum into different positions.



**Power Required to Drive Cranes.**—The power required to drive the different parts of a crane is determined by allowing a certain friction percentage over the power required to move the dead load. On hoist motions  $33\frac{1}{3}$  per cent. is allowed for friction of the moving parts, thus giving a motor one-third greater capacity than if friction were neglected.

For a bridge and trolley motions, a journal friction of the track wheel axles of 10 per cent. of the total weight of the crane and load is allowed. There is then added an allowance of  $33\frac{1}{3}$  per cent. of the horse power required to drive the crane and load plus the track wheel axle friction to cover friction of the gearing.

**Telpherage.**—This word is defined as: *Automatic aerial transportation as by the aid of electricity, especially that system in which carriages having independent motors are run on a stout wire conducting an electric current.*

Telpherage is a name introduced by the late Prof. Fleeming Jenkin to designate a system devised by him, by which the transmission of a vehicle by electricity to a distance is effected independently of any control exercised from the vehicle; it is an aerial electrical railway.

Telpherage properly includes those systems employing a wire or cable for a track, but the term is erroneously applied to systems using a rail. There are two divisions of telphers.

1. Automatic;
2. Non-automatic.

**NOTE.**—**Power required for travelling cranes and hoists.** Ulrich Peters, in *Machinery*, November 1907, develops a series of formulæ for the power required to hoist and to move trolleys on cranes. The following is a brief abstract. Resistance to be overcome in moving a trolley or crane bridge.  $P_1$ =rolling friction of trolley wheels,  $P_2$ =journal friction of wheels or axles,  $P_3$ =inertia of trolley and load.  $P$ =sum of these resistances =

$$P_1 + P_2 + P_3 = (T + L) \left( \frac{F_1 + F_2 d}{D} + \frac{V}{1932t} \right) \text{ in which } T = \text{weight of trolley, } L = \text{load, } F_1 =$$

coefficient of rolling friction, about .002 (.001 to .003 for cast iron on steel);  $F_2$ =coefficient of journal friction, =.1 for starting and .01 for running, assuming a load on brasses of 1,000 to 3,000 lb. per sq. in.; [ $F_2$  is more apt to be .05 unless the lubrication be perfect];  $d$ =diam. of journal;  $D$ =diam. of wheels;  $V$ =trolley speed in feet per minute;  $t$ =time in seconds in which the trolley under full load is required to come to the maximum speed. Horse power = sum of the resistances  $\times$  speed, feet per min.  $\div 33,000$ . Force required for hoisting and lowering:  $F_h$ =actual hoisting force,  $F_o$ =theoretical force or pull,  $L$ =load,  $V$ =speed in feet per min. of the rope or chain,  $c$ =hoisting speed of the load  $L$ ,  $c \div V$ =transmission ratio of the hoist,  $e$ =efficiency =  $F_o \div F_h$ . The actual work to raise the load per minute =  $F_h V = L c = F_o V \div e$ . The efficiency  $e$  is the product of the efficiencies of all the several parts of the hoisting mechanism, such as pulleys, windlass, gearing, etc. Methods of calculating these efficiencies, with examples, are given at length in the original paper by Mr. Peters.

**Ques.** What are automatic telfers?

**Ans.** Those which are driven by electric motors, the control being apart or remote from the telfer. The original telfers were automatic, the telfer being placed in the middle of the train.

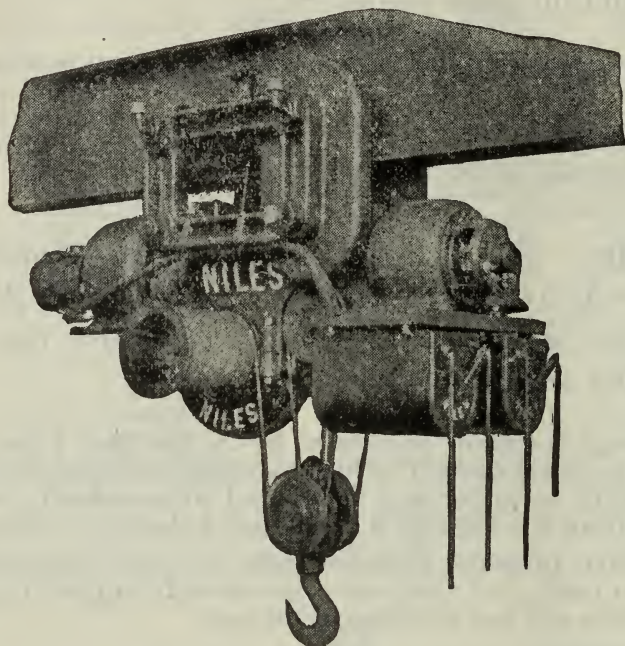


FIG. 4,237.—Niles electric mono-rail hoist, built in capacities from three-quarters to six tons. They will run on straight and curved tracks, and are generally provided with a separate motor for traversing. The hoist is self-contained in one heavy cast iron frame to which the motors are attached end on, and the power is transmitted directly from the armature shaft to the drum shaft through worm and worm wheel. The traversing mechanism is also driven by worm and worm wheel, similarly to the hoisting mechanism except that, when the trolley is arranged to run on a single I beam, a double set of transmission gears is used. The worm gear mechanism is enclosed in oil and dust proof casings, and is noiseless in operation. In addition to the braking effect obtained by use of the worm and worm wheel, a powerful electric brake is attached to the hoist motor. These hoists when mounted on a traveling bridge may be used as small capacity cranes. When used as cranes, the hoists are usually arranged to run between the two I beams or channels of the bridge, and the controllers for raising and lowering the hook and operating the traversing mechanism may be placed either on the hoist or on the bridge, and may be operated by cords from the floor or from an operator's cage attached to the bridge.

**Ques.** What is the chief use of automatic telfers?

**Ans.** They are employed for handling coal, ore, and bulk material.



**Ques. Define non-automatic telfers.**

Ans. Non-automatic telfers are those which are controlled by an operator who travels with the load and who operates both the telfer and hoists from a cab or case which is attached to the telfer or carriage.

Non-automatic telfers are employed for bulk material, like the automatic telfer, and are also used for the hoisting and conveying of

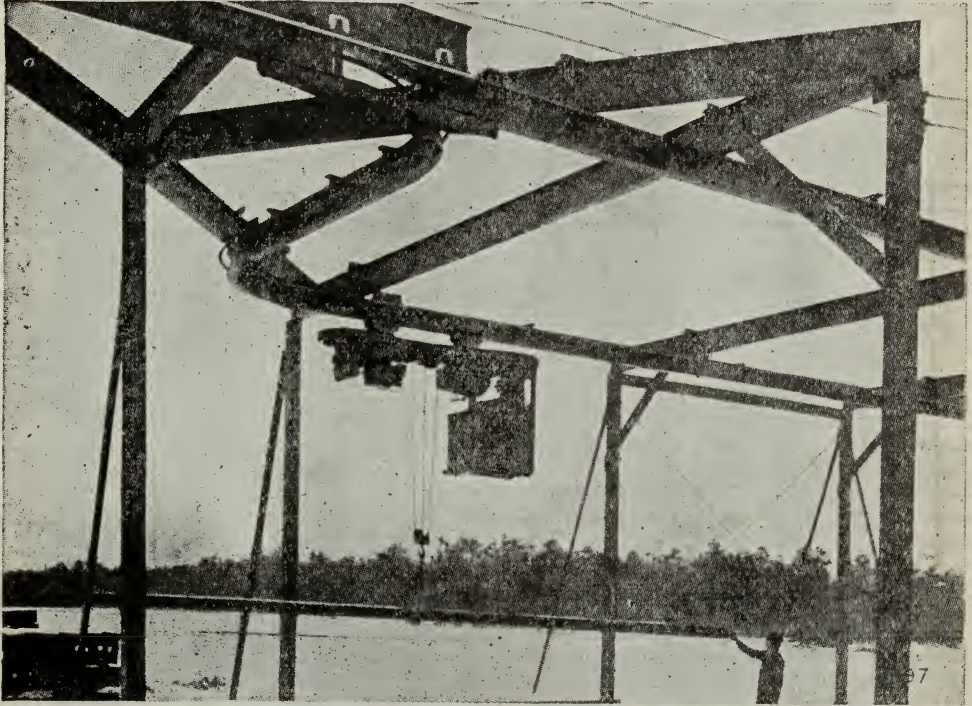


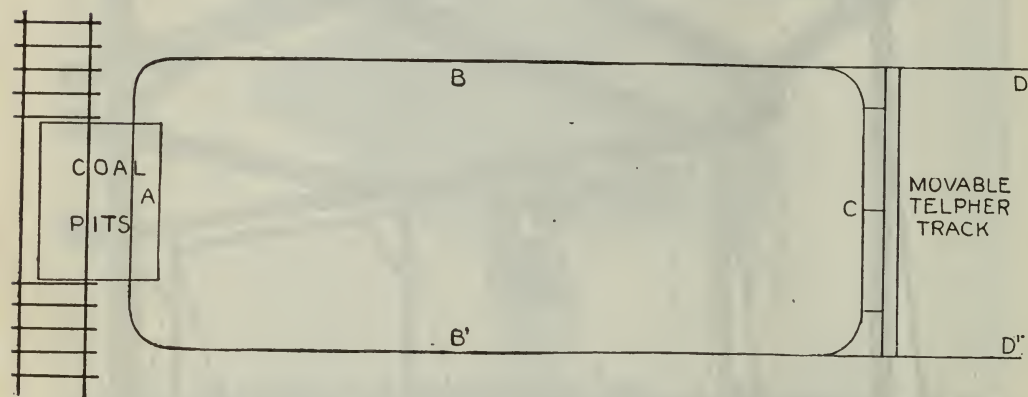
FIG. 4,238.—Shaw mono-rail system, showing fixed tongue track switch in upper foreground. The two I beams, as shown, constituting the main or shaft through track and the third I beam constituting the spur or curved track, terminals near the point of tangency of these center lines and have rigidly secured to each a cast steel extension piece or tongue, the projecting portion of which is on the same level as, and constitutes a continuation of, the bottom flange of the I beam. These tongues are so shaped as to leave between them open slots, through which the truck sides of the trolley pass, as it traverses the track switch. On approaching a track switch at which the operator desires to run from the main to the spur track, he pulls the steering lever, which is located on the trolley, near the controllers. This raises a horizontal roller to a position in which it engages a curved rib on the underside of the central switch tongue and swivels the leading truck, thereby diverting it on to the spur track. By a positive and very simple means, which is not dependent on the operator, the trailing truck is also guided on to the spur track. No steering is necessary to return from the spur to the main track, nor to run through the track switch on the main track in either direction. The hoist motion is equipped with motor and load brakes, the latter being of the multi-disc type and being located in the hoist gear case and lubricated by the same oil as the gears. The travel motion is equipped with a foot brake. An automatic limit stop is provided to prevent the lower block being accidentally wound up into the trolley machinery.

miscellaneous material, boxes, cases and barrels, the package freight of railways and the mixed cargoes of steamships.

**Ques. How is a telpher suspended, and driven?**

**Ans.** From one or more wheels in tandem, of which one or all are driven by the electric motor or motors.

In the minimum head room two ton type designed for railway and steamship terminals the vertical space from the underside of the roof girders to the bottom of the hoist hook is 4 ft. 9 in. (144.8 cm.). The



**FIG. 4,239.**—Typical arrangement of mono-rail tracks. The track is supported on brackets attached to buildings, or is supported on A bents. Supports under straight track are spaced 20 feet apart, and on curves, the spacing is 8 feet. For long spans, cables or trusses are used. The tracks may be either fixed or movable. In the figure, the side tracks BB' are fixed, but C is movable, being attached to a traveling bridge. The speed of this bridge is from 300 ft. to 900 ft. per min. The motor driving this bridge would have a load factor of .16. The telpher train is passed from these side tracks B', by means of a gliding switch upon the movable track C. This track therefore may be placed anywhere over the area between the fixed side tracks. The telpher returns by means of the track B', to its starting point A. By the operation of this movable track all the space can be served; this operation is called transferage. The minimum allowable radius of curves is 8 ft.

width of the hoist is 3 ft. 3 in., and 4 ft. 8 inches to the limit line for 10 degrees swing. From the center of the rail to the inner limit of the telpher and hoist is 16 inches.

**Ques. Describe the power features.**

**Ans.** Energy in the form of either direct or alternating current is communicated to the motors by conductors which lie



parallel to the track, the contact being made by shoes or wheels. Sometimes storage batteries suspended from the telpher or the carriage are employed. On steep grades the telpherage

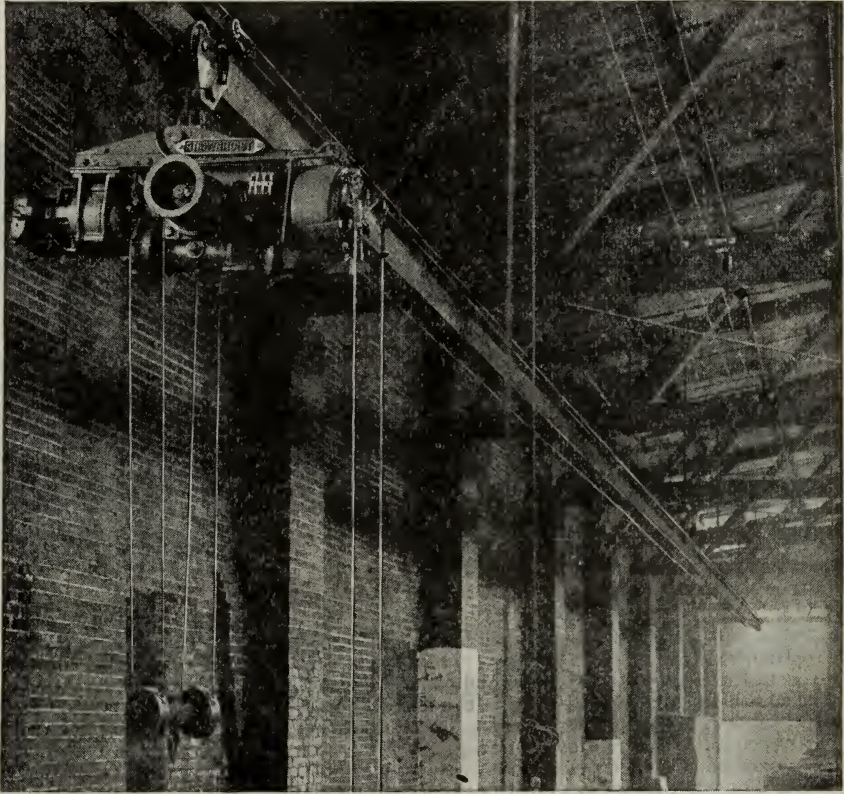


FIG. 4,240.—Brown electric hoist on plain steel plate trolley (clevis connection) as used by Pittsburgh Glass Co., in their warehouse at Cleveland, O. The hoist is operated from the floor and is used for loading, unloading, and transporting boxes of plate glass in the shipping department.

traction, in some installations, has been assisted by supplementary cables, either fixed or movable.

**Telpher Motors.**—The sizes of motor for telfers and hoists will depend upon the class of work to be done; the motors for telpher tractors vary from 5 to 15 h. p. and for the hoists,

from 3 to 75 h. p., the loads being from 500 lb. to 30,000 lb. The load factor for the tractor motor is .25 and for the hoisting motor .16. The driving wheels and the motors may be connected by gears or by chain drive. The maximum service efficiency of the motors is that corresponding to the efficiency obtained between one half and three-quarters full load. The motors are of slow or medium speed.

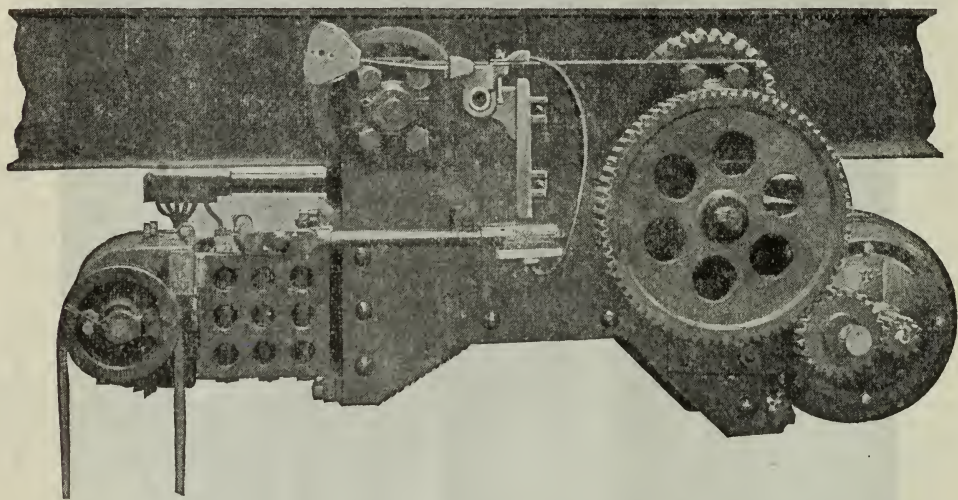


FIG. 4,241.—Brown motor driven trolley. *It consists of* two steel side plates connected by separator bolts. The steel pins which serve as axles for the wheels, are supported in castings which in turn are bolted to the side plates. These castings together with steel axles and wheels are easily removed. The wheels are bronze bushed and equipped with lubricating cups. The trolley is equipped with a crane motor for traveling under full load at a rate of 350 feet per minute on straight track. It is provided with a standard type controller with either pendent cords for floor operation, or handles for cab operation. It can be used with an electric hoist either hooked in, with a clevis connection, or built in. Current collectors are provided to take the current from wires or conductor bars strung along the I beam track.

Direct current 250 volt or, 500 volt series wound motors are preferable for tractors and hoists through alternating current motors afford satisfactory results. The motors should be dust and weather proof, and should have a 50 per cent. reserve in their rating. The average combined efficiency of the motors and gearing, for the tractor and hoist, is from 65 per cent. to 75 per cent.

**Brakes.**—The mechanical type of telfer brake is used and the hoist brake is of either the electro-mechanical or



electro-dynamic types. Spur gears and chain drive on the tractor transmit the power from motor to track wheels, and either spur or worm gear is used to transmit power to the hoisting drum.

**Trackage.**—Telfers either run in one direction on a closed track circuit, or to and fro over a single line. On the single line the automatic telfers reverse themselves on completing their trips.

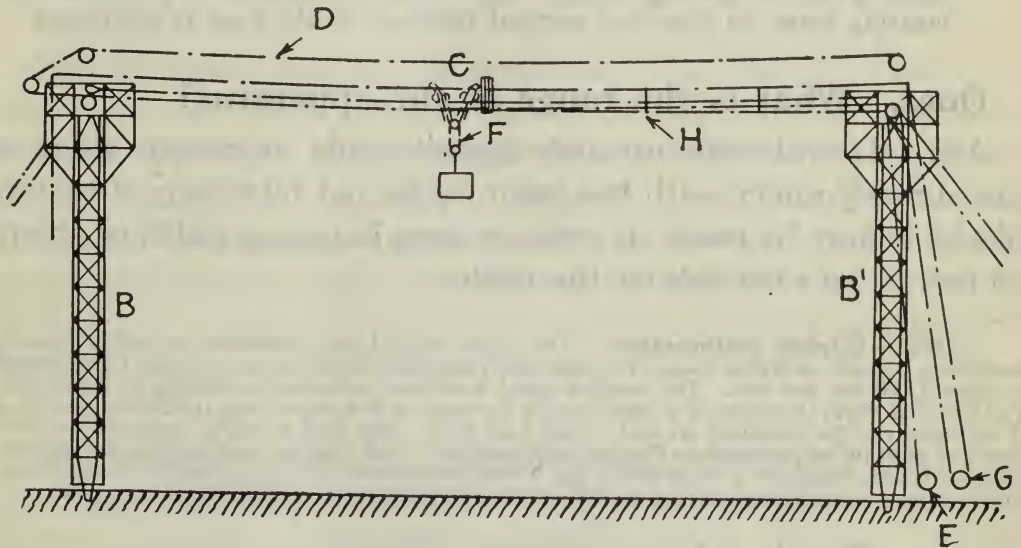


FIG. 4,242.—Cableway. The essential elements of construction are BB' towers; C, cable; D, hauling rope; E, hauling rope drum; F, hoisting rope; G, hoisting drum; H, hoisting rope slack carriers.

**Ques.** How is the spacing between the cars regulated?

**Ans.** Automatically by a block system.

**Essentials of Cableways.**—The term cableway may be defined as a rectilinear *hoisting and conveying apparatus supported by a cable*.

The elements of construction are shown in fig. 4,242. A strong steel wire rope or cable is stretched between the towers BB'. On this rope runs the carriage C, pulled backwards and forwards by the hauling rope

D, which is operated by the capstan drum E. One end of the hoisting rope F is secured to the carriage, and is led round the various pulleys shown and to the hoisting drum G.

The slack of the hoisting rope, when paying out, is supported by the carriers H. These carriers are dropped by the carriage when running from B to B', and are picked up again when returning from their position, being determined by buttons of different size arranged on the rope. Loads are hoisted and lowered by drum G, driver E being held by its brakes.

To travel the load, the two drums are clutched together. Driver E then hauls the carriage along, while drum G takes in or pays out the hoisting rope, so that the vertical position of the load is unaltered.

### **Ques. What is the range of the apparatus?**

Ans. It will take up and deposit loads anywhere along a line directly underneath the main cable, and by means of switch blocks it may be made to serve an area having a width of about 15 feet or so each side of the cable.

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**NOTE.—Telpher performance.** The loads hoisted and conveyed on telpher hoists have been as high as fifteen tons. The maximum speed of conveying on a straight level track is about 1,000 feet per min. The running speed is reduced at curves, according to their radii. For terminal work, the capacity of each hoist is two tons at 60 feet per min. (18.288 m. per min.) Two hoists can be combined so as to raise four tons. The motors being series wound, the speed of hoisting will increase as the load is diminished. For freight, handling from two to four carriage hoists constitute a train which has a total maximum carrying capacity of eight tons. Such trains are used for assorting as well as for distributing, according to consignments.



## CHAPTER LXXX

## ELECTRIC PUMPS

The electrical engineer or electrician who has to specify or install electric pumps, should not only understand the electrical features, but have a knowledge of the conditions of operation of the "water end" in order to respectively make proper selections and satisfactory installations. Accordingly each should at least be familiar with the elementary principles of hydraulics, of which an outline is here given as an introduction to the main subject.

**Hydraulics.**—The term *hydraulics* is commonly, though ill advisedly, defined as *the science which treats of liquids, especially water in motion*. **Properly speaking** there are two general divisions of the subject:

1. Hydrostatics;
2. Hydrodynamics.

Hydrostatics refers to liquids *at rest*, and hydrodynamics to liquids *in motion*. The outline here given relates to water.

**Water.**—Those who have had experience in the design or operation of pumps, have found that water is an unyielding substance when confined in pipes and pump passages, thus necessitating very substantial construction to withstand the pressure, and periodic shocks or water hammer.

Accordingly to Kopp, as corrected by Porter, the following table gives the relative volumes of water at different temperatures compared with its volume at its temperature of maximum density or 39.1° Fahr.

### Relative Volumes of Water at Different Temperatures

Degrees Fahr.	Volume	Degrees Fahr.	Volume	Degrees Fahr.	Volume
39.1	1.00000	95	1.00586	158	1.02241
41.0	1.00001	104	1.00767	167	1.02548
50.0	1.00025	113	1.00967	176	1.02872
59.0	1.00083	122	1.01186	185	1.03213
68.0	1.00171	131	1.01423	194	1.03570
77.0	1.00286	140	1.01678	203	1.03943
86.0	1.00425	149	1.01951	212	1.04332

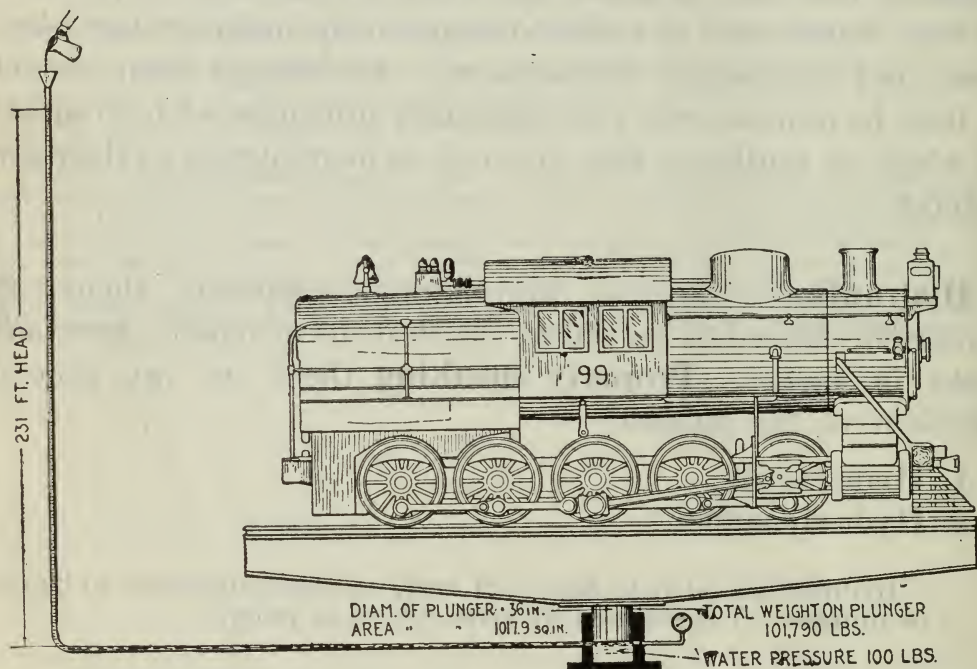


FIG. 4,243.—*Hydraulic principles: 1.* Any quantity of water however small may be made to balance any weight however great. The figure shows a locomotive on a turn table balanced by a hydraulic pivot or plunger. Assuming no leakage or friction at the joint, and that the vertical pipe leading to the plunger cylinder is very small, it is evident that it could be filled to the elevation shown with a very small quantity of water—say one quart. If the total weight of locomotive, turn table, etc., and the plunger be 101,790 lbs., and the plunger area be 1,017.9 sq. ins., then the water pressure per sq. in. on the piston necessary to balance the load =  $101,796 \div 1,017.9 = 100$  lbs. Hence the load will be balanced when the pipe is filled with water to a height of  $100 \times 2.31 = 231$  ft.



**Ques.** What is the most remarkable characteristic of water?

**Ans.** Water at its maximum density (39.1° Fahr.) will expand as heat is added, and it will also expand slightly as the temperature falls from this point.

**Ques.** What is the weight of a cubic foot of water at maximum density?

**Ans.** It is generally taken at the figure given by Rankine, 62.425 lbs. per cu. ft.

Some authorities give as low as 62.379. The figure 62.5 commonly given is approximate. The highest authoritative figure is 62.428. At 62° Fahr., the figures range from 62.291 to 62.36. *The figure 62.355 is generally accepted as the most accurate*, though for ordinary calculations the figure 62.4 is generally taken, this corresponding to the weight at 53° Fahr.

#### Weight of Water per Cubic Foot at Different Temperatures

Temp. deg. F.	Weight lbs. per cu. ft.	Temp. deg. F.	Weight lbs. per cu. ft.	Temp. deg. F.	Weight lbs. per cu. ft.	Temp. deg. F.	Weight lbs. per cu. ft.
32	62.42	80	62.23	130	61.56	180	60.55
35	62.42	85	62.18	135	61.47	185	60.44
40	62.42	90	62.13	140	61.37	190	60.32
45	62.42	95	62.08	145	61.28	195	60.20
50	62.41	100	62.02	150	61.18	200	60.07
55	62.39	105	61.96	155	61.08	205	59.95
60	62.37	110	61.89	160	60.98	209	59.84
65	62.34	115	61.82	165	60.87	210	59.82
70	62.31	120	61.74	170	60.77	211	59.79
75	62.28	125	61.65	175	60.66	212	59.76

**Ques.** What is the weight of one gallon of water?

**Ans.** For a U. S. gallon or 231 cu. ins., it is generally taken at  $8\frac{1}{3}$  lbs.

**Head and Pressure.**—These are the two primary considerations in hydraulics. The word head signifies *the difference in level of water between two points*, and it is usually expressed in feet.

There are two kinds of head:

1. Static head;
2. Dynamic head.

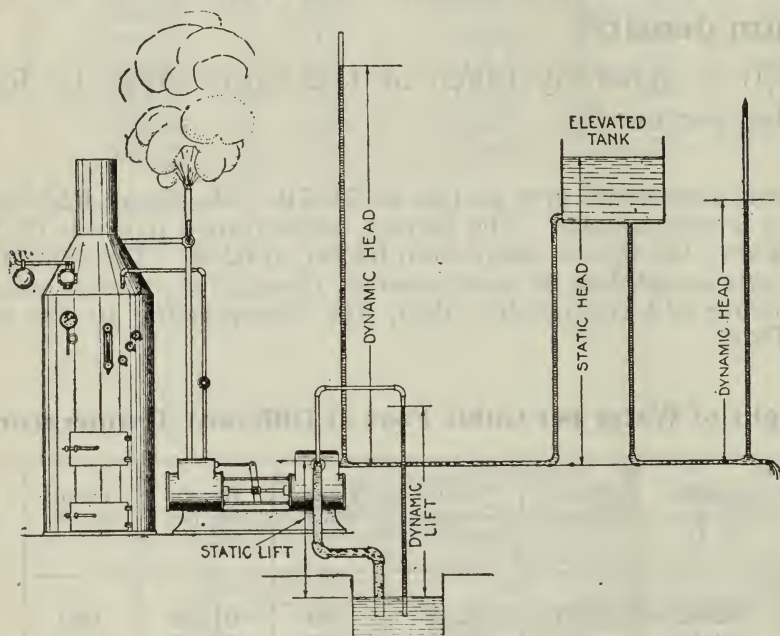


FIG. 4,244.—View of elevated tank with pump in operation maintaining the supply which is being drawn upon as shown, illustrating the terms static lift, dynamic lift, static head, and dynamic head.

**The static head** is the height from a given point of a column, or body of water at rest, considered as causing or measuring pressure.

**The dynamic head** is an equivalent or virtual head of water in motion which represents the resultant pressure due to the height of the water from a given point, and the resistance to flow due to friction.

Thus, when water is made to flow through pipes or nozzles there is a loss of head. These terms are illustrated in fig. 4,244. Here the dynamic head is *greater* than the static head in the supply line to the tank, and *less* in the tank discharge line because of frictional resistance to the flow of the water. The following table gives the loss of head due to friction of water in pipes of various sizes and for various rates of flow.



## Friction of Water in Pipes

Loss of head in feet due to Friction, per 100 feet of smooth, straight cast iron pipe

Gallons Per Minute	½-Inch Pipe		¾-Inch Pipe		1-Inch Pipe		1¼-Inch Pipe		1½-Inch Pipe		2-Inch Pipe		2½-Inch Pipe		3-Inch Pipe		4-Inch Pipe	
	Vel.	Frict.	Vel.	Frict.	Vel.	Frict.	Vel.	Frict.	Vel.	Frict.	Vel.	Frict.	Vel.	Frict.	Vel.	Frict.	Vel.	Frict.
2	2.10	5.30	1.20	1.40														
3	3.16	11.30	1.80	2.90	1.12	0.90												
4	4.21	19.20	2.41	5.00	1.49	1.52	0.86	0.40	0.63	0.187								
5	5.26	29.00	3.01	7.50	1.86	2.32	1.07	0.60	0.79	0.283	.51	.09	0.33	0.05				
10	10.52	105.00	6.02	27.10	3.72	8.40	2.14	2.18	1.57	1.02	1.02	.36	0.65	0.12	0.45	0.05		
15			9.02	57.00	6.13	18.90	3.92	4.65	2.72	2.25	1.53	0.81	0.98	0.25	0.68	0.11		
20			12.03	97.00	7.44	30.10	4.29	7.90	3.15	3.70	2.04	1.29	1.31	0.43	0.91	0.18		
25					9.30	45.50	5.36	11.90	4.56	5.60	2.55	1.96	1.63	0.66	1.13	0.27		
30					11.15	64.00	6.43	16.90	4.72	7.80	3.06	2.73	1.96	0.92	1.36	0.38		
35					13.02	85.00	7.51	22.30	5.51	10.30	3.57	3.66	2.29	1.23	1.59	0.51		
40					14.88	109.00	8.58	28.50	6.30	13.30	4.08	4.68	2.62	1.57	1.82	0.65	1.02	0.16
45							9.68	35.20	7.08	16.60	4.60	5.80	2.95	1.97	2.02	0.80	1.17	0.20
50							10.72	43.20	7.87	20.20	5.11	7.10	3.30	2.38	2.27	0.98	1.28	0.24
70							15.01	81.00	11.02	37.60	7.15	13.20	4.60	4.42	3.18	1.83	1.79	0.45
75									11.80	42.70	7.66	14.90	4.93	5.07	3.41	2.11	1.92	0.52
100									15.74	73.00	10.21	25.60	6.54	8.60	4.54	3.52	2.55	0.88
120											12.25	36.00	7.84	12.00	5.45	4.97	3.06	1.22
125											12.75	38.90	8.16	13.01	5.68	5.40	3.19	1.33
150											15.30	54.00	9.80	18.72	6.80	7.72	3.84	1.82
175													11.43	23.70	7.92	9.75	4.45	2.40
200													13.07	30.90	9.08	12.80	5.11	3.12
225															10.42	16.00	6.32	4.72
250															11.28	19.70	6.40	4.80
270															12.45	22.70	6.90	5.50
275															12.70	23.60	7.03	5.71
300															13.62	27.10	7.66	6.70
350																	8.90	8.80
400																	10.20	11.30
450																	11.50	14.10
470																	12.16	16.00
475																	12.30	16.40
500																	12.77	17.20

Gallons Per Minute	5-Inch Pipe		6-Inch Pipe		8-Inch Pipe		10-Inch Pipe		12-Inch Pipe		16-Inch Pipe		20-Inch Pipe		24-Inch Pipe		30-Inch Pipe	
	Vel.	Frict.	Vel.	Frict.	Vel.	Frict.	Vel.	Frict.	Vel.	Frict.	Vel.	Frict.	Vel.	Frict.	Vel.	Frict.	Vel.	Frict.
70	1.14	0.15																
100	1.63	0.29	1.14	0.10														
120	1.96	0.41	1.42	0.18														
125	2.04	0.46	1.48	0.20														
150	2.45	0.63	1.71	0.23														
175	2.86	0.84	2.00	0.34														
200	3.27	1.06	2.28	0.44														
225	3.67	1.33	2.57	0.53														
250	4.08	1.60	2.80	0.66	1.60	0.16												
270	4.42	1.86	3.03	0.81	1.70	0.18												
275	4.50	1.94	3.06	0.82	1.73	0.19												
300	4.90	2.25	3.40	0.92	1.90	0.26												
350	5.72	2.99	3.98	1.21	2.20	0.29												
400	6.54	3.81	4.54	1.58	2.60	0.40												
450	7.35	4.75	5.12	1.96	2.92	0.46	1.80	0.150										
470	7.78	5.30	5.49	2.23	3.07	0.55	1.92	0.170										
500	8.17	5.80	5.60	2.33	3.20	0.58	2.04	0.200	1.42	0.08								
550	8.99	6.90	6.16	2.81	3.52	0.70	2.25	0.236	1.57	0.098								
600	9.80	8.10	6.72	3.36	3.84	0.83	2.46	0.282	1.71	0.106								
650	10.62	9.40	7.28	3.93	4.16	0.96	2.66	0.327	1.85	0.134								
700	11.44	10.80	7.84	4.56	4.46	1.10	2.86	0.368	2.00	0.154								
750	12.26	12.30	8.50	5.00	4.80	1.24	3.06	0.422	2.13	0.170								
800			9.08	5.64	5.12	1.41	3.28	0.476	2.27	0.196								
850			9.58	6.25	5.48	1.63	3.48	0.534	2.41	0.22								
900			10.30	7.22	5.75	1.76	3.68	0.592	2.56	0.24								
950			10.72	7.65	6.06	2.05	3.88	0.653	2.70	0.25								
1000			11.32	8.60	6.40	2.16	4.08	0.718	2.84	0.295								
1100			12.50	10.22	7.03	2.51	4.50	0.860	3.13	0.35								
1200			13.52	11.92	7.67	3.04	4.91	1.040	3.41	0.41								
1500					9.60	4.48	6.10	1.490	4.20	0.61	2.39	0.171						
2000					12.70	7.65	8.10	2.500	5.60	1.02	3.19	0.280						
2500							10.10	3.810	7.00	1.56	3.99	0.397						
3000							12.10	5.300	8.40	2.42	4.79	0.568	3.08	0.191				
3500							14.10	7.200	9.80	2.80	5.59	0.745	3.59	0.251				
4000									11.35	3.80	6.38	0.956	4.10	0.323				
5000									14.20	5.82	7.96	0.144	5.13	0.488	3.55	0.199	2.27	0.067

When pipe is slightly rough, add 15 per cent. When very rough, add 30 per cent.  
 Vel.—Velocity feet per second. Frict.—Friction head in feet.

## Friction of Water in Elbows

Loss of head in feet, due to friction in various sizes of smooth 90° elbows when discharging the given quantities of water

Gals. per Minute	1-Inch		1½-Inch		1½-Inch		2-Inch		2½-Inch		3-Inch		4-Inch		5-Inch		6-Inch		8-Inch		10-Inch		12-Inch	
	Vel.	Fric.	Vel.	Fric.	Vel.	Fric.	Vel.	Fric.	Vel.	Fric.	Vel.	Fric.	Vel.	Fric.	Vel.	Fric.	Vel.	Fric.	Vel.	Fric.	Vel.	Fric.	Vel.	Fric.
5	2.04	0.06	1.30	0.14																				
10	4.08	0.22	2.60	0.21																				
15	6.12	0.49	3.90	0.29	2.73	0.09																		
20	8.16	0.87	5.20	0.52	3.64	0.16																		
25	10.20	1.35	6.50	0.80	4.55	0.25																		
30	12.24	1.95	7.80	1.15	5.46	0.36	3.06	0.13																
35	14.28	2.65	9.10	1.60	6.37	0.50	3.57	0.18	2.29	0.09														
40	16.32	3.46	10.40	2.05	7.28	0.64	4.05	0.23	2.62	0.11														
45			11.70	2.70	8.19	0.81	4.60	0.29	2.95	0.14	2.02	0.06												
50					9.10	0.99	5.11	0.35	3.30	0.18	2.27	0.08												
70					12.74	1.98	7.15	0.70	4.50	0.34	3.18	0.19												
100							10.20	1.41	6.54	0.74	4.54	0.29	1.79	0.05										
120							12.25	2.24	7.84	1.17	5.45	0.46	3.06	0.15	1.96	0.06								
150							15.30	3.20	9.80	1.58	6.80	0.66	3.84	0.22	2.45	0.09								
175									11.43	2.16	7.92	0.90	4.45	0.30	2.86	0.12	2.00	0.06						
200									13.07	2.96	9.08	1.18	5.11	0.40	3.27	0.16	2.28	0.07						
250											11.28	1.84	6.40	0.62	4.08	0.25	2.80	0.12	1.60	0.04				
270											12.45	2.35	6.90	0.70	4.42	0.25	3.03	0.14	1.70	0.05				
300											13.62	2.63	7.68	0.89	4.90	0.36	3.40	0.18	1.90	0.08				
350													8.90	1.24	5.72	0.50	3.98	0.24	2.20	0.09				
400													10.20	1.59	6.54	0.63	4.54	0.29	2.60	0.10				
450													11.50	2.01	7.35	0.81	5.12	0.39	2.92	0.13	1.80	0.05		
470													12.16	2.26	7.78	0.90	5.49	0.46	3.07	0.14	1.92	0.06		
500													12.77	2.47	8.17	1.01	5.60	0.48	3.20	0.16	2.00	0.07	1.40	0.04
750															12.26	2.24	8.40	1.09	4.80	0.36	3.00	0.15	2.10	0.07
1050																	12.57	2.41	7.04	0.78	4.40	0.28	3.08	0.14
1250																	14.10	3.02	8.00	1.00	5.00	0.40	3.50	0.20
1500																		9.60	1.44	6.10	0.58	4.20	0.20	3.9

When pipe is slightly rough, add 15 per cent. When very rough, add 30 per cent.

Vel.—Velocity in feet per second. Fric.—Friction head in feet.

Table shows loss for one elbow, and is based on Weisbach's Formula for short radius bends.

The term pressure is used in its ordinary sense in terms of pounds per square inch. At 62° Fahr. the pressure per square inch of a column of water of one foot head is .43302, or .433 lbs. At this temperature one cubic foot of water would weigh  $.433 \times 144 = 62.352$ . On this basis the pressure in pounds per square inch for different heads of water are as given in the following table.

## Pressure per Lb. per Sq. Ins. Corresponding to Various Heads of Water

Head feet	0	1	2	3	4	5	6	7	8	9
0		0.433	0.866	1.299	1.732	2.165	2.598	3.031	3.464	3.897
10	4.330	4.763	5.196	5.629	6.062	6.495	6.928	7.361	7.794	8.227
20	8.660	9.093	9.526	9.959	10.392	10.825	11.258	11.691	12.124	12.557
30	12.990	13.423	13.856	14.289	14.722	15.155	15.588	16.021	16.454	16.887
40	17.320	17.753	18.186	18.619	19.052	19.485	19.918	20.351	20.784	21.217
50	21.650	22.083	22.516	22.949	23.382	23.815	24.248	24.681	25.114	25.547
60	25.980	26.413	26.846	27.279	27.712	28.145	28.578	29.011	29.444	29.877
70	30.310	30.743	31.176	31.609	32.042	32.475	32.908	33.341	33.774	34.207
80	34.640	35.073	35.506	35.939	36.372	36.805	37.238	37.671	38.104	38.537
90	38.970	39.403	39.836	40.269	40.702	41.135	41.568	42.001	42.436	42.867



Head in Feet of Water Corresponding to Various Pressures

Pressure	0	1	2	3	4	5	6	7	8	9
0		2.309	4.619	6.928	9.238	11.547	13.857	16.166	18.476	20.785
10	23.0947	25.404	27.714	30.023	32.333	34.642	36.952	39.261	41.570	43.880
20	46.1894	48.499	50.808	53.118	55.427	57.737	60.046	62.356	64.665	66.975
30	69.2841	71.594	73.903	76.213	78.522	80.831	83.141	85.450	87.760	90.069
40	92.3788	94.688	96.998	99.307	101.62	103.93	106.24	108.55	110.85	113.16
50	115.4735	117.78	120.09	122.40	124.71	127.02	129.33	131.64	133.95	136.26
60	138.5682	140.88	143.19	145.50	147.81	150.12	152.42	154.73	157.04	159.35
70	161.6629	163.97	166.28	168.59	170.90	173.21	175.52	177.83	180.14	182.45
80	184.7576	187.07	189.38	191.69	194.00	196.31	198.61	200.92	203.23	205.54
90	207.8523	210.16	212.47	214.78	217.09	219.40	221.71	224.02	226.33	228.64

In ordinary calculation, it is common practice to estimate that every foot head is equal to one-half pound pressure per square inch, as this allows for ordinary friction in pipes.

**Ques.** In pump operation what is the total static head?

**Ans.** The static lift plus the static head.

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**Ans.** The dynamic lift plus the dynamic head.

**Lift.**—When the barometer reads 30 inches at sea level, the pressure of the atmosphere at that elevation is 14.73 lbs. per sq. in., that is to say, this pressure will maintain or balance a column of water 34.019 ft. high when the column is completely exhausted of air, and the water is at a temperature of 62° Fahr. In other words, the pressure of the atmosphere then *lifts* the water to such height as will establish equilibrium between the weight of the water and the pressure of the air. Similarly in pump operation, the receding piston or plunger establishes the vacuum and the pressure of the atmosphere lifts the water from the level of the supply to the level of the pump. Accordingly

**lift** as relating to pump operation may be defined as *the height in feet from the surface of the intake supply to the pump.*

Strictly speaking, it is the height to which the water is elevated by atmospheric pressure, which in some pumps may be measured by the elevation of the inlet valves and in others by the elevation of the piston.

**Ques.** What is the practical limit of lift?

**Ans.** 20 to 25 ft.

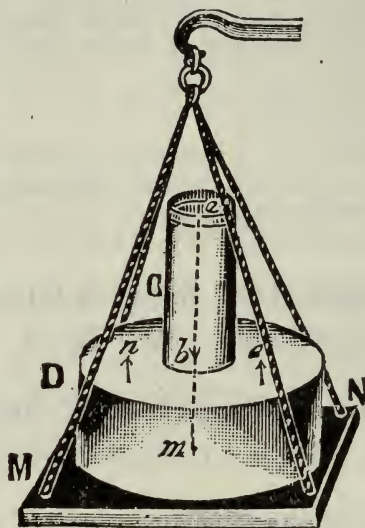


FIG. 4,245.—**Hydraulic principles:** 2. *Pressure exerted anywhere upon a mass of liquid is transmitted undiminished in all directions, and acts with the same force on all equal surfaces, and in a direction at right angles to those surfaces.* CD (fig. 4,245) is a vessel composed of two cylindrical parts of unequal diameters, and filled with water to *a*. The bottom of the vessel CD supports the same pressure as if its diameter were everywhere the same as that of its lower part; and it would at first sight seem that the scale MN of the balance in which the vessel CD is placed, ought to show the same weight as if there had been placed in it a cylindrical vessel having the same weight of water, and having the diameter of the part D. But the pressure exerted on the bottom of the vessel is not all transmitted to the scale MN; for the *upward* pressure upon the surface *n o* of the vessel is precisely equal to the weight of the *extra* quantity of water which a cylindrical vessel would contain, and balances an equal portion of the *downward* pressure on *m*. Consequently the pressure on the plate MN is simply equal to the weight of the vessel CD and of the water which it contains.

**Ques.** What conditions would require shorter lifts?

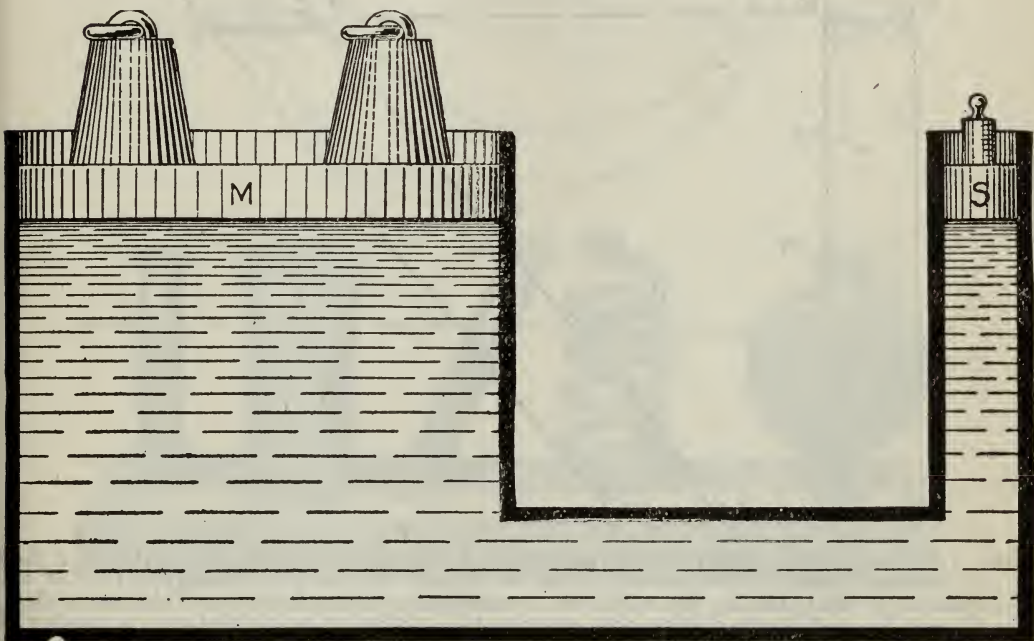
**Ans.** Long inlet lines, multiplicity of inlet elbows, and high temperature of the water.



**Ques.** Why must the lift be reduced as the temperature of the water is increased?

**Ans.** Because the boiling point of water corresponds to the pressure.

Theoretically a perfect pump will draw water from a height of 34 ft. when the barometer reads 30 ins., but since a perfect vacuum cannot be obtained on account of valve leakage, air contained in the water *and the vapor of the water itself*, the actual height is generally less than 30 feet, and for warm or hot water considerably less.



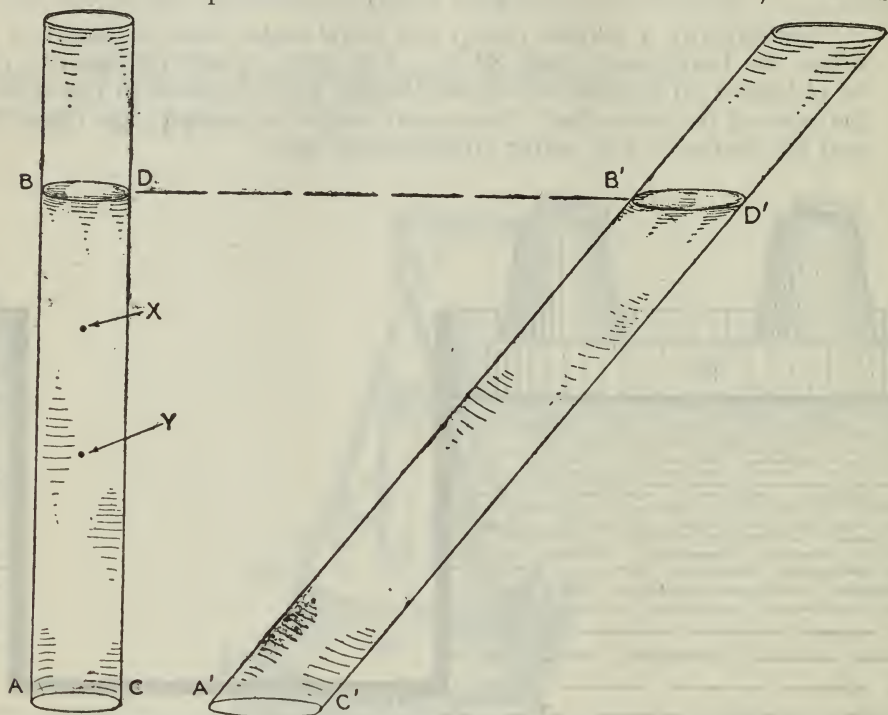
**FIG. 4,246.—Hydraulic principles:** 3. *The pressure exerted by a liquid on a surface is proportional to the area of the surface.* Two cylinders of different diameter are joined by a tube and filled with water. On the surface of the two pistons M and S, which hermetically close the cylinders, but move without friction. Let the area of the large piston M be, say thirty times that of the smaller one S, and let a weight, say of two pounds, be placed upon the small piston. The pressure will be transmitted to the water and to the large piston, and as this pressure amounts to two pounds in each portion of its surface equal to that of the small piston, the large piston must be exposed to an upward pressure thirty times as much, or 60 lbs. If now a 60 lb. weight be placed upon the large piston, both pistons will remain in equilibrium, but if the weight be greater or less, the equilibrium will be destroyed.

When the water is warm, the height to which it can be lifted decreases, on account of the increased pressure of the vapor. That is to say, for illustration, a boiler feed pump taking water at say 153° Fahr., could not produce a vacuum greater than 21.78 ins., because at that point

the water would begin to boil and fill the pump chamber with steam. Accordingly, the theoretical lift corresponding would be

$$34 \times \frac{21.78}{30} = 24.68 \text{ ft. approximately.}$$

The result is approximate because no correction has been made for the 34 which represents a 34 foot column of water at 62°; of course, at

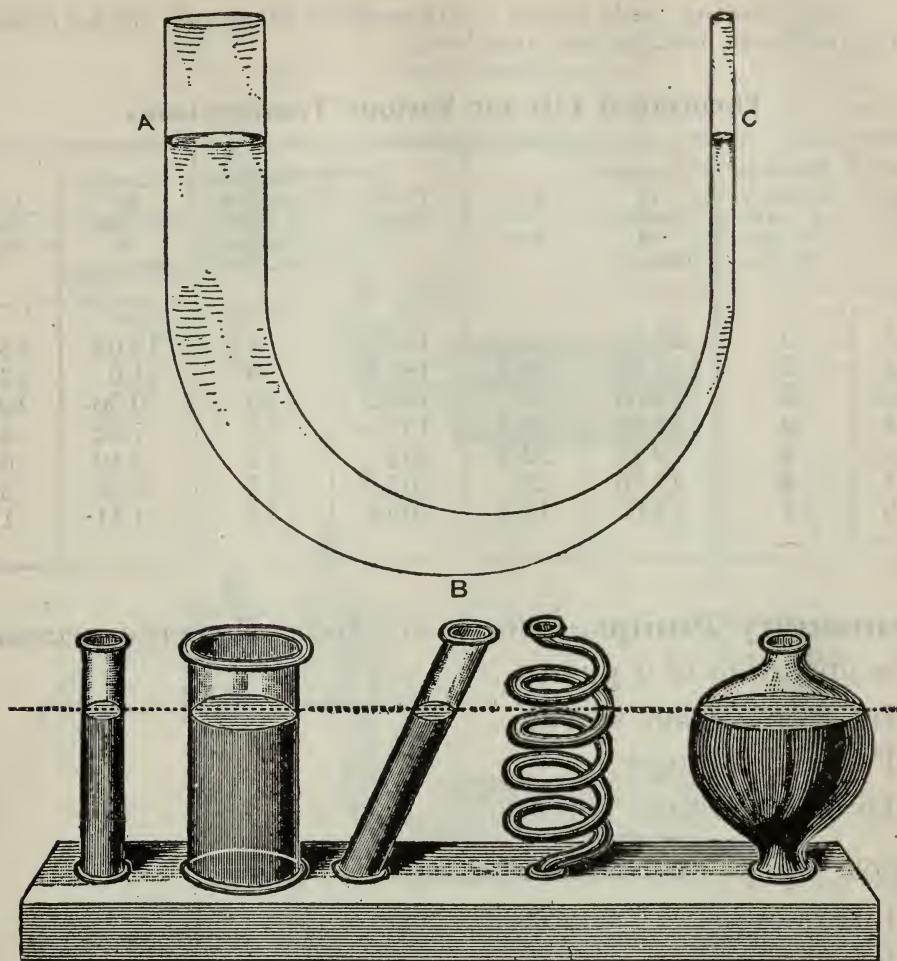


FIGS. 4,247 and 4,248.—**Hydraulic principles:** 4. *The pressure upon any particle of a fluid of uniform density is proportional to its depth below the surface.* **Example 1.** Let the column of fluid ABCD, fig. 4,247, be perpendicular to the horizon. Take any points, X and Y, at different depths, and conceive the column to be divided into a number of equal space by horizontal planes. Then, since the density of the fluid is uniform throughout, the pressure upon X and Y, respectively, must be in proportion to the number of equal space above them, and consequently in proportion to their depths. **Example 2.** Let the column be of the same perpendicular height as before, but inclined as is fig. 4,248; then its quantity, and of course its weight, is *increased* in the same ratio as its length exceeds its height; but since the column is partly supported by the plane, like any other heavy body, the force of gravity acting upon it is *diminished* on this account in the same ratio as its length exceeds its height; therefore as much as the pressure on the base would be augmented by the increased length of the column, just so much it is lessened by the action of the inclined plane, and the pressure of any part of C'D' will be, as before, proportioned to its perpendicular depth, and the pressure of the inclined column A'C'D'B' will be the same as that of the perpendicular column ABCD.

153° the length of such column would be slightly increased.

It should be noted that the figure 24.68 ft. is the *approximate* theoretical lift for water at 153°; the *practical* lift would be considerably less.





FIGS. 4,249 and 4250.—**Hydraulic principles:** 5. *Fluids rise to the same level in the opposite arms of a U tube.* Let A B C be a recurved tube; if water be poured into one arm of the tube, it will rise to the same height in the other arm because the pressure acting upon the lowest part at B, in opposite directions, is proportioned to its depth below the surface of the fluid. Therefore, these depths must be equal, that is, the height of the two columns must be equal, in order that the fluid at B may be at rest. Unless this part be at rest, the other parts of the column cannot be at rest. Moreover, since the equilibrium depends on nothing else than the heights of the respective columns, therefore, the opposite columns may differ to any degree in quantity, shape, or inclination to the horizon. Thus, if vessels and tubes vary diversely in shape and capacity, as in fig. 4,250, be connected with a reservoir, and water be poured into any one of them, it will rise to the same level in all of them. The reason of this fact will be further understood from the application of the principle of equal moments, for it will be seen that the velocity of the columns, when in motion, will be as much greater in the smaller than in the larger columns, as the quantity of matter is less; and hence the opposite moments will be constantly equal. Hence, water conveyed in aqueducts or running in natural channels, will rise just as high as its source. Between the place where the water of an aqueduct is delivered and the spring, the ground may rise into hills and descend into valleys, and the pipes which convey the water may follow all the undulations of the country, and the water will run freely, provided no pipe be laid higher than the spring

The following table shows the theoretical maximum lift for different temperatures, leakage not considered.

**Theoretical Lift for Various Temperatures**

Temp. Fahr.	Absolute pressure of vapor lbs. per sq. ins.	Vacuum in inches of mercury	Lift in feet	Temp. Fahr.	Absolute pressure of vapor lbs. per sq. ins.	Vacuum in inches of mercury	Lift in feet
102.1	1	27.88	31.6	182.9	8	13.63	15.4
126.3	2	25.85	29.3	188.3	9	11.6	13.1
141.6	3	23.83	27	193.2	10	9.56	10.8
153.1	4	21.78	24.7	197.8	11	7.52	8.5
162.3	5	19.74	22.3	202	12	5.49	6.2
170.1	6	17.70	20	205.9	13	3.45	3.9
176.9	7	15.67	17.7	209.6	14	1.41	1.6

**Elementary Pumps.**—There are three elements necessary for the operation of a pump:

1. Inlet or suction valve;
2. Piston or plunger;
3. Discharge valve.

Simple pumps may be divided into two classes:

1. Lift pumps;
2. Force pumps.

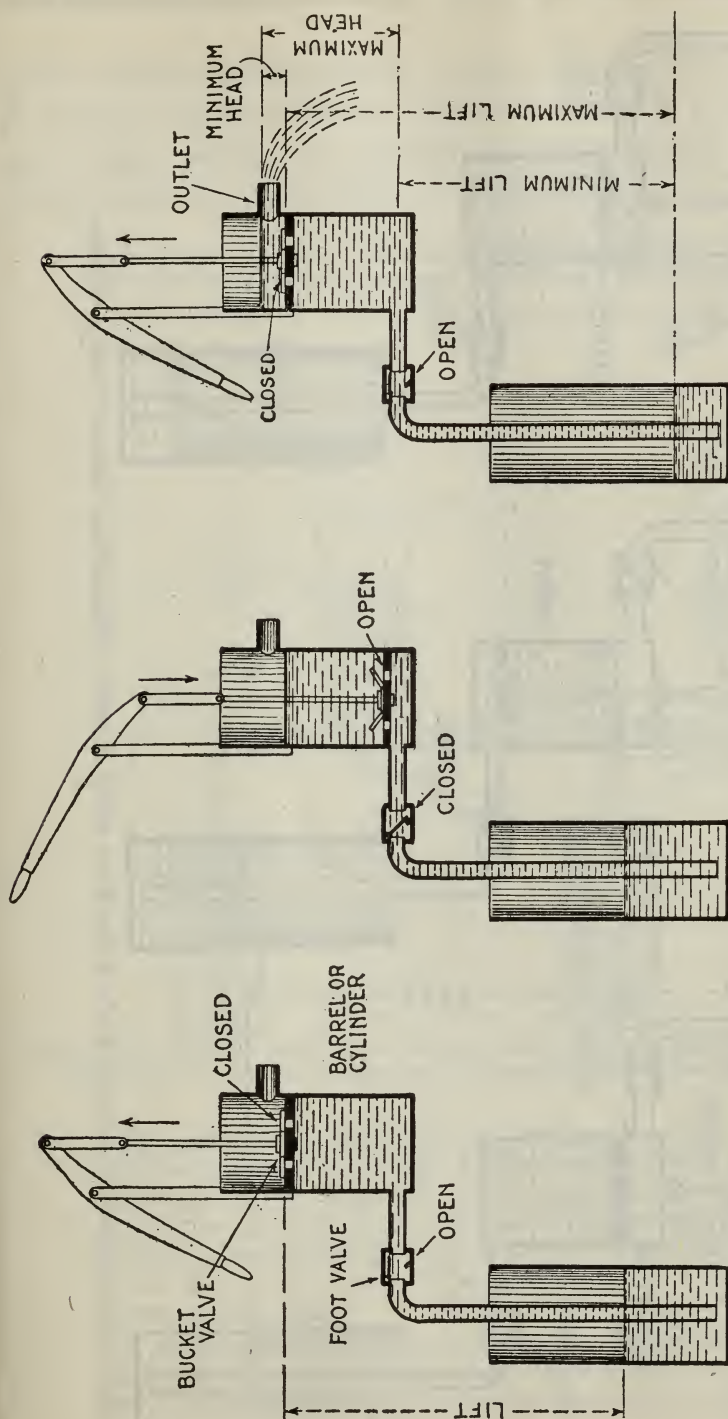
A lift pump is one which does not elevate the water higher than the lift; a force pump operates against both lift and head.

**Lift Pumps.**—Figs. 4,251 to 4,253 show the essentials and working principle of a simple lift pump.

**In construction** there are two valves in this type of pump, which are known as the foot valve and the bucket valve. **In operation** during the up stroke the bucket valve is closed and foot valve open, allowing the atmosphere to force the water into the cylinder.

When the piston begins to descend, the foot valve closes and bucket





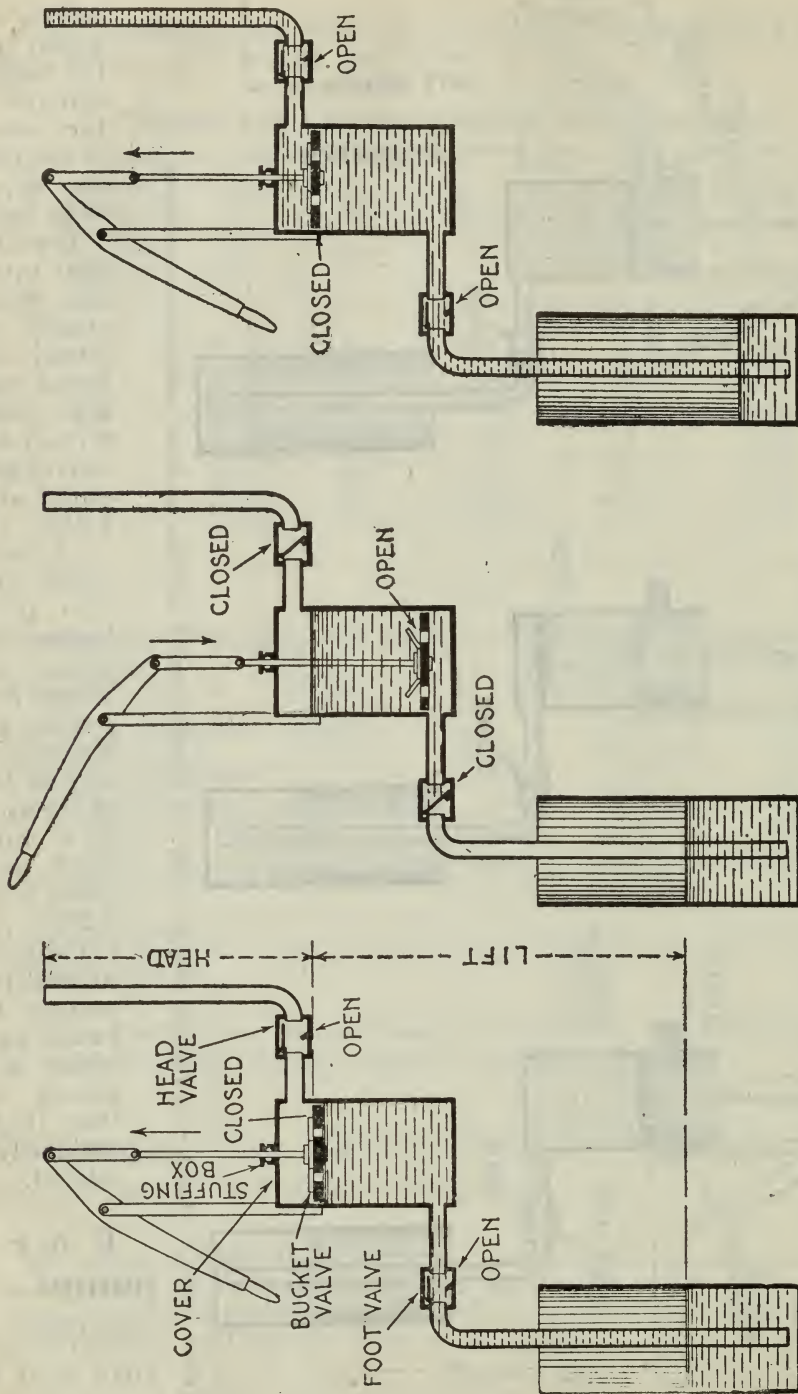
Figs. 4,251 to 4,253.—Elementary single acting lift pump showing essential features and cycle of operation.

valve opens, which transfers the water in the cylinder from the lower side of the piston to the upper side as in fig. 4,252.

During the next up stroke, the water, already transferred to the upper side of the piston, is discharged through the outlet as in fig. 4,253.

It will be noted that as the piston begins the up stroke of discharge it is subject to a small maximum head, and at the end of the up stroke to a minimum head as indicated in fig. 4,253. This variable head is so small in comparison to the head against which a force pump works that it is not ordinarily considered.

**Force pumps.**—The essential feature of a force



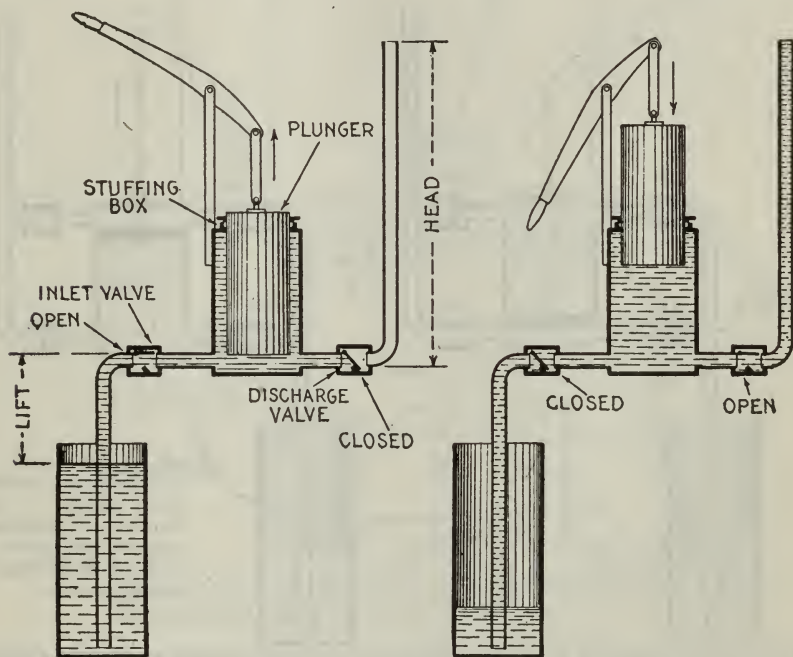
FIGS. 4,254 to 4,256.—Elementary single acting force pump showing distinguishing feature of closed cylinder.



pump which distinguishes it from a lift pump is that *the cylinder is always closed*, whereas in a lift pump it is **alternately** closed and open when the piston is respectively at the upper and lower ends of its stroke.

As shown in figs. 4,254 to 4,256, the cylinder top is closed by a cover, the piston rod passing through a stuffing box; this keeps the cylinder closed.

In addition to the foot and bucket valves of the lift pump, a head valve is provided.



FIGS. 4,257 and 4,258.—Elementary single acting plunger pump showing essential parts. The distinction between a plunger and a piston should be carefully noted.

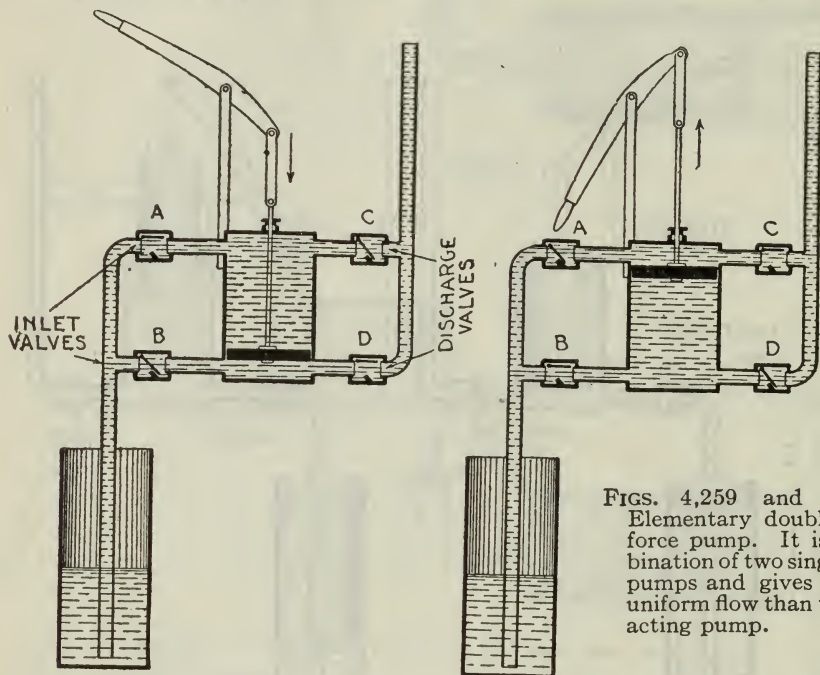
**In operation,** during the up stroke, atmospheric pressure forces water into the cylinder as in fig. 4,254; during the down stroke this water is transferred from the lower to the upper side of the piston as in fig. 4,255; during the next up stroke, the piston forces the water out of the cylinder through the head valve which closes when the piston reaches the end of the stroke and the cycle is repeated. The positions of the valve are shown in the cuts.

A simple form of force pump, is one known as a single acting plunger pump, a type extensively used, its cycle of operation being shown in figs. 4,257 and 4,258. The figures show the distinguishing features, such as closed cylinder, plunger, and only two valves.

**In operation** during the up stroke water fills the cylinder, inlet valve opens, and outlet valve closes, as shown in fig. 4,257. During the down stroke, the plunger "displaces" the water in the barrel, forcing it through the discharge valve against the pressure due to the head.

**Ques.** What is the difference between a piston and a plunger?

**Ans.** A piston is *shorter* than the stroke, whereas a plunger is *longer* than the stroke.



FIGS. 4,259 and 4,260.—Elementary double acting force pump. It is a combination of two single acting pumps and gives a nearer uniform flow than the single acting pump.

The word plunger is very frequently used *erroneously* for piston even by those who ought to know better.

**Double Acting Force Pump.**—By fitting a set of inlet and outlet valve at each end of a pump cylinder it is rendered **double acting**, that is, a cylinder full of water is pumped each stroke instead of every other stroke.

With this arrangement the piston need have approximately only half the area of the single acting piston for equal displacement, and accordingly the maximum stresses brought on the reciprocating parts are reduced approximately one-half, thus permitting lighter and more compact construction.



In the double acting pump there are no bucket valves, a solid piston being used. The essential features and operation are plainly shown in figs. 4,259 and 4,260. There are two inlet valves A, B, and two discharge valves C, D, the cylinder being closed and provided with a piston.

**In operation** during the down stroke, water follows the upper face of the piston through valve A. At the same time the previous

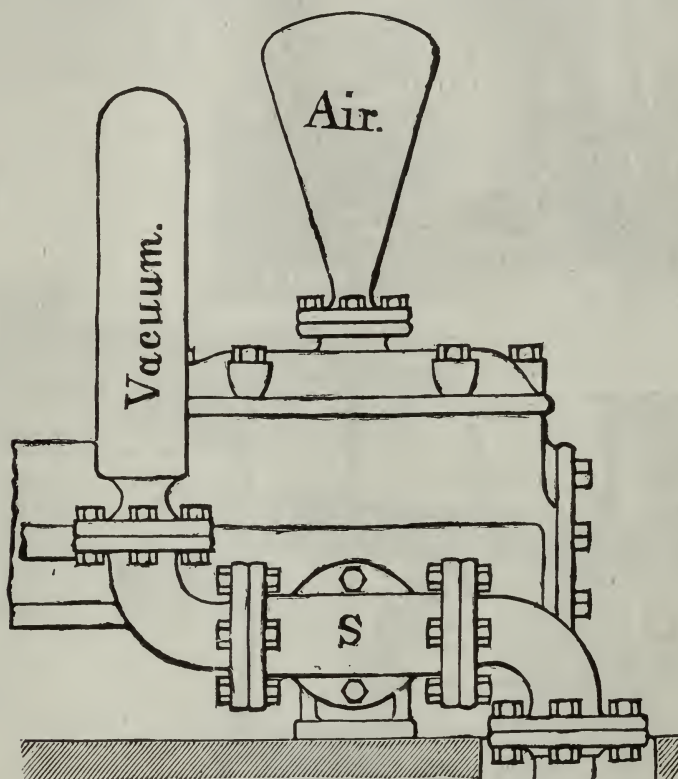
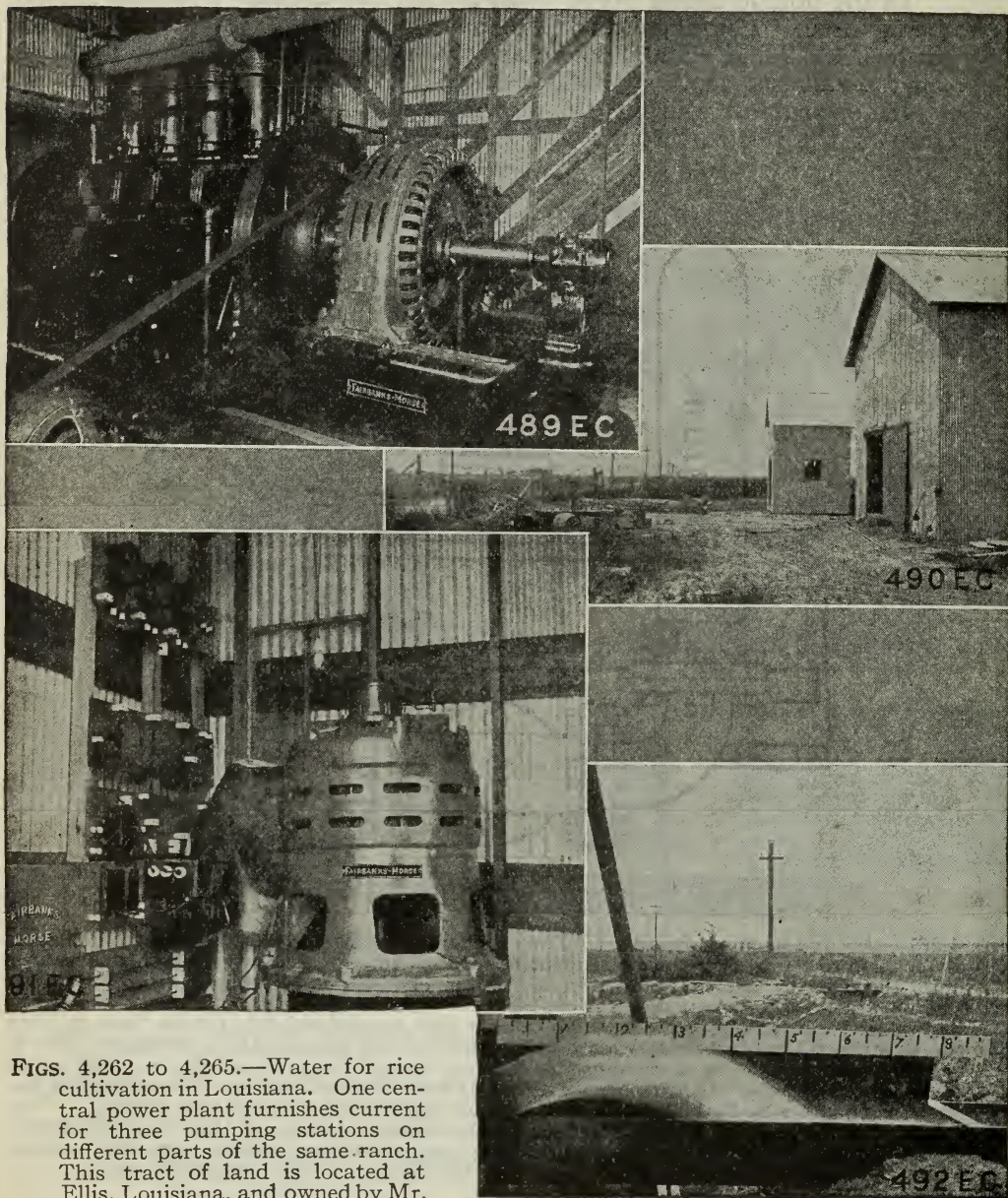


FIG. 4,261.—Air and vacuum chambers. The air chamber is for the purpose of introducing an air cushion to counteract the solidity of the water, thus preventing shocks as the water flows through the valves. Similarly, a vacuum chamber is sometimes attached to the suction pipe. When the column of water in the suction pipe of a pump is once set in motion, it is quite important, especially under high speeds and long intake lines, to keep the water in full motion, and when it is stopped, to stop it gradually and easily. This is accomplished by placing a vacuum chamber on the suction pipe, as shown. *The action of the vacuum chamber is practically the reverse of that of the air chamber.* The object of the vacuum chamber is to facilitate changing continuous into intermittent motion. The moving column of water compresses the air in the vacuum chamber at the ends of the stroke of the piston, and when the piston starts the air expands. (thus creating a partial vacuum above the water) and aids the piston in setting the column of water in motion again.

charge is forced out of the cylinder through valve D, by the lower face of the piston. During these simultaneous operations, valves A, and D, remain open, and B, and C, closed, as in fig. 4,259.

During the up stroke, water follows the lower face of the piston through valve B. At the same time, the previous charge is forced out



FIGS. 4,262 to 4,265.—Water for rice cultivation in Louisiana. One central power plant furnishes current for three pumping stations on different parts of the same ranch. This tract of land is located at Ellis, Louisiana, and owned by Mr. Floyd Williams. The motive power is a 200 horse power four cylinder oil engine direct connected to a 170 kva. 2,300 volt alternator. The current at this voltage is distributed over their own transmission line to three pumping stations. One station is located near the power plant, another  $\frac{1}{2}$  mile away and the third  $1\frac{1}{4}$  miles away. Each pumping plant is equipped with a 75 horse power vertical 2,200 volt motor, direct connected to a vertical centrifugal pump. Each one of these pumps has a capacity of 3,000 to 4,000 gallons per minute, and irrigates about 250 acres of land.



of the cylinder through valve C, by the upper face of the piston. During these simultaneous operations, valves B, and C, remain open, and A, and D, closed.

**Air Chambers.**—These are placed upon pumps on the head or discharge side of the discharge valve, and contain air for the purpose of introducing an *air cushion* to counteract the solidity of the water, thus preventing shocks or *water hammer* as the water flows through the valves; and also for the purpose of securing a steady discharge of water.

The water being under pressure in the discharge chamber, compresses the air in the air chamber during each stroke of the water piston and, when the piston stops momentarily at the end of the stroke, the air expands to a certain extent and tends to produce a gradual stopping of the flow of water, thus permitting the valves *to seat easily and without shock or jar*.

*The capacity of the air chamber varies in different makes of pump from 2 to  $3\frac{1}{2}$  times the volume of the water cylinder in single cylinder pumps, and from 1 to  $2\frac{1}{2}$  times the volume of the water cylinder in the duplex type. The volume of the water cylinder is represented by the area of the water piston multiplied by the length of stroke.*

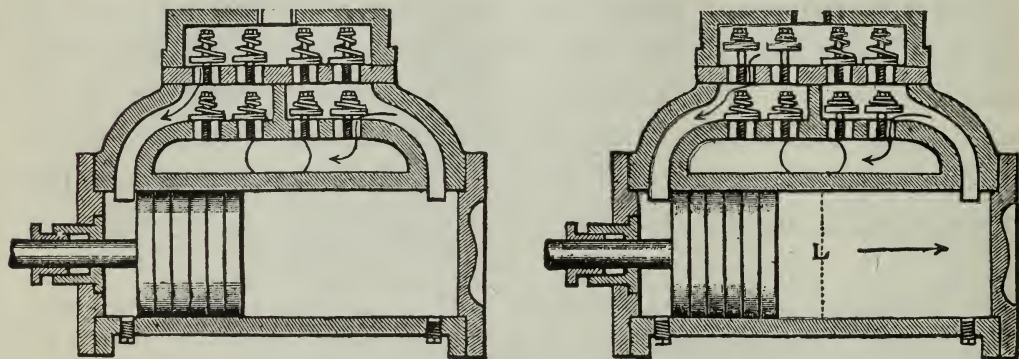
For single cylinder, boiler feed pumps and those employed for elevator and similar service the volume of the air chamber should be 3 times the volume of the water cylinder, and for duplex pumps, not less than twice the volume of the water cylinder. High speed pumps, such as fire pumps, should be provided with air chambers containing from 5 to 6 times the volume of the water cylinder.

The diameter of the neck should not exceed one-third the diameter of the chamber. When the pumps work under pressure exceeding 80 or 90 pounds per square inch, it is frequently found that the air gradually disappears from the air chamber, the air passing off with the water by absorption. Air should be supplied to the air chamber except at slow speed. At higher speed and with no air in the air chamber

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NOTE.—In large pumping plants small air pumps are employed for keeping the air chambers properly charged. In smaller plants an ordinary bicycle pump and a piece of rubber tubing are used to good advantage.

the valves are apt to seat heavily and cause more or less jar and noise, and the flow of water will not be uniform. The water level in the air chamber should be kept down to from  $\frac{1}{4}$  to  $\frac{1}{3}$  the height of the air chamber for smooth running at medium and high speeds.



FIGS. 4,266 and 4,267.—Sectional view of water end, illustrating lift of valve, and slip.

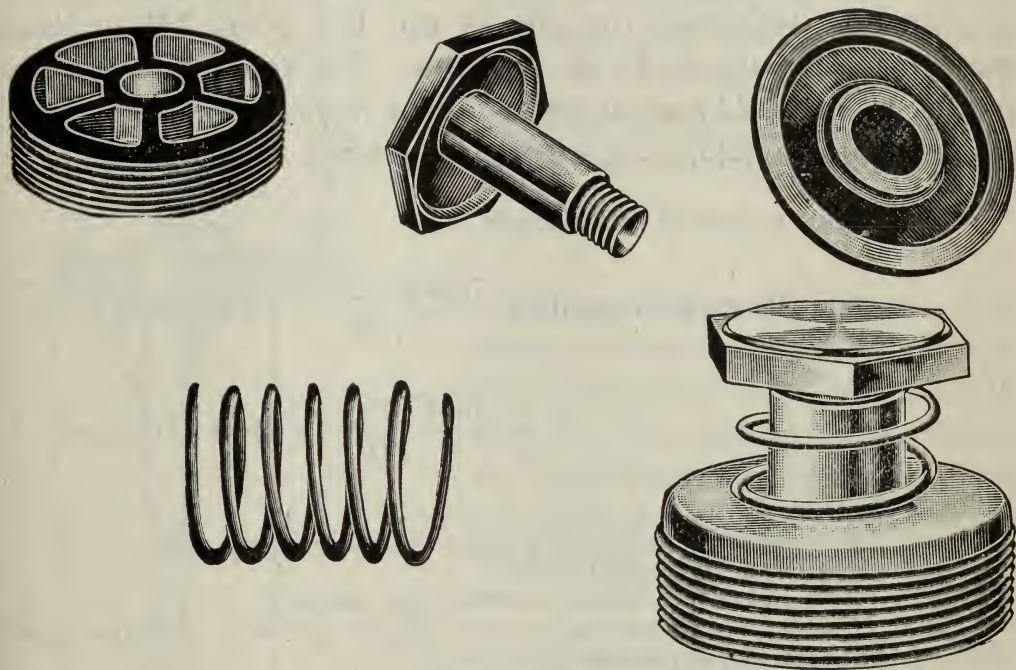
Fig. 4,266, lift for slow or moderate speed; fig. 4,267, lift for high speed. The cuts clearly show the relative position of the suction and discharge valves during the movements of the piston. **Pump slip** or slippage is a term used to denote the difference between the calculated and the actual discharge of a pump, and is generally expressed as a percentage of the calculated discharge. Thus, when the slippage is given as 15 per cent. it indicates that the loss due to slip amounts to 15 per cent. of the calculated discharge. Slippage is due to two causes, the time required for the suction and discharge valves to seat. When pumps run very fast the piston speed is so high that the water cannot enter the pump fast enough to completely fill the cylinder and consequently a partial cylinder full of water is delivered at each stroke. High speeds also increase slippage, due to the seating of the valves. Fig. 4,267 represents a sectional view of the water end of a pump, showing the position of the valves during a quick reversal in the direction of the arrows, which illustrates the position of the valves corresponding to high speeds. The valves in a pump, like almost every other part in the operation of machinery, do not act instantaneously, but require time to reach the seats. When pumps run at high speed the piston will move a considerable distance, while the valves are descending to their seats, and water flows back into the pump cylinder until the valves are tightly closed. The valves will remain in the raised position shown in fig. 4,267 until the piston stops at the end of the stroke, and under high speed the piston will reach the position on the return stroke indicated by the dotted line L by the time the valves are closed. The cylinder will be filled up to this point with water from the delivery chamber so that no vacuum can be formed until after the piston reaches this position. The volume of water that can be drawn into the cylinder must necessarily be represented by the cubic inches of space, minus the quantity which flows back during the time the valves are closing. It will thus be seen that the actual volume of water discharged is considerably less than a cylinderful, and the difference, whatever it may prove to be, is called, and is due to slippage. Fig. 4,266 represents the same pump running at a comparatively low speed. It will be noticed that the valves have not been raised as high as in fig. 4,267, because a longer time being allowed for the discharge of the water, a smaller orifice is sufficient. It will be seen also that the piston, moving at a lower velocity, cannot travel as far in fig. 4,266 before the valves seat, and consequently a vacuum can be created in the cylinder earlier in the stroke, and a larger volume of water can therefore be drawn in during the return stroke. In the latter case it is evident that the volume of water drawn into the cylinder will be nearly equal to a cylinderful and consequently the loss by slippage must be correspondingly less. In order to reduce the loss by slippage several valves are used instead of a single valve of equal area. A flat disc valve will rise a distance equal to one-fourth the diameter of the port or of the opening in the seat to discharge the same volume of water that can flow through the port in the same time. In practice the rise exceeds this proportion of one-fourth a trifle, owing to the friction of the water, and this is especially true at high speeds.



**Capacity of Pump.**—This term relates to the amount of water a pump is able to deliver when operated at a specified speed. There are two kinds of capacity:

1. Theoretical capacity;
2. Actual or net capacity.

*The theoretical capacity* represents the pumping ability of a perfect pump, and is expressed as *the volume in cubic feet or gallons displaced by the pump per minute.*



FIGS. 4,268 to 4,272.—Metal valve with screw seat details. Fig. 4,268, screw seat; fig. 4,269, stud; fig. 4,270, metal valve; fig. 4,271, spring; fig. 4,272, assembly.

Since it is impossible to construct a perfect pump, it is customary in computing capacity, to first calculate the theoretical capacity and then make allowance for the various losses due to slip, leakage, etc.

**Ques.** What is slip?

**Ans.** The back flow of water through the valves while they are in the act of closing.

**Ques.** Where is leakage liable to occur?

Ans. At the stuffing box, valves, piston and joints.

**Ques.** Name two kinds of leakage?

Ans. Water leakage and air leakage.

**How to Figure Capacity.**—*RULE: Multiply the area of the piston in sq. ins. by the length of the stroke in ins., and by the number of delivery strokes per minute, divide the product by 1,728, to obtain the theoretical capacity in cu. ft., or by 231 to obtain theoretical capacity in U. S. gallons. The result thus obtained is to be multiplied by an assumed factor representing the efficiency of the pump to obtain the approximate net capacity.*

The rule expressed as a formula is :

$$\begin{aligned}\text{Approximate net capacity} &= \frac{.7854 D^2 \times L \times N}{1,728} \times (1-f) \text{ cu. ft., or} \\ &= \frac{.7854 D^2 \times L \times N}{231} \times (1-f) \text{ gallons}\end{aligned}$$

in which

$D^2$  = square of piston or plunger diameter in sq. ins.;

$L$  = length of stroke in ins.;

$N$  = number of delivery stroke per minute;

$f$  = factor representing assumed slip in per cent. of displacement;

1,728 = cu. ins. in one cu. ft.;

231 = cu. ins. in one U. S. gallon.

**EXAMPLE.**—What is the approximate net capacity of a  $3 \times 5$  double acting power pump running at 75 revolutions per minute with an assumed slip of 5 per cent., applying this formula?

$$\text{Approximate net capacity} = \frac{.7854 \times 3^2 \times 5 \times 150}{1,728} \times (1-.05) = 2.91 \text{ cu. ft.}$$

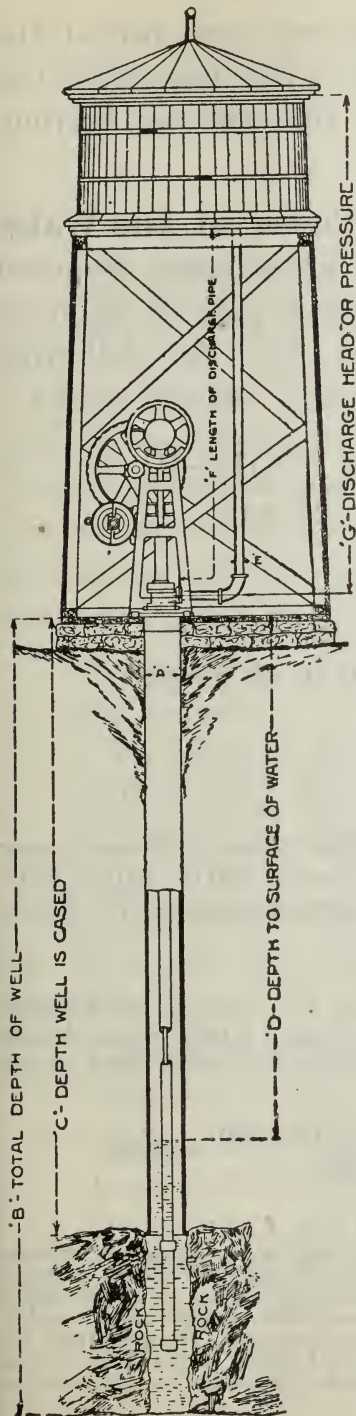
$$= \frac{.7854 \times 3^2 \times 5 \times 150}{231} \times (1-.05) = 21.8 \text{ galls.}$$



**Ques.** What kind of a pump will pump more than its theoretical capacity, and why?

**Ans.** A single acting lift pump having bucket valves, because the column of water does not cease flowing when the bucket descends, that is, especially at high speeds the foot and head valves remain open all the time, and the bucket valve accordingly under such conditions is the only valve essential to operation.

**Horse Power of Pump.**—The power required to elevate water at a given rate to a given elevation is expressed in horse power, as theoretical or actual, according to whether the various losses are considered. In a pump there is to be



**FIG. 4,273.—Suggestion relating to the installation of deep well pumps.** The cylinder should be placed at such depth as to insure its being constantly submerged, and unless tests show that the water level does not recede materially it is advisable to place the cylinder near the bottom of the well. In placing the cylinder in the well special care should be taken to make all pipe and sucker rod joints tight. For convenience in shipping, cylinders are usually sent with the plunger and lower valve screwed together, and these must be disconnected before lowering the cylinder in the well. The well is supposed to have a straight clear bore of the size specified so that the pump parts will go into it when reasonable clearance is allowed, and also to furnish sufficient clear water to supply the pump. The letters A, B, C, etc., are items necessary to intelligently select the best style of deep well pump. In addition it should be known if the water level recede when pumped, and how much, also capacity in gallons required.

considered the horse power at the water end, and also at the power end. The horse power at the power end represents the actual power to be applied and includes that lost by friction.

**Theoretical Horse Power at the Water End.**—The theoretical horse power required to raise water at a given rate to a given elevation is obtained by the following formula:

$$\text{T. H. P.} = \frac{V \times W \times (L + H)}{33,000}$$

in which

V = volume in cu. ft. per minute;

W = weight of one cu. ft. of water;

L = lift in ft.;

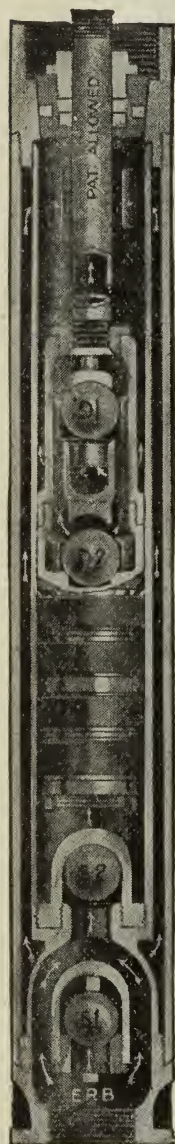
H = head in ft.

**EXAMPLE.**—What is the theoretical horse power required to raise 100 cu. ft. of water 200 ft., with a 10 ft. lift when the water is at a temperature of 75° Fahr., and when at 35° Fahr.?

For a temperature of 75°, one cu. ft. of water according to the table (page 2,965) weighs 62.28 lbs. Substituting this and the other data in the formula,

$$\text{T. H. P.} = \frac{100 \times 62.28 \times (10 + 200)}{33,000} = 39.63$$

**FIGS. 4,274 and 4,275.**—Deming double acting deep well cylinder with ball valves. The inner cylinder is of heavy seamless drawn brass tubing, while the outer casing is of galvanized pipe, and the ball valves, cages and plunger are of brass. The plunger can be readily withdrawn for renewing the leathers without removing the drop pipe. *In operation*, the water is discharged on up stroke through discharge valve D1, which is located in the top of pump plunger. D2 is the discharge valve on down stroke. S1 is the suction valve on down stroke. S2 is the suction valve on up stroke.





Now if the water have a temperature of only 35°, as might be in very cold weather, the weight of one cu. ft. will increase to 62.42, and the horse power would accordingly increase in proportion to the ratio of the two weights, or

$$\text{T. H. P. (at 35° Fahr.)} = 39.63 \times \frac{62.42}{62.28} = 39.7$$

By observing the very slight difference in the two results it will be seen that, for ordinary calculation, the temperature need not be considered, taking the usual value 62.4 lbs.

**Horse Power Absorbed at the Water End.**—The actual horse power required at the water end of a pump (not including slip or mechanical efficiency) is equal to *the theoretical horse power plus an allowance for the friction of the water through the pipes and pump passages*. The latter being usually very small as compared with the former, may be neglected.

There is also friction of water in the elbows which is usually taken into account.

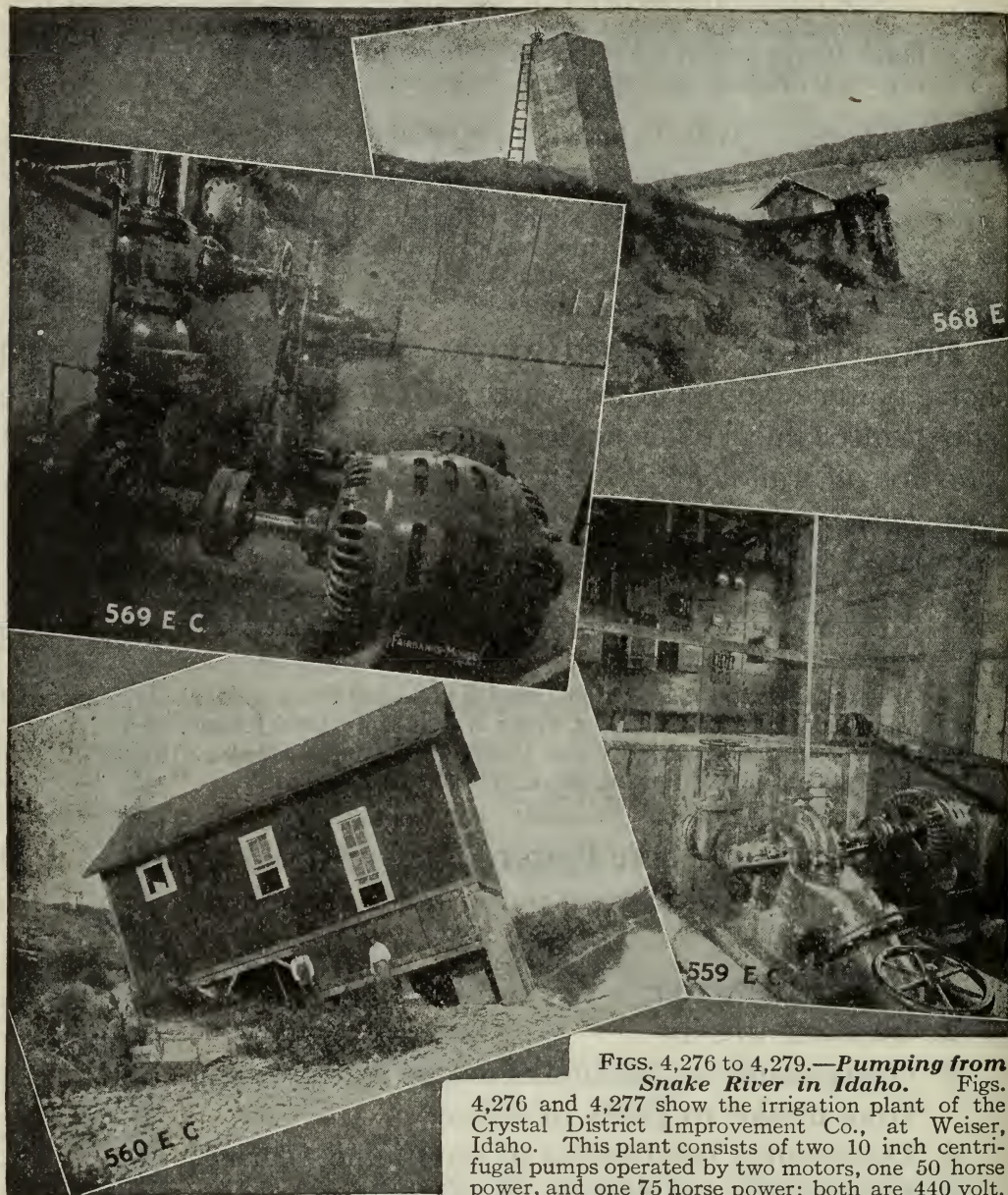
The tables on pages 2,967 and 2,968 give the approximate friction of water in pipes and elbows, from which the virtual head to be used is easily found and which when inserted in the T. H. P. formula will give the "actual horse power" as above defined.

**The Electrical Horse Power.**—The number of watt required by the motor of an electric pump must be sufficient to furnish power for:

1. Lifting the water;
2. Loss due to slip;
3. Overcoming the friction of water in traversing the system from intake to point of delivery;
4. Overcoming the friction of pump and gearing;
5. Overcoming the friction of the motor;
6. Electrical losses in motor.

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NOTE.—If the quantity of water be given in gallons, W is taken as 8½ lbs., instead of 62.4 lbs.



FIGS. 4,276 to 4,279.—*Pumping from Snake River in Idaho.* Figs.

4,276 and 4,277 show the irrigation plant of the Crystal District Improvement Co., at Weiser, Idaho. This plant consists of two 10 inch centrifugal pumps operated by two motors, one 50 horse power, and one 75 horse power; both are 440 volt, 900 R. P. M. machines. When both outfits are in

operation they deliver nearly 7,000 gallons per minute into the five miles of distributing line which irrigate 1,500 acres of sandy loam. Figs. 4,278 and 4,279, illustrate the plant of the Weiser Flat Line Pipe Co., Weiser, Idaho. This plant is similar to the other, and has one 30 horse power motor and 8 inch pump, and one 25 horse power motor and 6 inch pump. The two pumps deliver over 3,000 gallons per minute into three miles of pipe line which is used to irrigate about 500 acres. Before these plants were installed the land was covered with sage brush and now grows alfalfa, grain, etc.



Accordingly, as must be evident, the actual power to be supplied to the motor is considerably less than the theoretical power required to lift the water.

For illustration, assuming that a certain pump have an efficiency of 85 per cent. and the motor which runs it, 88 per cent., then the combined efficiency, or efficiency of the system is  $.85 \times .88 = .75$ . That is to say, if the electrical power delivered to the motor be 100 horse power and the efficiency of the system be 75 per cent., then only

$$100 \times .75 = 75 \text{ horse power}$$

is available for elevating the water.

**How to Figure the Cost of Electric Pumping.**—To get the actual electrical power required, first, the theoretical head should be increased by the loss of head in feet due to friction in the pipe line, as determined from the accompanying tables. The result determined in this way must then be considered for the power loss in the pumping unit. This is determined by dividing the theoretical horse power by the efficiency of the system expressed as a decimal, thus:

$$\text{H. P. required by motor} = \frac{W \times H}{33,000 \times E} \quad \dots \quad (1)$$

in which

W = weight of water pumped per minute in pounds;

H = total dynamic head;

E = efficiency of the system comprising pump, motor, and gearing connecting them.

**EXAMPLE.**—It is required to pump 300 gallons of water per minute against a combined static lift and head of 200 ft. The pipe line is 400 ft. long and contains 5 ninety degree elbows.

From the table showing friction of water in pipes (page 2,967), the friction loss in 100 ft. of 5 in. pipe, discharging 300 gals. per min. is 2.25 ft. Accordingly for 400 ft. it is  $4 \times 2.25 = 9$  ft. From the table showing friction of water in elbows (page 2,968), one 5 in. 90° elbow, discharging 300 gals. per min. = .36 ft. Five elbows =  $5 \times .36 = 1.8$  ft.

The total dynamic head is therefore,  $200+9+1.8=210.8$  ft. Now the weight of water pumped per minute is  $8\frac{1}{2}\times 300=2,499$  lbs.

Assuming an efficiency of 75 per cent. for the system, and substituting in (1)

$$\text{H. P.} = \frac{2,499 \times 210.8}{33,000 \times .75} = 21.3 \text{ horse power.}$$

Having determined the actual horse power to be delivered to the motor, the cost per hour for operating the pump can be readily determined by multiplying the horse power just obtained by .746 and by the central station charge per kw. hour. Thus, if the charge be 10c, then

$$\text{Cost of pumping} = 21.3 \times .746 \times .10 = \$1.59 \text{ per hour}$$

**Electric Pumps.**—Pumping machinery of various form constitutes a part of practically all operations involved in modern industrial development, and in many cases, such as irrigation and drainage projects, sewage disposal, mining, etc., pumps are of vital importance, and in many instances they are operated by electric power to advantage.

To meet the varied conditions of service, there are a multiplicity of type which may be classified:

1. With respect to the cycle of operation, as

- a. Reciprocating { single acting;  
double acting;
- b. Rotary;
- c. Centrifugal { single stage;  
multi-stage;

2. With respect to the number of cylinder, as

- a. Single cylinder;
- b. Duplex;
- c. Triplex;
- d. Quadruplex, etc.

3. With respect to the reciprocating part, as

- a. Piston;
- b. Plunger.



4. With respect to the stuffing box, as

- a. Inside packed;
- b. Outside packed.

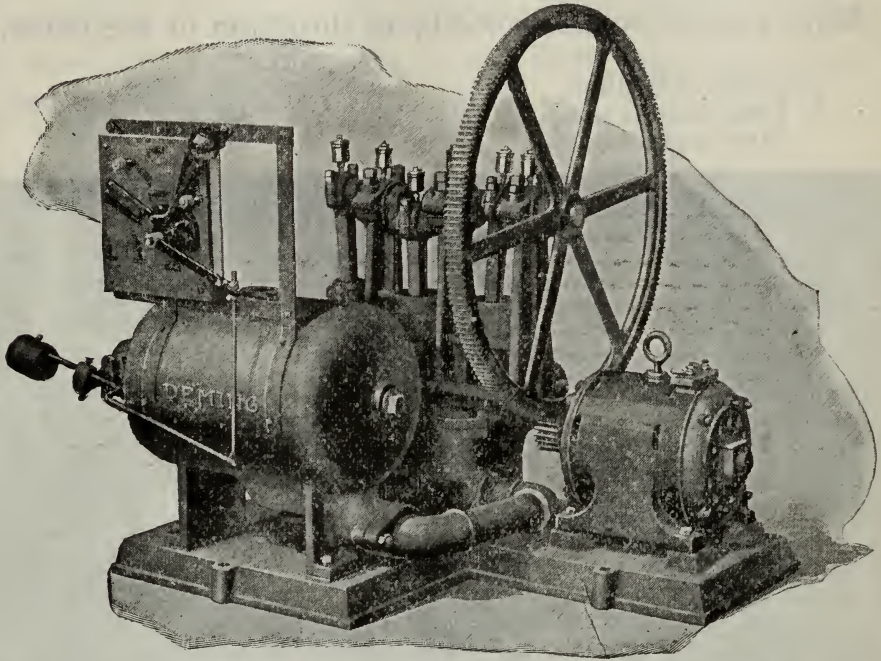


FIG. 4,280.—Deming automatic 3×3 triplex piston feed pump and receiver. *It is designed* to automatically drain steam coils, radiators, heaters, etc., of the water of condensation constantly collecting therein, and to return this water to the boiler at a temperature otherwise impossible without the use of a special water heater. The outfit includes the pump and cast iron receiver, with a float connected to a lever at the top of the receiver for operating the motor controlling switch. The pump and receiver are mounted on a cast iron bed plate, this being also extended to receive the electric motor, which is connected to the pump by single reduction spur drive. The pump and receiver are set below the water level of the steam coils, so that the condensation will flow to the receiver by gravity. As the water flows into the receiver the float rises, and by moving the lever at the top, starts the motor and pump by throwing in the switch and automatic starter. The pump is also automatically stopped when the water in the receiver is lowered by pumping, the variation of water level being regulated by properly locating the buttons on the chain which passes through the switch lever.

5. With respect to the valve arrangement, as

- a. Single valve;
- b. Multi-valve;
- c. Bucket valve;
- d. Pot valve.

6. With respect to the pressure, as

- a.* Low pressure;
- b.* Medium pressure;
- c.* High pressure.

7. With respect to the velocity of direction of the drive, as

- a.* Single reduction;
- b.* Double reduction;
- c.* Multi-reduction.

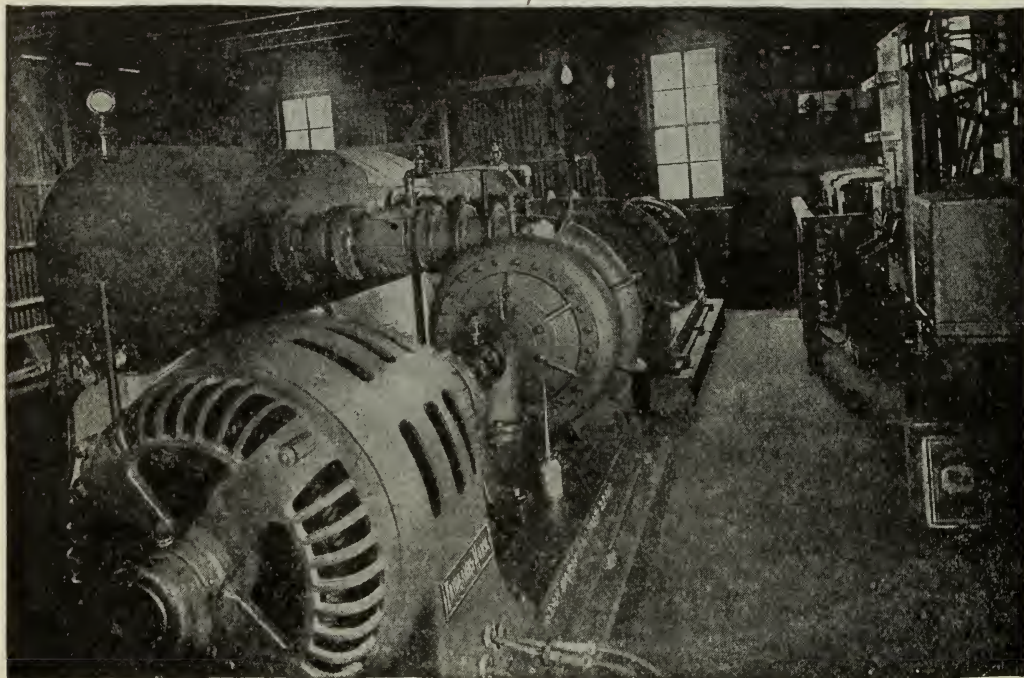


FIG. 4,281.—Fairbanks-Morse electrically driven irrigating plant at Payette river, near Payette, Idaho, which furnishes water to irrigate 600 acres of orchard land. The two 7 inch centrifugal pumps are driven by two 75 horse power induction motors, delivering 2,700 gallons per minute into 660 feet of 30 inch pipe.

8. With respect to the drive construction, as

- a.* Spur gear;
- b.* Spiral gear;
- c.* Worm gear;
- d.* Combination silent chain and toothed gear;
- e.* Combination belt and toothed gear.



**Reciprocating Pumps.**—The large variety of pump represented under this heading are used for almost every condition of service. They are either single or double acting, single or multi-cylinder, vertical or horizontal, piston or plunger, etc., as may be best suited to any particular condition of service.

The principles of operation have been given under elementary pumps, and the accompanying cuts illustrate the trend of design and construction.

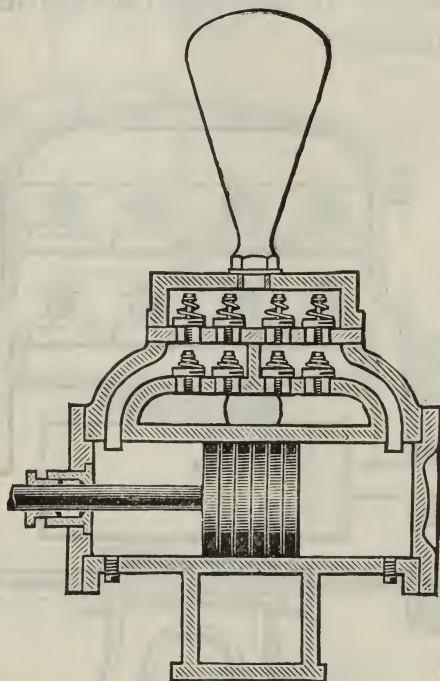


FIG. 4,282.—Double acting piston water end, showing sectional view of piston, cylinder, stuffing box, valves, and water passages. The lower row of valve are the inlet valves, and the upper row the discharge valves.

**Water Ends.**—There are, properly speaking, four kinds of water end to power pumps:

1. A piston packed with fibrous material within the cylinder, as shown in fig. 4,282. The letter P in fig. 4,283 and the following cuts indicates the plunger.
2. Inside packed plunger, with a stuffing box used for heavy pressures in hydraulic apparatus, or as shown in fig. 4,283 for larger plungers.

3. A single acting outside packed plunger as in fig. 4,284.

4. Two plungers, fig. 4,285, connected outside of the cylinder with a stuffing box in two cylinder heads, through which the plungers work.

The construction of the water ends of single cylinder and duplex pumps is practically the same; any slight differences which may be found are confined to minor details which in no way affect the general design or operation of the pump.

**Pump Valves.**—The valve apparatus is perhaps the most important part of any form of pump and its design has a material bearing upon its efficiency.

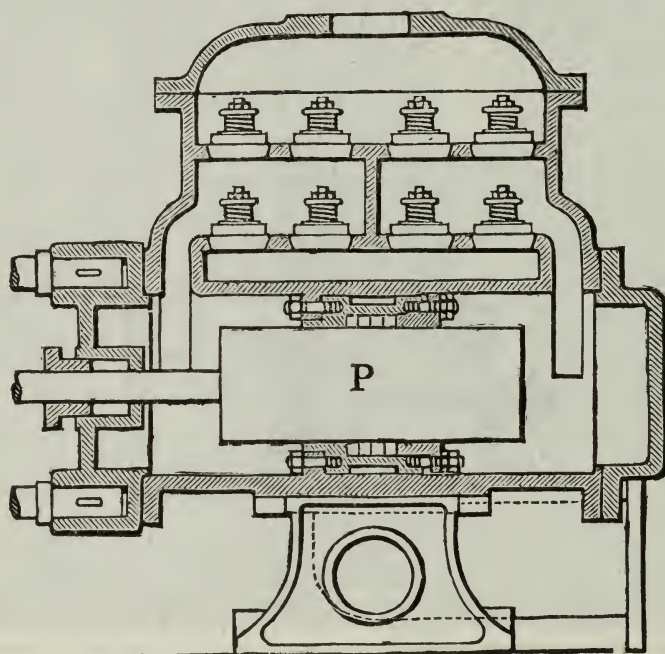


FIG. 4,283.—Double acting inside packed plunger water end showing sectional view of working parts.

The valves shown in fig. 4,282 are carried by two plates or decks, the suction valves being attached to the lower plate and the delivery valves to the upper one. The upper deck, and sometimes both decks, are removable.

The valves are secured to the seats by means of bolts or long screws, which, in turn, are screwed into the seat, as shown in figs. 4,286 and 4,288 or capped as in fig. 4,289.



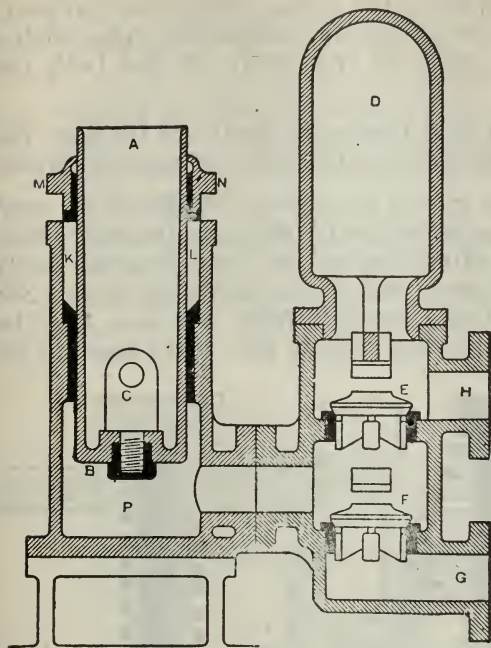


FIG. 4,284.—Single acting outside packed plunger pump. *In construction*, the moving part consists of the plunger AB working in the stuffing box KL. There are two valves or sets of valve, F and E. The stuffing box KL being on the outside can be kept in perfect adjustment, and with proper design the suction and discharge valves may be examined by the simple removal of a bonnet. The strong points of this pump are its simplicity, and the ready accessibility for examination and adjustment of all parts on which the operation of the pump may depend.

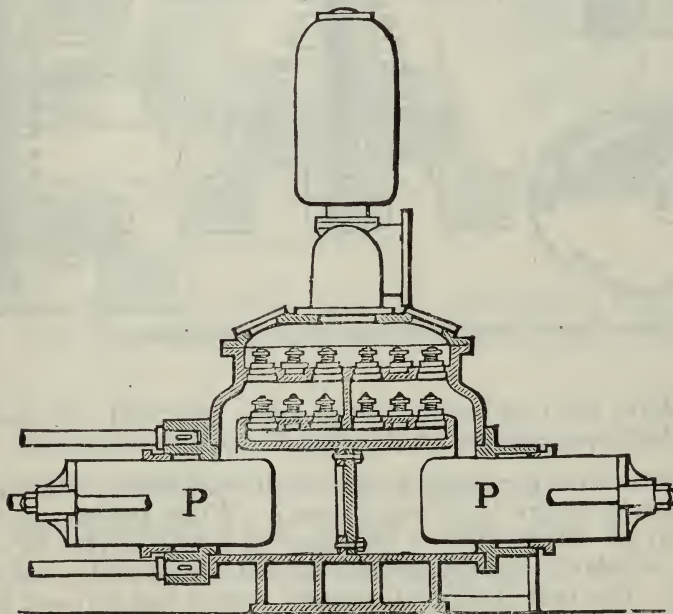
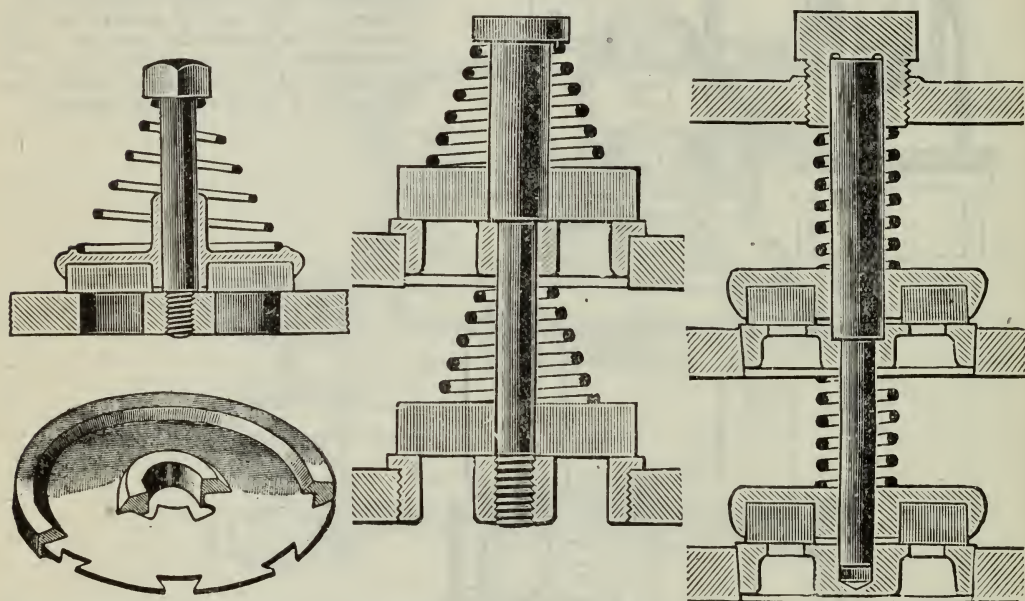


FIG. 4,285.—Double acting outside packed plunger water end. These plungers are connected by yokes and outside rods, the yokes and a portion of the rods being shown in the figure. The construction is virtually a combination of two single acting plunger pumps so connected as to give the equivalent of a double acting pump cycle.

The valves in all pumps except the large sizes, which may properly be classed with pumping engines, are of the *flat rubber disc type*, with a hole in the center to enable the valve to rise easily on the bolt, the latter serving as a guide.

A *conical spring* is employed to hold the valve firmly to its seat, the spring being held in position by the head of the bolt, or cap, as shown.

Certain improvements in pump valves have been made which tend to increase the durability and to prevent the liability of sticking, which is not an uncommon occurrence after the valves have become badly worn. The improved forms of pump valve are shown in figs. 4,288 and 4,289. When these valves leak, through wear, the disc may be reversed, using the upper side of the disc next to the valve seat. This



FIGS. 4,286 to 4,289.—Various details of pump valve construction.

can be done with ordinary valves also, provided the spring has not injured the upper surface of the disc.

Valve seats are generally pressed into the plates, although instances may be found where they are screwed. When pressed in they may be withdrawn by substituting a bolt having longer length of screw thread than the regular bolt, and provided with a nut and yoke, as shown in fig. 4,290. The bolt is slipped through a yoke and screwed into the seat. By turning the nut the seat can generally be started without difficulty.

Fig. 4,291 represents the customary *gland and stuffing box*, in which the gland is adjusted by the nuts C and D upon two studs. After the



adjustment has been properly made, lock nuts are tightened which leaves the gland free, yet preserves the alignment.

It has been proven by practice, after long and costly experiments, that a number of small valve instead of one large valve are more durable. Worthington, Dunham, Leavitt, Holly and other leading pump engineers had occasion to find the truth of this statement early in their careers.

H. F. Dunham confines his practice to four or four and one-half inch valves in all cases except for pumps of very small capacity; the author considers this good practice, as larger valves involve too great lift, and the smaller sizes necessitate an undue multiplicity of valve unit. The "slamming" of large valves under moderate speeds proved itself a

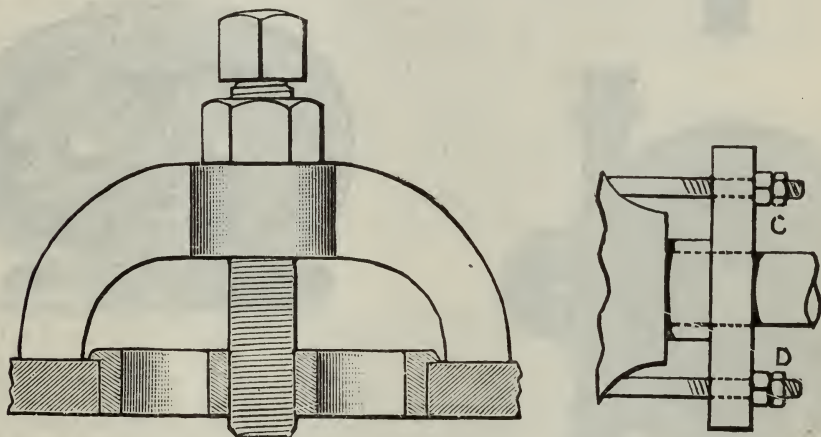
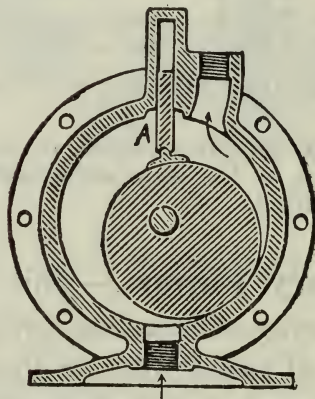
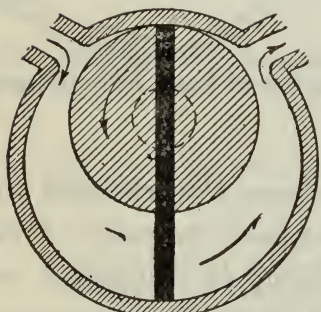
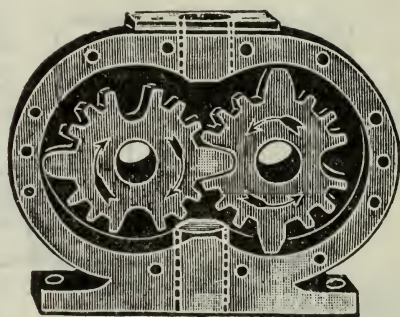
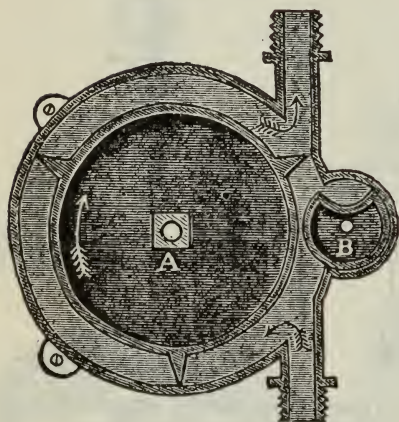
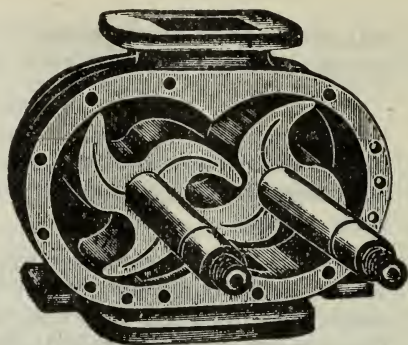
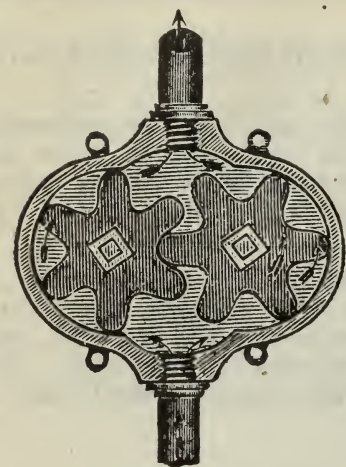


FIG. 4,290.—Jig for removing valve seats of the press fit type. It consists of a bolt with extra length of thread, a yoke and nut as shown. The operation is apparent from the cut.

FIG. 4,291.—Detail of stuffing box for piston pump.

difficulty hard to overcome, until the principle of keeping the valve area as low as possible within reasonable limits had been fully demonstrated.

**Rotary Pumps.**—This type of pump may be defined, as *one having a revolving piston, or pistons which partake of the nature of cams, rotating upon an axis and being in contact at one or more points with the walls of the enclosing chamber.* In operation, a rotary pump continuously "scoops" the water from its chamber, the operation being somewhat similar to bailing a boat with a scoop.



FIGS. 4,292 to 4,297.—Various types of rotary pump. Fig. 4,292 represents one of the oldest and most efficient forms of the rotary pump. Cog wheels, the teeth of which are fitted to work accurately into each other, are enclosed in an elliptical case. The sides of these wheel turn close to those of the case so that water cannot enter between them. The shaft of one of the wheel is continued through one end of the case (which is removed in the figure to show the interior) and the opening made tight by a stuffing box or collar of leather. A crank is applied at the end to turn it, and as one wheel revolves, it necessarily turns the



Rotary pumps may be divided into several classes according to the forms of, and methods of working the pistons or impellers, as they are usually called, that is, according to the construction and arrangement of the abutment.

The abutment receives the force of the water when driven forward by the pistons or impellers and also prevents the water being carried around the cylinder, thus compelling it to enter the delivery pipe.

In the construction of the impellers or pistons, and of the abutments, lie the principal differences in rotary pumps.

In some pumps the abutments are movable, and are arranged to draw back, as shown in fig. 4,297, to allow the piston to pass. In others the pistons give way when passing fixed abutments, and in others the pistons are fitted with a movable wing, as in fig. 4,296, which slides radially in and out when passing the abutment.

Rotary pumps are especially suitable for low pressures, and the absence of close fitting parts renders it possible to handle water containing a considerable quantity of impurity, such as silt, grain and gravel. This type of pump is compact and is generally self-contained, especially in the smaller sizes, and will deliver more water for a given

FIGS. 4,292 to 4297.—*Continued.*

other, the direction of their motions being indicated by the arrows. The water that enters the lower part of the case is swept up by the ends of each cog in rotation; and as it cannot return between the wheels in consequence of the cogs being always in contact there, it must necessarily rise in the ascending or forcing pipe. Fig. 4,293 represents a pump similarly constructed to the foregoing, *but having cams*, shaped so as to reduce the wear. *In Eve's pump*, shown in fig. 4,294, a solid or hollow drum, A, revolves in a cylindrical case. On the drum are three projecting pieces, which fit close to the inner periphery of the case. The surface of the drum revolves in contact with that of a smaller cylinder, B, from which a portion is cut off to form a groove or recess sufficiently deep to receive within it each piston as it moves past. The diameter of the small cylinder is just one-third that of the drum. The shafts of both are continued through one or both ends of the case, and the openings made tight with stuffing boxes. On one end of each axle is fixed a toothed wheel of the same diameter as its respective cylinder; and these are so geared into one another, that when the crank attached to the drum axle is turned (in the direction of the arrow) the groove in the small cylinder receives successively each piston, thus affording room for its passage, and at the same time, by the contact of the edge of the piston with its curved part, preventing water passing. *In operation*, the water that enters the lower part of the pump through the suction pipe is forced round and compelled to rise in the discharging one, as indicated by the arrows. Other pumps of the same class have a portion of the small cylinder cut off, so that the concave surface of the remainder forms a continuation of the case in front of the recess while the pistons are passing; and then, by a similar movement to that in the figure described, the convex part is brought in contact with the periphery of the drum until the return of the piston. The next improvement in rotary pumps is shown in fig. 4,295. This type was used for many years as fire pump. The Silsby fire engine is practically this pump in design although it has packing strips in the center of each of the long teeth of the elliptical gears. Fig. 4,296 shows a design with a piston passing through the eccentric rotor. The simplicity, and operation of this type is apparent from the illustration. In the design shown in fig. 4,297, a sliding partition or abutment, A, is used to imprison the water. As the piston or inside cylinder turned around, the abutment was pushed up and fell of its own gravity. A strip of metal supported this abutment and furnished a suitable wearing surface upon the surface of a revolving cylinder and also accommodated itself to the tilting motion introduced by the eccentricity of the revolving cylinder.

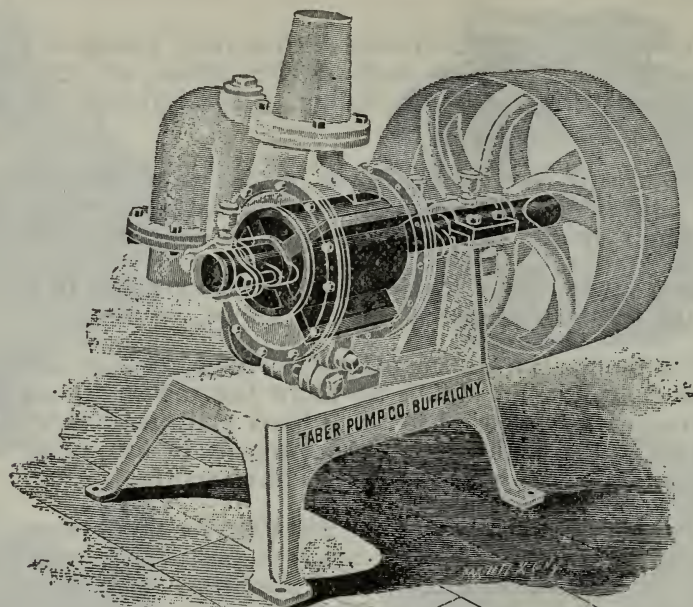


FIG. 4,298.—Transparent view of Taber rotary pump showing all parts. *It consists of a circular barrel containing four vanes or valves projecting through slots of a cylinder eccentric to the circular barrel, and arranged to move in or out to maintain contact with the interior surface of the circular barrel, as shown. In operation,* when power is applied to the pulley, the valves automatically adjust themselves to the inside surface of the barrel and create a vacuum which starts the flow of liquid.

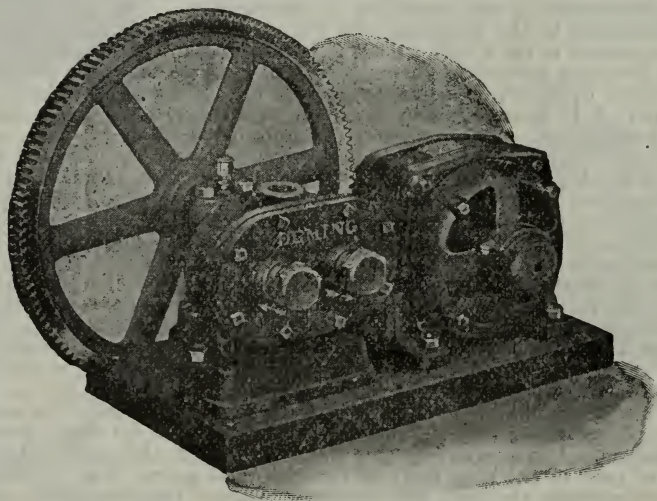
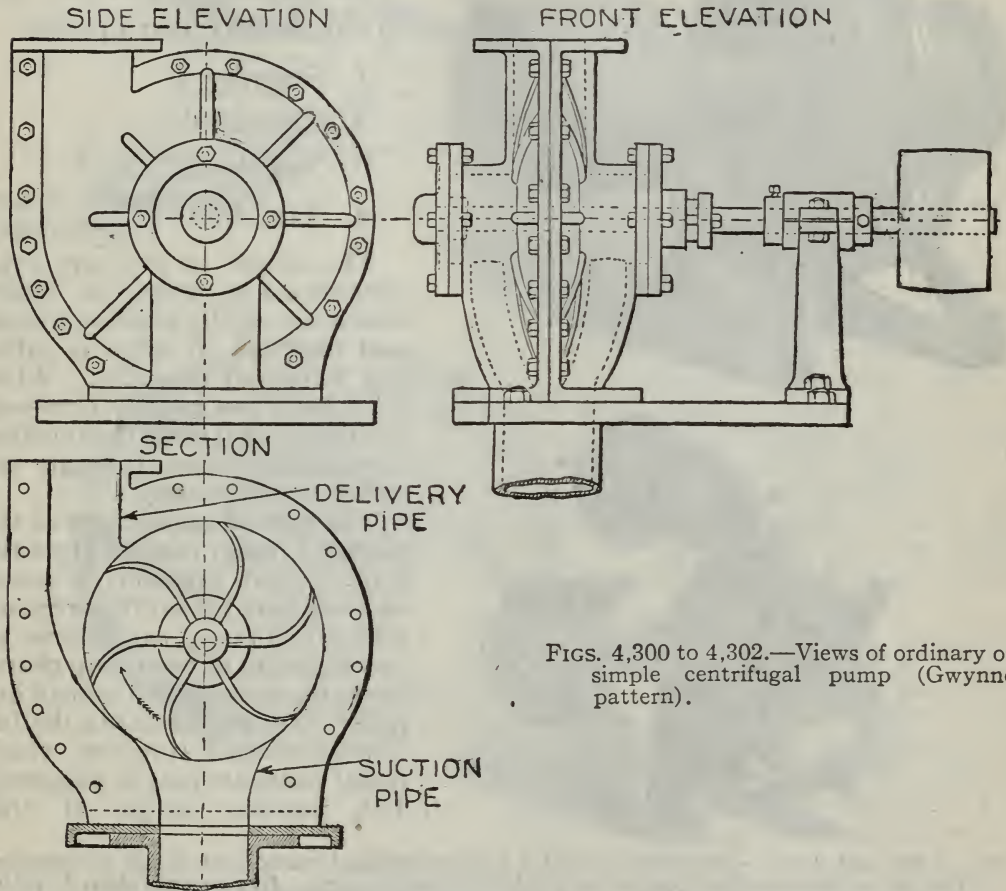


FIG. 4,299.—Deming rotary force pump designed to meet the demand for pumps for pumping small quantities of oil or gasoline. It is also recommended for pumping water for house supply or other purposes where power is available, and the liquid is entirely free from gritty substances. It is simple in construction, consisting of a pair of machine cut gears running together in a tight case. It is mounted on an iron base frame with babbitted bearing for shaft. Suction connection at either side, and discharge at the top.



weight and space occupied than the reciprocating types, while its simplicity of construction not only lessens the liability to derangement, but enables persons having a limited knowledge of machinery to set up and operate these pumps successfully.

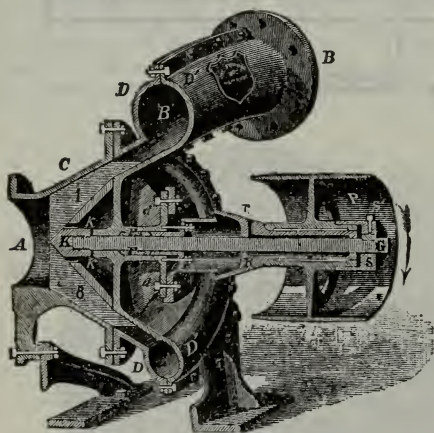
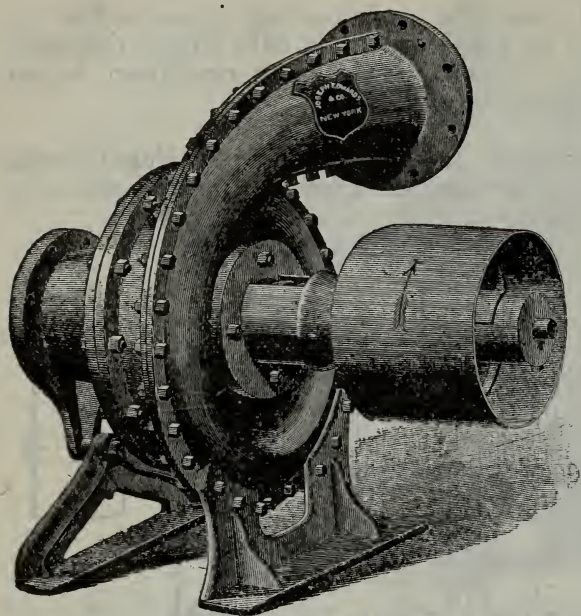
Rotary pumps have an advantage over single stage centrifugal pumps in working under widely varying heads. They are usually not eco-



FIGS. 4,300 to 4,302.—Views of ordinary or simple centrifugal pump (Gwynne pattern).

nomical, but when carefully designed with the impellers of the correct cycloidal shape, like those used in positive rotary blowers, they give a moderately high efficiency.

**Centrifugal Pumps.**—This type of pump may be defined as one in which curved vanes or impellers, rotating inside a close fitting casing, draw in the liquid at the center and, by virtue of



**centrifugal force, throw out the liquid through an opening at the periphery of the casing.**

Centrifugal pumps are divided into four classes:

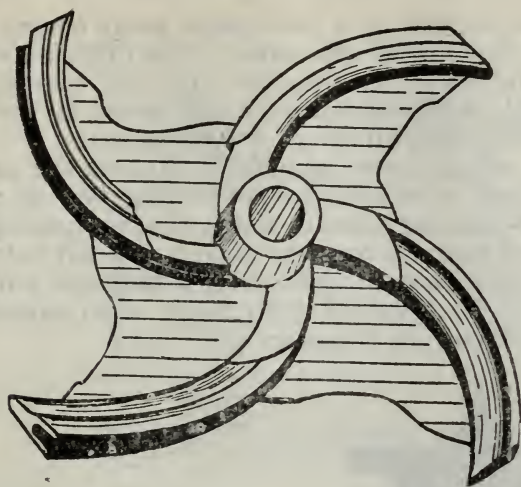
1. Simple;
2. Conoidal;
3. Volute;
4. Turbine { single stage;  
multi-stage.

The simple or ordinary type consists of a series of blade, which are rigidly fixed on a shaft and enclosed in what is called the whirlpool chamber. When the blades are rapidly revolved, the centrifugal force thus created throws the water through the outlet in the casing.

The general appearance of the conoidal pump (named from the cone shaped impeller) is somewhat different from the ordinary centrifugal pump, on account of the widening of the pump chamber to receive a special form of impeller, which consists of a double conical shaped core, on which radial vanes are cast or mounted. The peculiar shape of this

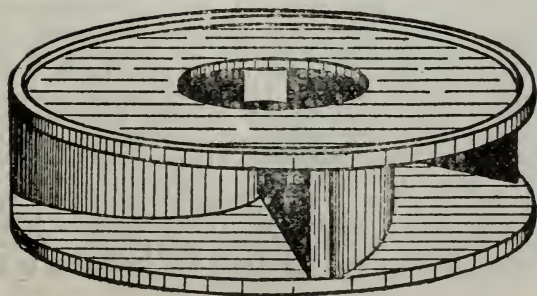
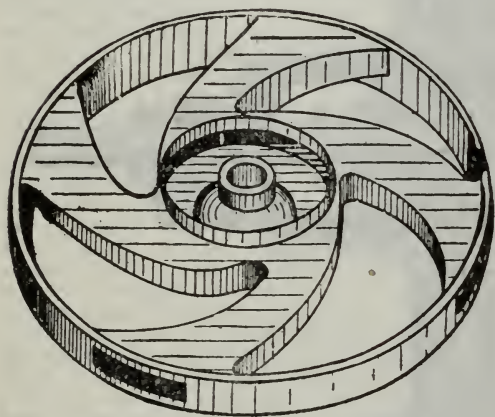
FIGS. 4,303 and 4,304.—Gwynne's conoidal type centrifugal pump and detail of impeller. The arrows indicate the direction in which the impeller turns. **In construction.** A, is the inlet; B, discharge; C, the bottom chamber within which the impeller consisting of disc K, and blades or vanes 1 to 8, revolve closely without touching the surrounding casing. To chamber C, are attached the conducting case D and D', which form between them an easy curved spiral discharge passage, gradually enlarging toward its outlet B. The shaft G, passes through the stuffing box F, thence through and into the sleeve R, which is securely bolted by wide flanges to the case D', thus forming a central rigid and long bearing for the spindle. The driving pulley P, has its bearing babbitted and runs on the outer diameter of the sleeve R. S is the driving clutch secured to spindle by the feather key and set screw S', and engages by the lugs to the driving pulley. Means of lubrication is afforded by the oil holes *r*. The vanes on disc K, extend above the disc to exclude dirt from the bearings, and partially relieve the downward pressure upon the disc. The spaces above and below the disc are connected by the holes *kk* through the disc, equalizing the vacuum therein, relieving it from downward pressure, and balancing it so that no lower bearing is required.





core serves to modify gradually the direction of the incoming current, thereby preventing waste of power. The pump chamber is divided into two parts by a radial partition, which extends entirely around the interior of the chambers and encloses the base of the conoidal impellers. This partition prevents the impingement and consequent disturbance of the two entering columns of water. Conoidal pumps are especially suitable for supplying water to surface condensers, or for irrigation, pumping sewage, or purposes where the liquid pumped is accompanied by sand, mud, silt, etc. They are comparatively inexpensive and the space required by them, relative to the quantity of water delivered, is claimed to be about one half that of a centrifugal pump of the ordinary pattern. They are designed for a maximum head of 30 feet.

*Volute pumps* are built for medium lifts, but for all capacities. They are desirable for heads up to 70 feet, without necessitating the use of pumps, which are either especially large or very expensive. Volute pumps run at moderate speed.



FIGS. 4,305 to 4,307.—Three styles of impeller for centrifugal pumps. Fig. 4,305, shows a form used for small sizes and for thick liquids; fig. 4,306, is a hollow arm type used in large pumps, and has the advantage that the water is thrown outward without any churning action, and that there are no dead spaces; fig. 4,307 is used for dredges and has the advantage that the sand is prevented grinding between the blades and the casing, yet large openings are free for the passage of sand and mud.

The turbine type may be defined as a *centrifugal pump having stationary guides or diffusion vanes inside the casing*. The diffusion vanes are placed between the periphery of the impeller and the case which take the place of the usual whirlpool chamber and assist in guiding the water to the outlet without internal shock or commotion.

The very limited head at which it was possible to operate the earlier pumps with economy has been overcome by connecting two or more units upon one shaft and operating them in series, that is, passing the water through each unit in succession, thus the head is divided between the units by a multi-stage operation and by providing a sufficient number of units or stages, they may be operated with heads even exceeding two thousand feet without impairing the economy.

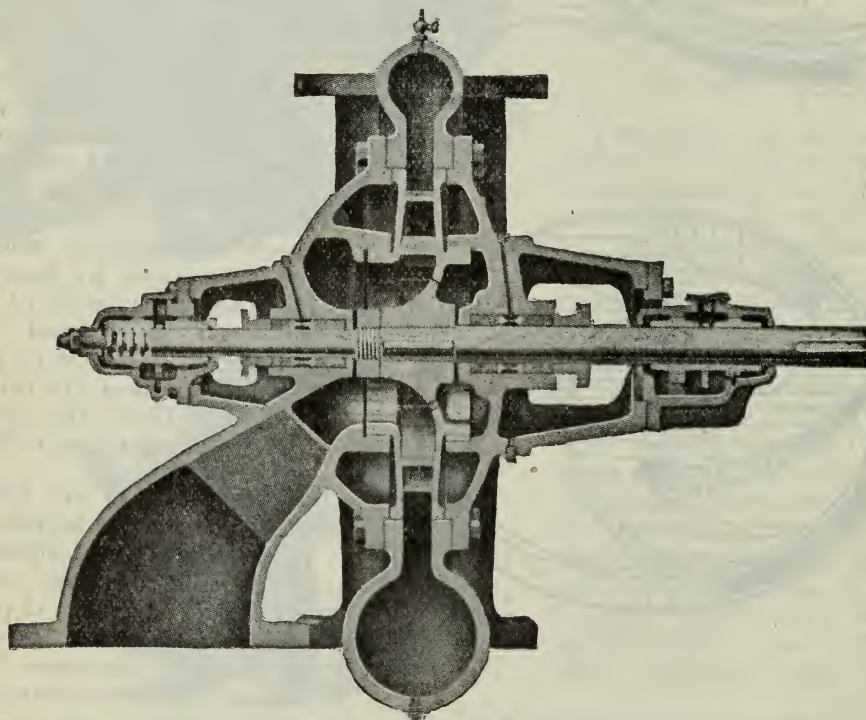
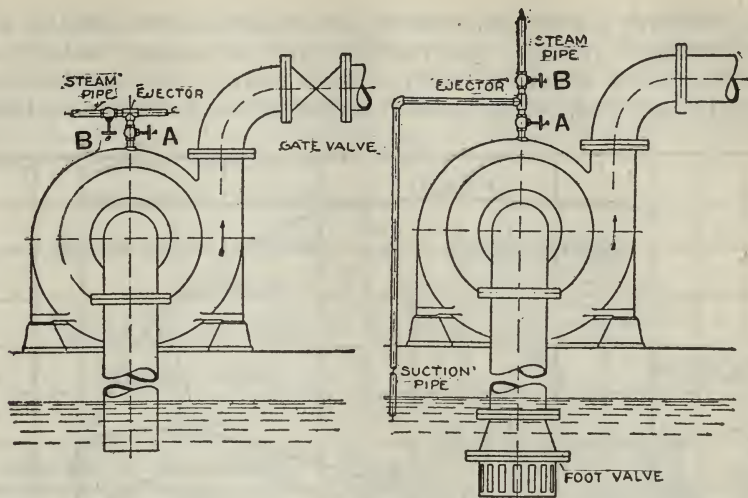


FIG. 4,308.—Sectional view of a typical single suction standard volute pump designed for direct connection to moderate speed motors or for belt or gear drive. A single suction opening is provided on the side furthest from the driving power, thus affording the facility for connecting the suction pipe. The casing is in one piece with feet for mounting on the base plate. The side plates are removable, affording access to the internal parts of the pump. There is a male and female joint between the side plates and casing insuring perfect alignment. The bearings are fastened to brackets cast integral with the side plates, there being a male and female joint between the bracket and bearing body. The impeller is of the enclosed type of cast iron or bronze as required. Alberger regular volute pumps are of the same type and general design, except that the respective sizes are of greater diameter, thus permitting a slower speed for a given head, making this type particularly suitable for engine drive. Standard and regular volutes can be built for heads up to about 85 feet, provided the available speed of the driving power will permit. Standard volute pumps are built in sizes having discharge openings from  $1\frac{1}{2}$  inches up to 72 inches in diameter.





FIGS. 4,309 and 4,310.—Method of priming centrifugal pumps. All centrifugal pumps which do not operate with pressure on the suction side, must have the casing and suction pipe filled with the fluid to be pumped, before starting. This priming is accomplished by some combination of the following devices:—hand primer, foot valve, flap valve, check valve or ejector. **If a hand primer be used**, the air cock on the top of the pump is opened, and the primer is worked until water flows through this cock. Then the pump is started. If there be a foot valve on the bottom of the suction pipe, the pump can be primed by running water into it from an overhead tank, hose, city main, etc., as the valve will hold the water in the pump. **Where steam is available** and a foot valve is not used, the pump can be primed by means of an ejector as shown in fig. 4,309. The valve A is opened; then the steam valve B is opened. The current of steam will draw the water up through the suction pipe of the ejector and fill the pump. A and B can then be closed and the pump can be started. **Where a foot valve is used**, a steam ejector can be used as shown in fig. 4,310. The valve A is opened; then the steam valve B is opened. The current of steam in the ejector will draw the air out of the pump casing, and the water will rise through the suction pipe of the pump. When water begins to flow from the ejector pipe, the pump is primed. A and B can be closed and the pump started. When bolting the pump to the foundation, care must be taken not to spring the bed plate. Every joint in the suction pipe should be air tight. The pump should be installed to run in the direction indicated by the arrow on the casing. The stuffing boxes should be packed properly and the water seal ring should be in the proper position. The bearings should be cleaned and filled with a good grade of engine oil. **Long sweep elbows only, and as few of them as possible** should be used in the suction and discharge piping. It is also advisable to use large pipe lines, as this reduces the power necessary to drive the pump and will save money in the long run. **To prevent freezing** in cold weather, the pump should always be drained when not in use, by unscrewing the plug in the bottom of the pump casing.

NOTE.—In priming a centrifugal pump where steam is not available and it is impracticable to fill the suction line with water, a hand or power operated air pump should be provided. The use of an air pump requires the placing of a valve on the discharge line of the centrifugal pump. Such a power operated pump should be driven by its individual motor. In priming multi-stage pumps, it is necessary to exhaust the air thoroughly from each stage, and if primed by exhauster, it should be connected to each stage. The pump should be started only after it is entirely filled with water. The pump must not be run empty, as the clearance rings and shaft sleeves, which in good designs have very small clearances, will bind, heat and cut if run dry. When first starting the motor, be sure to see that its direction of rotation agrees with that of the pump, as pump must not run in a direction opposite to that for which it is intended. This will be usually stamped on the casing or may be marked on the blue print of the pump. After the pump is primed, the shaft should be turned over one or two revolutions to allow all air to free itself from the vanes of the impeller.

The turbine pump has created an entirely new field of application for centrifugal pumps, embracing mine drainage, water works, and numerous other services where rotary pumps are desirable but have not been employed, owing to their former limited efficiency at high heads.

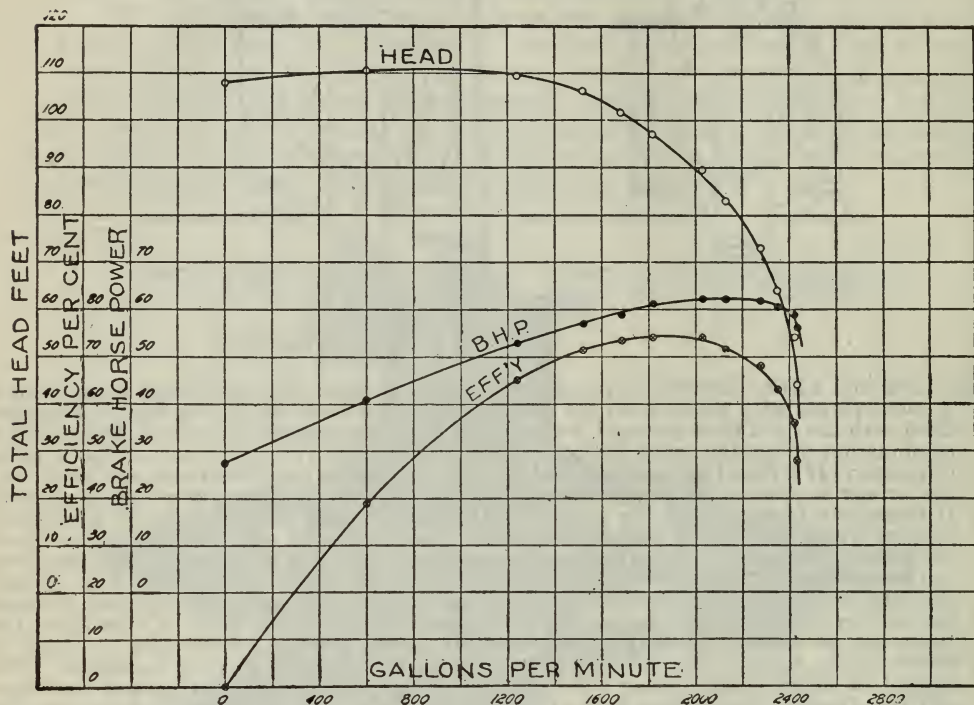


FIG. 4.311.—**Characteristic curves** of No. 88 Gould single stage double suction centrifugal pump operating at 1,740 R. P. M. constant speed. **Characteristics:** The curve marked *head* shows the variation in total head generated by the pump as the capacity increases from zero to maximum. The B. H. P. curve illustrates the change in horse power input at the pump shaft as the capacity varies, and the *efficiency* curve shows how the efficiency of the pump changes with its output. From inspection of the head curve it is seen that the pump will deliver 2,200 G. P. M. against 79 feet, 2,000 G. P. M. against 90 feet, 1,800 G. P. M. against 97 feet, and that the head at no delivery is above 108 feet. This point is actually somewhat higher, in case pump is driven by an independent motor or turbine, as the speed will increase as the load decreases. From the B. H. P. and Efficiency curves we find that 62 horse power is required to pump 2,200 G. P. M. and that the efficiency of the pump is 70 per cent. under these conditions. Likewise the efficiency is 74 per cent. when pumping 2,000 or 18,000 G. P. M. and 62 B. H. P. and 61 B. H. P. respectively is required. The pump efficiency is 70 per cent. or better over a capacity range of from 1,440 G. P. M. to 2,200 G. P. M. It is further to be noted that the power curve reaches its peak at a point nearly coincident with the maximum efficiency. In other words, if a motor be chosen of just sufficient power to drive the pump at its most efficient capacity—in this case 1,900 G. P. M., that motor cannot be overloaded, or otherwise damaged, by any change in the head against which pump will operate. As the capacity of the pump decreases the power also decreases. Power can therefore be saved by throttling the discharge until just the desired quantity is obtained. At the point of no delivery about 28 H. P. is required to rotate the impeller. The efficiency at this point is, of course, zero, as all the power is absorbed in overcoming friction and no useful work is performed. If the head curve were continued to zero head, about 2,430 G. P. M. would be discharged, and the efficiency would again be zero, as no useful work would be performed under such condition.



As a sinking or station pump for mine service, the turbine pump is ideal. There are no valves, guards or springs, no reciprocating parts, and, most important of all, there is no contact surface in the machine except the shaft and its bearings. The design is such that parts subjected to the action of mine water may be made of acid resisting metal, and, when desired, lead lined.

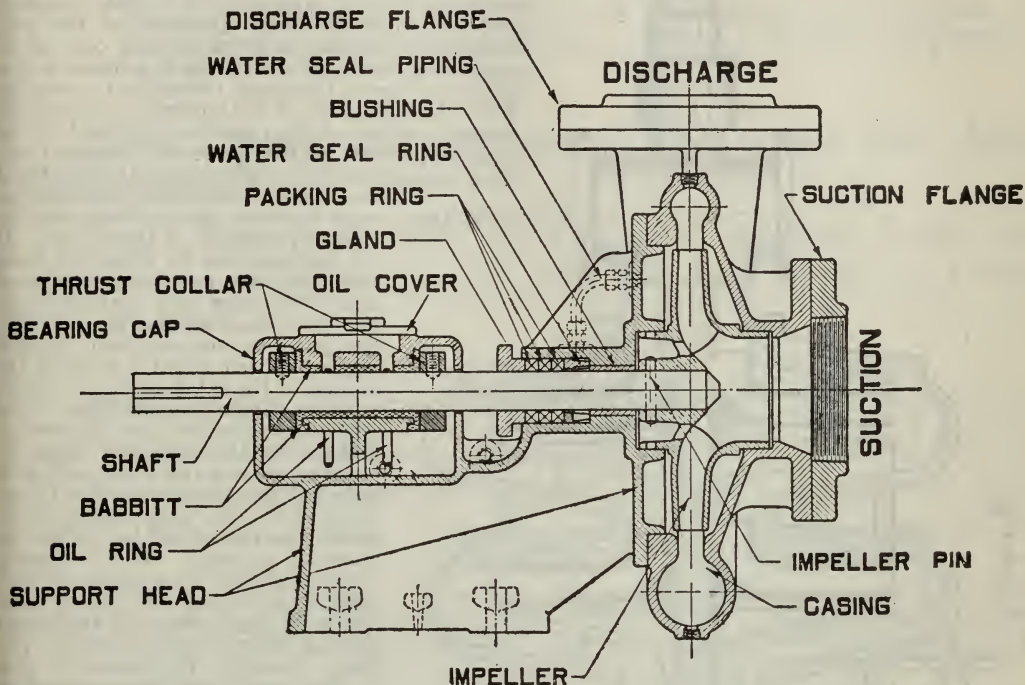


FIG. 4,312.—Section of Goulds single stage single suction centrifugal pump, enclosed impeller type, showing parts.

**NOTE.—The importance of correct head determination:** In estimating the total head against which a centrifugal pump must operate, use great care and do not resort to guess work; select a motor somewhat larger than apparently necessary so that in case of increased head there will be sufficient power. The total head against which a centrifugal pump operates is made up of the sum of four factors, namely: suction lift, discharge head, friction head (due to losses in pipe line), and velocity head. The suction lift is the vertical distance from the level of the water to be pumped to the floor level of the pump. If the water level be above the center line of the pump, the pump is then said to operate under a suction head, or "flooded suction," and the distance must be subtracted from the sum of the remaining factors. The discharge head is the vertical distance between the floor level of the pump and the level to which the water is elevated. The friction head is determined by referring to tables on pages 2,967 and 2,968 which give the losses in pipe lines and elbows for different sizes. The velocity head ( $H$ ) in feet is determined by solving for  $H$  in the equation  $H = V_1^2 \div 64.4$  where  $V$  is the velocity in feet per second of the water at the discharge nozzle of the pump. The velocity head need be considered only when the sum of the other factors is less than 20 feet. If the actual head be found to be greater than that for which the pump was designed, less than the desired capacity will be discharged. If pump be driven by a direct current motor its speed can be increased so as to discharge more water against the higher head, provided the motor is large enough to carry the increased load. If an induction motor be used, however, it would be necessary to fit the pump with a new impeller and, possibly a larger motor. These brief examples are cited to illustrate the importance of accurately determining the total head.

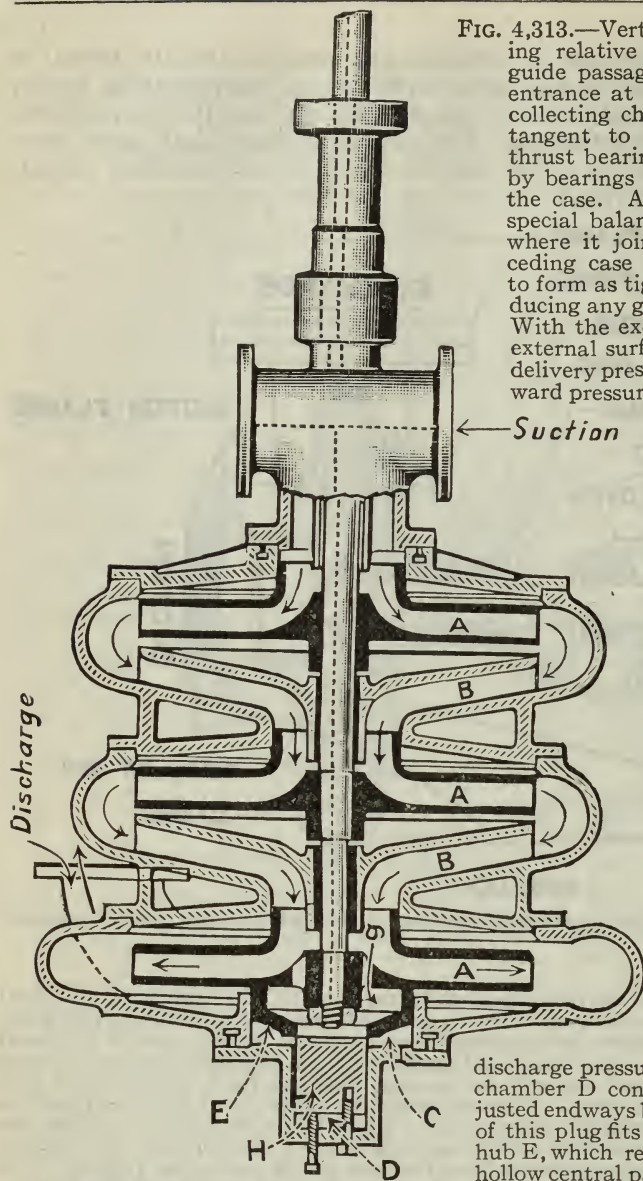


FIG. 4,313.—Vertical three stage turbine pump showing relative arrangement of impellers A, and guide passages B. This pump has the suction entrance at the top; the discharge leaves the collecting chamber of the last (lowest) impeller tangent to the circle. The shaft rests in a thrust bearing at the top, and is further held by bearings formed in the successive sections of the case. At the bottom it is provided with a special balancing arrangement. Each impeller where it joins the guide passages of the preceding case section, is fitted into the case so as to form as tight a joint as possible without introducing any great frictional resistance to rotation. With the exception of the entrance opening, the external surface of the impeller is exposed to the delivery pressure, so that there is a resultant upward pressure on each impeller, equal to the area of

its entrance multiplied by the difference between the entrance and discharge pressures of that stage. If all the impellers be alike, the total upward thrust is equal to the product of entrance area multiplied by the total head on the pump. The pumps are so proportioned that this upward thrust slightly exceeds the weight of the rotating portion, consisting of impellers and shaft. The excess of upward pressure, however, is relieved by the balancing device located at the lower end of the shaft, with the result that the rotating part is precisely balanced, thus relieving the thrust bearing of all load while the pump is running. The balancing device referred to consists of two chambers, C and D, formed centrally in the bottom of the pump case. The large chamber C encloses a projecting hub E on the lower surface of the impeller. This hub rotates with the impeller, and the joint between the hub and the walls of the chamber is, therefore, loose enough to allow water from the delivery side of the last impeller to leak into chamber C, and establish the full

discharge pressure in that chamber. The small lower chamber D contains a plug H, which may be adjusted endways by means of screws. The forward end of this plug fits closely into a recess in the face of the hub E, which recess communicates, by way of the hollow central part of the hub and the passage g, with

entrance side of the last impeller. **In operation**, when chamber C becomes filled with water, or rather when leakage through the joint around the tube E has raised the pressure in the chamber C to the delivery pressure, the total upward pressure on the impellers is greater than the total weight of the rotating part of the pump. The rotating element is therefore lifted until the recess in hub E is raised clear of the plug H. In this position the pressure in chamber C is relieved through the passage g, with the result that the rotating element again settles down over the adjusting plug H. As this action tends to recur, a position of equilibrium is established near the point where the plug just enters the recess in the hub E. The precise position of this point may be altered by the adjusting screws of the plug H, thereby adjusting the endwise position of the impellers in the casing. When the pump is not in operation, of course the upward pressure of the water does not act, and the weight of the rotating part must be carried by the thrust bearing.



For mine service, it is preferable that they be driven by electric motors, thereby minimizing space and requiring little attention other than that which is necessary to insure the proper lubrication of the pumps and motors. In addition to the various types of centrifugal pump just described, there are two modifications of design with respect to the inlet feature, namely: the *single inlet*, in which the water enters the case parallel to and in line with its center, and the *double inlet*, in which the suction pipe is divided, forming a U shape, and enters the case at both sides of the center.

**Ques.** What are the uses of the single and double inlet types?

**Ans.** The single inlet type is used for clear water only, while the double inlet type will pass everything that enters the suction.

**Motors for Reciprocating Pumps.**—When direct current motors are used, the compound wound type is generally selected for single acting pumps, on account of the rather pulsating load, but for double and triplex pumps having steadier load

**NOTE.**—In multi-stage centrifugal pumps and in single stage pumps where the pressure is high, an effective check valve as well as a gate valve should be placed in the discharge line. This should be installed between the gate valve and the pump. In shutting down the pump in cases where there is a foot valve and possibility of water hammer, it is advisable that the discharge valve be first closed before shutting off the power.

**NOTE.**—Where the suction lift of a centrifugal pump is not very high it is frequently advisable to install a foot valve. By its use, the priming of the pump is simplified, if water be available for that purpose. Care must be taken, however, to keep the foot valve from becoming choked by foreign substances in the water, and for this purpose an efficient strainer should be provided. It is not advisable to use a foot valve where the pump is to work against a very high static head, for instance, into standpipes, reservoirs, etc.; by shutting off the driving power the pump would stop suddenly, and the water rushing back might close the foot valve before the discharge check valve could act, thus producing a very heavy water hammer. The foot valve should be of flap type, rather than multi-spring type, and of ample size so as to introduce no more friction in the suction line than necessary. It is advisable that the suction inlet should be so arranged or placed as to prevent foreign objects being drawn into the pump or clogging up the foot valve. If there be very much refuse or other substances in the water, such as sticks, twigs, leaves, etc., it would be well to have a large outside screen to prevent too frequent stoppage of the water through the strainers. The foot valve or strainer should be placed sufficiently deep in the water to prevent whirl in the surface and consequent drawing in of air.

**NOTE.**—Before starting a centrifugal pump and its motor, care should be taken to clean the bearings, as dirt and substances may get in during shipment or erection. They should then be filled with a pure, clean mineral oil. This oil should be changed when it becomes dirty and the bearings thoroughly cleaned at the same time. At regular intervals these bearings should be examined.

**NOTE.**—In operating centrifugal pumps, where there is a considerable amount of air or gases in the water, the air stop cock on top of casing should be opened occasionally; in extreme cases, the cock may be left partially open.

characteristics, the shunt wound type is used to advantage. Both squirrel cage and phase wound induction motors are suitable, the latter as a rule being selected where it is desirable to reduce the starting current to a minimum, or where a somewhat variable speed is required. Synchronous motors may be, and are frequently used for driving large pumps. By pass valves must then, however, be provided for reducing the torque at starting.

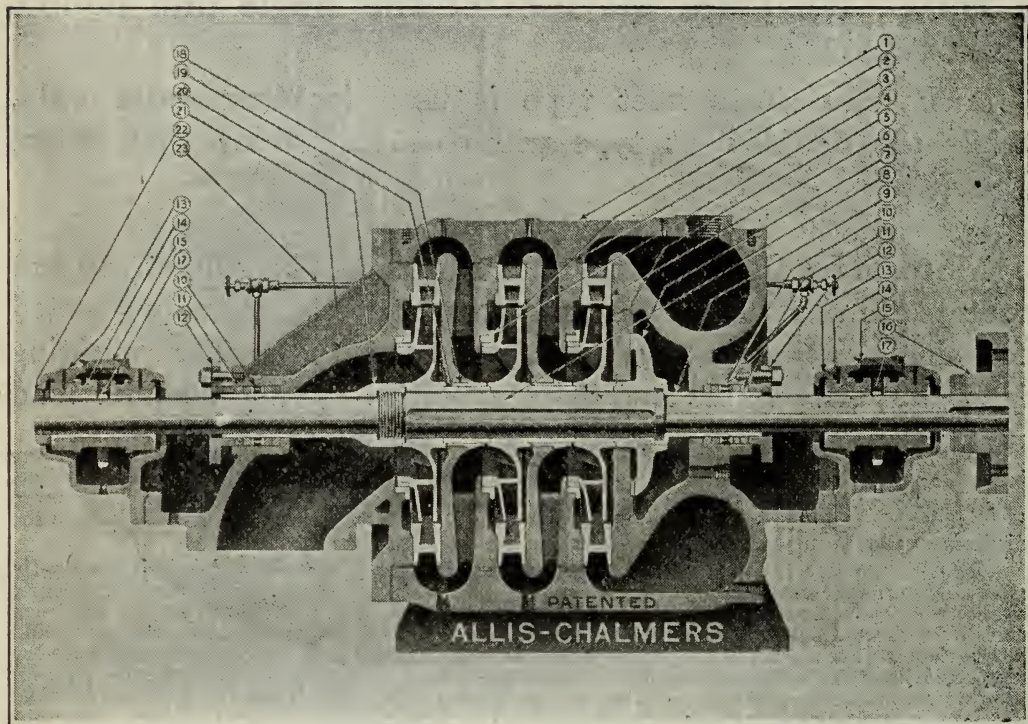


FIG. 4,314.—Sectional view of Allis-Chalmers three stage centrifugal pump showing construction. *The parts are:* 1, cast iron casing; 2, bronze enclosed runner; 3, cast iron return guide; 4, bronze wearing ring; 5, cast iron thrust plate; 6, bronze diffusers; 7, balancing disc; 8, open hearth steel shaft; 9, bronze shaft sleeve; 10, bronze water seal ring; 11, packing; 12, cast iron glands; 13, cast iron bearing cap; 14, cast iron babbitted shell; 15, cast iron hinged lid; 16, cast iron flexible coupling; 17, bronze oiling ring; 18, bronze return guide bushing; 19, bronze spacer sleeve; 20, bronze shaft sleeve; 21, cast iron suction cover; 22, cast iron set collar; 23, water seal piping.

**Motors for Centrifugal Pumps.**—On account of the peculiar characteristics of the centrifugal pump, special care is required in selecting the type of motor best suited. With a reciprocating



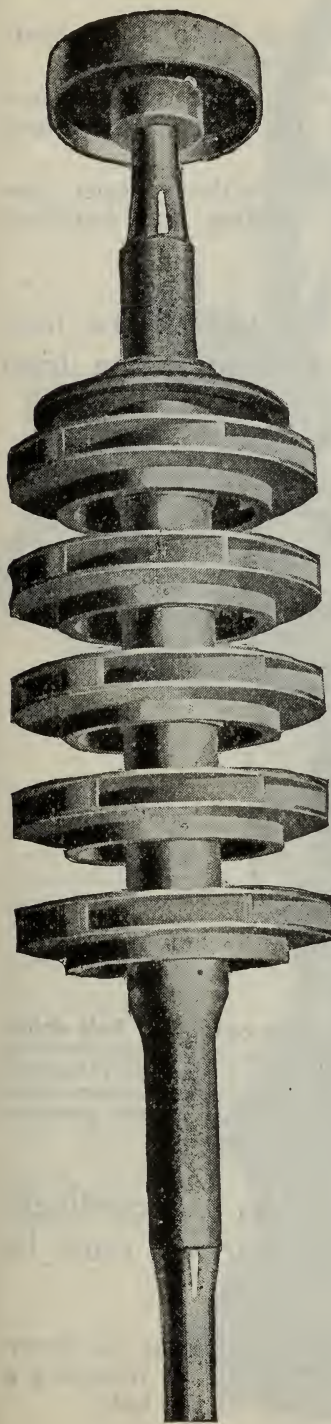


FIG. 4.315.—Rotating element or impellers of Allis-Chalmers five stage centrifugal pump showing runners and balancing disc.

pump operating at constant speed an increase of the resistance increases the pressure and therefore the load on the motor, but with a centrifugal pump, an increase of the resistance reduces the load. The volume of water delivered by a reciprocating pump is not affected by the reduction of the head, but the required power is reduced. A reduction of the head with a centrifugal pump, however, increases the volume of water, and as the efficiency at the same time goes down rapidly, the load increases. It is accordingly of importance to know what this overload, caused by a reduction of the head, amounts to—the duration of this overload. The capacity of the motor should as a rule be governed by the low and not the high head conditions. The condition of starting must also be given careful consideration in selecting the motor.

In starting a centrifugal pump the discharge valve may be closed until the motor comes up to speed, so that the motor may start as nearly light as possible. At rest, the torque required is small, usually from 15 to 25 per cent. of full load torque, and this drops from 5 to 6 per cent. as soon as the machine starts. The pump casing is full of water, however, and as the machine comes up to speed this water is churned around in the casing, causing the motor to load up as it approaches full speed,

when with pumps of the usual design, it takes from 40 to 50 per cent. of full load torque to drive it, even though pumping no water.

Shunt wound direct current motors and either squirrel cage or phase wound induction motors are well adapted for this type of pump and will readily meet the above conditions.

A synchronous motor may lead to difficulties unless proper precautions are taken in designing the starting winding and auxiliary starting equipment.

**The Drive.**—The reciprocating pump, because of the necessarily low speed at which it must operate requires a high

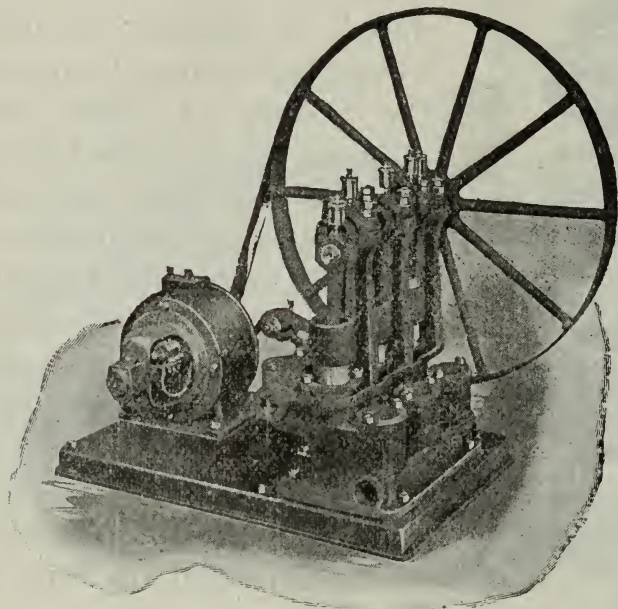


FIG. 4,316.—Deming single acting plunger triplex pump with *single reduction belt drive*. As shown, a short belt is used which runs over an idler having spring tension, the idler serving to maintain the proper belt tension and to give a large arc of contact with the small pulley. This type has the desirable feature of quiet running in addition to its compact arrangement. It makes a desirable arrangement for light service such as tank pumping in residences, apartment houses, hotels, or wherever noise is objectionable.

velocity reduction between the motor and pump. Accordingly some form of gearing which constitutes the “drive” must be interposed between the two machines.

Of the various type of drive, the single reduction belt gear, as shown in fig. 4,316, is the simplest but has the disadvantages of requiring a large pulley and is subject to slippage and breakage of the belt.



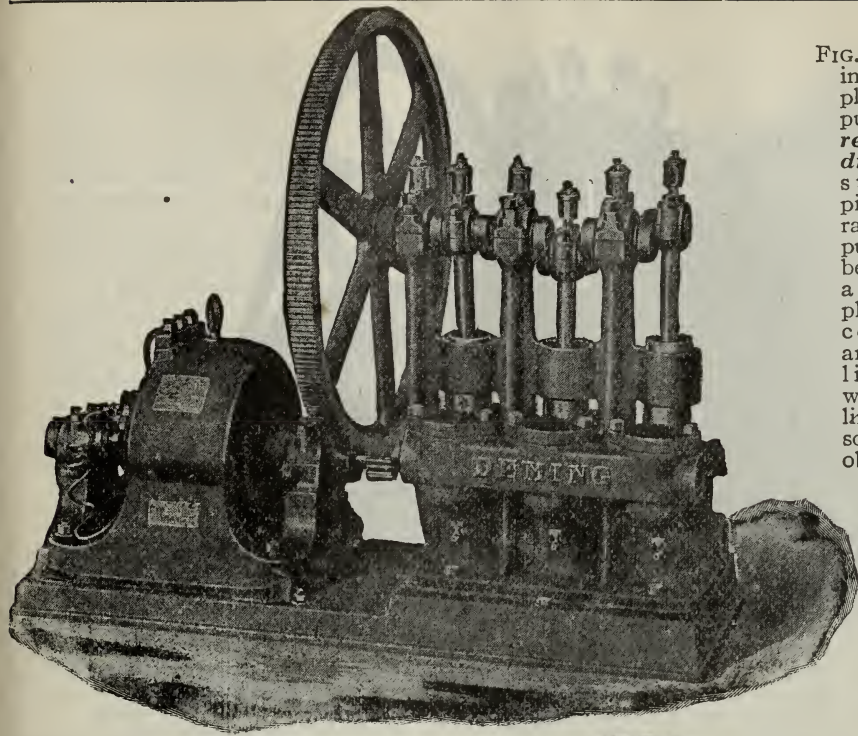
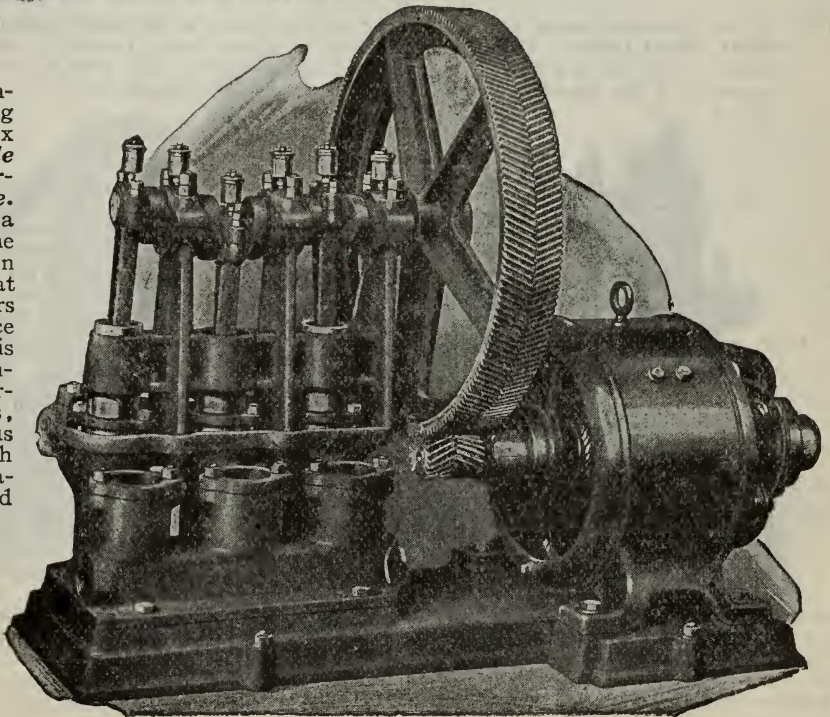


FIG. 4,317.—Deming single acting plunger triplex pump with *single reduction spur drive*. As constructed the pinion is made of rawhide, both pump and motor being mounted on a cast iron bed plate. This is a compact drive and is suitable for light service where space is limited and where some noise is not objectionable.

FIG. 4,318.—Deming single acting plunger triplex pump with *single reduction herringbone drive*. This drive is a refinement of the drive shown in fig. 4,317, in that herringbone gears are used in place of spur gears, this giving the advantages due to herringbone gears, viz.: continuous and smooth action, elimination of shock, and reduced wear.



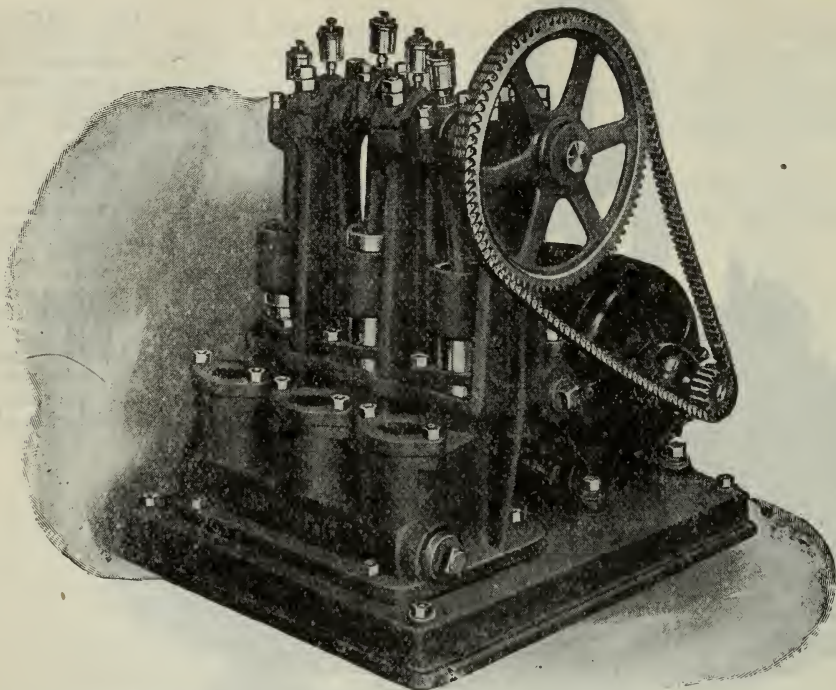


FIG. 4,319.—Deming single acting plunger triplex pump with *single reduction, so called silent chain drive*. This drive is desirable where quiet running is essential and space limited. It gives a positive connection between motor and pump, but when worn, the operation of the chain becomes jerky, necessitating replacement.

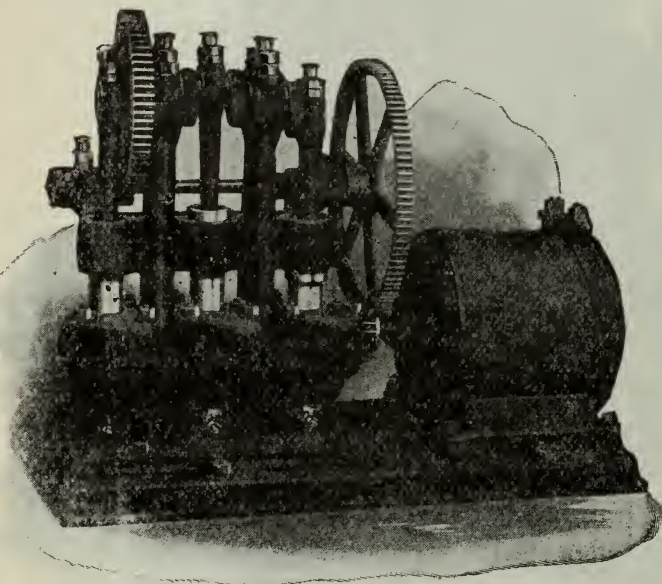


FIG. 4,320.—Deming single acting plunger triplex pump with *double reduction spur gear drive*. As shown, the pinion gear on the motor engages with a large gear on the intermediate shaft which has at its other end a small gear or pinion which engages with a large gear on the pump shaft. As is evident, a large speed reduction between motor and pump is obtained in a small space. The arrangement permits the use of a high speed motor with a heavy duty pump.



The single reduction spur drive shown in fig. 4,317, avoids the large pulley necessary in belt drive, and gives a "positive" connection between motor and pump, but its operation is accompanied by noise which may be more or less objectionable according to location.

A refinement designed to secure quiet running is the herringbone single reduction drive, shown in fig. 4,318, or a so called silent chain as in fig. 4,319. These single reduction drives are suitable for low or moderate pressures, but for heavy duty and large pumps, a higher velocity reduction between motor and pump is desirable, requiring double reduction drives.

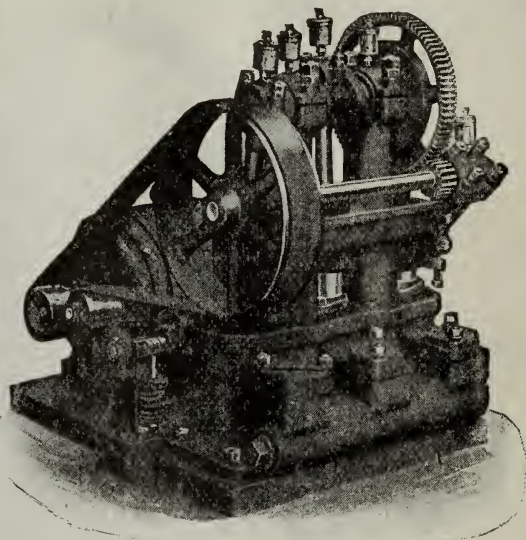


FIG. 4,321.—Deming single acting plunger triplex pump with **double reduction combination short belt and spur gear drive**. This type has the desirable features of quiet running and compactness. When a rawhide pinion is used practically all noise is eliminated. This type of drive is desirable for tank pumping in residences, apartment houses, hotels, or wherever noise is objectionable. The cut shows plainly the idler pulley with its spring holding the belt in proper tension, and also the increased arc of contact secured on the belt pinion by the use of the idler.

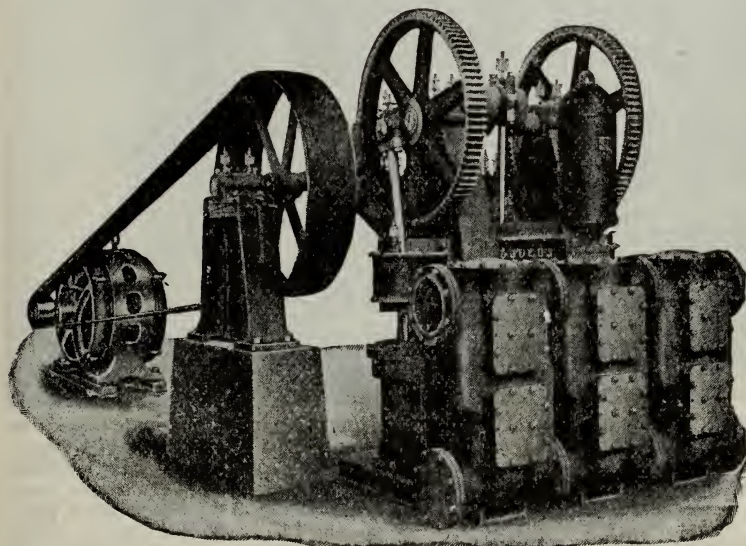


Fig. 4,320 shows a double reduction spur gear drive which makes a compact unit, and fig. 4,321, a combination spur gear and belt double reduction drive, the belt rendering the drive less noisy than when both reductions are by spur gear, and yet retaining a high degree of compactness.

FIG. 4,322.—Goulds double acting piston triplex pump with **double reduction combination long belt and spur gear drive**. As shown, the intermediate shaft carrying the spur pinion gear is extended and supported by outboard bearing for carrying the driving pulley, though on some designs this bearing is integral with the pump structure. The cut clearly shows the long belt connection permitting placement of motor in any desirable location.



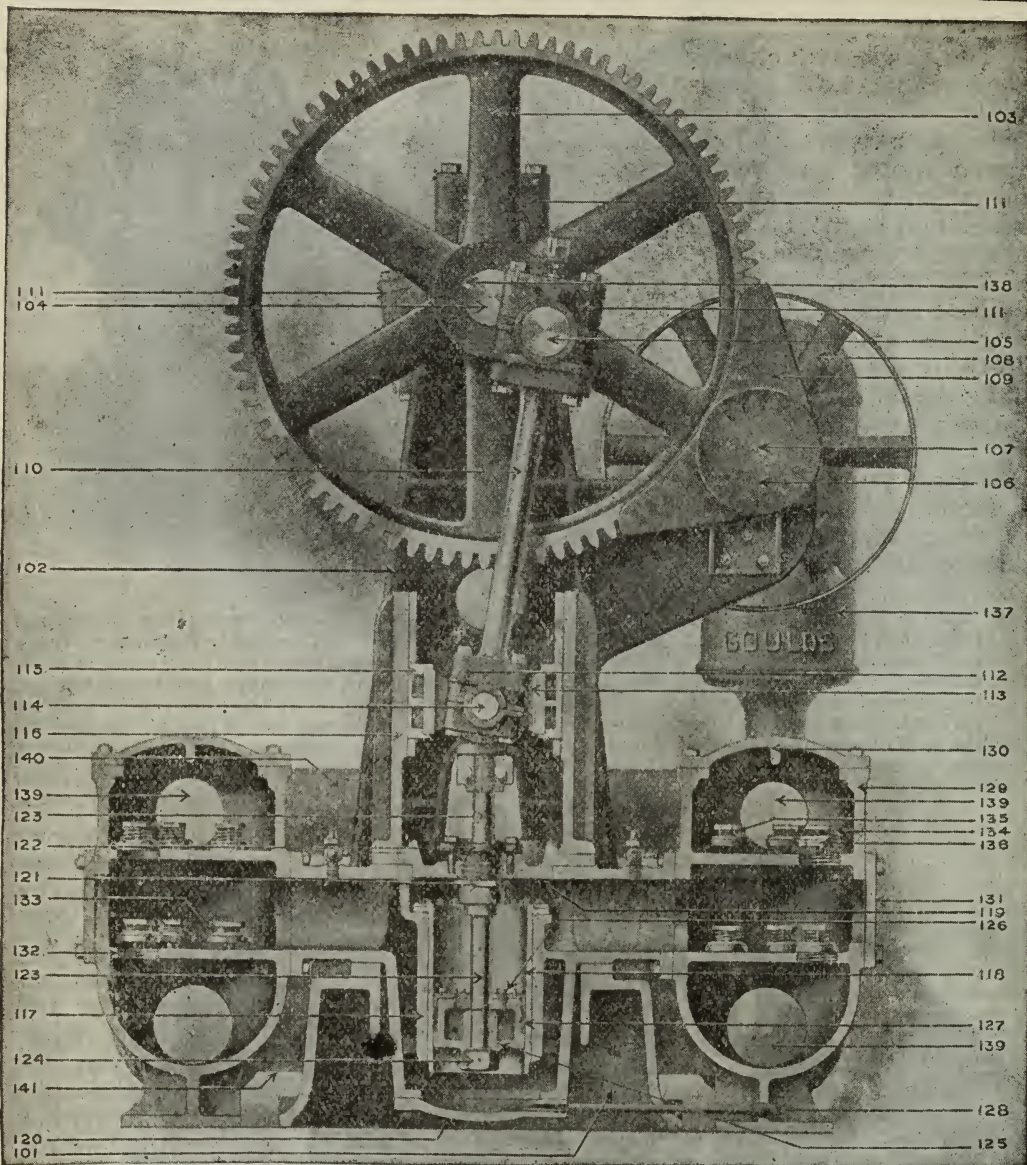


FIG. 4,323.—Sectional view of Goulds double acting piston triplex pump with *double reduction combination long belt and spur gear drive*, showing construction. *The parts are:* 101, base; 102, standard; 103, main gear; 104, crank shaft; 105, crank pin 106, main pinion; 107, pinion shaft; 108, pulley; 109, gear guard; 110, connecting rod; 111, upper connecting rod box; 112, lower connecting rod box; 113, cross head; 114, cross head pin; 115, cross head shoe; 116, cross head guide; 117, cylinder; 118, cylinder lining; 119, cylinder head; 120, cylinder bottom flange; 121, stuffing box; 122, gland; 123, piston rod; 124, piston rod nut; 125, piston body; 126, piston follower; 127, piston packing; 128, drain pipe and plug; 129, valve box; 130, valve box cover; 131, hand hole cover; 132, valve seat; 133, valve plate; 134, valve stem; 135, valve spring; 136, rubber valve disc; 137, air chamber; 138, gear key; 139, water passages; 140, discharge pipe; 141, suction pipe.



Where there is ample space and in locations where it is desirable to place the motor at some distance from the pump the type of spur gear and belt drive shown in fig. 4,322 is desirable.

Fig. 4,324 shows a form of worm drive. This gear gives a high velocity ratio on single reduction and is quiet in operation.

**Control Devices ; Water End.**—For the proper operation of pumps under different conditions various devices have been applied to effect the proper control. Fig. 4,325 shows an automatic pressure regulator and by pass which may be used to

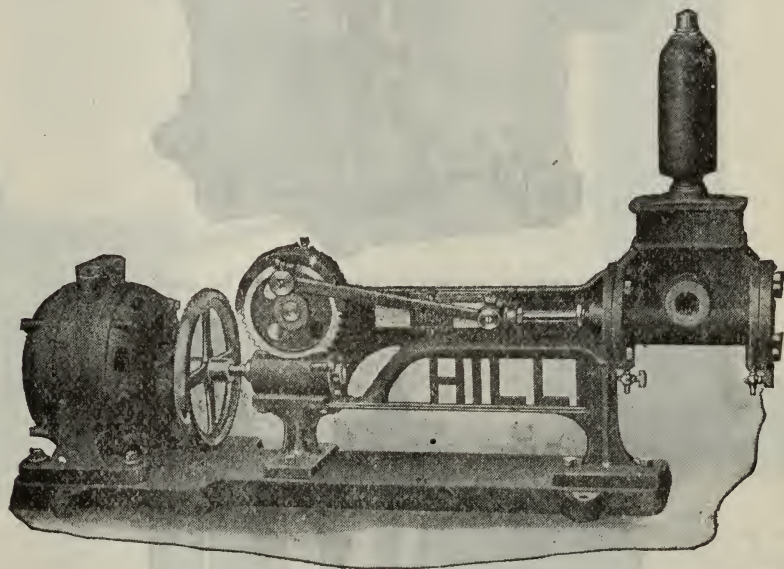


FIG. 4,324.—Hill double acting single cylinder piston pump with *single reduction worm drive*. This form of drive secures practically silent operation, a desirable feature in house tank pumping. The worm is provided with ball bearing thrust collar to reduce end friction. The wheel forming connection between motor and worm shafts also acts as a flywheel as well as a hand wheel for turning around by hand when necessary to pack or work at the machine. Suitable flexible coupling is also formed with this wheel. The position of the worm below the gear wheel allows it to run in an oil bath, thus giving maximum lubrication.

advantage when the demand on the pump is practically constant. The pressure on the pump is controlled by the pressure in a compression tank. The regulator is adjusted to open the by pass valve when the limit pressure is reached. Again, when the pressure begins to drop, the by pass closes and the pump discharges into the tank.

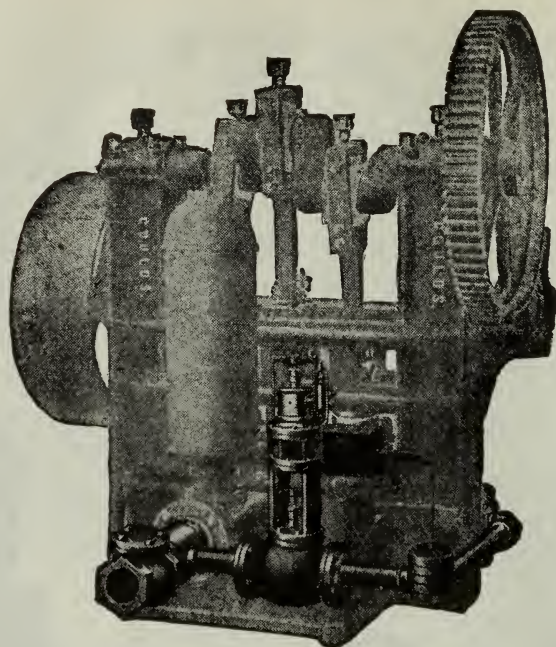


FIG. 4,325.—Goulds type L automatic pressure regulator and by pass.

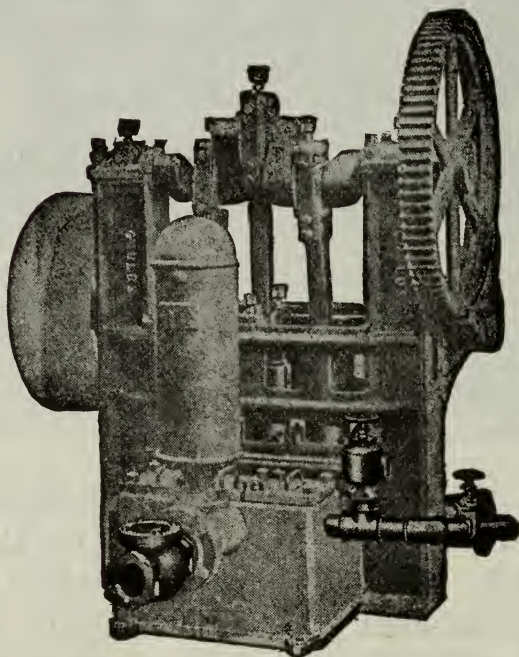
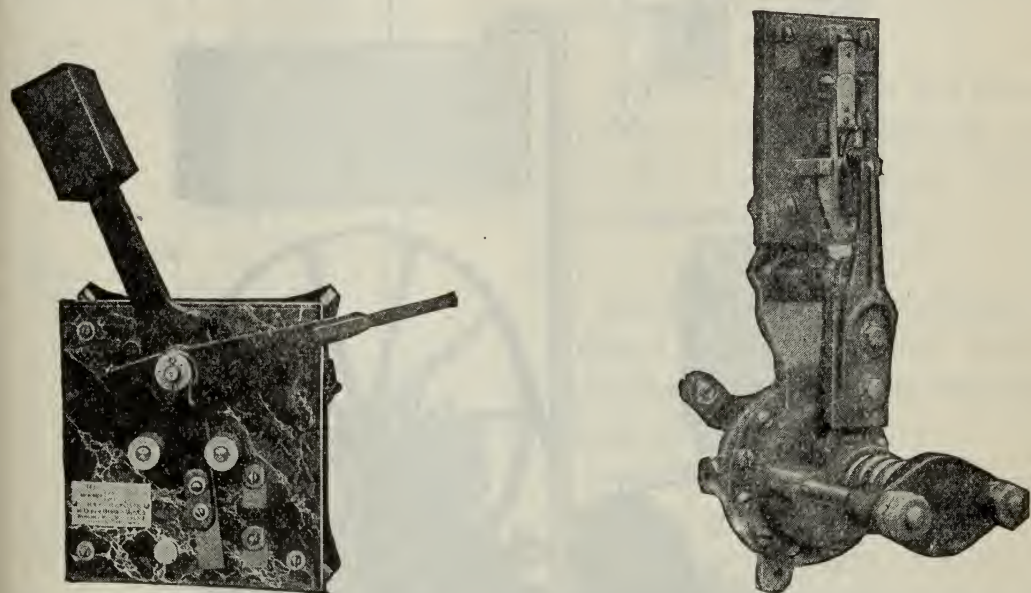


FIG. 4,326.—Goulds type K by pass control consisting of gate valve, discharge check valve, and relief valve.



For boiler feeding, a pump is generally run continuously at a fixed speed, delivering enough water to supply the maximum demands of the boilers, while the actual quantity required may vary. To allow for this variation a by pass should be provided. By means of a gate valve in the by pass pipe the feed may be regulated, the surplus water returning to the source of supply, as shown in fig. 4,326.



FIGS. 4,327 and 4,328.—Deming single pole float switch, and diaphragm pressure regulator. Fig. 4,327, switch; fig. 4,328, regulator. The switch is of the single pole sliding contact type for use with self-starting for automatically starting and stopping the pump motor with open tank systems. This switch is intended to break solenoid currents only and must not be used to handle main line currents. The diaphragm pressure regulator controls a single pole switch designed primarily as a pilot switch for use with a self starter, although it may also be used for throwing a small motor directly on the line in such cases where a single pole switch only is required. Direct or alternating current motors in capacity not over  $\frac{1}{4}$  horse power, 110 volts, and  $\frac{1}{2}$  horse power, 220 volts to 250 volts can be handled in this way.

**Control Devices ; Power End.**—There are various devices for automatically starting and stopping the motor when predetermined conditions of pumping are reached. These consist of pressure regulators, float switches, etc.

Fig. 4,329 illustrates the method of automatically controlling an electric house pump when the open tank pumping system is used. The

pump is usually placed in the basement, the discharge pipe passing up through the building to the open tank in the attic, where it is generally located. In the tank is placed a float which follows the water level, and a chain from the float passes over pulleys through the automatic switch arm (the switch being usually located near the tank), and then to a counterweight. Small buttons attached to the chain above and below the switch arm afford a means of regulating the points where

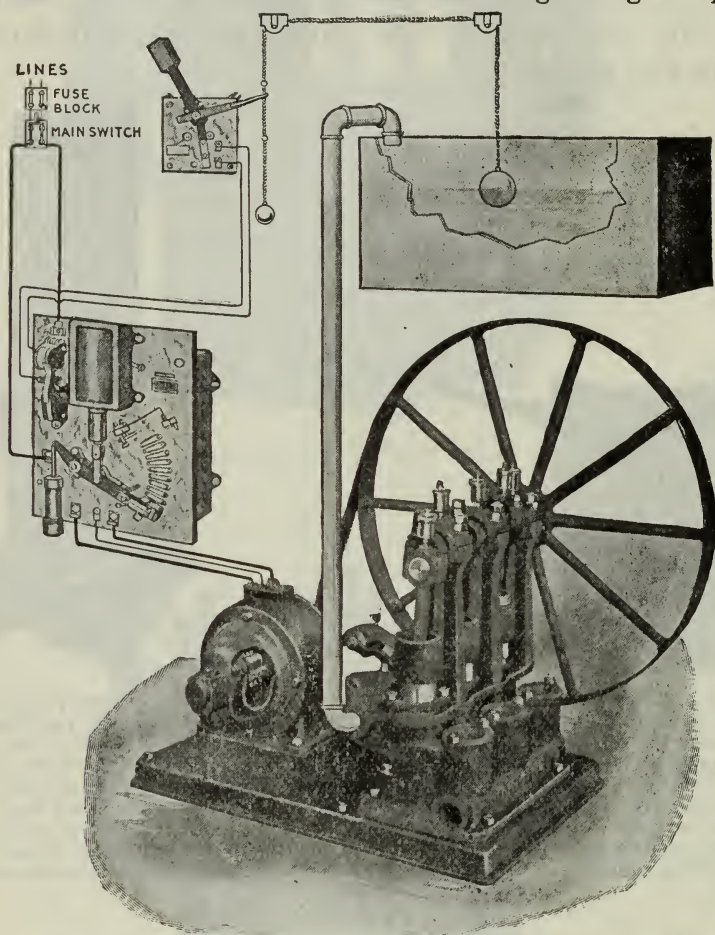
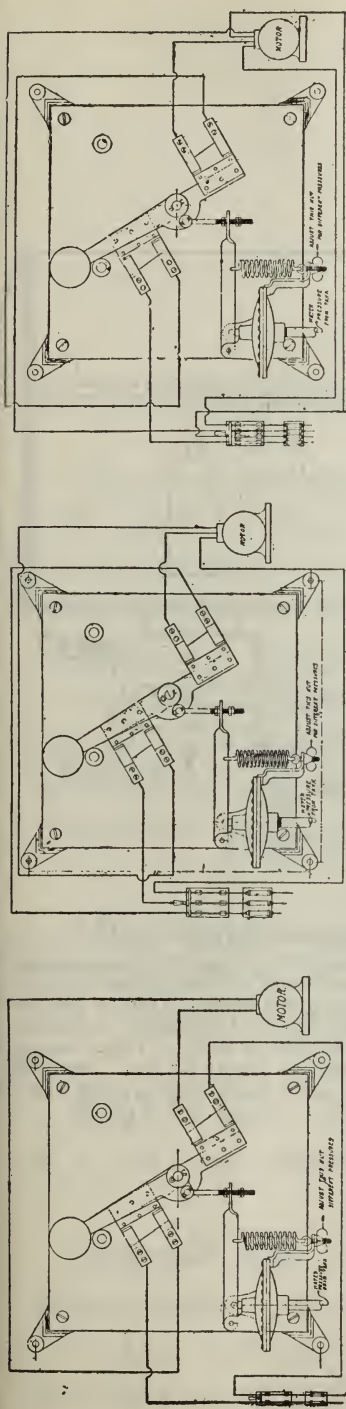


FIG. 4,329.—Automatic control for electric house pump, consisting of float switch, starter, and connection, as shown.

the motor will start and stop. The figure shows the starting rheostat, fuse block, main switch, and wiring.

In place of a tank float, control may be effected by means of the varying pressure of the water due to the head.





FIGS. 4,330 TO 4,332.—Wiring diagrams for Hill double pole automatic pressure tank switch. Fig. 4,330, direct, or alternating current, single phase, two wires; fig. 4,331, alternating current, three phase, three wires; fig. 4,332, alternating current, three phase, four wires.

The method, which operates on the same principle as the well known diaphragm damper regulator placed on steam heating boilers, is illustrated in fig. 4,333. The cut shows a switch operated by a pressure diaphragm.

Water is piped to the diaphragm chamber through a quarter inch pipe from tank or discharge of pump.

As pressure rises, diaphragm moves lever until ball falls across center, throwing switch open suddenly.

When pressure in tank decreases, on account of lowering of the water level, lever is moved until ball falls to the opposite side, closing switch and again starting motor and pump. The apparatus is set for different pressures by adjusting the thumb nut shown in the cut. A valve should be placed on the quarter inch pipe to permit water to be shut off in case it be necessary to clean or repair switch.

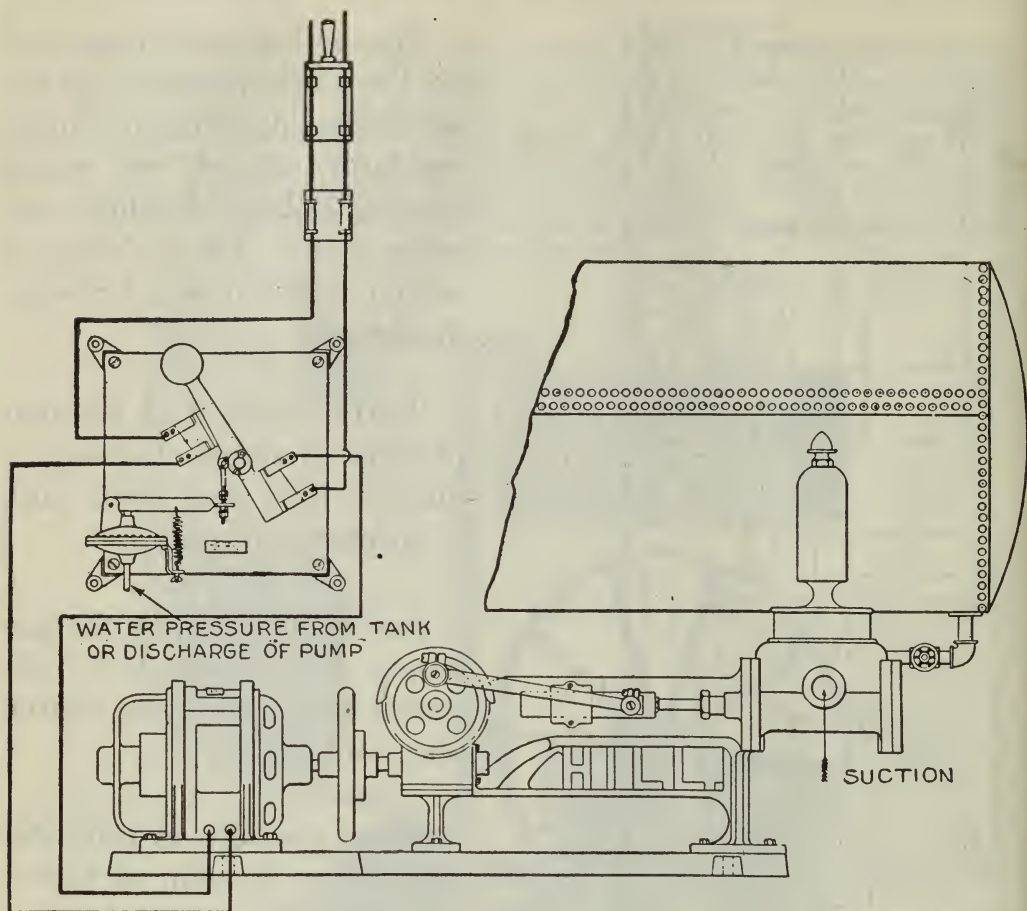


FIG. 4,333.—Hill electric tank pump and *method of pressure control*. The illustration shows a double pole switch connected with a diaphragm pressure regulator, whose operation is described in the accompanying text. The switch here shown is designed for pumps up to  $2\frac{1}{2}$  horse power direct current, and 5 horse power alternating current, 110 or 220 volts. The switch is not intended for a closer regulation than about 15 pounds variation in water pressure. That is, if the switch be set to throw at 50 lbs., it will not throw on again and start the motor until pressure in tank has gone down to about 35 lbs. Sometimes closer regulation can be had, but the former serves for most cases, and avoids the too frequent starting and stopping of the motor.



## CHAPTER LXXXI

## AIR COMPRESSORS

The ever broadening field for the use of compressed air, and the rapid increase of invention of compressed air appliance, have produced a number of change in the design of the earlier compressors the scope of which was confined almost entirely to mine and tunnel work.

Compressed air is used in almost every art known to man, and in many cases its use depends so much upon its economical production, that the modern compressor must embody every refinement which has proved to be of practical value.

**The Compression of Air.**—When the space occupied by a given volume of air is changed, both its pressure and temperature are changed in accordance with the following laws:

**Boyle's law:** *At constant temperature, the absolute pressure of a gas varies inversely as its volume.*

**Charles' law:** *At constant pressure, the volume of a gas is proportional to its absolute temperature.*

In the ordinary process of air compression, therefore, two elements are at work toward the production of a higher pressure:

1. The reduction of volume by the advancing piston;
2. The increasing temperature due to the increasing pressure corresponding to the reduced volume.

The application of the two laws is illustrated in fig. 4,334, which shows a cylinder fitted with an air tight piston. If the cylinder be filled with air at atmospheric pressure (14.7 lbs. per sq. in. **absolute**) represented by volume A, and the piston

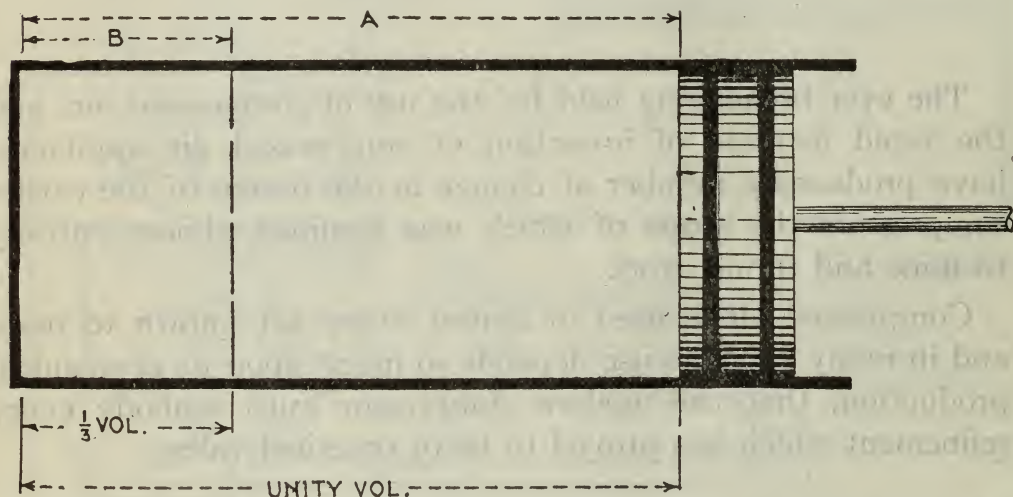


FIG. 4,334.—Elementary air compressor illustrating the phenomena of compression as stated in Boyle's and Charles' laws.

be moved to reduce the volume, say to  $\frac{1}{3}$  A, as represented by B, then according to Boyle's law the pressure will be trebled or  $= 14.7 \times 3 = 44.1$  lbs. absolute, or  $44.1 - 14.7 = 29.4$  **gauge** pressure. *In reality, however, a pressure gauge on the cylinder would at this time show a higher pressure than 14.7 gauge pressure because of the **increase in temperature** produced in compressing the air.*

Now, in the actual work of compressing air, it should be carefully noted that *the extra work which must be expended to overcome the excess pressure due to rise of temperature is lost, because after*



*the compressed air leaves the cylinder it cools, and the pressure drops to what it would have been if compressed at constant temperature.*

Accordingly, in the construction of air compressors, where working efficiency is considered, some means of cooling the cylinder is provided, such as projecting fins, or jackets for the circulation of cooling water.

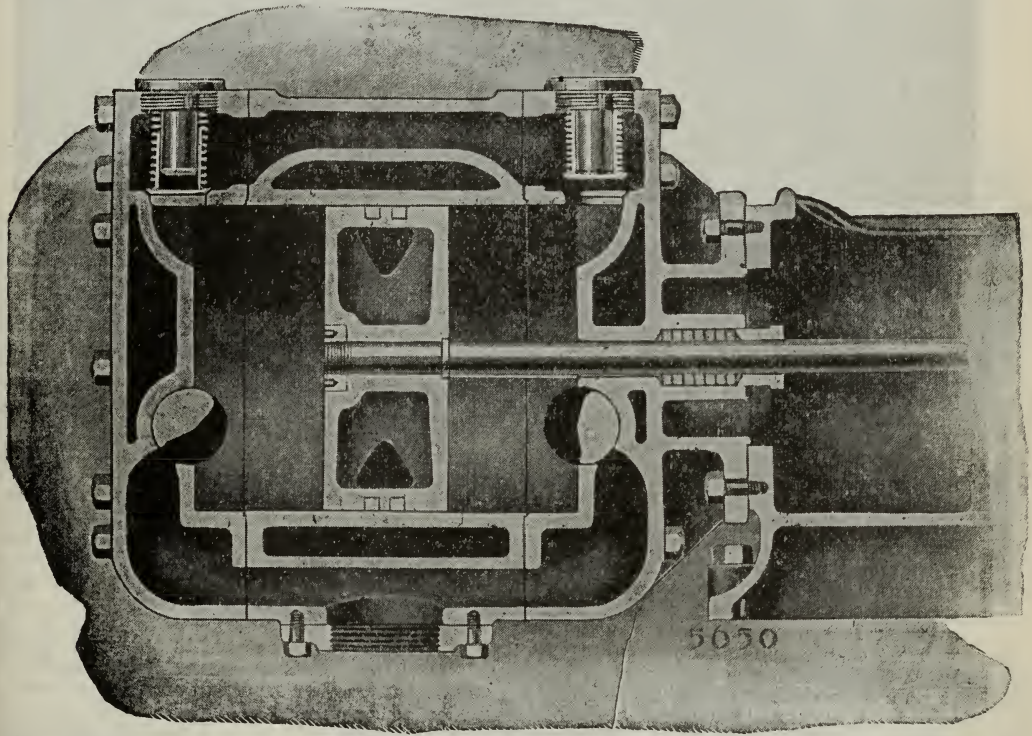


FIG. 4,335.—Ingersoll-Rand imperial air compressor cylinder with Corliss inlet valves, and direct lift discharge valves. The construction provides short, free passages for the entering air and minimizes clearance. The walls of the valve chamber or seat are water jacketed, so that the entering air encounters a cold valve and passage walls.

**Ques.** What is “free air?”

**Ans.** Air at ordinary atmospheric pressure and temperature, whatever these may be.

**NOTE.**—In air compressor problems careful distinction should be made between *gauge pressure* and *absolute pressure*, the former being the pressure as indicated by a pressure gauge, as distinguished from absolute pressure which is the gauge pressure plus 14.72 lbs., the weight of the atmosphere at sea level, when the barometer reads 30 ins. or, for ordinary calculations, 14.7 lbs.

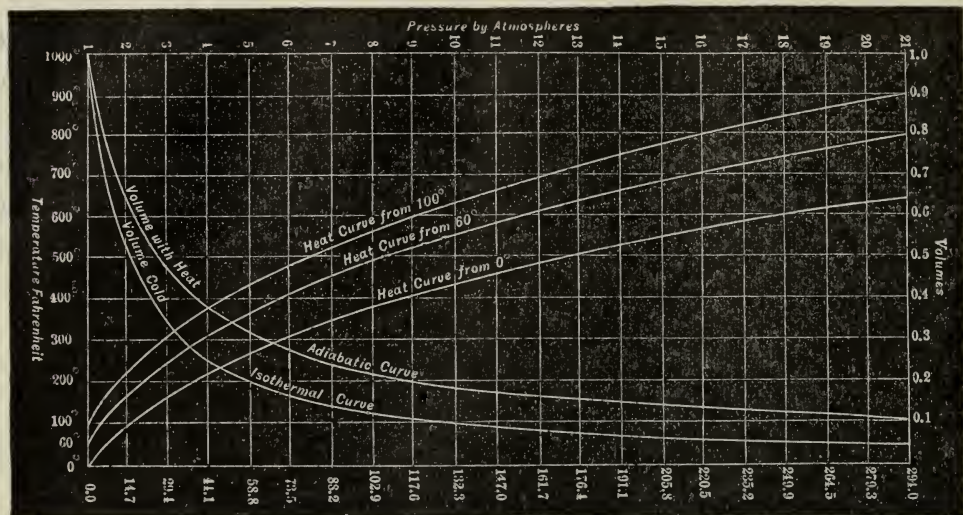
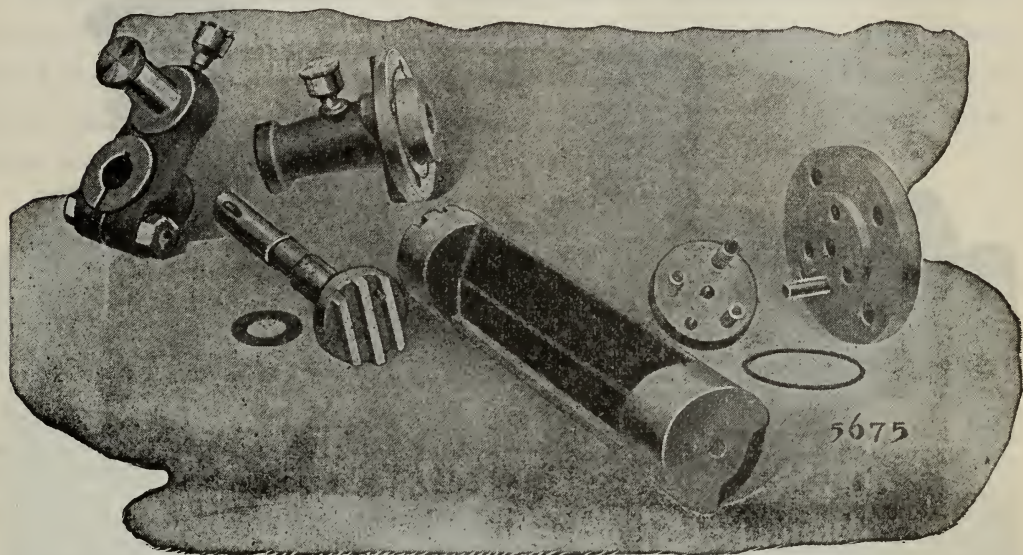


FIG. 4,336.—**Air compression characteristics;** curves showing the thermal result of air compression and expansion. The simplest application of this diagram is that which gives the gauge pressure represented at different points of the stroke. This is shown in the vertical lines. But in compressing air, heat is produced, and it is important to know the temperature at any given pressure, also the relative volume. All of these are shown in the diagram. The initial volume of air equal to one is taken and divided into ten equal parts. Each division between two horizontal lines, shown by the figures at the right, representing one-tenth of the original volume. The horizontal and vertical lines are the measures of volumes, pressures and temperatures. The figures at the top indicate pressure in atmospheres above a vacuum; the corresponding figures at the bottom denote pressures by the gauge. At the right are volumes from one tenth to one; at the left, degrees of temperature from zero to 1,000 degrees Fahr. The two curves which begin at the upper left hand corner and extend to the lower right are the compression curves. The upper one is the *adiabatic* curve, or that which represents the pressure at any point on the stroke, with the heat developed by compression remaining in the air; the lower is the *isothermal*, or the pressure curve uninfluenced by heat. The three curves which begin at the lower left hand corner and rise to the right are heat curves, and represent the increase of temperature corresponding with different pressures and volumes, assuming in one case that the temperature of the air before admission to the compressor is zero, in another 60 degrees, and in another 100 degrees. Beginning with the adiabatic curve, it will be noted that for one volume of air, when compressed without cooling, the curve intersects the first vertical line at a point between .6 and .7 volume, the gauge pressure being 14.7 pounds. If it be assumed that this air was admitted to the compressor at a temperature of zero, it will reach about 100° when the gauge pressure is 14.7 pounds. If the air had been admitted to the compressor at 60°, it would register about 176° at 14.7 pounds gauge pressure. If the air were 100° before compression, it would go up to about 230° at this pressure. Following this adiabatic curve until it intersects line No. 5, representing a pressure of five atmospheres above a vacuum (58.8 pounds gauge pressure), the total increase of temperature on the zero heat curve is about 270°; for the 60° curve it is about 370°, and for the 100° curve it is 435°. **The diagram shows that** when a volume of air is compressed adiabatically to 21 atmospheres (294 pounds gauge pressure), it will occupy a volume a little more than one tenth; the total increase of temperature with an initial temperature of zero is about 650°; with 60° initial temperature it is 800° and with 100° initial it is 900°. It will be observed that the zero heat curve is flatter than the others, indicating that when free air is admitted to a compressor cold, the relative increase of temperature is less than when the air is hot. This points to the importance of low initial temperature. It is plain that a high initial temperature means a higher temperature throughout the stroke of a compressor. **The diagram gives** the loss of temperature during compression from initial temperatures of 0°, 60°, 100°. Comparing the compression curve from zero with the compression curve from 100°, it will be noted that in compressing the air from, say, 1 atmosphere to 10 atmospheres, the original difference, which at the start was only 100°, has now been about doubled; that is, it has reached 200°, and in carrying



**The Heat of Compression.**—This subject has probably received more consideration in air compressor design than any other. The principal losses in the earlier compressors were traceable to this source.

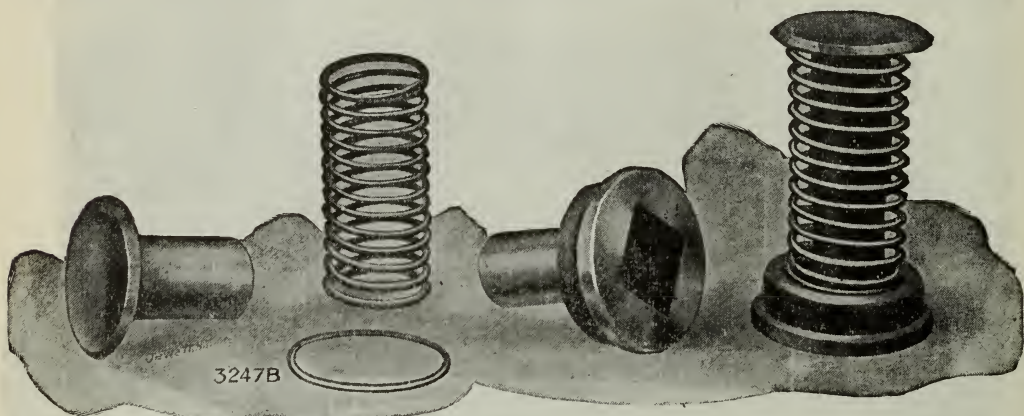


FIGS. 4,337 to 4,344.—Parts of Ingersoll-Rand's *Corliss type inlet valve*. The working pressure is distributed over the entire valve surface, which is almost a half circle. *In operation*, ample port opening is provided at the beginning of the stroke, when the piston is moving most slowly. This opening increases toward mid-stroke; with the piston at its highest speed the port is fully open. The closing of the valve is timed to coincide with the stopping of the piston at the end of the stroke. Thus air is admitted for full stroke and shut off suddenly at the end, so that there can be no escape of free air.

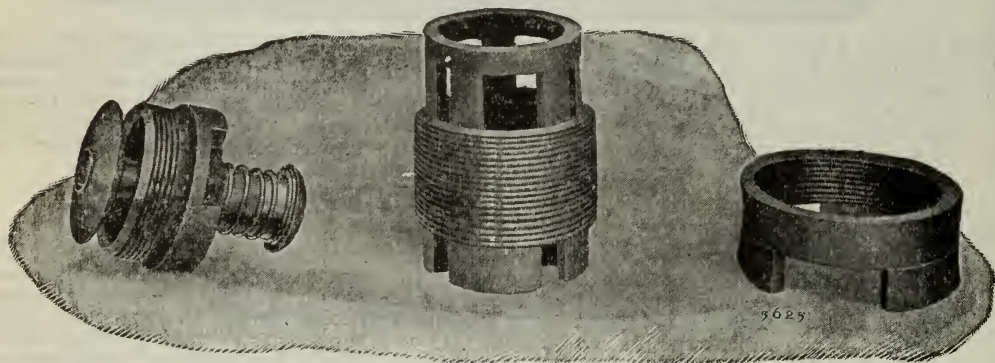
FIG. 4,336.—Text Continued.

the compression to 20 atmospheres, the difference now becomes about 250°. Each vertical division represented by the figures at the left is equal to 100°, and the space between any two adjacent vertical lines may be subdivided into 100 equal parts representing 1° each. Where there is a system of cooling the air during compression, the lines on the indicator cards can be traced between the adiabatic and isothermal curves on the diagram. In practice, the best compressors show a line about midway between these two curves. For all practical purposes, in using the diagram it is best to follow the adiabatic curve in all determinations, except where the exact pressure line is known. This diagram will be found convenient to those who are called upon to figure the pressure at different points in the stroke of an air compressor and it points out the common error of neglecting to take into consideration in calculating, the fact that, at the beginning of the stroke, one atmosphere in volume already exists. Beginning at the upper left hand corner, the adiabatic pressure curve intersects the first vertical line at that point in the stroke, when the pressure on the gauge will register 14.7 pounds. The next vertical line shows where the gauge reaches 29.4 pounds, and it is evident here that the piston of an air compressor travels much farther in reaching 14.7 pounds than in doubling that pressure or in reaching 29.4 pounds; thus an air compressor is an engine of unevenly distributed resistance. During the early stages of the stroke it has a slowly accumulating load to carry, while later on this load is multiplied very rapidly. This is one of the reasons for heavy flywheels in air compressors.

By reference to a table giving the temperatures at end of compression for various terminal pressures, it is seen that aside from the injurious effect such high temperatures would have on the lubrication of the cylinder and valves of an air



FIGS. 4,345 to 4,349.—Parts of Ingersoll-Rand Imperial *direct lift discharge valve* and assembly. The valve proper is machined from steel and ground to seat; the projecting lip or rim above the seat is caught in the back lash of the compressed air when the piston stops and assists the spring in closing the seat quickly. The valve is cup shaped.



FIGS. 4,350 to 4,352.—Ingersoll-Rand *direct lift inlet valve*, with its bonnet and locking nut. Each unit is self-contained, screwing into place in the cylinder and locked with an auxiliary nut. The valve seats in the cage so that its condition is easily ascertained on the removal of a unit.

compressor, the thermal loss would grow as the pressure increased, if no means were provided for abstracting this heat during compression. It should be noted that the heat of compression, as already explained, represents work done upon the air for which there is



usually no equivalent obtained, since the heat is all lost by radiation, before the air is used.

**Simple Compression.**—In the earlier compressors, compression was accomplished in one stage or single cylinder machines, and the heat of compression was removed by injecting water into the cylinder in the form of a spray; or, in another type, the water was used as a piston for compressing.

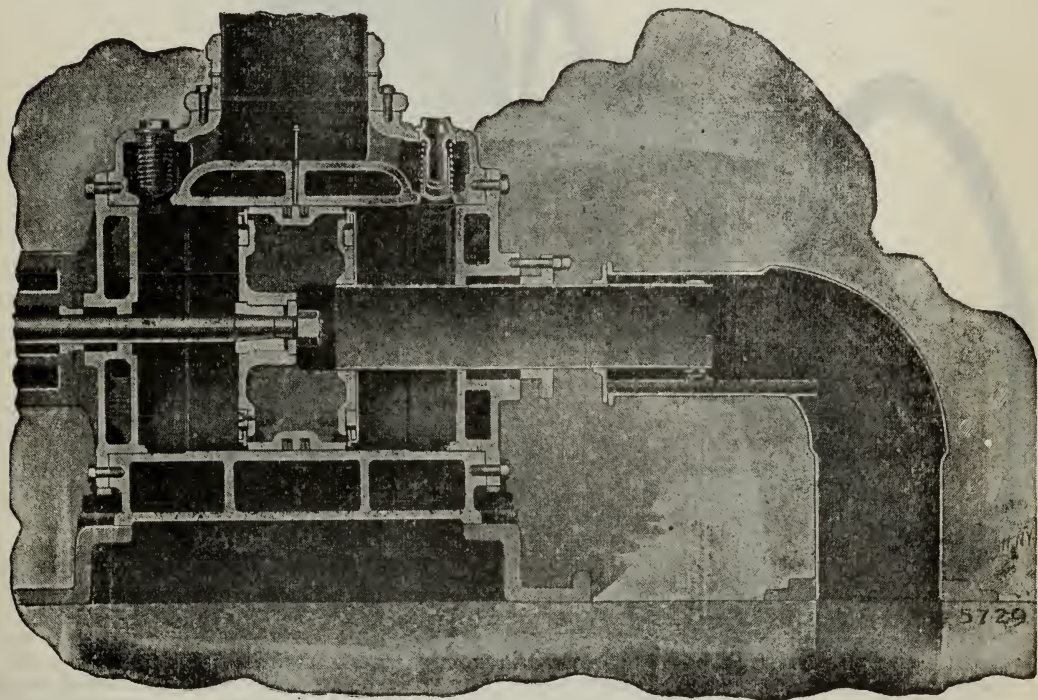


FIG. 4,353.—Ingersoll-Rand air cylinder with *hurricane inlet valves*.

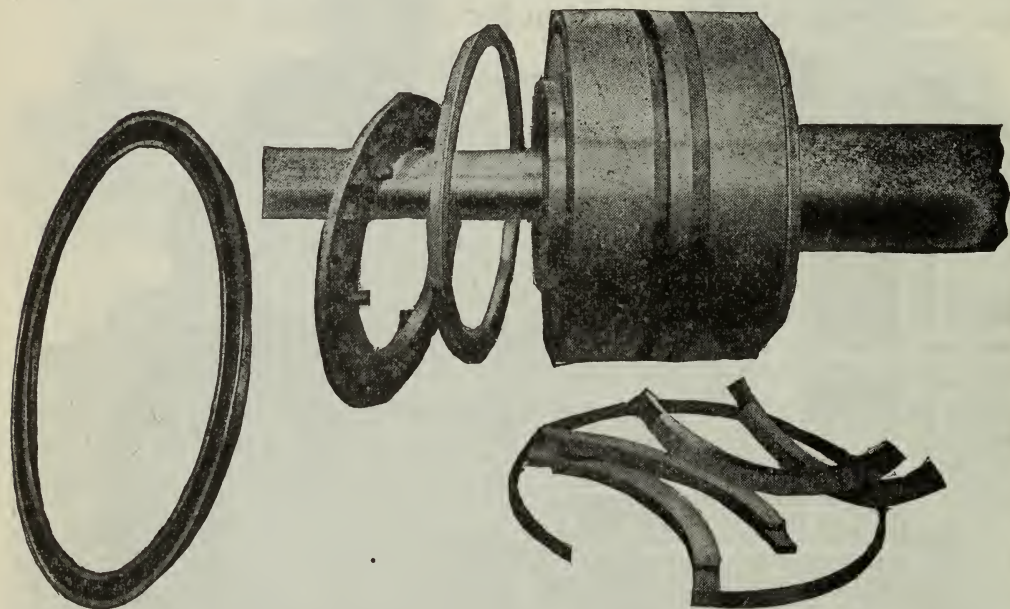
The spray injection cylinder has now given way almost entirely in this country to the dry or jacketed cylinder.

**Ques.** What are the features of the spray injection process?

**Ans.** A higher thermal efficiency may be attained than by the dry process, but from a commercial point of view its

efficiency is not so high, for the water in the cylinder prevents proper lubrication.

Impurities in the water also attack the walls of the cylinder, calling for repeated reboring of cylinder and other heavy repairs; the heat absorbs considerable of the moisture and this is deposited in the delivery pipe where it freezes in cold weather and restricts the passage of air, or it is carried to the motor, where it chokes the exhaust ports by reason of low temperatures resulting from expansion.



FIGS. 4,354 to 4,362.—Ingersoll-Rand hurricane inlet valve, and a hurricane inlet piston with its component parts. *In construction* the piston carries two ring valves, one on each face. Each valve is a simple ring forged without welds from a solid billet and turned to a light T section. The inlet part is an annular opening in each piston face, of very large area and free from any obstruction, so that its entire area is effective. Bolted to the face of the piston is a steel guide plate with a series of large openings just within its circumference. The ring valve rests loosely between the guide plate and the piston face, the bar of the T forming the valve face and the upright of the T, the guide section sliding on the guide plate. The travel between the guide plate and piston is the lift of the valve. The construction is identical on both faces of the piston. *In operation* the two valves travel with the piston, the one in front closing by its inertia and remaining closed under the air pressure in advance of the piston. The other valve (assuming that this is the first stroke) drops back against its guide plate the moment the piston starts, making a full valve opening which is maintained until the piston stops, when this valve, continuing its motion, slides gently to its seat. On the return stroke the leading valve (which was the following valve on the forward stroke) is already closed and compression begins. The following valve is now held to its seat by clearance pressure until enough of the stroke has been completed to expand the clearance air to intake pressure. This valve then drops behind the piston because of its inertia, thus fully opening and remaining open until the end of the stroke, when it closes instantly, thus completing the cycle. The valve is double ported, air entering the cylinder outside the ring valve and inside of it through the openings in the guide plate.



**Ques.** What are the features of the dry or jacketed compressor process?

**Ans.** In this system the external walls of the cylinder are flooded with cooling water which keeps the cylinder walls sufficiently cool so that proper lubrication is not interfered with and all other disadvantages of the wet compressor are obviated.

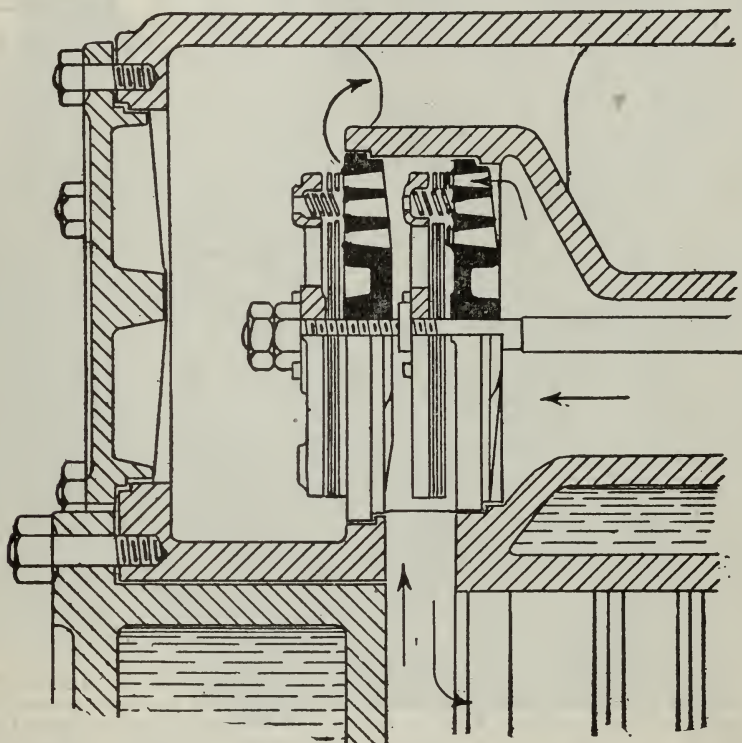
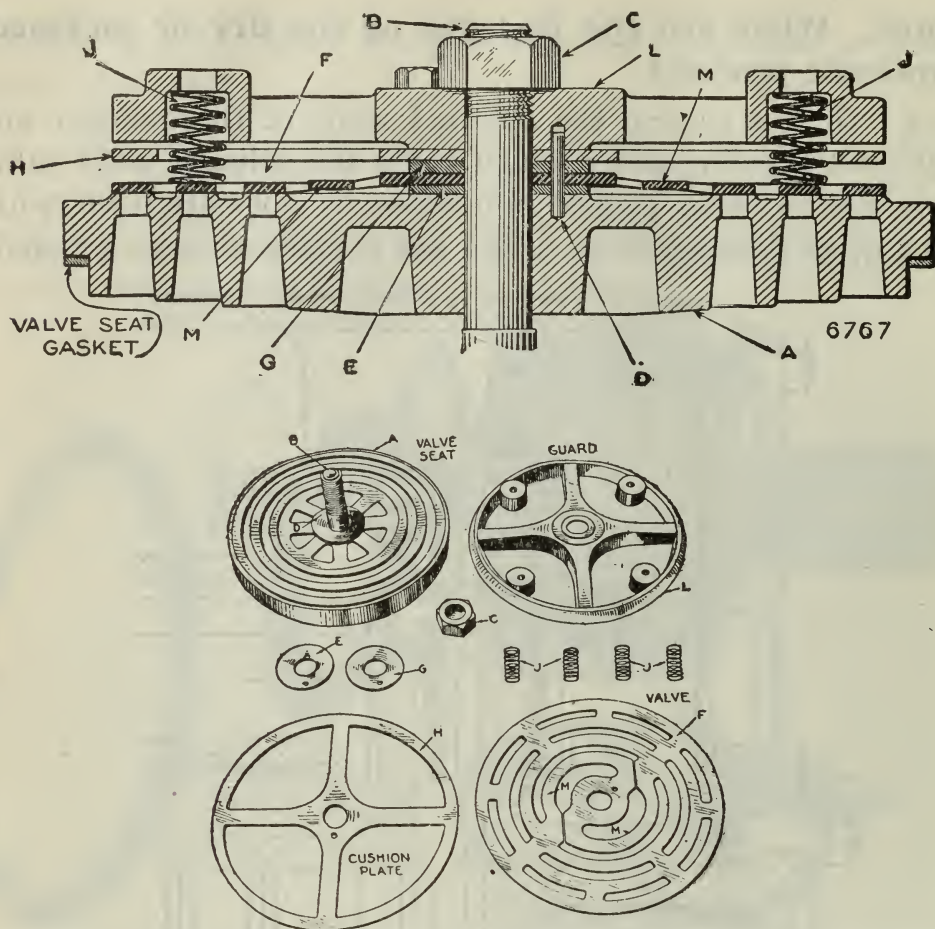


FIG. 4,363.—Sectional view showing method of placing Ingersoll-Rogler inlet and discharge valves in the cylinder of duplex compressors.

**Compound Compression.**—The efficiency due to the heat of compression decreases as the terminal pressure increases, and for pressures above 60 lbs., the water jacket of the simple compressor is not sufficiently effective for producing the most economical results, and stage or compound compression is resorted to as the most practical and efficient method for reducing the loss due to the *heat of compression*.



FIGS. 4,364 to 4,375.—Cross section of Ingersoll-Rogler valve and parts. **In construction** A is the valve seat; B, the valve bolt; C, the valve bolt nut; E, a washer placed between the valve seat and the valve proper. F is the valve; G a washer placed between the valve and cushion plate H. L is the guard; J, the valve springs, placed inside the four pockets of the guard and which act on the valve. Washers E and G, valve F, and stop plate H are clamped by means of valve bolt B and kept from turning by a dowel pin D. The portions M of the valve F are integral spring arms. They are ground to about half the thickness of the valve proper, and are made narrow, giving elasticity. The portions M of the valve proper, and are made narrow, giving them great elasticity. These portions M should not be confused with the term springs; they are merely connecting arms between the fixed and the moving sections of the valve and serve to hold the valve in one position and seat it always in the same place. With valve at rest, it is held in its seat by the four main springs J, against a slight tension of the integral valve arms M. As soon as the air pressure required to open is reached, the valve opens against these four coil springs to very nearly its full opening. It then comes in contact with the cushion plate H and moves the last  $\frac{1}{32}$  inch to  $\frac{1}{64}$  inch of its travel against its additional spring tension, the cushion plate having a certain amount of elasticity, it being fixed in the center only. When the piston passes the dead center on the return stroke, the valve closes. The function of the cushion plate is to act as a buffer, absorbing any shock that might otherwise fall on the valve, thus prolonging the life of the valve and reducing the noise.



**Ques.** How are the cylinder diameters of a compound compressor proportioned?

**Ans.** They are so proportioned as to divide the work of compression equally between the given number of cylinders.

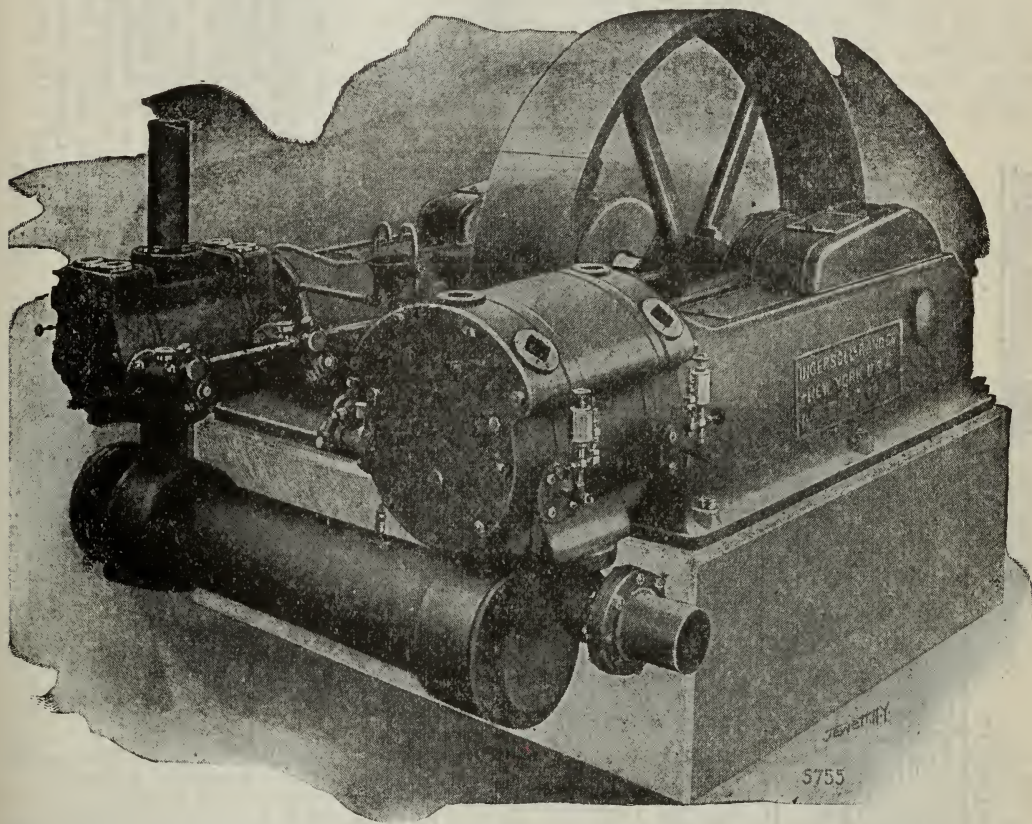


FIG. 4,376.—Ingersoll-Rand Imperial type, compound or two stage duplex belt driven air compressor with underneath intercooler. The cranks are at  $90^\circ$ , thus giving the advantages of stress reduction, and nearer uniform effort inherent in this sequence of crank.

**Ques.** Describe the cycle of compound compression with intercooling.

**Ans.** Free air is admitted to the low pressure cylinder, where it is partially compressed, and then forced into an *intercooler*. The intercooler acts as a receiver and at the same time removes the heat of compression of the intake cylinder before the air

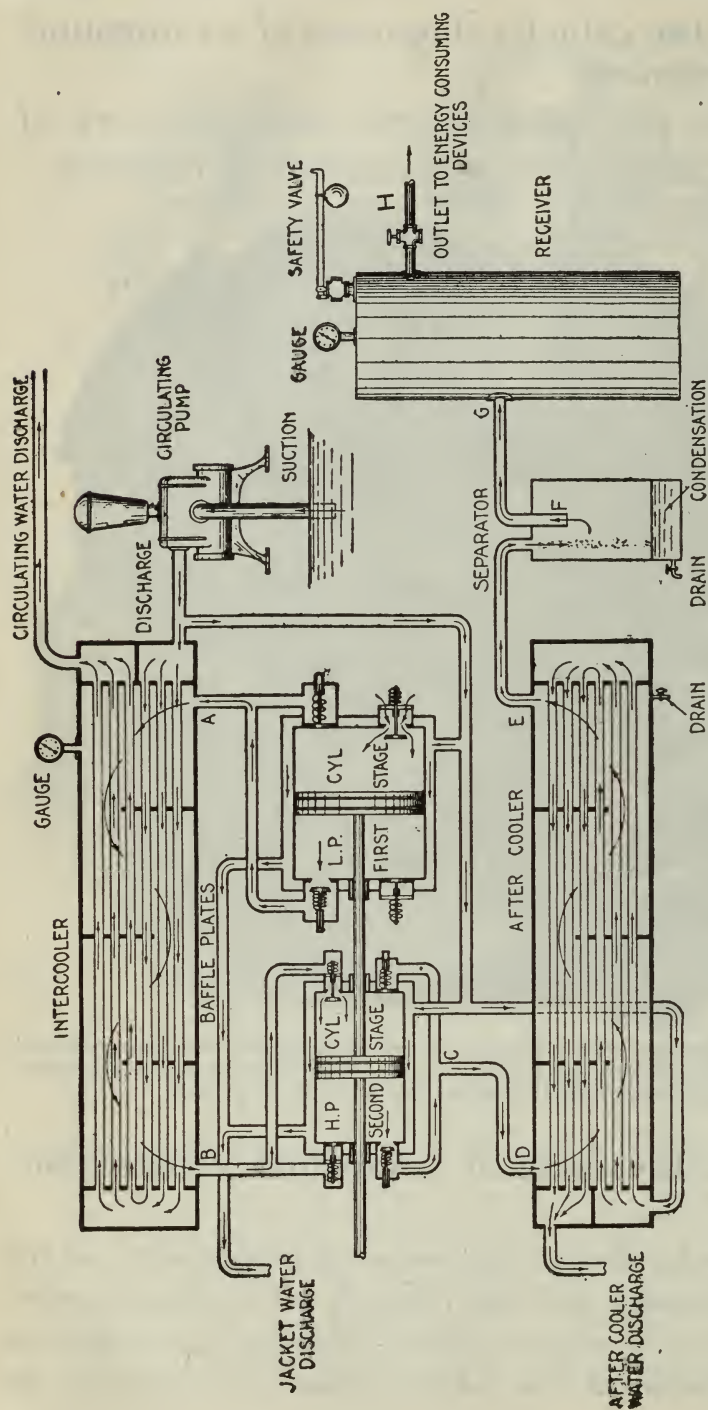


FIG. 4.377.—Elementary compound or two stage air compressor showing all the auxiliary apparatus essential for maximum efficiency in two stage compression. *The cycle of operation* is as follows: Free air is compressed in the **low pressure cylinder** to a moderate pressure and discharged into the intercooler at A, where the **heat of compression** is carried away by the **cooling or circulating water** which flows from the **circulating pump** through the **intercooler cooling tubes**, short circulating being prevented by the series of **baffle plate**. Passing out of the intercooler at B, it enters the **high pressure cylinder** and is again compressed from moderate to high or working pressure, being discharged at C, into the intercooler, the circulating water connection being clearly shown. The highly compressed air now leaves the after cooler at E, and passes to the **separator**. The construction of this device, as shown, causes the current of compressed air to **suddenly change its direction** 180°, thus causing any moisture or water that may be in the air to be hurled to the bottom of the separator by **centrifugal force**. Thus freed of water and moisture, the dry air leaves the separator at F, and enters the **receiver** at G, wherein it is stored, at the working pressure, and is discharged through the outlet H, to perform various kinds of work such as driving rock drills, engines, and all kinds of pneumatic tools. The numerous arrows seen in the diagram show: 1, course of the air in traversing the apparatus; 2, direction of piston movement at the instant depicted; and 3, the direction of water flow: a, through the cylinder jacket; b, through the intercooler; and c, through the after cooler.



is admitted to the second stage cylinder. In the high pressure cylinder the process of compression is completed and the air is delivered to the receiver at the required terminal pressure.

The final temperature in each cylinder will be the same if the work has been divided equally and the intercooler properly designed, but it will be very much lower than if the compression were done in one cylinder. For instance, in compressing air to 100 pounds pressure in a two stage compressor, the air is compressed from atmospheric pressure to, say,  $26\frac{1}{2}$  pounds in the intake cylinder and is delivered to the

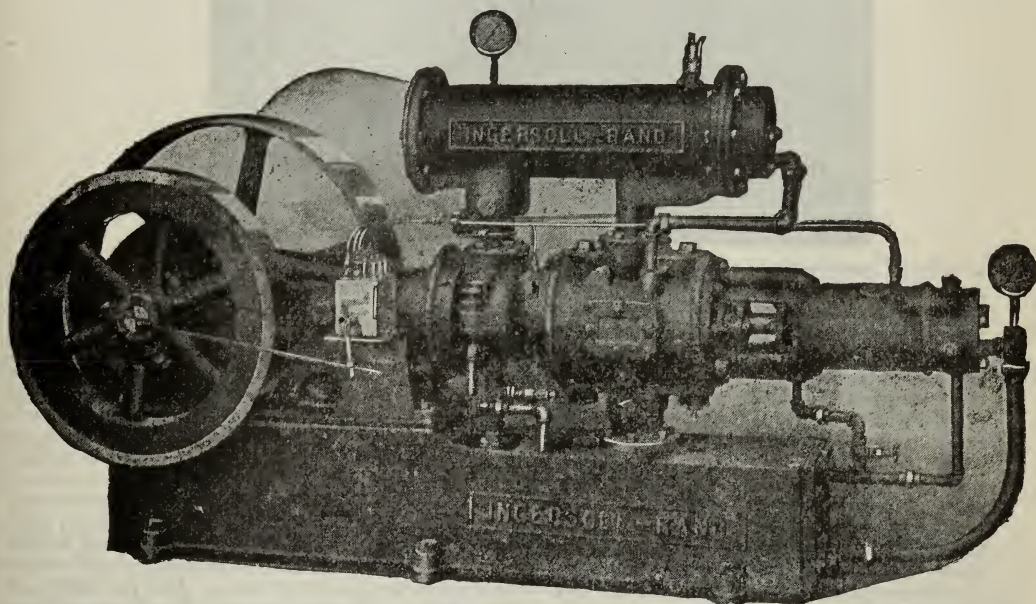
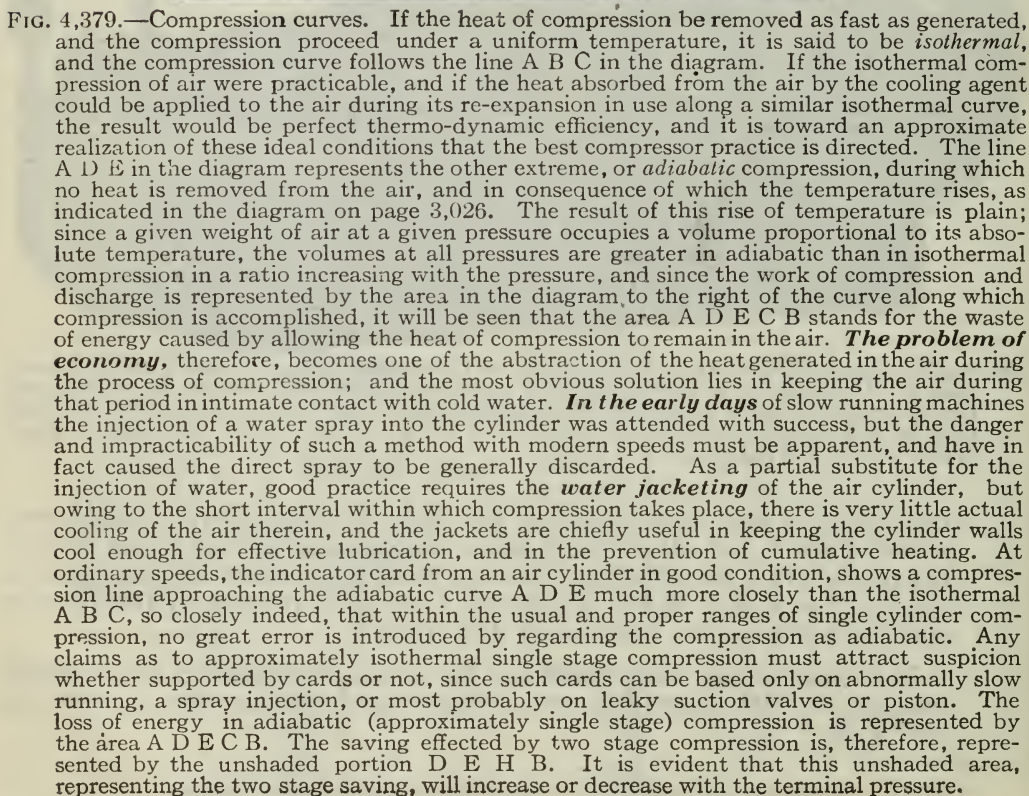


FIG. 4,378.—Ingersoll-Rand triple compression, or three stage high pressure air and gas compressor. Probably the largest demand for high air pressures comes from the mining and contracting fields where pneumatic haulage is employed. Scientific and experimental work calls for still higher pressures in air and gas and the U. S. Government uses high pressure air for a variety of purpose.

intercooler at this pressure and at  $240^{\circ}$  Fahr.\* (atmospheric temperature at  $60^{\circ}$  Fahr.). If all of the heat of compression be taken out by the intercooler, it is admitted to the high pressure cylinder at atmospheric temperature and is there compressed from  $26\frac{1}{2}$  pounds to 100 pounds and delivered to the receiver at  $240^{\circ}$  Fahr.\*

In a single stage compressor the air is compressed from atmospheric pressure to 100 pounds in one cylinder and reaches the receiver at  $482^{\circ}$  Fahr.\*

\* NOTE.—Radiation and cooling influence of water jacket not considered.





**Ques.** What is the principal advantage of compound compression over simple compression?

**Ans.** The reduction of the loss due to the heat of compression.

Other important advantages due to compounding may be enumerated as follows:

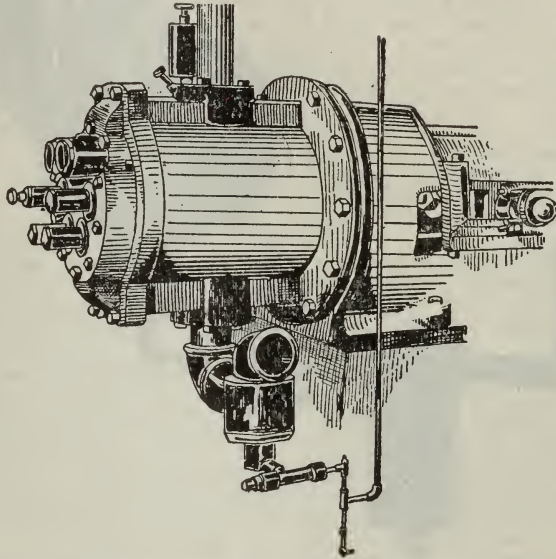


FIG. 4,380.—Rand air cylinder showing control devices. **Unloading device:** The speed of a belt driven air compressor cannot be controlled the same as that of a steam driven machine; its regulation must be accomplished either by throwing off the load, or by stopping the machine during the intervals when there is no demand for compressed air. Accordingly on belt driven compressors a device is provided called an *unloader*, which is placed in the air inlet pipe close to the intake cylinder, and unloads the compressor by cutting off the supply of air. When the unloader is in action, no work is done by the machine excepting that necessary to overcome friction. **Relief starting valve:** This device is used on compressors employing poppet inlet valves. One is placed in each head and consists of a screw, with a knurled handle, threaded into an inlet valve bonnet, and when screwed in, it forces the inlet valve from its seat. By thus holding an inlet valve open in either head, the compressor may be started without load, and when full speed is attained, the valves may be closed, and the compressor permitted to perform its regular work.

1. Cooler intake air;
2. Better lubrication;
3. Reduction of clearance losses;
4. Lower maximum strains and nearer uniform resistance.

The temperature of air leaving the intake cylinder being low, the cooling influence of the jacket is better, the cylinder walls are cooler

between strokes, and the air enters the cylinder cooler than in a single stage compressor. The lubricant for cylinders and valves is not subject to the pernicious influence of high temperatures; and the clearance losses, or losses due to dead spaces, are less in a compound compressor than in a simple compressor. Clearance loss in an air compressor is principally a loss in capacity, and therefore affects only the intake cylinder; it increases with the terminal pressure, but since the terminal

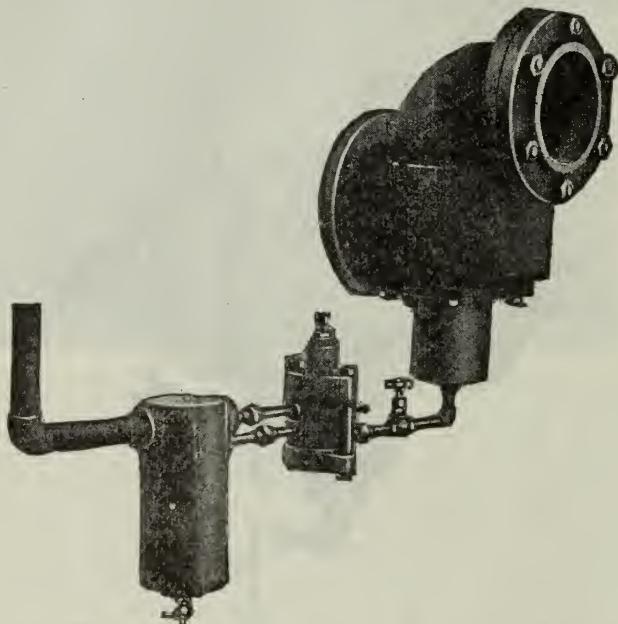


FIG. 4,381.—Ingersoll-Rand Imperial unloader. *It operates* by closing the air intake, and automatically regulates the compressor, maintaining the line pressure within a satisfactory range. *It consists* of a valve on the compressor intake pipe, normally held open by its own weight. When receiver pressure rises above normal this pressure is communicated through a small pipe from the regulating valve, acting to close the valve in the intake pipe, thus shutting off the air supply. The regulating valve can be adjusted for any working pressure by means of a spring adjusting screw.

NOTE.—Air compressor builders and those who use compressed air will agree that the problem of heating or cooling air is a difficult one. Hot air in the cylinder of an air compressor means a reduction in the efficiency of the machine. The trouble is, that there is not sufficient time during the stroke to cool thoroughly by any available means. Water jacketing is the generally accepted practice, but it does not by any means effect thorough cooling. The air in the cylinder is so large in volume that but a fraction of its surface is brought in contact with the jacketed parts. Air is a bad conductor of heat and takes time to change its temperature. The piston while pushing the air toward the head, rapidly drives it away from the jacketed surfaces so that little or no cooling takes place. This is especially true of large cylinders, where the economy effected by water jackets is considerably less than in small cylinders. Engineers who are shown indicator cards from large air compressors with pressure lines running away from the adiabatic, naturally regard them with suspicion, and look for leaks past the piston or through the valves. Such leaks will explain many isothermal cards, and until something better than a water jacket is devised, it is well to seek economy in air compression through compounding. The great advantage of compounding is in the fact that more time is taken to compress a certain volume of air, and that this air while being compressed is brought into contact with a larger percentage of jacketed surfaces.



NOTE.—Since the power driven compressor is almost always a constant speed machine various methods of regulation are employed. Constant speed means constant piston displacement; the problem of delivering a variable volume of air with constant piston displacement, becomes one of making a portion of that displacement non-effective in the compression and delivery of air. Only the fundamental principles of several methods of accomplishing this will here be discussed.

NOTE.—*The first method* is really one of unloading, rather than of regulating. A pressure controlled mechanism is arranged so that when pressure exceeds normal a communication is opened between the two sides of the compressing piston. Usually this is accomplished by opening and holding open one or several of the discharge valves at both ends of the cylinder, the air is then simply swept back and forth from one side of the piston to the other through the open valves and the air discharge passage. When normal pressure is restored, the valves are automatically closed, and compression and delivery are resumed. Evidently this is practically a total unloading of the machine for a longer or shorter period—a sudden release from load and a sudden resumption of load. Moreover, the air which is swept back and forth by the piston in its travel is air under full pressure; so that when the discharge valves suddenly close, the piston at once encounters a full cylinder of air at maximum pressure. These facts limit regulators of this class to machines of comparatively small capacity.

NOTE.—*The second method* provides, by means of a pressure operated device, for the partial or total closing of the compressor intake under reduced load. To avoid the dangers attendant upon such an operation acting suddenly, these devices are provided with some damping mechanism so that they are compelled to operate slowly, making the release or resumption of the load gradual. The cutting down of the air intake results in a rarefaction of the air entering the cylinder, and a greater range between initial and discharge pressures, with a corresponding increase in the range of temperatures. This method of regulation, therefore, is not suitable for very great load variations.

NOTE.—*The third method* is very similar to the first, except that here the inlet valves, instead of the discharge valves, are held open when the machine is unloaded, the piston thus simply drawing in and forcing out air at atmospheric pressure. It is open to the same criticism (though in somewhat less degree) as the first method, namely, undue shock and strain on release and resumption of load.

NOTE.—*The fourth method* uses a pressure controlled valve on the compressor discharge of single stage machine, combining also the functions of a check valve to limit the escape of air from the receiver or air line. Excessive pressure blows the discharge to atmosphere, instead of into the line. This arrangement is also used on two stage machines by placing it on the low pressure discharge to the intercooler. Then, when the governor valve is opened by excess pressure, the low pressure cylinder discharges to atmosphere, and the high pressure cylinder acts simply as a low pressure cylinder with intake at atmospheric pressure. This device is more of a relief valve than an unloader, for the piston must continue to compress to a pressure which will open the discharge valves; this volume of compressed air is wasted.

NOTE.—*The fifth method* provides auxiliary clearance spaces, or pockets, at each end of the cylinder, which are successively "cut in" as load diminishes. The excess air is simply compressed into these clearance spaces and expanded on the back stroke. The capacity of the cylinder is reduced without any appreciable waste of power; for the energy used in compressing the clearance air is given back by its expansion.

NOTE.—On power driven compressors with Corliss intake valves, several different methods of unloading or regulating are used. By one method, the Corliss valve is held open for the full admission stroke, and also for a part of the compression stroke, this latter portion being determined by the unloading called for. Evidently this is practically equivalent to a shortening of the stroke of the compressor. By another method the Corliss intake valve is opened full at beginning of admission, but closes later in the admission stroke. The air admitted to that point is expanded or rarefied for the remainder of the compression stroke, and then compressed, the volume of compressed air delivered being of course reduced. This arrangement is productive of an excessive temperature range in the cylinder. Still a third method opens and holds open the intake valves at the end of the cylinder, or at opposite ends in duplex machines. The effect of this is to make ineffective one out of every two strokes. If still further unloading be necessary, the intake valves at the other end of the cylinder or cylinders are opened and held open. The three arrangements just outlined all operate by a pressure controlled mechanism which actuates some form of trip on the Corliss air valve gear.

NOTE.—Three things are to be avoided in the successful unloader or regulator for power driven machines; first, a sudden release or resumption of load, throwing heavy strains on the machine; second, undue rarefaction of the intake air, resulting in a wide range of cylinder pressures and temperatures; third, the blowing off of compressed air to the atmosphere with a waste of power.

pressure of the intake or low pressure cylinder of a compound compressor is much less than the terminal pressure of a simple compressor, the volumetric efficiency of the compound compressor is greater than that of the simple compressor.

The life of a compound compressor is longer than that of a simple compressor for like duty. The maximum strains on most all wearing parts of a compound compressor are less than those of the simple compressor, due to better distribution of pressures, and the resistance due to compression is more uniform, which influence on the power distribution tends to higher steam economy.

**Intercoolers.**—A properly designed intercooler should reduce the temperature of the air back to the original point, that is,



FIGS. 4,382 to 4,384.—Ingersoll-Rand overhead intercooler and intermediate separator. On small sizes it is placed crosswise beneath the air cylinders; in sizes heavy 16 inch and larger the intercooler is crosswise of the compressor and above the air cylinders. **It consists of** a shell containing a nest of galvanized iron tube through which cold water circulates. The discharge from the low pressure cylinder passes over, across, and between these tubes, being directed back and forth transversely by suitable baffle plates. Prolonged contact with cooling surfaces and complete subdivision is obtained by the design of the water heads, which give a lengthened circulation of cooling water, resulting in economical use of water. **In construction** the baffle plates are held in place by a system of spreader, which constitute a frame for the nest of tube. Since the tubes and inside water head are free in the shell, they can expand or contract without causing leakage. The entire set of tube can be withdrawn at one end of the intercooler for cleaning, if necessary. On the overhead intercoolers, the connection between intercooler and high pressure air cylinders forms a water separator through which the air passes. Entrained moisture is caught and drains to the chamber in bottom of the separator, where a drain cock is provided for its removal. This results in the delivery of practically dry air to the high pressure cylinder.

**NOTE.**—It is usually desirable to start a power driven compressor with no load, throwing on the load gradually after normal speed has been reached. This is in fact essential in machines driven by electric motors, for the heavy inrush of current in starting under load is dangerous, particularly where power is taken from a transmission circuit supplying other motors. Evidently almost any of the unloading devices noted in the previous section can be used for this purpose if properly arranged for manipulation. The usual form, however, is simply a by pass valve to atmosphere on the line close to the compressor protected by a check valve between it and the receiver to prevent the return of air from the line when the starting unloader valve is open. This check valve is essential where several compressors serve one line, permitting cutting in or out any machine without unloading the others. This by pass valve is opened on starting, when the compressor simply compresses to a pressure sufficient to open its discharge valves, this air escaping to atmosphere. When normal speed is reached, the by pass or unloading valve is gradually closed and load resumed. On two stage machines, an unloader valve should be provided on the low pressure discharge to the intercooler, as well as on the high pressure discharge to the line. In the latter case, both cylinders operate momentarily as low pressure cylinders.



to the temperature of the intake air. It can even do more than this, especially in winter, when the water used in the intercooler is of low temperature. A simple coil of pipe submerged in water is not an effective intercooler, because the air passes through the coil too rapidly to be cooled to the core, and such intercoolers do not sufficiently split up the air to enable it to be cooled rapidly. This splitting up of air is an important point. A nest

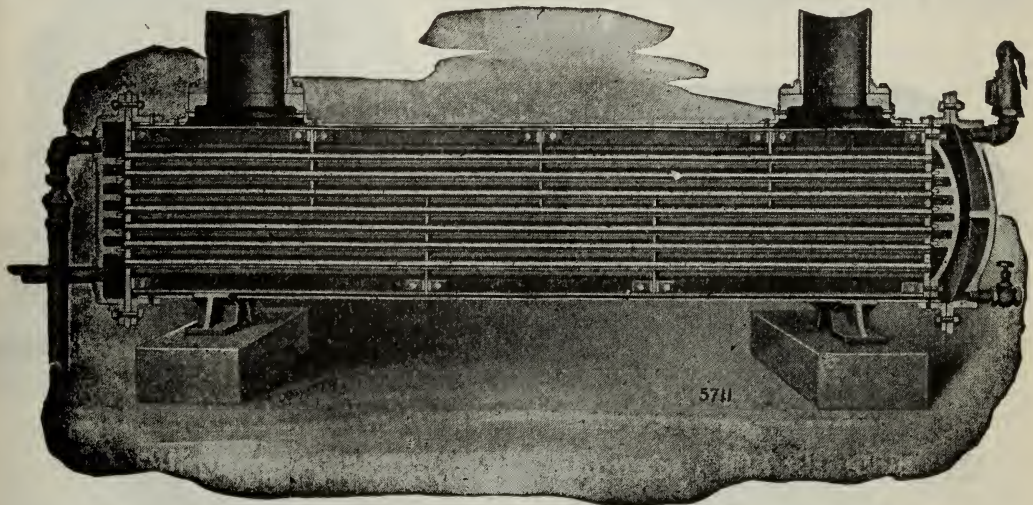


FIG. 4,385.—Ingersoll-Rand horizontal aftercooler with brass tubes. *It consists of a horizontal shell supported on cast foot pieces. Air inlet and discharge connections are usually at the top and the water drain at the bottom. Within the shell is a nest of tinned brass tubes expanded in steel tube plates at each end, an expansion joint being provided at one end. Baffle plates face a cross circulation of the air over the tubes. The cooling water enters the lower set of tube, traversing each row, forward and back, leaving at the top of the one end of the after cooler. In another design galvanized iron pipes are used instead of brass tubes. These pipes are of two sizes, the larger telescoping the smaller and so arranged in pairs that water flows *in* through the inner tube and *out* through the annular space between the inner and outer tubes.*

NOTE.—H. V. Haight in *American Machinist* says: "In multi-stage air compressors, the efficiency is greater the more nearly the temperature of the air leaving the intercooler approaches that of the water entering it. The difference of these temperatures for given temperatures of the entering water and air is diminished by increasing the surface of the intercooler and thereby decreasing the ratio of the quantity of air cooled to the area of cooling surface. Numerous tests of intercoolers with different ratios of quantity of air to area of surface, on being plotted, approximate to a straight line diagram for which the following figures are taken:

Cu. ft. of free air per minute per sq. ft. of air cooling surface . . .	5	10	15
Diff. of Temp. F. between water entering and air leaving . . . . .	12.5°	25°	37.5°

of tube carrying water and arranged so that the air is forced between and around the tubes is an efficient form of inter-cooler. If the tubes be close enough together and are kept cold, the air must split up into thin sheets while passing through. Such devices are naturally expensive, but first cost is a small expense when compared with the efficiency of the compressor, measured in terms of coal and water consumed. Receiver inter-coolers are more efficient than those of the common type because

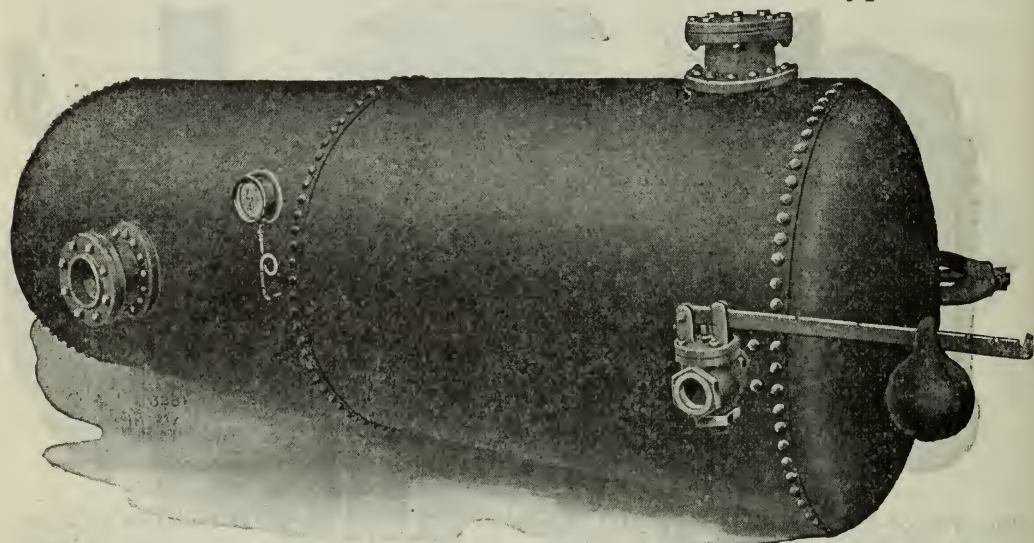
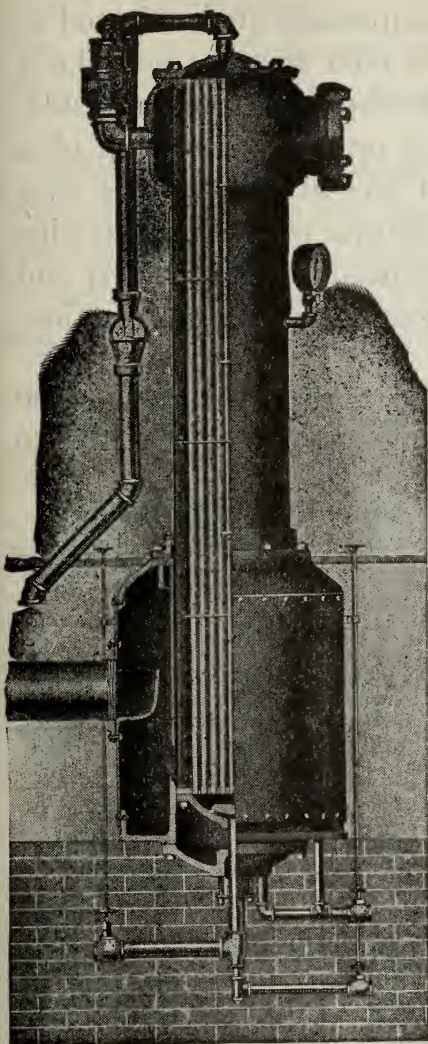


FIG. 4,386.—Horizontal air receivers. The discharge from an air compressor is more or less pulsating in character, and the receiver is analogous to an electrical rectifier, that is it receives and absorbs the pulsations, delivering a steady flow to the pipe line. It is, in a very small degree, an accumulator in which excess energy is momentarily stored and withdrawn. The receiver should be placed as close as possible to the compressor or after-cooler, and it is good practice to make the pipe between the receiver and compressor a size larger than that leaving the receiver. A safety valve and pressure gauge should be provided, and when the receiver is out of doors, the safety valve should be piped back into the compressor room to avoid freezing. There is some cooling of the air in the receiver, and since cooling involves condensation, the receiver should preferably be placed out of doors, where its cooling effect will reduce the moisture in the air. A drain cock should be provided at the lowest point which should be opened often for the discharge of accumulated water. Primary or main receivers, or those next to the compressor, should be so piped up that the air will enter at the top and leave near, but a little above, the bottom. On secondary receivers this arrangement should be reversed. On long pipe line systems small receivers, or moisture traps, should be placed at the low points in the lines, the piping entering and leaving at the top. These will catch the moisture condensed in the lines, which should be withdrawn frequently through a drain cock.

NOTE.—The successful intercooler must provide for a complete and minute subdivision of the air passing through it, that the heat may be dissipated without any dependence upon the heat conducting qualities of the air itself. The air should be split up into thin sheets or streams so as to dissipate its internal heat. There must be an ample cooling surface presented to this subdivided air stream.





the air is given more time to pass through the cooling stages because of the freedom from wire drawing which may take place in intercoolers of small volumetric capacity.

**After Coolers.**—The function of an after cooler is to *reduce the temperature of the air after the final compression*. In doing this it serves as a drier, reducing the temperature of air to the dew point, thus abstracting moisture before the air is started on its journey. In cold weather, with the air pipes laid over the ground, an after cooler may prevent accumulation of frost in the interior

FIG. 4,387.—Ingersoll-Rand vertical type after cooler, half in section. *In construction*, it has a shell or body made of steel throughout, with the exception of the head, which is an iron casting. Tinned brass tubes expanded in steel tube plates stand vertically in the body with provision for expansion and contraction at the lower end. Water enters at the lower end of the nest of tube leaving at the top. The air enters at the top or head, and leaves at the bottom, surrounding the tubes in transit and traveling counter current to the water. An open funnel in the water discharge shows the flow of water and permits of its proper adjustment. The enlargement of the body at the bottom gives a little receiver capacity and also catches the condensed moisture which may be drained off at

intervals. A plate in front of the air discharge, guards against the escape of water which may be splashed up by the flowing air.

**NOTE.**—The after cooler has been devised to perform the cooling and drying functions by bringing the hot moist air from the compressor discharge in contact with the water cooled surfaces of such extent and during such a time that the moisture in the air will be condensed and deposited before it can enter the distribution system. Obviously the proper proportioning of the cooling surface and air velocity to volume of air to secure complete after cooling is a rather complex problem which needs a wide experience for its best solution.

**NOTE.**—After coolers, with adequate cooling surface, and properly supplied with water, will readily reduce the temperature of the compressed air to within 15 or 20 degrees of that of the cooling water. Obviously, the cooler the water supplied, the more complete the cooling and drying effected. The following figures (according to Ingersoll-Rand) are based on good cooling results with air at 80 to 100 lbs. pressure: When the temperature of the cooling water is 50, 60, 70, 80, 90 degrees Fahr., the gallons per hour required per 100 cubic feet of free air per minute, are respectively 120, 140, 160, 180, 200.

walls of the pipes, for where the hot compressed air is allowed to cool gradually, the walls of the pipe in cold weather act like a surface condenser and moisture may be deposited on the inside, for the same reason that frost appears on the inner side of a window pane. Another advantage of the after cooler is that it keeps the temperature of the pipe uniform, otherwise this pipe will be hottest near the compressor, gradually cooling down and being thus subject to irregularities of expansion and contraction.

**The Saving Due to Compounding.**—The table here given will serve to illustrate the large saving that it is possible to

**Work Lost in Terms of Isothermal and Adiabatic Compression**

Gauge Pressures	One Stage		Two Stages		Four Stages	
	Percentage of work lost in terms of isothermal compression	Percentage of work lost in terms of adiabatic compression	Percentage of work lost in terms of isothermal compression	Percentage of work lost in terms of adiabatic compression	Percentage of work lost in terms of isothermal compression	Percentage of work lost in terms of adiabatic compression
60	30.00	23.00	13.38	11.80	4.65	4.45
80	34.00	25.26	15.12	13.12	5.04	4.80
100	38.00	27.58	17.10	14.62	8.00	7.41
200	52.35	34.40	23.20	18.88	9.01	8.27
400	68.60	40.75	29.70	22.90	12.40	11.04
600	83.75	44.60	32.65	24.60	15.06	13.10
800	90.00	47.40	35.80	26.33	16.74	14.32
1000	96.80	49.20	39.00	28.10	16.90	14.45
1200	106.15	51.60	40.00	28.60	17.45	14.85
1400	108.00	52.00	41.60	29.40	17.70	15.00
1600	110.00	53.30	42.90	30.00	18.40	15.54
1800	116.80	54.00	44.40	30.60	19.12	16.05
2000	121.70	54.80	44.60	30.80	20.00	16.65

NOTE.—In the above table no account is taken of jacket cooling, it being a well known fact among pneumatic engineers that water jackets, especially cylinder jackets, though useful and perhaps indispensable, are not efficient in cooling, especially so in large compressors. The volume of air is so great in proportion to the surface exposed and the time of compression so short, that very little cooling takes place. Jacketed heads are useful auxiliaries in cooling, but it has become an accepted theory among engineers that compounding or stage compression is more fertile as a means of economy than any other system that has yet been



effect by compounding. This table gives the percentage of work lost by the heat of compression, taking isothermal compression, or compression without heat, as a base.

**Altitude Compression.**—The height of the atmosphere surrounding the earth has been variously estimated to extend from fifty miles to twenty thousand miles, and since air has weight it exerts a pressure upon surrounding objects which is equal to the weight of the air column above the object.

Since air is very elastic its weight will cause it to have a variable density throughout its height and exert varying pressures at different altitudes.

At the sea level an atmospheric column balances a column of mercury 30 inches high and of equal area, which corresponds to a pressure of 14.7 pounds per square inch. The variation in pressure for different elevations has been determined by barometric observations and by examining a table of such observations it will be noted that the atmospheric pressure decreases with increasing height, and as a consequence one pound of air occupies a greater volume at an altitude than at the sea level (at the same temperature); or a cubic foot of air weighs less at a higher altitude than at a lower one.

In descending the shaft of a mine the contrary effect is noticed, but in a mine or any level below the sea, increase in density is counter-balanced by increase in temperature as the center of the earth is approached. The temperature of the atmosphere also changes with increasing altitude, but is not always uniform for any two places at the same elevation.

NOTE.—Continued from page 3,044.

devised. The two and four stage figures, as given in this table, are based on reduction to atmospheric temperature 60° Fahr. between stages. This is an important condition, and in order to effect it, much depends on the intercooler. This device represents a case of jacket cooling which in practice has been found to be efficient where engineers specify inter-coolers of proper design. While cooling between stages the air may be split up into thin layers and thus cool it efficiently in a short time, a condition not possible during compression. This splitting up process should be done thoroughly, and while it adds to the cost of the plans to provide efficient coolers, it pays in the end. A rule which might be observed to advantage among engineers is to specify that the manufacturers should supply a compressor with coolers provided with one square foot of tube cooling surface for every ten cubic feet of free air per minute furnished by the compressor at its normal speed. Referring again to the table, it will be noted that when air is compressed to 100 pounds pressure per square inch in a single stage compressor without cooling, the heat loss may be 38 per cent. The condition, of course, does not exist in practice, except, perhaps, at exceedingly high speeds, as there will be some absorption of heat by the exposed parts of the machine. It is safe, however, to say that in large air compressors that compress in a single stage up to 100 pounds gauge pressure, the heat loss is 30 per cent. This, as shown in the table, may be cut down more than one-half by compounding or compressing in two stages, and with four stages this loss is brought down to 8 per cent. theoretically, and perhaps to 3 or 5 per cent. in practice. As higher pressures are used, the gain by compounding is greater.

The volumetric efficiency of an air compressor, expressed in terms of *free air*, is the same at all altitudes (for the displacement in a given size of cylinder is the same); but the volumetric efficiency, expressed in terms of *compressed air* at a given pressure, decreases as the altitude increases, for the quantity of air taken into a given cylinder per stroke being less dense at an altitude (due to lower initial or atmospheric pressure) it must be compressed into a smaller space for a given terminal pressure.

**Example.**—300 cubic feet of air, at atmospheric pressure of 14.7 pounds, compressed to 80 pounds gauge, will represent a volume of  $300 \times 14.7 \div 94.7 = 46.6$  cubic feet.

If the atmospheric pressure were 10.1 pounds in the above example, then the volume delivered would be  $300 \times 10.1 \div 94.7 = 34.1$  cubic feet; or the volumetric efficiency of a compressor performing the above work at the lower initial pressure would be but 73.2 per cent. of what it would be at the higher initial pressure.

In order, therefore, that an air compressor may deliver, at an altitude corresponding to the lower initial pressure, a volume of compressed air per stroke equal to that which it would deliver at a level corresponding to the higher initial pressure, the corresponding intake cylinder must be proportionately larger for the lower initial pressure as compared with the higher initial pressure.



## CHAPTER LXXXII

## ELECTRIC HEATING

Electricity is extensively used for heating both for domestic and industrial purposes. Its chief advantages are its cleanliness and the ease with which it can be controlled.

Some of the domestic appliances on the market are not quite satisfactory, but improvements are continually being made.

For instance, some are not sufficiently robust in construction to withstand kitchen wear; in others, the heating elements either soon fail, or else the temperature obtained gradually falls too low to be of practical service. Others have *live* parts that can be easily short circuited. This point should be noted in selecting heating devices.

The *cleanliness* of electric heat is its chief feature, no polluting gas, smoke, or soot being given off; in short, nothing but heat is generated.

With electric heating there is *less waste heat* than with any other method, because the heat can be generated or applied at just those parts of the appliance where it can most effectively do its work. It should be noted, that this does not mean that electric heating is more economical than other methods, for on the contrary it is more expensive except when electricity can be obtained at a very low cost, and moreover, the cost of the heating devices is high.

With an electric cooker, the surrounding atmosphere is not heated to anything like the extent that it is by a coal, gas, or oil cooking stove, and there are no fumes. This is a great advantage, especially during the summer months. As for *control* electric heating may be started and stopped with an ease which is impossible with any other method.



FIG. 4,388.—Simplex electric coffee percolator. Starting with cold water, through the circulating process as shown, drip coffee is ready in a few minutes, depending upon the degree of strength required. Three degrees of heat are provided, permitting quick making, and allowing the coffee to be kept hot at the lowest current consumption.

**Production of the Heat.**—For domestic and some industrial purposes, heat is produced by electricity by forcing it through resistance wires, raising the temperature of the latter, and applying the heat thus generated to the articles to be heated. Resistance wires are made of special materials and are capable of withstanding high temperatures without deteriorating. Metals and alloys having high specific resistance or low temperature coefficient of resistance are largely used for resistors. The following are the principal resistance wires:



**Advance.**—This material is a copper nickel alloy, containing no zinc. It is uniform in its composition and constant in its resistance under all conditions of service. It is recommended for apparatus in which the wire is subjected to repeated heating and cooling.

**Calido.**—This is a high percentage nickel chromium alloy containing a small percentage of iron. The melting point is about 2,822° Fahr. It is recommended for electrically heated devices.

**Climax.**—This is a high resistance nickel steel alloy. It is well suited for use in rheostats. It is one of the cheapest resistance metals.

**Excello.**—This is adapted for use in electric heating devices.

**Ferro-nickel.**—This alloy has a high current carrying capacity, on account of its low specific resistance. As it will rust, it can only be used where it is not attacked by moisture.

**German Silver.**—This is an alloy of copper, nickel and zinc. The grade of the wire designates the percentage of nickel. The 18 per cent. grade is the most common.

The resistance of any particular grade depends upon the degree of annealing; hard wire is slightly higher in resistance than soft. German silver was for many years the only resistance alloy obtainable, but it is now being generally displaced by materials of the same specific resistance but of superior qualities.

**Ia Ia** is recommended for use in instruments and electrical devices where a low temperature coefficient is desired.

**Ideal.**—This is an alloy of nickel and copper, and contains no zinc. The manufacturers state that its temperature coefficient is nil.

It may be used at an incipient red heat of 968° Fahr., and is adapted for resistors and measuring instruments.

**Krupp Metal.**—This is a special grade of nickel steel adapted for resistors.

**Manganin.**—This is a material developed by the Reichsanstalt, for use in instruments and standards.

The alloy which was shown to be the best for ordinary purposes is one containing 85 per cent. of copper, 12 per cent. of manganese, and 3 per cent. of nickel.

**Monel Metal.**—This metal contains approximately three parts nickel to one of copper.

The resistance varies somewhat in different lots, and according to temper. The variation is, however, no greater than that of 18 per cent. German silver.

**Nichrome.**—This alloy is practically non-corrosive, has an extremely high melting point (about 2,822° Fahr.) and is far superior to nickel in its ability to withstand high temperatures.

It is especially recommended for use in electrically heated appliances and resistance elements generally where extreme conditions are encountered.

**Nichrome 11.** This alloy is strongly resistant to oxidation. It has been especially developed for use in carbon combustion furnaces, and other laboratory furnaces where the more extreme temperatures are to be met.

**Nickel.**—Due to its high temperature coefficient nickel is very efficient for use in resistance thermometers and owing to its non-corrosive qualities it may be employed for rheostats where acid fumes are to be met with.

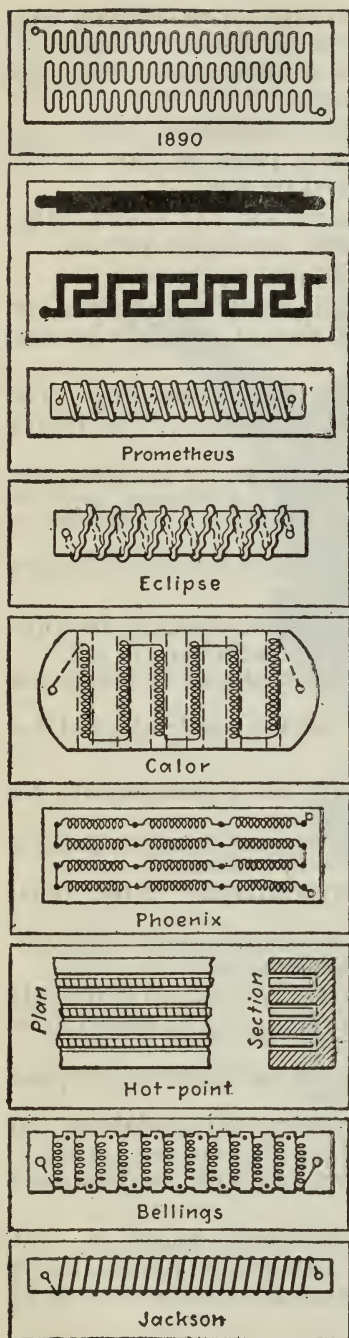
**Superior.**—This is recommended for use in rheostats, arc lamps, resistances, etc.

**Therlo.**—An alloy of copper, manganese and aluminum for work where low thermo-electric effect against copper is demanded. Compared with manganin, this alloy gives a higher specific resistance, does not oxidize so fast, and is more stable in its electrical and mechanical behavior. This material is especially suitable for shunts. Temperature coefficient is  $+0.0000031$  per  $1^{\circ}$  Fahr.

**Yankee silver.**—This is a new alloy with most of the qualities of "18 per cent German silver." It will withstand repeated heating and cooling and often gives satisfactory service where German silver fails.

**Heating Units.**—The term heating unit is given to that portion of a cooker or heater which gives out the heat for warming an oven or hot plate or for raising the temperature of a room. It consists of some material which is more or less a bad conductor of electricity, and when current is taken through it, by making it form a portion of an electrical circuit, it becomes hot owing to the resistance it sets up to the current. In order to meet the varied conditions of service there are numerous forms of resistor or heating unit, and these may be classified as :

1. Exposed coils of wire or ribbon open to air and wound around insulating material;
2. Wire or ribbon in the form of coil or flat layer embedded in enamel, asbestos, mica, or other insulators;



FIGS. 4,389 to 4,399.—Various types of heating unit.



3. Filling of metal fixed on enamel, mica, or glass;
4. Metallic powder mixed with clay and compressed in forms, and crystallized silica in tubes of glass.
5. Incandescent filaments in vacuum.

A common form of heating unit for use in percolators, chafing dishes, flat irons, etc., is the encased disc, the resistor being either a ribbon wound on a mica disc or a grid stamped from a thin sheet of the alloy and mounted between thin sheets of mica.

Electric radiators for room heating consist usually of a resistance wire wound on asbestos tubes covered with a coating of fire proof cementing compound. When air is thus excluded, German silver may be used as a resistor.

The "Cartridge" type of unit is used for grids, broilers, and disc stoves. It consists of a high resistance ribbon wound on a mica cylinder and coated with insulating cement. In placement, it is inserted in a hole in the casting which is to transfer the heat to the point where it is wanted. When a comparatively low operating temperature is required, as in flexible heating pads, asbestos insulated wire woven into a sort of honeycombed mat is used.

The following details are given of some of the heating units in general use:

**The Eclipse element** consists of high resistance ribbon crimped to give greater length and free air space, wound over mica strips with the ends connected to heavy eyelet terminals.

**The Calor element** has a base of fireclay with grooves into which spirals of fine high resistance wire are placed.

**The Phoenix element** has spiral wire coils held lightly at short intervals by porcelain insulators mounted on a suitable base.

**The hot point element** is made up of nichrome wire or ribbon, wound lightly around thin strips of mica, then further covered with a thin mica covering and inserted very tightly into grooves or slots made in the hot plate or iron base to receive the finished strips.

**The Belling element** consists of a fire clay strip with spirals of nichrome wire stretched across the width of the base, notches being provided in the base for receiving the ends of the spiral and holding them tightly in position in the manner shown.

**The Jackson element** has a different class of fire clay base with quite a smooth surface, the section of the strips being a flat oval wire or ribbon of nichrome, is wound tightly over the strip in one continuous length and clamped between heavy terminals at each end.

**The Tricity elements** consist of nichrome ribbon wound over thin mica and clamped between thin sheets of mica and metal. The method of winding provides for uniform distribution of heat at any loading.

**The Bastian or Quartzalite element** consists of a spiral of nichrome wire or ribbon coated with a film of oxide insulation. The spiral is held in or on a tube of quartz. The turns of the spiral may be close together without fear of short circuit. This gives it a "hot rod" appearance.

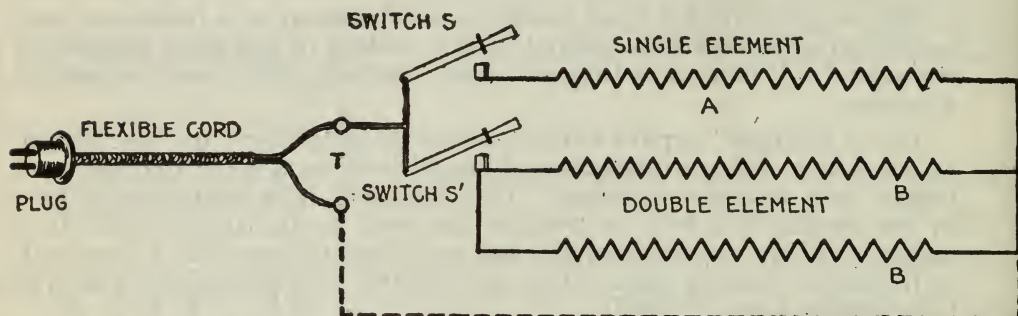


FIG. 4,400.—Arrangement of internal circuit for heaters giving three heating values. In the diagram A, represents one third of the heating circuit; BB, two thirds. With switch S on, one-third of full heat is given; with S', two thirds, while with both S and S' on, the heater works with full power. At T, are two terminals to which the ends of the flexible cord from the plug are secured.

**Temperature Regulation in Electric Heaters.**—Many appliances have only one internal circuit so that only one heating value can be obtained. There are, however, a great number which have their resistances divided into two or more parts, which can be connected in different ways, so that several heating values can be obtained.

In the simplest case, the internal circuit consists of two parts of equal heating capacity, each being independently controlled by an ordinary switch, or the two by a double switch, thus permitting operation

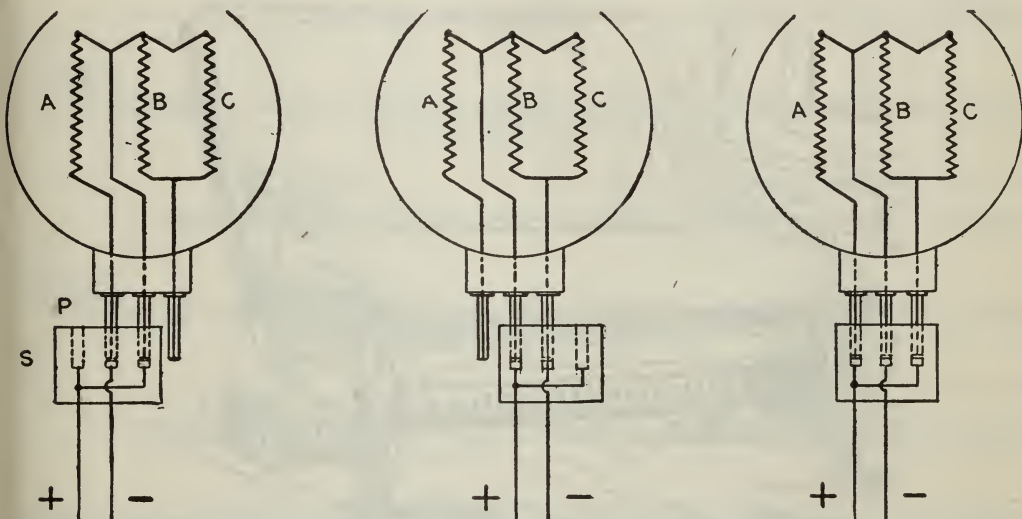
1. With either circuit on;
2. With both circuits on.



In some cases the internal circuit is divided into two parts of unequal heating capacity so three heating values can be obtained, by operating

1. No. 1 circuit alone;
2. No. 2 circuit alone;
3. Both circuits.

Thus, any degree of refinement of control can be obtained by providing enough internal circuit charges.



FIGS. 4.401 to 4.403.—Internal circuits of heater. As shown the heater wires are divided into three sections: A, B, and C, connected to the external terminals P. A three hole socket S has one conductor of a twin flexible cord connected to the two outer sockets, and the other to the middle socket. The socket piece may thus be put on the pins in three different ways, as shown in the three figures. In fig. 4.401, section A only of the heater is in circuit; in fig. 4.402, sections B and C are connected, and in fig. 4.403, all sections are in circuit. The signs + and - in each figure indicate the heater end of the flexible cord, the other terminating in a plug connection or switch plug on the wall. In some apparatus, a three or four hole socket is made to fit a corresponding number of pins in one position only, and is connected through a triple or quadruple flexible cord to a two or three way switch adjacent. The various degrees of heat are then obtained by altering the position of the switch.

**Room Heating.**—Only in a comparatively few instances is electricity employed to advantage in the heating of rooms, such practice being confined chiefly to intermittent auxiliary service in offices and dwellings, ticket booths, etc.

The following empirical formula gives the energy required in watts for heating rooms:

$$\text{watts} = \frac{\text{B. t. u. per hour}}{3.41} = \frac{2.71 (T - T_1) N}{3.41}$$

where  $T - T_1$  is the temperature difference in degrees Fahr. between the heated surface and the room, and  $N$  is the number of square feet of radiating surface. The power required to keep an ordinary sized room warm when the outside air is near the freezing point ranges from about 1 to 2 watts per cubic foot.

**Ques.** Is electric heating an economical method?

**Ans.** No.

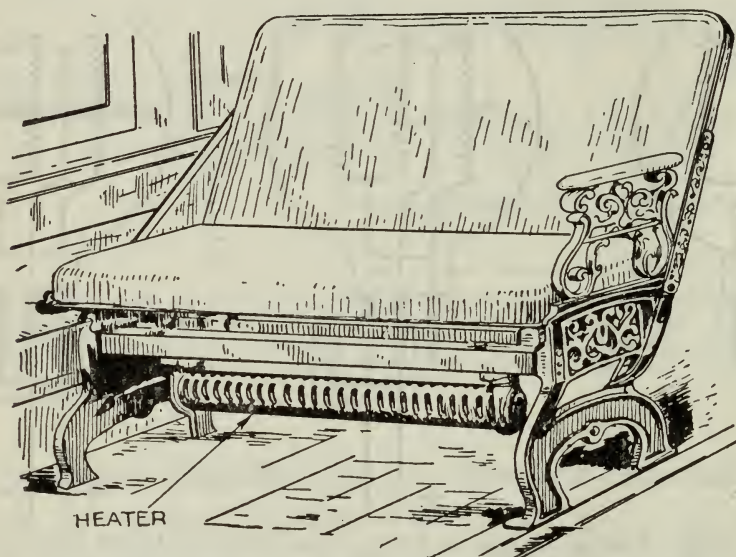


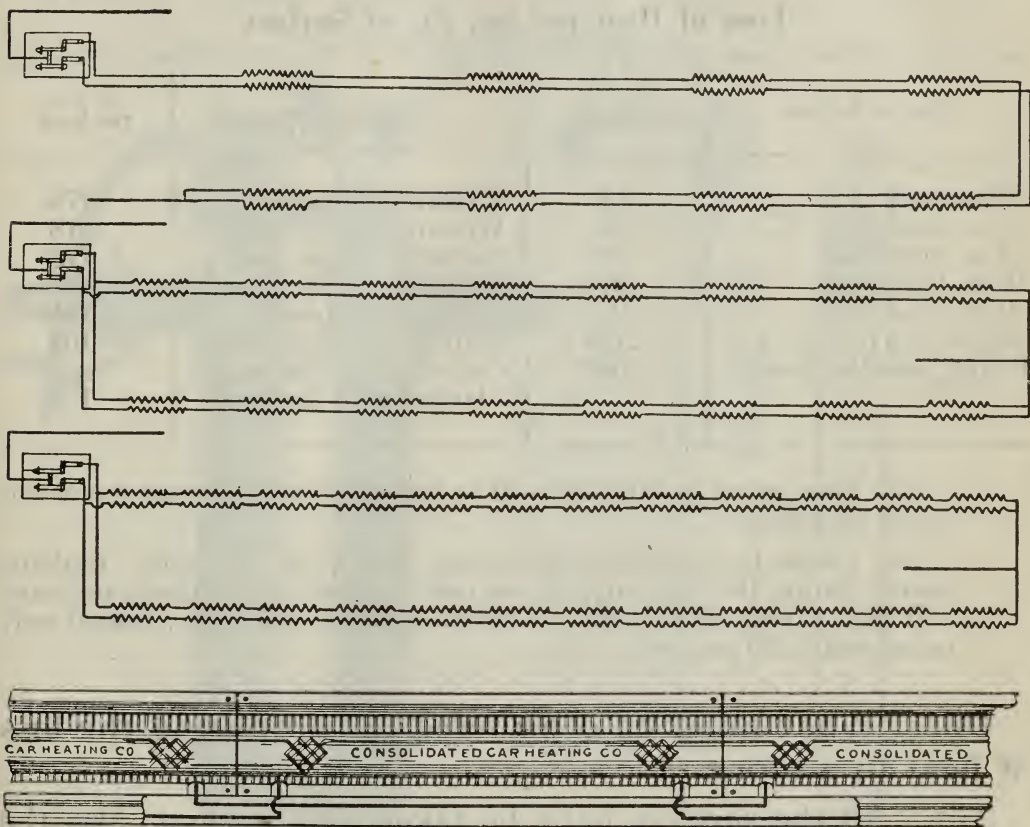
FIG. 4,404.—Underseat method of car heating; view showing seat and placement of heater. At the Montreal meeting of the American Street Railway Association some years ago, Mr. J. F. McElroy read an exhaustive paper on the subject of car heating, from which the following abstracts are taken: In practice it is found that 20,000 B.t.u. are necessary to heat an 18 to 20 foot car in zero weather. When the outside temperature is  $12\frac{1}{2}^{\circ}$  Fahr., only 16,000 B.t.u. are required, etc., which shows the necessity of having electric heaters adjustable. The amount of heat necessary in a car to maintain a given inside temperature depends on: 1, the amount of artificial heat which is given to it; 2, the number of passengers carried. The average person is capable of giving out an amount of heat in 24 hours which is equal to 191 B.t.u. This is evidently an error, as Kent says that a person gives out about 400 heat units per hour, and tests by the Bureau of Standards show approximately the same (413) for a person at rest, and about twice that for a man at hard labor (835).

**Loss of Heat.**—Heat escapes from buildings in two ways: 1, by conduction through the windows, walls, roof, and floor, and 2, by leakage of warm air.



**Ques.** Upon what does the loss by leakage depend?

**Ans.** Upon the tightening of the doors and windows, and upon the construction of the walls, floor and roof, especially in wooden buildings.



FIGS. 4,405 to 4,408.—Wiring diagrams for Consolidated heaters for use along truss plank, and view of truss plank in position showing wiring in moulding. Fig. 4,405, 8 heater equipment; fig. 4,406, 16 heater equipment; fig. 4,407, 24 heater equipment; fig. 4,408, truss plank heater.

If the outer walls be exposed to wind, the loss of heat by conduction will be increased from 10 to 30 per cent., and if they be not wind tight, the loss by leakage will be increased to an unknown amount.

**Ques.** What is the law relating to the rate at which heat is lost through walls and windows?

Ans. It is proportional to the difference in temperature between the inside and outside air.

The following table shows the loss of heat per square foot of window and wall surface, for one degree Fahr., difference of inside and outside temperature, the loss being expressed in heat units per hour.

**Loss of Heat per Sq. Ft. of Surface**

Kind of Surface	B. t. u. per hour	Kind of Surface	B. t. u. per hour
4 in. brick wall.....	.68	Window, single glass....	.776
8 in. brick wall.....	.46	Window, double glass...	.518
12 in. brick wall.....	.32	Skylight, single glass....	1.118
16 in. brick wall.....	.26	Skylight, double glass...	.621
20 in. brick wall.....	.23	Ceilings, fire proof.....	.145
Floors, fire proof.....	.124	Ceilings, wooden beams..	.104
Floors, wooden beams..	.683	Ordinary wooden wall, lathed and plastered..	.1

The losses given in the table will be increased under special conditions about as follows:

For northerly exposure, and strong winds, 10 per cent. Building heated during the day only, 10 per cent.; same with northerly exposure and high winds, 30 per cent. Churches, public halls, etc., heated only occasionally, 50 per cent.

**Ques. What must be considered in computing the loss of heat in a room.**

Ans. All the surfaces must be taken into account, also the surroundings.

If the room be located over a cold cellar, or lower side of floor exposed to cold, proper allowance must be made.

**EXAMPLE.**—What will be the loss of heat per hour in a single room wooden structure when the temperature inside is maintained at 70° Fahr., while the outside is at 32°. Size of room 10×10×10, having three 3×6 windows. Here all surfaces must be considered.

Area of windows = 3 (3×6) = 54 sq. ft.

Area of walls = 4 (10×10) − 54 = 364 sq. ft.



Area of floor =  $10 \times 10 = 100$ .

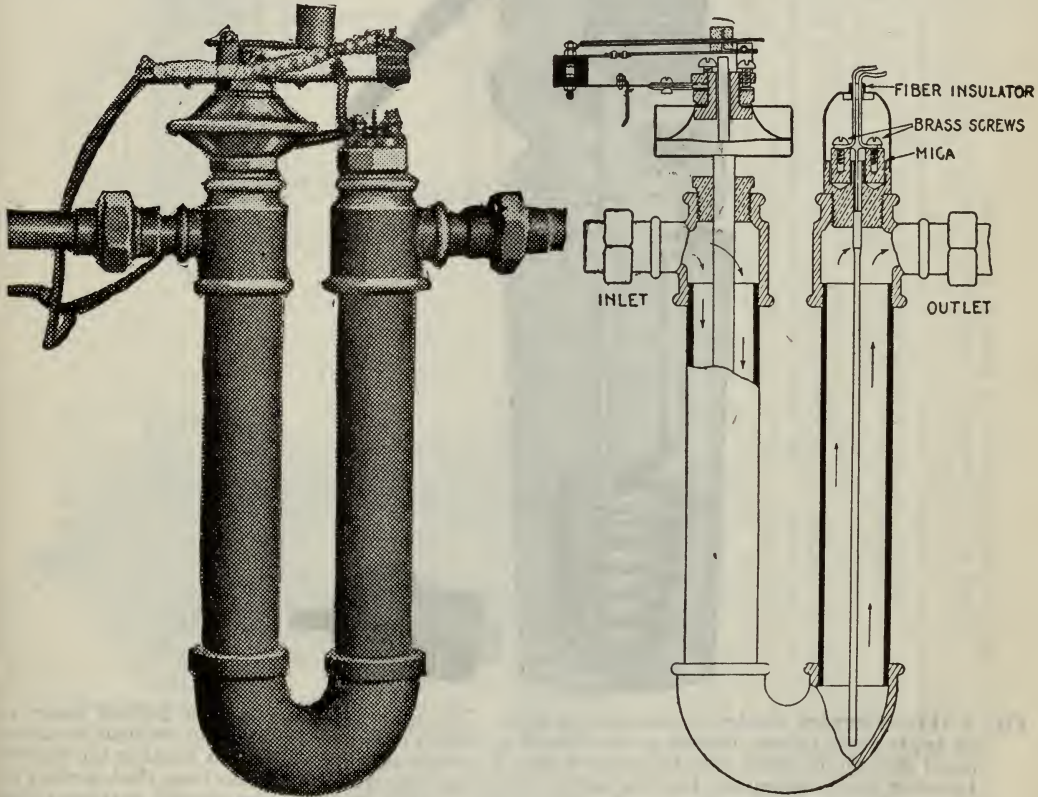
B. t. u. lost through windows =  $(70 - 32) \times .776 \times 54 = 1,592.4$

B. t. u. lost through walls =  $(70 - 32) \times .1 \times 346 = 1,314.8$

B. t. u. lost through floor =  $(70 - 32) \times .083 \times 100 = 315.4$

Total loss of heat per hour . . . . . = 3,222.6 B. t. u.

**Electric Water Heaters.**—These devices are made in a variety of form to suit different conditions.



FIGS. 4,409 and 4,410.—Exterior and sectional view of Good Housekeeping electric water heater designed to be connected on the circulation pipe of a kitchen boiler or other storage vessel for hot water. There is a resistance coil using 750 watts per hour (or greater consumption if desired, depending on the hot water requirements). The water is circulated from the bottom of the storage tank through the inlet in the water heater around the heating coil and through the outlet into the top of the storage tank. **In operation**, when all the water in the tank has been heated and the hot water circulates through the inlet of the water heater around the copper tube, the expansion of the liquid in the copper causes the diaphragm to buckle from convex to concave, which turns off the electricity, thus no current will be used until the water in the tank has cooled sufficiently to reduce the pressure, thereby allowing the diaphragm to buckle back and the circuit to be closed. When hot water is drawn from the top of the tank, cold water will replace it through the inlet around the copper tube reducing the pressure, the diaphragm will buckle back thereby closing the circuit, and only sufficient electricity is used to bring the temperature of the cold water up to the predetermined temperature of about  $180^{\circ}$  Fahr. in the bottom of tank.

The various methods of heating water may be classified

1. With respect to reserve capacity, as

- a. Non-storing;
- b. Storing.



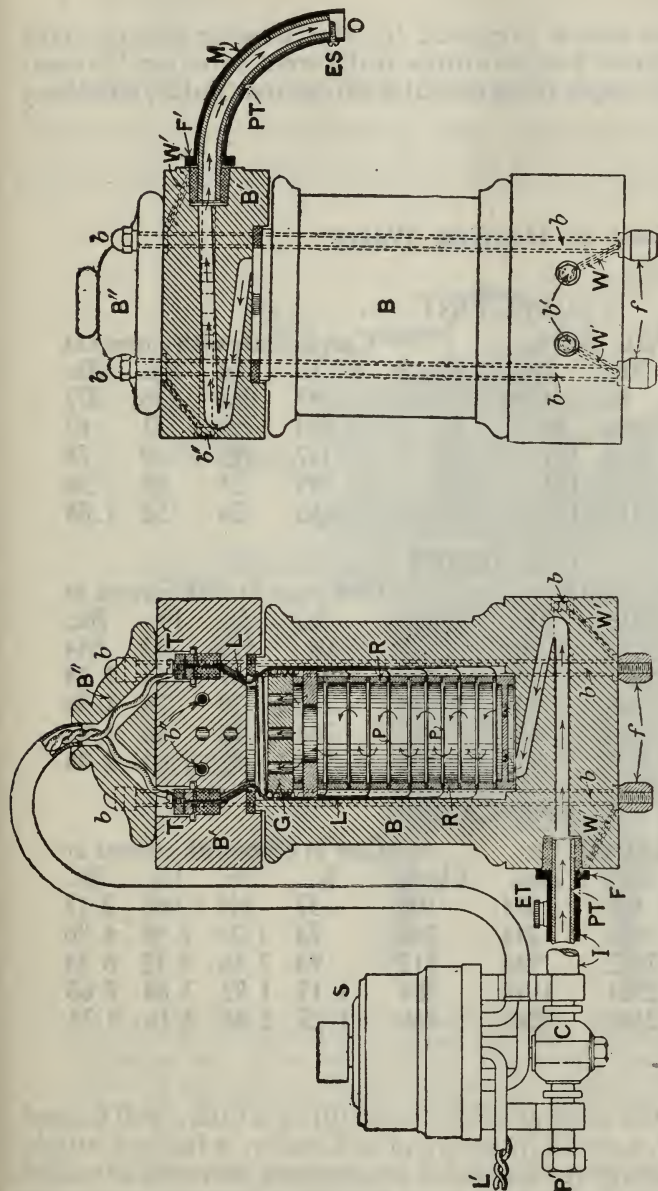
FIG. 4,411.—Simplex electric immersion heater. The most common way of boiling water is to apply heat to the outside of the vessel in which it is contained. But as heat radiates in all directions much of it is lost and only a part is usefully applied in heating the water. In other words when the heating agent surrounds the water only the heat that strikes in is used, that which strikes out is entirely lost. But if the water should surround the heating agent all the heat given off would be used. Advantage is taken of this fact in the Simplex heater by immersing the coil in a vessel of water.

2. With respect to the heating element, as

- a. External element;
- b. Immersed element.

The so called “instantaneous” is an example of the non-storing class and consists of a heating element and coil of pipe through which water passes, the rate of flow, and consequently the temperature being





Figs. 4,412 and 4,413.—Section of Fuller electric "geyser." **In construction** the body is made of porcelain, and is in three parts, B, B', and B'', the inside of B is hollowed out, and contains a number of platinum diaphragm P, separated from one another by porcelain rings R, and connected alternately with the terminals T, T' by platinum lugs L, L. Each diaphragm has a hole punched in it for the water to pass through. The stack of diaphragms and rings is tightly compressed by the porcelain grid G, which screws into the top of B. The double pole turn switch S, performs the double function of controlling the current and the water supply. The current flows through the leads L' to the terminals T, T', and so through the water between the + and - connected platinum electrodes. The water enters through a metal or rubber pipe at the point P', and after passing through the cock C (which is actuated by the switch spindle), and traversing the apparatus it emerges by the outlet O. The path of the water through the geyser is indicated by various small arrows, the metal inlet and outlet pipes being insulated by porcelain tubes PT, PT. At the outlet the water passes an earthing screw ES, so that any electrification it may possess is neutralized. ES is connected through the outlet tube M and wire W' to one of the four bolts b, b'. At their lower ends these bolts are similarly connected by wires W'', W''', to horizontal bolts b', b', which secure the flange F of the inlet tube I to the body of the geyser. This tube carries an earthing terminal ET, which is generally connected to the water main; though this connection is unnecessary if the supply to the geyser be brought through a continuous metal pipe. The flange F' of M, is bolted to B' by two bolts b'', b'', which are connected by wires to the vertical bolts b, b'. Thus every external metal part, including the feet f, is efficiently earthed, and all chance of a shock is avoided.

controlled by a valve. Nothing can be more ridiculous than to call these affairs "instantaneous" heaters, as no physical change takes place instantaneously.

According to the table below prepared by the Simplex Co. the cost for heating water to different temperatures at different rates per kilowatt hour is given, for initial temperature of water 60 degrees Fahr., efficiency of apparatus 85%.

### Cost of Heating Water

ONE PINT								
Total Temperature	Watts used for				Cost in cents with current at			
	5m.	10m.	20m.	1 hour	3c.	5c.	10c.	20c.
100°F.....	164	82	41.04	13.68	.041	.068	.136	.272
150°.....	372	186	93	31	.093	.155	.31	.62
175°.....	468	234	117	39	.117	.195	.39	.78
200°.....	576	288	144	48	.144	.24	.48	.96
212°.....	624	312	156	52	.156	.26	.52	1.04

ONE QUART								
Total Temperature	Watts used for				Cost in cents with current at			
	5m.	10m.	20m.	1 hour	3c.	5c.	10c.	20c.
100°F.....	324	162	81	27	.08	.136	.272	.544
150°.....	744	372	186	62	.186	.31	.62	1.24
175°.....	936	468	234	78	.234	.39	.78	1.56
200°.....	1152	576	288	96	.288	.48	.96	1.92
212°.....	1248	624	312	104	.312	.52	1.04	2.08

ONE GALLON								
Total Temperature	Watts used for				Cost in cents with current at			
	5m.	10m.	20m.	1 hour	3c.	5c.	10c.	20c.
100°F.....	1296	648	324	108	.32	.544	1.088	2.17
150°.....	2976	1488	744	248	.74	1.24	2.48	4.96
175°.....	3744	1872	936	312	.94	1.56	3.12	6.24
200°.....	4608	2304	1152	384	1.15	1.92	3.84	7.68
212°.....	4992	2496	1248	416	1.25	2.08	4.16	8.32

A system illustrating the storing class, stores up in a tank, well lagged with insulating material, a small quantity of hot water, a further supply being available very quickly by means of the heating element attached inside. Heaters of the immersion type have a heating element consisting of resistance wire placed in tubing of small diameter, bent into flat or long spirals of varying length, adapting them to shallow or deep vessels. The coils are immersed into the liquid to be heated.



**Electric Cooking Appliances.**—The multiplicity of cooking appliance now manufactured may be classed as

1. Portable;
2. Stationary.

Portable devices are designed for “cooking at the table.” There are any number of such appliance, such as electric coffee pots, toasters, grills, kettles, chafing dishes, frying pans, cake irons,



FIG. 4,414.—Simplex electric range consisting of oven, broiler, toaster, and two or more disc heaters with separate cooking utensils. Heating in top and bottom of oven are controlled by a three heat switch. **The broiler** has a corrugated top slanting slightly toward a grooved end which receives the juices of the meats. A separate smooth top fits on the broiler for making griddle cakes, toast, etc.

etc. With the exception of baking or roasting, a complete meal can be easily cooked at the table with these portable devices, some of which are illustrated in the accompanying cuts.

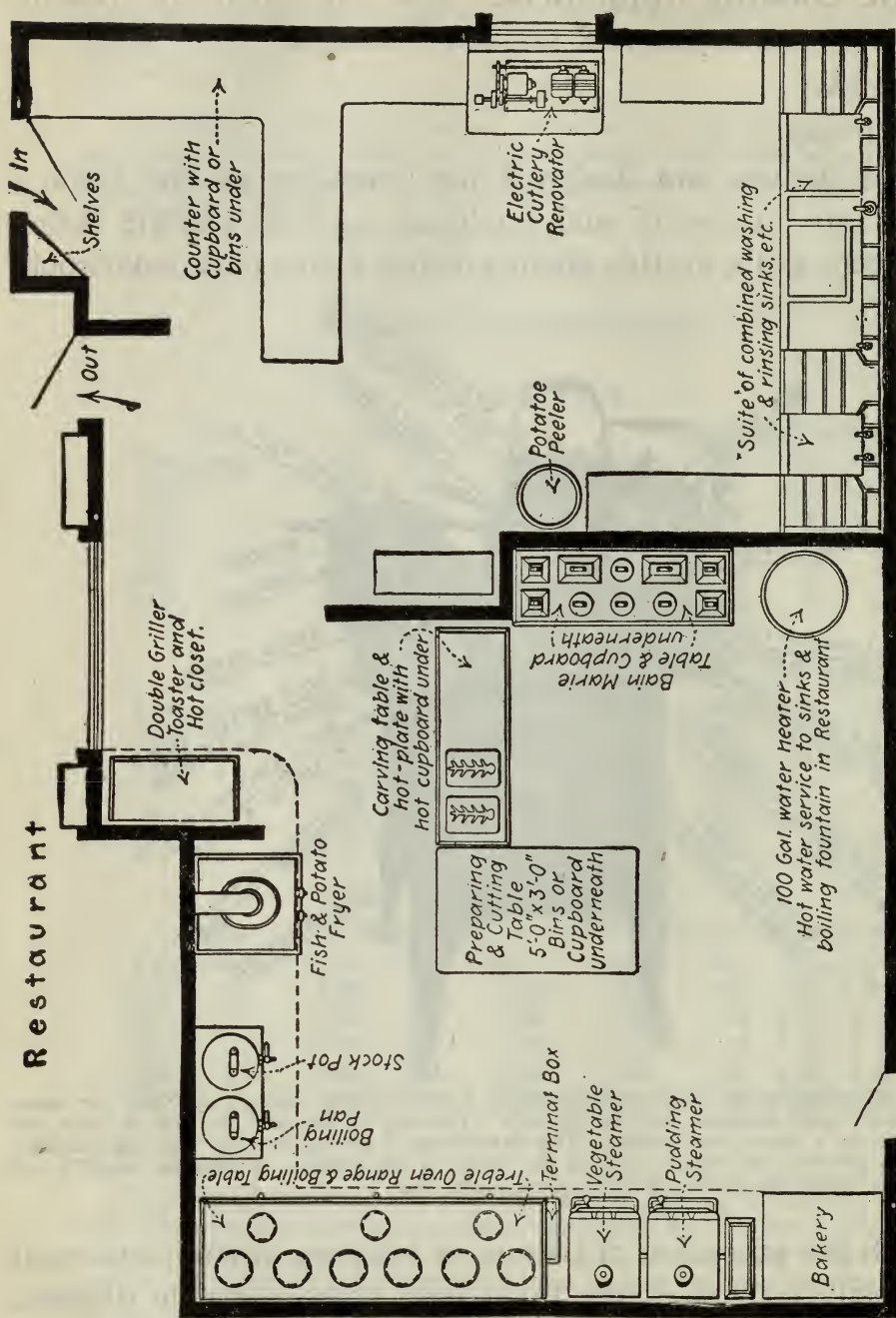
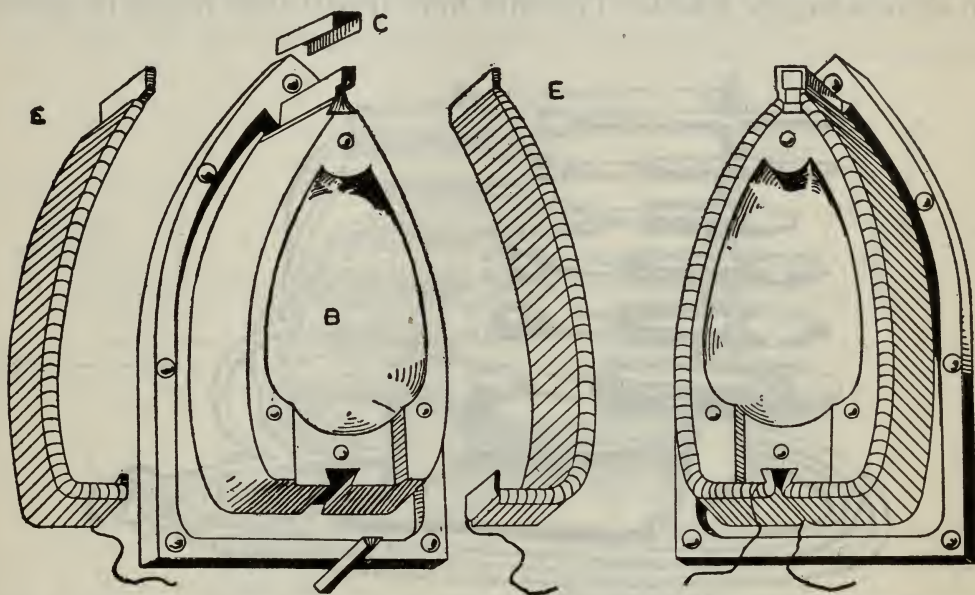


FIG. 4.415.—Plan of an all electric kitchen with bakery, grill, serving, preparing and wash room for a London restaurant. The equipment comprises: Bread and pastry bakers' oven, range of roasting ovens, with boiling table oven, vegetable cooker, pudding cooker, stock pot, boiling pans, fish and potato frier, double grill and toaster (a rack and canopy running the whole length over them with motor and small exhaust fan), carving and serving table, bain Marie, hot cupboards, water heater, scouring and cleaning sinks, polishing and cleaning motors and utensils. The vegetable preparing, cleaning and wash room being fitted with vegetable and fruit peelers, plate and dish washers, cutlery and plate polishing tables, washing and rinsing sinks, cupboards, etc., etc.



There are a number of stationary cooking devices, such as complete ranges, or "cookers," ovens, grills, etc., the details of which are illustrated in the accompanying cuts.

**Electric Flat Iron.**—The most difficult problem in the manufacture of a reliable device of this kind, is the proper construction of the heating elements to withstand the consequence due to the occasional neglect of being allowed to remain in



FIGS. 4,416 to 4,419.—Details of construction of electric iron. Figs. 4,416 and 4,418, heating elements; fig. 4,417, iron base; fig. 4,419, assembly.

circuit when not in use. Another difficulty is to distribute the heat generated, evenly over the entire working surface of the iron. The design should be such that the iron is quick acting without liability to over-heat. The irons, now turned out by many manufacturers, possess these qualifications in a high degree.

A typical design of electric iron is shown in figs. 4,416 to 4,419.

The heating elements E, E, consist of two resistance wires wound on cores of strip copper, carefully covered with a thoroughly fire-proof insulating material and bent to fit the shape of the iron. A V shaped slot is formed in the head of the central iron B, and the ends of the coils

are wedged lightly into the opening. A sheet of mica is inserted between the central core and the coils, and the coils are then pressed against it and fastened at the iron with a clip C. Another sheet of mica and a thin sheet of copper sheath held in place by a clip at the heel, constitutes the complete heating element of the iron. The coils are detachable and interchangeable. In case of a burn out, only one side need be replaced. By means of a detachable plug the iron can be used in any room wired for electricity, by attachment to any electric lamp socket.

**Electric Soldering Bits.**—The forms most commonly used are shown in fig. 4,420. The bits here illustrated range in power

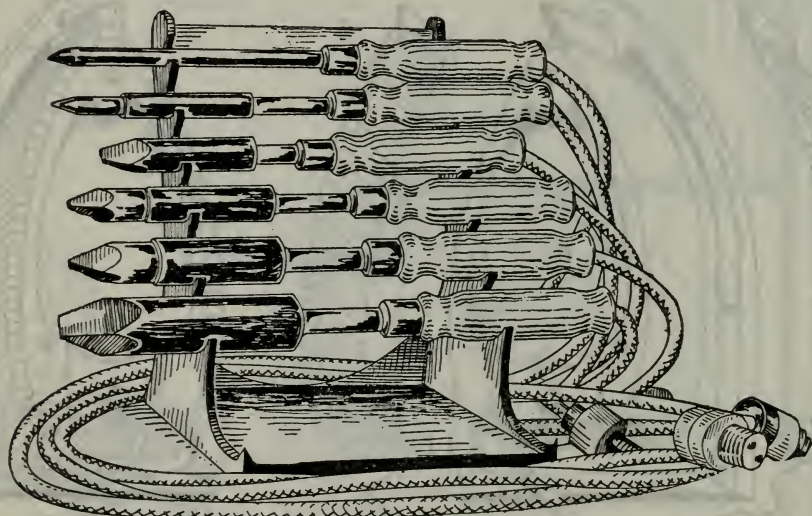


FIG. 4,420.—Nest of electric soldering bits, showing various forms and sizes.

consumption from 55 watts for the small, long, narrow pointed tool, suitable for intermittent telephone switchboard repair work, to 350 watts for the largest size, equal to a 6 pound soldering copper.

The heating element has a copper core with mica insulation, on which the fine wire heating coil is placed, and over which a steel shell is brazed in place. The soldering tip screws on to the copper core with a conical contact, which insures good heat conductivity. The *leading in* wires are taken out to binding posts, located in the interior of the handle, through lavite parts which keep the conductors separated. The handle can be unscrewed over the attachment cord to expose the binding posts.



**The Electrical Thawing of Frozen Water Pipes.**—A method usually employed in heating frozen pipes is shown in fig. 4,421. A, B, C, represent a line of  $2\frac{1}{2}$  inch pipe about 600 to 700 feet long, leading from a stand pipe to the house supply. The section A, B is underground and frozen solid; the section C, B is above ground and frozen to the height of 50 feet. The current is desired from 25 kilowatt lighting transformer; the two ends of the frozen pipe being connected to the secondary

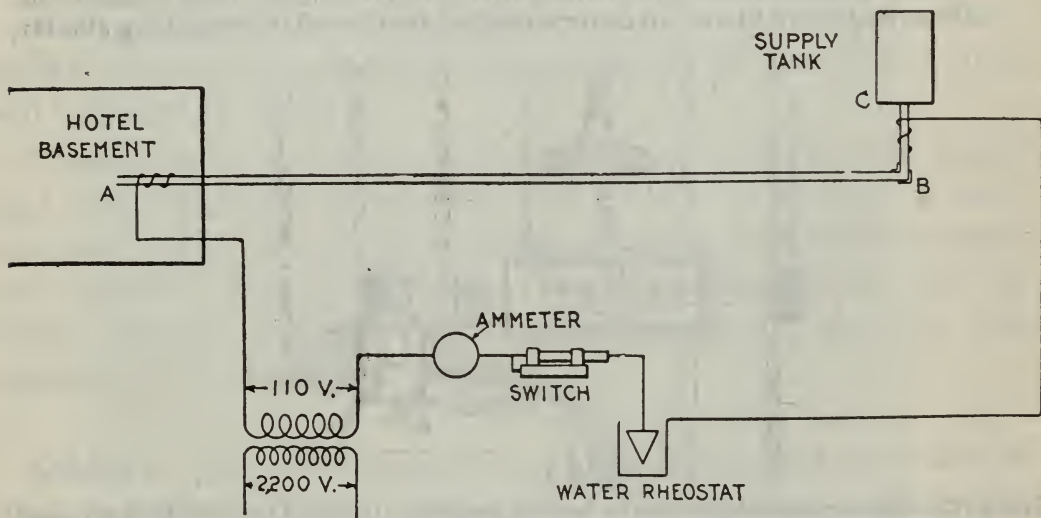


FIG. 4,421.—Diagram illustrating the electrical thawing of frozen water pipe. The description in the accompanying text serves to give an idea of the amount of electrical energy required for a particular installation.

110 volt terminals of the transformer in series with the ammeter, switch and water rheostat as shown, by means of No. 00 cable. The passing of a current of 275 amperes through the pipe for a period of  $2\frac{1}{2}$  hours would result in thawing the pipe.

**Wiring for Electric Heating and Cooking.**—The use of electricity for such service in addition to lighting, necessitates the installation of suitable extra outlets. The proper location of such outlets are matters which should be attended to by the

architect and the owners. However, an extra 25 ampere receptacle and a few feet of wiring, installed as shown in fig. 4,422, solves the problem in many cases.

The Underwriters' rules give the exact requirements necessary to pass inspection.

Most electric heating appliances are connected to the circuit through a length of flexible cord and a plug connection; so that they can be readily disconnected for cleaning purposes, or for moving from one place to another. Generally such appliances, especially radiators and convectors, are sent out by the makers with a length of twin flexible conductor attached ready for joining up to the consumers' plug connections. The plug should have an outer casing of hardwood or something similar,

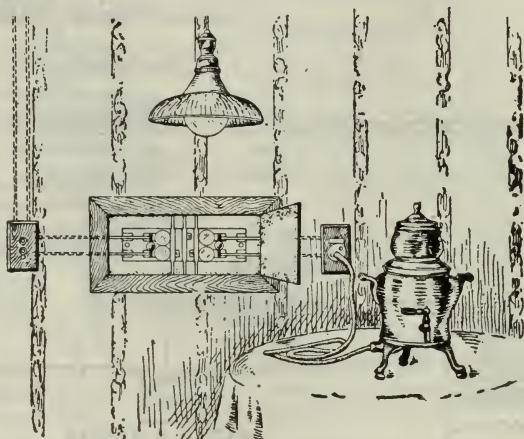


FIG. 4,422.—Extra receptacle for electric heating purposes. It should be carefully determined whether the wiring be of large enough size to carry the maximum current without overheating. See Underwriters' rules.

so that it will not break if dropped; and it should be so constructed that no strain can be thrown on the connections between the flexible conductors and the terminals.

One difficulty with electric heating appliances is the deterioration of the insulation of the flexible cord near the point of attachment to the heater. Owing to the heat developed in the adjacent apparatus, the insulation becomes hard and loses its flexibility; and there is some risk of the flexible conductors short circuiting, or breaking and setting up a momentary arc.

This difficulty arises more particularly with such devices as flat irons, kettles, and cooking appliances. Only the best flexible cord should be used, and when the portion next to the heater has become stiff, it should be cut off and a fresh connection made.



## CHAPTER LXXXIII

## SOLDERING AND BRAZING

A knowledge of soldering and brazing is useful to the electrician, and the acquirement of proficiency in these operations will be found of value.

Those who have made a first attempt at soldering will agree that it is a distinct art in itself, and while it looks easy, is not; moreover, skill cannot be acquired without considerable practice; however, the information to be obtained in books will be found helpful, not only to the beginner, but also to the experienced workman.

**Solder.**—The word *solder* is a generic name for fusible alloys used to unite different metal parts. In electrical engineering, the solder used is practically always an alloy of tin and lead. As the electrical conductivity of such an alloy is usually about one seventh that of copper, the best joint between copper conductors is made by bringing the copper surfaces as close together as possible and using a minimum of solder.

For jointing, especially where work has to be done in awkward positions, it is essential that the solder should have a plastic stage between its liquid and solid states.

The curve in fig. 4,423 gives the melting points of *tin lead* solders as a function of the percentage of tin, according to tables published by the Smithsonian Institute.

**Ques.** Name two classes of solder.

**Ans.** Soft and hard.

**Ques.** What is soft solder?

**Ans.** An alloy composed of lead and tin. Sometimes other metals are added to lower the melting point.

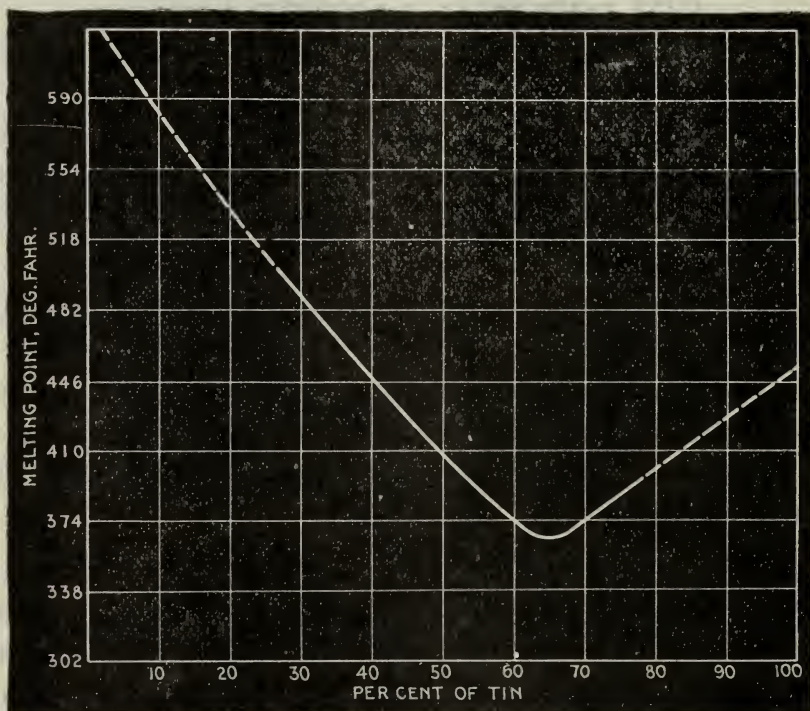


FIG. 4,423.—Characteristic curve showing the melting points of tin-lead solders, according to the Smithsonian Institution tables. Authorities differ as to the exact values. Those given in Kemp's handbook result in a curve lying considerably below the curve in the figure, while Hutte's pocketbook gives values resulting in a curve slightly higher. All, however, agree in showing a marked minimum of the melting point with about 60 to 65 per cent. of tin. These differences are doubtless due to the degree of purity of the ingredients used. A good electrical solder complying with the conditions mentioned above contains 40 to 45 per cent. of tin, and melts at about 428° to 446° Fahr. with pure ingredients, or lower with commercial samples.

**Ques.** What is hard solder?

**Ans.** An alloy composed of copper and zinc, or copper, zinc, and silver.

Hard solder in general is sometimes erroneously called *spelter*.



**Ques.** What necessary relation must exist between solder and the metals with which it is to unite?

**Ans.** The solder must have a lower melting point than the metals to be joined to it.

The melting point should approach as nearly as possible that of the metals to be joined so that a more tenacious joint is effected.

**Ques.** How can the fusibility of a solder be increased?

**Ans.** By the addition of a small portion of bismuth.

**Ques.** How do the melting points of soft and hard solder compare?

**Ans.** Soft solder melts at a low temperature compared to hard solder which melts at a red heat.

**Soft Solders.**—These consist chiefly of tin and lead, although other metals are occasionally added to lower the melting point. Those containing the most lead are the cheapest and have the highest melting point. According to the tin content they may be classed as

1. Common or plumber's;
2. Medium or fine.

Common or plumber's solder consists of one part of tin to two parts of lead, and melts at 441° Fahr. It is used by plumbers for ordinary work, and occasionally for electrical work where wiped joints are required, for instance, in large lead covered work. Medium or fine solder consists of equal parts of tin and lead, or *half and half*, and melts at 370° Fahr. This solder is always used for soldering joints in copper conductors, and for soldering lead sleeves on lead covered wires.

The following table gives the melting point and relative hardness of various *tin lead* solders.

## Melting Points and Hardness of Tin Lead Solders

Percentage		Melting Temp. Deg. F.	Brinell Hardness Test	Percentage		Melting Temp. Deg. F.	Brinell Hardness Test
Tin	Lead			Tin	Lead		
0	100	618.8	3.9	60	40	368.6	14.6
10	90	577.4	10.1	66	34	356.0	16.7
20	80	532.4	12.16	70	30	365.0	15.8
30	70	491.0	14.5	80	20	388.4	15.2
40	60	446.0	15.8	90	10	419.0	13.3
50	50	401.0	15.0	100	0	466.0	4.1

In the table which follows will be found the proper solder and flux to use with various metals.

## Soft Solders and Fluxes for Various Metals

Metal to be Soldered	Flux	SOFT SOLDER					
		Tin	Lead	Zinc	Alu- mi- num	Phos- phor tin	Bis- muth
Aluminum . . . . .	Stearin . . . . .	70		25	3	2	
Brass . . . . .	Chloride of zinc, rosin, or Chloride of ammonia. . . . .	66	34				
Gun metal . . . . .		63	37				
Copper . . . . .		60	40				
Lead . . . . .	Tallow or rosin . . . . .	33	67				
Block tin . . . . .	Chloride of zinc . . . . .	99	1				
Tinned steel . . . . .	Chloride of zinc or rosin . . . . .	64	36				
Galvanized steel . . . . .	Hydrochloric acid . . . . .	58	42				
Zinc . . . . .	Hydrochloric acid . . . . .	55	45				
Pewter . . . . .	Gallipoli oil . . . . .	25	25				50
Iron and steel . . . . .	Chloride of ammonia. . . . .	50	50				
Gold . . . . .	Chloride of zinc . . . . .	67	33				
Silver . . . . .	Chloride of zinc . . . . .	67	33				
Bismuth . . . . .	Chloride of zinc . . . . .	33	33				34



**Hard Solders.**—The various solders known as “hard” solders are used for joining such metals as copper, silver and gold, and such alloys as brass, German silver, gun metal, etc., which require a strong joint, and often a solder the color of which is near that of the metal to be joined.

**Ques. What is the difference between hard soldering and brazing?**

**Ans.** According to common usage hard soldering (which is the term used by jewelers) ordinarily means that silver solder is used, whereas, brazing is generally understood to mean the joining of metals by a filler of brass.

A distinguishing characteristic of hard soldering is that a soldering bit cannot be used as in soft soldering because of the excessive temperature (red heat) which necessitates a blow pipe, gas forge, or coke or charcoal fire. The chief advantage of a brazed joint is its superior strength.

The following table gives the various hard solders, proper flux, and metals for which they are suited.

**Hard Solders and Fluxes for Various Metals**

Metal to be soldered	Flux	HARD SOLDER			
		Copper	Zinc	Silver	Gold
Brass, soft . . . . .	Borax . . . . .	22	78		
Brass, hard . . . . .	Borax . . . . .	45	55		
Copper . . . . .	Borax . . . . .	50	50		
Gold . . . . .	Borax . . . . .	22		11	67
Silver . . . . .	Borax . . . . .	20	10	70	
Cast iron . . . . .	Cuprous oxide . . . . .	55	45		
Iron and steel . . . . .	Borax . . . . .	64	36		

As will be noted from the table, most of the hard solders are alloys of copper and zinc. An easily fusible hard solder may be made of one part copper to two parts zinc, this, however, makes a joint that will be weaker than when an alloy more difficult to melt is used.

A hard solder that is readily melted is made of 44% copper, 50% zinc, 4% tin, and 2% lead.

A hard solder for the richer alloy of copper and zinc may be produced from 53 parts copper and 47 parts zinc.

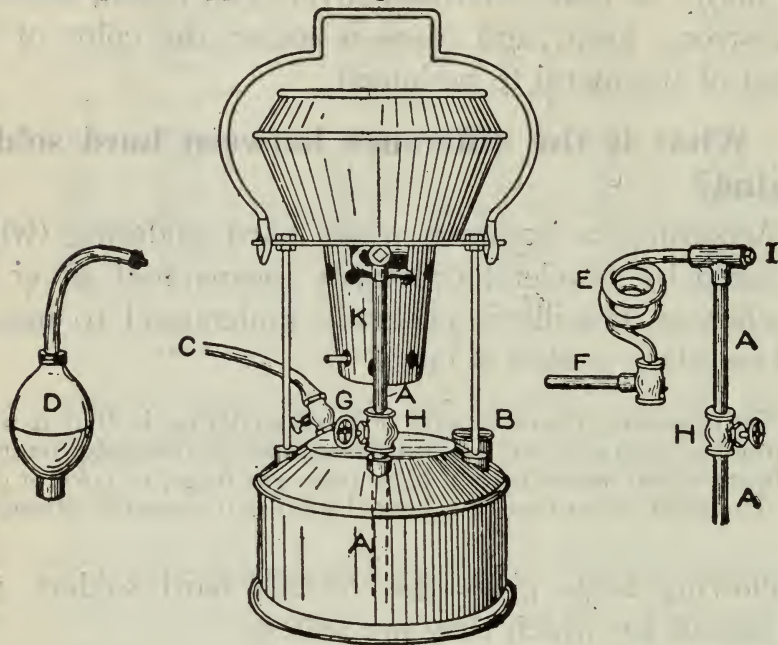


FIG. 4,424.—Plumber's gasoline furnace, adapted to heating soldering pots and copper bolts.

**In construction,** the gasoline supply for the blast passes through AA, and is provided with valve H and clean out plug I. The lower end of the supply extends nearly to the bottom of the reservoir. The gasoline passes through coil E, which is partially filled with wire, usually a scrap of small wire cable, to prevent flame running back into the reservoir. The fuel issues from a single small hole at F, which is turned so that the flame will impinge on the coil. Air pressure on top of the gasoline in the reservoir is necessary to make a blast. The air cock is shown at G. For ordinary purposes sufficient pressure can be obtained by blowing air in the hose at C with the lungs, but for a short blast, a bulb containing check valves, shown at D, is used to increase the pressure. The filling plug is at B. **To light the furnace,** valve H is opened and some of the gasoline allowed to play on the coil, from which it falls back into the bottom of cup K. Admit about two tablespoonfuls to cup, close H, and light the gasoline through one of the holes in K. When coil is sufficiently heated, gas instead of liquid will come from the end F, forming a blast which increases in intensity as E becomes hotter. The strength of the blast is regulated by valve H. One pumping keeps the furnace in working order until the lowering of the gasoline level has provided so much room that the pressure of the expanded air is not sufficient to maintain the blast; it then becomes necessary to pump in more air, or to replenish the gasoline and again establish the pressure.

**Ques.** What is the nature of alloys containing much lead?

**Ans.** Since lead does not transfuse with brass, the strength of the joint is decreased.



**Ques.** What is the effect of tin?

**Ans.** It increases the brittleness of the solder.

**Miscellaneous Solders.**—In addition to the solders already given, there are a number that are of value for various purposes.

**Very Hard Yellow Solders.**—The following formulæ make excellent hard solders for all purposes where a high melting point is required:

No. 1. Copper, 58 parts; zinc, 42 parts.

No. 2. Sheet brass, 85.42 parts; zinc, 13.58 parts.

No. 3. Brass, 7 parts; zinc, 1 part.

No. 4. Copper, 53.3 parts; zinc, 43.1 parts; tin, 1.3 parts; lead, .3 part.

The hardest solders are given first. The following four have lower melting points than those above, and are more suitable where it is desired to solder brass alone.

No. 5. Brass, 66.66 parts; zinc, 33.34 parts.

No. 6. Brass, 50 parts; zinc, 50 parts.

No. 7. Brass, 12 parts; zinc, 4 to 7 parts; tin, 1 part.

No. 8. Copper, 44 parts; zinc, 49 parts; tin, 3.2 parts; lead, 1.2 parts.

**Silver Solders.**—These are not, as might be inferred from the name, employed only for the purpose of joining silver, but because of their great strength and resistance are used for many other metals. Like all other solders, they may be divided into the two groups: hard, and soft. Silver solders are usually employed in the shape of wire, narrow strips, or filings. The following are especially adapted to soldering silverware:

#### **Hard Solders**

No. 1. Copper, 1 part; silver, 4 parts.

No. 2. Copper, 1 part; silver, 20 parts; brass, 9 parts.

No. 3. Copper, 2 parts; silver, 28 parts; brass, 10 parts.

#### **Soft Solders**

No. 4. Silver, 2 parts; brass, 1 part.

No. 5. Silver, 3 parts; copper, 2 parts; zinc, 1 part.

No. 6. Silver, 10 parts; brass, 10 parts; tin, 1 part.

The following silver solders are suitable for cast iron, steel and copper:

No. 1. Silver, 10 parts; copper, 10 parts.

No. 2. Silver, 20 parts; copper, 30 parts; zinc, 10 parts.

In addition to the various silver solders already given, two other formulæ should be included.

No. 1. Yellow brass, 70 parts; zinc, 7 parts; tin,  $11\frac{1}{2}$  parts.

No. 2. Silver, 145 parts; brass (3 copper, 1 zinc), 73 parts; zinc, 4 parts.

### Miscellaneous Silver Solders

**Solder for silver plated work:** No. 1. Fine silver, 2 parts; bronze, 1 part. No. 2. Silver, 68 parts; copper, 24 parts; zinc, 17 parts.

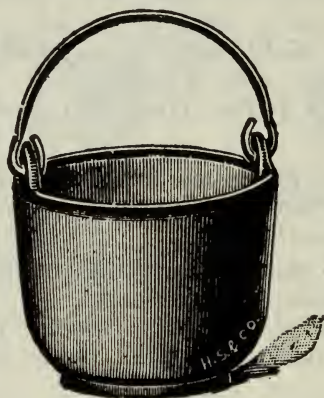


FIG. 4,425.—Soldering pot.

**Solder for silver chains:** No. 1. Fine silver, 74 parts; copper, 24 parts; orpiment, 2 parts. No. 2. Fine silver, 40 parts; orpiment, 20 parts; copper, 40 parts.



FIG. 4,426.—Ladle for removing solder from soldering pot and for pouring same in making wipe joints, etc.

**Resoldering silver solders:** These silver solders are for resoldering parts already soldered. No. 1. Silver, 3 parts; copper, 2 parts; zinc, 1 part. No. 2. Silver, 1 part; brass, 1 part; or, silver, 7 parts; copper, 3 parts; zinc, 2 parts.

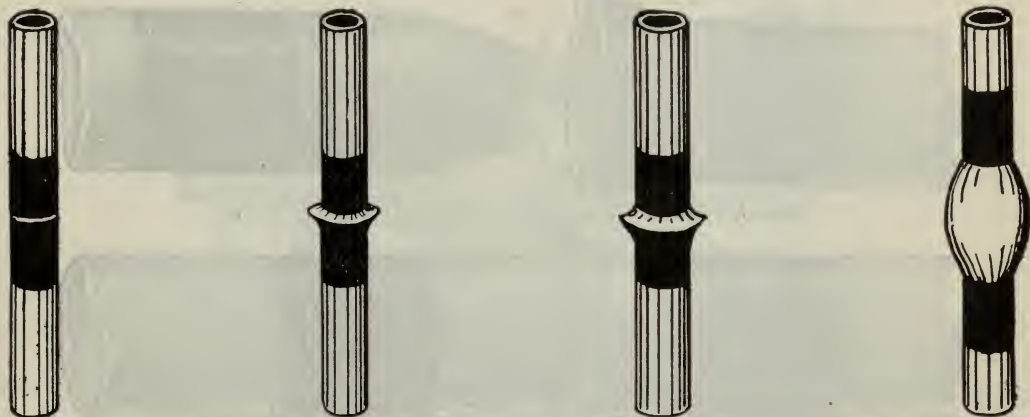
**Readily fusible silver solder for ordinary work:** Silver, 5 parts; copper, 6 parts; zinc, 2 parts.

French solders for silver: No. 1, for fine silver work: Fine silver, 87 parts; brass, 13 parts. No. 2, for work 792 fine: Fine silver, 83 parts;



brass, 17 parts. No. 3, for work 712 fine: Fine silver, 75 parts; brass, 25 parts. No. 4, for work 633 fine: Fine silver, 66 parts; brass, 34 parts. No. 5, for work 572 fine: Fine silver, 55 parts; brass, 45 parts.

**German Silver solders.**—German silver is a very hard alloy of copper (50 to 60%), nickel (15 to 25%), and zinc (15 to 20%). A German silver containing 1 to 2% of tungsten is called *platinoid*. These alloys have a high electrical resistance, platinoid being higher than the other varieties of German silver; the resistance increases uniformly between 32° and 212° Fahr.



FIGS. 4,427 to 4,430.—Various joints. Fig. 4,427, **butt joint** made by squaring the ends, tinning one, and sweating the other to it by heating with torch; this is a comparatively weak joint. Fig. 4,428, **blow joint**; fig. 4,429, **copper bit joint**, the only difference between these is that the solder is floated by a torch in fig. 4,428, and by a bit in fig. 4,429, the latter joint being heavier than the former. Fig. 4,430, round wiped joint.

German silver solders possess considerable strength, and are often used for soldering steel. The color is very similar to that of steel.

*In preparing German silver solders, the copper is melted first, and then the zinc and nickel added simultaneously.*

### Soft German Silver Solders

No. 3. Copper, 4.5 parts; zinc, 7 parts; nickel, 1 part.

No. 4. Copper, 35 parts; zinc, 56.5 parts; nickel, 8.5 parts.

The following No. 5 formulæ given by Kent is similar to No. 4.

No. 5. Copper, 38 parts; zinc, 54 parts; nickel, 8 parts.

### Hard German Silver Solders

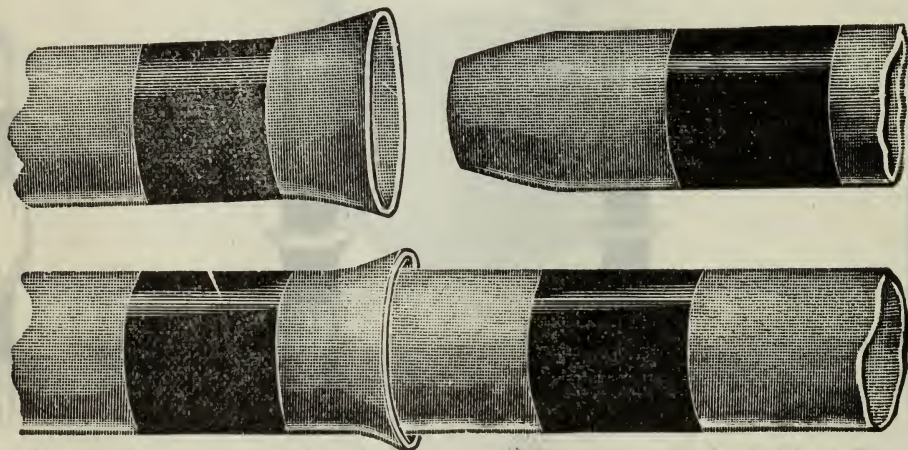
These solders, sometimes called steel solders, contain a large proportion of nickel and are very strong. They require a very high heat for melting, and usually cannot be fused without the aid of a bellows or blast.

No. 1. Copper, 35 parts; zinc, 56.5 parts; nickel, 9.5 parts.

No. 2. Copper, 38 parts; zinc, 50 parts; nickel, 12 parts.

**Ques.** How is the solder usually applied in soldering German silver articles?

**Ans.** In the form of a powder or in very small pieces or lumps.



FIGS. 4,431 to 4,433.—Round wiped joint; preparing the pipe ends. These ends to be united are sawed squarely across, to make the joints true with the pipe. It is usual to prepare the female end first, as shown in fig. 4,431. The end is flared or belled out with a *turnpin*, which is a taper boxwood plug, so that the pipe is enlarged a quarter of an inch. The cup thus formed serves to retain the solder. The internal and external surface must be shaved or scraped bright and clean with a *shave hook*, a small tool with a heart shaped blade set at right angles to its stem or handle. Immediately after a little tallow is applied to the parts to preserve them from the oxidizing action of the atmosphere, which would otherwise tarnish the surfaces, and form a film to which the solder cannot adhere. The male end of the pipe is tapered off with a rasp, as shown in fig. 4,432, cleaned with a shave hook and "touched" as before; the two pieces are brought together as in fig. 4,433, and are then ready for the joint.

The solder may be powdered in a mortar if taken from the fire at the right temperature, when it is brittle. This operation is a somewhat difficult one, and so the usual, and perhaps the best plan, is to cast it in the form of a bar or cylinder and then place the latter in a turning lathe, and adjust the tool so that fine shavings are cut off. The shavings are then heated until they become brittle, at which stage they are easily pulverized in a mortar.



**Gold Solders.**—The hard solder or gold solder which the jeweler frequently requires for the execution of various works, not only serves for soldering gold ware, but is also often employed for soldering fine steel goods, such as spectacles, etc. Fine gold is only used for soldering articles of platinum. The stronger the alloy of the gold, the more fusible must be the solder. Generally the gold solder is a composition of gold, silver, and copper. If it is to be very easily melted, a little zinc may be added. The shade of the solder is regulated by varying the proportions of silver and copper.

No. 1. For 18 carat gold: Gold (18K), 9 parts; silver, 2 parts; copper, 1 part.

No. 2. For 16 carat gold: Gold (16K), 24 parts; silver, 10 parts; copper, 1 part.

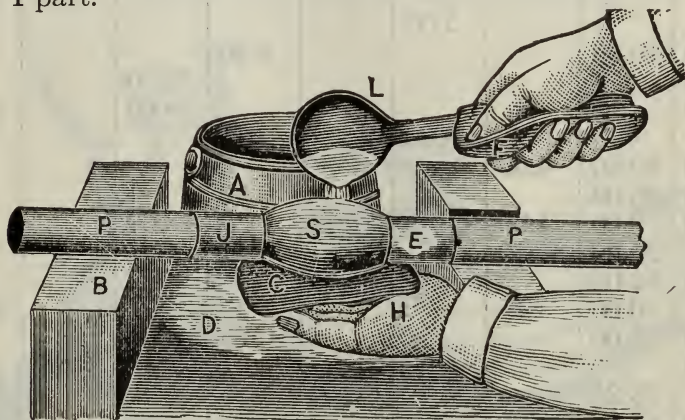


FIG. 4,434.—Method of wiping a horizontal joint. The cloth used for wiping is a pad of moleskin or fustian about four inches square made from a piece twelve inches by nine, folded six times, and sewed to keep it from opening; the side next the pipe is saturated with hot tallow when used. If the lead has been brought to the heat of the solder, and the latter properly manipulated and shaped while in a semi-fluid or plastic condition, the joint gradually assumes the finished egg shaped appearance. In making the joint a quantity of solder is taken from the pot by means of the ladle, the solder being previously heated so hot that the hand can be kept within two inches of its surface. The solder is poured lightly on the joint, the ladle being moved backwards and forwards, so that too much solder is not put in one place. The solder is also poured an inch or two on the soiling, to make the pipe of proper temperature. Naturally the further the heat is run or taken along the pipe, the better the chance of making the joint. The operator keeps pouring and with the left hand holds the cloth to catch the solder, and also to cause the same to tin the lower side of the pipe, and to keep the solder from dropping down. By the process of steady pouring the solder now becomes nice and soft and begins to feel shaped, firm and bulky. When in this shape and in a semi-fluid condition the ladle is put down, and, with the left hand, the operation of wiping, as illustrated, is begun working from the soiling towards the top of the bulb. If the lead cool rapidly, it is reheated to a plastic condition by a torch, or a heated iron. When the joint is completed, it is cooled with a water spray, so that the lead shall not have time to alter its shape.

No. 3. For 14 carat gold: Gold (14K), 25 parts; silver, 25 parts; brass, 12½ parts; zinc, 1 part.

**Aluminum Solders.**—In soldering aluminum it is necessary previously to tin the parts to be soldered. This tinning is done with the iron, using a composition of aluminum and tin. A pure aluminum

soldering bit should be used. To prepare an aluminum solder, first melt the copper, then add the aluminum gradually, stir well with an iron rod, next add the zinc and a little tallow or benzine at the same time. After adding the zinc do not heat too strongly. To avoid volatilization of the zinc, according to *Machinery*, the following aluminum solders have been successfully used:

### Aluminum Solders

Tin	Aluminum	Zinc	Copper	Bismuth	Lead	Phosphor Tin*	Silver	Antimony	Cadmium	Magnesium
95.00				5.00						
78.50	2.00	19.00				0.50				
	66.70						33.30			
20.00	70.00						10.00			
97.00				3.00						
	6.00	89.50	4.50							
71.25	2.25	26.00				0.50				
60.00	4.00	8.00	4.00		12.00		12.00			
37.50		25.00	37.50							
	8.00	92.00								
30.00		20.00							50.00	
80.00	2.25	17.00				0.75				
66.00	15.50			9.00				7.00	†	2.25
15.50	2.50	78.25			2.50	1.25				
	20.00	65.00	15.00							
49.05		20.31	1.15		26.06			3.43		
30.00	70.00									
	4.00	94.00	2.00							
85.10	10.80								1.35	2.75
60.00		15.00		5.00	10.00			5.00		‡
86.00				14.00						
98.00	1.00			1.00						
20.00	70.00		10.00							
48.00	2.00	27.00			23.00					
90.00	5.00			5.00						
84.95				15.05						

\*10% phosphorus.

†This solder also contains 0.25% vanadium.

‡This solder also contains 5% chromium.

Novel's solders for aluminum as given by Kent are as follows:

Tin 100 parts, lead 5 parts; melts at 536° to 572° Fahr.

Tin 100 parts, zinc 5 parts; melts at 536° to 612° Fahr.

Tin 1,000 parts, copper 10 to 15 parts; melts at 662° to 842° Fahr.

Tin 1,000 parts, nickel 10 to 15 parts; melts at 662° to 842° Fahr.



Novel's solder for aluminum bronze: Tin 900 parts; copper 100 parts; bismuth 2 to 3 parts. It is claimed that this solder is also suitable for joining aluminum to copper, brass, zinc, iron and nickel.

**Soldering Fluxes.**—The word *flux*, means a substance applied to a metal to make solder flow readily on its surface. The action of a flux is largely that of cleaning the surface, and of reducing any oxide on the surface to the metallic state.

If a piece of sheet copper be carefully cleaned by means of emery cloth and heated over a gas flame, the surface will be



FIG. 4,435.—Method of wiping a vertical joint. A small piece of cardboard cut open is placed under the joint to catch excess solder, or as shown, a lead flange cut open is placed around the pipe and held in place by twine.

seen to tarnish rapidly and assume a dark brown appearance. A small piece of resin dropped on the surface will melt, and when the liquid runs, the initial brightness of the surface will be found to reappear.

There are a number of flux suitable for various kind of soldering, but pine amber resin is the best for electrical work as it does not cause corrosion. A corrosive flux, such as zinc chloride

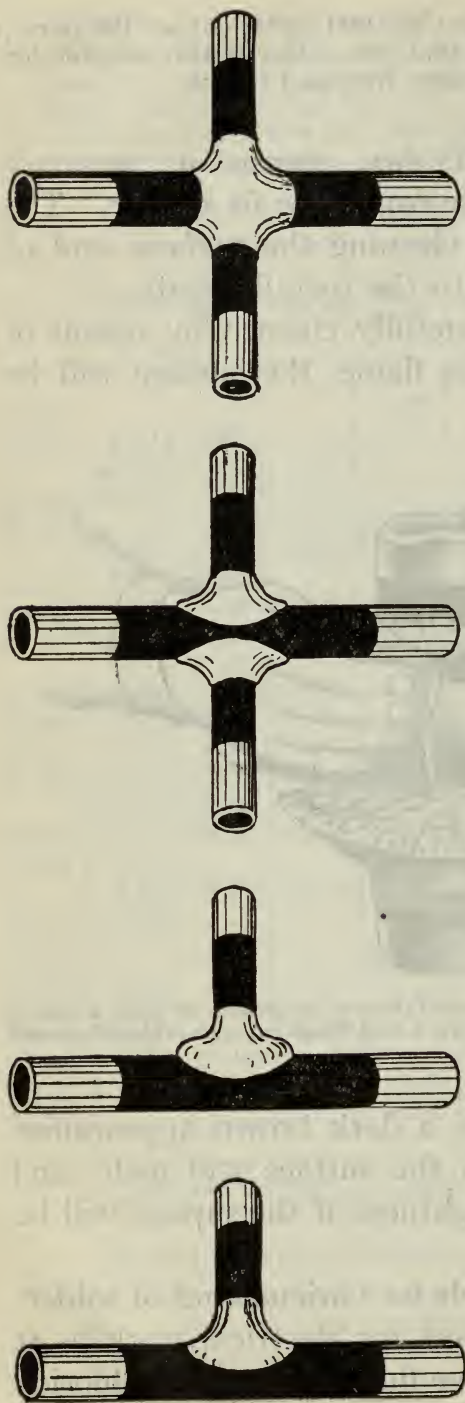


FIG. 4,436 to 4,439.—Various wiped joints. Fig. 4,436, *branch joint with concave neck*; fig. 4,437, *branch joint with swell neck*, this style is much more difficult to wipe than the one shown in fig. 4,436; fig. 4,438, *double branch cross*, this style looks well and is very easy to wipe because one branch may be wiped at a time by protecting the first with chalk or paste; fig. 4,439, *regular cross joint*, more difficult than the double branch because there are four edges to take care of at one heat.

solution (killed spirits) should be strictly excluded from any electrical work.

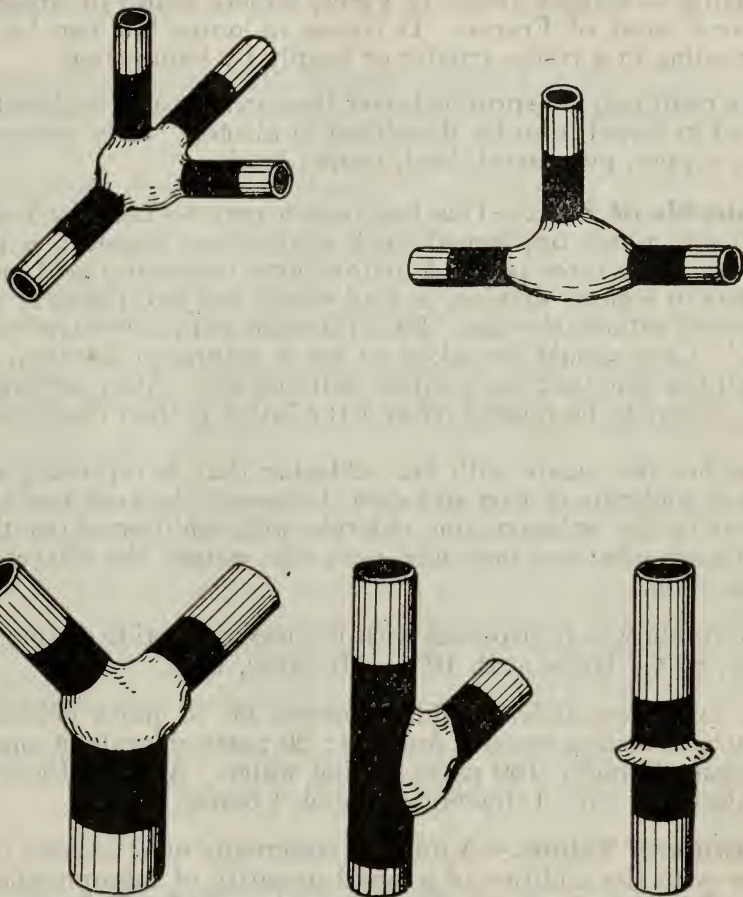
The Underwriters' code permits the use of a flux composed of chloride of zinc, alcohol, glycerine, and water. This preparation is easily applied and remains in place. It permits the solder to flow freely and is not highly corrosive. This flux is made as follows: Zinc chloride, 5 parts; alcohol, 4 parts; glycerine, 3 parts. Anhydrous zinc chloride crystals should be used dissolved in alcohol. The glycerine makes the flux adhesive. To prevent the alcoholigniting, the mixture may be diluted with water.

There are a number of prepared flux on the market, but are not to be recommended because of the ridiculously high prices demanded.

For electrical work, especially when very small wires are used, rosin should



be insisted upon to avoid any corrosion. No one flux can be assigned to any one metal as being peculiarly adapted or fitted to that metal for all purposes. The nature of the solder often determines the flux. The following fluxes are extensively used.



FIGS. 4,440 to 4,444.—Various wiped joints. Fig. 4,440, *angle cross*, a joint more difficult to make than the regular cross; fig. 4,441, *combination branch and round joint*, sometimes made where it is most convenient to have a branch joint come at a point where two ends of the supply line must be joined; fig. 4,442, *V joint*, generally used on telephone branch cables; fig. 4,443, *so called Y joint*, usually made on lead waste pipe; fig. 4,444, *common flange joint*.

**Resin.**—This substance, one variety being called rosin, is difficult to define. It is undoubtedly an exudation from the trunk and limbs of trees, but these exudations vary so much in all their properties that

the terminology of them is wide, complicated and in some cases, contradictory.

Rosin solidifies after exudation from the tree and is insoluble in water, but soluble in alcohol.

Colophony, or rosin, is the kind of resin used as a flux, and consists of other coagulated exudation obtained from cuts in the bark of trees belonging to several species of *Pinus*, largely grown in America, and on the west coast of France. It comes in lumps but can be granulated by grinding in a coffee grinder or simply by hammering.

The resin may be sprinkled over the surface to be soldered or may be applied in liquid form by dissolving in alcohol. It is used as a flux for brass, copper, gun metal, lead, tinned steel.

**Chloride of Zinc.**—This flux, which may be used for brass, copper, gun metal, block tin, tinned steel, gold, silver, bismuth, is prepared as follows: Place three parts of hydrochloric (muriatic) acid and one part of water in a glass, wooden, or lead vessel, and add pieces of zinc as long as the acid attacks the zinc. Put in the zinc gradually to prevent “boiling over.” Care should be taken to get a saturated solution, that is, to add all the zinc that the solution will dissolve. After settling, the clear solution should be poured off and the latter is then ready for use.

Another flux made with zinc chloride that is especially adapted to the soft soldering of iron and steel (because it does not make rust spots) consists of the ordinary zinc chloride with addition of one-third spirits of sal-ammoniac and one-third part rain water; the mixture is filtered before using.

A formula which dispenses with the use of chloride of zinc consists of: Water, 80%; lactic acid, 10%; glycerine, 10%.

An acid free soldering fluid consists of: 5 parts chloride of zinc, 25 parts of boiling water. Another: 20 parts chloride of zinc; 10 parts ammoniac chloride; 100 parts boiling water. Another formula consists of chloride of zinc, 1 drachm; alcohol, 1 ounce.

**Rosin and Tallow.**—A mixture commonly used consists of rosin and tallow with the addition of a small quantity of sal-ammoniac. This is adapted to tinned ware, because of the ease with which it may be wiped off the surface after soldering.

Another mixture consists of:  $1\frac{1}{2}$  lbs. olive oil;  $1\frac{1}{2}$  lbs. tallow; 12 oz. pulverized rosin. Let the mixture boil up and when cool add  $1\frac{3}{8}$  pints of water saturated with pulverized sal-ammoniac, stirring constantly.

**Soldering Grease.**—In a pot of sufficient size and over a slow fire melt together 500 parts of olive oil and 400 parts of tallow, then stir



in slowly 250 parts of rosin in powder, and let the whole boil up once. After cooling, add 125 parts of saturated solution of sal-ammoniac while stirring; use when cold.

**Ammonia Soap.**—Mix finely powdered rosin with strong ammonia solution. This is suitable for soldering together copper wires for electrical conduits.

**Soldering Fat for Iron.**—Olive oil, 50 parts; sal-ammoniac, 50 parts.

**Soldering Fat for Aluminum.**—Melt together equal parts of rosin and tallow, half the quantity of chloride of zinc being added to the mixture.

**Soldering Salt.**—Mix equal parts of neutral chloride of zinc, free from acid, and powdered sal-ammoniac. When required for use, 1 part of the salt should be dissolved in 3 or 4 parts of water.

**Soldering Paste.**—Consists of neutral soldering liquid thickened with starch paste. In using apply more lightly than the soldering liquid.

**Borax.**—This flux is most frequently used for hard soldering. It should be applied to the soldering seam either dry or stirred to a paste with water. It is advisable to use borax which has been dried by heat (calcined borax).

For soldering steel on steel, or iron on steel, melt in an earthen vessel: borax, 3 parts; colophony, 2 parts; pulverized glass, 3 parts; steel filings, 2 parts; carbonate of potash, 1 part; hard soap, powdered, 1 part. Flow the melted mass on a cold plate of sheet iron, and after cooling, break up the pieces and pulverize them. This powder is thrown on the surfaces a few minutes before the pieces to be soldered are brought together. The borax and glass dissolve, liquefying all impurities, which, if they were shut up between the pieces soldered, might form scales.

**Cryolite.**—Finely powdered cryolite is suitable for hard soldering copper and copper alloys, or a mixture of 2 parts powdered cryolite, and 1 part phosphoric acid may be used. For hard soldering of aluminum bronze, a mixture of equal parts of cryolite and barium chloride is used.

**Muller's Hard Soldering Liquid.**—This consists of equal parts of phosphoric acid and alcohol (80 per cent.).

**Dry Soldering Preparation.**—A good preparation consists of two vials, one of which is filled with chloride of zinc and the other with ammonium chloride. To use, dissolve a little of each salt in water, apply the ammonium chloride to the object to be soldered and heat the latter until it begins to give off vapor of ammonium, then apply the other, maintaining the heat in the meantime. This answers for very soft solder. For a harder solder dissolve the zinc in a very small portion of the ammonium chloride solution (from  $\frac{1}{4}$  to  $\frac{1}{2}$  pint).

The various fluxes and their use are given in tabular form in the accompanying tables. According to Haswell, the proper fluxes to use are as follows:

For iron, use borax

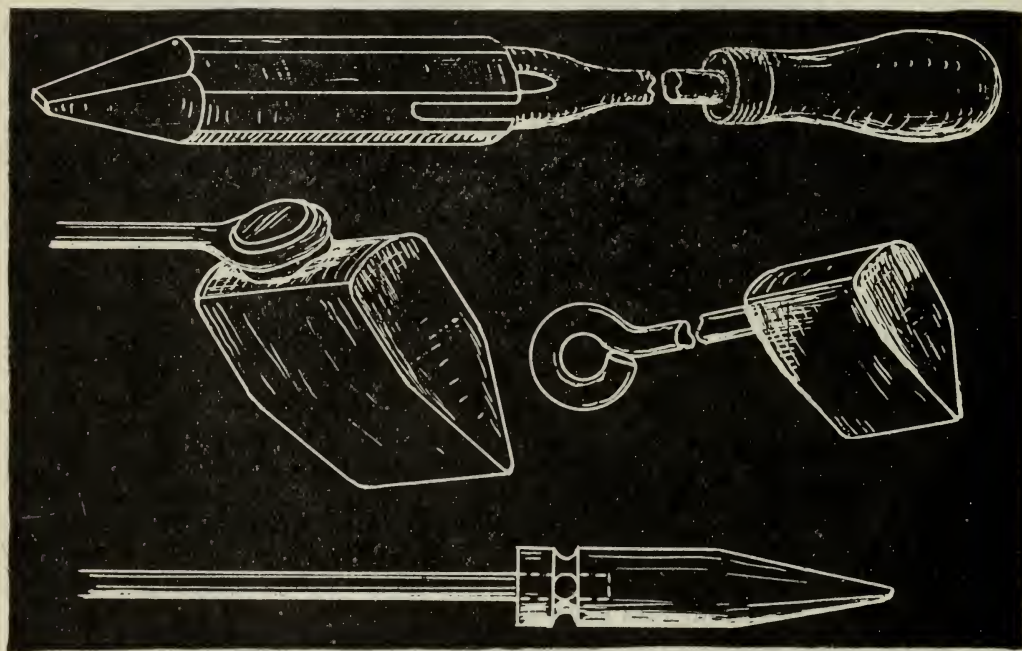
“ tinned iron, use rosin

“ copper and brass, use sal ammoniac

For zinc, use chloride of zinc

“ lead, use tallow or rosin

“ lead and tin, use rosin and sweet oil



FIGS. 4,445 to 4,448.—Various soldering bits, or so called “irons.” Fig. 4,445, ordinary edge bit; figs. 4,446 and 4,447 hatchet bit; fig. 4,448, pointed bit.

**Soldering Bolts or Bits.**—The erroneously called soldering “iron” or bit consists of a large piece of copper, drawn to a point or edge and fastened to an iron rod having a wooden handle as shown in fig. 4,445. There are a variety of bit which may be classed

1. With respect to their shape, or construction as

*a.* Pointed;

*b.* Grooved;

*c.* Hatchet;

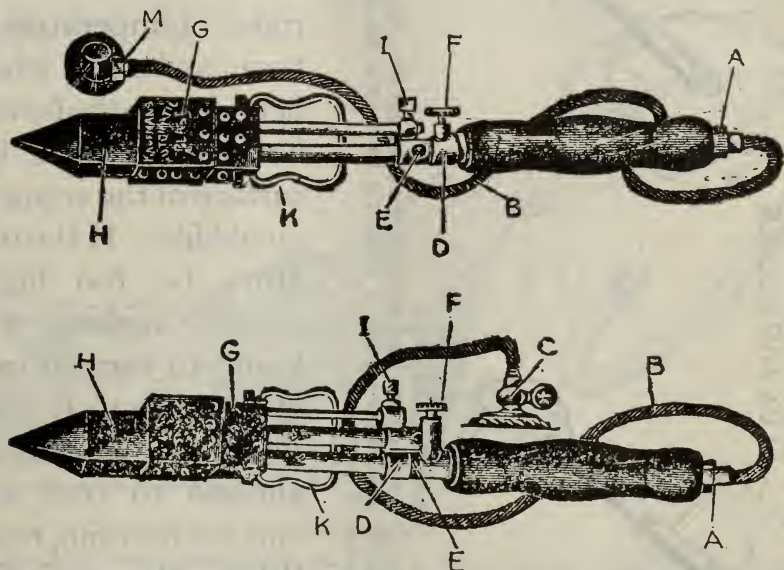
*d.* Reservoir.



2. With respect to the method of heating, as

- a. Externally heated; b. Internally heated { electrically, or by gasoline torch.

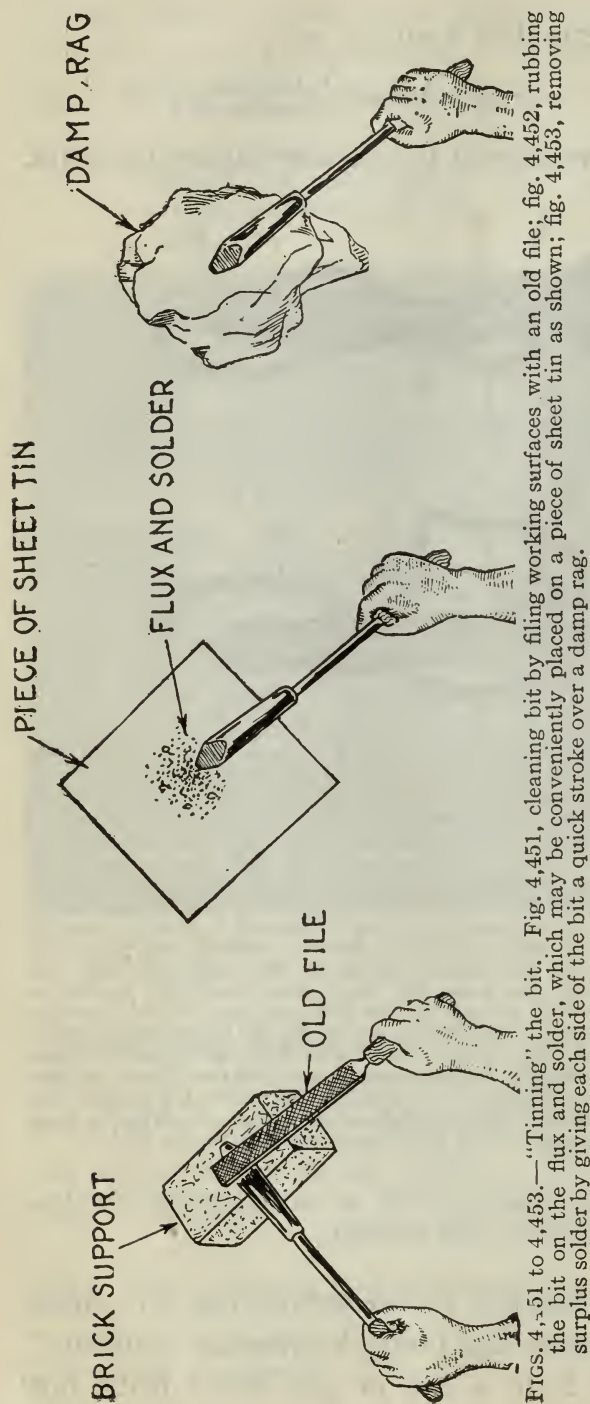
The various types of bit are shown in the accompanying cuts.



FIGS. 4,449 and 4,450.—Kageman self-heating gas soldering bit for bench work. Fig. 4,449, single torch; fig. 4,450, double torch. Any shape or weight of copper point for any class of work may be easily substituted by means of a set screw I. One end of a flexible tubing is attached to the nozzle or male screw near the handle A, and the other end is connected to the gas main M. ( $\frac{3}{8}$  main preferred.) Before lighting, close the Bunsen holes E by means of the air slide D, open the governor F, turn on gas main M, light near copper point at G, and gently open Bunsen holes by means of slide D. If flame appear within chamber E, turn off gas, slightly close holes by means of slide D, and light again. Shut off gas at main cock M. Where the gas main is already installed it is advantageous to bore a hole in the bench near the wall, connect a flexible metallic tubing to the gas main, pass tubing through the hole and fasten tubing to the underside near the outer edge of the bench. In that way the hose will hang freely and will hardly be noticeable. The soldering iron can be used away from the bench at any desired distance, depending upon the length of the tubing. The double torch, fig. 4,410, has two burner tubes generating two short but intensely hot blasts. The double flame is intended to heat heavy coppers quickly, and when the desired temperature is reached one flame is shut off by a half turn of the governor, the remaining flame keeping the point at a steady temperature throughout the day. For smaller coppers one flame is sufficient. When a large heating power is required it is often desirable to use both blasts throughout the day.

A heavy bit is preferable for jointing work, as one weighing less than two pounds does not retain the heat long enough.

**Tinning the Bit.**—Preliminary to soldering, the bit must be coated with solder, this operation being known as “tinning.” To tin a soldering bit, heat it in a fire or gas flame until hot



FIGS. 4,451 to 4,453.—"Tinning" the bit. Fig. 4,451, cleaning bit by filing working surfaces with an old file; fig. 4,452, rubbing the bit on the flux and solder, which may be conveniently placed on a piece of sheet tin as shown; fig. 4,453, removing surplus solder by giving each side of the bit a quick stroke over a damp rag.

enough to melt a stick of solder rapidly when it is lightly pressed against it. When the bit is at the right temperature, the heat can be felt when it is held close to the face. When hot enough clean up the surface of the copper with an *old* file. If the temperature be too high, the copper surface will be found to tarnish immediately, in which case the soldering bit must be allowed to cool slightly and the cleaning repeated. When the surface only tarnishes slowly a little flux is sprinkled upon it, it is then rubbed with a stick of solder. After the molten metal has spread over the whole of the surface which it is desired to tin, the superfluous solder is wiped off with a clean damp rag.

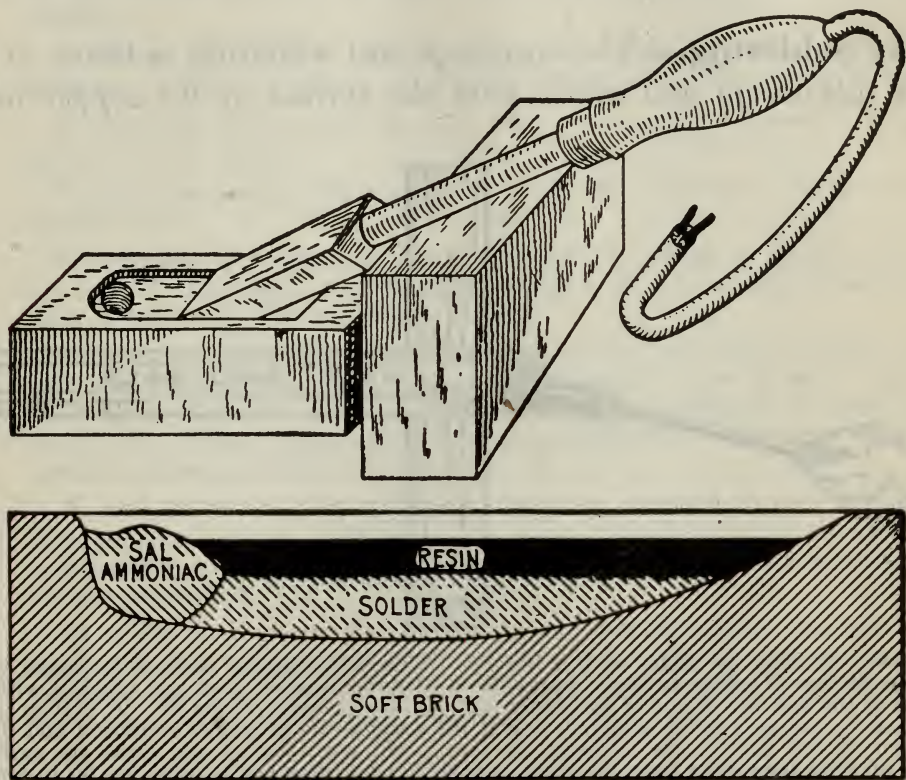
*The surface should then present a bright silvery appearance when properly tinned.*

Once a soldering bit has been well tinned care should be taken not



to overheat it. If the bit at any time reach a red heat it will be necessary to repeat the whole tinning process before it is fit to be used again. **No good work can be done with an untinned or badly tinned bit.**

**Ques.** If the bit be forgotten and left in the fire what should be done?



**FIGS. 4,454 and 4,455.**—Tinning block for electric soldering tool. It is made with two soft bricks. One brick is used to support the soldering tool, and the other to contain the tinning material and to furnish a material which will keep the copper bit bright enough to receive its coating of "tin." Fig. 4,455 represents a section of the tinning brick, which is scooped out on top as shown by the lower line. Into one end of the hollow in the brick, some sal-ammoniac is placed to help tin the copper bit. Sal-ammoniac is a natural flux for copper and aids greatly in keeping the tool well tinned. Next, some melted solder is run into the hollow of the brick, and lastly enough resin to fill the cavity nearly to the top. When the tool is not in use, the electricity is switched off and the tool permitted to lie in the resin. If it be desired to repair the tin coating a little when the tool is in use, the latter is rubbed on the brick below the layer of solder, and the layer of resin. If the tool be in very bad condition, it may be pushed into the sal-ammoniac once or twice and then rubbed in the solder again. It requires but little heat to keep the brick and its contents ready for use. In fact, the brick is a fair non-conductor of heat and prevents the escape of heat from one side of the tool. When momentarily not in use, the tool remains in the solder which becomes melted underneath the layer of resin. When the copper bit becomes too hot, it will begin to volatilize the resin, thus calling attention to this fact, whereupon the electricity should be turned off from the tool.

Ans. Heat to redness and then plunge into cold water, when most of the hard oxidized surface will scale off.

**Ques.** What kind of fire quickly destroys the tinning?

Ans. A soft coal fire.

**Soft Soldering.**—The theory of soft soldering is that: *as the solder adheres to and unites with the surface of the copper when*

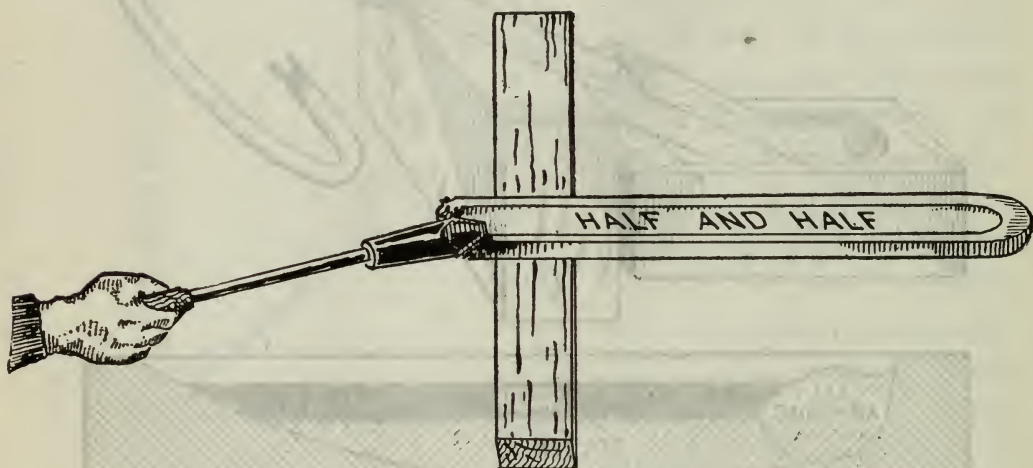


FIG. 4,456.—Picking up solder with a hot bit. This is the proper method for small work. Rest the bar of solder on some support as a brick or piece of wood and touch it with the end of the hot bit. Some of the solder will melt and remain on the bit. It is then transferred to the part to be soldered, and if the surfaces be in proper condition and fluxed when the bit touches the surfaces, the solder will leave the bit and cover the surfaces. **In picking up solder** from the stick, care should be taken not to leave the bit in contact with the solder too long or some of it will drop off. The larger the bit and area tinned, the more solder will the bit hold.

*the bit is tinned, so will it adhere to and unite the surfaces of the metals to be soldered.*

Soft soldering, as well as hard soldering, or brazing, consists of welding together two or more pieces of similar or dissimilar metals by means of another metal of lower melting point.

In order to solder successfully wire joints, the following instructions should be followed:



1. Clean and tin the bit as previously explained.

2. Heat the bit in the fire until it reaches the right temperature. Do not try to solder a joint with a bit so cool that it only melts the solder slowly, nor with one so hot that it gives dense clouds of smoke when in contact with rosin. Burned rosin must be regarded as dirt.

3. Remove the bit from the fire and hold it, or preferably support it on a brick or block of other material which does not conduct heat readily.

4. Wipe the surface clean with a rag. Apply solder until a pool remains on the flat surface, or in the groove, if a grooved bit be used.

5. Sprinkle with rosin, lay the joint in the pool of solder and again sprinkle with rosin.

6. Rub the joint with a stick of solder so that every crevice is thoroughly filled.

7. Remove the bit, and lightly brush superfluous solder from the bottom of the joint. See that no sharp points of solder remain which may afterwards pierce the insulation.

When the joint is first placed on the bit, the solder should run up into the joint. This will occur only when the joint is well made and thoroughly cleaned, and if the workmanship be perfect it is even possible to fill the joint completely by feeding in solder below the joint as it melts and runs up into the joint.

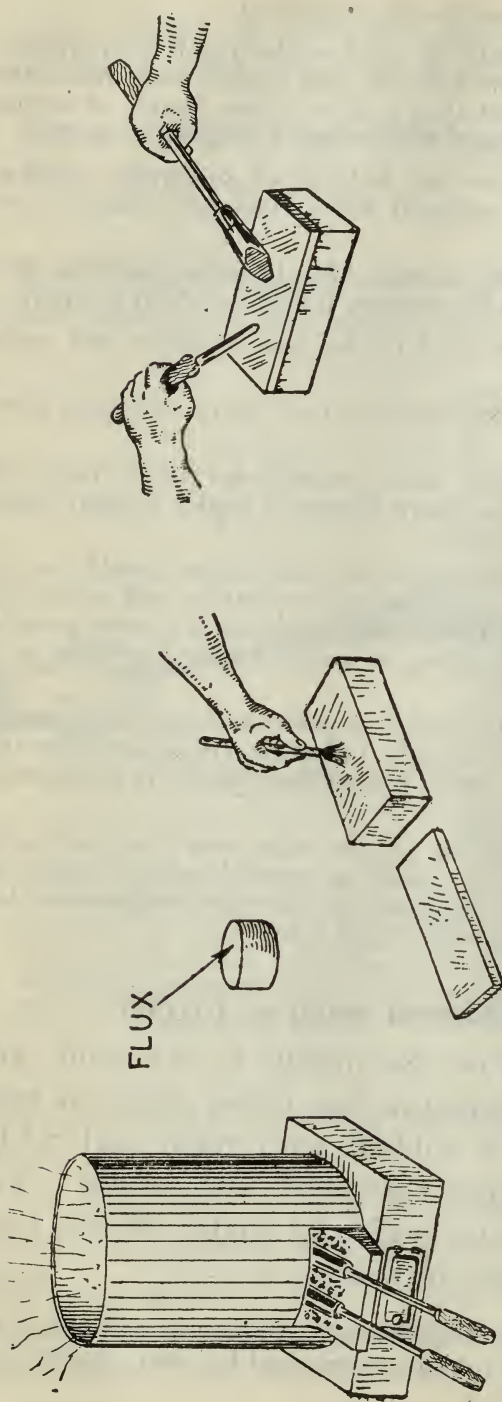
A well soldered joint should present a smooth, bright appearance like polished silver. Wiping the joint before it cools destroys this appearance, and is also liable to produce roughness, which is detrimental to the insulation.

In order to prevent the insulation on the wire near the joint being damaged, the process of soldering should be carried out as quickly as possible, and for this reason the tendency to burn the insulation is less with a *hot* bit (a quick bit) than with a cooler one.

### **Ques. How is a joint soldered with a torch?**

Ans. The flame is directed on the middle of the joint, and when a sufficient rise of temperature has taken place to melt the solder readily, the joint is rubbed with rosin and solder alternately until it is thoroughly saturated with solder. The usual precaution of brushing any points of solder off the joint with a clean rag must, of course, be taken.

In using the torch there is considerable danger of damaging the insulation with the flame. This may be minimized by wrapping the end



FIGS. 4,457 to 4,461.—*Sweating*. When two surfaces are to be united by sweating, first see that the surfaces are perfectly clean, then flux as in fig. 4,460. Put a piece of tinfoil over one surface and the other surface on top. They should be held firmly together by a clamp or other means and heated as in fig. 4,461 by a hot bit, or if the metal have considerable thickness by a torch, until the solder melts. When cool, the surfaces will be found to be firmly united.

of the insulation with selfedge tape before soldering. When big joints are being made it is sometimes advisable to wet the tape in order to prevent the conduction of heat along the copper to the insulation.

**Sweating.**—In this operation the surfaces are cleaned, heated, and covered with a film of solder. The soldered surfaces are then placed together and heated by passing the bit over the outside surface until the solder melts and unites the two surfaces.

Sweating is often employed for the temporary holding together of work which has to be turned or shaped, and which could not be so conveniently held by other methods. After having been turned or shaped, the separation of the parts is readily effected by the aid of heat.

### **Babbitting Boxes.**—

Although some special machines are provided with ball bearings, most dynamos and motors have



plain babbitted bearings, accordingly electricians and repair men should know how to babbitt a box should occasion arise for such operation.

Formerly, bearings for the journals of machinery were constructed of *brass or other alloys*, for the purpose of minimizing friction. Hard cast iron, which afforded an admirable surface becoming glazed over with a sort of skin after a little use, while efficient for sliding surfaces, had to be avoided for journals, as irreparable damage might be done to the bearing when overheated. Later practice evolved the idea

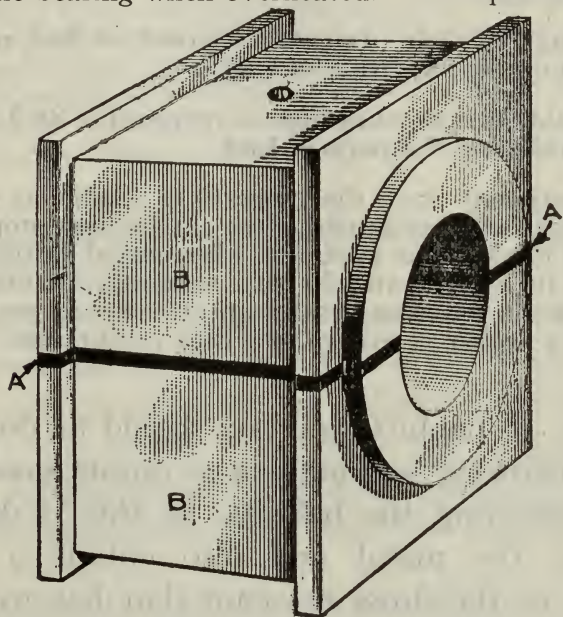


FIG. 4,462.—Sweating brasses. When brasses are sweated together, liners AA, are sometimes placed between them, as shown, to allow for wear when they are in the machine. The faces of the brasses and liners are planed smooth and rubbed bright. They are then heated in the forge, and when hot, the brasses fluxed with sal-ammoniac and tinned by the method employed in tinning the soldering copper. The liners, if of iron, are fluxed with borax and tinned. The pieces are then put together and heated sufficiently to melt the solder. If not heavy enough to make a tight joint, they are weighted down until cold. When the pieces have been bored out and finished in the machine shop, they are melted apart and the liners taken out, a number of thin liners being substituted.

of using a softer or elastic metal, popularly and *erroneously* known as *anti-friction metal*, which would accommodate itself to inequalities of the surfaces in contact, thus working with far less friction than iron or bronze, while on the other hand it would be much cheaper than a copper tin alloy.

Of the various so called anti-friction metals, Babbitt is extensively used. This is a soft white metal composed of tin

copper and antimony. Many different compositions of these metals are used for babbitt metal; the alloy originated by Isaac Babbitt was composed of tin,  $45\frac{1}{2}$  parts; copper,  $1\frac{1}{2}$  parts; antimony, 13 parts; lead, 40 parts.

At the beginning this proportion was used for all purposes, but it has been found that there is no one composition that will bring equally good results in all kinds of machinery, hence are given the following different proportions:

Babbitt metal for light duty is composed of 89.3 parts of copper, 1.8 parts of antimony, 8.9 parts of lead.

Babbitt metal for heavy bearings is composed of 88.9 parts of copper, 3.7 parts of antimony, 7.4 parts of lead.

Lead and antimony have the property of combining with each other in all proportions without impairing the anti-friction properties of either, the antimony hardens the lead, and when mixed in the proportions of 80 parts lead, by weight, with 20 parts antimony, no other known composition of metals possesses greater anti-friction or wearing properties or will stand a higher speed without heat or abrasion.

The operation of babbitting a box should be done in accordance with the following instructions to obtain good results.

1. Avoid overheating the babbitt, as this is destructive to the qualities of the metal and also entails a considerable loss on account of the dross or scum that has to be skimmed off the ladle.

To ascertain the proper temperature, the time honored test is to try it with a dry pine stick. The temperature should be such that the stick will char without catching fire. Cover the metal with powdered charcoal and put in the ladle a lump of sal-ammoniac.

Of course, it is sometimes necessary to heat the babbitt hotter than this to insure its running to all parts of the box when the section to be filled is thin, but if possible, in such cases, the box should be warmed up to prevent excessive chilling of the metal.

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NOTE.—The practice of lining journal boxes with a metal that is sufficiently fusible to be melted in a common ladle is not always so much for the purpose of securing anti-friction properties as for the convenience and cheapness of forming a perfect bearing in line with the shaft without the necessity of boring it. Boxes that are bored, no matter how accurately, require care in fitting and attaching them to the frame or other parts of a machine.



2. If the box is to be babbitted with the shaft in position for a mandrel, be careful to get the shaft properly lined and central in the box.

To hold it in position use an outside support if convenient, but if not, small pieces of lead hammered to the right thickness may be used to hold it at the proper height and in a central position. ***It is not good practice***, however, to use the shaft for the purpose of casting the bearings, especially if the shaft be of steel, for the reason that the hot metal is apt to spring it; the better plan is to use a mandrel of the same size or a trifle larger for this purpose. For slow running journals, where the load is moderate, almost any metal that may be conveniently melted and will run free will answer the purpose. For wearing properties with a moderate speed there is probably nothing superior to pure zinc, but when not combined with some other metal it shrinks so much in cooling that it cannot be held firmly in the recess, and soon works loose.

3. The shaft should be smoked or greased so that the babbitt will not adhere to it.

4. The ends of the box should be stopped with clay or cardboard washers cut to snugly encircle the shaft and held to the face of the box, to prevent the babbitt escaping.

Liners made of cardboard should be inserted between the halves of the box and should touch the shaft on each side so that the box can be divided without trouble after the pouring is completed.

5. A small hole at one end will be sufficient to insure the lower part filling properly.

6. With a large box and shaft, it is best to pour the lower part first and then the upper one.

7. Care should be taken that there is no water or dampness in the box, as serious consequences may follow if this precaution be neglected.

A rusty box is likely to throw the babbitt, as water will be liberated when the hot metal is poured on it. A small lump of rosin dropped in the ladle just before pouring increases the fluidity of the metal somewhat and reduces the liability of the babbitt to explode when the interior is slightly damp, although no risks should be taken in this direction.

8. If the oil hole be used to pour through, it will be necessary to drill it out and cut the oil grooves after the box is taken apart.

9. If the babbitt be poured from the side, a plug of pine wood can be inserted in the oil hole down to the shaft to keep it clear.

10. The shaft is sometimes wrapped with a stout cord laid in a spiral direction to get the proper oil runs, but it is usually better to cut them afterwards with a round nose chisel.

**Brazing.**—This is the art of *uniting metals by means of a hard solder*. Originally, as its name implies, it was devoted to the union of brass or other copper alloys.

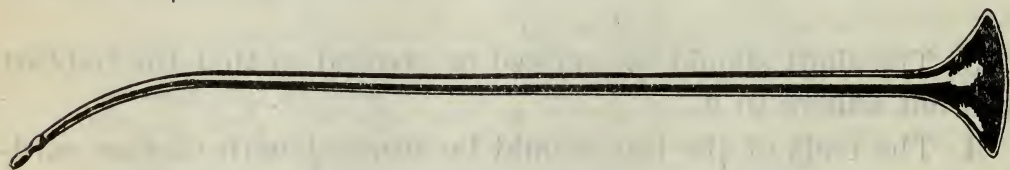


FIG. 4,463.—Ordinary mouth blow pipe.

The theory of brazing is *the melting of a low fusing metal against the metals to be united while they are in such a condition of cleanliness and temperature that the metal welds itself to them*.

Brass filings have been generally replaced by *spelter*, which is a composition of about equal parts of copper and zinc; this is used for brass work. For tubes, a composition of 8 parts of brass tube filings to 1 of zinc is used.

Brass or gun metal united by this process will produce a joint as hard as the metal pieces united.

Iron and steel, especially small pieces of finished work, may be united, by the same means. The process of brazing consists essentially of

1. Cleaning the parts to be brazed;
2. Applying the hard solder and flux;
3. Heating.



The work is first carefully cleaned with acid, and some fine spelter is mixed with borax to form a flux, a little water being added to make a paste. The compound is placed between the parts to be united, as much surface as possible being brought in contact, the two being held firmly together, in the case of small pieces by tongs, and heated until the flux and spelter are melted, the parts being held together until the spelter unites with the metal and solidifies.

Sometimes the work cannot be easily gripped, and so, after inserting the spelter and borax as before, the parts are bound with iron wire and

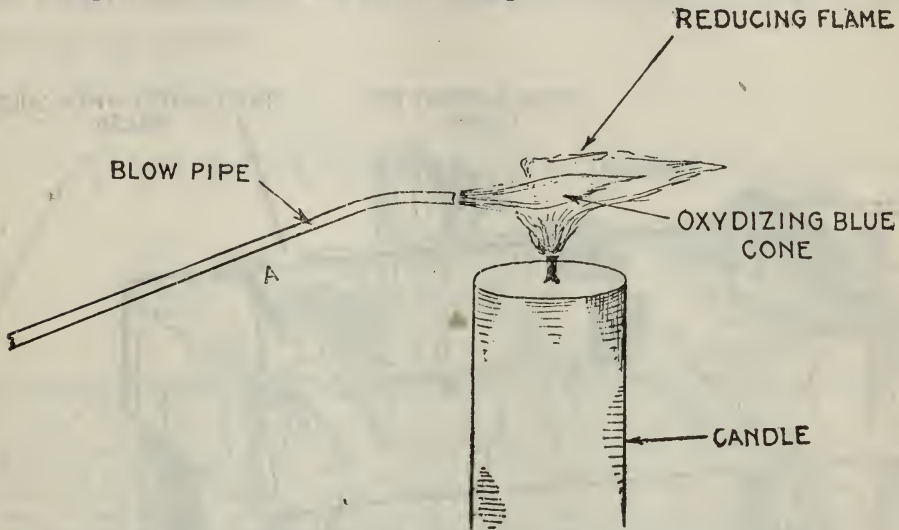


FIG. 4,464.—Method of using the mouth blow pipe. This is for small work, though the intensity of the heat thus produced is very great, the volume of flame is small. On some blow pipes a ball or enlargement is made at A to catch any moisture or saliva, thus increasing the efficiency of the instrument. The torch as shown, gives two flames as follows: **1, oxydizing flame**, commonly caused by the chemical uses of oxygen with another substance. If more oxygen be supplied than is needed for perfect combustion, the free oxygen in excess makes an oxydizing flame, one that rusts or burns the metal. A flame may be oxydized in one place and reducing in another; **2, reducing flame**, defined as a flame in which the fuel is in excess of the oxygen necessary for perfect combustion. *The tendency of such a flame is to draw some oxygen from the burned parts of the metal.* It prevents burning within its radius.

placed in a clear coke fire until the operation is complete. The superfluous metal around the joint will in each case need to be removed by means of the file.

There are various methods of brazing, such as

1. Butt brazing;
2. Lap brazing;
3. Dip brazing;
4. Muffle brazing.

**Butt Brazing.**—This method consists of placing the two pieces to be brazed *butt to butt*. If two thin pieces are to be butt brazed, the pieces must be held in position in a bench vise, or clamp, and the heat applied with a torch or blow pipe. The surfaces to be brazed are fluxed and then clamped in position and the proper hard solder, as given in the tables, applied.

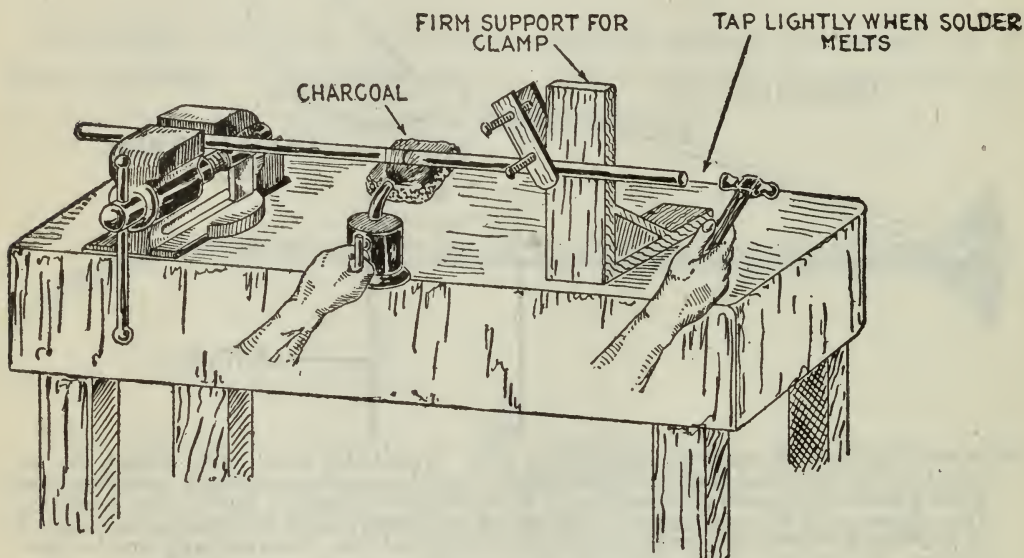


FIG. 4,465.—Butt brazing two lengths of small pipe. After cleaning the ends to be brazed and fluxing, they are clamped in position butt to butt using a vise and clamp as shown, or other means. A little brazing solder is sprinkled over the joint and heat applied. When the pieces are hot enough to melt the solder it must flow into the joint, butt brazing the two pieces. By giving one of the pieces a slight tap on the end, when the solder melts, the surplus solder is squeezed out, making a good and firm joint. If the pipes be large or of considerable length, the heat is quickly conducted away, necessitating a charcoal backing or more adequate means of heating.

Heat is then applied by means of a blow pipe, or Bunsen burner, until the pieces are hot enough to melt the solder, which will then flow into the crack.

By giving one of the pieces a slight tap on the end, they are brought tightly together. After cooling, the superfluous solder is scraped off.



**Lap Brazing.**—In this method the parts to be brazed are overlapped. Band saws are always lap brazed, the two ends being filed to make an accurate joint. Silver solder is generally used, it being applied between the two surfaces, or the surfaces are coated with borax and the solder allowed to flow into the joint from the edges. The operation of lap brazing a saw is shown in fig. 4,466.

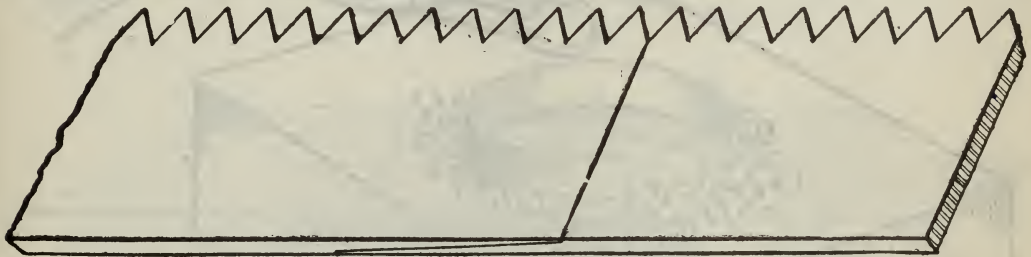


FIG. 4,466.—Lap brazing. A band saw is a good example of this method. In making the lap the two ends are chamfered by filing to make an accurate joint as shown. Silver solder is generally used, it being applied between the two surfaces, or the surfaces are coated with borax and the solder allowed to flow into the joint from the edges. After firmly clamping the parts in position, the solder is laid over the joint, or it may be placed between the two pieces to be united. When the heat is applied, the solder melts and the two pieces must be squeezed tightly together to force out surplus solder. Silver coins contain 10 per cent. of copper and make a good hard solder. When using a coin, pound it until very thin and then place between the two surfaces to be brazed.

**Dip Brazing.**—This consists of dipping the work into molten solder until the parts are heated sufficiently to be united by it. For duplicate work this method is well suited, and is extensively employed in bicycle manufacture.

**NOTE.—Cast iron soldering.** A new process consists in decarbonizing the surfaces of the cast iron to be soldered, the molten hard solder being at the same time brought into contact with the red hot metallic surfaces. The admission of air, however, should be carefully guarded against. First pickle the surfaces of the pieces to be soldered, as usual, with acid, and fasten the two pieces together. The place to be soldered is now to be covered with a metallic oxygen compound, and any one of the customary fluxes, and heated until red hot. The preparation best suited for this purpose is a paste made by intimately mingling together cuprous oxide and borax. The latter melts in soldering and protects the pickled surfaces, as well as the cuprous oxide from oxidation through the action of the air. During the heating the cuprous oxide imparts its oxygen to the carbon contained in the cast iron and burns it. Metallic copper separates in fine subdivision. Now apply hard solder to the place to be united, which in melting, forms an alloy with the eliminated copper, the alloy combining with the decarburized surfaces of the cast iron.

**Muffle Brazing.**—As indicated by the title, a tube or *muffle* is used in this method for enclosing the parts to be brazed. The object of the muffle is to insure uniform heating; it is especially adapted to brazing alloys, the melting temperature of which are rather close to that of the solder.

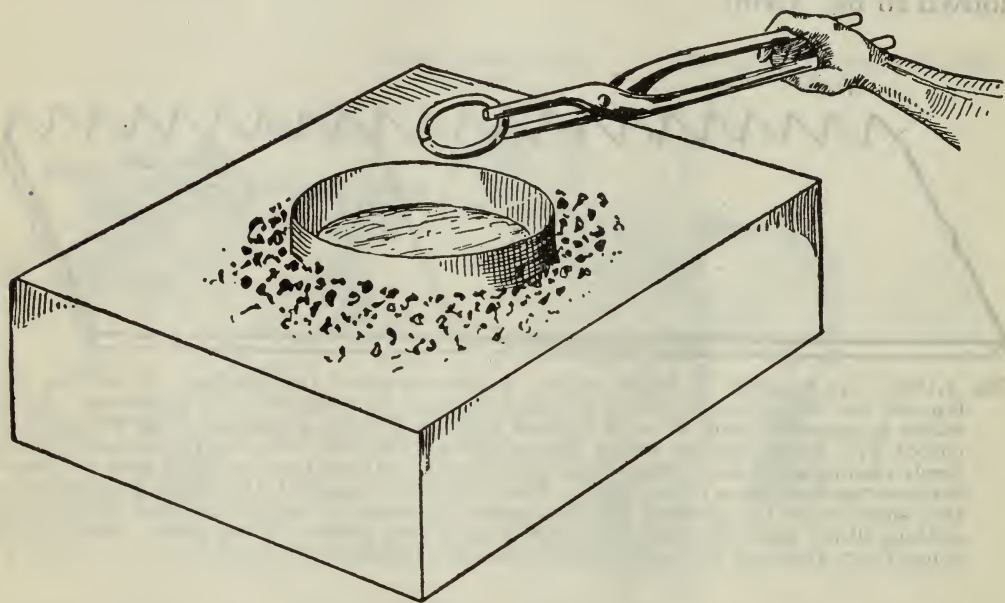


FIG. 4,467.—Brazing by immersion or dipping. The brazing solder is melted in a pot on the coal fire, as shown, or better in a gas furnace, flux being placed on top of the solder. **In brazing**, hold the object first in the flux a little while to heat and coat the article with a film of flux. Then, when it is lowered into the solder, the latter will flow in the joint and firmly attach itself. Before dipping, the article to be brazed is coated with a special anti-flux graphite, covering all the surface except that which is to be brazed. The layer of flux in the pot may be kept from  $\frac{1}{2}$  inch to 2 inches deep.

**Brazing of Copper.**—For coppersmith's work the joints are prepared either by *thinning* or *cramping*. The first process consists simply of scarfing the edges to a long bevel, and is used for heavy material only. The second, a necessity for lighter work, is rather more elaborate; notches are cut at a slight angle into one of the edges to be united, and the teeth thus formed are bent alternately to left and right. The edge of



the other piece is thinned and inserted between the cramp, so that alternate pieces come on opposite sides of the thinned edge, supporting it.

Copper joints to be brazed are cleaned by covering the parts with a strong brine made from salt and water; they are then heated to a cherry red and plunged into clean fresh water, which also has the effect of annealing the copper. Scouring follows with clean water and sand rubbed on with a wad of tow.

The brazing mixture is made of borax and spelter in equal parts, with water, and is preferably made a day or two previously. The

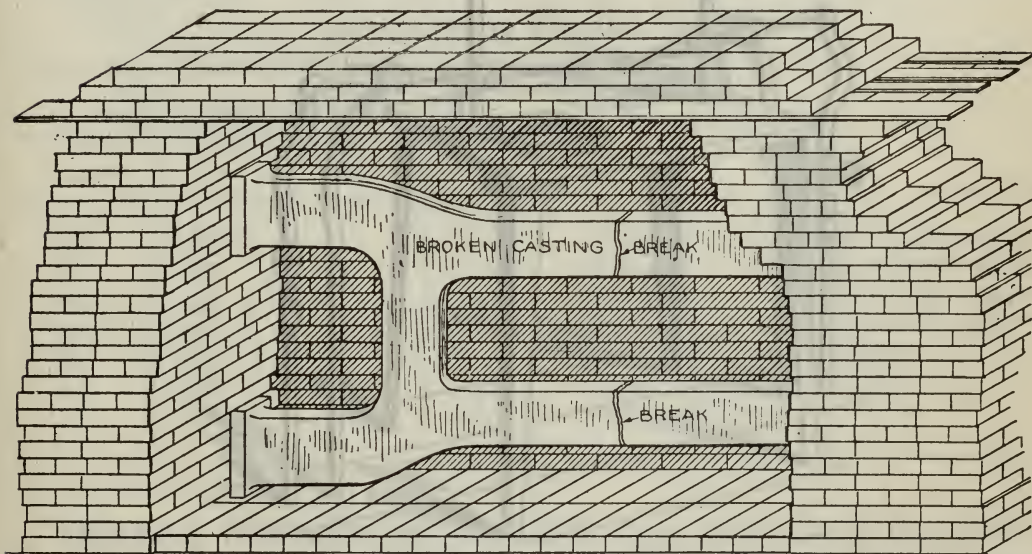


FIG. 4,468.—Quickly constructed furnace for brazing; view showing broken casting in position ready for brazing.

prepared portions of the article to be jointed are placed together and fastened, if for a pipe, by being bound with iron wire. The overlapping edges are closed by means of a mallet on a stake or mandrel.

The mixture is then laid evenly along the joint, and the pipe or other article placed upon a clear coke fire, the temperature of which is easily regulated. Presently, the borax fuses and forms into *drops*, and then the solder melts, which is indicated by blue fumes from the zinc. Probably it will be necessary to sprinkle a little more powdered borax, and the pipe may have to be tapped with a mallet or hammer to cause the

lapped parts to open slightly and permit of the solder flowing readily in between them. Salt is often strewn on the surface immediately after the solder has run, to kill the borax, as it would leave a hard scale interfering with future filing.

All flanges to be brazed to copper pipes must be of copper or what is known as brazing metal, 98 copper to 2 of tin, as gun metal flanges would melt before the spelter ran.

The hole in the flange is slightly tapered, and the end of the pipe also, to form a clearance in which the spelter may flow, a countersink being also formed in the face side of the flange, and the pipe slightly opened to fit it.

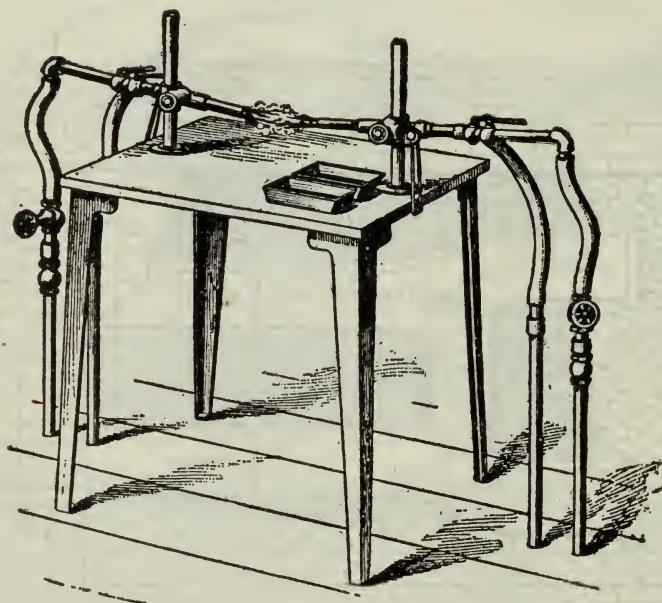


FIG. 4,469.—Brazing furnace without fire bricks. At opposite sides of the top are standards upon which sleeves freely slide, and which are held at any desired height by thumb screws. Each sleeve carries a burner to which gas and air pipes are connected, each pipe being provided with a valve for regulating the flow. The two burners can thus be adjusted so that the meeting points of their flames will be at any desired height above the table.

After the mixture is placed in the joint and the parts put together, the countersink is stopped with clay, to retain the solder. The pipe is then slung vertically over the fire, with the flange underneath, and the previous process carried out.

It will frequently be necessary to close the pipe with a clay tamping or a wooden plug to prevent the heat from going up it. Projections from flanges are protected from the fire by means of a covering of clay.



Table of Brazing Solders

Description	Copper	Zinc	Tin	Lead
Coppersmiths' strong spelter .....	75	25		
Coppersmiths' spelter.....	58	42		
Ordinary refractory spelter.....	50	50		
Hard white solder.....	57½	28	14½	
Half white, easily fusible.....	44	50	4½	1½
Spelter, readily fusible.....	33⅓	66⅔		

A few additional brazing solders are here given with their characteristics and colors.

Miscellaneous Brazing Solders

PERCENTAGE				Characteristics	Color
Copper	Zinc	Tin	Lead		
58	42			Very strong	Reddish yellow
53	47			Strong	Reddish yellow
48	52			Medium	Reddish yellow
54.5	43.5	1.5	0.5	Medium	Reddish yellow
34	66			Easily fusible	White
44	50	4	2	Easily fusible	Gray
55	26	15	4	White solder	White

**Heating Methods in Brazing.**—On account of the higher temperature required in brazing, a flame is generally used instead of a heated bit. For small work a blow pipe or torch is used, and a forge for large work. A torch alone is ordinarily insufficient as the heat must be put where it is needed and held there. This is usually done by building around the work with charcoal which becomes incandescent from the heat of the gasoline flame, and also gives off some heat from its own combustion.

If the article to be brazed be very small, it can be placed bodily in a hole scooped in a bit of charcoal as shown in fig. 4,470.

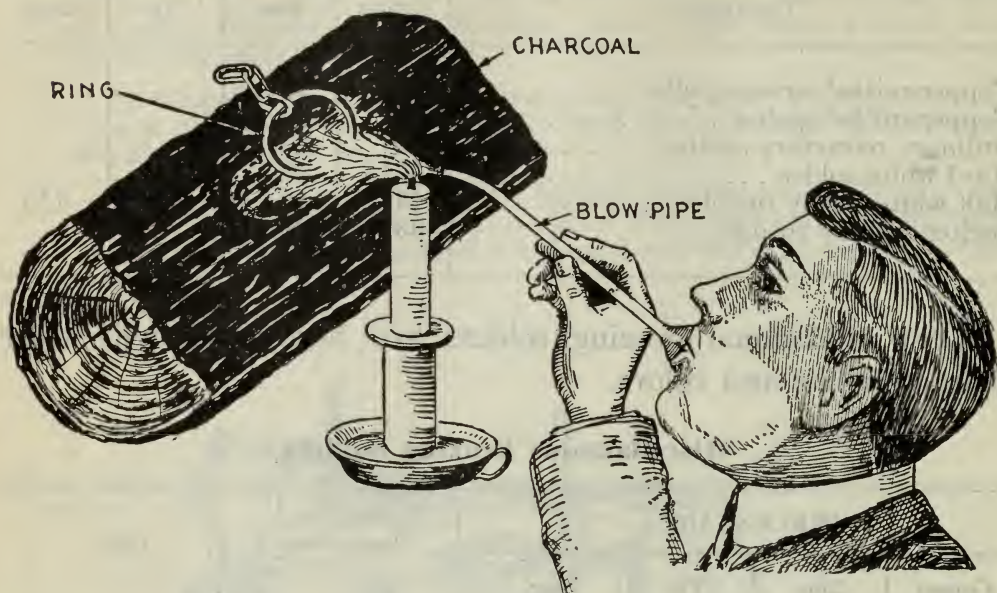


FIG. 4,470.—Brazing a small chain link in charcoal with a blow pipe. Place the broken link in a small hole scooped in the charcoal and heat with the candle flame and blow pipe after applying the solder and flux.

In brazing in the smith's forge it is well to hold the work high up, that is, so that it does not rest on the coal, but is kept suspended between banks of incandescent fuel so that the heating will be as near uniform as possible.

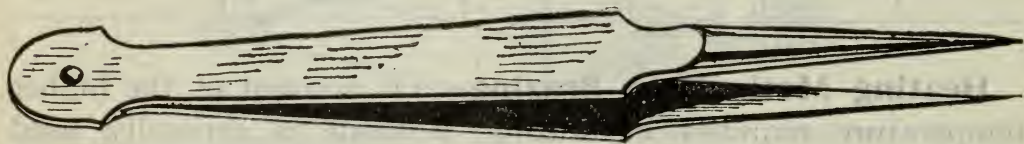


FIG. 4,471.—Brazing the joint of a pair of tweezers. The surfaces to be brazed are cleaned, some of the spelter applied to each surface, and the pieces tied together with a fine iron wire and heated sufficiently to melt the spelter. The heat may be applied with a blow pipe or by holding the pieces in a pair of hot tongs. When the spelter is melted the piece is cooled and the iron wire is taken off. When the pieces are clamped in hot tongs, the iron wire is sometimes omitted, the pieces being placed in their proper relation and the tongs depended on to keep them there, or stops may be arranged to determine the location of the pieces.

A charcoal fire should be used, but if bituminous coal be used, coke enough of it to do the work, as the sulphur in the soft coal is to be avoided where good brazing is desired.



A gas furnace is very desirable for brazing. An air blast is necessary as in the forge but a comparatively small blower will suffice.

The accompanying cuts show the various methods of heating in brazing.

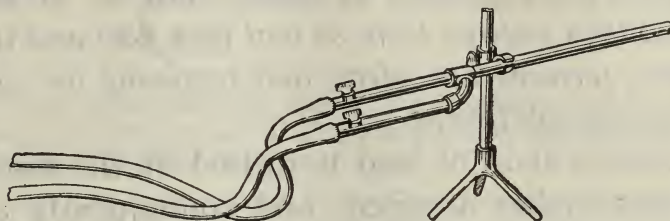


FIG. 4,472.—Air gas torch for brazing.

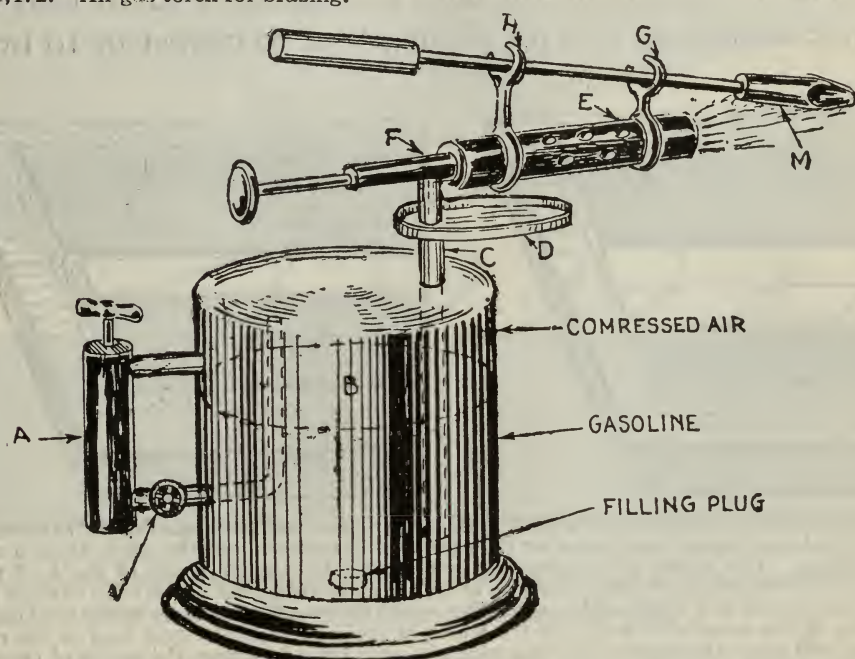
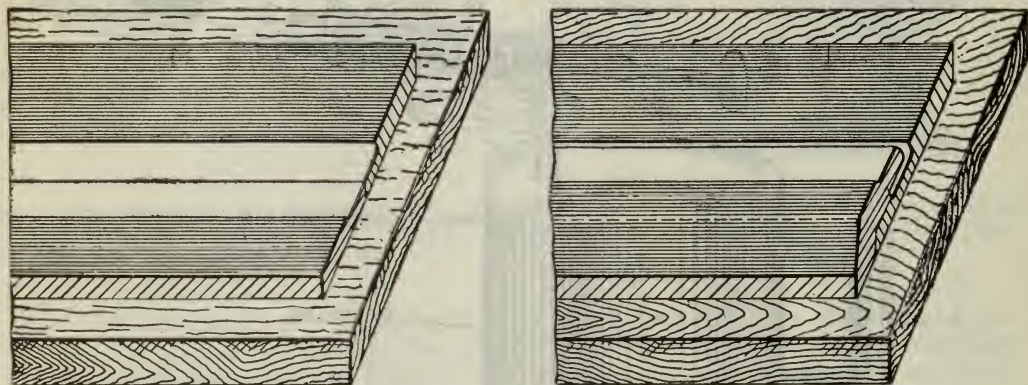


FIG. 4,473.—Gasoline torch with rests for holding soldering bit. *In construction* A is a hand air pump, which may have automatic, or hand operated valve; B is the reservoir containing gasoline and compressed air, the latter being furnished by the pump. A valve V, prevents leakage of the compressed air through pump. A pipe C projects to bottom of reservoir, as indicated by dotted lines, and connects with vaporizer E through needle valve F. A trough D is for holding a small quantity of gasoline to heat vaporizer E in starting. Two supports H and G clamped to the vaporizer support a soldering bit so that it will rest in the flame in heating. *In operation*, the reservoir is filled about two-thirds full through filler plug and the pump given a few strokes to compress air in the top of reservoir. After heating vaporizer E, with a little gasoline placed in D, needle valve F, is opened slightly. The gasoline under pressure in the reservoir will flow through needle valve F, into the vaporizer and ignite. As the vapor becomes hotter the valve may be given more opening and when fully heated an almost colorless flame of great heat will issue from the end of the vaporizer. Air supply is admitted into the vaporizer through the small holes shown. In attaching the supports H, G, care should be taken not to cover any of the air holes, because this will cause a poor flame.

**Lead Burning.**—This process, sometimes erroneously called autogenous soldering, consists of *joining pieces of lead together by simply placing the edges to be joined close to, or overlapping each other, and then melting them so that they flow and intermingle with each other, forming one piece, and retaining the same condition of unison on solidifying.*

In some cases a strip of lead is melted at the same time as the edges; this makes a raised, and consequently a stronger seam. The process is useful only for joining lead to lead and would not answer so well for joining lead to copper or to brass.



FIGS. 4,474 and 4,475.—Preparation of butt and lap seams for lead burning. Fig. 4,474 shows the edges of a butt seam placed together on a piece of flat board, and the seam shaved ready for burning. The width of the shaving is governed by the thickness of the lead to be joined. For 5 lb. lead the rear should be about  $\frac{3}{8}$  inch wide, that is the edge of each piece should be shaved to a width of  $\frac{3}{16}$  inch. Fig. 4,475 shows a lapped seam ready for burning. The face of the under side is shaved the width of the seam, and the over lead on the under side, as well as on the upper face, the width being a little less than the width of the seam for butt burning. The shaving is done with an ordinary shave hook and straight edge.

In lead burning, a hydrogen flame is used in connection with a jet of air, the hydrogen being produced in a machine or generator as explained fully in Guide No. 4, page 928, fig. 1,128.

For joining lead sheets together by burning, it is essential that the pieces touch or overlap each other when in the horizontal position, and overlap when in either slanting, upright, or overhead positions. It is not necessary to *soil* the sides of the



seams, because the lead will flow only where it is directed by the flame jet. No fluxes are necessary.

The details of preparation of butt and lap seams are shown in figs. 4,474 and 4,475.

To burn either of these seams, first regulate the gas and air cocks or the gas and oxygen cocks of the generator as the case may be, so as to obtain a "hard solid flame."

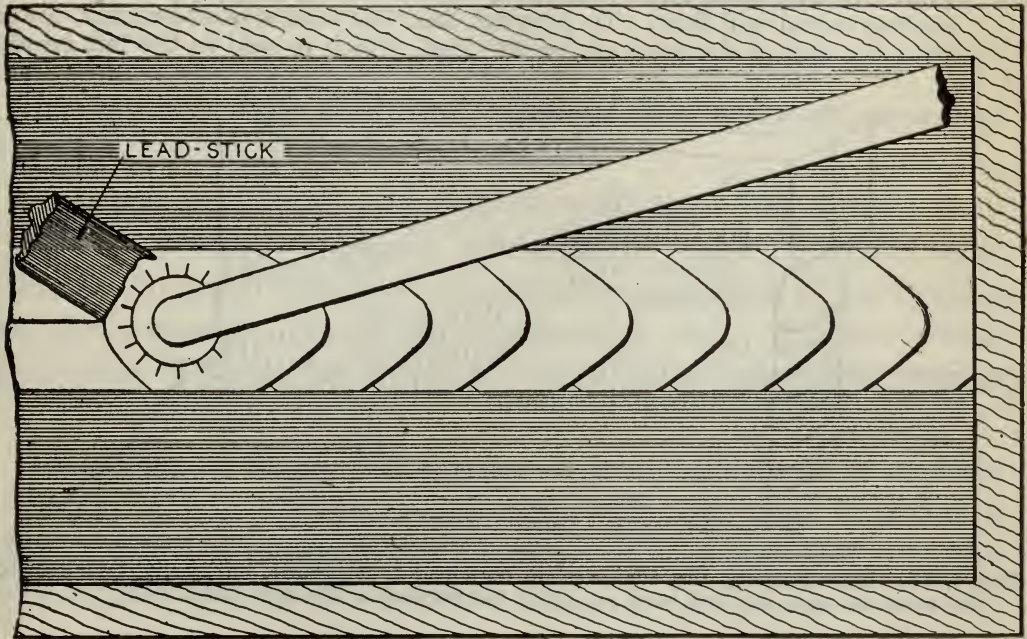


FIG. 4,476.—Process of burning a butt seam in two sheets of lead.

**For flat butt burning** the end of a stick of lead should be held on the seam so as to be melted at the same time as the other lead, as shown in fig. 4,476.

Before beginning to burn the seam, a stick of lead should be held in the hand and the flame made to play upon it so as to ascertain the hottest part of the flame to apply to the seam.

If the flame tarnish or smoke the lead stick, more air or oxygen should be burned in, but if the lead turn to a silvery brightness, when the flame impinges, the heat will be right and the part of the flame to be used will be ascertained.

Now tack the two ends of the seam by melting little beads on them to hold the pieces in position.

The burning can now be started, beginning being made at the right hand end. The flame is lifted immediately when the metal begins to flow and reapplied at a distance of from  $\frac{1}{8}$  to  $\frac{1}{2}$  inch, according to the thickness of the lead being joined together, giving the appearance shown in fig. 4,476.

During the process of burning, the sheet lead will be expanded when the heat is applied, and being a poor conductor, the heat is not distributed to the adjoining sides of the seam, hence the heated parts will rise up and leave hollow spaces underneath. When this happens, leaving places where the lead does not rest in the board the lead melts more readily, with the result that a hole is made, through which the molten metal will flow. To prevent this, the lead should be held down with the end of the stick of feeding lead, which is held in the left hand.

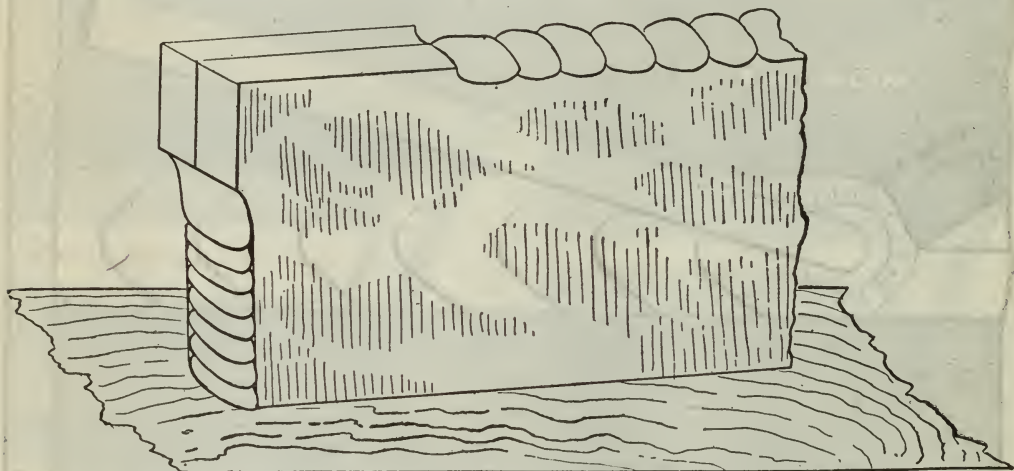


FIG. 4,477.—Edge burning. In this case no feed lead is necessary, but a slight jar has to be given to start the first bead on either the vertical or the horizontal seam.



## CHAPTER LXXXIV

## WELDING

The art of *forcing two pieces of metal into union by means of heat and pressure*, is known as **welding**.

Until the introduction of electric welders, it has always been a difficult process, requiring considerable experience and skill of hand and eye. Not only must the temperature of the heated iron be properly judged for a successful weld, but the metal itself must be protected from the effect of the oxygen in the air.

**Oxidation of Iron.**—If a piece of iron be heated in contact with air, it will absorb oxygen from the air, thus forming a scale of oxide of iron on the surface. The hotter the iron, the more rapidly will the scale form.

**Ques. What is the character of the oxide of iron?**

**Ans.** It is in the form of scale which does not firmly adhere to the iron, and cannot be welded.

**Ques. Why does it prevent welding?**

**Ans.** Because it lies between the two surfaces to be united and prevents them coming into contact.

**Methods of Preventing Oxidation.**—There are two methods used in welding to prevent the formation of oxide of iron, and

both methods are based upon some means of protecting the hot iron from the oxygen in the air.

Oxidation is prevented by using

1. A reducing fire, or
2. A protective coating.

**Ques. What is a reducing fire?**

Ans. One in which all the oxygen is consumed in the combustion.

**Ques. How is the oxygen completely consumed in practice?**

Ans. By having a closed thick bed of fire for the air to pass through before coming in contact with the iron and by maintaining a moderate blast.

Care should be used to regulate the air supply so that there will be just enough and no more, otherwise air will be blown through and cause oxidation.

**Ques. What is a protective coating?**

Ans. A substance containing no oxygen, which is applied to the heated metal, and which possesses certain qualities which prevent oxidation.

**Ques. What is the usual name for a protecting coating?**

Ans. *Flux*.

**Fluxes.**—These require considerable care in their preparation. Although their use in greater or less quantity has generally no effect on the composition of the metal, their defective manufacture tends to produce inconvenience when they are used, and in consequence, the bad execution of the weld. The



cleaning fluxes for the various metals are most conveniently used in powdered form.

The usual composition of fluxes for the various metals are as follows:

**Cast Iron.**—Equal parts of carbonate and bicarbonate of soda to which is added 10 to 15 per cent. of borax and 5 per cent. of precipitated silica. Ordinary table salt may also be used.

**Ques. When and how should the cast iron flux be used?**

**Ans.** Only when the metal does not run freely, and then only sparingly.

**Ques. What is the effect of too much cast iron flux?**

**Ans.** It causes the metal to harden so that it cannot be drilled or machined.

**Steel.**—Borax, boracic acid, sodium chloride (salt).

**Ques. When should the steel flux be used.**

**Ans.** Only when the metal will not run.

**Mild Steel and Wrought Iron.**—Same as for steel, used sparingly or not at all.

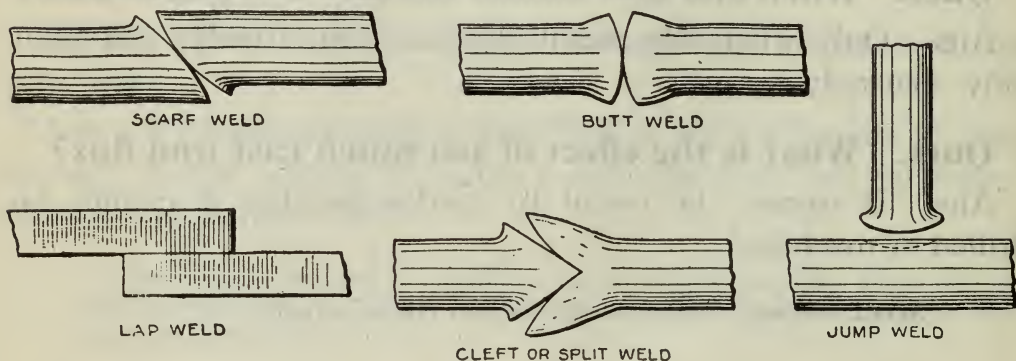
**Copper, Brass, and Bronze.**—Same as above. When used for brass make a paste with a little water.

**Aluminum.**—Flux consists of: 15% lithium chloride; 45% potassium; 30% sodium; 7% potassium fluoride; 3% bisulphate of potassium. Another flux for aluminum is plain borax.

**Various Welds.**—There are many ways in which the joint between two pieces to be welded can be made, and the selection of the method to be used is made with reference to the use of the finished object, the strains it is to resist, and the equipment for making the weld.

The following are the principal kinds of weld, and are described under the accompanying cuts. These are classified according to the way the ends are formed prior to making the weld, as

1. Scarf weld;
2. Butt weld;
3. Lap weld;



FIGS. 4,478 to 4,482.—Various welds. Fig. 4,478, **scarf weld**. In this weld the two pieces are chamfered, that is beveled. If the iron be of uniform thickness it is first upset at the point where the weld is to be made to make it a little thicker, then it is scarfed. To scarf, the upset end is thinned down, generally with the peen of the hammer, drawing it out thin at the point and crowding the metal together at the stick. The faces to be welded are given a crown shape to facilitate squeezing out of the slag as the weld is closed. Fig. 4,479, **butt weld**. This is an end to end weld. Usually the two pieces are upset a little at first, and then ends welded together. They are hammered on end to bring them together, and as this tends to upset the pieces some more, they are drawn out to the required size after the weld has been made. In preparing the ends, the surfaces to be welded are made convex as in the scarf weld, in order to allow the slag to work out. Fig. 4,480, **lap weld**: a weld in which the faces of the two pieces overlap. When the faces are not crowned or rounded care should be taken to begin hammering at the center and work outward to force out all the slag. Fig. 4,481, **cleft or split weld**: a "tongue and groove" form of weld. One of the pieces after upsetting on the end to gain width, is split in the center making a V shaped groove; the other piece is chamfered on both sides bringing it to a point to form a V tongue to fit the groove. In welding the two pieces they are "stuck" together by hammering on the end, and then on the sides of the groove piece to close the weld. The V groove should not have straight sides but slightly rounded as shown so that the slag may be forced out in closing the weld. Fig. 4,482, **jump weld**. A weld formed by bringing the ends of a bar together and jumping them upon the anvil, or with a heavy hammer.

4. Cleft or split weld.
5. Jump weld;
6. Glut weld.



In addition to these there are two processes, known as

1. Fagoting;
2. Building up.

It will be noticed from the illustration of the various weld that *the surfaces are in most cases rounded or curved*. This is done so that when the heated ends are brought together they will unite first in the center. Any slag or dirt which may have adhered to the heated surfaces *will then be forced out as the welding proceeds from the center outward*.

When making a lap weld, the hammering should begin at the center in order to work all the slag out, as the faces in this case are not rounded.

### Ques. What is fagoting?

Ans. This operation consists in assembling a quantity of

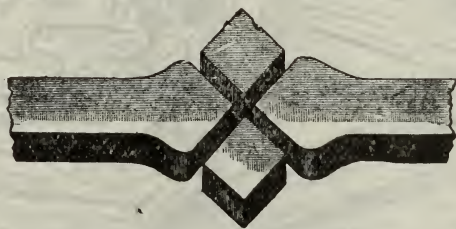


FIG. 4,483, *Glut weld*. A weld in which the ends of the two parts are tapered down, and the angles filled with wedges of iron, the whole being welded together while checking the length with a trammel, excess material being subsequently cut away. This type of weld is generally used in repair work where it is necessary to maintain unchanged the length of the broken part.

iron junk such as old bolts, pieces of chain, turnings, and other scrap iron, and forging the mass into a billet or slab.

The various articles after being carefully assembled into a firm rectangular pile, usually built up on a flat iron base, is heated in a furnace and then welded under a steam hammer.

### Ques. What is "building up"?

Ans. The process of making a multi-piece forging.

That is, a forging built up out of several pieces forged to the approximate shape, and then welded together.

**Forge Fuels.**—Several kinds of fuel, such as, charcoal, coal, coke, and gas are used for heating metal in welding. Perhaps

bituminous coal is mostly used, though for general work coke is considered the best.

**Ques.** What kind of bituminous coal or coke is most desirable?

**Ans.** A grade containing the least percentage of sulphur.

The effect of sulphur is to make iron brittle while hot.

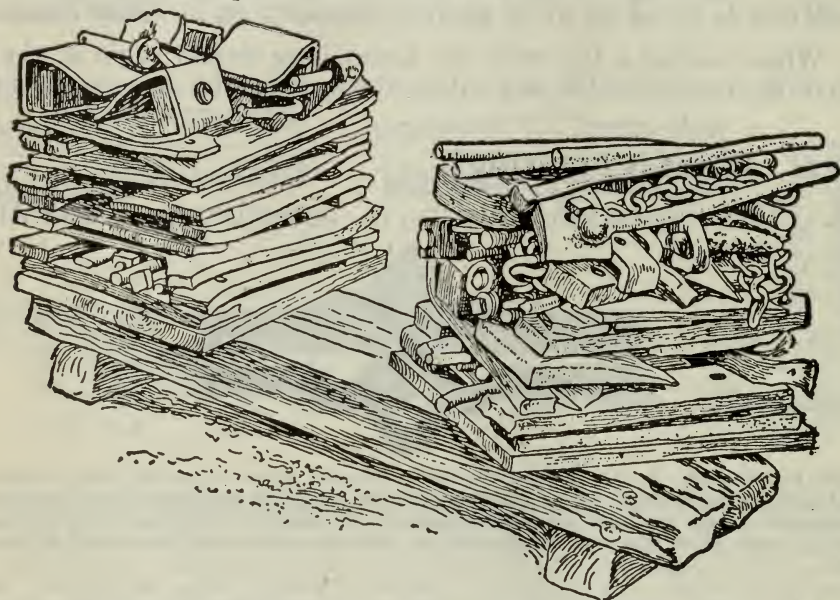


FIG. 4,484.—**Fagoting.** When a quantity of wrought iron in small pieces, such as scrap iron, turnings, etc., is welded up into a *slab* or *billet*, the operation is called *fagoting*. For this, a flat piece of iron, generally fagoted up of small pieces, is laid on a board and the pieces of scrap iron piled on top of this, making a firm rectangular pile with large pieces around the outside and small pieces in the center, or the flat piece on the board may be omitted. It is then heated in a furnace and welded under a steam or a machine hammer.

**Ques.** What difficulty is encountered with anthracite coal?

**Ans.** There is trouble in getting a hot enough fire, especially on a small forge.

**Ques.** What substances should not be in the fuel or fire?

**Ans.** Lead, sulphur, brass or bronze.



**Systems of Welding.**—Welding is and has long been a matter of great practical importance, chiefly in the manufacture of iron and steel, and of the various tools, utensils and implements of those metals. Iron has the valuable property of continuing in a kind of pasty condition through quite a wide range of temperature, below its melting point, and this is a circumstance highly favorable to the process of welding. Most metals,

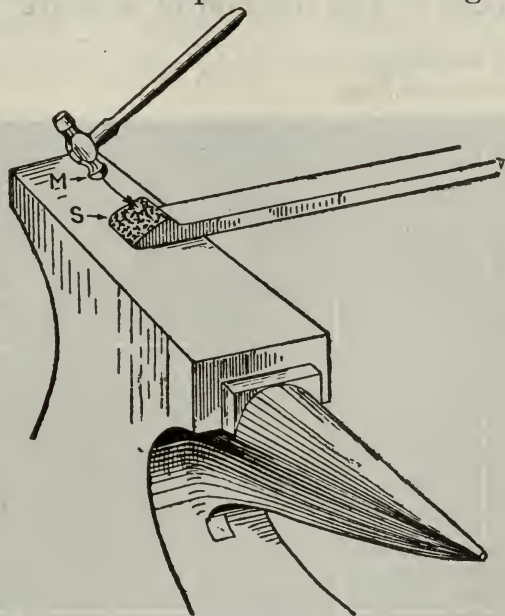


FIG. 4,485.—Making a scarf for a scarf weld. To do this, the upset end is thinned down, generally with the peen of the hammer, drawing it out thin at the point and crowding the metal together at the stock by drawing the hammer as shown at M. The faces to be welded should be rounded as shown at S, so that the pieces first come in contact at the center, in order to give the slag and impurities an opportunity to squeeze out as the weld is being closed.

however, pass quickly, when sufficiently heated, from a solid to a liquid condition, and with such welding is more difficult.

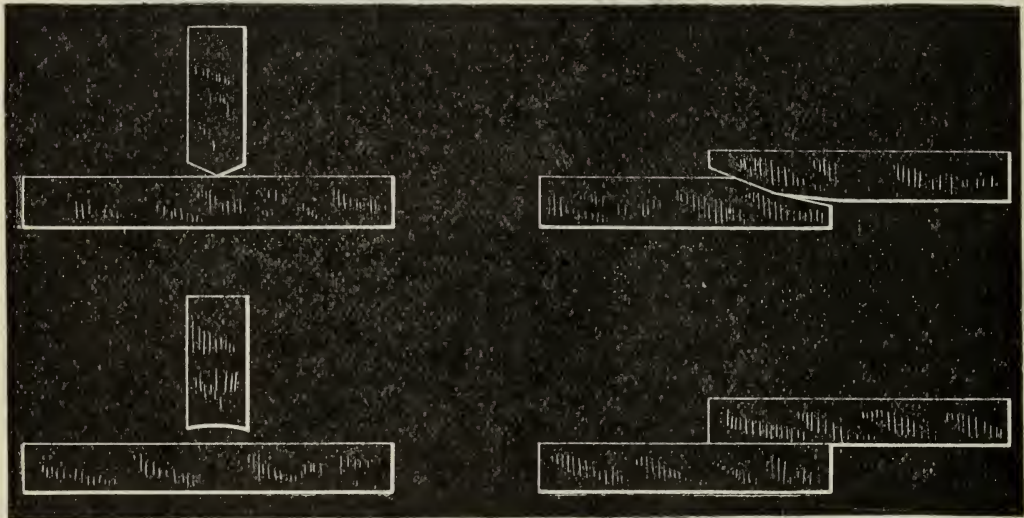
The term welding is more generally used when the junction of the pieces is effected without the actual fusing point of the metal having been reached. Sheets of lead have sometimes been united together by fusing the metal with a blow pipe along the two edges in contact with each other, and this has been called autogenous soldering, or burning if the heating were done with a hot iron.

According to Percy, "the difference between welding and autogenous soldering is only one of degree. The term welding is also used in speaking of the uniting of articles not metallic. Most metals when in the form of powder can be consolidated or welded into a perfectly homogeneous mass by sufficient pressure, without the aid of heat. The same is true of various non-metallic substances, such as graphite, coal, and probably many others.

The various systems of welding may be classified:

1. With respect to the method of working, as

1. Hand welding;
2. Machine welding.



FIGS. 4,486 and 4,487.—Correct shapes for jump and lap welds.

FIG. 4,488 and 4,489.—Incorrect shapes for jump and lap welds.

2. With respect to the treatment of the metal, as

1. By hammering;
2. By fusing (autogenous).

3. With respect to the method of heating, as

1. By forge fire;
2. By blow pipe;
3. By combustible mixture;
4. By *electricity*.



**Ques. Define blow pipe welding.**

Ans. It consists in uniting the metal pieces by means of a flame of appropriate temperature with the addition of metal of the same composition, the joint thus obtained is called autogenous.

**Ques. What is a blow pipe?**

Ans. An instrument in which the flames are produced and projected on the metallic parts to be welded.

**Ques. What is the character of the flames produced by the blow pipe?**

Ans. They are of unusually high temperature.

**Ques. What kinds of fuel are used in the blow pipe?**

Ans. First oxy-hydrogen was used, then oxy-acetylene, and later, oxygen and coal gas, and oxygen and benzol, etc.

**Ques. What is the characteristic of autogenous welding with the blow pipe?**

Ans. It looks easy, but isn't, and an inexperienced workman may produce a joint of perfect appearance, though defective under the surface.

**Ques. What are the features of the oxy-hydrogen and the oxy-acetylene flames?**

Ans. The temperature of the oxy-hydrogen flame is approximately 4,000° Fahr., and the oxy-acetylene flame, 6,300°, giving with the latter flame about five times greater number of B. t. u. per cu. ft., than with the oxy-hydrogen flame.

**Ques. How is the oxy-acetylene torch adjusted?**

Ans. Before lighting the torch, the regulator on the oxygen tank should be set to give the proper pressure. The average

pressures used are, acetylene, 1 to 8 lbs.; oxygen, 2 to 20 lbs., corresponding to a range of work from  $\frac{1}{32}$ " to  $1\frac{1}{2}$ " in thicknesses. For greater thicknesses two torches may be used, or preheating of the parts resorted to. The acetylene is lighted first, the regulator being adjusted to the working pressure so that there is a fairly strong flame. The full working pressure of the oxygen is then turned on, after which the pressure is slightly varied by regulation until the two cores which appear in the inner flame at first are merged into one smaller core, giving the proper welding flame.

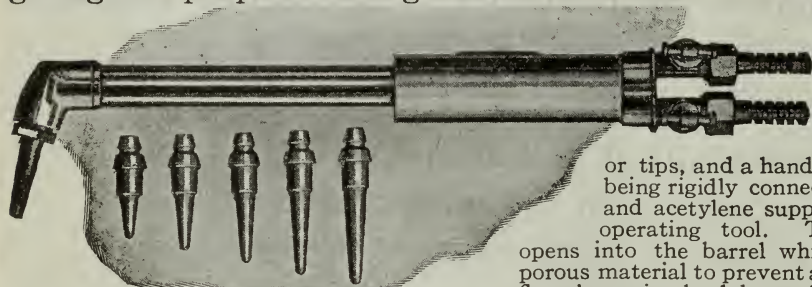


FIG. 4,490.—Davis-Bournonville oxy-acetylene blow-pipe, or "torch." It consists of a head piece for receiving the mixing nozzles

or tips, and a handle or barrel, the two being rigidly connected by the oxygen and acetylene supply pipes to form the operating tool. The acetylene pipe opens into the barrel which is packed with porous material to prevent any possibility of the flame's passing back beyond this point. Inter-

changeable "gas-proportioning and mixing nozzles" of varying capacity are provided, adapting the torch to a large range of work. The mixing of the two gases takes place within these interchangeable tips, each size tip providing a prescribed volume of gases but always in definite proportions which closely approximate the exact theoretical proportions necessary for the combustion reaction, without any excess of either gas, thus providing a neutral flame, or, one to which is fed no excess of either acetylene or oxygen which might change the properties of the metal operated upon. Both gases being admitted to the mixing chamber at appreciable pressure, and at right angles to each other, the maximum of molecular contact of the two gases is secured. The working pressure of both gases are controlled by regulators on the tanks. The type of torch shown, the "positive mixture torch," is for light, medium or heavy welding.

**Ques. How is the torch handled in autogenous weld?**

**Ans.** The torch should be given a rotary motion, accompanied by a slight upward and forward movement with each rotation.

This movement assists in blending the metal and reduces the liability of local overheating. It is desirable to keep the metal surrounding the spot operated upon to a fairly high temperature to prevent excessive conduction of heat away from this spot.

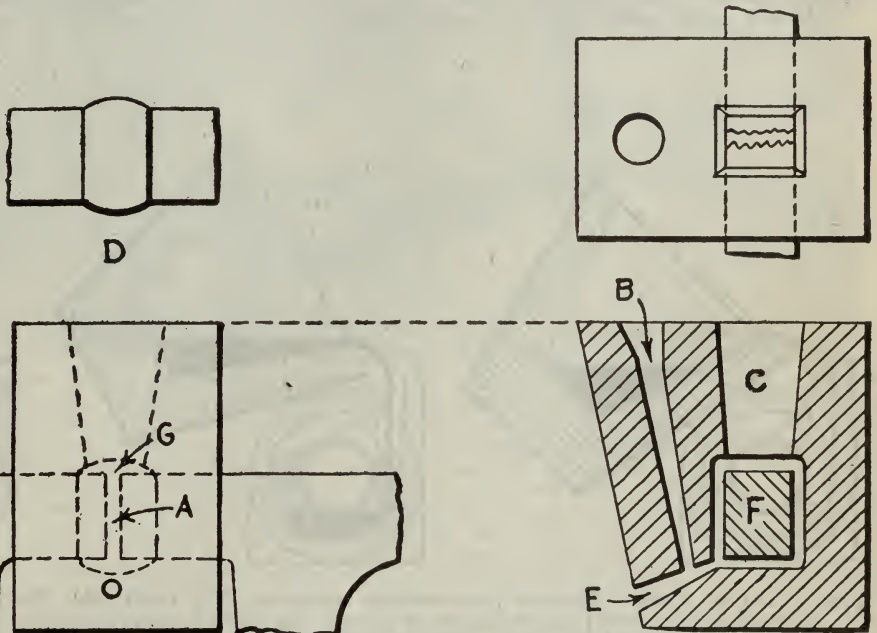
**Ques. What should be done when fusion occurs?**

**Ans.** New metal should be added from a "weld rod" of suitable composition.

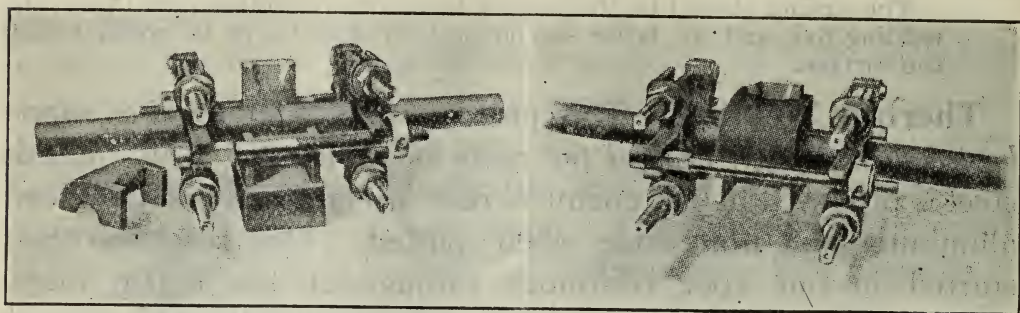


The surface should be thoroughly fused before adding metal from the welding rod, and the latter should be held close to, or in contact with the surface.

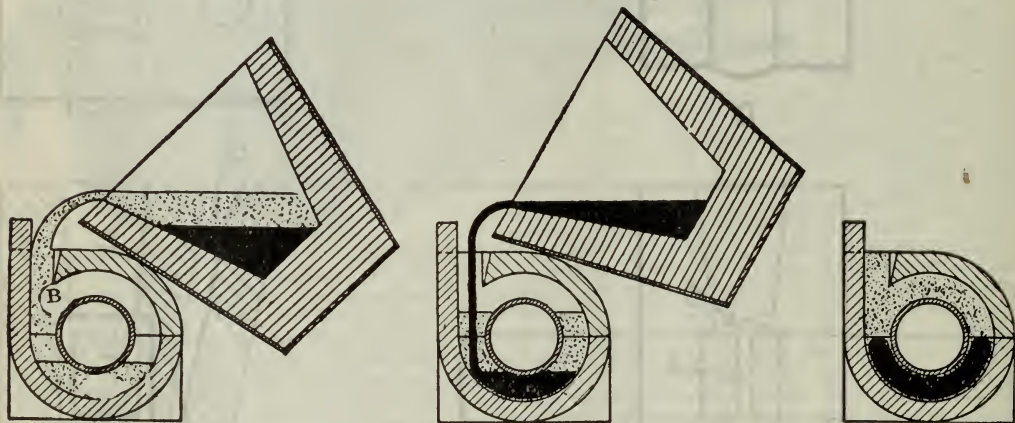
**Thermit Welding.**—This process consists in *pouring super-heated thermit steel around the parts to be united*. This thermit steel is produced by the chemical reaction between finely divided aluminum and iron oxide when ignited. This reaction when started in one spot continues throughout the entire mass, without the supply of heat or power from outside and produces



FIGS. 4,491 to 4,493.—Mould for thermit welding of locomotive frame that has been broken between the pedestals at A. The mould surrounding the broken part should be so arranged that the molten thermit will run through a gate to the lowest part of the mould and rise through into a large riser. In the mould here shown the thermit is poured through gate B, and rises into space C, after passing through and between the ends of frame F. The mould must allow for a reinforcing band or collar of thermit steel to be cast around the ends to be welded. Space G, for forming this collar, and the opening between the frame ends must be filled before ramming up the mould. Yellow wax is ordinarily used for this purpose. The shape of this band or collar should be as indicated by the view of the completed weld at D. The thickest part is directly over the fracture and the band overlaps the edges of the break at least one inch. Pattern for the riser, pouring and heating gates can be made of wood. The riser C should be quite large because the steel that first enters the mould is chilled somewhat by coming into contact with the metal, even when pre-heated. This chilling effect is overcome by using enough thermit steel to force the chilled portion up into the riser and replacing it by metal which has practically the full temperature received during reaction. The mould must be of a refractory material owing to the intense heat. When the mould and box are filled and tamped, the wooden runner and riser patterns are withdrawn. The mould is then ready for pre-heating and the drying operation, which causes the wax matrix to melt and run out.



FIGS. 4,492 and 4,493.—Thermit pipe clamps and mould. Fig. 4,492, pipes held in clamps. Mould partly assembled for thermit welding. Fig. 4,493, mould fully assembled ready for weld.



FIGS. 4,494 to 4,496.—Thermit pipe welding operation. Fig. 4,494, slag flowing into mould and coating inside of pipe and inside of mould. Fig. 4,495, slag in mould and steel following, displacing slag in bottom part. Fig. 4,496, both slag and steel in mould but steel separated from pipe and mould by film of slag. In making a butt to butt thermit pipe weld, the pipe ends are first faced very accurately and are then held tightly together by means of clamps. A cast iron mould is then placed around the pipe ends and the proper amount of thermit ignited in a small flat bottom crucible or ladle. As soon as the thermit reaction is over (about  $\frac{1}{2}$  minute), the contents of the crucible are poured into the cast iron mould. The liquid alumina or slag which floats on top of the molten mass in the crucible, naturally goes into the mould first and covers the inside of the mold and the outside of the pipes with a protective coating which prevents the superheated liquid steel, which flows in afterwards coming in contact with either. The heat of the entire mass, however, serves to bring the pipe ends up to a welding temperature at which time they are squeezed together by means of the clamps and a butt weld effected. The entire thermit mass can then be knocked away from the pipes and nothing will stick to either the pipe or the mould. A slight upset will be observed on the outside of the welded pipe but the inside diameter is in no way affected. The necessary apparatus, consisting of the pipe facing machine, pipe clamps, crucible and mould are light and portable and can be carried to any point where work is to be done. As no outside power is required, the welding can be executed wherever the pipes are laid. It has been found in practice that two men, one facing the pipe with the pipe facing machine and the other doing the welding, can complete a weld inside of ten minutes and make from 40 to 50 finished pipe welds per day.



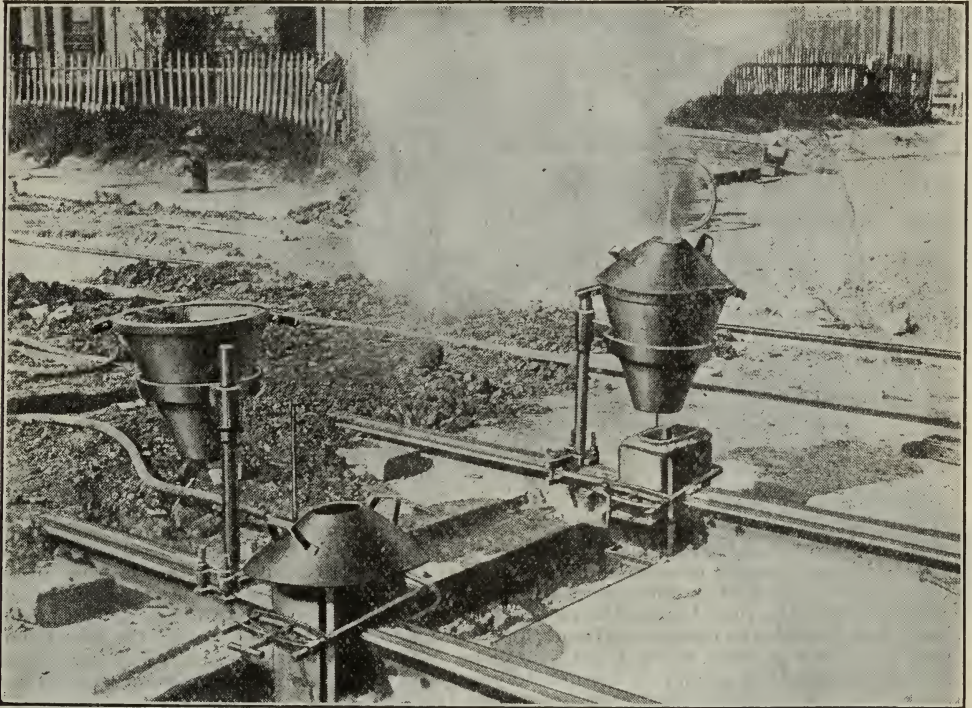
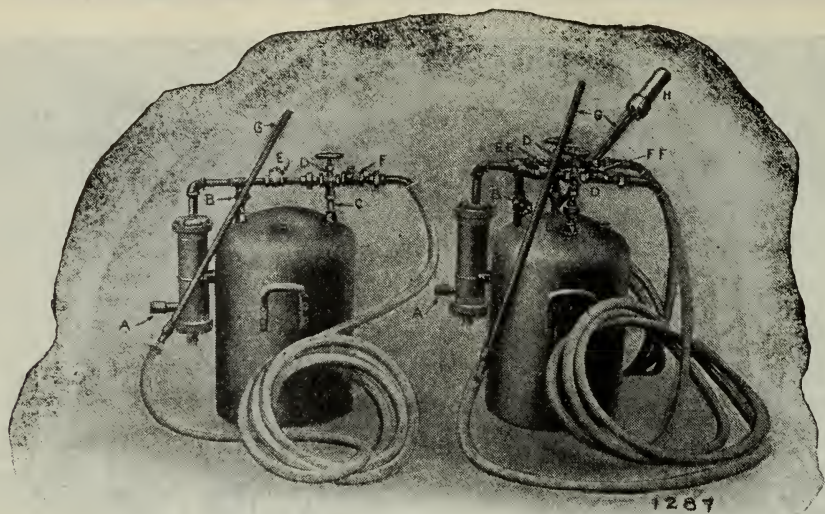


FIG. 4,497.—Open mould and crucible in position for making Clark thermit rail joint. In its original form the Clark joint consisted of a combination of splice bar and thermit steel, it being Mr. Clark's opinion that the head of the rail could be supported by using plates that would come under the ball of the rail. Furthermore, in order to hold the rail rigid, he considered it important that there should be no play in the bolts, so the holes in the plates and rails were drilled round and machine bolts used after reaming for a drive fit. In order to keep the bolts and plates from working loose, and to afford bonding between the rails, a thermit steel shoe was cast around the base. In practice, the rails and splice bars are drilled with holes  $\frac{1}{16}$  of an inch less in diameter than the bolt to be used. The splice bar is then applied in the ordinary way and held in place by a couple of temporary bolts, a drift pin being driven into one hole each side of the joint to keep the rails in position. The remaining holes are then reamed with straight end cutting reamers, after which the machined bolts are driven and tightened up in the usual manner. After pre-heating the rail ends, the thermit steel is run into an open mould surrounding the lower part of the rails. In the latest type of Clark joint, rivets are substituted for the machined bolts, the riveting being accomplished by a pneumatic riveter mounted on a flat car manipulated by means of a small derrick. A modification of the Clark joint has recently been adopted by the United Railways & Electric Co., of Baltimore. The object of the modification was to obtain a larger weld of the base, and in order to do this, the thermit steel was poured into an enclosed mould box instead of into an open mould and the rail ends were preheated to a red heat with the moulds in place before the thermit charge was ignited. Furthermore the design of the fish plates is somewhat changed, being of special design, one inch thick and 32 inches long and so formed as to fit snugly the carbon of the head and base of the rail. At the same time, they provide a minimum amount of space between the web of the rail and the vertical sides of the fish plates. The channel bars and rails are of the same kind of steel (high carbon) and both are punched at the mill with ten  $\frac{1}{16}$  inch holes, spaced 3 inch centers and beginning 2 inches from the end of the rail. The joint has been applied thus far exclusively to 7 inch girder groove rail weighing 103 pounds per yard. These 7 inch girder sections are undercut by the manufacturers  $\frac{1}{16}$  inch so as to provide a space of  $\frac{1}{8}$  inch at the base when the rail ends are butted. This procedure more effectively enables the thermit steel to weld the rail and fish plates into a solid mass at the joints.

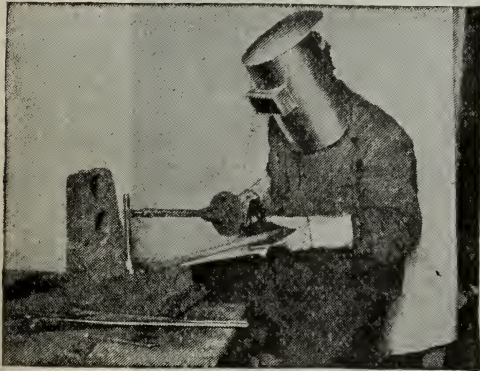




**FIG. 4,498.—Thermit preheater.** *Directions for operating:* The preheater is connected with compressed air supply at A. The air pressure should be at least 15 lbs. per sq. in., but 50 lbs. or more is recommended. Valve B allows the compressed air to flow into the top of the gasoline tank and places the gasoline contained therein under pressure, driving it up through the pipe C into the needle valve D, which regulates the amount of gasoline to be mixed with the compressed air which flows across by pass E around the needle valve and through the check valve F into the hose and so on to the burner. The gasoline and air become mixed together at the needle valve and also through the passage from D to the burner G. To regulate the torch, use valves D and E, which control the gasoline and the flow of compressed air respectively. In starting the torch, place it in position in front of the heating gate of the mould but about 1 inch away from the mould. Place some oily waste or a flame of some kind at the end of the burner pipe, sufficient to keep the burner lighted until it is satisfactorily regulated. Open the air valve B wide and then open the air valve E from one-half to one full turn according to the air pressure used, and then the gasoline valve D about one-half to three-quarter of a turn, this amount also depending upon the air pressure. The burner will take a few minutes to get properly started because the hose and burner pipe are cold, tending to liquify the gasoline vapor. Gradually as the burner pipe becomes hot the flame will become steady. The burner is lighted more easily if at first an excess of gasoline be used, as the flame becomes more steady this excess should be cut down. Unless the mould be intricate so that a strong flame would tend to break it, the air should be increased after the flame is well started, and then the gasoline increased correspondingly. Too much air will tend to extinguish the flame. Too much gasoline will result in liquid gasoline dripping from the end of the burner pipe. If wax has been used as a pattern it should of course have been provided with a vent connecting the heating gate with the riser. Shortly after the burner is started this wax will melt out, running out of the heating gate and coming from the riser in the form of a heavy white vapor. This heavy white vapor should be ignited at the top of the riser and pouring gate to eliminate the fumes from the room and the burner removed from time to time to allow the liquid wax to run out. If the mixture be right there should be no flame at the end of the burner pipe when it is taken away from the mould. If there should be a flame at the burner pipe the air valve and probably the gasoline valve should be opened wider. After the wax is burned out small sheet iron plates should be placed over the riser and over the pouring gates to hold the heat in the mould. If one part heat more rapidly than another, the heat should be regulated by means of these plates, and by shifting the burner pipe in, out and sideways. Toward the end of the preheating, place the burner in the riser and in the pouring gate so that any loose sand may be blown out through the heating gate. In stopping the burner turn off the gasoline valves D and B completely, but leave the air valve E turned on or perhaps open it wider to blow all gasoline vapor out of the burner pipe. Drain the water out of the water separator from time to time through the pet cock at the bottom. All the above applies equally well to kerosene and to gasoline.



superheated liquid steel and superheated liquid slag (aluminum oxide) at a temperature of approximately 5,400° Fahr. From 30 seconds to one minute is sufficient time to bring into reaction almost any amount of thermit. The thermit steel when poured into a mould surrounding the ends of the sections to be united dissolves the metal with which it comes in contact and amalgamates with it to form a single homogeneous mass when cooled. It is necessary, however, in all cases to preheat the sections



FIGS. 4,499 and 4,500.—C and C electric arc welding apparatus. Fig. 4,499, operator with one type of head shield and combination electrode holder for both metallic and graphite electrodes. Fig. 4,500, graphite electrode holder and hand shield.

before pouring the thermit steel, as otherwise they would exert a chilling effect on the incoming metal and prevent successful fusion.

The essential steps of the operation, therefore, are to clean the sections, and remove enough metal to allow for a free flow of thermit steel, then surround them with a mould, preheat by means of a gasoline torch, ignite the thermit in the crucible suspended over the pouring gate of the mould, and then pour the thermit steel.

**Ques.** What is the average composition of thermit steel?

Ans. Carbon, .05 to .1; manganese, .08 to .1; silicin, .09 to .2; sulphur, .03 to .04; phosphorus, .04 to .05; aluminum, .07 to .18.

**Electric Welding.**—By the electric process, all metals and alloys can be welded, and dissimilar metals and alloys united, because the temperature can be maintained or increased while the weld is being made. An ordinary forge fire, involving as it does, the possible inclusion of dirt, irregular heating, difficulty of inspection and control of heat, cannot comply with the best conditions of welding which are:



Fig. 4,501.—Operator using C and C electric arc welding metallic electrode. The electrode itself is melted and supplies the extra metal necessary for welding or building up.

1. The impossibility of introducing foreign matter into the weld.
2. Uniform heating of the area to be welded.
3. Continuous inspection during the process of heating.
4. Early and complete regulation of the heat.

All systems of electric welding are based upon the principle of causing a current of electricity to pass through a high



resistance, thereby generating heat. There are, however, important differences in the manner in which the heat so generated is applied to the welding of metals.

The amount of work done in a given time to force a current through a resistance is

$$\text{watts} = \text{amperes} \times \text{volts}$$

and since by Ohm's law,  $\text{volts} = \text{amperes} \times \text{ohms}$ ,

$$\text{watts} = \text{amperes}^2 \times \text{ohms}$$

or expressed in the usual symbols

$$W = I^2 R$$

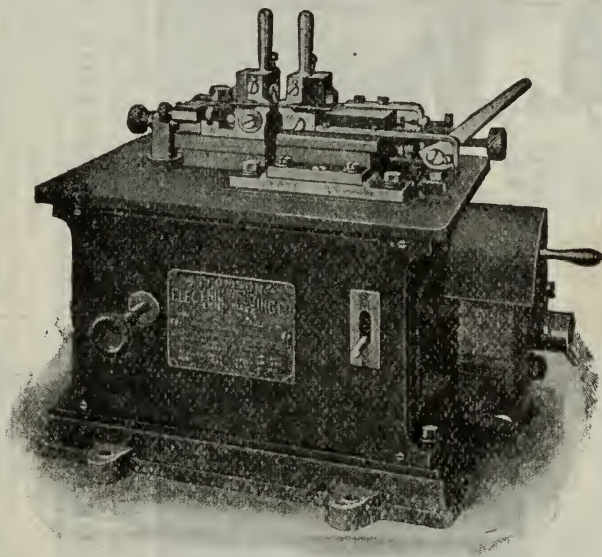
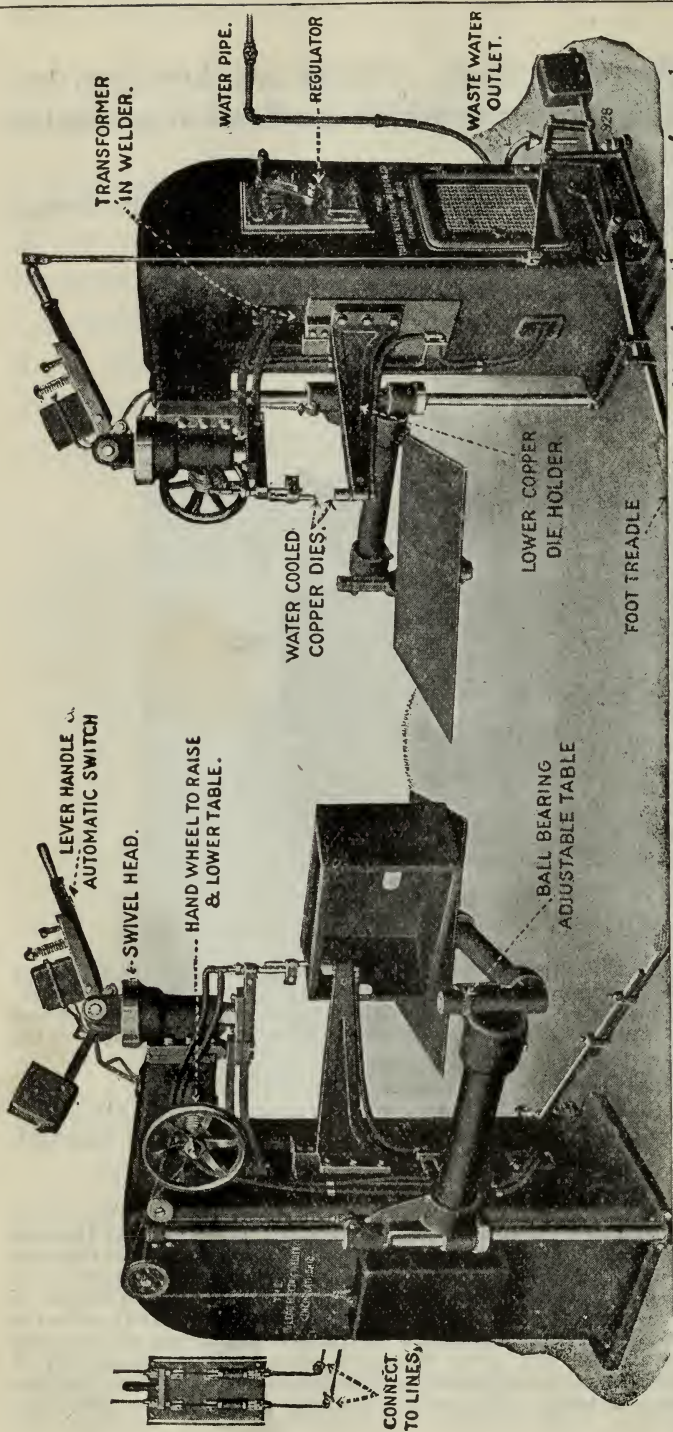


FIG. 4,502.—Thomson welder. Portable, pressure and cut out, mercury slide, with regulator and automatic break switch. Copper wire No. 23 to No. 15 Power 1.5 kw. Time, fraction of second. **To operate**, move lever at right to position shown; hold back levers at center and insert wire; return lever at right to opposite position; press button and the weld is made.

which shows that in order to obtain a considerable heating effect by means of electricity, it is only necessary to send a large current through a conductor of high resistance.

NOTE.—Prof. Elihu Thomson, in 1877, at the Franklin Institute, Philadelphia, while experimenting with induction coils caused the discharge of a Leyden battery to pass through the fine wire coil, which thus became a high pressure primary, while at the same time the ends of the coarse wire coil were brought into light contact. He noticed that these ends were partially welded together, so that it took some little force to separate them. His invention of electric welding was accordingly the outgrowth of this early observation. In 1881, when it was impossible to obtain copper wire in long lengths for dynamo fields, which necessitated the making of frequent joints in a heavy coil, Prof. Thomson discussed the possibility of electrically welding these wires, and in 1885 he constructed a practical electric welding machine for welding small sections of wire and tools. The various methods of electrical welding are here briefly described.



Figs. 4,503 and 4,504.—Views of Toledo, spot welder showing parts. Two wires run to the machine from the source of supply. Connect these to the wires from the welder marked "line." A half-inch water pipe connected to the city water is ample for cooling.

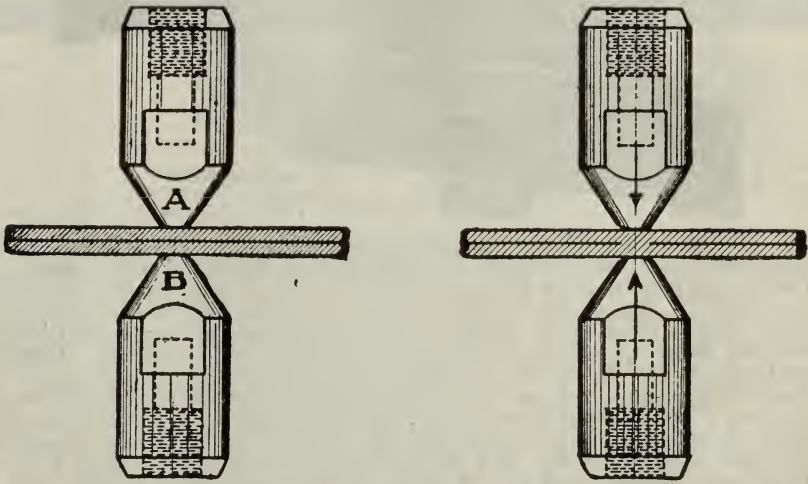
SIZE WIRE TO USE WHEN WELDER IS NOT MORE THAN 150 FEET FROM SOURCE OF POWER

Kw. capacity	Kva. capacity	110 Volt			220 Volt			440 Volt			Standard dynamo to operate welder	Motor generator set to operate welder	
		Wire No.	Fuses amp.	Switch amp.	Wire No.	Fuses amp.	Switch amp.	Wire No.	Fuses amp.	Switch amp.		H.P. of D.C. motor	A.C. dynamo
5	7.5	6	60	60	8	30	30	10	15	15	7.5	7.5	7.5 K.V.A.
10	15	2	150	150	6	75	75	8	40	50	15	15	15
15	20	0	200	200	4	100	100	6	50	50	20	20	20
20	30	000	300	300	2	150	150	6	75	75	30	30	30
35	50	...	...	...	00	250	250	2	125	125	50	50	50

The above is safe carrying capacity for intermittent service, where current is never on more than two to three seconds.



**Thomson Process.**—This method, invented by Elihu Thomson, appears to be capable of being employed with a variety of metal on a very extensive scale. A current of electricity heats the abutting ends of the two objects which are to be welded, these being pressed together by mechanical force, and so arranged with the electric current that there is great and rapid accumulation of heat at the joint, in consequence of the greater relative conductivity of the rest of the circuit. This method of welding in some cases partakes of the nature of autogenous soldering, the pieces of metal being actually fused while uniting;



**FIGS. 4,505 and 4,506.—Spot welding.**—This is the process of joining or fusing together electrically two or more metal sheets or parts without any preparation of stock. Mechanically it is equivalent to riveting, but it is stronger and can be done much more quickly and economically. The principle of spot welding is simple. Two electrodes, or welding points, A and B, fig. 4,505, are brought to bear on the plates where it is desired to make the weld and a heavy current at a low electrical pressure is passed through the electrodes. The metal plates, as they are much poorer conductors of electricity, offer so great a resistance to the flow of current that they heat to a molten state, and then, by applying pressure on the electrodes, the metals are forced together and the weld is made, as shown in fig. 4,506. **Current.** Single phase, alternating current must be used in electric welding. Where two or three phase current is furnished power must be taken from one phase of the poly-phase system. As pressure is reduced in machines by a transformer to a very low voltage, there is no possibility of the operator receiving a shock. **Weldable materials.** Wrought iron and steel are the best materials for electric welding. Rust, scale and dry paint act as insulators and should be removed from steel before welding so that the current may flow freely. Grinding or sand blasting is recommended for this purpose, as pickling causes material to rust very quickly on exposure to the air. Galvanized iron can be welded but the coating must be burned off first, making the operation a trifle slower than with plain sheets. Copper, brass, bronze and aluminum are usually unsatisfactory materials for welding as they are such good conductors of electricity they offer practically no resistance to the flow of current.

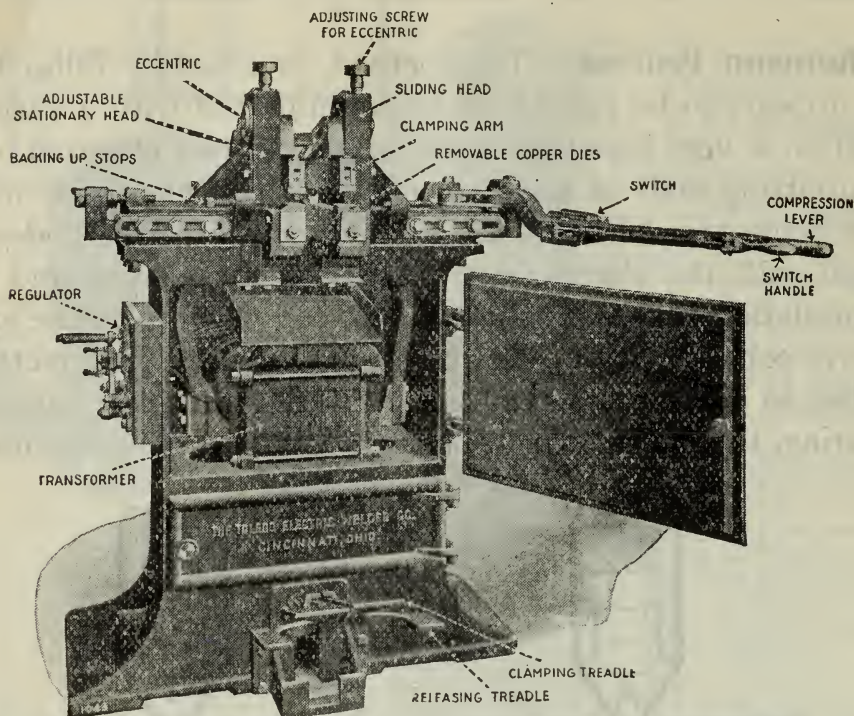
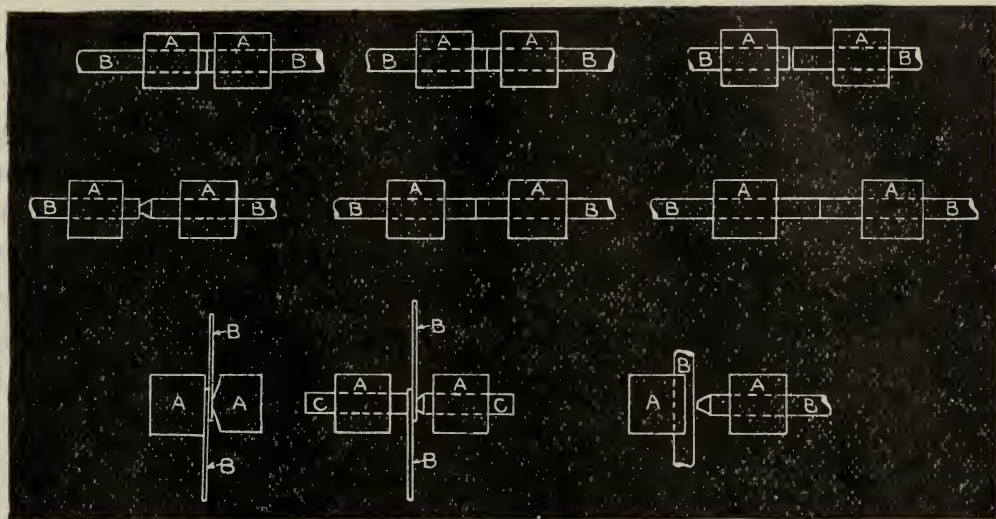


FIG. 4,507.—Toledo butt welder; view showing different parts. There are no auxiliary devices required when installing a welder, except the switch, fuses and water supply. Two wires run to the machine from the source of supply. Connect these to the wires from the welder marked "line." The switch to cut off the current when the machine is not in use and the fuses are usually mounted on the wall. A half-inch water pipe connected to the city water mains will afford an ample supply of water under all conditions. **Instructions for operating:** 1. Set the welder on either a wood or cement foundation and fasten down by lag screws or bolts. If set on wood foundation, the machine should be grounded by connecting a small copper wire from frame of machine to a water or gas pipe. 2. The wiring to the machine should be arranged with fuses and a double pole, single throw switch. 3. The transformer furnished with the machine is located in the base and is used to transform the current from the source of supply (either a dynamo or transformer) to the three to five volts used in the welding operation. The primary coils are connected to the double pole switch at the side of the machine. 4. Rubber tubing is furnished to connect the machine to city water supply and through the dies to the sewer. A globe valve should be inserted ahead of the welder to regulate the flow of water; just enough to keep the dies from becoming excessively heated. The amount of water required for this purpose is small and a  $\frac{1}{2}$  inch feed pipe to the welder will be ample. 5. After connecting the machine and water connections, the machine is ready to operate. Set the regulator handle to the extreme left hand side or No. 1, and the double pole, double throw switch to the left. Place two pieces to be welded in the copper dies, which are set from  $\frac{1}{4}$  in. to 1 in. apart, according to the size stock to be welded. Let the ends of the stock touch each other; then turn on the current by means of the switch. If the stock do not heat rapidly enough, turn regulator handle to the right, or No. 2; if not enough heat be obtained at this point, keep on until point No. 5 is reached. If enough heat be not obtained, throw the double pole switch to the right and the lever handle to No. 1. The maximum current is obtained when the regulator is at the right, or at point No. 5, with the switch in the right hand position. A little experimenting will give the correct heat necessary for getting the best results. Copper, brass, tool steel and all other metals that are deteriorated by high temperatures must be heated quickly and pressed together with sufficient force to push out all the burnt metal from the weld. On flash or upset welding of iron or steel, not more than once the diameter of stock is taken up in the weld. For example, in welding two pieces of  $\frac{1}{2}$  in. round stock, not more than  $\frac{1}{4}$  in. of each piece is taken up by the weld, or a total of  $\frac{1}{2}$  in.

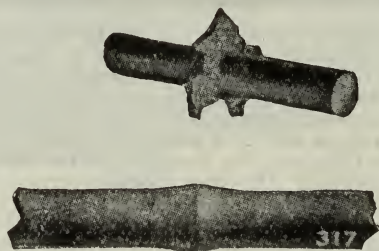




FIGS. 4,508 to 4,516.—General hints on electric welding. **Cast iron** cannot be commercially welded, as it is high in carbon and silicon, and passes suddenly from a crystalline to a fluid condition when brought up to the welding temperature. **Iron or steel.** It is necessary to keep the temperature below the melting point to avoid injury to the metal, and consequently considerable pressure is required to make the weld. The stock should be placed in the dies as shown in fig. 4,508 for a flash weld, and as shown in fig. 4,509 for an upset weld, A representing the dies, and B, the stock to be welded. **High carbon steel** can be welded, but must be annealed after welding to overcome the strains set up by the heat being applied locally at one place. Good commercial results are hard to obtain when the carbon runs as high as point 75 or above, and can only be done by an experienced operator. When below point 25, the operator can always be sure of making a good weld. To weld high carbon steel to low carbon steel, the stock should be clamped in the dies as shown in fig. 4,510, with the low carbon stock extending considerably further out from the dies than the high carbon stock. **Nickel steel.** This welds readily, and a small percentage of nickel materially increases the tensile strength of the metal. **Iron to copper.** These metals can be welded to each other, but it will be found necessary to reduce the cross section of the copper as shown in fig. 4,511. **Copper and brass.** When welding copper and brass the pressure must be less than when welding iron. The metal is allowed to actually fuse or melt at the juncture, and the pressure should only be sufficient to force out the burnt metal. This burnt portion being forced out, accounts for the good results obtained in welding these metals. The current must be cut off the instant the ends of the metal begin to soften. This is done by using an automatic switch which opens at any predetermined point. The sliding head is actuated by either a spring or weight to force the heads together as soon as the metal softens, and this automatically operates the switch. As copper and brass are good conductors of the electric current, a larger volume of current at lower secondary voltage is used and the sliding heads are arranged to move with the least possible friction. The dies should be set apart approximately three times the diameter of the stock for brass and four for copper. See figs 4,512 and 4,513. A represents the dies, and B, the stock to be welded. The welds when properly made will stand the strain of the rolling or drawing process to reduce them to a smaller size. **Spot welding.** To weld two pieces of sheet steel at one small place or spot is called spot welding. For convenience of handling the stock this is usually done in a machine with vertical clamping dies. Where the size and shape of the pieces to be welded will admit, the work can be done in a butt welder equally as well. In this case one of the dies is slightly pointed and the stock welded between the dies as shown in fig. 4,514. Another way is shown by fig. 4,515, where two pieces of copper rod C, one of them slightly pointed, are clamped in the dies A. If galvanized iron is to be welded it will be found necessary to use two pointed dies instead of one flat and one pointed. **Jump welding.** This is for light stock only and the best results are obtained by slightly pointing one of the pieces as shown in fig. 4,516. The other piece is held with a portion extending outside the die, then bring them together, turn on the current and weld quickly.

in other cases, as with iron, nickel, or platinum, the union may take place without fusion, as in ordinary welding.

In electric welding the intensity of the pressure which forces the metallic surfaces together depends on the kind of metal being welded. Copper, brass, tool steel and all other metals that are deteriorated by high temperatures must be heated quickly and pressed together with sufficient force to push out all the burnt metal from the weld. In case of large articles, hydraulic pressure can be used to force their surfaces into contact with each other.



FIGS. 4,517 and 4,518.—Flash weld, and upset weld. **A flash weld** is generally used on stock that is wide and thin; where it is rectangular in shape, and where it is not possible to have the welding faces cut square and true. Also in welding tubing to forgings, or tubing to tubing. In all cases where a small amount of stock is to be taken up in welds, or when it is desired to shear or grind off the fin, a flash weld is made. **Upset welding** is used in all cases where the weld is to be hammered, using the heat generated in the welding. Also for small rods or rings where it is not necessary to have a uniform thickness of stock. On brass or copper a flash weld is made. Three times the diameter of stock between the dies should be allowed on brass and four times on copper, but only once the diameter of stock is actually taken up in the weld.

**Zerner or Electric Blow Pipe Process**—In this method, *an electric arc is drawn between two carbon electrodes*. This arc is then caused to impinge upon the metal surfaces to be welded by means of an electromagnet. The arc is pointed to concentrate the heat, and the metal is fused around its point of contact with the arc. This method is applicable to a rather limited range of small work, such as welding small steel and brass castings, plates, tubes, tanks, etc.



**Bernados Process.**—*The metal to be welded is connected to one pole of an electric circuit. When iron or steel is being welded, for which a high temperature is needed, the metal is made the positive and the carbon the negative. In the case of lead, or any metal requiring a comparatively low temperature, this polarity is reversed.*

The supply of current is generally furnished by a dynamo, and a series regulating resistance is used for steadying the arc and adjusting the amount of current. This process is of very considerable value in the filling up of blow holes, cracks, etc., in steel castings.

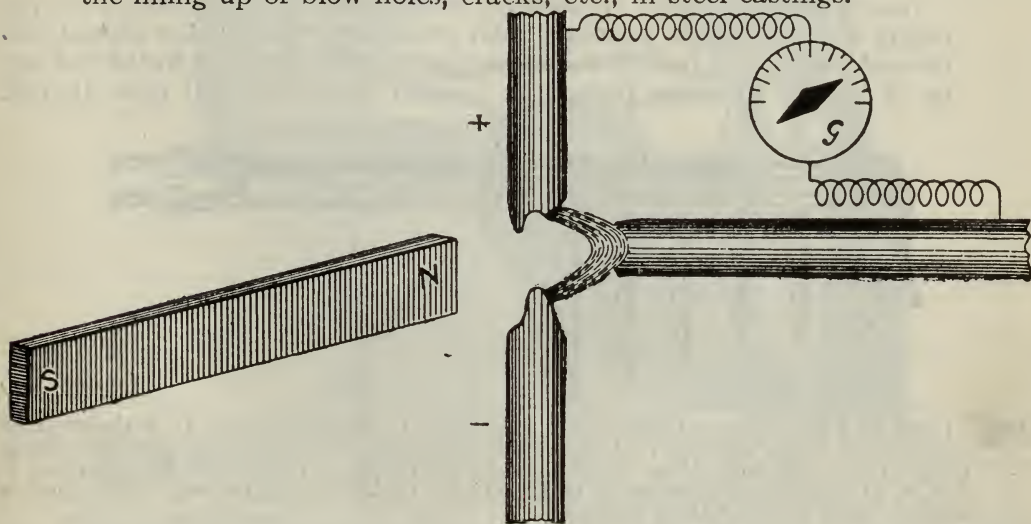
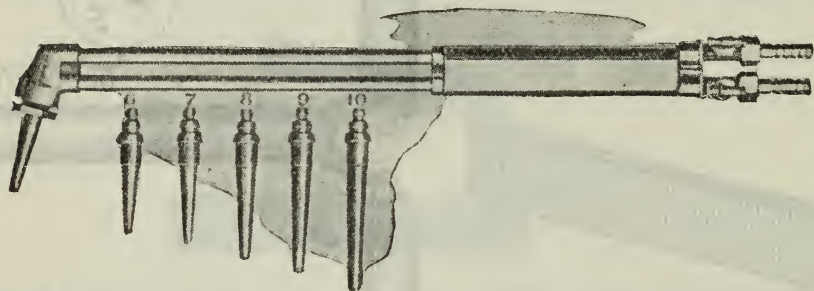


FIG. 4,519.—Diagram illustrating the electric blow pipe. In order to overcome the difficulty in the Bernados process of the extreme concentration of heat in the portion of the metal which forms one pole of the arc, apparatus has been devised by Werdmann, Zerener, and others, in which phenomenon of the magnetic blow pipe is practically applied. It is well known that *when a magnet or electromagnet is brought near an electric arc, the latter is deflected in trying to set itself in a direction at right angles to its length and to the magnetic lines of force*, as shown in the diagram. The apparatus usually consists of two carbon rods, to each of which one pole of the electric circuit is connected, and an electromagnet energized by a shunt current is suspended over the arc. When the current is turned on a strong magnetic field is formed which produces a blow lamp effect on the arc, and by placing the article to be welded or brazed at varying distances from this flame, the heat can be regulated. The various sizes of lamp of the Zerener type require from 25 to 75 amperes or more, at about 70 volts. The Coffin type of lamp consists of two eccentric carbons attached to a suitable handle. Between the two is the iron core of an electromagnet, the winding of which is connected in series with the arc. This apparatus is another form of the electric blow pipe. A different type of electric blow pipe apparatus is that devised by De Tunzelmann. In this there is no magnet or electromagnet, but the two carbon rods are held in a frame nearly at right angles to one another. The feed of the carbons is adjustable, and special carbons are used containing a percentage of metallic oxide. A long arc in the form of a horizontal flame is easily maintained. This apparatus is particularly useful for brazing, and for the welding of thin steel strip. Various sizes of the apparatus are made for currents varying from 25 amperes to 400 amperes or more, at about 55 to 70 volts.

The carbon, which is held in a suitable holder, with hand shield, is placed in contact with the metal and withdrawn a short distance, the arc following and being maintained generally from  $\frac{3}{4}$  to  $1\frac{1}{2}$  inches in length. By withdrawing the carbon from the work the current ceases. The arc is moved about until the whole surface on which it plays becomes molten, and where necessary additional metal in the form of rod or small pieces is melted in.

Some excellent work has also been done by this process in the way of making longitudinal seams in boats and barrels of thin plate steel. Small pieces of steel scrap are laid over the abutting edges, and by means of the arc are raised to a welding temperature. It is usual to complete the work by hammering.

Another considerable application is the making of a joint by simply fusing the two edges together. An example of this is the dished end of steel barrels. A further important application has been in the welding on of flanges to steam pipes, the manufacture of special tube fittings,



FIGS. 4,520 to 4,525.—Davis-Bournonville long style C welding torch. It is designed for medium and heavy welding, for boiler repairs and for general shop work requiring a strong, rugged torch. Weight, 2 lbs. Length, over-all, 20 inches. Fitted with five tips, Nos. 6, 7, 8, 9, 10, using oxygen pressures of 12, 14, 16, 18, 20 lbs. respectively. This torch is used on metal from  $\frac{1}{4}$ " thick upward.

such as tees, elbows, sockets and bends, and in making large pipes out of steel by welding the longitudinal seam.

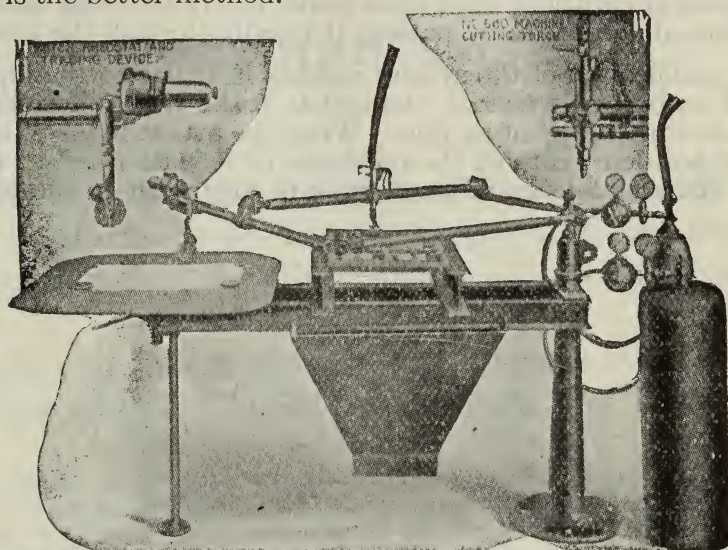
The *Bernardos* process is of much value in the repair of castings, as it often enables valuable castings which have some small defect to be made quite sound, thereby saving the whole of the cost of labor expended on them. Generators employed for this system are usually compound wound, having a pressure of from 70 to 85 volts.

**Slavianoff or Modified Bernardos Process.**—In this method, *an electrode which is of the same material as the metal to be welded is used instead of a carbon electrode.*—This change is made so as to prevent the hard welds which sometimes result with the Bernardos or Zerener processes, owing, principally, to the transfer



of carbon from the electrode to the weld. A direct current of about 130 amperes and 24 to 26 volts across the arc is adapted for this process.

The arc is not a long one, as in the Bernardos process, the length being only about  $\frac{1}{8}$  or  $\frac{3}{16}$  inch. This process is not as rapid as the Bernardos, but, if subsequent machinery be required or the material be thin, it is the better method.



FIGS. 4,526 to 4,528.—Davis-Bournonville oxygraph; fig. 4,526, a motor rheostat and tracing device; fig. 4,527, cutting torch; fig. 4,528, oxygraph. This machine will cut steel up to six inches in thickness, at the rate of three to twelve inches per minute, a larger size cutting up to 18" in thickness, and another modification, for circle or straight line cutting only, taking in armor plate up to 24" thick. It has an electrically propelled rolling tracer, which is guided along the lines of a drawing, and the cutting flame will make an exact reproduction in one machine of one-half the dimensions, in another of the exact size of drawing. Steel can be cleanly and smoothly cut at short angles and of any irregular shape. The machine is desirable for die makers, blanking out connecting rods, crank shafts, etc. The motor can be connected to a lighting circuit or to a battery. The automatic uninterrupted feed adapts the machine to quantity work, and to all work where accuracy, as well as smoothness of cutting surfaces, or roughing out close to the required finished surface are essential.

**Hoho and Lagrange Process.**—The apparatus used usually consists of a lead-lined wooden tank, filled with an electrolyte of any conducting liquid solution, either alkaline or acid.

The positive pole of a dynamo, giving usually about 200 volts, is connected directly to the inner leaden sheath. The bar of steel or other metal to be heated, is connected to the negative pole and plunged into the bath.

Directly the bar touches the liquid, electrolysis is set up and the water splits up into its component parts, the oxygen going to the leaden sheath and the hydrogen clinging to the metal, forming a complete gaseous envelope around it, and thus preventing the metal actually touching the solution. Here again, a high resistance to the flow of current is offered by the hydrogen sheath, and the electric energy is transformed into heat.

It is difficult with this process to control the temperature, but some practical applications have been made, one of the most successful being the annealing of wire by passing it rapidly through the solution.

A modification of the system consists in replacing the liquid by powdered carbon or charcoal, the article to be heated forming one pole, and the carbon, the other pole. When the article touches, or is inserted in the powdered carbon, the resistance of the latter and its poor contact with the metal generate heat which is conducted to the object.



## CHAPTER LXXXV

## ELECTROLYSIS

This term signifies the decomposition of a chemical compound in solution, called the *electrolyte*, into its constituent elements, called *ions*, by the passage of an electric current through it.

There are two kinds of ions: 1. The electro-positive ions called *cations* and, 2. The electro-negative ions called *anions*.

The former appear at the cathode and the latter at the anode. The current may be regarded as being carried through the electrolyte by the ions; since an ion is capable of carrying a fixed charge only of + or - electricity, any increase in the current strength necessitates an increase in the number of ions.

An experiment illustrating electrolysis is shown in fig. 4,529. The electrolytic treatment of copper is one of the most important electro-metallurgical processes. Copper thus obtained possesses a purity unattainable by any other means. The electrolytic cell used for this purpose is known as a *copper bath*.

**Industrial Electrolysis.**—A few applications of electrolysis in various manufacturing enterprises is here given briefly, yet with sufficient detail to give a clear understanding of the principles underlying the use of electricity or electrolysis in the following industries: Alkali and bleach; aluminum; bullion refining, chlorates; hypochlorites, ozone, organic chemicals; oxygen and hydrogen; sodium and potassium; also the wet methods for extracting copper, nickel, tin, and zinc.

**Alkali and Bleach.**—The term alkali denotes, in the chemical industry, sodium or potassium hydrate or carbonate, while bleach denotes hypochlorite of lime.

When an electric current is passed through a solution of sodium chloride in water, using electrodes which are not attacked by the chloride or by free chlorine, the chloride is split up into its constituent parts, the metal sodium is separated at the cathode, while the gas chlorine

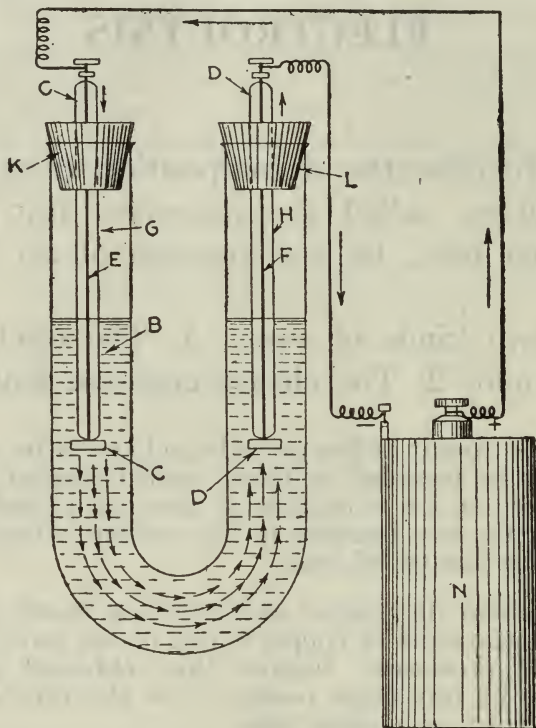


FIG. 4,529.—Electrolysis of copper. Fill the U shaped glass tube shown above, with a solution B, made by dissolving some crystals of copper sulphate or bluestone. Immerse in the solution two platinum electrodes C and D, attached to the copper wires E and F, sealed in the glass tube G and H, which are held in the tube openings by loosely fitting rubber corks K and L. Attach the positive pole of the battery N, to the terminal of the electrode C, and the negative pole of the battery to the upper terminal of the electrode D. The electric current from the battery will then pass from the platinum *anode* C, through the copper sulphate electrolyte B, to the platinum *cathode* D, thence to the negative terminal of the battery. The passage of the current through the electrolyte will result in the liberation of the constituent ions of the latter, oxygen gas being liberated at the anode C, metallic copper deposited on the cathode D, and the copper sulphate solution B, changed to sulphuric acid. Allow this action to continue until all the copper has been taken from the electrolyte and deposited on the cathode, completely plating the latter with metallic copper, then reverse the current through the electrolyte by changing the connections at the battery terminals. The copper plated cathode D, will now become a copper anode, with the platinum plate C, for a cathode, and electrolytic action of the current will return the copper deposit on D to the electrolyte, and transfer it to the surface of the platinum plate C.



forms in minute bubbles at the surface of the anode and rises to the surface of the liquid in the cell.

The metal sodium, however, has a great affinity for the hydroxyl constituent of water, and it at once enters into union with this, and produces sodium hydrate and hydrogen gas at the surface of the cathode. These changes are the basis of all the patented processes and cells for the production of alkalies and chlorine products by electrolysis. Both chlorine gas and sodium hydrate are, however, very active chemicals, and the various electrolytic cells and processes for their production differ considerably in the details of cell construction and in the means taken to prevent the sodium hydrate formed at the cathode and the chlorine formed at the anode, entering into further reactions within the cell, or from sharing in the electrolysis in the place of the sodium chloride which it is desired to split up.

**Aluminum.**—This is the lightest metal known, with the exception of magnesium, and until the year 1891, pure aluminum was produced entirely by chemical and metallurgical methods.

The process of aluminum manufacture consists in the electrolysis of a fused mixture of the fluorides of sodium, calcium and aluminum, in which alumina (aluminum oxide) is dissolved. When an electric current is passed through such a mixture of fused salt, using carbon electrodes, aluminum separates as drops of molten metal at the cathode, while oxygen is liberated at the anode and at once unites with it to form carbonic acid gas. The bath is kept in the fused state by the heating action of the current. The action taking place in the electrolytic bath is therefore, virtually, a reduction of the alumina or aluminum oxide by the carbon of the anode; but this reduction would be impossible without the aid of the current to first separate the oxygen and aluminum, which have great affinity one for the other.

The aluminum separated at the cathode is in the molten state and falls to the bottom of the bath, and it is allowed to collect there, being removed at stated intervals, either by a syphon or by tilting. Fresh alumina is fed into the bath at short intervals to replace that which has been decomposed by the current; and the process is, therefore, a continuous one.

The fused salts employed to dissolve the alumina do not undergo any change; but care must be given to the purity of these and of the alumina used for feeding into the bath, in order to obtain high grade aluminum by this process of manufacture, silicon and iron being the most troublesome impurities.

**Bullion Refining.**—In the extraction of gold and silver from their ores, and from old articles of plate and jewelry, the

precious metals are generally obtained alloyed with one another, and with copper as an impurity. The technical name for this product is "bullion."

The general principle of electrolytic bullion refining is to use the alloy of precious metals, or bullion, as an anode in an electrolyte which dissolves only one of the two metals to be separated, and to use a sheet of the pure metal that is being deposited, as cathode.

For silver deposition an acid solution of nitrate is employed as the electrolyte (the Moebius process), while for gold an acid solution of gold chloride is found to yield the best results (the Wohlwill process). In the former case, gold and lead remain undissolved, and collect as

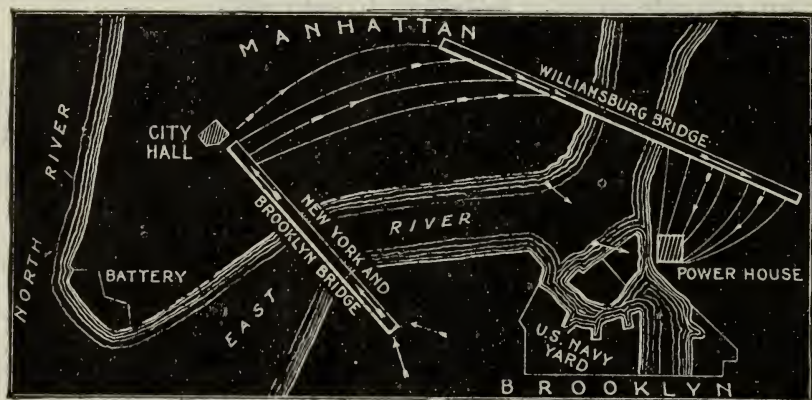


FIG. 4,530.—Electrolysis in lower New York. The figure illustrates current movements as discovered. The power house is located near the navy yard in Brooklyn. A portion of the returning currents, as shown by arrows, flows over the New York and Brooklyn bridge to Manhattan, thence north to Williamsburg bridge via underground mains, subway structures, and other metals, and passes over that bridge back to Brooklyn, thence through mains to rails and negatives, to power house. In this case damage may be expected at three points: 1, where currents leave bridge metals on the Manhattan side; 2, where they leave pipes to enter Williamsburg bridge; 3, where they leave same bridge for pipes in Brooklyn side. When the two bridge structures are connected in Manhattan as proposed, then there will be further changes in the direction of current. Before the Williamsburg bridge was built, these currents recrossed through the river bed, leaving mains all along the docks in the Manhattan side, for the river, and leaving the river for mains or other metals along the docks of the Brooklyn side. Traces of these currents have been found as far north as 23d st., a distance of over two miles from the Brooklyn bridge. Since the Williamsburg bridge has been built, nearly all traces of these currents flowing north of it have disappeared, showing that the mass of metal composing the structure acts as a short circuit or path of lower resistance which carries practically all of the returning currents flowing from Manhattan back to Brooklyn.

a slime or mud on the floor of the vat, while in the latter case silver chloride forms, and collects as an insoluble precipitate in the same manner.

**Chlorates.**—Chlorate of potash or of soda is produced electrolytically by the electrolysis of the corresponding chloride.



The electrolytic and chemical changes which first occur when a solution of sodium or potassium chloride is electrolyzed by the aid of electrodes not acted on by the products of the electrolytic decomposition, have been already described under *Alkali and Bleach*.

**Hypochlorites.**—Sodium hypochlorite is a compound whose molecule contains two atoms of oxygen less than the chlorate and is expressed chemically by the symbol  $\text{NaClO}$ . It is produced at some intermediate stages in the electrolytic process for making chlorate.

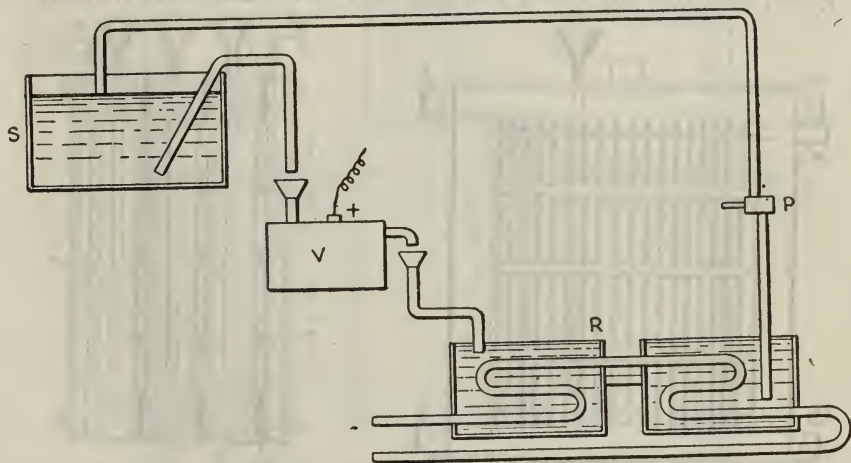


FIG. 4,531.—Arrangement of Gibb's process. The process **consists in** the electrolysis of potassium chloride solutions, using a copper or iron cathode and a platinum anode. S is the supply tank; V, the electrolytic cell; R, the refrigerators; and P, the pump by means of which the exhausted electrolyte is returned to the supply tank, while the chlorate precipitates out as crystals. The reason for using the refrigerator is that in solutions containing only 3 per cent. of chlorate, the latter will not crystallize out upon natural cooling, as it would if present in large quantities. This low percentage of chlorate present is necessary to obtain quick recovery, as otherwise the presence of hydrogen will cause secondary reactions, and cut down the efficiency of the conversion. The pressure employed is about 4 volts per cell, of which 1.4 is required to convert the chloride into chlorate. The circuit density is about 500 amperes per sq. ft. of anode surface.

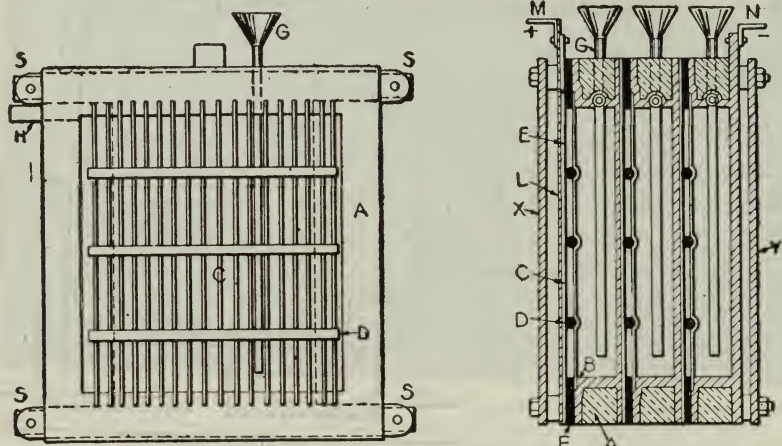
If the cell designed for chlorate production be worked with a low current density, and at a temperature which does not rise above  $68^{\circ}$  Fahr., little chlorate will be produced, and sodium hypochlorite will be formed in its place.

**Ozone.**—This is condensed oxygen, and contains three atoms of this gas in the volume usually occupied by two. It is represented chemically by the symbol  $\text{O}_3$ .

Ozone can be produced by chemical methods, but it is also produced by the sparkless discharge of electricity through dry air or oxygen from conductors charged at a high pressure and it is always formed when a frictional electric machine of the old plate type is worked with an air discharge.

Since ozone is a very active oxidizing agent, and is of value for killing the disease germs in contaminated water, the electrostatic method of producing it in air has been developed upon an industrial scale.

A large number of ozonizers have been patented in Europe and America, and some of these are now being employed in connection with water purification and organic chemical works. The principle of the construction is much the same in all, two metallic conductors, kept charged with electricity at a high pressure, being separated by a tube or sheet of glass, and dry air being led through the space thus formed between



FIGS. 4,532 and 4,533.—Gibb's cell and battery of three cells. The cells *consists of* a wooden frame A, covered with some metal B, such as lead, not attacked by the electrolyte. The cathode consists of a grid of vertical copper wire C, kept in position by cross bars D, of some insulating material. The grid is placed in a vertical position against one side of the cell frame, and kept in place by the anode of the adjoining cell, from which it is insulated by the strips, F, and bars D. The opposite side of the cell from that occupied by the cathode is partially closed by the anode indicated by dotted lines. This consists of a thick lead plate L, covered with platinum foil on the outer side E, (fig. 4,533), and is held in position by the cathode and framework of the following cell. G is a pipe, reaching to the bottom of the cell, by which the potassium chloride is continuously supplied, and it is the overflow pipe to convey the mixed solution of the chloride and chlorate as well as the liberated hydrogen gas away from the cell. S, S, S, S, are lugs projecting from the framework by means of which any number of cell can be bolted together to form a series of cell. In fig. 4,533, the heavy plates X and Y, are used to close the ends of the wooden framework and form a fully closed series of cell with only the openings at the various supply and overflow points. Current connections are made at the points M and N. **In normal operation**, the cell is continuously fed by each of the supply pipe G, with a solution of potassium chloride, the rate of supply being so regulated as to maintain the temperature of the cell at 122° Fahr., and the amount of chlorate in the discharged solution slightly under 3 per cent. Since the plates C and L, of each cell are in metallic contact, due to the lead lining, the electrolysis occurs between the anode of one cell and the cathode of the following cell (see narrow space between cells), this space being not more than one-eighth inch wide. The fact that the cathode is a grid allows the electrolyte to circulate around it, and all the solution thus passes upwards and out of the cells at H. The percentage of chlorate in the overflow solution is low, and refrigeration is necessary to recover it as shown in fig. 4,531.



them. An induction coil is usually employed for laboratory experiments, to raise the pressure to that required for ozone production (8,000 to 10,000 volts), but transformers are required for large installations.

**Organic Chemicals.**—In the manufacture of organic chemicals and dyes, there are many stages of chemical change to be passed through before the final product is obtained, and

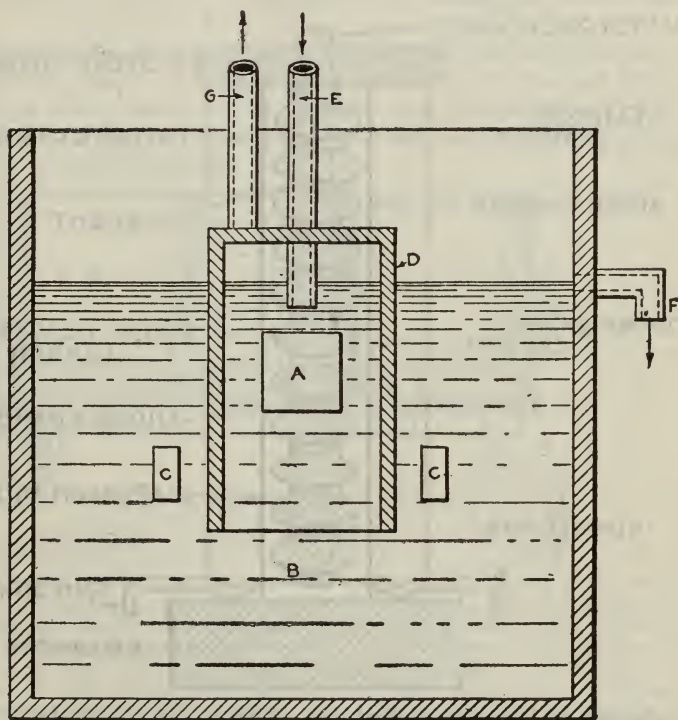


FIG. 4,534.—Aussig bell cell. **The parts are:** A, anode; B, electrolyte; D, bell; E, drive supply pipe; F, overflow pipe; G, chlorine exit pipe; CC, cathodes.

in these, what are called “reductions” and “oxidations” play a leading part. To “reduce” a chemical compound is to bring it to a lower stage of oxidation (*i.e.*, with less oxygen) while to “oxidize” it, is to raise it to a higher stage.

When water, slightly acidified with sulphuric acid, is electrolyzed, oxygen gas is liberated at the anode, and hydrogen gas at the cathode. At a moment of such liberation, these gases are in the ionic or nascent state and they are much more active than when the atoms or ions have

united to form molecules. If, then, the organic compound which it is desired to oxidize be present in the cell near the anode, and the compound which it is desired to reduce be present in the cell near the cathode, and a diaphragm be employed to divide the two compartments of the cell, the nascent oxygen and hydrogen at the moment of their liberation will bring about the desired effects. This, then, is the principle of the use of the electric current for oxidizing and reducing changes in the manufacture of organic chemicals.

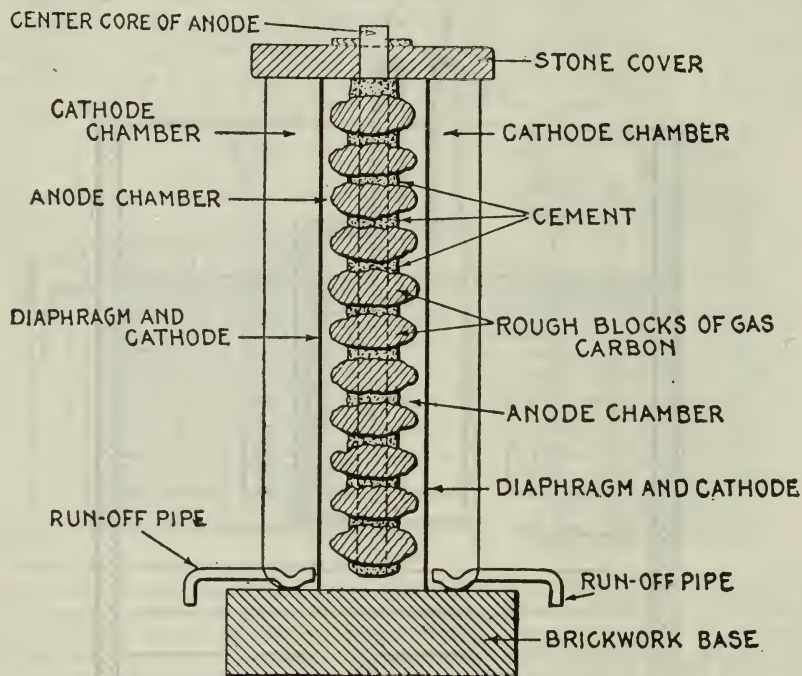


FIG. 4,535.—Section of Hargreaves-Bird cell. This is the diaphragm type of cell, in which a porous diaphragm is placed between the anode and cathode chambers of the cell, and the mixing of the anode and cathode liquids is hindered but not altogether prevented in this way, although the ions, which carry the electric current, have to pass through the diaphragm in their transit from anode to cathode.

**Oxygen and Hydrogen.**—Dilute sulphuric acid is employed in one form of apparatus as electrolyte, namely, that patented by Schoop, the more customary electrolyte being a solution of caustic soda.

The primary products of electrolysis in this case are hydroxyl (OH) and the metal sodium (Na) but these immediately enter into secondary chemical changes which produce oxygen gas at the anode and hydrogen



gas at the cathode. The gases obtained in this way are not quite free from impurity, but for industrial requirements they are sufficiently pure, and this method of manufacture is much cheaper and more cleanly than the usual chemical methods of production.

**Sodium and Potassium.**—The method which Sir Humphrey Davy employed to produce a few grains of potassium and sodium is now used to manufacture these metals by the ton.

It is necessary to work with a fused electrolyte in place of an aqueous solution in this case. Owing to the readiness of sodium and potassium to enter into combination with water, the difficulties of operating the process upon a commercial scale are chiefly due to this great chemical activity of the alkali metals.

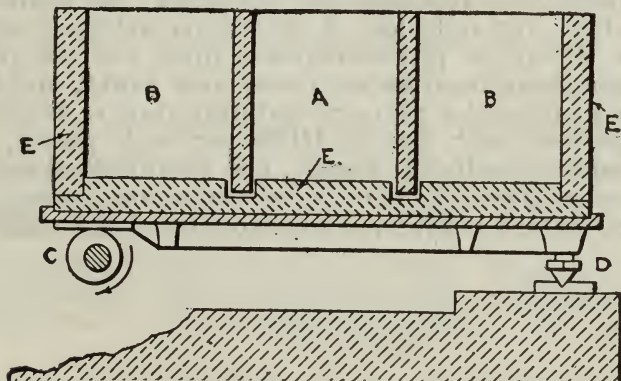


FIG. 4,536.—Castner cell. *The parts are:* A, cathode chamber; BB, anode chambers; C, eccentric for producing a rocking movement of cell; D, pivot support for framework of cell; E, slate walls of cell. The Castner cell is of the mercury type in which advantage is taken of the property possessed by mercury of forming an alloy with sodium, fluid at the ordinary temperature, this alloy being known chemically as an amalgam. When the amalgam is heated with water it is decomposed, and a solution of sodium hydrate is formed, while the mercury is restored to its original condition of purity. Hence, if a layer of mercury be employed as cathode on the floor of a cell in which a solution of sodium chloride is being decomposed by the current, the sodium liberated at the surface of the mercury will at once enter into union with it, and will be kept safe from further chemical or electrolytic changes. The layer of mercury, in fact, acts as a reservoir for the sodium atoms, or ions, brought to its surface, and stores up these until they are wanted.

**Wet Extraction Processes for Metals.**—Copper, nickel, tin and zinc have all been extracted from their ores or slags by the use of electrolytic processes, and in many cases these processes are still being worked upon an industrial scale.

**Copper.**—The principle of the wet copper extraction processes is as follows: The ore is roasted to drive off the sulphur, and then leached

in suitable vats with a solution which will dissolve the copper and leave the other metals and impurities undissolved. This solution is then electrolyzed in order to recover the copper as a cathode deposit.

**Nickel.**—The roasted ore is leached with a solution containing both copper and calcium salts as chlorides, and the copper is first deposited by electrolysis. The last traces of copper are then removed from the electrolyte by chemical means, and the nickel is in turn deposited by use of a higher voltage from the remaining solution.

**Tin.**—The Böhne process depends upon the use of sulphuric acid as a leaching agent and upon electrolytic deposition of the tin, from the sulphate solution so obtained. In the recovery of tin from old tin cans and tin scrap by electrolysis, sodium hydrate is used as the electrolyte.

**Zinc.**—A great amount of investigation and large sums of money have been spent upon processes for extracting zinc from its ores, by aid of electrolysis, but only two of these have achieved any industrial success. The Hoepfner process depends upon the use of the waste calcium chloride solution from ammonia soda works, and was worked out chiefly as a process for recovery and utilization of the chlorine from this waste product; zinc, testing 99.96 per cent. purity, and bleach being the products finally obtained. The Swinburne-Ashcroft method (the other successful process) is not a wet extraction process, but depends upon the electrolytic separation of zinc from fused zinc chloride.



## CHAPTER LXXXVI

## ELECTRO-PLATING

This process consists in obtaining *an electro-deposit of one metal, used as an anode, upon some metallic article which is connected to form the cathode in an electrolytic bath*, that is to say, the substance upon which it is desired to deposit the metal is connected with the negative pole of the source of current, and the metal which is to be plated upon is connected with the positive pole.

The chemical nature of the *electrolyte* employed depends upon the kind of plating. For plating with gold or with silver, the electrolyte is always alkaline, for plating with nickel or with copper, it is usually acid.

Substances other than metal can be electroplated by first coating their surfaces with powdered graphite or plumbago, as in the case of *electrotyping*.

**Ques.** What is the most essential condition for successful electro-plating.

**Ans.** Cleanliness.

The merest trace of grease or dirt is sufficient to completely spoil the plating; in fact, the presence of even the small amount of grease caused by handling the article with the naked hand is often sufficient to prevent an adherent deposit.

**Ques.** How are articles to be plated cleaned?

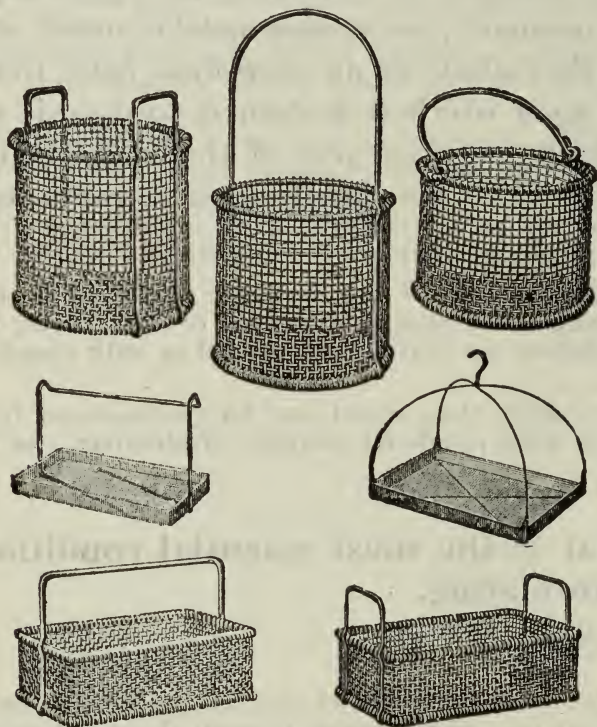
**Ans.** This is generally done by means of emery paper or wet sand; the article is also scrubbed with a scratch brush.

**Ques. What is the next operation?**

**Ans.** The articles are treated with caustic soda and then thoroughly rinsed in running water.

**Ques. What is sometimes done before placing articles in the plating bath, and why?**

**Ans.** They are sometimes dipped in acid; this is partly for cleansing purposes, and partly to slightly roughen or frost the surfaces.



FIGS. 4,537 to 4,543.—Various dipping baskets.

**Ques. Mention some other important considerations in electro-plating.**

**Ans.** 1, The current density per square foot or square inch of surface; 2, the condition of the anode and its size compared



with that of the cathode; 3, the concentration and composition of the depositing solution; 4, the presence of impurities in the solution.

When the anode is made from impure material, the solution rapidly becomes contaminated with impurities, and gives unsatisfactory results. When the anode is very large in comparison with the cathode, the solution usually becomes too concentrated. When the depositing solution is too strong, the metallic salt often crystallizes out upon the anode and cathode, thus preventing a good deposit and increasing the resistance of the bath.

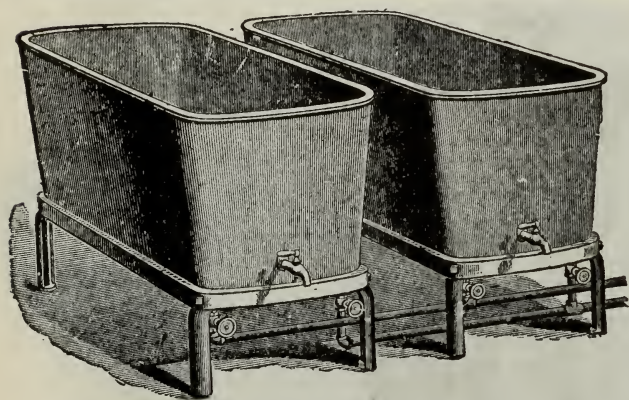


FIG. 4,544.—Heating tanks. Small shops usually depend upon gas or oil stoves placed under the various tanks or jars containing solutions that must be kept hot, such as lye, rinsing water, gold solutions, etc., as either offers a means of keeping up the desired temperature with very little trouble or expense. Larger establishments, however, find it cheaper and better in every way to use steam jacketed tanks, as here shown. These can be purchased in regular sizes, holding from three gallons up to forty gallons, and the smaller and medium

sizes are rapidly finding favor in many machine shops and factories where it is important to cleanse the work quickly and cheaply. Still larger tanks for heavy work are made of boiler iron and heated by a steam coil placed in the bottom of the tank; this usually is allowed to simply lie upon the bottom of the tank, so that it may be readily removed should it become necessary in cleaning the tank or repairing the coil. In arranging the tanks in the plating rooms, much will depend upon the work to be done and the space that is available; the only rule that can be given, therefore, is to follow the order in which the work is handled in both polishing and plating rooms, so that little time and labor will be lost in carrying work back and forth, with the consequent dripping of the lye and acids, etc., upon the floor.

### Ques. What is stripping?

Ans. Metals of a like character do not adhere firmly to each other; thus electro-deposited gold will not adhere to a gold surface, and so on. Worn articles of electro-plate, which are to be re-plated, require therefore to have the whole of the previous plating removed before receiving a new coat. This process of removal, which is accomplished by various acids, is technically known as *stripping*.

**Current Supply for Electro-plating.**—Low pressure direct current is used for this purpose, the pressure used being from 1 to 16 volts, depending upon the nature of the electrolyte employed, and the rate at which the plating is accomplished.

**Ques.** What are the objections to the use of primary batteries for electro-plating?

**Ans.** The current furnished is not constant; the increasing internal resistance of the battery causing a gradual diminution

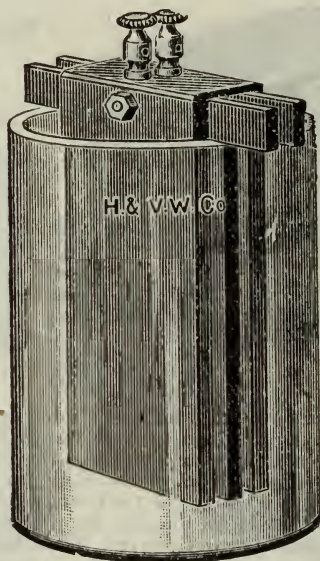


FIG. 4,545.—Smee cell with carbon plates for use with silver and gold plating solutions.  
**Directions:** Amalgamate the zincs and fill the jar to within about one inch of the wooden support with a mixture of 1 part oil of vitriol to 10 parts water. After using remove zincs and carbon, and wash them in clean water. **Amalgamating solution for cell zincs:** FORMULA: Water, 1 gallon; corrosive sublimate, 1 pound; muriatic acid, 1 pint. Mix in the order named. Dissolve the corrosive sublimate in hot water. The zinc must be thoroughly cleaned before it can be properly amalgamated. This should be done by immersing it in a solution of lye or potash, after which rinse in clean cold water, then place the zinc in the amalgamating solution, and the mercury will readily adhere to it. Another method of amalgamating zinc is to clean it by dipping in dilute sulphuric acid and rubbing on metallic mercury with a cloth or brush. **Electroplating solution:** FORMULA: Water,  $\frac{1}{4}$  gallon; oil of vitriol, 1 quart; bichromate soda, pulverized,  $1\frac{1}{4}$  lbs. Mix in order named. Pour oil of vitriol slowly in water, and at the same time keep stirring the mixture which will become hot. While the mixture is still hot, stir in the bichromate of soda. When cold, the solution is ready for use.

of the current in the working circuit throughout the period of operation. Furthermore, the high price of zinc and its excitants



make them expensive; they require much time and labor for setting up and removing after the completion of operations; they give off fumes which are injurious to the health, unless they be placed by themselves in properly built and ventilated closets.

The adverse conditions obtaining in the case of batteries, have resulted in the general adoption of suitable types of dynamo especially where the operations require a large and constant current.

There are many cases, however, where the lack of power facilities prevents the advantageous use of dynamos, or motor generator sets,

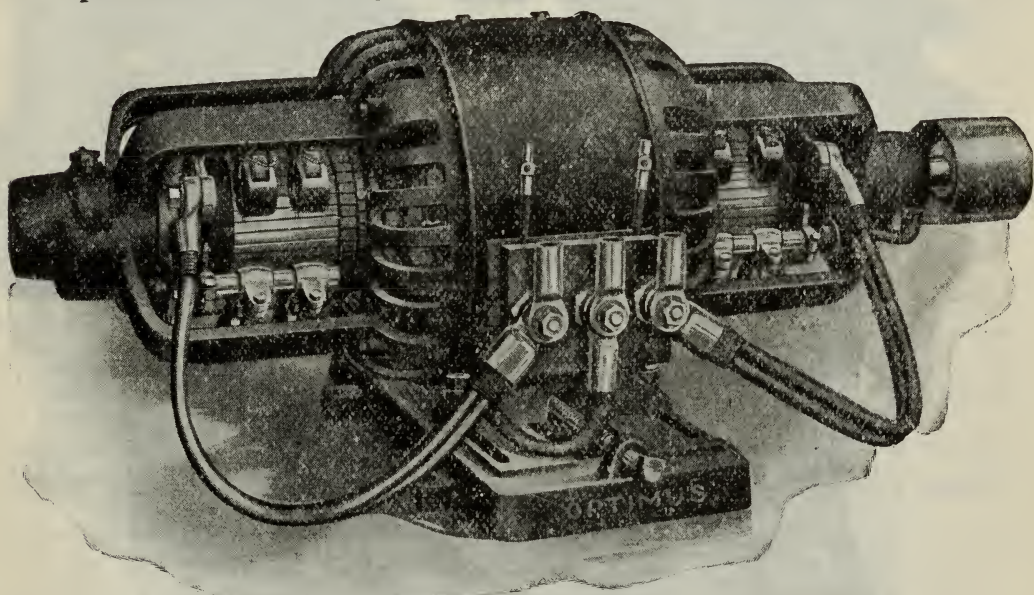


FIG. 4,546.—Optimus double commutator, belt driven electroplating dynamo having a capacity of 750 amperes at 6 volts, or 375 amperes at 12 volts. Two commutators are used in order to keep down the current density in the commutator bars.

so that the use of batteries becomes compulsory. In such cases, several cells of Bunsen, Daniel, or Wallorton type, properly coupled together may be used. As a rule those Bunsen cells having a pressure of 1.8 volts each, will produce sufficient current to run about twenty gallons of nickel electrolyte. Nickel is a very hard metal and cannot be deposited rapidly by low pressure battery currents.

**Dynamos for Electro-plating.**—Where power is available it is much more economical to employ a dynamo. Although the first cost is greater, the capacity of the outfit is not only

greatly increased, but the work facilitated by the constancy of the current supplied, and comparatively little attention required by the dynamo itself.

**Ques.** How do plating dynamos differ from those designed for electric lighting and power?

**Ans.** They are proportioned to deliver a large current at low pressure, instead of a low current at high pressure.

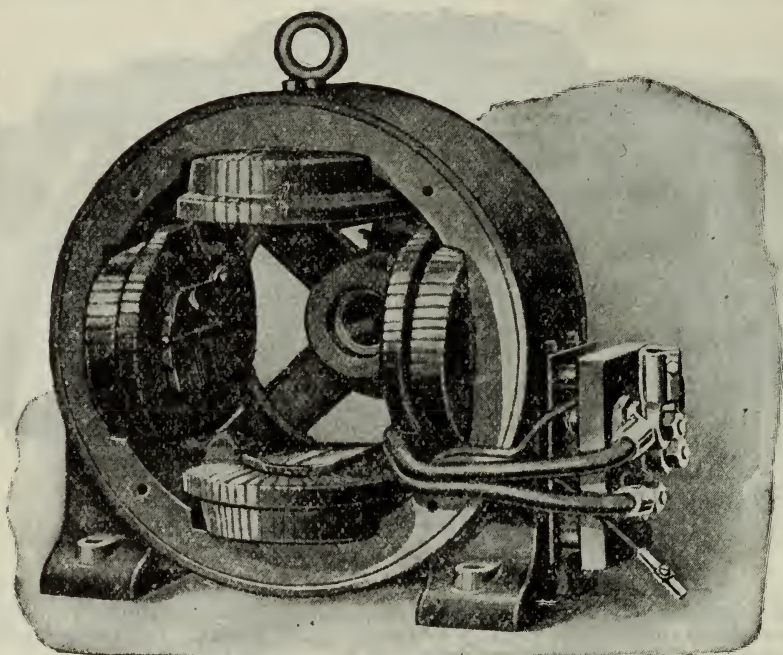


FIG. 4,547.—Optimus frame and field magnets of plating dynamo.

This necessitates large commutators and large brush gear, also large inductors. Some dynamos have double commutators to secure sufficient brush contact area to take care of the large current. The construction of electro-plating dynamos is shown in the accompanying cuts.

**Current Required, and Size of Wire.**—The amperes required to plate one square foot with a deposit of each of the various metals are given in the following table and will be found useful for determining the capacity of dynamo in square feet



of plated surface, and also for determining the sizes of wire leading from the main lines to the various tanks.

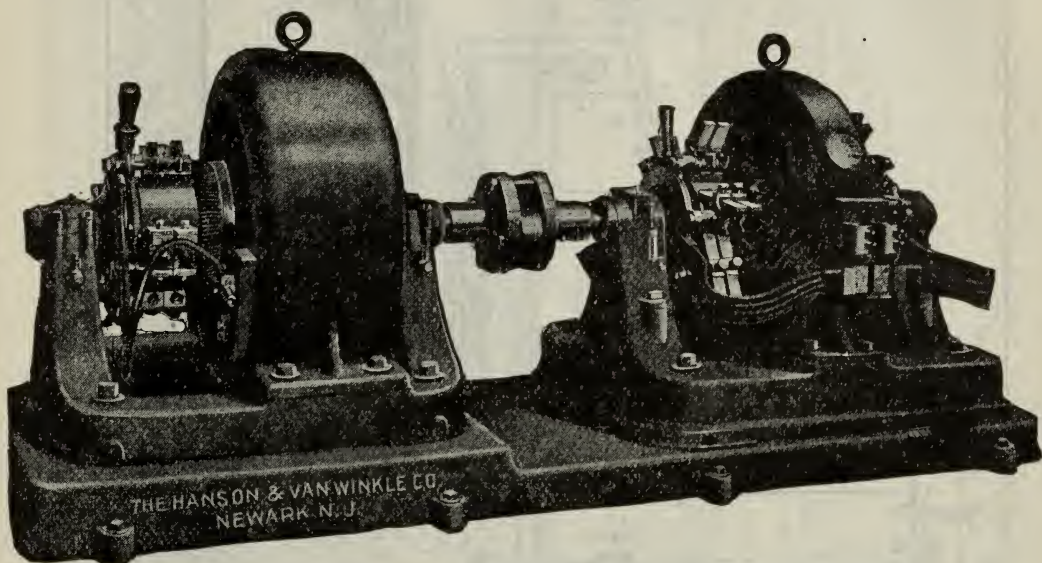


FIG. 4,548.—Hanson and Van Winkle motor generator set consisting of a six volt dynamo and an alternating current motor. For mining and other purposes, recovery of gold, etc., this form of outfit is desirable, as the current to operate the motor can be carried to the point most available for the location of the dynamo, and the expense of maintaining long lines of heavy copper conductors materially reduced.

***Amperes required to plate one square foot.***

Solution and metal.	Average amperes.
Nickel.....	4
Brass.....	6 to 8
Bronze.....	6 to 8
Copper.....	6 to 8
Acid copper.....	10 to 12
Silver.....	2
Gold.....	1½
Zinc.....	10

***Carrying capacity of copper wire.***

Size.	Amperes.
1/16".... .0625	3
1/8".... .125	12
3/16".... .1875	27
1/4".... .250	49
5/16".... .3125	76
3/8".... .375	110
1/2".... .500	196
5/8".... .625	306
3/4".... .750	441
7/8".... .875	601
1".... 1.000	785
1 1/8".... 1.125	994

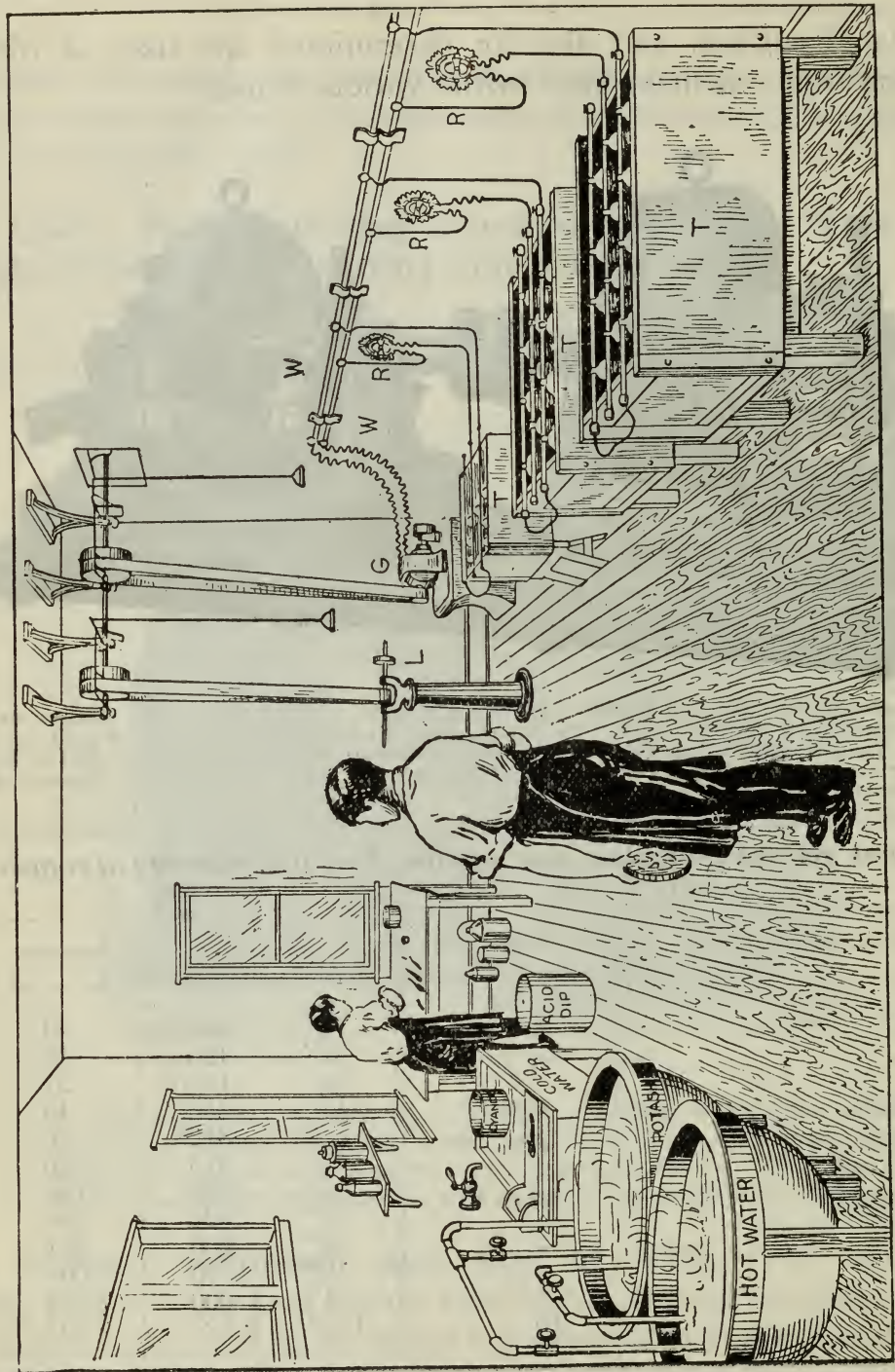


FIG. 4,549.—Electroplating outfit with two wire system of distribution.



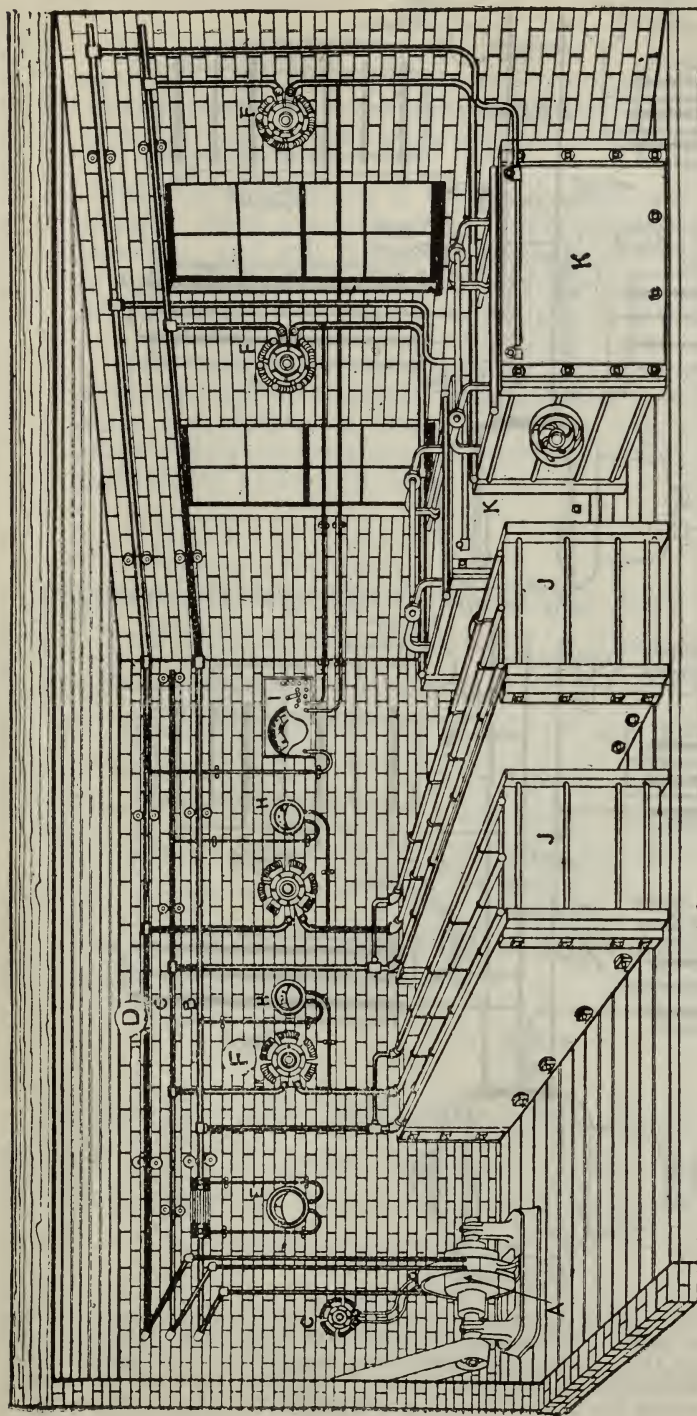
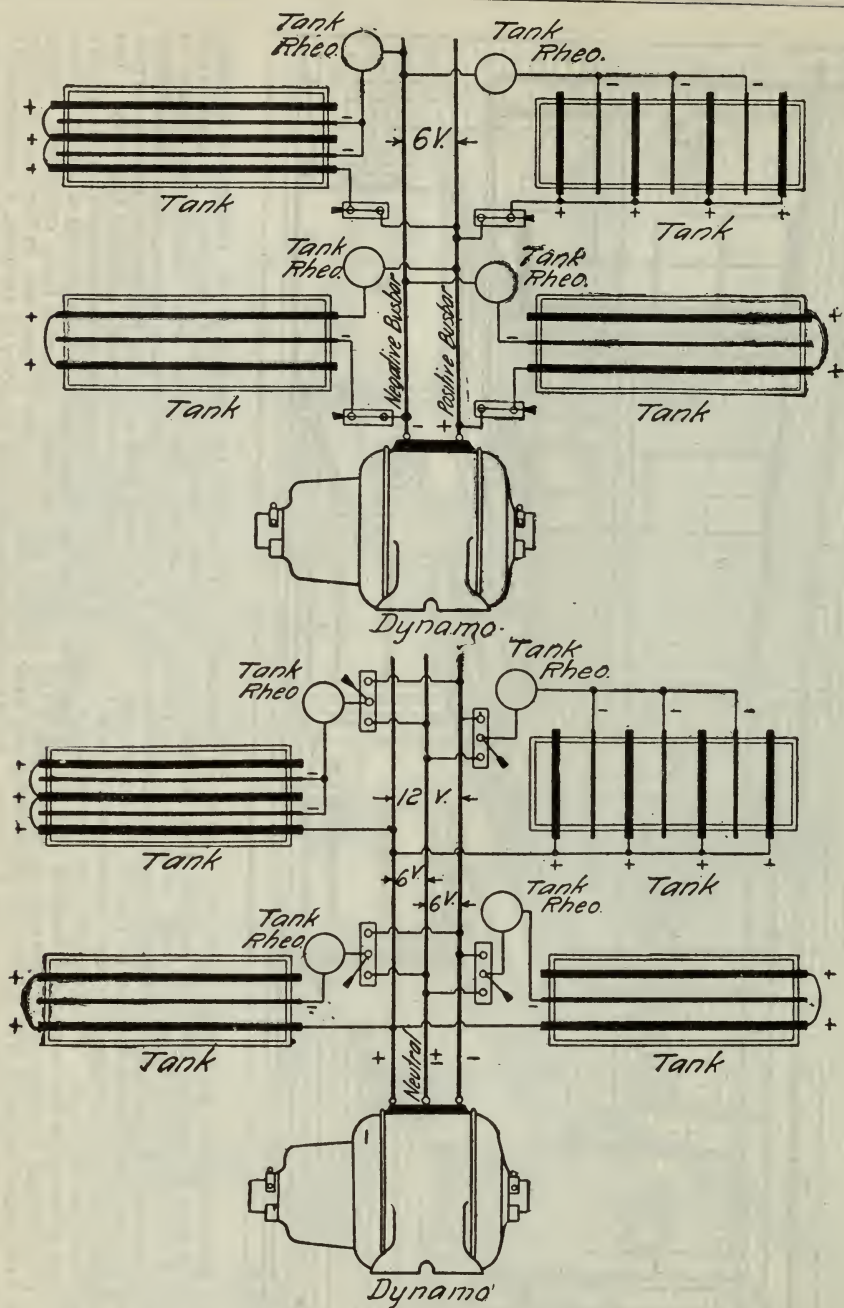


FIG. 4,550.—Electro-plating outfit with three wire system of distribution. The apparatus consists of: A, multipolar dynamo; B, positive line; C, neutral line; D, negative line; E, ammeter; F, tank rheostat; G, field rheostat; H, tank voltmeter; I, Starrett voltmeter; J, still solution; K, plating apparatus. The three wire distributing system is generally employed in the larger electroplating establishments where a variety of solutions are in use, thus necessitating the employment of different voltages in the different solutions. It is well known that a higher voltage and greater current strength can now be advantageously used in many solutions in the working of which it was formerly assumed that only a low voltage could be employed. Furthermore, the necessity for reducing the time of deposition without impairing the quality of the work is desirable for economical reasons, and it is effected by agitating the solution and employing a higher voltage with a proportional increase of the current strength. Since the general run of stock dynamos have capacities ranging from 4 to 6 volts, the three wire system of distribution not only effects a saving of over 37 per cent. in the cost of copper conductors, but permits of desirable voltage variation. For example: with a dynamo capacity of 10 volts, a pressure of 10 volts can be obtained in some of the tanks by connecting them to the outside wires of the system, while five volts can be obtained in other tanks, by connecting the latter to either one of the outside wire and to the neutral wire.



FIGS. 4,551 and 4,552.—Optimus wiring diagram for two wire and three wire installations. Fig. 4,551 shows the usual method of connecting tanks with a two wire dynamo; each tank has a separate rheostat, thus permitting independent regulation of voltage for each tank. Fig. 4,552 shows a three wire installation, so wired that each tank can be thrown across the low voltage or across the high voltage line independently of the other tanks.



Special attention should be given to install wires amply large to carry the heavy current. In this connection, it should be noted that a 40 foot conductor must have a cross sectional area equal to one square inch, to carry 1,000 amperes, without heating.

The current density is especially important and varies with different metals. With a high current density the deposit may be crystalline or powdery, and will not adhere well to the cathode. What is required is to regulate the current so that the deposited metal may be smooth and adherent, and capable of being burnished without being detached.

Hard and fast lines cannot be laid down, but, generally speaking, with high current densities the deposit is powdery, and of a dark color, when it is said to be "burnt." Much higher current densities can be employed if the solution be rapidly circulated by means of a pump or agitated by blowing in air.

**Electro-plating Outfits.**—These vary in general arrangement and equipment according to the character of the work done, its amount, and the source of current supplied. Fig. 4,549, shows the general arrangement of an outfit for plating with three different kinds of metal. The current is distributed on the two wire system, and a rheostat is provided for each tank.

Fig. 4,550, shows the general arrangement of an electro-plating outfit wired for the usual solution tanks and also for the operation of mechanical plating apparatus, on the three wire system of distribution.

**Rheostats and Switchboards.**—Rheostats are employed for varying the current strength required for working different kinds of solutions or for handling various sizes of baths. When metals such as silver and copper, which require low resistance solutions, are to be deposited in connection with such metals as nickel and brass, which require high resistance solutions, a considerable drop in voltage is required for the former, in order to prevent the blackening of the work.

A rheostat inserted in the field of the dynamo will maintain an initial voltage on the whole system, but rheostats at each tank are necessary to further reduce the current to the proportions required by the solutions in those tanks. While the field rheostat effects the voltage by

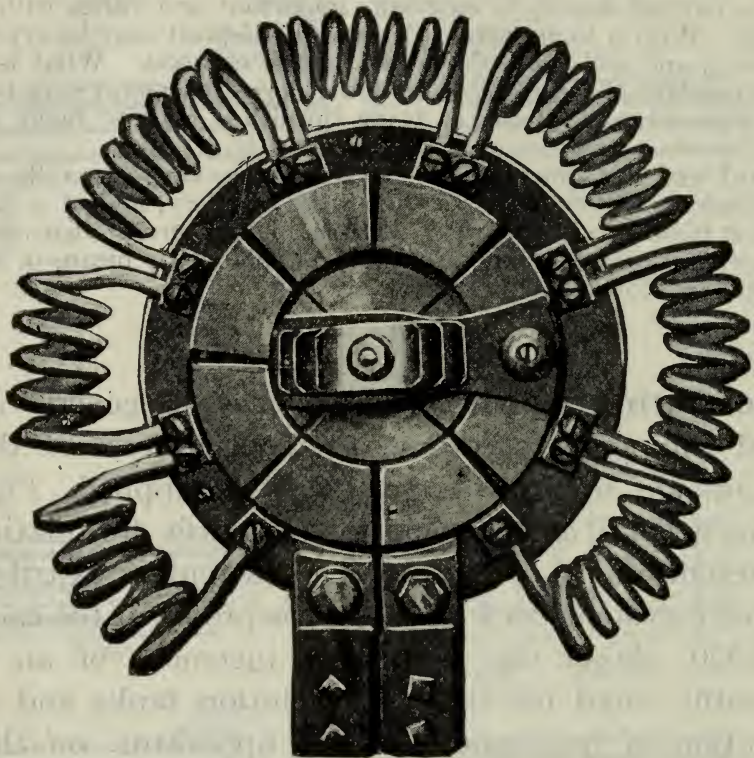


FIG. 4,553.—Form of rheostat for controlling heavy currents. It has a capacity of 800 amperes. The variation of voltage obtainable is 2.1 volts. It is suitable for solutions containing 175 to 200 square feet of nickel, 125 feet of copper or brass work, or 75 feet of zinc work. The capacity of rheostats of this and other types range from a few to many hundreds of amperes, so that no difficulty is experienced in selecting those of proper capacity to suit any combination of tank capacity and character of solution. All platers understand that different voltages are required to operate successfully different kinds of solution, and that when a sufficient voltage is to be generated for a solution of the highest resistance, and at the same time utilized in low resistance solutions, the tank nearest the dynamo, with the customary method, receives the most current, and a tendency to burn and blacken is noticed to a marked degree. When metals such as silver and copper are to be deposited in connection with such metals as nickel and brass, a higher voltage is required, and considerable drop in voltage is demanded in the lower resistance solutions so as not to blacken the work.

NOTE.—The use of voltmeters at each tank is very desirable, as it is well known that the character of the deposit obtained by the use of a certain solution largely depends upon the reproduction of certain voltages and amperage values of the applied current. The ordinary galvanometer, which indicates only a change of polarity, is insufficient for this purpose, while on the other hand a sensitive voltmeter will indicate any irregularity of power, due to the slipping of belts, short circuits in tanks, etc.



setting a fixed resistance in the dynamo field, it does not affect the amperage except to a small extent.

When a rheostat is placed between the main line and the tank, the amperage is reduced in proportion to the reduction of the voltage. Therefore it is necessary that a tank rheostat should be capable of carrying the amperes of current required by the solution in its particular tank, otherwise the proper amount of current will not flow into the tank.

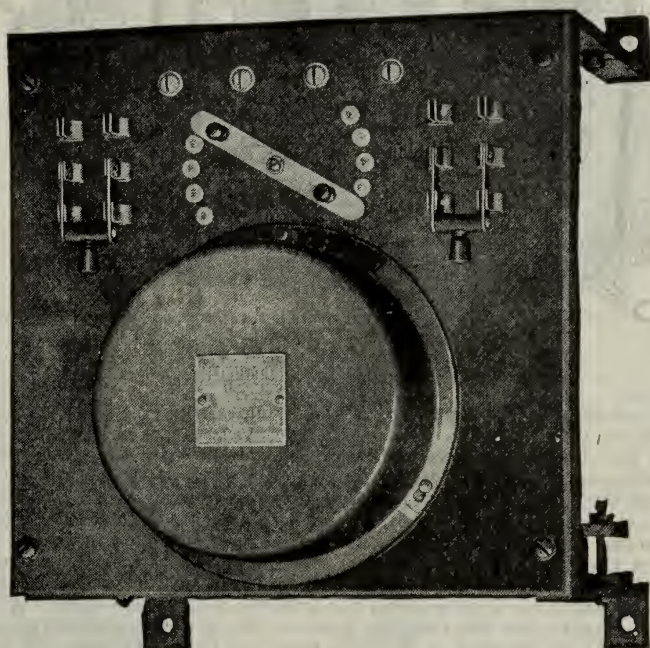


FIG. 4,554.—General Electric voltage regulator for use with electrolytic dynamos. It is sometimes desirable in electro-plating, where more than one tank is operated from a single machine, to maintain a constant voltage under all load conditions without manipulating the field rheostat. To meet these requirements, the regulator here shown has been designed.

**Mechanical Electro-plating Apparatus.**—A great variety of form have been designed to reduce the cost of plating articles, which in the absence of some form of mechanical plating apparatus must be strung or plated in trays. The cheapening in the

NOTE.—The substitution of steel for the high priced copper or brass has increased the demand for electro-plating more than any other cause. In plating brass or bronze on steel in a stationary tank there is a tendency to an excess or deficiency of the copper. This seems to be overcome in the mechanical plater. The deposit of nickel, brass, copper, zinc, etc., in the mechanical plater is a more protective coating for the same amount of metal used, resembling more a burnished metal.

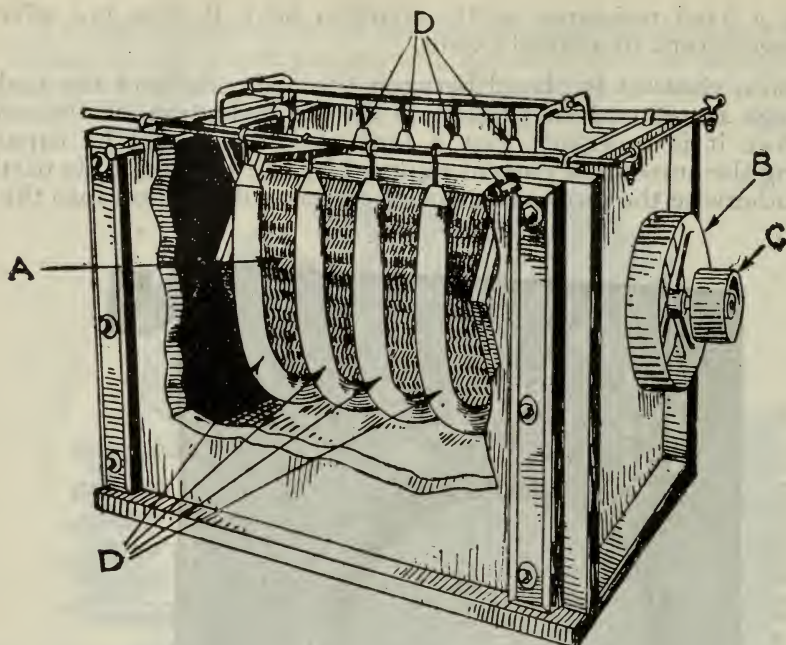


FIG. 4,555.—Mechanical electro-plating apparatus. *It consists of* a barrel A, in which are placed the articles to be plated. This barrel is revolved by belt device over the pulleys B or C, which provide two speeds. The barrel is removable at any time without interfering with the device. The anodes D, D, are curved to fit the periphery of the revolving barrel, and when the anodes are hung at each side of the tank, as shown, the work is always equidistant from the anodes, thereby insuring a regular deposit of even depth. ***In setting up and operating*** the mechanical electro-plating apparatus, connect the anode rod to the positive wire of the main line, and the cathode rod to the negative wire. Use suitable size wires for this purpose; as shown by the branch holes in the rod connections. Insert a rheostat in the negative line between the tank and the main line. When the barrel is being filled or emptied move the rheostat lever to the *off* point, so as to prevent the burning or blackening of the work when it is being removed from the tank. This should receive particular attention when a high voltage current is used. All contact points should be kept perfectly clean. A strip of thin sheet lead, or a split length of rubber hose, bent into the shape of a U, should be placed over the entire length of the anode rod to prevent the slop and dirt from the solution impairing the contact of the anode hooks with the positive rod. The revolving barrel may be operated at two speeds. In order to obtain the correct speeds, the countershaft should be driven at the rate of 10 revolutions per minute. ***The following voltages should be used*** with the various solutions: Acid copper solution, 18° Baume, 2½ to 5 volts; cyanide copper and brass solution, 12°–15° Baume, 4 to 5 volts; nickel solution, 10° Baume, 4 to 5 volts; zinc solution, 20° Baume, 6 to 10 volts. ***With the lower speed***, almost any kind of article which will not hang to the periphery of the barrel, may be handled with the lower voltages. ***The higher speed*** and the higher voltages should be used for round articles, or those having no sharp edges or corners, with a consequent shortening of the time of deposition. The best results are obtained when the articles fill about one-half the barrel. The average length of time required to obtain a good deposit of the different metals under proper working conditions is approximately as follows: Acid copper solution, 20 to 40 minutes; cyanide copper and brass solutions, 30 to 45 minutes; nickel solution on brass, 15 to 30 minutes; nickel solution on steel, 45 to 60 minutes; zinc solution, 1½ to 2 hours. In the case of all solutions, the crystallization of the salts during cold weather tend to give a great deal of trouble. Therefore, all solutions should be kept at a temperature of 70 to 80 degrees Fahr., thereby permitting the use of denser and more highly conductive solutions, with a consequent shortening of the time of deposition. A loop of bare steam pipe immersed in the solution will serve to supply the necessary heat.



cost of plating has been so marked that mechanical plating apparatus is now recognized as a necessity in the metal manufacturing industry.

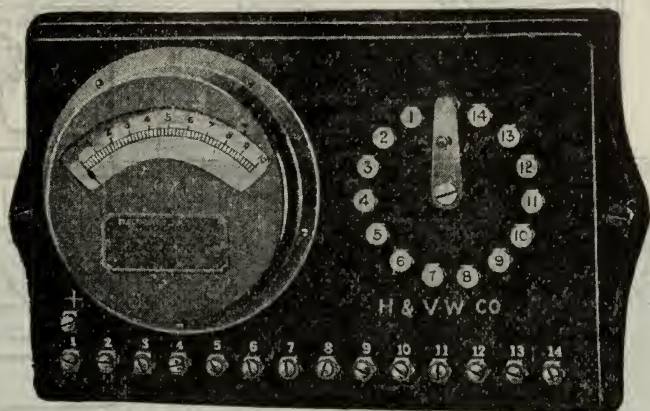


FIG. 4,556.—Waverly voltmeter with binding posts for fourteen tanks, thus enabling the operator to use only one instrument in obtaining the reading of any number of tank up to fourteen, by simply moving the switch lever to the tank numbers indicated on the switch of the instrument, and, when used in connection with tank rheostats, will enable the operator to reproduce at all times the same electrical conditions which by observation and experience he has found necessary in order to obtain a satisfactory deposit of uniform thickness and color in the shortest possible time.

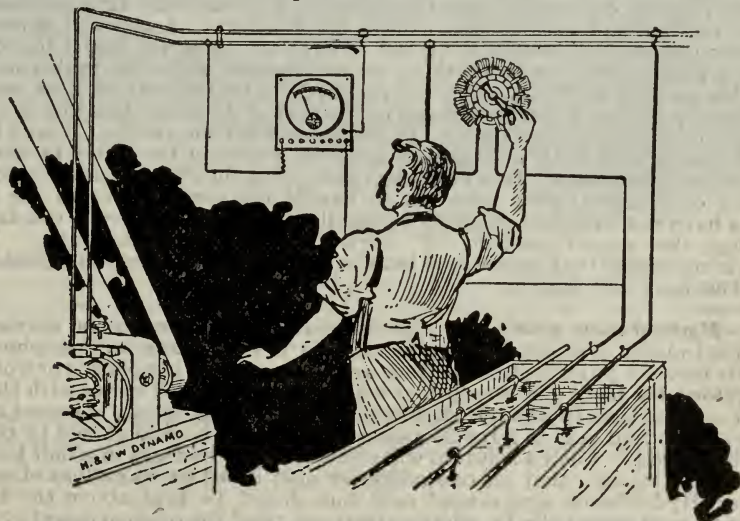


FIG. 4,557.—Connections and manipulation of rheostat on large copper, brass, and bronze solutions where variations of voltage are necessary to secure different colors.

**The Tanks, or Vats.**—These vessels are for holding the plating solutions, and should be made of well seasoned wood, liquid

tight, and lined with some suitable material which will not be acted upon by the solution the tank is intended to contain.



FIG. 4,558.—Two tank electro-plating installation showing rheostat and voltmeter connections.

**Use of rheostats:** Rheostats are of the first importance in the plating room. Without them the varying degrees of current necessary for handling different solutions, or for manipulating baths of various size, cannot be obtained. A rheostat is necessary in the field of the dynamo where it will control the voltage along the entire line of connection, enabling an initial current strength to be maintained while the tank rheostats further reduce this current to the proportions required. The rheostat in field, while it affects the voltage by setting a fixed resistance in the field of dynamo, does not affect the ampere capacity except in a minor degree. On the other hand the rheostat placed between main line and tank affects both voltage and amperes, reducing the latter in same proportion as the former is cut down. It is necessary, then, that the rheostat selected for the tank be of ampere carrying capacity sufficient to handle the current used in the tank. If the rheostats have not sufficient capacity to handle the ampere current a resistance is formed, preventing the proper amount of current flowing into the tank. In arranging tanks it is necessary that conductors be of sufficient size to carry the greatest number of ampere the tank will handle.

**NOTE.—Hydrofluoric acid.** For cleaning castings that are to be galvanized, tinned, enameled, nickel-plated or painted, hydrofluoric acid is vastly superior to sulphuric or muriatic acid because it leaves a purer metallic surface and does not rust the plating or work through the paint. **Directions for use.** The strength at which the acid is used varies with the kind of iron to be cleaned and the time in which it should be finished, but generally it is used in a proportion of one gallon of standard acid to 20 or 25 gallons of water. The acid should be poured into the water and well stirred. Such a solution will clean ordinary castings in a half hour to an hour. If used only half as strong—that is, one gallon of acid in 40 to 50 gallons of water—it takes several hours. Hydrofluoric acid is used cold, but should be kept above the freezing point. The bath can be used repeatedly by adding about one third the original quantity of acid before charging again with iron. If it be desired to keep the iron bright, it should be washed with water at about 200° F. immediately after coming out of the acid, so as to dry quickly. By this means all trace of the acid is eradicated and all chance of corrosion or tarnish resulting obviated. If washed with cold water, it will remain wet for some time and rust. A little lime may be added to the wash water. As the strong acid will cause inflammation wherever it comes in contact with the skin, it should be handled as carefully as other acids. Rubber gloves are the best protection, but if acid has splashed on the skin it should be washed off at once with water and diluted borax or sal soda solution, or with aqua ammonia, which will prevent any injury.



For example: the tanks for holding gold plating solutions should be impervious to the action of potassium cyanide at a temperature of 150 to 180 degrees Fahr. Tanks for nickel plating solutions should be lined with a mixture of asphaltum and pitch. Wooden tanks for gold, silver, copper, brass, or any plating solution containing cyanide, should be lined with paraffine well worked into the wood.

**Ques. What use is made of iron tanks?**

**Ans.** They are used for all hot solutions.

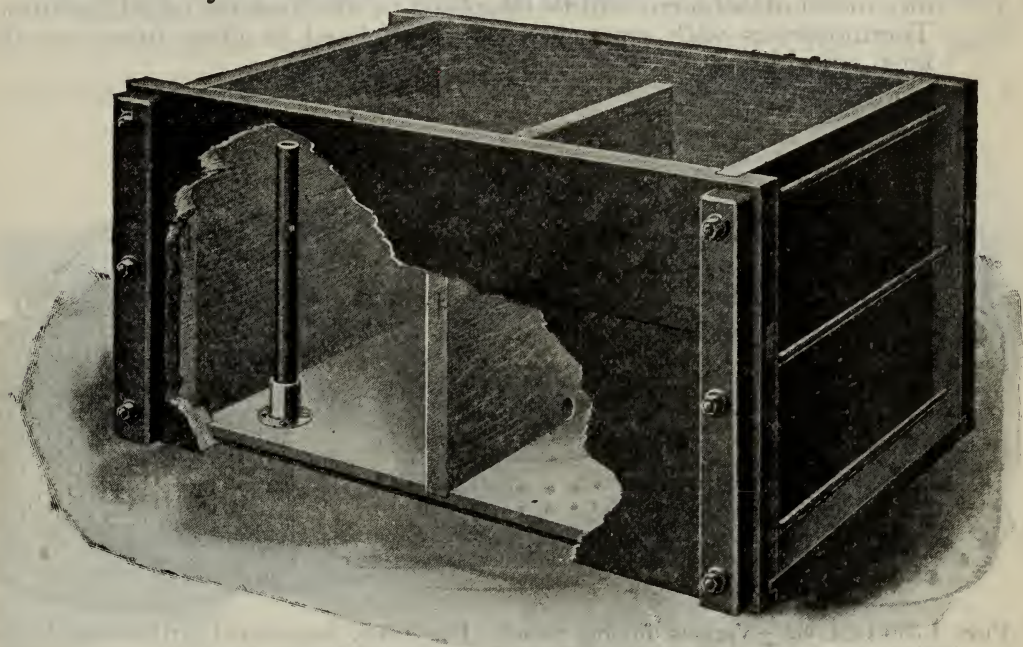


FIG. 4,559.—Wood tank for scouring, rinsing, and hot water. It is fitted with an overflow and outlet stand pipe made with a brass plug and taper socket. The socket should extend below the bottom of the tank, allowing for a threaded or wipe joint connection. For hot water a single compartment tank is desirable; for scouring and rinsing, a two compartment tank is generally used.

When iron tanks are used, great care should be taken to prevent the anode rods and the work in the solution coming in contact with the tank, thereby causing a short circuit.

**Ques. What attention should be given to wooden tanks?**

**Ans.** When not in use, they should be kept filled with water in order to prevent them drying, cracking, and becoming leaky.

**Ques. How should gilding solutions be kept?**

**Ans.** In small enamelled iron tanks, provided with legs, so as to permit the placing of a gas burner, lamp, or stove beneath the tank.

A thermometer should be permanently fixed to the tank below the surface of the solution, for ascertaining the right temperature of the latter. The thermometer should be entirely of glass as the presence of any metal attachment will be dissolved by the heat of the gild solution. Thermometers with enamelled scales enclosed in glass tubes are the most suitable.



FIGS. 4,560 to 4,562.—Various dipping vessels. Fig. 4,560, deep glazed earthenware dipping basket; fig. 4,561, shallow glazed earthenware dipping basket; fig. 4,562, aluminum wire dipping basket. The aluminum basket is adapted for use in washing and dipping in all acid solutions, but cannot be used in potash solutions. Different shapes and sizes of basket are required for various kinds of work. Successful dipping depends, however, chiefly upon quick and careful handling rather than upon the shapes of the dip, therefore, the holes in these baskets should be as large as possible, so as to allow the acid or cyanide solution to drain out quickly.

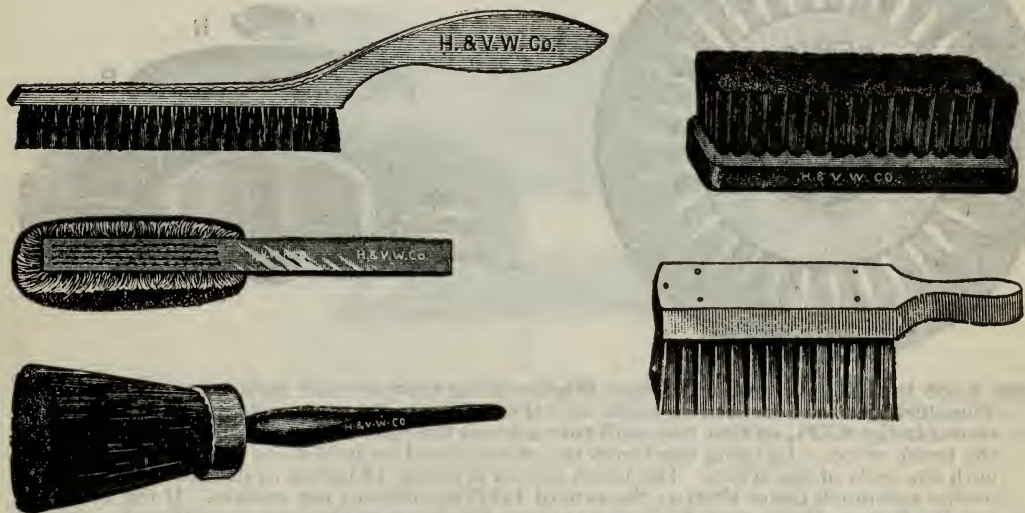
**Dipping Vessels.**—These are employed for holding the articles and dipping them into the various solutions used in cleaning the articles preparatory to the plating.

All dipping vessels used in acid solutions should be made of vitrified or glazed stoneware or glass. Various forms of dipping vessel are shown in the accompanying illustrations.



**Scouring, Swilling and Rinsing Troughs.**—These are usually made of wood, lined with lead and divided in the middle by a partition, one part being used for scouring and the other for holding clean water for rinsing the articles after they have been scoured clean.

**Scouring and Wash Out Brushes.**—There are a variety of these, made of various materials, and in many different patterns and sizes suitable for different kinds of work.



FIGS. 4,563 to 4,567—Various brushes. Fig. 4,563, jeweler's shoe handle wash out hand brush; fig. 4,564, flat scouring brush; fig. 4,565, cotton potash brush; fig. 4,566, sawdust brush; fig. 4,567, wire foundry brush.

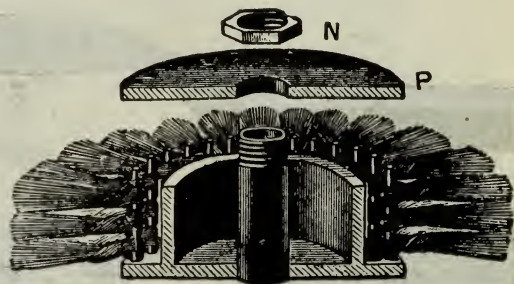
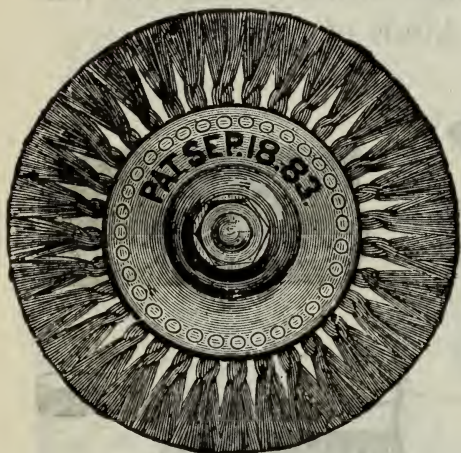
Fig. 4,563 shows a jeweler's wash out brush. They are made with both straight and curved handles, and of brass or steel wire, bristles and tampico fibre. Extra soft brushes are made of goat's hair.

Fig. 4,564 shows an example of a flat scouring brush of tampico fibre. Their sizes are indicated by the number of knots included in the length, and the number of rows of knots included in the width. The brush shown is 5 rows wide, and 15 knots, about 10 inches long. Flat brushes for nickel scouring are made of extra stiff tampico; they range in width from 2 to 3 rows, and in length from 6 to 8 inches.

Brushes made of cotton and other vegetable fibre are commonly known as potash brushes. They are used for cleaning work requiring

strong alkaline solutions for removing grease. Brushes made of animal fibre cannot be used for this work, as they would soon wear away under the dissolving action of the potash.

Other useful forms of brush are the horse hair sawdust brush shown in fig. 4,566; various forms and sizes of wire foundry brushes shown in fig. 4,567; cup shaped brushes of wire or bristles for watch case work, and steel wire scratch brushes, operated by lathes, for cleaning and removing sand and scale from castings, which cannot be removed by pickling processes. Figs. 4,568 to 4,571 show a circular steel wire casting brush.



FIGS. 4,568 to 4,571.—Hanson and Van Winkle swing type, circular steel wire, casting brush.

The steel wires are twisted in knots and the knots are hung on rods around the hub, as shown in fig. 4,571, so that they will turn around the rods if the work be held too close to the brush wheel. In using the brush the work should be held so as to be just in contact with the ends of the wires. The brush shown is about 15 inches in diameter, and should not be run much faster than at the rate of 1,000 revolutions per minute. If the brush be run too fast, or if the work be held too close, the wires will become crystallized and soon break off. After the brush has been run for a while, the ends of the wires will become bent and drag over the surface of the work; the brush should then be taken off the spindle, turned around, and replaced with the hub next to the collar on the spindle, so that the wire ends will again strike the surface of the work. When the wires are worn out a new set of knot can be readily substituted for the old set by unscrewing the nut N and taking off the hub plate P.

In the packed type of scratch brush, the wires are attached evenly to the surface of the hub. The wires used are stiffer and will wear longer than those of a swing brush, but they are more liable to breakage from careless handling, and do not reach into uneven work as well as the latter.

**Tumbling or Rattling Barrels.**—Small objects, such as small castings, stampings, etc., that are not required to have



square edges, are best cleaned by tumbling, or rattling, as it is called in foundries. Large quantities of work are thus easily and cheaply cleaned without much manual labor, which is the expensive item in polishing. If rough castings are being worked, the sand, scale, etc., adhering to them is allowed to remain in the barrel, where it acts as a polishing powder, brightening the parts which are not reached by the metal of other castings; but when tumbling for a bright finish, the sand, dirt, etc., are exhausted by means of the blower, so that the surfaces are finely polished by friction only—burnished, as it were, by

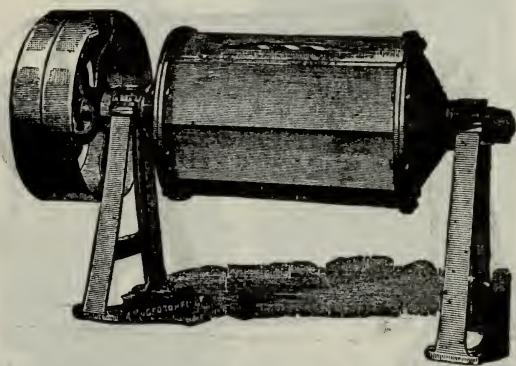


FIG. 4,572.—Hanson and Van Winkle tumbling barrel with convex head for dry tumbling. The type of barrel is especially adapted for removing burrs and for smoothing small castings. This barrel gives three distinct motions to the articles: rolling, shaking, and spreading.

rubbing against other metal of the same kind. A strong exhaust should be kept up when polishing in this way or the finish will be dead instead of bright.

Bright work can only be obtained by long continued tumbling, and the bright finish comes rather quickly after all the pieces in the barrel become smooth, accordingly, it is necessary not to add any pieces once the barrel is charged, or the work will not finish evenly.

**Ques.** How should the speed be regulated in tumbling?

**Ans.** The speed should be so adjusted that the articles will have time to “tumble” down upon and slide over each other as much as possible.

If run too fast, centrifugal force will cause the articles to cling to the sides.

**Steel Ball Burnishing Barrels.**—Burnishing with steel balls is done both on small articles preparatory to plating and also on articles that have been plated and require a highly burnished finish.

This process is intended for burnishing large quantities of small metal articles and for that purpose is more practical, more effective, and more economical than any other method. This process is especially

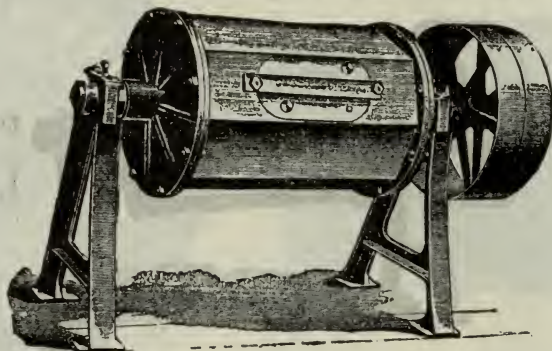


FIG. 4,573.—Hanson and Van Winkle tumbling barrel for wet grinding or polishing. It is intended for sand and water grinding, washing out core sand, etc., and is adapted for brass castings. The barrel is provided with a gland for connecting a water pipe to supply a constant flow of water.

adapted for figured work as the steel balls used readily slide in and out of the crevices, angles, and curves and give the parts being tumbled a high luster that cannot be obtained by any other method.

Almost as fine a surface may be obtained by burnishing in this manner as can be obtained by buffing.

It should be noted that successful burnishing by this method depends upon using enough steel balls of proper size. The balls used run from  $\frac{1}{8}$  inch to  $\frac{1}{4}$  inch in diameter, but for general use the smaller balls do better work.

As the balls do the burnishing enough should always be used, so that the articles will not rub one another. A good rule is to use two pails of ball for each pail of work and for each pail of work a pail of hot water is needed. Before adding the water dissolve in same about six ounces of borax soap, ivory soap, or some other mild, pure quality soap. Common soaps will not answer as they contain alkalies, etc., which attack both the balls and the work.



**Polishing Powders.**—In order to hold fine powders on the wheels and buffs, they must be mixed with some medium that will perform this office and at the same time act as a lubricant to the work.

The best powder consists of the largest proportion of powder per part of "binder."

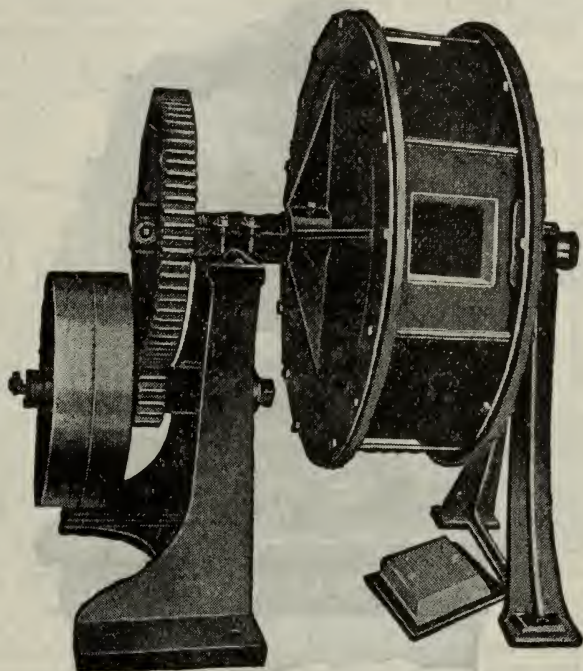


FIG. 4,574.—Hanson and Van Winkle steel ball octagon shape burnishing barrel. It is made of cast iron and has a hard maple lining.

Manufacturers put up powder in the form of a cake that is hard enough so that a small amount of composition may be evenly distributed over the entire cutting surface of the buff by holding the cake against the buff while it is in motion.

Polishes are generally designated by the manufacturer in such a way as to show the metal they are to be used upon, and the grade of polishing material as: Nickel rouge, hard No. 1; nickel rouge, hard No. 2, etc.

The polishing compositions generally employed are various preparations of rouge, tripoli, crocus, white rouge, Vienna lime and powdered pumice stone, described as follows:

**Rouge.** This is used either in stick or powdered form, the former to remove any scratches and to put on the first polish; the latter mixed to the consistency of their soft paste with alcohol and water for giving the finished polish or color. Rouge is put up in various grades, either in hard or powdered form, suitable for use with different kinds of metal.

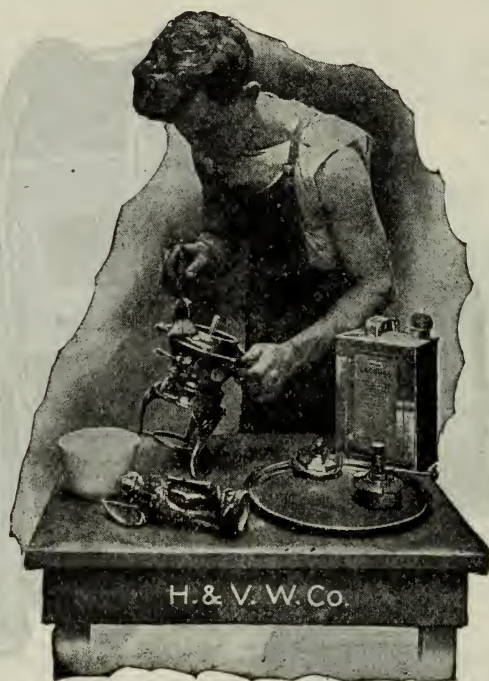


FIG. 4,575.—Method of applying lacquers. **Instructions:** Use a glass tumbler or porcelain cup as a container. Apply a flowing coat with a soft brush. A stiff brush will cause foaming or small air bubbles, and will require a heavier body lacquer. Prepare the work the same as for plating. It must be absolutely clean and free from grease or moisture. It requires only the smallest amount of moisture to ruin the work. Use the lacquer as thin as possible without showing iridescent colors. Dry in a temperature of 100° Fahr., if possible, using a thermometer. Brush lacquers will dry in the ordinary temperature, but baking improves the finish. Iridescent colors are in most cases caused by the lacquer being too thin, or by carelessness in removing the polishing composition or rouge from the work. Iridescent colors will often disappear when the article is given a second coating of lacquer after the first has dried. When the body becomes too heavy it needs thinner. *Be sure to use only a thinner of the same grade as the lacquer.*

These various grades are known by the trade as gold rouge, silver rouge, nickel rouge, brass rouge and glass polishing rouge. Gold rouge is the finest of all.



All gold and silver work being finished on buffs should be washed in hot soap suds containing a little ammonia, then rinsed in hot water and dried in *boxwood* sawdust, or with clean soft rags. Other kinds of sawdust are liable to discolor the metal.

**Tripoli** is used mixed with tallow and beeswax, melted together and run into moulds of convenient size. If made in the shop, care should be taken to avoid the use of an excess of either tallow or beeswax, as the former is liable to stick to the work and may be removed only with great difficulty; while the latter will render the work greasy and dirty, and retard the work of buffing or polishing.



FIG. 4,576.—The lacquer room. When possible, a separate room should be used for lacquering, or a portion of the shop may be partitioned off for the purpose in order to avoid all dust or moisture. If the room be heated by steam pipes, it is advisable to have the regulating valves outside. The lacquer room should be light, dry, and well ventilated. When it is necessary to use artificial light, it is safer and better to use incandescent lamps. Do not have a stove or gaslight near the lacquer room, as both the lacquer and thinner, as well as the gases which arise from them, are very inflammable. The most suitable dryers for this purpose are sheet metal ovens, zinc lined wooden ovens, or wooden closets with dust-proof doors, these to contain a steam radiator with regulating valves on the outside. Rods or hooks can be placed at a convenient height on which to suspend the work with wires. Shelves or racks of wire netting will also be found very convenient. Keep a thermometer in the dryer. Keep the temperature at about 100° Fahr.

**Crocus** is used mixed with tallow and oil, only a sufficient amount of the latter ingredients being used to allow the mixture to be made into cakes, and to furnish the proper lubrication. Crocus compositions are used chiefly for finishing steel goods such as fine cutlery, surgical instruments, tools, etc., which require a high finish. It is also used for finishing plated articles of brass or nickel.

**Vienna lime** is used in buffing nickel and silver ware. In order to be effective it must be used while slacking. It is usually put up in the form of pressed bars which are dipped into paraffine and then wrapped in paraffine paper. This treatment makes it air tight, and prevents it slacking until it is being used, when it is disintegrated with slight pressure, and slacking in the air gives the metal a chemically clear surface. It is extensively employed in watch factories.

**Pumice stone or rotten stone powder** is employed for polishing Britannia metal and other soft metals, which would roughen, become

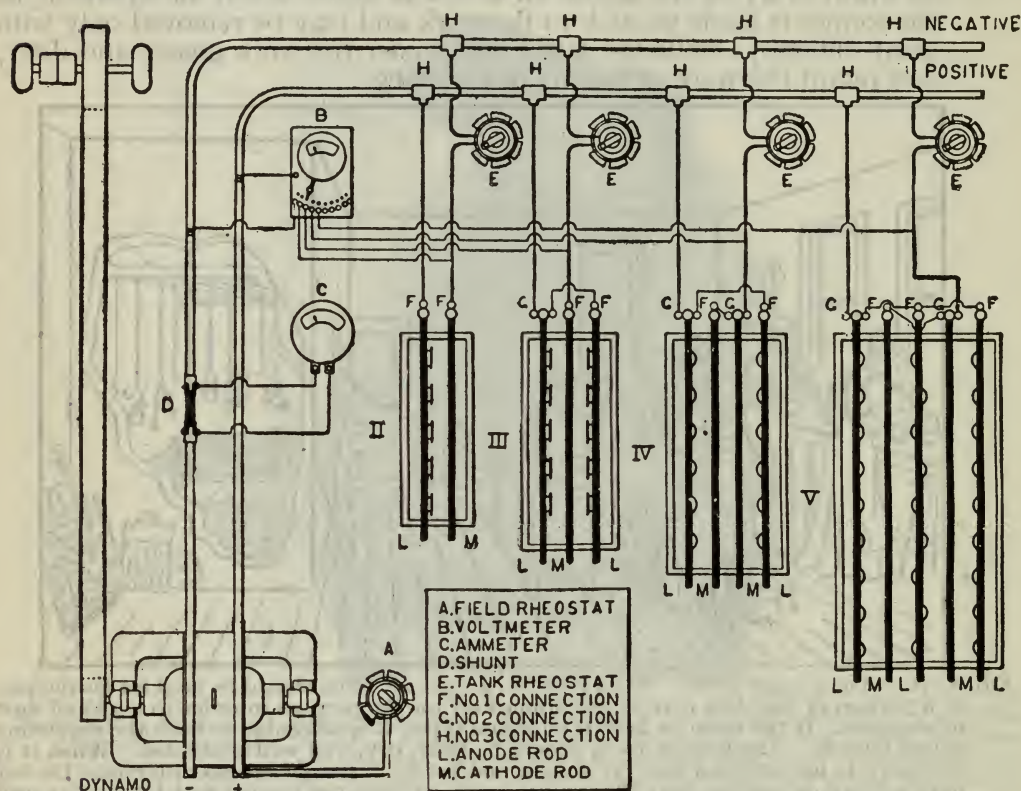


FIG. 4,577.—Wiring details, two wire, four tank installation.

distorted in shape, or melt under the ordinary methods of polishing. Such articles are polished with small leather wheels and bobs of walrus hide, bull neck leather, or sheepskin, according to the requirements of the work, revolving in a box containing the powder mixed with a little oil. The amount of oil used should be just enough to keep down the dust and prevent the powder flying all over the room, but not enough to make the powder lumpy or sticky to the fingers. The polisher holds the work with one hand, so that it will barely touch the wheel, and applies the pumice to the work with the other hand.



## Solutions for Electro-plating with Different Metals.—

These may contain the necessary constituents in various percentages. The following solutions are considered the best in general practice.

**Twenty-four carat Gilding Solution.**—Take 12 pennyweight of pure gold, roll it out as thin as possible with jewelers' rolls. Heat it

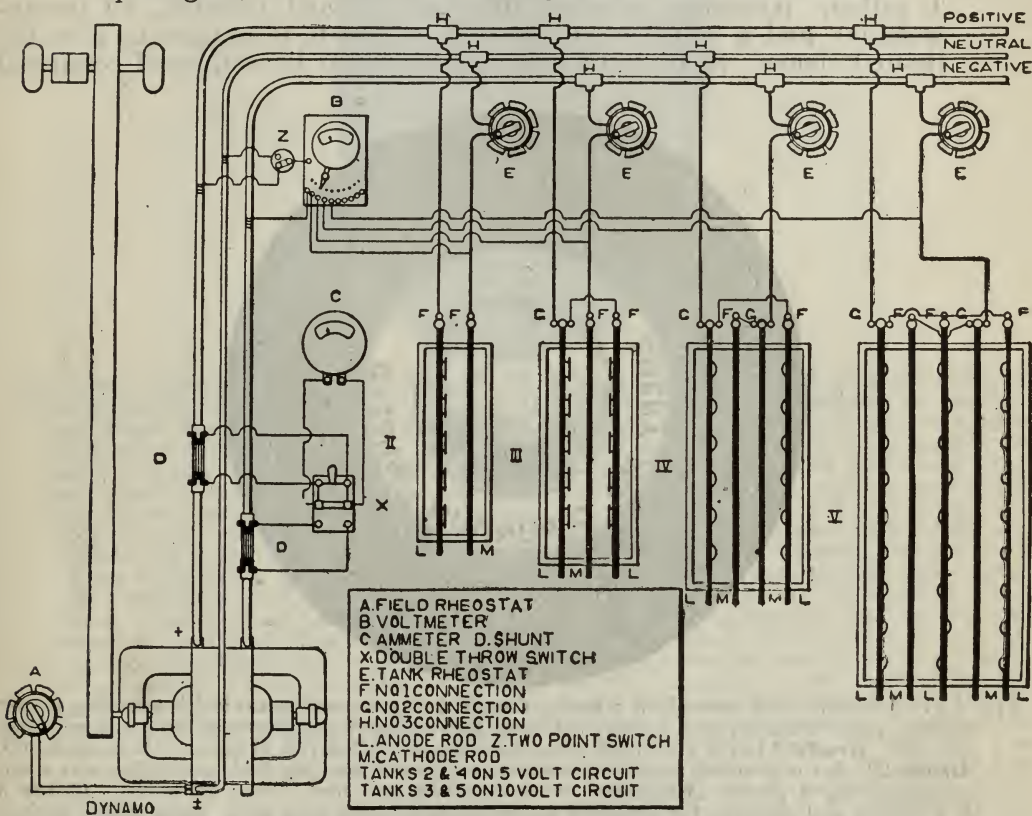


FIG. 4,578.—Wiring details, three wire, four tank installation.

gently with a blow pipe to a red heat, and after it has been allowed to cool, cut it up into small pieces, and place the latter in a porcelain lined evaporating dish. Then pour in two parts C. P. hydrochloric acid, and one part C. P. nitric acid; the latter should be added slowly and stirred with a glass rod. Place the dish in a sand bath over a gentle heat until all the metallic gold disappears, then accelerate the evaporation of the acid by occasionally tipping the dish from side to side until all the acid is evaporated, leaving the chloride of gold on the bottom and sides of the dish, in the form of a brown deposit.

To the chloride of gold thus obtained, add one gallon of distilled or pure soft water and a small quantity of C. P. cyanide of potassium. With a glass rod stir the solution until it assumes an almost colorless appearance; it will then be ready for use. This gilding solution should be worked at a temperature not below 120 degrees Fahr., nor above 130 degrees Fahr. About 20 pennyweight of fine gold should be used for the anode.

**A good 14 carat gold plating solution** is composed of water, 1 gallon; potassium cyanide, 10 ounces; gold chloride, 10 pennyweights; and a sufficient amount of carbonate of copper to give the desired shade. A 14 carat gold anode should be employed composed



FIG. 4,579.—Emery and corundum wheel. **Grade 1** is soft and suitable for grinding planer knives, paper cutting, and leather splitting knives, light surface work and roll grinding. Nos. 36 to 60. **Grade 2** is for gumming saws, and rough chilled roll grinding. Nos. 36 to 60. **Grade 2½** is for grinding moulding cutters, and wood working tools generally, soft steel, mouldboards of plows, and surface work on brass and iron. Nos. 20 to 60. **Grade 3** is medium and suitable for grinding machine shop tools, tool steel, twist drills, surface work, polishing the edges of stoves, and will do a greater variety of work than any other grade. Nos. 30 to 70. **Grade 3¼** is somewhat harder than grade 3, and is used for tool grinding in machine shops. Nos. 36 to 60. **Grade 3½** is for rough work in a machine shop, brass castings, malleable iron, soft foundry castings, ivory, horn, and shell grinding. This is a fast cutting wheel. Nos. 36 to 60. **Grade 3¾** is used for general grinding in foundries; is a faster cutting wheel than grade 4 and is more in use. Nos. 16 to 24. **Grade 4** is medium hard and is adapted to grinding heavy iron castings, malleable and wrought iron, steel castings, stove work, and sprues and gates from heavy castings. Nos. 16 to 24. **Grade 4¼** is a hard wheel, to be used on heavy iron and steel castings, when a faster cutting wheel than grade 4½ is required. Nos. 16 to 20. **Grade 4½** is hard and adapted to grinding heavy iron castings and edge work on iron and steel. Nos. 16 to 20. **Grade 5** is very hard. This wheel is made especially for plow jointing and very hard steel edge grinding; will not do surface work. Nos. 16 to 20. **Grade 6** is made of the finer grades of emery, to be used where there is not much metal to be removed, and where the wheel is expected to retain a certain shape, as in grinding flutes of taps, milling cutters, etc. Nos. 60 to 120.





FIG. 4,580.—Hanson and Van Winkle universal polishing wheel, for all polishing operations that require felt, canvas, or bullneck wheel. **When used for roughing:** A medium soft wheel should be used for brass, steel or malleable iron. The wheel may be a trifle hard when new, but will soften up after a few days' use. The softening process may be aided by pounding the wheel before and after using, just as is done with canvas and other soft wheels. A flat piece of metal should be used for this, in order to avoid denting the face of the wheel. To set up a new wheel, first cut down the face and true with a file, buff stick, or coarse sand paper, while running; it should then be sized with a thin coat of glue to lap the nap. Let it run awhile and then, while still revolving, apply a piece of wet waste and a polistone to the face. This will give it a fine, smooth face. After this preliminary work, take the wheel off the arbor and allow it to dry thoroughly. When dry it is ready to set up with two thin coats of emery. For the first coat use No. 120 emery for a No. 80 wheel, and No. 149 for a No. 120 wheel. This method is unusual, but experience shows this to give best results. After a wheel has been in use long enough to accumulate a body of emery, one coat is usually sufficient, unless the work be very hard, in which case two coats should be applied. When the wheel becomes so thickly coated with emery that it must be cleaned, this may be accomplished by loosening the emery with a piece of iron pipe or a broken casting while the wheel is in motion. The next step is to cut down the face with a buff stock or wheel trimmer. If a flat, smooth surface be desired, hold a piece of wet waste and a polistone on the surface of the wheel while running. Let the wheel dry, then set up in the ordinary manner. Keep the roughing wheel open with a steel wire, flat back foundry hand brush. A twelve inch wheel running 1,800 to 1,900 R. P. M. will give best results on gray or malleable iron and brass. **When used for fining:** For use on iron and steel set it up with No. 140 emery dry; for brass, with No. 120 emery with tallow. Fining wheels are cleaned in the same manner as the roughing wheel, but it is not necessary or advisable to clean them unless they have too much emery. If the wheel get too soft, roll the face in hot water and put in a press or under an iron weight for a couple of hours. This will harden it. **When used for oil or grease wheels:** For this operation it is better to use a wheel that has done service as a fining wheel. No. 140 emery should be used for cast iron and No. 160 emery for malleable iron and steel. Have a spare wheel for use in case there should be trouble with the glue on account of the weather, etc. To clean the oil wheel, use lump pumice stone for removing the grease. Next apply a piece of waste wet in warm water, and a polistone. Keep the waste wet and hold the stone under the waste. The wet waste softens and loosens the glue and the polistone cleans it off. When the wheel is thoroughly cleaned, let it run until dry, then size and set up in the ordinary way. To preserve the cutting qualities of the grease wheel, keep it open with pumice and use tallow instead of oil.

of fine gold and the latter being composed of 80 parts of copper, 83 parts zinc, and 6 parts nickel.

**The best solution for silver plating** is the double cyanide of silver and potassium solution.

The single cyanide of silver is prepared by adding a solution of cyanide of potassium to a solution of nitrate of silver until a precipitate ceases to form.

The double cyanide of silver and potassium is prepared by dissolving an equivalent of silver cyanide (134 parts) in a solution containing an

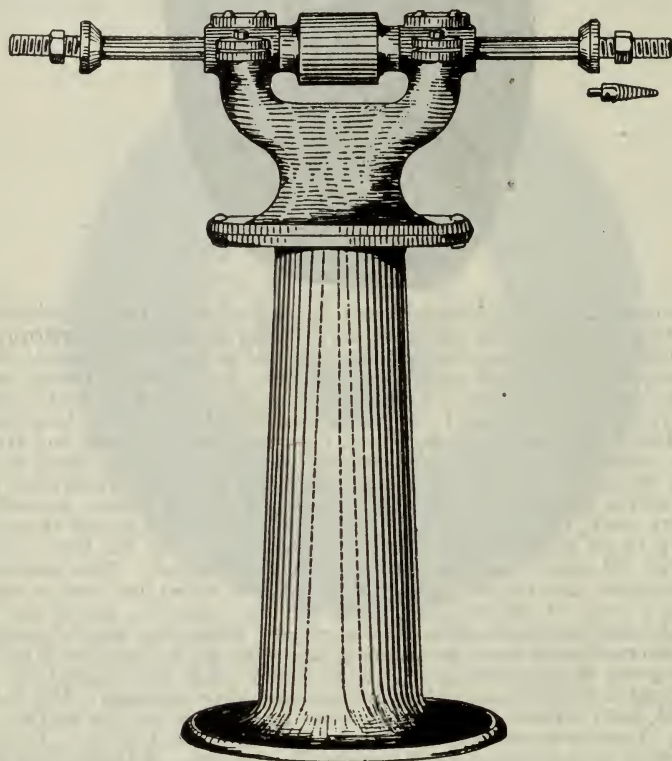


FIG. 4,581.—Polishing and buffing head. Polishing and buffing heads range in size from those sufficiently strong to run wooden polishing wheels up to 16 inches in diameter, and those designed to run 9 or 10 inch buffs at 3,000 revolutions per minute, to those known as light polishing heads, capable of being operated on a bench without the use of a counter shaft.

equivalent of cyanide of potassium (65 parts). The silver plating solution is made up with distilled water, the proportion by weight of silver per gallon of water varying from  $\frac{1}{2}$  ounce to 5 ounces or more.

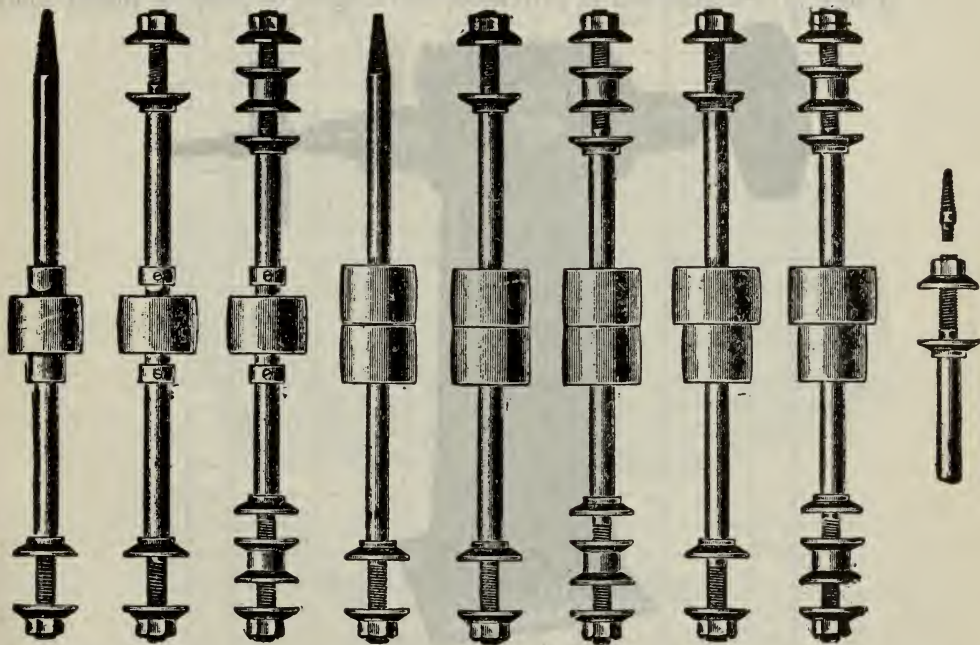
**The best nickel plating solution** is that which is made up of the double sulphate of nickel and ammonium, in the proportion of 12 ounces to one pound of the double salt to each gallon of solution. The crystals



should be dissolved in boiling water in a wooden tub, frequently stirred and cold water added to make up the desired quantity. After the solution has become cool it should be filtered through a large volume, 1,000 gallons or more, held in large lead lined tanks.

**Electro-plating with copper** is employed chiefly to form a coating on iron, steel, tin, zinc, lead, Britannia metal and pewter articles preparatory to silver plating the same, for the reason that silver will not adhere perfectly to those metals, while on the other hand, silver will adhere perfectly to copper and copper to the soft metals.

**The copper plating solutions** employed for this purpose, and for electrotyping are acid solutions of copper sulphate.



FIGS. 4,582 to 4,591.—Steel spindles used with polishing head.

**Polishing and Grinding Machines.**—These machines, or heads consist of a stand carrying a small pulley between two bearings with shaft extended at each end to take the various buffing, polishing and grinding wheels, brushes, etc.

Fig. 4,581, shows a type of polishing and buffing machine suitable for both light and heavy work. It is provided with tapered steel spindles, wide bearings, and is designed for high speed. The forms of steel spindle used for different kinds of work are shown in figs. 4,582 to 4,591.

Foot power polishing wheels are made in a great variety of form, and are chiefly used in small jewelers' establishments for buffing watch cases, rings and other small articles.

**Polishing Wheels.**—These are made of canvas, wood, felt, leather, and walrus hide. Rough heavy castings are first ground upon coarse solid emery or carborundum wheels, usually run at a slow speed, not exceeding 1,000 revolutions per minute.

Where no exhaust fan is provided, some form of glass or metal shade

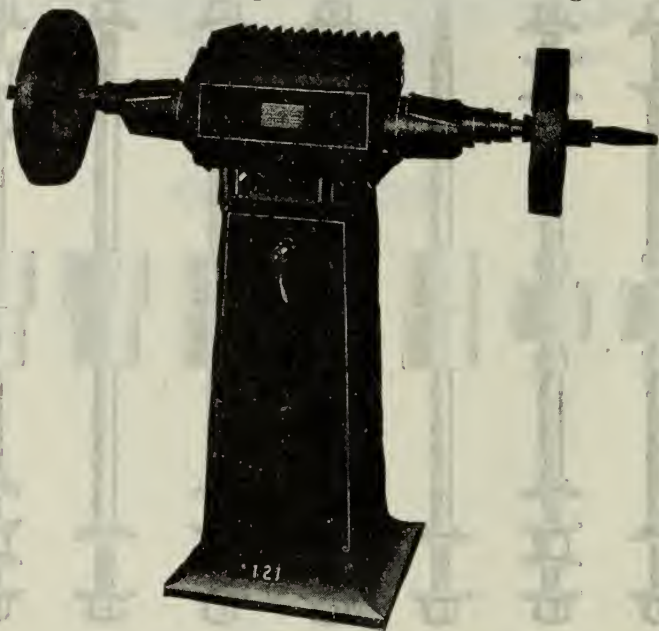


FIG. 4,592.—Hanson and Van Winkle polishing and grinding machine with electric motor drive. The magnetic frame is made of a combination of cast iron and cast steel, having many ribs around the top, back, and bottom to assist in keeping the motor cool under all conditions of load, and enabling it to withstand heavy overloads. The poles are of steel castings, and are of round cross section. The switch, starting box, and regulator are contained within the stand, with the operating handles extending through suitable openings. An important feature of these machines is the ability of operator to regulate the speed of the wheels, running them at the speeds most suitable for the work in hand. This regulation of the speed is accomplished by the simple movement of a handle, the speed remaining practically constant at any point.

should be placed over the wheel for preventing the particles of emery and metal flying into the face and eyes of the workman.

Where emery wheels are continuously used, their grinding surfaces soon become glazed, and tend to cut very slowly. The glaze should be removed by means of an *emery wheel dresser*.



**Canvas wheels** are commonly called *roughing out wheels*.

The first operation in polishing rough castings after they have been trimmed up and the gates removed, is the use of canvas wheels set up in No. 60 or 70 emery. They are composed of several thicknesses of canvas or duck, cut into discs and glued or cemented together to the required thickness. They are not fitted for working on machine parts, tools, etc., in which sharp edges and square corners are necessary.

**Wood wheels** are usually employed for roughing out work in which sharp corners and straight edges must be preserved. As these wheels

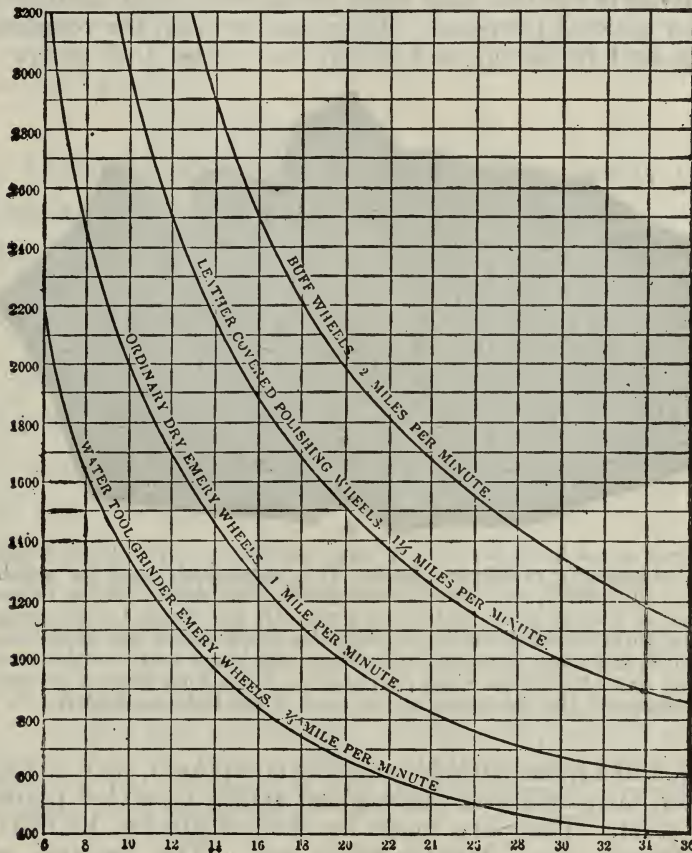


FIG. 4,593.—Speed curves for emery and polishing wheels. There can be no hard and fast rules for the speed of emery and polishing wheels since there is so great a variety in the nature of the work to be done, but a peripheral speed of about a mile a minute for ordinary emery wheels is commonly regarded as good practice. For water tool grinders the speed is usually about two-thirds that of dry grinders, while on the other hand, polishing wheels are generally run at about one and one-half, and buff wheels at twice the speed of dry grinders. The above diagram affords a convenient means for determining the revolutions that will give the above speeds and will be preferred by many to a table of figures. It is only necessary to trace a vertical line from the figure representing the diameter of the wheel to the proper curve and from the intersection point to trace a horizontal line to the figure which will give the revolutions per minute.

are run at speeds ranging from 1,000 to 3,000 revolutions per minute, they are usually built of selected kiln dried lumber one-half inch thick laid up with the grain cross in alternate layers, and then rigidly glued together. They are usually covered with heavy oak tanned leather. They may be used on any work requiring a hard, firm wheel, and they may be set up in any grade of coarse or fine emery.

When the emery begins to wear off, they should be washed in a *wheel washer*, or the old emery and glue may be removed by means of an *emery stick* or buff stick.

**Felt wheels** are the kind most extensively used, as they are the best suited for general purposes. They can be used for roughing, grinding, polishing and finishing, and when the glue and emery have been



FIG. 4,594.—Walrus or sea horse leather. Walrus leather has a peculiarly tough grain making it especially adapted for polishing wheels. It is extensively used for polishing iron, steel, brass, cutlery, silverware, etc., where a fine polish is required. It can be used with emery, crocus, rouge, or rotten stone and gives a smooth fine finish to the work. The leather is used in the form of solid wheels or cut into strips which are used for covering wood wheels. Walrus hides are invariably uneven in thickness and in order to avoid any misunderstanding as to thickness when purchasing, it has long been a recognized custom of the trade to measure the thickness at the part of the hide marked A.

removed, and a little suitable polishing compound, such as rouge or crocus is applied, they will give the highest polish to nickel plated articles of iron or steel. They are made in several grades, known as Mexican brown, French gray, Spanish white, etc. The Spanish white is the most expensive in first cost, but as it lasts longer and gives better results than the others, it is the cheapest and best in the end.

**Walrine wheels** made of Walrus hide represent the most efficient type of leather wheel. Their flexibility and elasticity combined with their hardness render them especially suitable for hard grinding. They are made of discs of hide varying from  $\frac{3}{4}$  to  $1\frac{1}{2}$  inches in thickness. The hides require from three to five years for tanning and possess a very tough grain.



These wheels are used chiefly in giving a fine polish to silverware, brass goods, bicycle parts, stoves, cutlery, edge tools, agricultural implements, etc. They can be used with crocus, emery, rouge, or rotten stone, and give a smooth fine finish to the work.

In using Walrine wheels, screw on spindle only tight enough to hold in place. Any flutter or side motion can be remedied by side pressure of the hand, or by either loosening or tightening the nut on the spindle. Always run in the direction indicated by the arrow marked on the face of the wheel.

For silver, nickel, or brass work, use the *soft* and *medium* grades; for stove, axe and plow work, and for saddlery hardware use the medium grade; for gold, brass, emery hard grinding and for grease or oil work use the hard grade.

**Ques. How do buffing wheels differ from the various kinds of grinding and polishing wheel?**

Ans. They differ in that they are usually made of loose sections of sheep skin, or unbleached cotton cloth or muslin.

**Ques. How are they used?**

Ans. Various kinds of buffing composition are held against the buff from time to time, for setting them up during the progress of the work.

**Ques. At what speed do buffs cut best?**

Ans. At a speed that will make them stand up stiffly.

For cutting down work, buffs should be run at speeds ranging from 10,000 to 15,000 feet per minute, rim velocity, while for coloring work, they should be run from 5,000 to 8,000 feet per minute. As a rule, the larger the buff the greater will be the amount of work that may be accomplished in a given time.

**Pickles and Dips.**—While the best polish is secured by grinding and wheel polishing, many articles are best cleaned chemically by immersing them in solutions which dissolve the scale, grease, etc., adhering to them, leaving a clean but rough surface which must be polished afterwards.

**Ques. What are pickles?**

**Ans.** Solutions intended for prolonged action on rough surfaces.

**Ques. What are dips?**

**Ans.** Solutions intended for momentary action on a surface already smooth.



FIG. 4,595.—Dipping or immersion; a method of chemically cleaning many articles consisting of dipping them in solutions which dissolve the grease scale, etc. Successful dipping depends chiefly upon quick and careful handling rather than upon the dips themselves, and the holes in these baskets should be as large as possible to allow the rapid escape of acid or cyanide. The usual sizes of hole in dipping baskets are  $\frac{1}{8}$ ,  $\frac{1}{4}$ ,  $\frac{3}{8}$ ,  $\frac{1}{2}$ ,  $\frac{5}{8}$ ,  $\frac{3}{4}$ ,  $\frac{7}{8}$ , to 1 inch in diameter.

**Ques. What precautions should be taken in pickling and dipping?**

**Ans.** The articles to be immersed should be clean and dry.

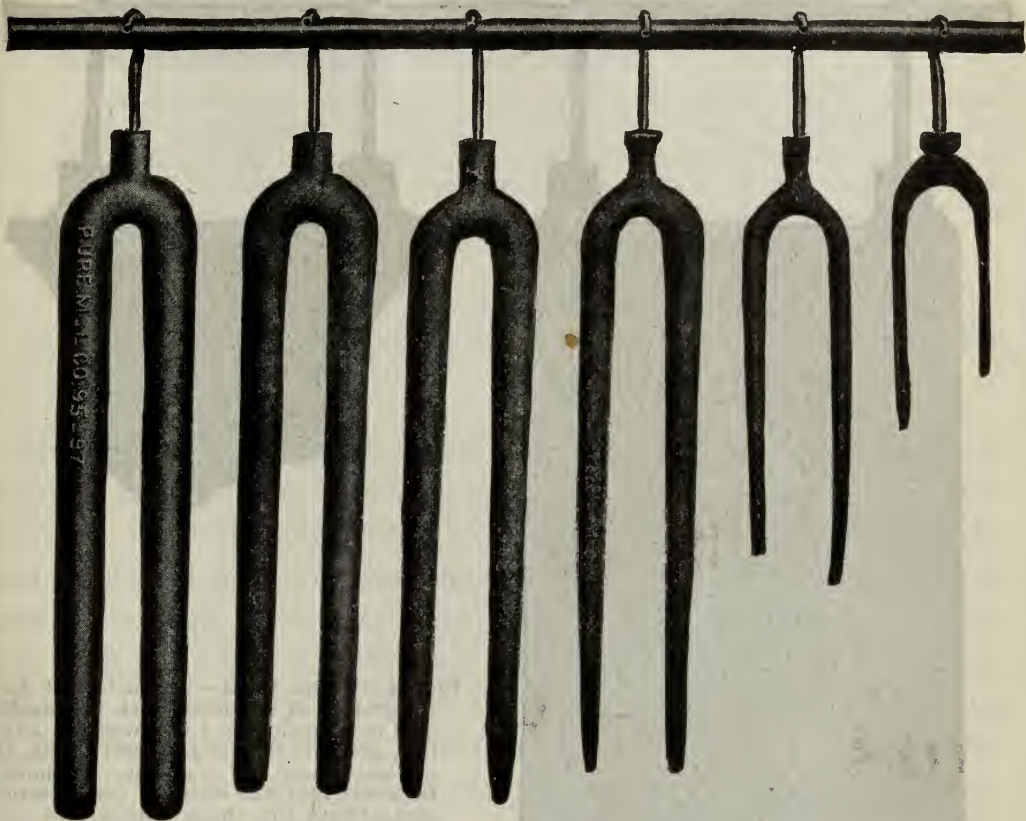
This is secured by dipping the work in boiling lye and then rinsing in boiling water, shaking a moment to drive off the water and then immersing in the dip.

**Black Pickle for Iron:**—Sulphuric acid 66° Baume, 1 part; water, 15 parts. Used chiefly for removing scale from castings and forgings.



**Bright Pickle for Iron:**—Water, 10 quarts; concentrated sulphuric acid, 28 ozs.; zinc, 2 ozs.; nitric acid, 12 ozs. Mix in the order named. The pickle leaves the metal bright.

**Dip for Copper, Brass, etc.:**—Sulphuric acid, 66° Baume, 50 parts by weight; nitric acid, 36° Baume, 100 parts by weight; common salt, 1 part by weight; lamp black, 1 part by weight. Forgings, punchings, etc., are pickled in dilute sulphuric acid to remove scale, and then cleaned and brightened by dipping in the above solution.



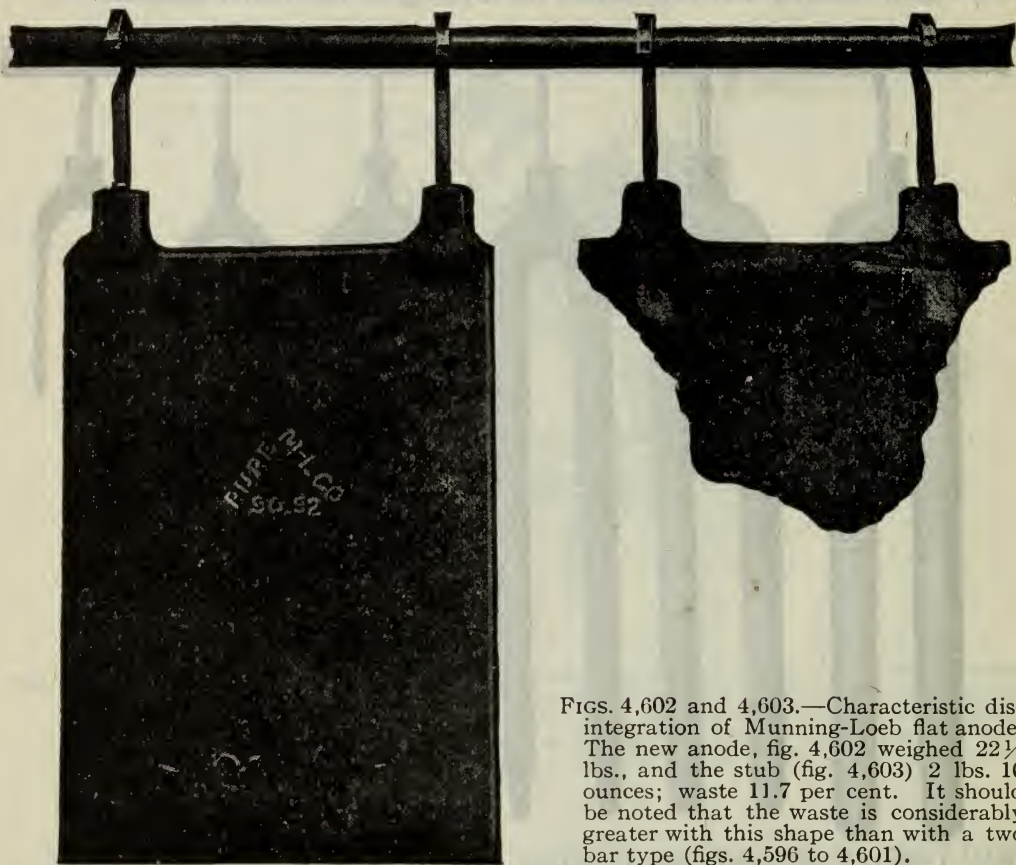
FIGS. 4,596 to 4,601.—Characteristic disintegration stages of Munning-Loeb 2 bar anodes. The nickel anode on the left weighed 14 lbs., that on the right in the last stage of disintegration weighed 8½ ounces; 3.8 per cent. waste.

**Cyanide Dip for Brass:**—Potassium cyanide in ten times its weight of water is used as a preliminary dip when plating articles that would have the polish injured by the acid dips. The work must be allowed to remain longer in this than in the acid solutions.

**Pickle for German Silver:**—German silver may be cleaned in the bright dip for brass, or in a preliminary pickle of dilute nitric acid and

water (12 to 1), followed by a dip of equal parts of sulphuric and nitric acids, and then by rinsing in boiling water and drying in sawdust. Use sawdust that contains no tannin.

**Nickel Plating.**—Nickel, when electrolytically deposited is extremely hard and brittle, and it is not at all easy to deposit to any great degree of thickness, as, after a certain amount has



FIGS. 4,602 and 4,603.—Characteristic disintegration of Munning-Loeb flat anode. The new anode, fig. 4,602 weighed  $22\frac{1}{2}$  lbs., and the stub (fig. 4,603) 2 lbs. 10 ounces; waste 11.7 per cent. It should be noted that the waste is considerably greater with this shape than with a two bar type (figs. 4,596 to 4,601).

been plated on, it is inclined to flake off. It does not adhere very well to iron or steel articles, and furthermore, if after being plated upon steel, the article becomes scratched, the steel rusts, and the rust, getting beneath the nickel film, causes it to peel off. It is, therefore, very usual to first coat the iron with a film of copper, which, being a soft metal, is not readily removed by



scratching. The nickel is then deposited upon the copper coating. Nickel cannot be deposited from solutions containing more than a trace of acid; most nickel plating solutions consist of a solution of the double salt of ammonium sulphate and nickel sulphate, which is rendered alkaline with ammonia.

In order to obtain a thoroughly satisfactory and brilliant deposit of nickel, the articles which are to be plated must be very carefully prepared, and should have a burnished surface.

The minutest scratches upon the goods to be plated can be seen even after a considerable thickness of nickel has been deposited. It has been found that the addition of minute quantities of carbon disulphide to the plating bath causes the metal to be deposited in a very brilliant form, the addition of small quantities of boric acid also improved the appearance of the deposited metal.

Since plated nickel has such an extremely hard surface, it is important that the metal should be plated in a brilliant form, because it is extremely difficult to burnish should the deposited metal have a dull appearance.

**Electrotyping.**—In preparing electrotypes a wax impression is taken of the form, which is made up usually of type, or illustrations, or both. In order to do this a metal plate is evenly coated with a wax composition, and this is placed with the wax face downward upon the form. The form with the wax upon it is then placed in a hydraulic press and subjected to a steady pressure of about two tons to the square inch. To prevent the type adhering to the wax, it is dusted over with finely powdered graphite. After being taken out of the press, the wax is carefully removed from the type, and then graphited in order to render the surface conducting. It is then thoroughly washed with water.

Although graphite will conduct the current by simply placing a prepared plate in the bath, it is not always easy to obtain good contact. It is usual, therefore, to either coat the mould with copper by some chemical process, or to drive little brass nails through the wax in order to make electrical contact with the metal plate at the back, and thereby get the current evenly distributed over the surface. Of course, the

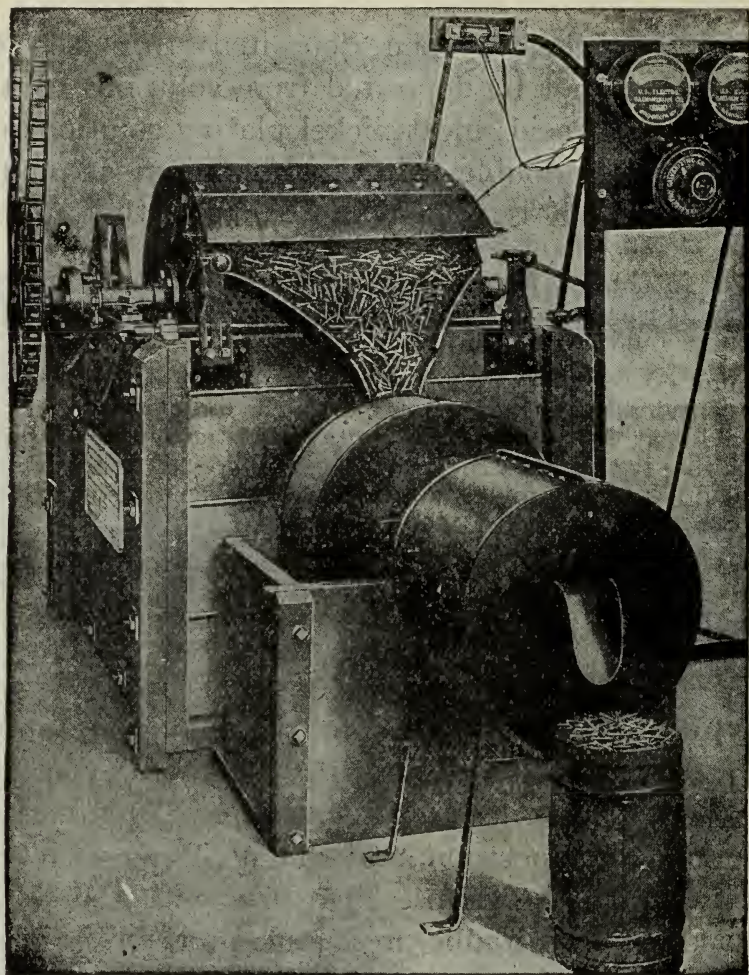


FIG. 4,604.—U. S. electro-plating and self-emptying barrel for brass, nickel, copper, tin, zinc, etc.

**Method of galvanizing:** After pickling and cleaning the material the galvanizing barrel is then filled by means of pails, shovels, etc., with from 150 to 200 lbs. of material at a time, and is then started to turn slowly "in the galvanizing direction," and in about 40 to 50 minutes the material is finished. Upon reversing the motion of the barrel, it thereupon empties the galvanized material (in from three to four minutes) into the washing drum of the washing and drying apparatus and gradually goes into draining drum, from there to drying drum, from there into whatever receptacle is placed for receiving the material ready for shipment.

**Quality and thickness of coating:** The thickness of the coating can be regulated according to requirements, and depends upon the length of time the material is allowed to remain in the galvanizing barrel while galvanizing. The coating deposited consists of chemically pure zinc, uniformly smooth. With the apparatus, one laborer can attend to two barrels and turn out from 3,000 to 5,000 lbs. of material per day; two men and a boy will be able to attend to about six barrels.

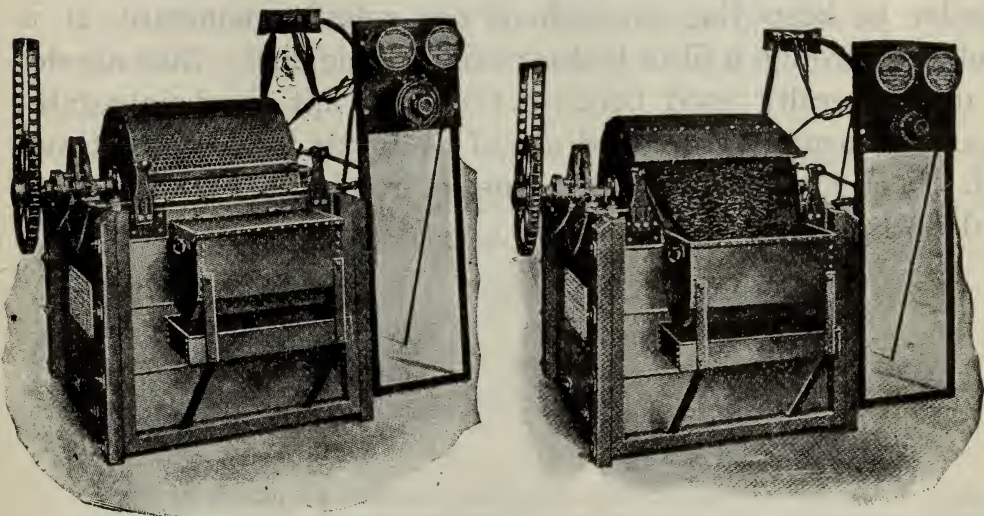
**Cost of galvanizing:** This depends on the number of barrel in use, thickness of coating required, and upon the nature of the material treated. It is equivalent to from 25 to 40 cents per 100 lbs.

**Range of the barrel:** The barrel will galvanize any kind of small material as, for instance: bolts and nuts (from the smallest size to 8 in. long), nails, rivets, spikes, screws, small castings and fittings, stampings, sash pulleys, lag screws, washers, springs, etc., in fact all such material excepting that having very deep recesses or hollow material which requires inside galvanizing.



nails must only be driven in between spaces, otherwise the impressions of the type would be injured. The chemical method is the better one. The mould, after having been washed, is covered with a solution of copper sulphate and then fine iron filings are sprinkled over it; in about half a minute by this means the whole surface becomes covered with a thin coating of metallic copper. The excess of copper sulphate and the iron filings are washed off with a jet of water, and the mould placed in the depositing vat, being so hung that the coppered part faces the anode.

The time required for the production of the copper shell varies considerably in different establishments. When the electrolyte is in good condition, and is heated to the correct temperature, high current densities may be employed, and a shell of sufficient thickness can be prepared in from 30 to 40 minutes. In most electrotyping works a considerably longer time is, however, employed.



FIGS. 4,605 and 4,606.—U. S. electro plating barrel. Fig. 4,605, view while plating; fig. 4,606, view while emptying. It empties by lifting a lever which reverses the motion of the barrel.

When a sufficiently thick deposit has been obtained (and this varies with the work for which the electrotype is required) the mould is taken out of the bath, and the shell separated from the wax by pouring hot water on it, or with a jet of steam.

In the case of electrotypes used for lettering or illustrating the outsides of books, very heavy deposits are made.

The next process is to pour the backing metal into the copper 'shell' to make it a standard thickness. The shell is carefully cleaned and painted over with soldering fluid, and then a double sheet of tin foil spread over it. The shell is now placed on a sheet of iron, and floated upon a bath of melted "stereo" metal. The tin foil melts and produces

an even coating all over the inner surface of the copper mould. As soon as the whole of the foil has melted the plate is removed from the bath and placed on a slightly recessed iron table. "Stereo" metal is now poured in until the shell is completely filled. It is then allowed to cool. The next process consists in planing down the back, bevelling the edges and hammering up any depressions. Any shell spaces which might get in the way during printing are then "routed" out, and the "electro" is mounted "type high" either on metal or on wood, and is now ready for the printing press.

**Galvanizing.**—A bath containing zinc sulphate, which must only be slightly acid, is employed; as the electrolysis proceeds the solution becomes acid by the zinc being deposited out, and in order to keep the strength of the solution constant, it is circulated through a filter bed containing zinc dust. Zinc anodes are not generally used because they are apt to disintegrate; the anodes usually employed are of lead, but iron is sometimes used. In fact, the presence of a trace of iron in the bath improves the deposit.



## CHAPTER LXXXVII

## ELECTRO-THERAPEUTICS

By definition electro-therapeutics is *the treatment of disease by electricity*; it embraces the laws, principles, and doctrines of such treatment.

Electricity is of special value in the treatment of various forms of nerve lesion, thus giving a distinct place in the practice of every reputable physician.

The kinds of electricity used may be classed as.

1. So called static;
2. Current;
3. Radiant.

Such terms as *galvanic electricity* (produced by means of a primary battery), and *faradic electricity* (produced by secondary induction coils), are commonly, though ill advisedly, used by the medical profession.

**Ques.** How is the so called static electricity produced?

**Ans.** By influence machines.

The principal types of influence machine are the Wimshurst and the Toepler-Holtz.

Fig. 4,607 shows a Baker static machine of the Toepler-Holtz type. The central plate A, is of glass, and is stationary. The outside plates B, one on each side of the plate A, are mounted on a common shaft, rotatable either by a crank handle, as in the smaller machines, or by

electric motor drive in the case of large high speed machines. The outside or revolving plates in this particular machine are constructed of a patent fibrous material in the form of a sheet, which extend over the entire area of the plate and are pinned together in cement and hardened under hydraulic pressure. They are of extremely high insulation and are not resonant like glass and mica. The operation of the machine is explained under the figure.

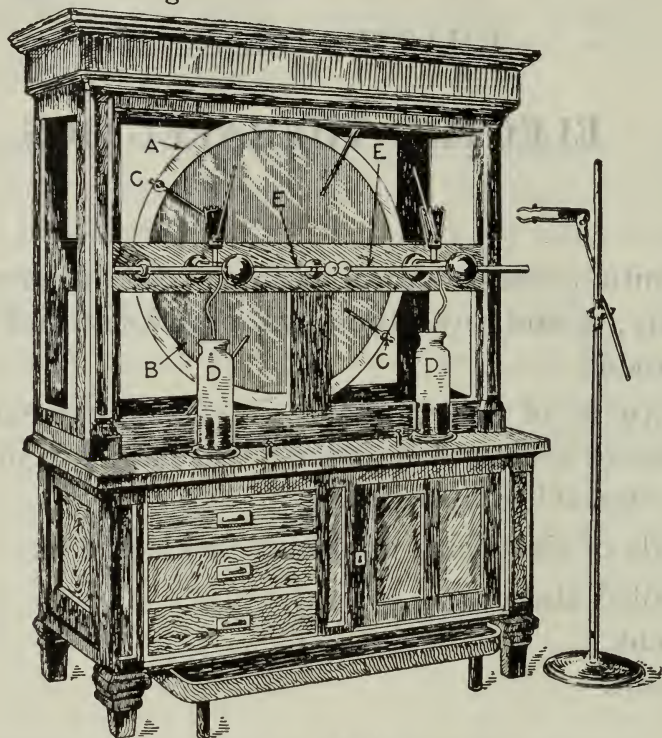


FIG. 4,607.—Toepler-Holtz influence machine. Its principle of operation is induction. **In operation,** an initial charge is required. This is given to one of the metallic surfaced field plates, cemented to the stationary plate. When the outside plates are revolved, the tinfoil buttons—current carriers, on their external surfaces become charged inductively as they pass the field plates, a brush of fine brass wire permitting the escape of the electricity of the same kind as that of the charge of the field plate. The carriers thus charged pass the collecting combs, C, C', communicating to the latter a portion of their charges. They are then discharged by a neutralizing brush similar to the brass wire contact brush, already mentioned, and connecting with the field plates, thus increasing the charge of the latter. Since there are two field plates, located opposite each other on the stationary plate, but charged with opposite kinds of electricity, the process of recharge and discharge becomes continuous. The electricity for the collecting combs connecting with the main conductors passes to the Leyden jars D, D', where it is collected in the form of a powerful static charge. The charges on the field plates increase automatically until the leakage between the plates equals the additions to the charges. The leakage, therefore, limits the maximum voltage obtainable. When the discharging rods E, E', are close together, the electrical pressure obtained is lower, due to the smaller pressure required for a spark discharge across the air gap. With a lower pressure, the discharges will occur in rapid succession. Increasing the distance between the knobs of the discharging rods will give an increase of pressure attended by a diminished frequency of discharge. *The effect of the Leyden jars* is to diminish the electrostatic resistance between the main terminals of the machine, thereby enabling a given voltage, to accumulate a greater charge between the terminals.



**Ques.** What precaution should be taken in operating influence machines?

**Ans.** Great care should be taken to maintain their insulation, especially during damp weather, so as to reduce the leakage to a minimum. The different parts and conductors, particularly all glass parts which are liable to become coated with conducting films of moisture, should be covered with shellac, varnish or paraffin. The better class of machine is enclosed in a glass

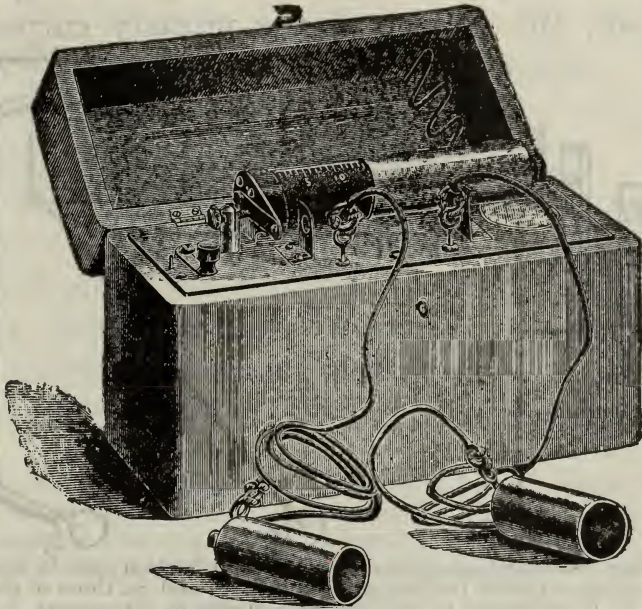


FIG. 4,603.—Medical induction coil, or faradic battery set. *In operation* metallic tube A is moved over the surface of the secondary coil. The latter is practically an independent secondary coil made up of a single turn, having a very low resistance. Its presence has a reactive influence on the primary circuit, which increases the further the tube is pushed over the coil, thereby reducing the induced voltage in the secondary coil. The current through the external circuit, including the body of the patient, when the resistance of the latter and the voltage at the secondary terminals of a coil are known may be determined by Ohm's law as follows: assuming the resistance of the external circuit as 3,000 ohms, and the pressure at the secondary terminals 8 volts, the current through the external circuit will be  $(8 \div 3,000) = 2\frac{2}{3}$  milli-amperes.

case, and the air within kept dry by the absorbing property of calcium chloride or other highly hygroscopic substance.

**Induction Coils.**—These are employed chiefly for the application of currents of varying voltage, strength and

frequency and wave form directly to the patient, and for supplying the high frequency current required from the operation of vacuum tubes.

All medical induction coils are of practically similar construction, consisting of a primary and secondary coil in mutual inductive relation to each other, a core made up of a bundle of soft iron wires, and an interrupter to vary the frequency of the primary current. The number of turn in the primary and secondary coils, the voltage of the primary current, and the

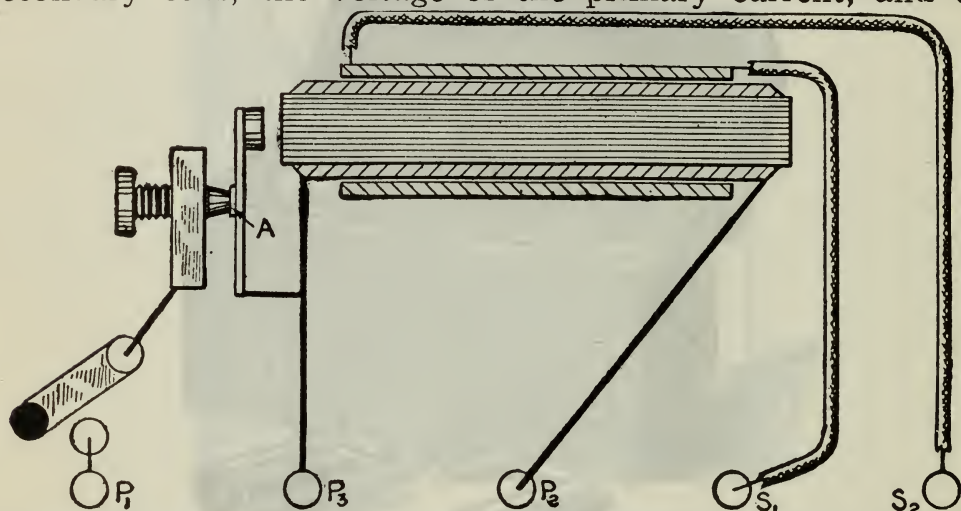


FIG. 4,609.—Diagram showing connections of a medical induction coil.  $P_1$  and  $P_2$ , are the terminals of the primary circuit (including vibrator).  $S_1$  and  $S_2$ , those of the secondary coil. The terminal  $P_3$ , is connected to the vibrating spring or interrupter *A*. **In operation**, when the vibrator spring breaks the circuit, the pressure in the primary circuit will be generated between the terminals  $P_2$  and  $P_3$ , while that due to mutual induction will be developed between the terminals  $S_1$  and  $S_2$ , of the secondary coil. The voltages supplied from the two sets of terminal are quite different, however, as  $S_1$  and  $S_2$ , will supply the same both at the making and breaking of the primary circuit, in opposite direction, on the other hand, the voltage obtainable from  $P_2$  and  $P_3$ , will be practically zero at making, and rise to its full value suddenly at breaking. The primaries of medical induction coils consist of from 4 to 6 layers of No. 24, 22, or 20 wire, according to the dimensions of the coil, while the secondaries are wound with No. 36, or 34 wire.

manner in which the mutual induction between the coils is varied, depends entirely upon the purpose for which the coil is used.

The value of the voltage induced in the secondary circuit depends on the number of turn in the secondary coil and the frequency of the primary current.



When the interrupter consists of a vibrating spring, alterations of the frequency in the primary circuit are made by means of the spring contact screw. Increasing the tension of the vibrating spring and reducing its range of vibration increases the frequency, and *vice versa*. Ordinary spring vibrators give a frequency of from 150 to 300 cycles per second.

The action of a coil varies greatly, not only with variations in the rate of frequency, but also with the character of the interrupter. The use of slow speed spring vibrators give powerful secondary currents.

The connections of a medical coil is shown in fig. 4,609. Usually, they are so arranged that the pressure induced in either the primary or secondary circuits may be externally used.

Induction coils or spark coils may be operated:

1. By means of either primary batteries or storage batteries, through vibrators or rotary circuit breakers;
2. From direct current electric light circuits operating small motor generators for producing low tension currents;
3. By connecting the primary winding directly to electric light circuits through suitable resistance and contact breakers;
4. From alternating current electric light circuits in connection with an air gap, a *Tesla* coil, and a suitable condenser.

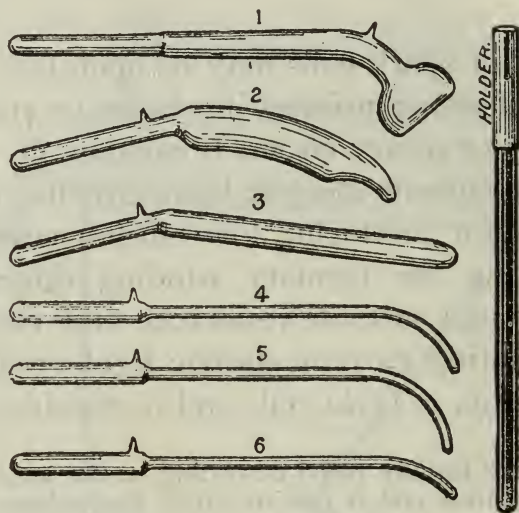
Spark coils are usually rated according to the length of spark. For instance, a two inch coil is one in which the voltage in the circuit is high enough to cause a spark to jump across an air gap of two inches between the knobs of the secondary terminals.

**High Frequency Apparatus.**—This is used for therapeutic or radiographic purposes, and includes various forms of alternators producing directly frequencies up to 10,000 cycles per second; powerful induction coils charging condenser, which produce high pressures through the discharging circuit, in a manner similar to that of influence machines through the medium of Leyden jars; and suitable influence machines.

**Ques.** How are high frequency discharges applied in the treatment of diseased parts?

Ans. By means of tubular glass electrodes which are properly shaped to fit the cavities for which they are intended, as shown in figs. 4,610 to 4,616, thus avoiding the possibility of their becoming broken therein.

**Interrupters.**—For the successful operation of an induction coil, the current must be rapidly interrupted. There are various methods of interrupting the current which may be classed as



FIGS. 4,610 to 4,616.—High frequency electrodes for treatment of diseased parts. The set comprises suitable tubes for vaginal, rectum, throat, nose, and general application, and an insulated universal holder.

1. Magnetic;
2. Electrolytic;
3. Mechanical.

The ordinary “vibrator” placed on many coils, represents the magnetic method, and though called a vibrator, it is in fact a magnetic interrupter.

**Ques. Describe the Wehnelt electrolytic interrupter?**

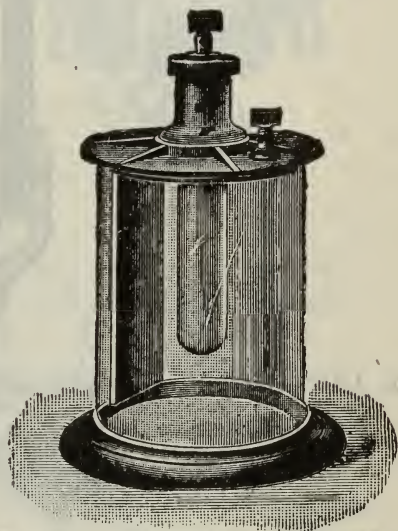
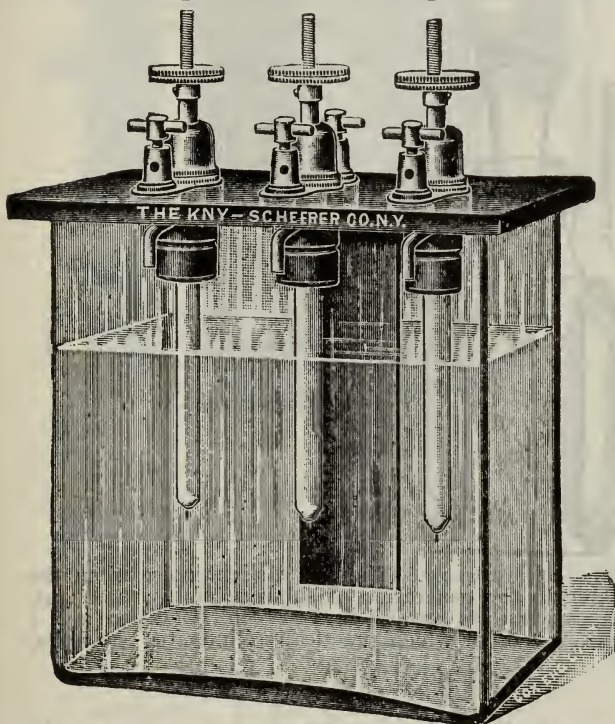
Ans. It consists of a porcelain jar, a large lead electrode, a small platinum electrode, and an electrolyte consisting of



dilute sulphuric acid. The platinum parts are mounted on a lead stem and protrude through a porcelain tube.

**Ques. Explain its operation?**

Ans. When the electric current flows through the electrolyte from the small platinum electrode to the large lead electrode, bubbles of gas form at the platinum point, momentarily stopping



FIGS. 4,617 and 4,618.—Wehnelt electrolytic interrupters. Fig. 4,617, 3 point interrupter; fig. 4,618, 1 point interrupter. In the multi-point type two or more anodes can be used at one time in parallel, thus more current can be passed through the primary.

the passage of the current. The bubbles are absorbed by the electrolytic action and the current flows again and this operation is continually repeated.

**Ques. How is the current regulated?**

Ans. The amount of current that will pass depends on the size of the platinum point, also on the amount exposed.

For this reason a multi-point interrupter is preferable, allowing a selection of the various sized points.

For practical work the three point type is the more successful. When a great volume of current is necessary for radiographic work, the heavy point is used; for medium or lighter work, the medium point, and for prolonged treatment, the smallest point, which operates the outfit on one-fourth to one-tenth the current consumed by the larger point.

For prolonged use an interrupter should have a metal water jacket to prevent heating.

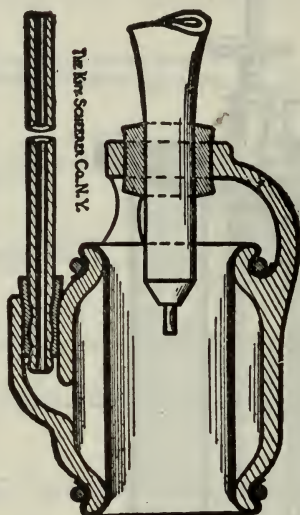


FIG. 4,619.—Muffler for Wehnelt electrolytic interrupter. There is a slight noise when the electrolytic interrupter is in action due to the generation of sulphide of hydrogen gas. This is hardly objectionable, but as patients are usually in a nervous condition and a sound may figure as a disturbing factor, a muffler which practically eliminates the noise, is desirable.

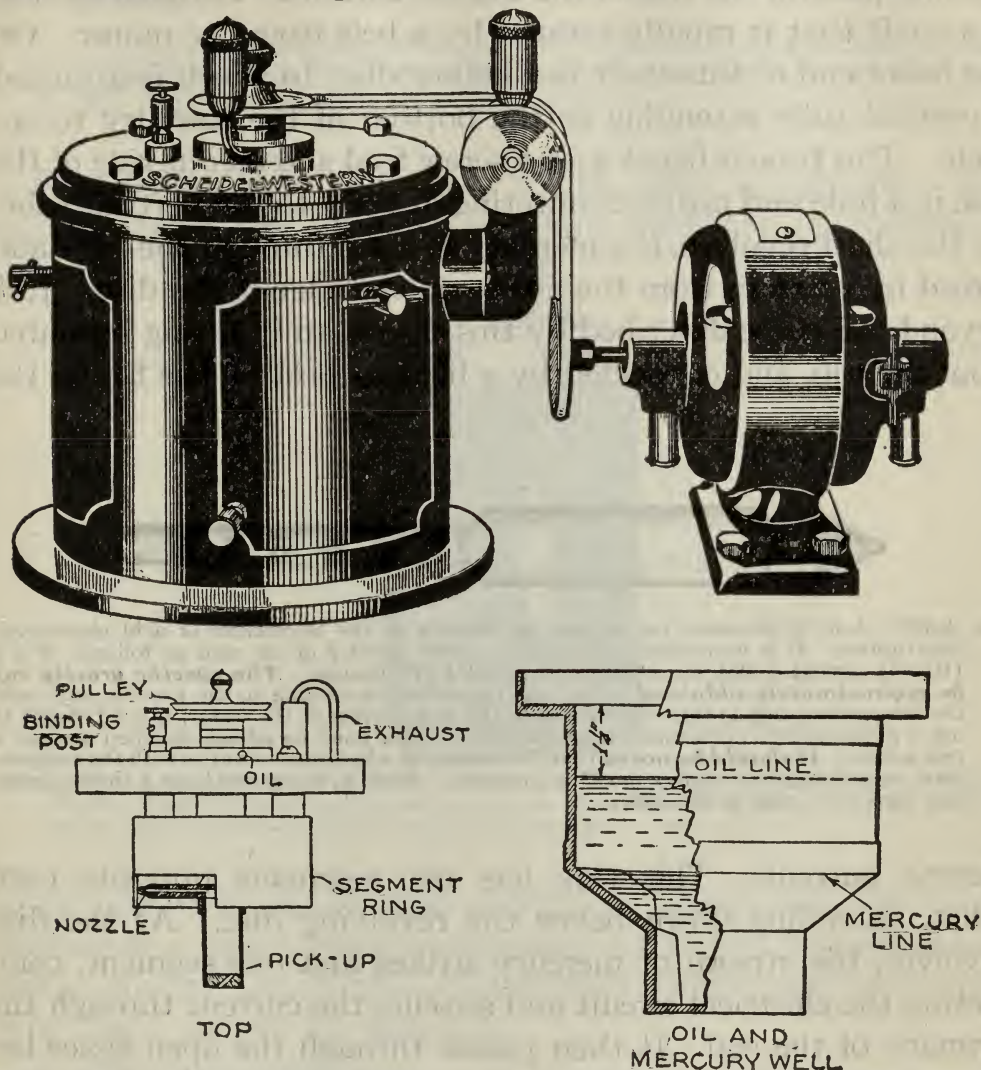
**Ques.** Describe, and explain the action of an anti-acid interrupter.

**Ans.** As its name implies no acid is used, the electrolyte consisting of an alkaline solution. By using an aluminum plate in place of a lead plate, it acts on alternating current both as a rectifier, and an interrupter.

For continuous service as in treatment, the anti-acid interrupter can be readily substituted for the mercury interrupter, when the latter has been used with a rectifier with indifferent results.



**Ques.** Describe the construction and operation of the mechanical interrupter shown in figs. 4,620 to 4,622.



FIGS. 4,620 to 4,622.—Scheidel-Western mercury turbine or *mechanical interrupter*.

Fig. 4,620, view of interrupter and motor; fig. 4,621, mechanical parts; fig. 4,622, oil and mercury well. When an induction coil is used with direct current for considerable periods for X ray treatment, for fluoroscopic work, or for operating a resonator, a mechanical interrupter will be found more desirable than the electrolytic type. If an electrolytic interrupter be used for such work, the solution heats by continual use, the rate of interruption varies and there is considerable wear on the platinum points. It should be noted, however, that the electrolytic interrupter passes a greater amount of current than is possible with the mercury type, and accordingly is more efficient for rapid radiographic work. The mercury interrupter is not as suitable for alternating as for direct current even if a rectifier be employed; for alternating current an anti-acid interrupter is preferable.

Ans. Mercury is placed in an iron vessel connected by a binding post on the side of the electric current. Through the top is a shaft that is rapidly rotated by a belt from the motor. On the lower end of this shaft is a hollow disc, to which is attached a vertical tube extending to the bottom of the mercury receptacle. This tube is fitted with a screw feed and on one side of the disc is a hole and nozzle connecting directly to the vertical tube. As the shaft revolves, the mercury is lifted through the tube and forced in a stream from the nozzle on the edge of the disc. Just beyond the circle described by this disc is an iron ring insulated from the top, and connected by a binding post on the top to the



FIG. 4,623.—Acid hydrometer for testing the density of the electrolyte of acid electrolytic interrupters. It is important to have the specific gravity of the acid as follows: For a 110 volt current, 1,220; for a 220 volt current 1,070 Baume. **The specific gravity can be approximately obtained** by mixing ingredients according to the formula sent with the interrupter, but as this will vary from the evaporation of the water, it is advisable to use a hydrometer to determine when (*distilled*) water must be added, or when making a new solution. **It should be noted** that the reading of a hydrometer varies with the temperature, accordingly the reading must be corrected. Some hydrometers have a thermometer and correction scale in the neck.

electric current. This ring has two segments opposite each other, extending down below the revolving disc. As the disc revolves, the stream of mercury strikes first one segment, completing the electrical circuit and sending the current through the primary of the coil. It then passes through the open space between the segments, breaking the contact, and striking the other segment, making contact again, and so on, completing the revolution, making and breaking circuit twice. The rate of these interruptions is varied by the speed at which the revolving disc rotates and is controlled through a separate rheostat that varies the speed of the motor.



In order to produce a satisfactory discharge from the secondary of the coil, the interruptions must be very rapid and at perfectly regular intervals.

To prevent oxidation of the mercury from the arc and to make a sharp break, the part of the interrupter above the mercury is partly filled with 175° flash test kerosene oil or Elaine oil.

**Rectifiers.**—The physician whose office is supplied with alternating current finds it necessary upon the installation of

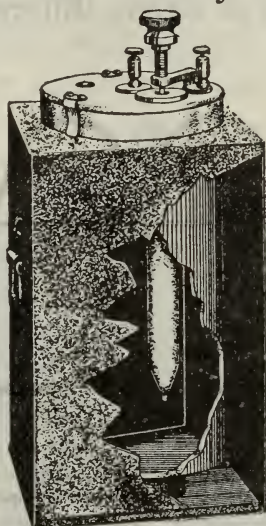


FIG. 4,624.—Scheidel-Western anti-acid interrupter. In this type of interrupter an alkaline solution is used. By using an aluminum plate in place of the lead plate, it acts as the alternating current both as a rectifier and an interrupter.

a wall plate to put in some device to change the alternating current to a direct current possessing the proper proportions for use in galvanic application. Alternating current may be changed into direct current by means of

1. Rotary converters, or
2. Rectifiers.

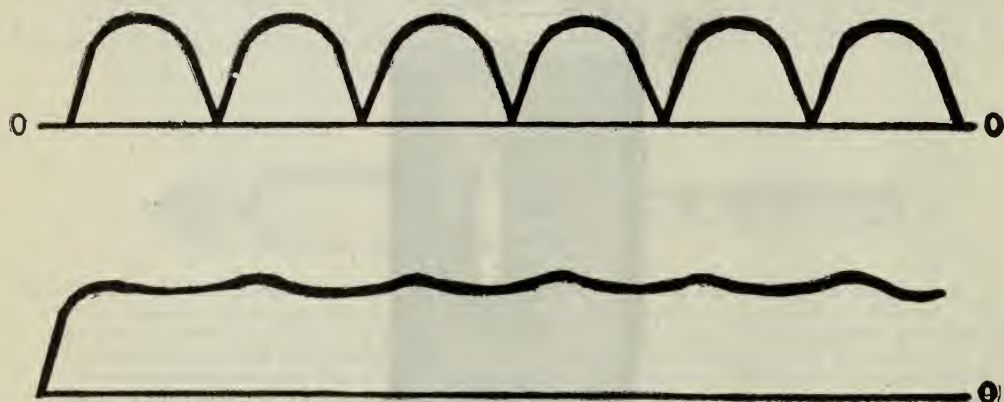
Both are satisfactory, but the converter is much more expensive to install.

**Ques.** Describe a rectifier and explain its operation.

**Ans.** It consists of steel and aluminum electrodes in an

alkaline solution, the combination or cell acts as a valve, permitting the current to pass from the steel to the aluminum plates, but not in the opposite direction (from the aluminum to the steel). In this way a uni-directional current is obtained, on which an electrolytic interrupter will operate.

**Currents used in Electro-therapeutics.**—Many kinds of electric current are used, to secure different effects, all of which may be classed as



FIGS. 4,625 and 4,626.—Electrolytic rectifier current curves. The electrolytic or chemical rectifier, operating on the principle of transposing one half of the alternating current cycle, delivers a direct current possessing the polar properties required in galvanism, but consisting of a number of minute impulses of current flowing in the same direction and joined together as indicated in fig. 4,625. The current thus produced is capable of producing the same chemical reaction as the current from a dynamo, or battery, although there is quite a noticeable pulsation in the current due to the undulation in voltage as is noted by observing the rise and fall of the pressure as in fig. 4,625. It has been found that by connecting a condenser across the direct current terminals of the rectifier that the undulation of the voltage indicated in fig. 4,625 is equalized as shown in fig. 4,626, so that the current delivered possesses an almost unwavering strength.

1. Direct;
2. Intermittent;
3. Alternating, or some modification formed by combination.

The apparatus used permits of many modifications. Usually a dial selector switch is provided by means of which any of the currents may be obtained, thus producing various changes, as: frequency control; primary faradic wave; secondary faradic



wave, interrupted galvanic wave; combined galvanic and faradic wave, etc.

**The Selection of Electrodes.**—The physician entering the field of electro-therapeutics finds the selection of suitable electrodes a rather perplexing problem, especially as some writers recommend the use of some favorite metal in almost every conceivable application. Neiswanger is partial to copper, Massey holds fast to zinc, and Martin is a strong advocate of platinum. The matter really resolves itself to the question:

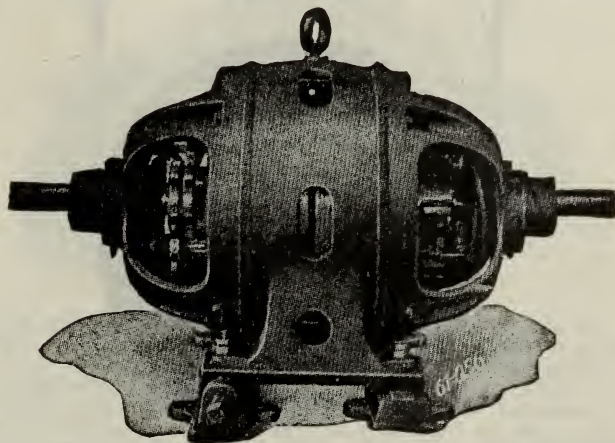


FIG. 4,627.—Scheidel-Western single phase rotary converter for changing alternating current to direct current for operating X ray coils, and other apparatus when a very large amount of current is desired for short periods.

“Shall the particular electrode be soluble or insoluble?” in other words, shall it be immune or subject to the electrolytic decomposition which takes place at the positive pole?

The following items will be found helpful in the matter of selecting electrodes.

**The positive pole** of the galvanic current liberates and attracts the atoms of oxygen and chlorine found in the fluids of the body which attack the metal composing the electrode; and if it be one of the baser metals, such as copper, zinc, or iron, a salt is readily formed; this constituting the oxy-chloride of the respective metal.

**The negative pole** gives rise to no such decomposition as takes place at the positive, and hence, the metal is not an important factor, although

nickel plated instruments are usually utilized for special applications with this pole, because they do not tarnish or rust.

*The faradic current* has no chemical properties and the metal utilized is not an essential item, although nickel plating is preferred.

*The sinusoidal current* lays no claim to any special polar effects and accommodates itself to the form of electrode most readily available.

*Copper, zinc, and iron* are used largely for their antiseptic and astringent properties and the former is in popular favor at the present day. A copper electrode is valuable for metallic electrolysis at the positive pole and is useful on the negative pole or with the faradic current.



FIG. 4,628.—McIntosh monomotive rheotome, for interrupting galvanic, faradic, or sinusoidal current for therapeutic application. The range of interruption is from 20 to 400. *The instrument consists of* a clock work mechanism with platinum tipped contact, and is wound up with a key, running 45 minutes with a single winding. *In adjusting*, a lever is turned to the frequency desired; this movement of the lever turns on the clock mechanism, selects the frequency and places the rheotome in the circuit. Turning the lever back to the "off" point similarly cuts it out of circuit and stops the mechanism. The motion of the spring is impeded by a fan, hence the resistance is the same in either horizontal or vertical position. *In connecting*, it is placed in series between the patient and battery or other apparatus.

*Nickel plated electrodes* are designed especially for use with the faradic current or the negative pole in galvanism, and should on no account be employed on the positive pole, as the plating would be stripped; this also applies to gold plated needles, for, it will be recollected, gold is subject to the influence of chlorine.

*Block-tin, platinum, and carbon* are capable of withstanding the action of the positive pole, being unaffected by either chlorine or oxygen, and therefore may be utilized where the effects of this pole are



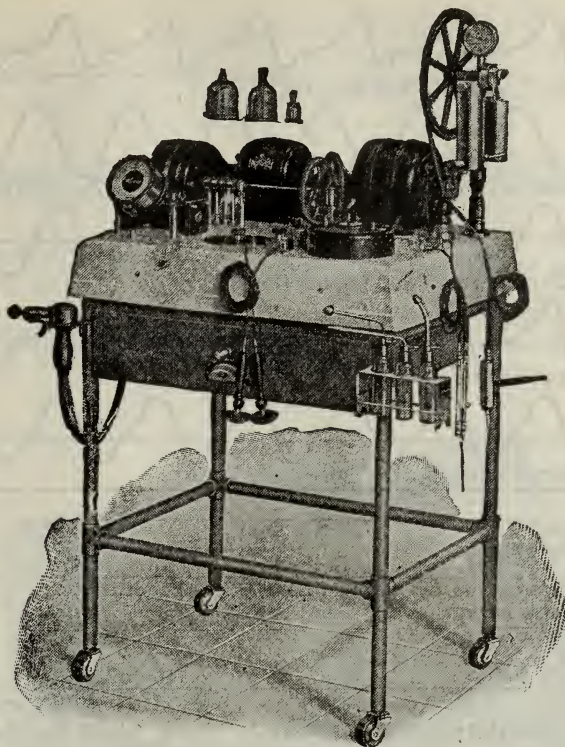
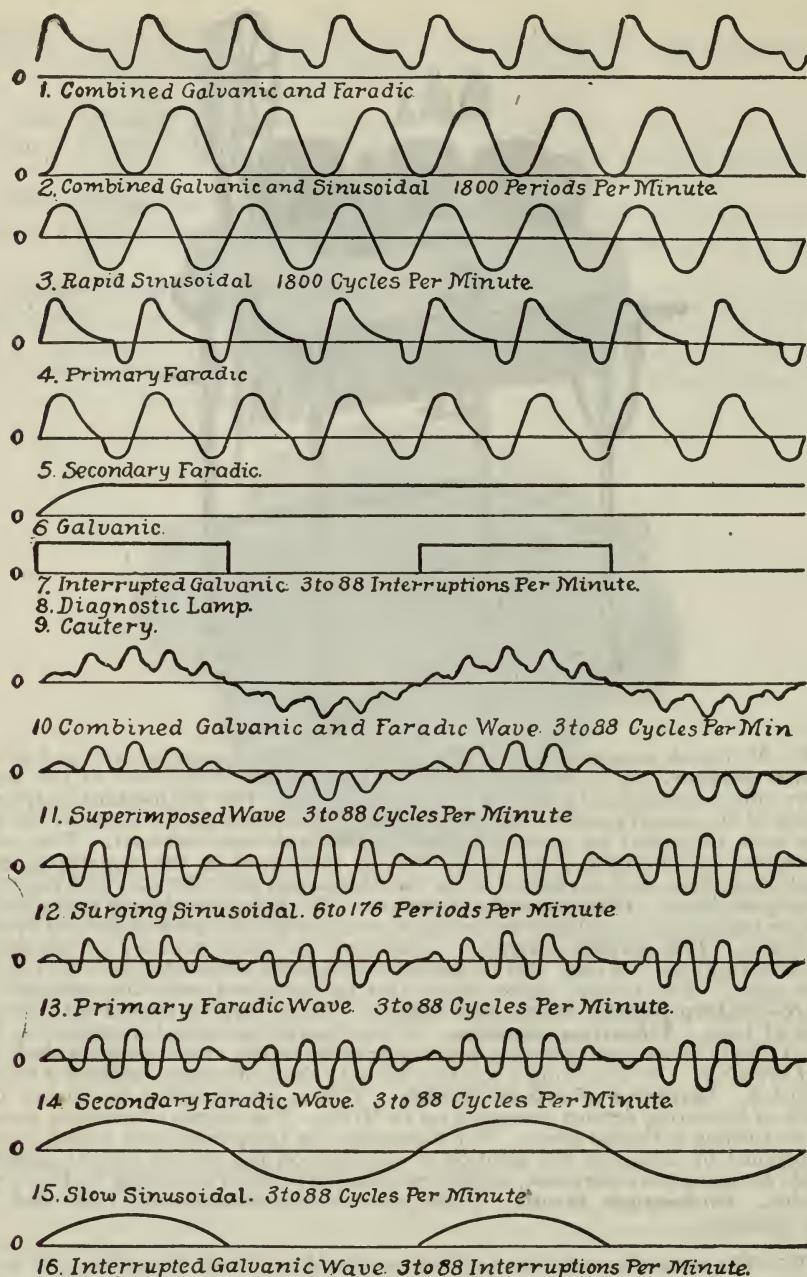


FIG. 4,629.—McIntosh universal mode. The features of the apparatus are as follows: **Dial current selector.** A single knob controls the selection of any one of the sixteen distinctive effects secured, all plainly lettered on the dial. **The sinusoidal current.** Nine varieties of sinusoidal current may be obtained. A friction device controls the frequency of the slow sinusoidal by turning a knob. **The galvanic current.** This current for electrolytes, calaphoreses, gynecology, etc., is generated in the apparatus, having no ground connection, and is controlled by the MacLagan wire rheostat and measured by a milli-ampere meter. **Interrupted galvanism.** This is for muscle and nerve testing in reaction or degeneration and is obtained by a mechanical rotary break from 3 to 88 periods per minute. **The faradic current.** This may be either primary or secondary, with rapid interruptions. It may also be passed through the sinusoidal rotor and delivered in a sine wave. The faradic current may also be combined with the galvanic current. **Electro-cautery points, loops, and snares.** These may be heated with regulation of degree of heat. **Vibrating massage.** When desired for spinal stimulation, inhibition or local effects is secured by fitting a massage cable to the attachment on shaft of motor. **Nasal drilling.** By attaching a suitable cable to shaft of motor, means for nasal drilling is afforded. **Spraying of oils or liquids.** This is accomplished by means of a pump capable of operating against pressures up to 50 lbs. The degree of pressure may be regulated by turning a thumb screw. For massaging the tympanum, the length of stroke can be shortened by adjusting the position of eccentric on the driving wheel. Deep suction, suitable for aspiratory purposes, or for producing hyperemia according to Bier's method is available. **Endoscopic lamps.** These may be illuminated and controlled for diagnostic purposes.

NOTE.—The term sinusoidal current has been used by many manufacturers as a rather vague characterization covering many forms of current having very little in common in the way of physiologic action. The first form of sinusoidal apparatus introduced to the medical profession was of the nature of a magneto with pole pieces cut away so as to produce a gradual rise and fall in the voltage of the current developed. This style of apparatus had among its early advocates Dr. Kellogg of Battle Creek, who has done much to advance the use of this modality, especially in hydrotherapeutic work.



FIGS. 4,630 to 4,643.—Modalities of the McIntosh universal mode. In addition to the sixteen illustrated, the following are also available: 17, mechanical vibratory massage; 18, nasal drilling to remove obstructions; 19, electrically heated air; 20, pneumo-massage of tympanum, eye or skin; 21, spraying of liquids or powder blowing in nose or throat work; 22, vaporizing or nebulizing of oils; 23, deep suction suitable for aspirating in congested sinuses; 24, Bier's hyperemia,



desired in cases where the application of metallic salts is not indicated. Platinum is very costly and carbon is brittle and hard to work, but block tin is more practical as the cost is not prohibitive and it is easy of adaptation.

**Vaginal and intra-uterine electrodes** are always best of copper, except for faradization or dilating, when nickel plating is preferable.

**Rectal electrodes** are usually more desirable in copper, as the treatment of hemorrhoids demands this particular metallic salt.

**Abdominal electrodes** are preferably composed of a block tin plate with a suitable covering.

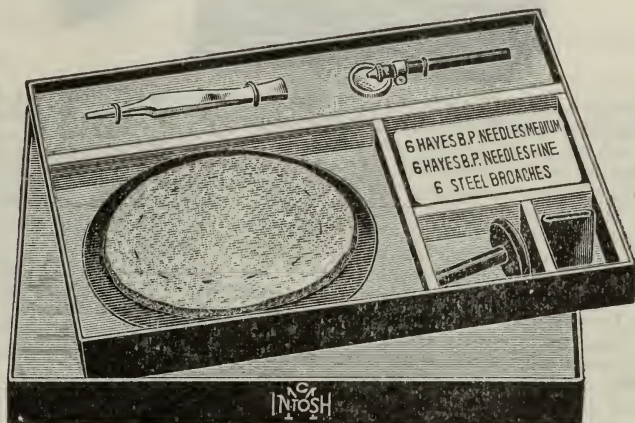


FIG. 4,644.—Dr. Rice's epilation set comprising electrodes necessary for epilation according to the method introduced by Dr. May Rice of Chicago. The set contains: Face anæsthetizer; lip anæsthetizer; needle holder with magnifying glass; forceps; hand spongio electrode; bulbous pointed epilator needles; broaches for growths.

**Urethral electrodes**, if required solely for the treatment of stricture, should be nickel plated, but for the treatment of gleet and kindred ailments copper is indicated.

**Eye, ear, nose and throat electrodes** are largely called for in copper, but in cases where the faradic or sinusoidal currents are to be employed, nickel plating is more desirable.

**Epilating electrodes or needles** are usually of steel, as the negative pole is most commonly employed for this purpose.

**As a summary** it might be said that copper is a very serviceable, all round metal, and can occasionally be replaced by zinc or iron; but nickel plated instruments are in a class of their own, and are unexcelled for certain special applications.

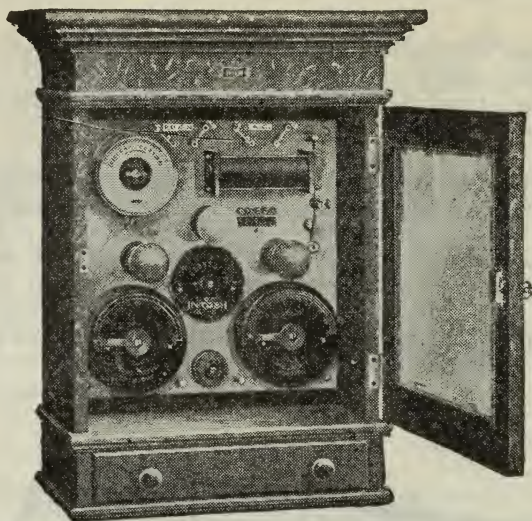


FIG. 4,645.—McIntosh type 12 aseptic porcelain plate. **Direct current operation.** When the plate is employed with direct current lighting circuit, the galvanic and faradic circuits of the plate are supplied by the direct current; while a motor generator must be employed to transform the *direct* current to an *alternating* current to properly energize the transformer for cautery and sinusoidal currents. In this manner each circuit of the plate is supplied with its appropriate form of energy. **Battery equipment.** With a battery of 50 dry cells and a motor generator the same results can be had as with the direct lighting current, the cells being good for 100 brief cautery operations and several hundred galvanic, faradic and sinusoidal applications. Dry cells, however, constitute an expensive current service. **Alternating current installation.** With the alternating current the rectifier with pressure equalizer is necessary to transform the *alternating* current to a *direct* current in order to operate the galvanic and faradic circuits, while the *alternating* current in its original form is employed with the transformer for cautery and sinusoidal currents. **The dial current selector.** With one turn of the knob all connections for any given modality are instantly made and the current is ready for use. Eleven distinct modalities are plainly indicated on the dial. When the knob is turned "off", the current is completely cut off from all circuits of the plate. **The rheostat.** This consists of a solid block of porcelain, wound with high grade resistance wire, with a traveling contact which increases or diminishes the current strength imperceptibly controlling the galvanic, faradic and sinusoidal currents. The volt scale shows the voltage of galvanic current used. **Monomotive rheotome.** This is an interrupter, which may be used to interrupt either the galvanic, faradic or sinusoidal currents; being especially valuable with the former in muscular diagnosis. It is wound up as a clock by means of the key accompanying the outfit, and, as its name indicates, requires but *one motion* to start mechanism, select frequency, and close circuit. **The faradic coil.** This is a secondary coil with a primary winding of 230 feet of No. 20, a rather coarse wire; and a secondary of 1,300 feet of No. 30, a comparatively fine wire, thus affording a comprehensive range of induced currents. The slowly interrupted faradic currents are secured with the monomotive rheotome, varying from 20 to 400 per minute. **The transformer.** This transforms alternating current of 110 volts,  $1\frac{1}{2}$  amperes, to a cautery current (which is also an alternating current) of 4 volts, 35 amperes, sufficient for all ordinary knives, under perfect control of operator. The sinusoidal current obtained from the transformer is "earth free," having no "ground" connection, and, if desired, may be used in bath tub application, something unattainable with the ordinary wall plate on account of the average bath tub being grounded by the waste pipe connection. This feature is of especial value in a sanitarium. **Milli-ampere meter.** The meter has two scales, one in black figures reading 0-400, suitable for recording heavy dosages, which is placed in service by inserting the hard rubber plug in the socket marked "B;" and one in red figures reading 0-20, adapted to measuring lighter currents, which is in effect when the hard rubber plug is inserted in socket marked "R." The meter reads to right or left according to position of pole changer. Before using meter, the knob on scale pan may be adjusted so that the needle rests exactly at zero.



**Galvanic Therapy.**—The importance of the galvanic current in gynecology, rectal work, urology and for cosmetic purposes is recognized by all engaged in these branches of practice. The galvanic current possesses the following properties:

### Positive pole

1. Oxygen;
2. Acid;
3. Will stop bleeding;
4. Sedative;
5. Hardens tissues;
6. Is an acid caustic and the resultant cicatrix is hard and unyielding;
7. Is a vaso constrictor.

### Negative pole

1. Hydrogen;
2. Alkaline;
3. Increases bleeding;
4. Produces hypersensitiveness;
5. Liquefies and disintegrates;
6. Is an alkaline caustic and the resultant cicatrix is soft and pliable;
7. Is a vaso dilator.

### Galvanic Technique

**Cervical erosions.** As erosions are commonly caused by excoriating discharges, they generally heal after the discharge ceases. Should the erosions persist, it is well to give two or three local applications with the Fitz Hugh electrode amalgamated and bare to the erosion. Thirty to forty milli-amperes with the positive pole of the continuous current will saturate the friable tissue with copper salts. This should be given four days to heal, when, if it seem necessary, the cataphoric application may be repeated. Follicular erosions should be opened with a bistoury and then treated with the bare tip of the amalgamated copper sound.

**Epilation.** (Hayes). Select a fine bulbous pointed steel needle, attach to needle holder, connect to negative pole, turn on about 20 volts and insert in hair follicle, allowing it to find its own way and avoiding perforating the follicle sheath. The patient is instructed to place the hand with gradual pressure on a well moistened pad connected with the positive pole until the circuit is completed, when a white froth at the needle indicates that electrolysis is complete and the hair may be withdrawn without traction.

**Internal hemorrhoids.** (Neiswanger). Place the patient upon the table in the gynecological position, wet thoroughly a pad as large as the hand, or larger, attach it to the negative terminal of the battery and place upon the abdomen. The positive is connected with the rectal electrode, which is then carefully introduced with the curved side down, pushing up with the electrode any fringe or prolapsed membrane. The current is now turned on by means of the rheostat until ten or fifteen milli-amperes is reached, and allowed to flow for ten minutes.

**Urethral stricture.** (Neiswanger). The technique is simple and may be briefly given as follows: The caliber of the stricture is taken in the usual manner with any set of urethral sounds, then an olive pointed

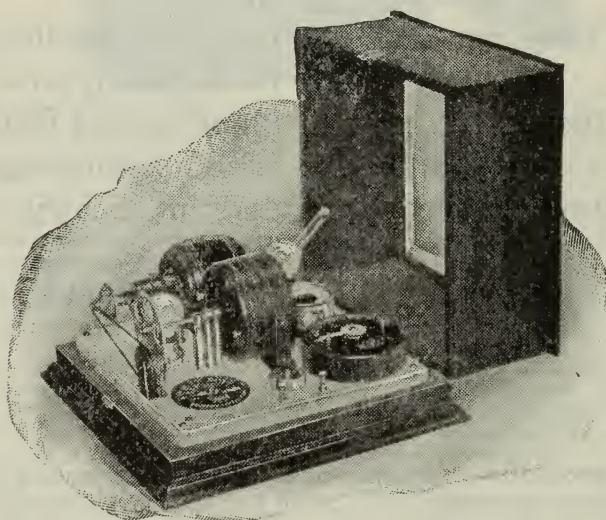


FIG. 4,646.—McIntosh polysine generator. It supplies a slow sine wave ranging from 12 to 120 cycles per minute; a rapid sine wave of 1800 per minute; a superimposed wave consisting of the 1800 cycle rapid sine wave imposed upon the slow wave; a surging sinusoidal, somewhat similar in character to the former; a slow surging galvanic current; a rapid surging galvanic current; a straight galvanic current; a combined galvanic and sinusoidal current; and a current for diagnostic lamps.

electrode about two sizes larger than the caliber of the stricture is attached to the negative pole of a galvanic current and introduced into the urethra so as to engage the stricture. The positive pole may be a pad the size of the hand or larger on some indifferent point. The current is now turned on until five milli-amperes is reached. No appreciable pressure is used, but the electrode is allowed, by its own weight, to slowly pass through the stricture, which it will do in about five minutes. The current is then turned off, the electrode withdrawn and the operation not repeated sooner than five to seven days, at which time a sound two sizes larger is employed.



**Sinusoidal Therapy.**—The value of the sinusoidal current has been proven in many chronic nervous and muscular conditions not amenable to drug therapy, such as atonic constipation, prostatic hypertrophy, splanchnic engorgement, locomotor ataxia, anterior poliomyelitis, menorrhagia, prolapsed ovaries and many other cases.

The rapid sinusoidal current possesses one feature of the high frequency current; that is, the greater its rate of alternation, the less painful is the current. As in the case of the high frequency current, this is supposed to be because the alternations or vibrations are too rapid for the comprehension of the sensory nerves. Muscular fibres frequently react to the sinusoidal current which fail to respond to the faradic current.

The sinusoidal current increases the elimination of urea, sulphates and phosphates in the urine. Indican, if present, is at first increased, or if not found before, frequently appears after administration of the current. After a number of treatment it is much less evident, as it is looked upon as the product of proteid putrefaction. The inference is that the sinusoidal current tends to lessen toxic intestinal products through improved intra-abdominal circulation. In general terms, it may be said that the sinusoidal current is employed in all cases where faradism is ordinarily employed, following essentially the same technique. In addition there are certain conditions that deserve special mention, which will be classified according to the method of applying the treatment. The usual guide to dosage is the patient's toleration. The current is not caustic.

1. By abdominal applications. Intestinal toxemia, strengthening of the abdominal muscles, prolapsed abdominal viscera, abdominal arterio-sclerosis, diabetes mellitus, disease arising from faulty metabolism of abdominal viscera, diseases caused by portal congestion, neurasthenia, melancholia, conditions arising from venous congestion of the abdomen, constipation, etc.

2. Diseases of the stomach, especially those due to atony and motor insufficiency.

3. Hyperesthesias, neuralgias, muscular rheumatism, headaches and localized pains outside of orifices.

4. Gleet, urethritis, spasmodic strictures, incontinence of urine, endometritis, cervical catarrh, fibroids, etc.

5. Prostatic diseases, hemorrhoids, fissure of anus, prolapse of rectum, inflammation of seminal vesicles, inflammation of bladder in males, etc.

6. Vaginitis, leucorrhea, cystitis in females, relaxed ligaments, etc.

## Sinusoidal Technique

**Amenorrhoea:** Galvanic (Neiswanger.)

Negative galvanism is a vaso motor dilator, bringing increased blood supply to the parts. Vaginal electrode covered with wet cotton pad is used in vault of vagina with positive pad on abdomen. Use 40 ma. ten minutes every second day. The results in one month will restore normal condition.

**Aphonia:** Galvanic. Sinusoidal.

Cases of simple aphonia. Galvanic: Place a positive felt covered electrode 3 inches by 4 inches at back of neck, bend a flexible electrode over the larynx so that it covers both sides. Wet both sides with sodium bicarbonate solution. Give 15 ma. and treat ten minutes. Next apply

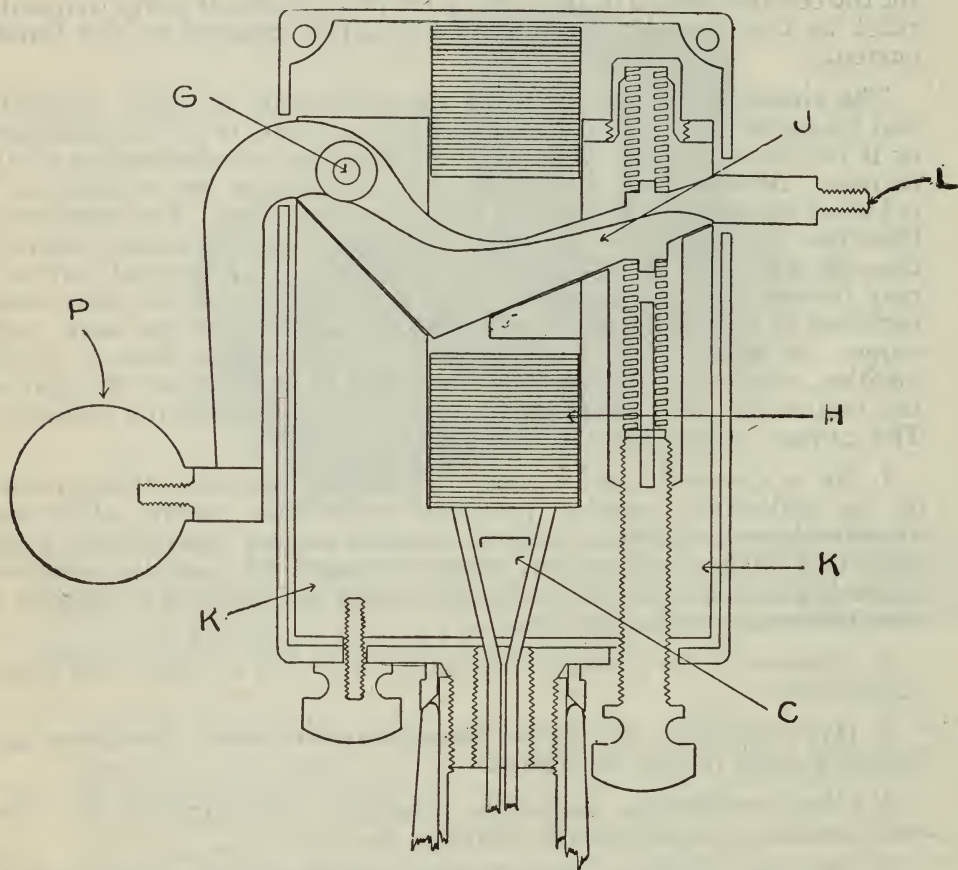


FIG. 4,647.—Diagram of Scheidel-Western vebragenitant. It consists of a synchronized motor geared to a vibrator. Current enters through the leading in wires to the simple switch C and through the coil H. Every alternation of the current causes the armature J, which is pivoted at G, to be pulled toward the field K, imparting a percussive stroke to the applicator at P, and a lateral stroke to the applicator when placed at L.



negative on one side, positive on the opposite side, regardless of polarity. \*Turn the dial selector to "Surging Galvanic," shift the belt to the right to fifth grooves in pulleys, which gives a frequency of 72 per minute, regulate the current so as to cause strong contractions of the vocal apparatus for a few minutes. After five or six treatments with the galvanic current, use low sinusoidal with belt same as for the above treatment, then increase the current from zero through rheostat until strong sensible but painless contractions are secured. The duration of the entire treatment should be about ten minutes, treatment three times per week.

**Asthma, bronchial.** Rapid Sinusoidal. (Abrams.)

Stimulate lung reflex of contraction. Strong rapid sinusoidal current, one electrode over the spines of the fourth and fifth cervical vertebræ and the other over the sacrum, fifteen minutes to one hour every day. The interrupting electrode may be used over the cervical vertebra.

**Catelepsy:** Sinusoidal. (Monell.)

Monell gives account of cataleptic patients who refused to respond to all measures resorted to until the current was applied to the left nipple. Try surging sinusoidal current.

**Catarrh, cervical:** Galvanic. (Neiswanger.)

This disease is more amenable to treatment and results more permanent than curettement. Large copper electrode to positive pole that will fill the cervical canal. Introduce electrode up to internal os and employ current of 30 to 42 ma. Do not move electrode to prevent sticking, for that is what is wanted. Negative to large pad on abdomen. In five minutes the mucous plug will have adhered to electrode and by a little traction may be withdrawn. Slight bleeding is of no consequence.

**Constipation:** Slow sinusoidal.

One moistened pad electrode on second lumbar spine, other electrode on abdomen from twenty to thirty minutes three times a week.

**Diabetes:** Slow sinusoidal. (Dugan.)

In diabetes the patient may be so weak that excessive exercise may excite proteid metabolism. From twelve to 120 contractions per minute will exercise the muscles sufficiently without producing the above results. (See Sinusoidal Electric Bath.)

**Endocervitis:** Galvanic.

Treatment same as Endometritis. The treatment can be followed by rapid sinusoidal current, one pad on abdomen and one to vaginal electrode, fifteen minutes.

**Endometritis:** Galvanic. (Rice.)

Prepare large pad for negative pole, wet and place over lower part of abdomen. Through the speculum introduce amalgamated sound (see p. 66, Dr. Rice's "Electricity in Gynecology") connect with positive pole, 20 to 50 ma., as the patient can tolerate, five or ten minutes.

**Gastrectasis:** (Dr. A. W. Herr, Cleveland, O.)

Extracts from paper read at the Meeting of the American Association for the Study of Spondylotherapy at Chicago, Nov. 14, 1912:

"The method I am relying upon to the greatest extent (supplemented by mechanical vibrator) is that of the strong sinusoidal current. I make use of from 65 to 75 volts, employing for the purpose the McIntosh No. 1 polysine generator. I use slow alternations, as slow as one per second, believing that this approximates the physiological rhythm of the muscles. Patients seem to enjoy this treatment and become enthusiastic over it and usually results are soon apparent and recognized by the patients themselves. I am today making use of this current in chronic hepatitis with unexpected early results. Many cases of gastric disorder are accompanied by motor disturbances, and wherever you find muscle involved (particularly visceral muscle) in those I can recommend the use of the sinusoidal current."

**Gastritis:** Slow sinusoidal.

One pad over the fifth dorsal and the other over the stomach, fifteen minutes every day. Fifth dorsal empties the stomach by dilating pylorus.

**Headaches:** Slow sinusoidal.

Acidity: Double electrode opposite seventh cervical.

Alkaline: Double electrode opposite eleventh dorsal. Ten minutes every day.

**Hemorrhoids:** Galvanic. (Rice.)

Select rectal electrode for case. To avoid holding electrode so that copper bulb is in opposition to the growth, the short electrode with hard rubber arm is of great service. (No. 63, Rice's Electrode.) Fit a piece of chamois over the copper bulb so as to leave no rough surfaces, place patient on left side with wet pad with negative pole on abdomen. If any of the hemorrhoids are prolapsed and difficult to replace, lay a little dry cotton over the anus and with the ball attachment of mechanical vibrator apply massage. Then connect rectal electrode to positive pole. Fifteen ma. ten minutes.

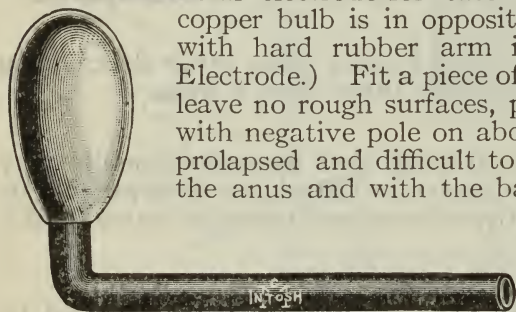


FIG. 4,648.—Dr. Rice's rectal electrode.

**Infantile Paralysis:** Slow sinusoidal. (Abrams.)

Both electrodes opposite tenth dorsal to second lumbar. Ten to twenty minutes every day.

**Infantile Paralysis:** Slow sinusoidal. (Geyser.)

How often does it occur that a child at three years suffers from anterior poliomyelitis, recovers only partially and for the balance of its life wears braces? In such if a trace of muscular contraction be discernible, a



favorable prognosis may be given. The technique is simple. The foot of the affected limb is placed in foot bath connected with one electrode; the other electrode is placed over the lumbar region. Always begin with an interrupted current. Rapid sinusoidal. Note all the muscles that fail to respond. Then use the galvanic current, noting all of the muscles that fail to respond, as they contract with worm-like contractions, a positive sign of partial reaction of degeneration. Care must be taken to avoid all healthy muscles, while the abnormal ones must receive our best attention. I have seen such cases restored to almost normal usefulness after ten years of cripple life.

**Insomnia:** Slow sinusoidal. (J. J. P. Armstrong, M.D., Douglas, Ariz.)  
Cases of insomnia recover very rapidly by the use of the sinusoidal current.

**Locomotor Ataxia:** Slow sinusoidal. (Geyser.)

Frequently we meet with a condition of paralysis or atony of the lower bowel only with or without spasm of the sphincter. The spinal electrode is placed over the sacral vertebra, while the rectal electrode, connected with a fountain syringe containing warm water to which a small amount of salt has been added, is placed into the rectum and the water used as an electrode. The pressure 30 to 40 volts, while the current may be



FIG. 4,649.—Johnson's hydro-electric rectal tube.

from 25 to 75 ma. When this condition has existed for a long time, as when associated with spinal cord lesions, especially locomotor ataxia, the sinusoidal current with 10 to 15 cycles per minute, should be interrupted at first about 100 times per minute or 15 to 25 times for each cycle. (Note. This effect can be best obtained by using the superimposed wave.) This causes powerful muscular stimulant: it tends to throw all fibres capable of responding into a state closely bordering on tetanic contractions, and as this is not a physiological state, the interruptions must be decreased as soon as tonic contractions can be produced and again omitted as soon as the bowel responds to the simple sinusoidal current.

**Lumbago:** Surging or slow sinusoidal.

One pad on cervical spine, the other on sacrum. Give fifteen to twenty minutes' treatment every day of surging or slow sinusoidal to relieve pain.

**Lumbago:** Slow sinusoidal. (S. J. Wright, M.D., Akron, O.)

Case 1. Mr. F., age 35, has complained of lumbago for some time. Has tried many remedies with only temporary mitigation. Of late he has been unable to attend to his insurance and real estate business. He came to me. I used other methods of treatment without results and his condition became so painful he resorted to morphine to get relief. He has taken five slow sinusoidal treatments in twelve days and he is delighted with every treatment and is hard at work again. Length

of treatment fifteen to twenty minutes. In irritable conditions of the kidneys where dilatation is present, the organ can be contracted by applying the sinusoidal current to the twelfth dorsal spine with a pad at the sacrum.

**Mammary Glands, Insufficiency of:** Rapid sinusoidal. (Dr. Chas. L. Ireland.)

One pad between third and fourth dorsal vertebræ and other over glands. Treatments five to ten minutes daily until normal secretions are obtained.

Cases have been reported where nourishment was impossible in which an abundant secretion of milk followed in two or three days. It is a well known fact that one of the principal causes of infant mortality in America is the almost universal habit of artificial nursing.

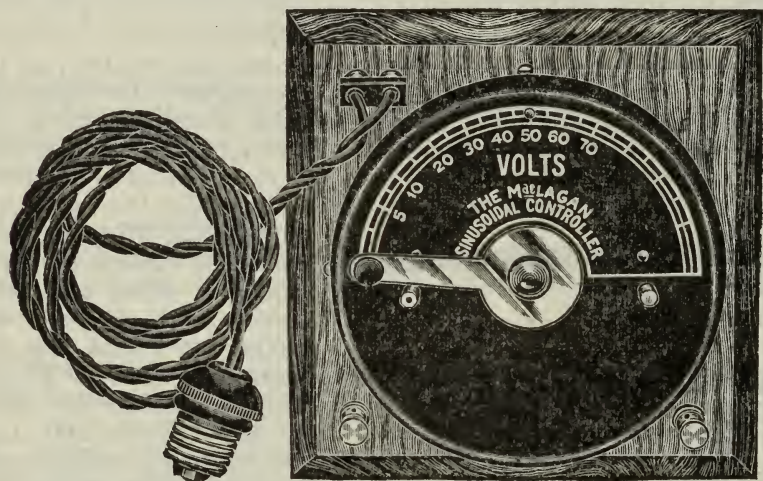


FIG. 4,650.—MacLagan sinusoidal controller for securing a rapid sinusoidal current for connection with 110 volt, alternating current circuit. The apparatus consists of a current controller or rheostat wound with a fine quality of resistance wire controlled by a lever which permits of a gradual increase or decrease of the current strength absolutely without shock. The rapid sinusoidal is desirable in constipation and other gastro-intestinal disorders. In sciatica, lumbago and neuritis it is of great value. This current can be used to elicit the reflexes according to Abrams by applying one electrode to the spinal center and an indifferent pad at the sacrum. At the seventh cervical the heart and aorta are contracted; at the fifth dorsal the pylorus is opened, discharging contents of stomach into duodenum; the twelfth dorsal contracts the prostate; at the seventh and eighth dorsal the abdominal muscles are contracted; and at the second lumbar the uterus and ovaries are contracted.

**Melancholia:** Slow sinusoidal. (J. J. P. Armstrong, M.D., Douglas, Ariz.)

Cases of melancholia are benefited by this current, especially if due to intestinal disorders. One pad on sacrum, other on abdomen. Seance 15 minutes.

**Muscles, Atrophy of:** Slow sinusoidal. (Dugan.)

The sinusoidal current will show a rapid muscular development if daily applications are made. If used on the abdominal muscles, we will see



an improvement in the nerves, together with a marked improvement in the tone of the muscles. It has been shown that the sinusoidal current, by contracting the blood vessels of the splanchnic circulation, aids in improving the general blood circulation.

**Neuralgia, trigeminal:** Slow sinusoidal. (Abrams.)

The slow sinusoidal is fine in cases of trigeminal neuralgia. One pole on back of neck and other on the Gasserian ganglion from ten to twelve minutes.

**Neuralgia, visceral:** Rapid sinusoidal. (Dugan.)

Visceral neuralgia is relieved by the analgesic effect of this current, as it relieves the congestion. We should use large electrodes and place one

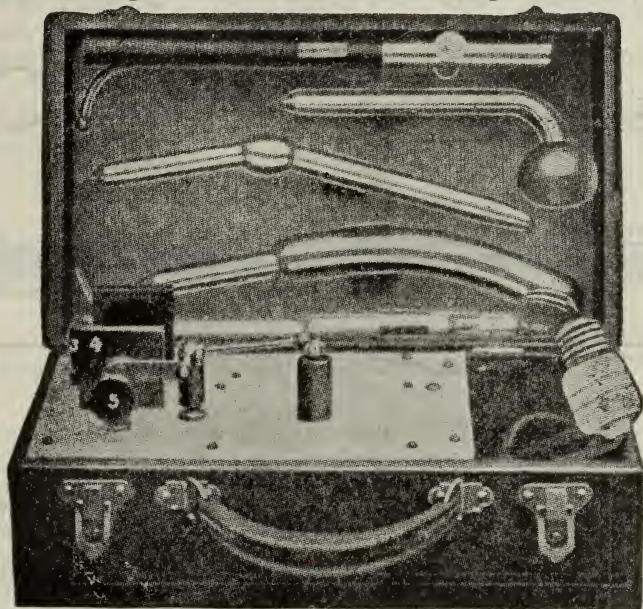


FIG. 4,651.—Columbia high frequency outfit consisting of a coil in carrying case ( $7\frac{1}{2} \times 12\frac{1}{2} \times 6\frac{1}{2}$  in.), 8 ft. silk covered cord and plug ready to attach to any light socket. One insulated connecting cord. One set of six vacuum electrodes: No. 1, surface; No. 2, nasal; No. 3, urethral; No. 4, throat; No. 5, rectal; No. 6, vaginal; No. 7, insulated handle with swivel connector and adjustable to different sizes of electrode.

over the lumbar region and the other on the abdomen or over the painful part. Seance ten minutes.

**Neurasthenia, intestinal:** Superimposed wave. (J. J. P. Armstrong, M.D., Douglas, Ariz.)

The superimposed wave has done fine work in cases of intestinal neurasthenia. Use small pad in intrascapular region and large pad on the abdomen for twelve minutes at a time.

**Neurasthenia, splanchnic.**

Sinusoidal, slow or rapid, both electrodes. Eighth dorsal twenty minutes once or twice a day.

**Neuritis:** Rapid sinusoidal. (Dugan.)

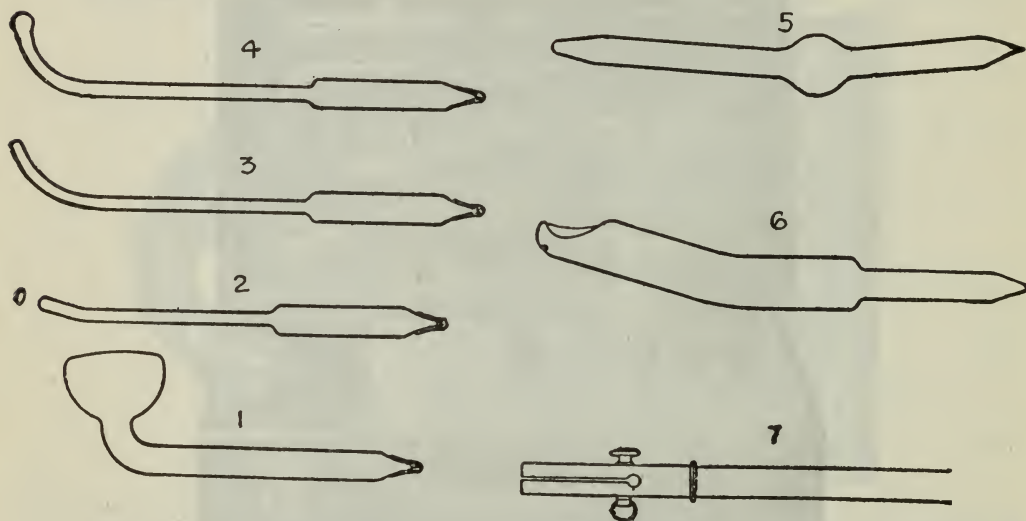
In chronic neuritis, lumbago and intercostal neuralgia, the same technique should be followed as in visceral neuralgia.

**Obesity:** Slow sinusoidal. (Dugan.)

A general application of slow sinusoidal current will cause contraction of the muscles all over the body. In obesity a large amount of muscular activity is needed to burn up the surplus fat. (See Sinusoidal Electric Bath.)

**Optic Atrophy:** Rapid sinusoidal. (W. Franklin Coleman, M.D.)

Dr. Coleman, in his new book "Electricity in Diseases of the Eye, Ear, Nose and Throat," tabulates many cases of atrophy of the optic nerve



FIGS. 4,652 to 4,658.—Columbia vacuum electrodes. 1, surface; 2, nasal; 3, urethral; 4, throat; 5, rectal; 6, vaginal; 7, handle.

where vision was greatly increased by the application of the rapid sinusoidal current with a double eye sponge electrode and an oval pad placed at the nape of the neck. Treatments 20 minutes daily.

**Ovarian neuralgia:** Slow sinusoidal.

One electrode on tenth dorsal, the other over ovary, twenty minutes every day.

**Paralysis:** Slow sinusoidal.

Double electrode: For arms, third to seventh dorsal. For limbs, tenth to twelfth dorsal. In some cases the surging sinusoidal current is recommended, being interrupted.

**Paralysis due to central lesions:** Surging sinusoidal. (A. J. Smith, M.D.)

One electrode in cervical region, other at periphery. Treatments: One



hour every day with a mild current, according to severity. It has been claimed that the stimulation thus set up acts upon the trophic centers in the cord, favoring increased metabolism and carrying away the products of stasis.

**Pelvic Diseases:** Rapid sinusoidal. (Dugan.)

In pain due to a neuralgic condition of the ovaries or tubes, in cases in which the uterus is very sensitive, but no acute or chronic endometritis is present, the rapid sinusoidal will afford most satisfactory results. Whenever passive congestion is present we should use one electrode on the abdomen and the other applied to the uterus. Use rapid sinusoidal for ten minutes, then use the slow sinusoidal current for five minutes.

**Pelvic disease, Neurosis in the woman due to:** (A. J. White, M.D.)

(a) Surging sinusoidal. Pad electrode at sacrum, another pad in cervical region.

(b) Galvanism positive. Copper ball electrode in vagina, negative to large pad on abdomen.



FIG. 4,659.—Neiswanger's perforated copper ball electrode for galvanic current. May be used as an irrigating electrode.

Beginning treatment with (a) for tonic effect for 10 minutes, change to (b) for 5 minutes for the local antiseptic effect of the copper salt. Treatments every day for first week, every other day during second week, afterward twice weekly.

**Pleurisy:** Rapid sinusoidal.

In pleurisy or intercostal pain of the chest wall, use one electrode over the eighth dorsal spine and one over the seat of pain with stabile application for ten minutes. Very efficient in relief of pain.

**Ptoxis:** Surging sinusoidal. (J. F. Roemer, M.D.)

F. B. ———. Farmer, white, aged 66. Poorly nourished. Complaints of stomach sore, painful, no appetite, cannot eat, tongue coated, center thick brownish white, edges clear. Likes meat and potatoes but cannot eat much. Heart palpitates, feels it beat all through his body, feet cold, cannot get them warm, blood pressure 166. Difficult breathing, but lungs clear. Sleep, restless, wakes at 1:00 a. m. Dreams all night long, especially if lying on back. Back sore and lame, hips very sore and painful, cannot lie on side, says he is lame and nervous all over, all tissues sore. Frequent urination at night. Painful erections awaken him. Unable to pass water for long time in morning. Examination showed ptosis of all organs. Heart not enlarged, but two inches below normal, stomach below umbilicus in left inguinal region. Spleen easily

palpated. Liver two inches below ribs, and no doubt the inability to pass urine in early morning was due to relaxed condition of walls of bladder. He has complained of the same symptoms for the past twelve years, and has so far received no relief. When I told him of my findings and located his organs for him, he answered: "Yes, that is what Dr. T. said. He told me they were out of place, that they had fallen down." **Enteroptosis**, a good and plenty. **Neurasthenia; treatment:** The indicated remedy, vibrator three times a week for two weeks to start blood current through back, and then applied the surging sinusoidal current for fifteen minutes three times a week. My case book shows he had just 29 treatments. In one week his heart had ceased paining him. In three weeks his stomach was feeling better, tongue had cleaned and he was eating fine, as he expressed it. The nervous feeling persisted longer and gradually left him and after four months have

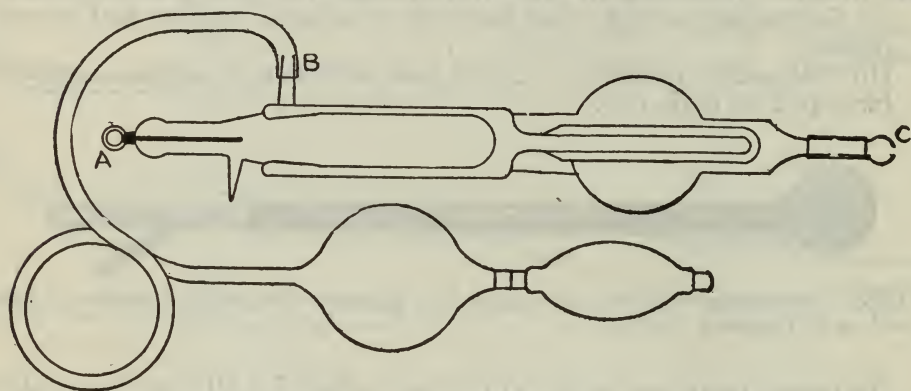


FIG. 4,660.—Columbia ozone generator. *In operation*, a current of air passes through the high frequency discharge and through a reservoir containing oils of eucalyptus and pine needles. The vapor is inhaled by the patient and is said to have an oxydizing and anti-septic effect; desirable in treatment of diseases of the respiratory organs.

elapsed since his last treatment the report from his son is "Father is better than he has been in 16 years. Wants to go back to farming. Is enjoying himself this winter. We are all well pleased over the results." The sinusoidal current was applied from a McIntosh polysine generator, using the surging sinusoidal from 40 to 80 volts, varied as he could endure it or rather as it was comfortable to him, applied by a special electrode made by myself for the purpose, using the ordinary sponge disc electrodes on back but the eight inch spongio-piline electrode on abdomen. I first applied the current for five minutes over the space between the sixth and seventh dorsal vertebrae, one sponge disc on either side. At this point all of the muscles of abdomen and contents can be influenced and the patient feel no pain. None of the fiery burning feeling experienced in other locations. Then I placed the electrodes over the fifth and sixth cervical or, at times, the seventh cervical. Here I got the contracting effect on the neck and shoulder muscles. Then placing the sponge discs far apart I placed them over the third and



fourth lumbar vertebræ, using a bifurcated cord from one binding post of the generator, and with a cord from the other binding post of the generator to the large eight inch pad over the abdomen, using this five minutes. A

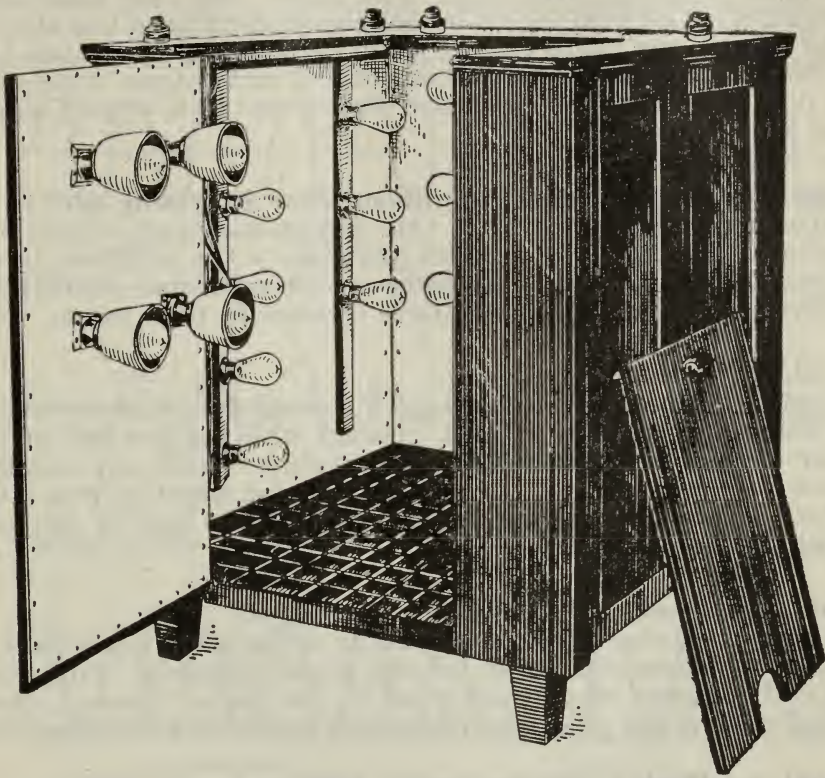


FIG. 4,661.—Columbia electric light bath cabinet. Dr. Otto Juettner in "Modern Physiotherapy" says: "Among the various physical and mechanical therapeutic agents known to modern medicine, light is, in point of clinical usefulness and therapeutic efficiency, surely entitled to a foremost place." Briefly, *the physiological effects of light are as follows*: By stimulating the nerve endings in the skin, the reflex phenomena are: dilating the capillaries, securing local hyperemia, stimulating the circulation of blood and lymph and relieving stasis; increasing the functions of the sweat glands, eliminating toxins; absorbing inflammatory products; increasing nutrition by reflex stimulation of the trophic nerves; raising the temperature en masse and thereby modifying metabolism and nutrition; muscular activity enhanced; the coloring matter of the red corpuscles increased; inhibiting the growth of bacteria, fungi and lower organisms; acting as a germicide and oxy-generator, the chemical rays have a disintegrating effect on living tissues and in cutaneous tissue with tubercle bacilli or other germs, oxygen is attracted, and a healthy reaction set up. *In using the light treatment*, it should be borne in mind that the white light, combining as it does all the various rays, is in most general use. The red light, giving the thermal rays, acts as a nerve stimulant, having a special effect on the sympathetic nervous system, and through this on all functions of the animal economy. Used as a general tonic, this is the most satisfactory color and valuable in contusions, bruises, sprains, etc. The green light contains the luminous rays and acts as a mild sedative. Blue light, containing the chemical or actinic rays, is a more pronounced sedative, diminishing pain, rectifying metabolism and is a local anesthetic. The investigation of Professor Minin, of St. Petersburg, has done much to cause this light to be accepted for its chemical and actinic rays. In skin diseases, in old ulcers and certain forms of malnutrition the blue light is worthy of a place in every physician's office.

better result was obtained by using the two sponge discs in holder over the exits of the nerves than was obtained by using one large pad covering the same surface. The advantage of the electrode: After being applied to back, assistant could hold it in place with one hand and turn current on or off with the other hand, leaving one hand free all the time. The holes in the plates enabled us to place sponge discs close together or far apart as was needed to cover exit of nerves from vertebræ; close on dorsal, farther apart on lumbar region, and to do it with least effort and loss of time.

### **Pre-menstrual psychological manifestations in young girls:**

Rapid or Surging Sinusoidal. One pad over cervical region, other at sacrum. Treatments 20 minutes every day. The action of the surging sinusoidal is particularly soothing in all conditions bordering upon hysteria and it makes an admirable measure in these cases.

### **Rectal Ulcer: Galvanic. (Monell.)**

Negative electrolysis. Moisten a felt covered flat electrode 4×6 inches in solution bicarbonate of soda, connect with positive pole of the galvanic current and place it under the sacrum. Select any metallic electrode with oval tip and connect it with the negative pole. Cleanse ulcer. Apply to it the metallic tip, apply seven ma. for five minutes. Apply again in four days.

### **Segmental Analgesia: Slow sinusoidal. (Abrams.)**

Under this caption reference is made to the annihilation of pain in skin areas and viscera related to different spinal segments. Cutaneous and visceral analgesia may be achieved by concussion, freezing, slow sinusoidal current and pressure. (See nerve centers in Dr. Ireland's chart.)

### **Sinusoidal Analgesia: Slow sinusoidal. (Abrams.)**

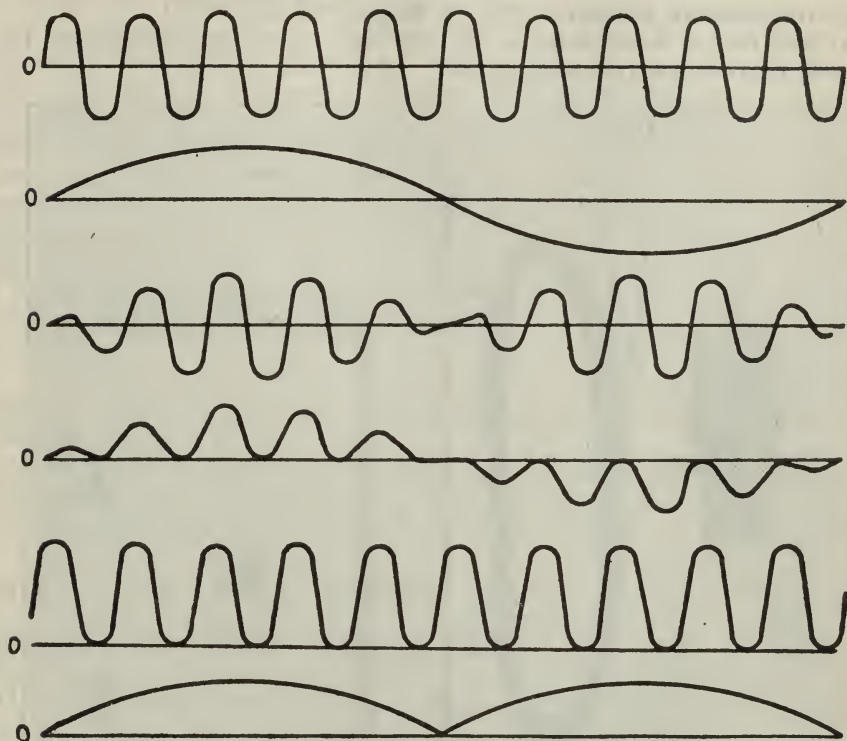
The slow sinusoidal current is the most effective. This current bombards the segments with a series of painless concussion blows. A strong current must be used and the duration of the seance must not be less than five minutes. Small electrodes are placed on either side of the spinous process (corresponding to the segment) or if more spinous processes represent the area of pain, the electrodes are placed along the entire segmental area.

### **Sinusoidal Electric Bath: Sinusoidal. (Dugan.)**

This form of electric bath is the best method of giving a powerful general electric treatment. We are permitted to apply currents of greater magnitude because the sinusoidal current is a painless one. It is well known that only a small amount of faradic current can be used. When the sinusoidal electric bath is used we will find no pain even when nearly every group of muscle is brought into action. If the patient be put into the bath at 85° Fahr., he will complain of cold. When the sinusoidal current is applied muscular contractions are produced and the patient rapidly



becomes warm. If the sinusoidal bath be applied at  $90^{\circ}$  for five minutes, tonic effects are obtained that are not produced by any other bath. Temperatures as low as  $80^{\circ}$  can be borne, thus increasing the tonic effects. For alterative effects the bath is continued for twenty minutes. Benefit may be received by these baths in gout, chronic rheumatism, obesity, gastric forms of neurasthenia, locomotor ataxia, insomnia and myalgia.



FIGS. 4,662 to 4,667.—Modalities secured from McIntosh No. 4 polysine generator. 1. **Rapid sinusoidal**, 1,200–3,600 cycles per minute. Obtained from the collecting rings on generator. Frequency is controlled by motor rheostat. Utilized for eliciting the vertebral reflexes and for stimulation of muscular tissue. Said to be superior to faradic current for general use. 2. **Slow sinusoidal**, 10–120 cycles per minute. This current is desirable for involuntary muscles, such as stomach and intestines. Very soothing for hyperesthesias and for anaesthetizing sensitive areas, as trigeminal neuralgia, etc. 3. **Surging sinusoidal**, 10–120 cycles per minute. This is obtained by passing the rapid sinusoidal current through the rotor producing a compound sine wave. It has proven of value in contracting the abdominal muscles through the spinal centers. 4. **Superimposed wave**, 10–120 cycles per minute. This consists of the combined galvanic and sinusoidal current sent through the rotor. It is much more tonic and stimulating than the slow sinusoidal and can be used to good advantage in auto-intoxication. 5. **Combined galvanic and sinusoidal**, 1,200–3,600 cycles per minute. Combines the tonic properties of the rapid sinusoidal with the distinctive polar effects of the galvanic. 6. **Slow surging galvanic**, 10–120 periods per minute. This current has practically the same sensation as the slow sinusoidal but the contraction can be concentrated at one pole. Often of value in different forms of paralysis. It combines the chemical action of the galvanic with the stimulation of the slow sinusoidal. 7. **Galvanic**. This modality possesses all of the characteristic effects which have been accredited to this form of current, such as electrolysis, cataphoresis; it may be employed in gynecology, G-U work, rectal treatment, facial blemishes, or any of the well known applications of this current.

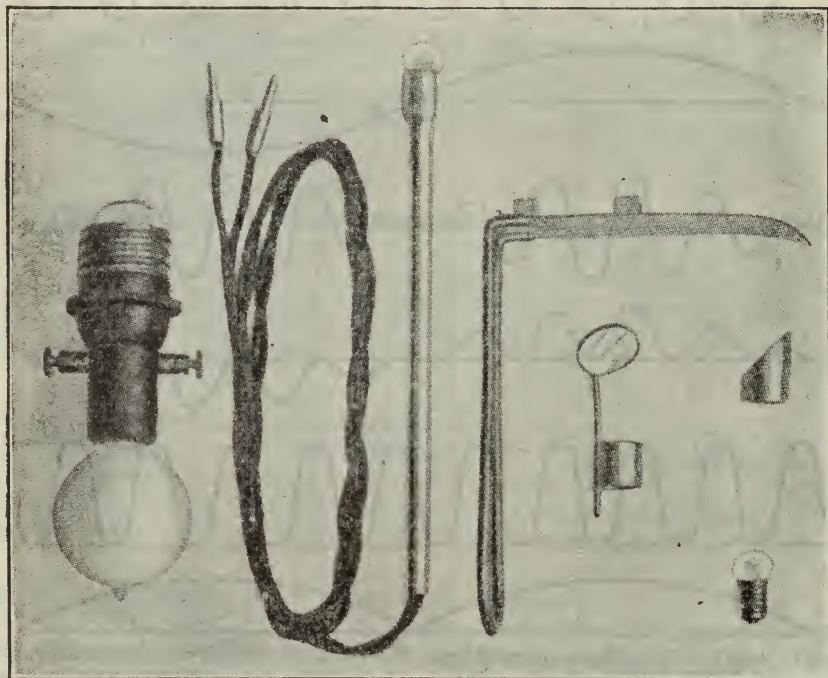
**Uterus, Infantile:** (A. J. Smith, M.D.)

(A) Slow or Surging Sinusoidal. Large nickel plated electrode in vagina and pad on abdomen.

(B) Galvanism. Negative electrode in vagina, large pad on abdomen. Treatments: Thirty minutes every other day, alternating between A and B.

**Uterus, to increase tone to:** (A. J. Smith, M.D.)

(A) Surging or rapid sinusoidal. One electrode on abdomen and a large nickel plated electrode in vagina.



FIGS. 4,668 to 4673.—Columbia diagnostic lamp outfit. *It consists of a*  $\frac{1}{4}$  inch nickel plated brass tube 6 inches long, with a socket on end  $\frac{7}{16}$  inch in diameter, for standard miniature base lamps. An 8 ft. green silk cord is provided with cord tips to connect to any current controller, series socket, wall cabinet, etc. The  $2\frac{3}{4}$  volt lamp bulb has a lens blown in the end.

(B) Galvanism. Copper ball electrode with positive cord in vagina and large negative pad on abdomen. Treatments: Begin with A for thirty minutes for increased tonicity and change to B for five minutes for the local, astringent, prophylactic effect of the copper salts.

**Vagus Hypotonia (Low Vagus Tone):** Rapid sinusoidal. (Abrams.)

Claud Bernard produced diabetes in the animal by irritating the floor of the fourth ventricle. Since then it has been shown that other parts of the nervous system when irritated will produce diabetes, hence there has arisen a neurotic theory of diabetes which supposes it to be



caused by a vaso-motor paralysis, resulting in a greater quantity of blood flowing through the liver. The tone of the vagus may be permanently increased by applying the rapid sinusoidal current to the seventh cervical spine by means of the double interrupting electrode. Seance from ten to fifteen minutes, being careful not to over stimulate.

**Velum, Post-Diphtheritic Paralysis of the:** Rapid sinusoidal.

Five cases are reported. In the first three cases the paralysis was of twenty to forty days' standing. After three or four treatments, great improvement was apparent and entire relief resulted after eight to eleven applications. In the fourth case reported the paralysis was of seven years' standing and no benefit resulted. In the fifth case the treatment was begun too soon, on the sixth day while the diphtheritic neuritis was still in progress, and an aggravation of both subjective and objective symptoms was the result. A rapid, intermittent, faradic or alternating sinusoidal current may be used, for fifteen minutes at a time. A large electrode is placed on the back of the neck and the patient's hands or feet are placed in a bowl of water. The treatment should not be painful.

**Vomiting in Pregnancy:** Rapid sinusoidal. (J. J. P. Armstrong, M. D., Douglas, Ariz.)

I have used the rapid sinusoidal in ten consecutive cases of vomiting in pregnancy with most excellent results and depend on it almost entirely in such cases, especially those of obstinate type.

**Wasting of muscles, due to impaired nutrition from pelvic sources:**

(A. J. Smith, M. D.)

(A) Superimposed wave. One electrode in cervical region, other over affected region.

(B) Faradic current or rapid sinusoidal: One electrode on abdomen, other in vagina.

Starting with A for 10 minutes, change to B for 10 to 30 minutes, giving treatments every day for the first month, then every other day.

**Mechanical Vibration.**—This is a remedial agent of proven value. Massage is one of the oldest forms of physical therapy, in fact it is almost as old as medicine itself.

**Vibratory Technique**

**Constipation.** (Rice.)

Let the patient lie upon the left side. Place the tip of the dilator, lubricated with tragacanth lubricant, against the sphincter muscle,

turn on the vibrator, gradually increasing the speed and making light pressure at the same time with the dilator until it passes as high up as possible. Turn the vibrator off and wait a moment before again turning it on. Continue turning on and off for about five minutes. Managed gently with interrupted vibrations, there is not the danger of over-exhausting the muscles that there is when the vibrations are continuous. For general stimulation to the gastro-intestinal tract, as well as for systemic effect, it is well to follow this application with interrupted vibration to the spinal column, vibrating from the fourth dorsal to the end of the spine, and also to vibrate the colon through the abdominal walls. In the latter the vibrator should have a long stroke and should be passed over the colon from the right to the left side. The vibratory treatment requires about ten minutes.

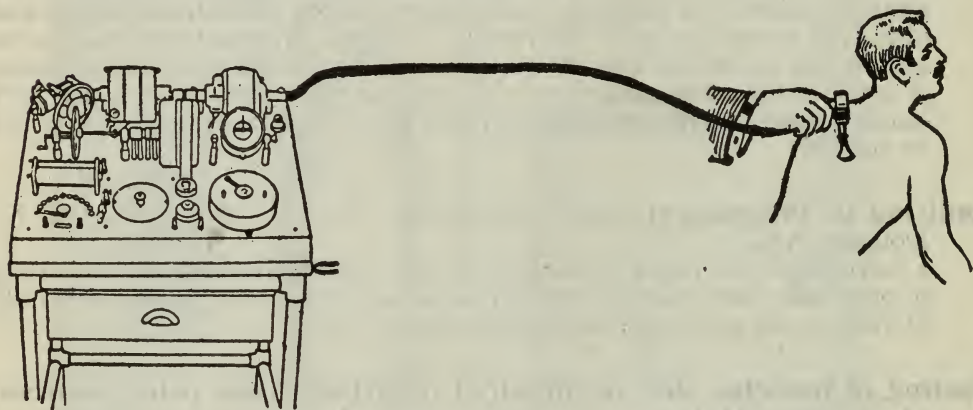


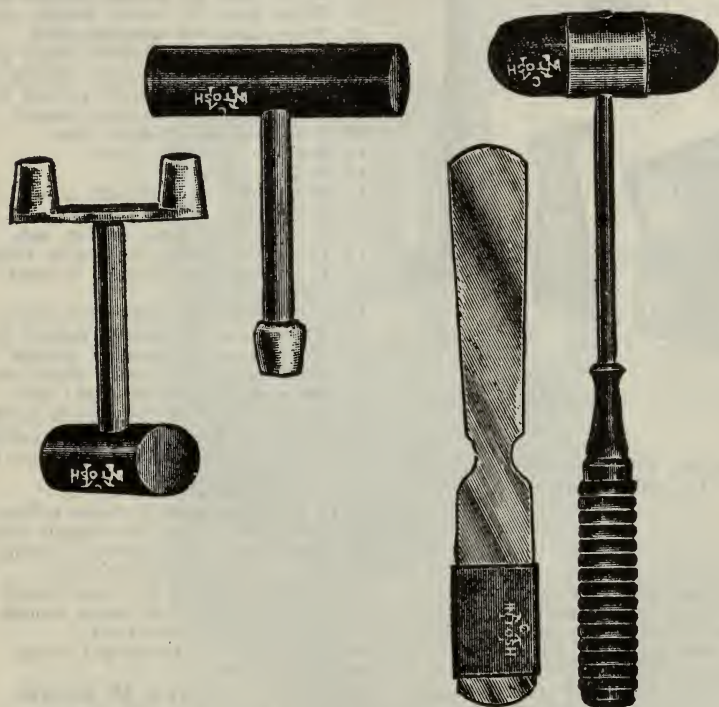
FIG. 4,674.—McIntosh apparatus showing application of *mechanical vibration*. The effects claimed for mechanical vibration are: 1. Cardiac activity is regulated. Blood pressure may be lowered reflexly. It may be raised also. 2. Contracts arterial blood vessels. If prolonged, dilatation results. Pulse rate may be lowered. 3. It induces many reflex effects as well as motor, sensory, secretory and vaso-motor effects. It lessens and removes hyperactivity of nerves. It diminishes pain and relieves congestion not due to organic conditions. 4. Diminishes and relieves muscular pain and stiffness. It can relax tense muscles and cause relaxed and atrophied muscles to become firm and increase in size. It tones up cardiac muscles. 5. Reflexly induces contraction of the lungs. Relieves pain and dyspnoea. Improves respiration. 6. Diminishes size of glands, directly and reflexly. 7. Contracts or dilates the liver, stomach and spleen. 8. Diminishes irritability of the bladder when not due to organic conditions. 9. Induces peristalsis. 10. Increases or diminishes lymphatic circulation according to the vibratory friction given, centripetal or centrifugal. 11. Assists in diminishing intraocular tension. 12. Lessens nasal hyperemia. 13. Suction vibrations are valuable in removing pus from a boil, etc.

**Mechanical vibration of the eye is indicated for twitching of the lids, blepharospasm and glaucoma. (Arnold-Snow.)**

The greatest gentleness and skill must be employed in the treatment of the eye, avoiding the possibility of causing irreparable injury, such as retinal detachment. In some cases vibratory treatment alone is effective, while in others a combination with other methods gives the best results. As with other affections, treatments should vary from twice a day to once a week, according to the indications of the case.



Mechanical vibration when applied over the eye in the treatment of eye diseases should be employed in the form of a vibra-massage. Make the application for but a short time, 30 seconds to a minute or so, and as a rule only once daily, using a soft rubber cup vibratode with the shortest stroke and no pressure over the eye ball. In all cases indicated constitutional treatment, with due consideration of diet and hygiene, must be observed. A study of the blood pressure should be made in every case.



FIGS. 4,675 to 4,678.—Dr. Abrams' reflex set for the physician who desires to test the value of concussion according to Dr. Abrams' method. The hammer, for evoking vertebral reflexes, is called a **plexor**. It is employed for diagnostic purposes and as a concussion apparatus in spondylotherapy. Many use it exclusively to attain their therapeutic results. **The pleximeter** is of metal, covered at one end with rubber and is employed concurrently with the plexor. **The single pronged instrument** is used for demonstrating areas of paravertebral tenderness. Better than the fingers. **The two pronged instrument** (radicularpressor) is employed for making bilateral pressure on the roots of the spinal nerves at their exit from the intervertebral foramina. The employment of pressure in treatment and the use of these various instruments is explained in Dr. Abrams' book on spondylotherapy. The hammer and pressor instruments are fitted with polished hard rubber handles, while all metal parts are nickel plated.

### Splenic congestion. (Arnold-Snow.)

Deep vibratory friction or interrupted vibration with the disc vibratode should be administered over the side of the gland from the ninth to, and including, the eleventh rib between the axillary lines. Reflex contraction of the spleen can be induced by vibrating with the ball

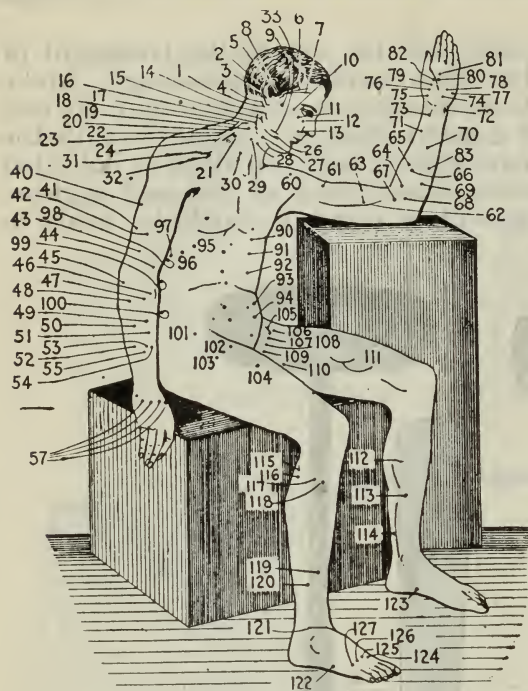


FIG. 4,679.—Diagram showing motor points (after Myer) for testing for reaction of degeneration.

1. Facial nerve at its exit.
2. Auriculo-posterior branch of facial nerve.
3. Branch of facial to occipito-frontalis muscle.
4. Branch of facial to trapezius muscle.
5. Auriculo-anterior branch of facial.
6. Branch of facial supplying frontalis muscle.
7. Facial branch to corrugator supercilii.
8. Facial branch to orbicularis palpebrarum.
9. Facial branch to zygomaticus major.
10. Facial branch to zygomaticus minor.
11. Facial branch to levator labii superioris.
12. Facial branch to compressor nasi.
13. Facial branch to levator labii sup. proprius.
14. Buccal branches of the facial.
15. Infra maxillary cutaneous branches.
16. Subcutaneous branches of colli super.
- 17-18. Branches of spinal accessory.
19. Affects the platysma myoides.
20. Branch from cervical plexus to lev. Aug. scap.
21. Phrenic nerve. Respiration.
22. Dorsalis scapula nerves.
23. Posterior thoracic nerve.
24. Supra-scapular nerve.
26. Branch of facial to triangularis menti muscle.
27. Hypoglossus nerve.
28. Motor point of omo-hyoid muscle.
29. Motor point of sterno-thyroid muscle.
30. Motor point of sterno-hyoid muscle.

31. Outer cord of brachial plexus.
32. Anterior thoracic nerve.
33. Branch of facial to depressor labii inf.
40. Branch of radial nerve to triceps.
41. Radial nerve.
42. Radial branch to brachialis ant. muscle.
43. Radial branch to supinator longus muscle.
44. Radial branch to exten. carpi rad. long.
45. Radial branch to anconeus quartus.
46. Nerve to extensor carpi rad. brevior.
47. Nerve to extensor com. digitorum.
48. Nerve supplying the extensor carpi ulnaris.
49. Motor point for abduct. pollicis longus.
50. Motor point for exten. minimi digit. prop.
51. Motor point for extensor digiti.
52. Motor point for extensor indicis prop.
53. Motor point for extensor pollicis longus.
54. Motor point of extensor pollicis brevis.
57. Motor point of interossei externi.
60. Branch of ant. thoracic nerve.
61. Musculo-cutaneous nerve.
62. Median nerve.
63. Motor point of brachialis int.
64. Motor point of pronator teres.
- 65, 66. Points of flexor digitor. sub.
71. Branch of median to pollicis longus.
72. Branch of ulnar to palm of hand.
73. (See 62.)
74. Motor point of volaris profundus.
75. Motor point of abduct. pollicis brevis.
76. Motor point of opponens pollicis.
77. Motor point of abductor digiti min.
78. Motor point of flexor digiti min.
79. Motor point of flexor pollicis brevis.
80. Branch of ulnar to abductor pollicis.
- 81-82. Branch of median supplying the lumbricals.
83. Motor point of flexor digitor.
- 90 to 94. Motor point of rectus abdom. ext.
- 95 to 98. Motor point of obliquus abdom. ext.
99. Motor point of transversus abdom.
100. Motor point obl. abdom. inter.
101. Branch of crural to tensor fascia lat.
102. Branch of crural to rectus femoris.
103. Motor point of vastus ext.
104. Motor point of vastus and rectus.
105. Crural nerve.
106. Branch of crural to M. Sartoris.
107. Motor point of pectineus muscle.
108. Motor point of abductor brevis.
109. Motor point of abductor longus.
110. Motor point of gracilis.
111. Motor point of vastus int.
112. Motor point of soleus.
113. Branch of tibialis to flexor digitor.
114. Tibial nerve.
115. Peroneal nerve.
116. Popliteal nerve.
117. Motor point of ext. digitor com. long.
118. Motor point of tibialis anticus.
119. Motor point of ext. hallucis long.
120. Motor point of peroneus tert.
121. Motor point ext. digitor com.
122. Motor point of abductor digiti min.
123. Motor point of hallucis.
- 124-127. Motor points of interossei ext.

The motor point of the sciatic nerve (not shown in cut) lies between the trochanter major and tuber. ischii.



between the first and second, and second and third lumbar vertebræ, following Abrams' method of vertebral concussion. The treatment should be prolonged for five, ten, or even fifteen minutes, as the response warrants. This is of value in malaria and pathological states characterized by an enlarged spleen.

**Electro-Cautery.**—This treatment utilizes the heating effect of the electric current for surgical purposes. Various forms of cautery knife are used, some being shown in figs. 4,682 to 4,686.

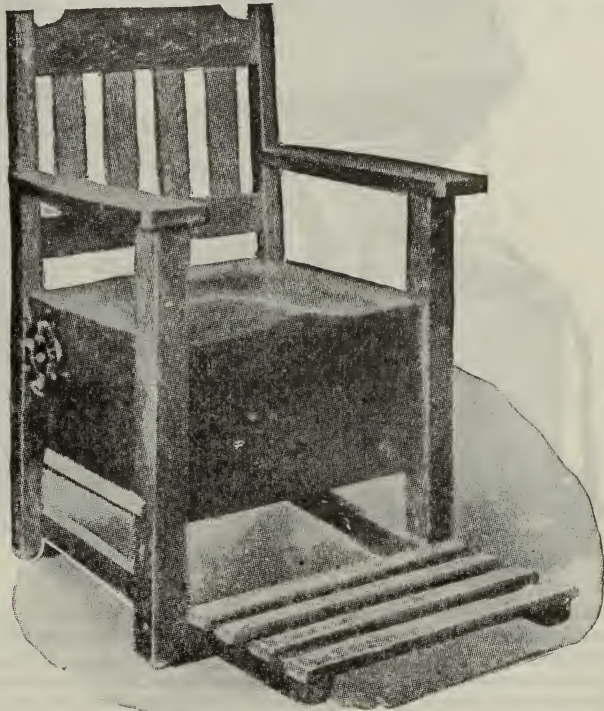


FIG. 4,680.—Columbia vibrating chair. In appearance this is a heavy and substantial chair, and there is nothing about it that would give apprehension to the most sensitive patient. Concealed rubber bumpers prevent transmission of the vibration to the floor and prevent noise, so that in operation there is just a slight hum. By means of a simple mechanism the strength and rapidity of the vibration is varied from a very light movement to as heavy a vibration as can be desired. The adjusting device is separate from the chair and may be placed on the physician's desk and the degree of vibration varied by him as desired. A switch is on the chair where the current may be turned off or on. *While taking a treatment* the patient experiences a pleasing sensation, as the circulation is increased and the nervous tension relaxed on account of the rapidity of the vibration, and they nearly all remark: "How is the electricity applied?" as the sensation feels similar to a rapidly interrupted faradic current. The use of the chair is indicated in rheumatism, locomotor ataxia, paralysis agitans, neurasthenia, anemia, constipation, obesity, etc. It is used in many sanitariums where patients are too weak to exercise and where the circulation may be increased without increasing the pulse. The work of Zander, Ling, Granville, Kellogg and others indicates that this is an effectual method of treatment. No special wiring is required; all that is necessary is to connect to the electric light socket.

They consist of suitably shaped platinum wires which require different amounts of electric energy to render them red hot, depending upon the surface of heated metal which they expose to the air. The broad flat blades requiring more energy than the narrower blades. The broadest blades require from 25 to

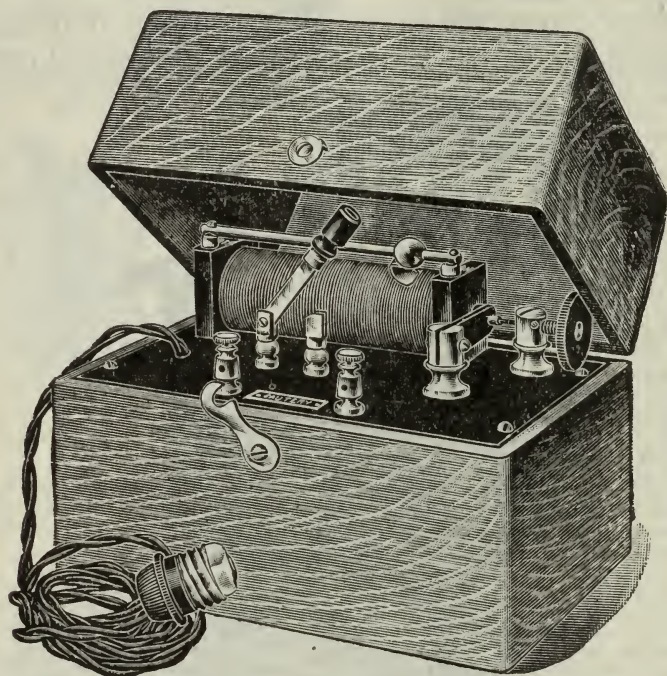


FIG. 4,681.—McIntosh universal cautery transformer, for either alternating or direct current.

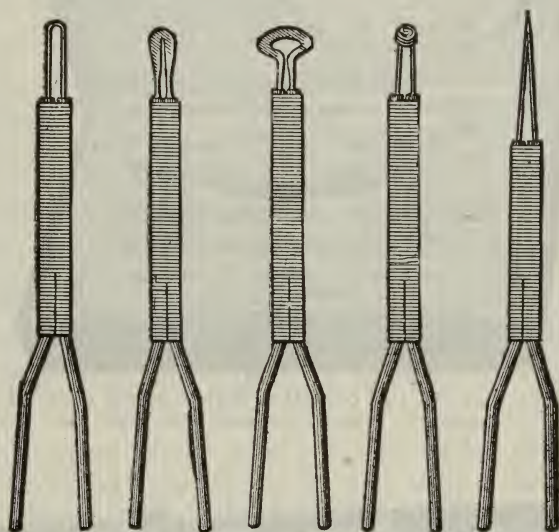
*It consists of* an open core transformer, in appearance like an induction coil, mounted on a finely finished black enameled slate base and fitted in a highly polished, quarter sawed golden oak case, measuring  $9 \times 6 \times 7\frac{1}{2}$  inches. The transformer can be connected to any lamp socket in the office with either direct or alternating current providing the voltage is 110 volts, approximately. For a higher voltage a series lamp and tap can be furnished at a slight additional expense. Control of the heat of the cautery knife is had by sliding the regulating knob on top of coil from left to right, thus increasing the current strength very gradually until the desired heat is obtained. Any electrode from the lightest eye point to the heaviest used in nose or throat work may be employed. Diagnostic lamps of almost any style, ranging from small  $3\frac{1}{2}$  volt urethroscopes or auriscopes to heavy trans-illuminators requiring 18 volts, can be illuminated to full brilliance, by proper adjustment of the regulator. A compartment is provided in the lid of box which will hold cautery handle, cords or any accessories desired, a metal plate forming a cover for this section.

35 amperes at one volt, or from 25 to 35 watts. According to E. L. Smith, M.D., the degree of heat of the platinum point is important. Cherry red heat is generally used. The object is



to press the mucous membrane down to the periosteum with the edge of the electrode, with the least amount of cicatricial tissue.

If hypersensitive areas are to be destroyed, then use the electrode flat with white heat and make a superficial burn. When the platinum point comes in contact with the tissues it will be noticed that it lowers the heating point, hence, if a large area is to be treated, it will be necessary to go in with a higher point of heat than is needed.



FIGS. 4,682 to 4,686.—Various electric cautery knives. The snare cautery consisting of a loop of platinum wire which is placed around the growth or part to be removed, then the loop drawn tight and the current passed through it, so that the flowing wire is pulled through the part, consumes a smaller number of watt, but requires a greater voltage to send a sufficient amount of current through the platinum wires. The current for the operation of electric cautery knives may be either continuous or alternating. It may be obtained from either primary batteries or storage batteries, or from alternating current sources of supply, the voltage in the latter case being stepped down by means of suitable transformers to that required for the operation of the knives.

**The Technique to be Used.**—After selecting an electrode to fit the pathological condition, place the platinum surface on the tissue, but do not press the closing button while the electrode is still. Just before pressing the button to heat the platinum wire, start a gentle to and fro motion over the area to be treated. Do not stop with the current on, as it will adhere and break the eschar and bleed. Remove the platinum point before the heat is turned off. Care should be taken not to allow the cautery point to come in contact with two opposite surfaces,

as they would be very likely to adhere and form a troublesome synechia. This can be avoided by using an electrode where one part is wrapped. When possible, treat only one location at a time. Keep the area well cleaned out with any good alkaline solution and hydrogen peroxide (1 in 5), and the crusts will come off in a week to ten days.

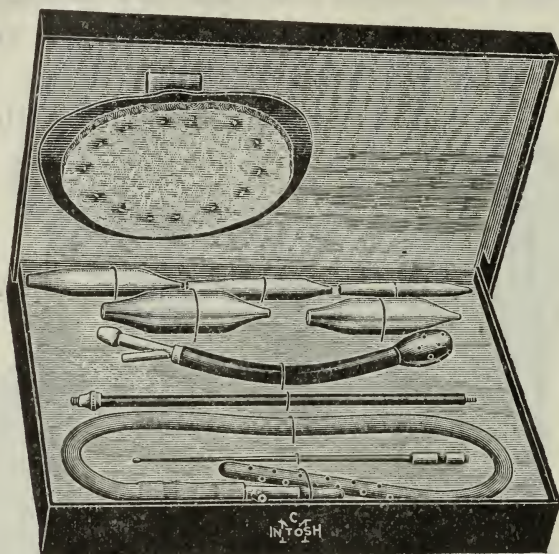


FIG. 4,687.—Protologists' special set. *It contains* hollow rectal electrode, fistula electrode, rectal stricture set; hydro-electric rectal tube and a sponger pad electrode.

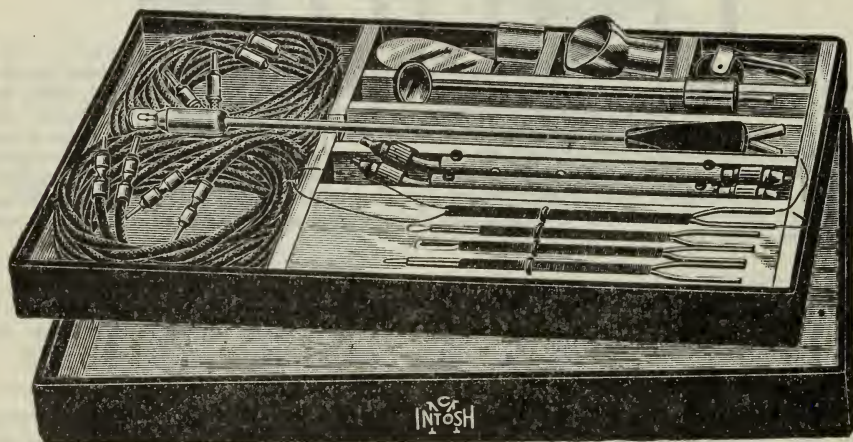


FIG. 4,688.—McIntosh cautery illuminator set comprising a list of attachments for electro-cautery and lamp diagnoses. It is suitable to be employed in connection with a transformer, converter or wall plate with cautery.



## CHAPTER LXXXVIII

## X-RAYS

These rays, discovered by Roentgen were called X-rays because of their unknown real nature. Some scientists have regarded X-rays as light rays of very small wave length, but the sounder theory seems to be that they are instantaneous impulses produced by the impact of electrons upon the anti-cathode. They may be likened to the sound waves produced by rain drops on the roof, not of a definite pitch. The velocity of X-rays is probably the same as that of Hertzian waves.

The exact nature of the X ray is still under discussion. The most commonly accepted explanation is that it is a disturbance of the luminiferous ether similar to visible light, but having much shorter wave length than ultra-violet light.

**Ques. What apparatus is necessary for the production of X-rays?**

---

NOTE.—Roentgen spoke of his discovery, made on Nov. 8, 1895, as follows: "I was working with a Crookes tube covered by a shield or screen of black cardboard. A piece of barium platino-cyanide paper lay near by on the table. I had been passing a current through the tube and noticed a peculiar black line across the paper. As this effect could be produced by the passage of light only, and as no light except from the tube could have struck the plate, I made a test at once, and found that some kind of ray actually passed through the black cardboard cover. In a completely darkened room the paper screen washed on one side with barium platino-cyanide lighted up brilliantly, and fluoresced equally well no matter which of its sides was turned towards the tube. This fluorescence was noticeable even at a distance of two meters. The most remarkable thing to me was that this fluorescence passed through the black cardboard cover, which transmits none of the ultra-violet rays of the sun or of the electric arc. I found by experiments that all bodies are transparent to this influence, although in very different degrees."

Ans. A vacuum tube, a battery, and an induction coil with interrupter.

**Ques. How are X rays produced?**

Ans. If an electrical discharge be passed through a vacuum tube exhausted to a Crookes vacuum (much higher degree of exhaustion than in the tubes of Hillorf, Geissler and Lenard)

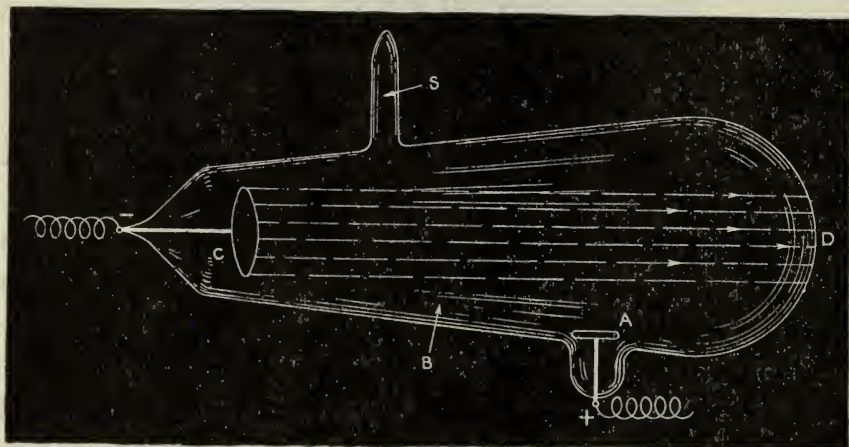


FIG. 4,689.—Old form of Crookes tube illustrating the production of X rays. The anode A and the cathode C, are aluminum plates cemented on the ends of iron or copper rods sealed in the glass bulb B. S is the seal off tube, which is closed after the bulb has been exhausted of air to the desired vacuum. In the various forms of tube used for different purposes, various degrees of vacuum are employed, but complete exhaustion is never used as the electric spark will not pass through an absolute vacuum. *In operation*, when the anode A is connected to the positive terminal, the cathode C to the negative terminal of an induction coil or influence machine, and current turned on the following phenomena will occur: 1. If the vacuum in the tube be low, (not much below the pressure of the atmosphere), the discharge will pass in the form of a spark, between the anode and the cathode, but no cathode rays are found. 2. If the vacuum be sufficiently high to prevent the passage of a spark, no matter how high a pressure may be applied, the bulb will have a dark appearance except around the area D, which will be illuminated by a bright canary yellow light. This light is due to the fluorescence of the glass under the action of the *cathode rays* emitted in straight lines from the cathode C, as shown by the dotted lines. The *cathode rays* are generally accepted as a form of *radiant matter* consisting of streams of negatively electrified material particles either of the air remaining in the bulb after exhaustion, or of particles torn from the cathode, and repelled from the latter at enormous velocity. In other words, the stream of cathode rays is accepted as the equivalent of an electric current. This theory is sustained by the fact that cathode rays are deflected by a magnet, and furthermore, that they are capable of producing marked mechanical, heat, and light effects, in the *fluorescence* of various solid substances, various kinds of glass, chemical salts and acids, placed in its path. The fluorescence being the actual conversion of the energy and momentum of the cathode stream into light. In 1895, Roentgen accidentally discovered that the surface rendered fluorescent by the action of the cathode rays emitted rays which differed from cathode rays in that they were not deflected by a magnet, and were capable of penetrating opaque objects to a remarkable degree. These rays are now commonly known as Roentgen rays or X rays and the special forms of tube (X ray tubes) employed in their production are merely Crookes tubes having a somewhat higher vacuum than is usually employed for the production of cathode rays.



X rays are produced whenever the cathode stream is arrested by the walls of the tube or metallic objects therein.

**Ques. What is the cathode stream?**

Ans. This is believed to be a discharge of negatively charged electrons from the surface of the cathode.

**Ques. What is a focus tube?**

Ans. One in which a concave cathode focuses the cathode stream upon a flat metallic target as shown in fig. 4,690.

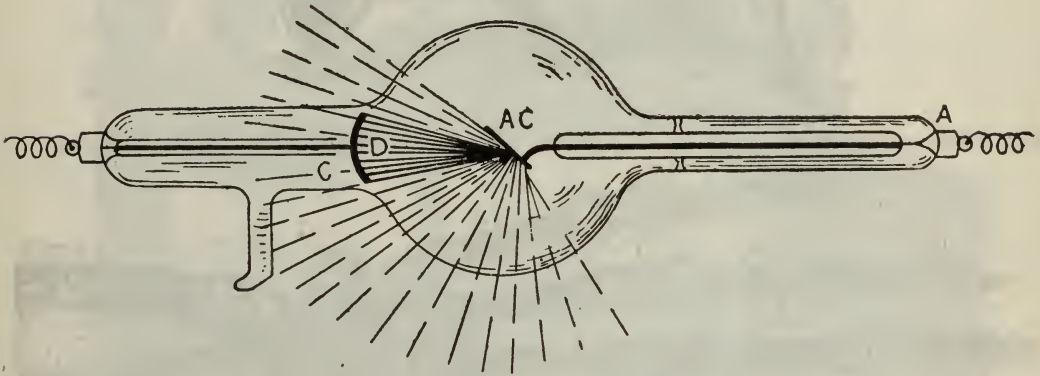


FIG. 4,690.—Single focus X ray tube. This is the simplest form of single focus tube designed for limiting the X ray radiations to a point source, thereby obviating the necessity of placing an object far from the tube when the former cannot be brought close to a fluorescent screen. In other words for the purpose of reducing the time of exposure required for making a *radiograph* or *skiagraph* of such an object. In this tube, the copper wire A, is the *anode*, the cup shaped aluminum plate C, the *cathode*, and the thin plate of platinum foil A, C, is the *anti-cathode*. The copper wire connecting the anode with the anti-cathode, makes the latter the anode. **In operation**, the cathode rays represented by the dark cone D, converge onto the inclined surface of the anti-cathode, so that the latter becomes a *point source of X ray*, the rays being radiated in all directions as shown by the broken lines. The anti-cathode is made of platinum so as to enable it to resist the powerful heating effects of the concentrated cathode rays.

**Fluorescing Screens.**—Examination of objects, such as the bones of the hand, foreign bodies in the system, etc., are made with the aid of a *fluorescing screen* or *fluoroscope*. This device consists of light tight box A, fig. 4,691, provided with an aperture for the eyes at B, and an opening C, at the opposite end for the

fluorescing screen D. The latter consists of a piece of paper or cardboard coated with platinum-barium cyanide crystals, which fluoresce under the action of X rays. When such a screen is held against the face by means of the handle, and the aperture

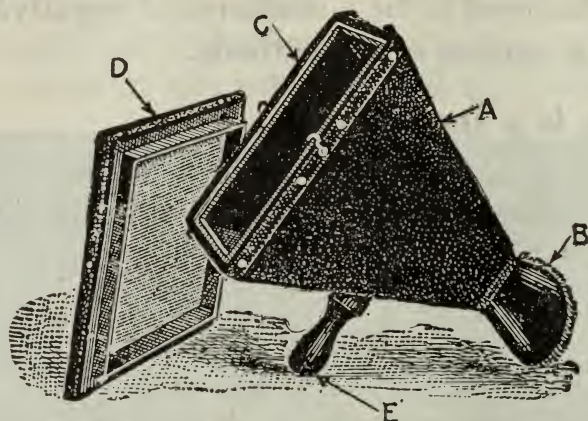


FIG. 4,691.—Fluoroscope. A, box; B, opening for eyes; C, opening for screen; D, screen.

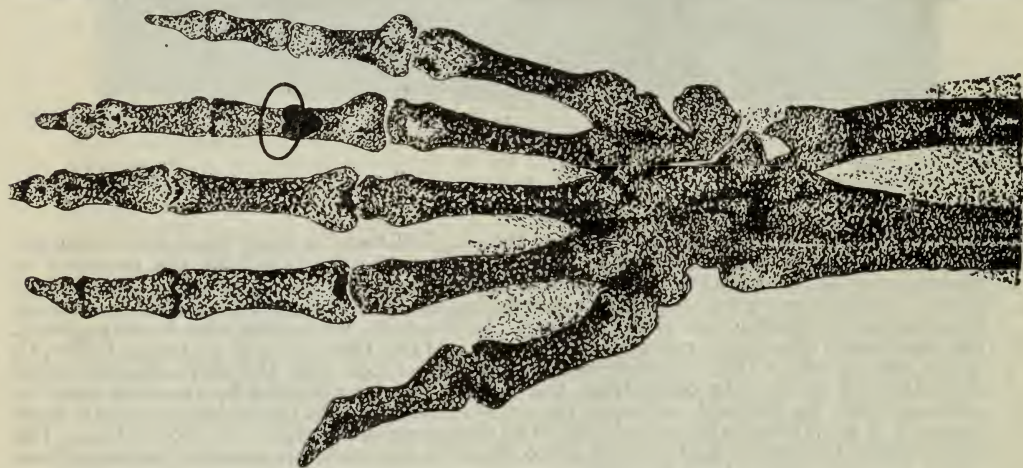


FIG. 4,692.—X ray fluorescent shadow of the bones of the hand and wrist.

B, pressed tightly around the eyes so as to exclude all outside light, and the screen placed near an active X ray tube, the former will fluoresce with a greenish yellow light.

If a hand, for instance, be placed between the screen and the tube, the X rays will pass through the fleshy parts and impinging on the screen



will cause it to fluoresce, but, being intercepted by the bones, will not affect the screen, thus leaving thereon a shadow picture of the bones as shown in fig. 4,692. It is immaterial whether the screen be placed in the holder box with the crystal coated, or opposite side turned to the eye aperture.

The intensity of the illumination produced by the fluorescence on the screen rapidly diminishes with the distance of the screen from the tube, therefore, in order to obtain a maximum illumination and consequently

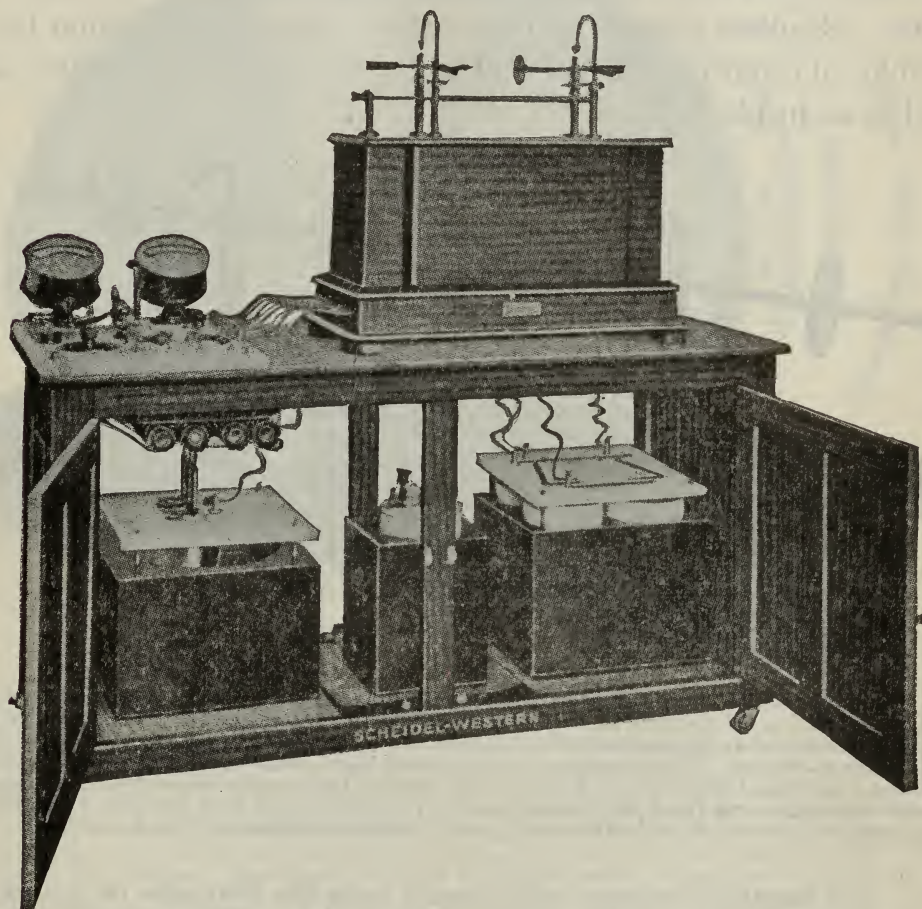


FIG. 4,693.—Scheidel-Western radiographic special coil with anti-acid interrupter for X ray treatment.

a sharply defined shadow, the screen should be held close as possible to the source of X ray, and the hand close to the screen.

**Ques. What is a radiograph?**

Ans. A picture taken upon a photographic plate by means of X rays.

The picture is usually of an opaque object through which the rays pass.

**Ques. How is a radiograph taken?**

Ans. Replace the fluorescent screen of the fluoroscope by a suitable photographic plate, give it the proper exposure and develop as in photography.

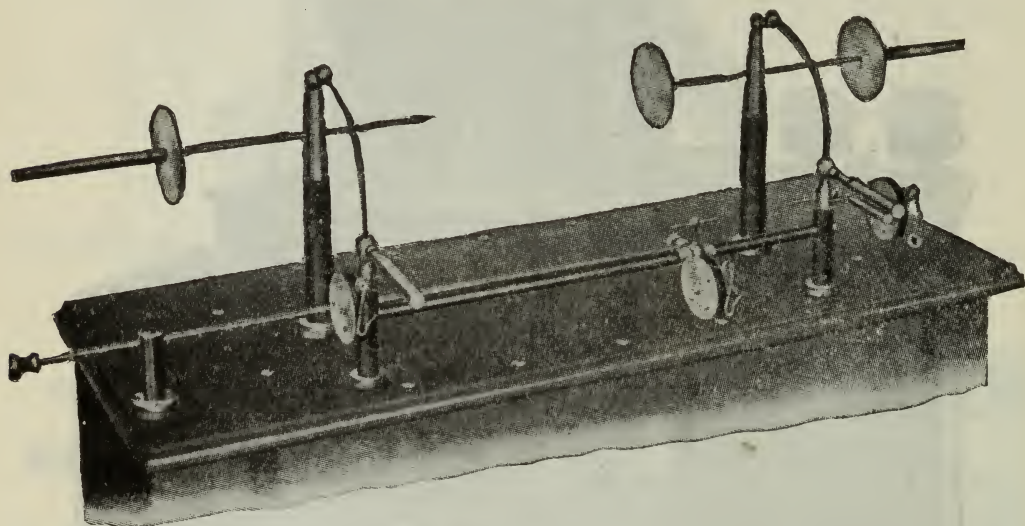


FIG. 4,694.—Scheidel-Western third terminal on radiographic special coils. The third terminal is for regulating the vacuum in X ray tubes, which is accomplished by moving a cord reel that is connected to the regulating bulb of the tube either to or from the negative or positive pole as desired. This transfers the unpleasant regulating spark from near the patient to the coil, several feet away, and enables the vacuum to be regulated without stopping the machine or moving from the switchboard. The series gaps also provide a means for putting into the circuit a double spark gap to eliminate inverse if ever required.

The length of exposure will depend upon the character of the object radiographed, the quality of the X ray tube, and the current strength employed.

**Practical Points on X Ray Photography.**—1. Radiographs may be made on photographic paper, films, or glass plates. For best results, however, specially prepared X ray plates with double coating should be used.

2. Very rapid plates have not the same advantage over medium or slow plates as they have in ordinary photography.



3. Stored plates must never be kept near the X ray room or even within 20 feet of the same unless kept in a lead lined box or drawer impervious to the X radiance.

4. Keep dry plates in a dark room free from sudden changes of cold to warmth to avoid condensation, placing the package on edge to avoid pressure.

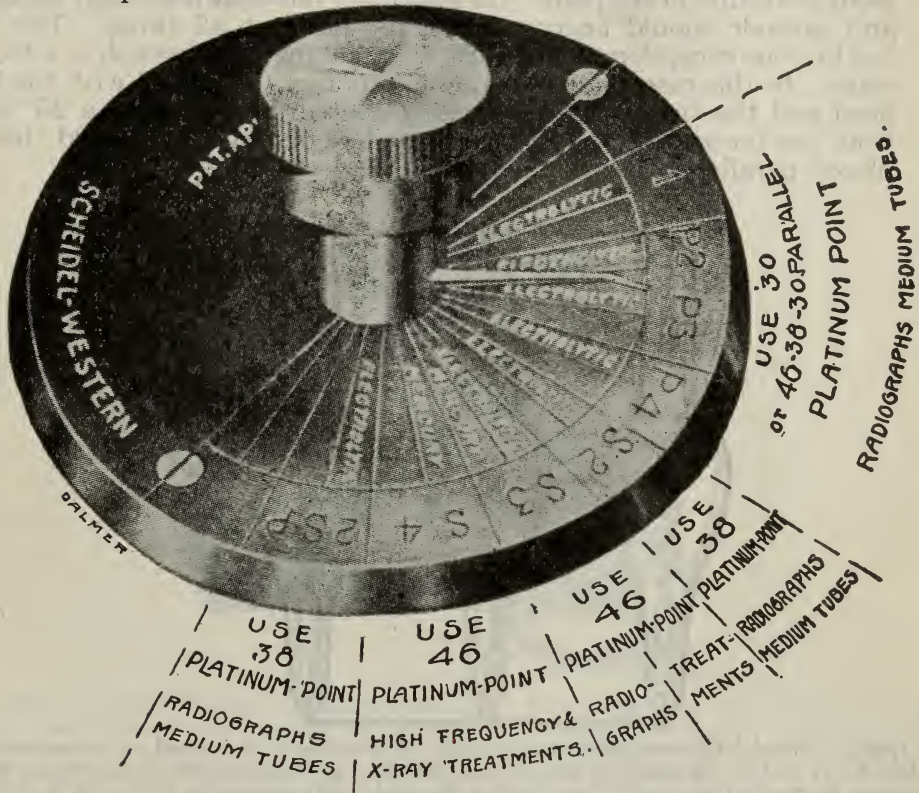


FIG. 4,695.—Hulton inductance switch. Every point on the inductance represents a distinct value in the secondary voltage from the coil by changing the ratio of the primary turns of wire to the secondary. The connections are made so that the markings on the dial represent the turns of wire as follows: P1 equals one layer primary winding; P2 equals two layers primary winding in parallel; P3 equals three layers primary winding in parallel; P4 equals four layers primary winding in parallel; S2 equals two layers primary winding in series; S3 equals three layers primary winding in series; S4 equals four layers primary winding in series; 2SP equals four layers primary winding in series parallel. **Uses of the different winding:** All windings are used with the electrolytic interrupter, and only windings S3 and S4 with the mercury interrupter. For X ray with the anti-acid interrupter S2 and S3 are used and for high frequency treatment S2 and S3. When used with the electrolytic interrupter, setting the switch P1 to P4 is for radiographic work with hard tubes. P4 gives the least inverse in the tube. For use with medium tubes, use the setting 2SP, which gives more detail in the radiograph than does P4, and practically no inverse. S2 is the setting for medium or high tubes for treatment work, and S3 and S4 for low tubes, or, with the mercury interrupter. Both 2SP and S2 give greater amperage and less voltage, therefore but one-half the regular spark length is obtained that will be given by the setting on P4. From the description given, it will be seen that this acts as a selector switch and is essential for the best radiographic and treatment work under all conditions.

5. It is of advantage to place a sheet of lead or zinc below the plate on the non-coated side to intensify the contrast, details, etc.

6. The position of the tube in relation to the plate and patient must be minutely observed. Place the tube so that the anode and cathode terminals are in a parallel position. The anti-cathode is then to directly focus the center of the plate. An imaginary line drawn through the anode and cathode should be parallel to the plate at all times. This rule has but one exception, and that is, when taking a radiograph of a frontal sinus. In this case the patient should lie face downward with the forehead and the tip of the nose touching a surface tilted to a  $25^\circ$  angle from the horizontal. The imaginary line of the tube should then be placed parallel to the horizontal plane.

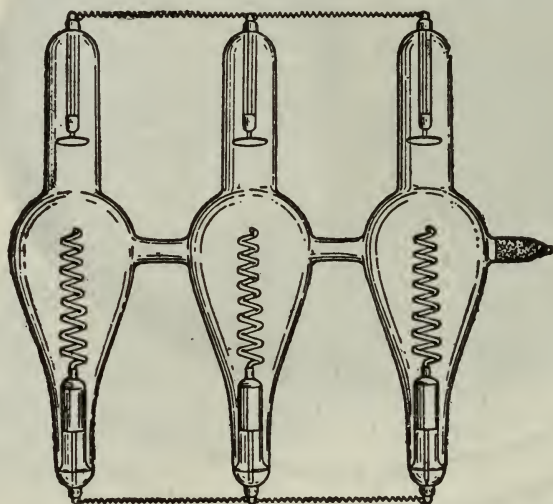


FIG. 4,696.—Scheidel-Western triple valve tube. The valve tube is used as an accessory to the X ray coil for eliminating any inverse current. It assists in obtaining greater definition in the radiograph, and by eliminating the heat rays prolongs the life of the X ray tube.

7. The distance of the tube from the patient or plate must not be too great, as the intensity of the X radiance diminishes unevenly with the distance; if too short, image will appear too large and distorted, moreover, there is some danger of producing dermatitis.

8. The longest distance between anti-cathode and emulsion of plate for thorax, pelvis, etc., need not exceed 20 inches, while the shortest distance of small objects, as teeth, finger, toes, etc., should not be less than 10 inches.

9. Make the patient comfortable so that the part to be radiographed is motionless.

10. Start apparatus once before plate is in position to avoid movement due to possible fright of patient.



11. The object should be as near the plate as possible.

12. If the exposure is to be as short as possible to avoid movements due to respiratory motion, heart action, or with children who cannot be persuaded to keep quiet, a hard tube must be selected unless a photographic or intensifying screen be used with the X ray plate.

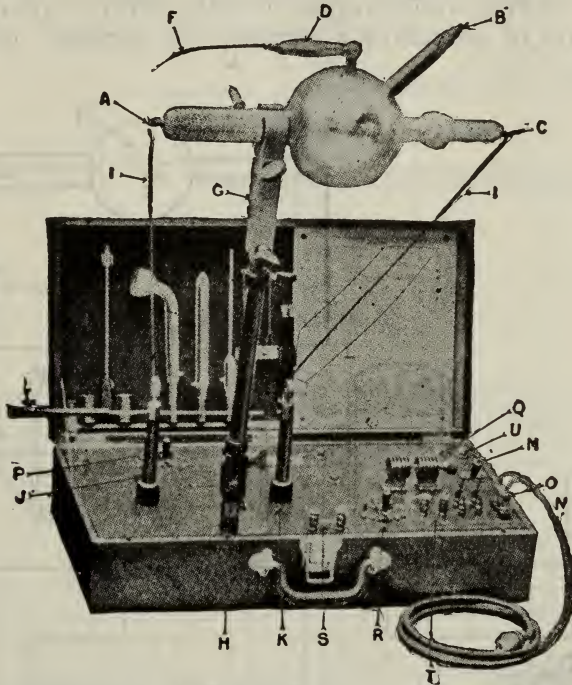


FIG. 4.697.—Scheidel-Western suitcase portable coil. *The parts are:* A, cathode; B, anode; C, assistant anode; D, regulating chamber; F, regulating adjuster; G, tube holder; H, tube holder socket; I, connection tapes; J, left hand terminal post; K, right hand terminal post; L, regulating rod; M, main line switch; N, connecting cord; O, connecting cord sockets; P, selector switch; Q, interrupter spark gap; R, controller switch; S, D'Arsonval; T, cautery and diagnostic lamp; U, sinusoidal current. *To operate,* set the X ray switch at the back to the point marked X ray, or controller switch to any of the six points of varying strength; close the main switch, and adjust the spark gap until the tube is operating satisfactory. Then open the main line switch, and, after the plate is in position, close the switch for the length of time necessary to make the exposure. A radiograph of the hip can be obtained in 45 seconds, or if an intensifying screen be used, the time is reduced to between 10 and 15 seconds; other parts in proportion. The high frequency current may be applied by means of the three vacuum electrodes furnished with the coil, connecting to either of the two main posts. This current has a very high rate of oscillation, making it practically without sensation. The D'Arsonval current is applied by connecting to the two binding posts marked "D'Arsonval" and the strength of this current is regulated in the same manner as is the high frequency, by the setting of the controller switch and spark gap. The cautery is used by connecting handle and electrodes furnished with the outfit to the binding posts marked *cautery*, and varying the amount of current with the controller switch. A diagnostic lamp on a long handle is supplied and the amount of current controlled by varying the strength with the main controlling switch. Any electric lighted diagnostic instruments may be used with this coil. The sinusoidal current for inducing muscular contraction without pain is applied by means of metal or moist electrodes, connections being made to the two binding posts marked *sinusoidal*.

14. Induction coils with a flame discharge are used with good results, but accessory devices, such as spark gaps or valve tubes, should be used to properly supply the inverse current.

15. When making radiographs directly onto a photographic plate without the aid of intensifying screens, the operator must judge the

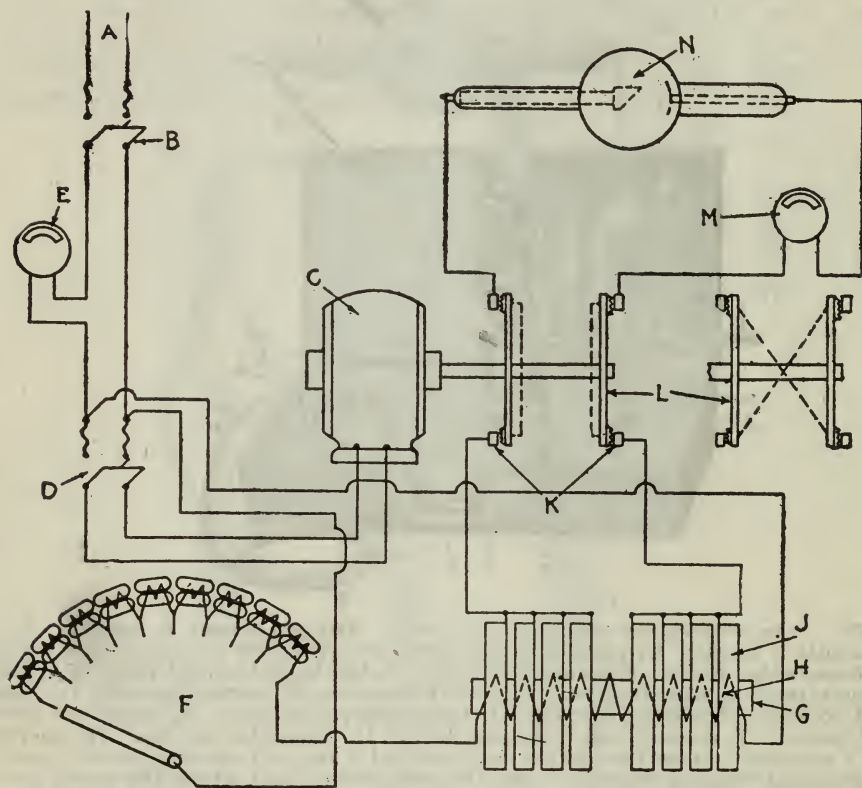


FIG. 4,698.—Diagram of Scheidel-Western interrupterless transformer. *The parts are:* A, current mains; B, main line switch; C, motor; D, motor switch; E, meter; F, choke coil; G, core; H, primary winding; J, secondary winding; K, secondary terminals; L, rectifying wheel; M, milli-ampere meter; N, X ray tube. The commercial current is generally furnished, having a rate of 7,200 alternations a minute, two alternations forming a complete cycle, which would be at the rate of 60 cycles a second. Each cycle comprises a current flow from zero to full pressure in one direction, back to zero and then to full pressure in the opposite direction and back to zero, completing the cycle. The rectifying wheel is in reality a pole changer, and as it has four contacts each edge must revolve at the constant speed of 1,800 revolutions per minute. The contacts crossing the wheel are arranged so that two on either side are connected together and two on opposite sides are connected across the wheel. As there are four contacts on the edges of this wheel and it revolves at a speed of 1,800 revolutions per minute ( $4 \times 1,800 = 7,200$  alternations per minute), passing the current in one direction 3,600 times per minute and then reversing the direction an equal number of times, giving in this way a uni-directional pulsating current delivered to the X ray tube, eliminating chance of inverse current.



current and penetration of his tubes very carefully, especially if the tube be a new one, as a heavy current or prolonged exposure has a tendency to make it soft. Should this happen, the quantity of primary current or its frequency of interruption should be reduced at once if an induction coil be used, otherwise a blue light will show within the tube and no X radiance of sufficient penetrating power is emitted.

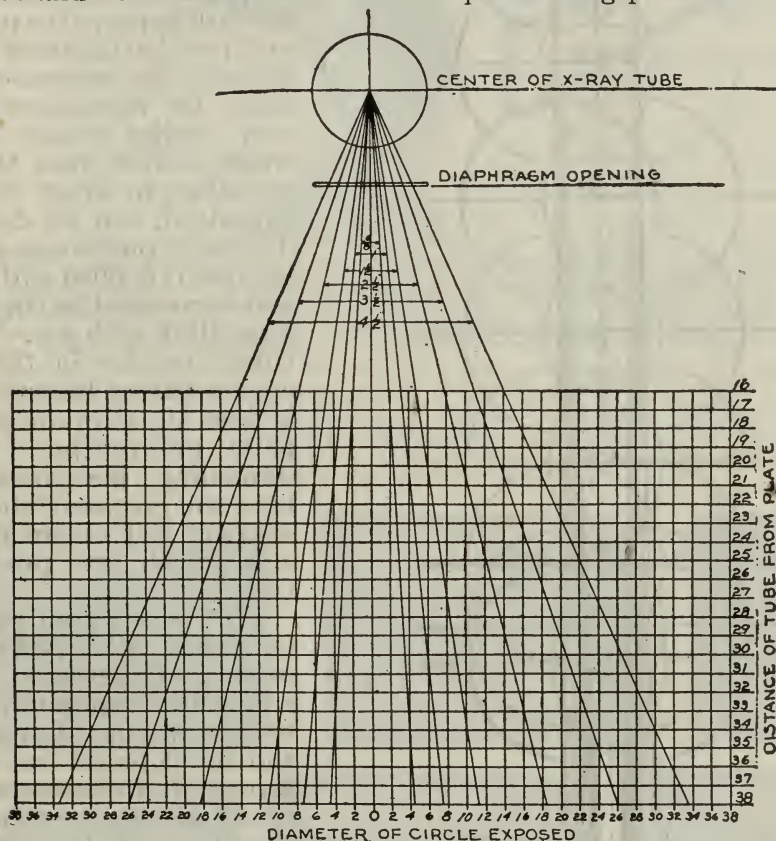
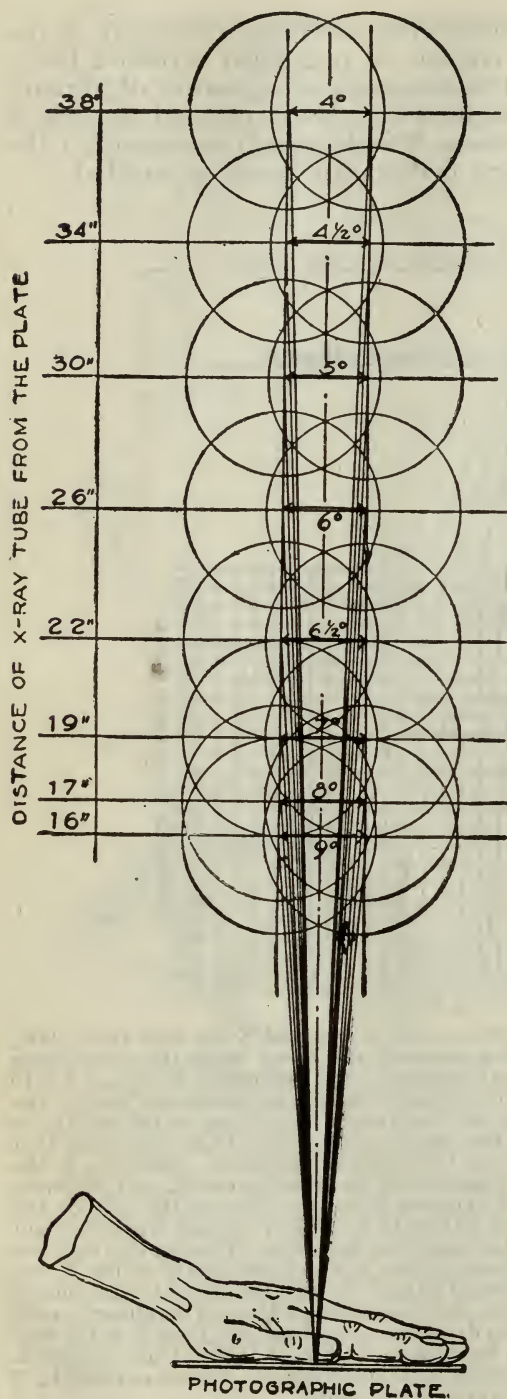


FIG. 4,699.—Diagram for estimating size of diaphragm and distance of X ray tube from plate, showing diameter of the circle exposed to the action of the X ray when the various size diaphragm are used at varying distances from the plates. **For example:** With, say  $8 \times 10$  plate, first it is desired to find the smallest circle that will accommodate this plate. Determine by taking the square of the width, or  $8^2 = 64$ , and the square of the length, or  $10^2 = 100$ ; adding  $64 + 100 = 164$ . Taking the square root  $164 = 12.8$ , indicating that the plate will go inside a circle approximating 13 inches in diameter. Referring to the table, the bottom of the bars indicate the diameter of the circle exposed, and following up between 12 and 14, it is found that the line drawn from the center of the tube on the outside edge of the diaphragm crosses between 12 and 14 at the line marked 27, at the right hand side, which indicates the distance of the tube from the plate. Tracing this distance of the tube from the plate. Tracing this diagonal line towards the center of the X ray tube, indicates that a  $2\frac{1}{2}$  inch diaphragm should be used, having the tube at a distance of 27 inches from the plate; or going further along, it is found that a  $3\frac{1}{2}$  inch diaphragm could be used, say 19 inches from the plate, or if no diaphragm was used and there is a  $4\frac{1}{2}$  inch opening below the tube, the tube could be brought to within 15 inches from the plate. Many operators do not care to expose the entire plate, utilizing the surface covered by a circle, the diameter of which is equal to the width of the plate.



16. The easiest parts to photograph are the hands, elbows and feet. Next come the knee, head, thorax, and shoulders. The most difficult part is the abdomen, and the task to prove the presence and position of stones in the kidneys, the ureters, etc. It must be remembered that only bodies whose atomic weight differs from the surroundings in which they are embedded, can be detected. The heart produces a shadow because it is filled with blood and surrounded by the lighter lung filled with air. Tuberculosis patches in the lungs appear darker because there is less air than in healthy parts, or even pus. Stones containing phosphate and lime will give some shadows, whereas gall stones or uric acid calculi give practically none.

17. To verify an exposure for stones, either part of a rib or part of the spine should appear on the negative, so as to show whether the exposure and development have been correct. If the transverse processes of the vertebra are clearly shown together with muscular details, most stones will also be shown. Failures are frequent in cases of stout patients and it is sometimes hopeless to verify stones.

FIG. 4,700.—Diagram for estimating the stereoscopic angle when tube is shifted  $2\frac{1}{2}$  inches. **Example:** If distance from tube be 30 ins., shift tube  $1\frac{1}{4}$  inch to either side of center and tilt it  $2\frac{1}{2}^\circ$  either way toward center line. The greater the distance between the plate and the tube, the less the necessity of tilting it.



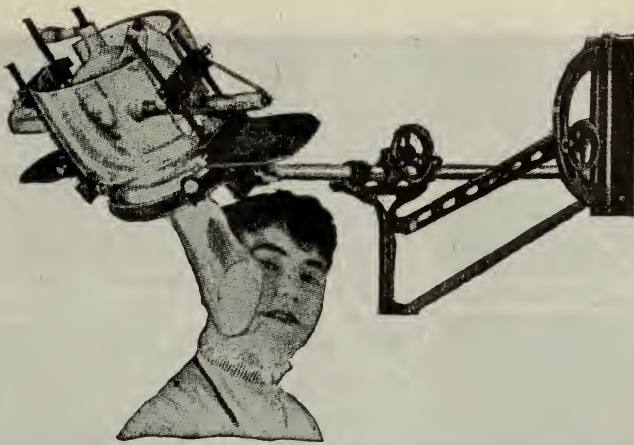
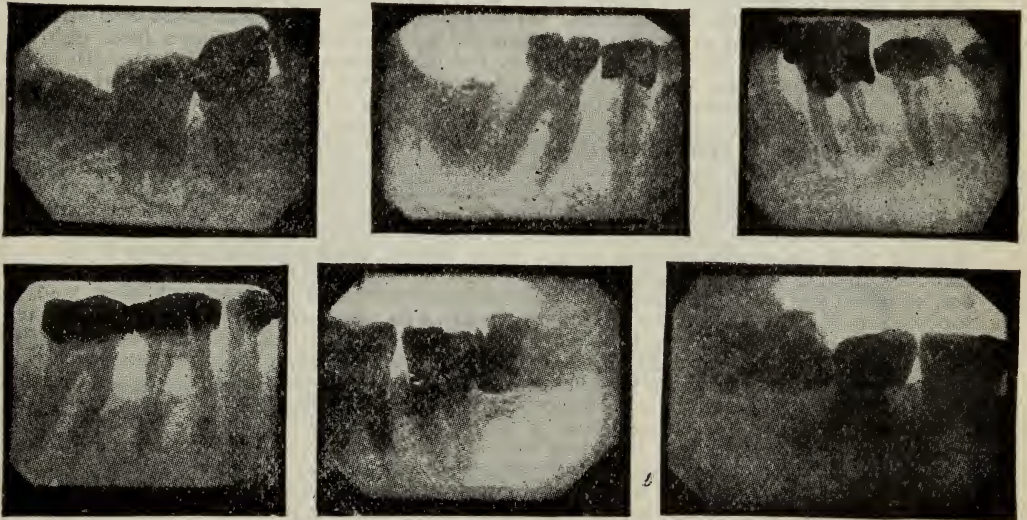


FIG. 4,701.—Scheidel-Western X ray bracket stand and patient. The illustrations show the bracket fastened to the wall by means of screws or bolts through a heavy plate to which is attached an arc that swings from side to side. To this arc is attached the arm supporting the tube and protection bowl. It will be noted in the illustration that a separate connecting rod keeps this bearing so that the tube is horizontal at any height. The tube bowl is mounted in a special saddle that may be tilted from side to side. As this can be revolved, also, every adjustment desired can be obtained, quickly. The tube is held in position securely by rubber and fibre clamps. It will be noted in the illustration that this bracket stand may be used for making Roentgenograms from either side of the head without moving the patient. The tube travel is from  $30\frac{1}{2}$  inches from the wall to a maximum of  $52\frac{1}{2}$  inches, and the up and down motion is 38 inches.



FIGS. 4,702 to 4,707.—Dental Roentgenograms. Fig 4,702, unerupted lower third molar, abscessed anterior root of 12 year molar due to pressure from third molar, and imperfect fitting crown of 12 year molar with abscessed distal root; fig. 4,703, both roots of 12 year molar remaining after attempted extraction. This was completely hidden by gum tissue, the patient suffering great pain from abscess; fig. 4,704, abscessed anterior and posterior roots of lower 6 year molar, the result of imperfect root filling, alloy filling extending into bifurcation, and region between teeth; fig. 4,705, poorly fitting crowns; fig. 4,706, impacted lower third molar; fig. 4,707, impacted lower third, and irreparable injury to second molar.

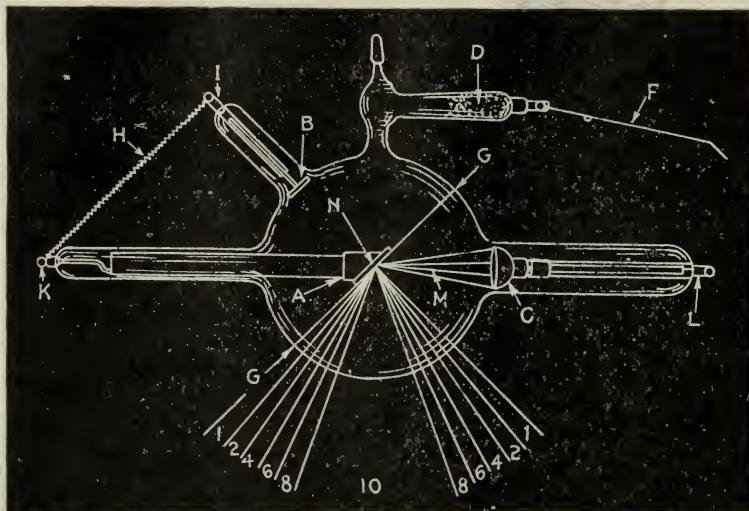


FIG. 4,708.—X ray tube. **The parts are:** A, anode; B, assistant anode; C, cathode; D, regulating chamber; F, regulating adjuster; G, hemisphere; H, connection wire; I, assistant anode cap; K, anode cap; L, cathode cap; M, cathode stream; N, focal point.

**SUGGESTIONS FOR USING X RAY TUBES:** **Connecting X ray tubes:** The positive pole of the coil is connected with the anode cap K and the negative pole to the cathode cap L. The current passes from the anode A to the cathode C and is reflected back as the invisible cathode stream M to the focal point N, producing the X ray which passes through the walls of the tube. **Strength of ray:** The most rapid and effective rays are those reflected at right angles from the cathode stream forming a focal point on the anode surface and shown graphically by the heavy cone No. 10. The strength of the rays gradually decreases, as indicated by the numbers 8-6-4, etc. **Adjustment:** Before passing the current through the tube, set the regulating adjuster F, if this be on the tube so that its end is from one and one-half to three inches from cathode cap L, according to the vacuum desired. **Visible hemisphere:** When the tube is correctly connected there should be a distinctly marked visible hemisphere of green fluorescence. **Regulation:** If sparks pass between the regulating adjuster F and the cathode cap L, it means the vacuum is high. If too high for the work to be done, allow the sparks to continue reducing the vacuum until the right degree is reached. When the vacuum is right, raise the regulating adjuster until the sparks cease to pass. Never permit the regulating adjuster F, to touch cathode cap L, as so many sparks would pass into the chemicals in the regulating chamber D, and so much gas would be driven off that the vacuum would be destroyed, or at least be too low for effective work. **To raise the vacuum in the tube:** If tube be warm it will generally be higher in vacuum than when cold. Reverse the connections, connecting the positive pole to the assistant anode cap I, and the negative pole to anode cap K. First removing the connecting wire H, and using a light current, permit it to pass for one or two minutes. The two cords connecting I, and K, to the coil should be so arranged that before reaching the connections on the tube, they will be closer together than the distance between any part of the glass surrounding anode K, and the assistant anode cap I, or there will be danger of sparks jumping from assistant anode cap I, through glass to anode. After operating tube with a light current in this manner for a short time, change the connections, connecting up in the regular way, and the tube will be found to have a higher vacuum. Repeat the operation if not high enough. Be careful in doing this not to raise the vacuum too high, for if this method is used very much, it has a tendency to make the tubes freaky. **High frequency tubes:** When using these tubes be sure that the connection wire H, is removed. In the illustration of the ordinary tube the point marked B, is called the assistant anode. In the high frequency tubes it is really the anode, and frequently the position of B, and K, are reversed. Connect one wire to the cap I, and the other wire to cap L, and be sure the tube is so adjusted that the wire connected to I, does not pass close to anode stem K, as there would be a leakage of current from the wire to anode stem which might puncture the tube.



A cylinder diaphragm compressor, is of great advantage in all abdominal cases.

18. The essential factor for radiographic results is the vacuum of the tube; select a "seasoned" tube so the vacuum and relative penetration will not change during the time of exposure. By far shorter exposures must be given where a larger amount of current passes through the X ray tube. X ray as well as outdoor photography requires correctly exposed plates. The amateur outdoor worker usually under exposes while the X ray beginner over exposes his plates.

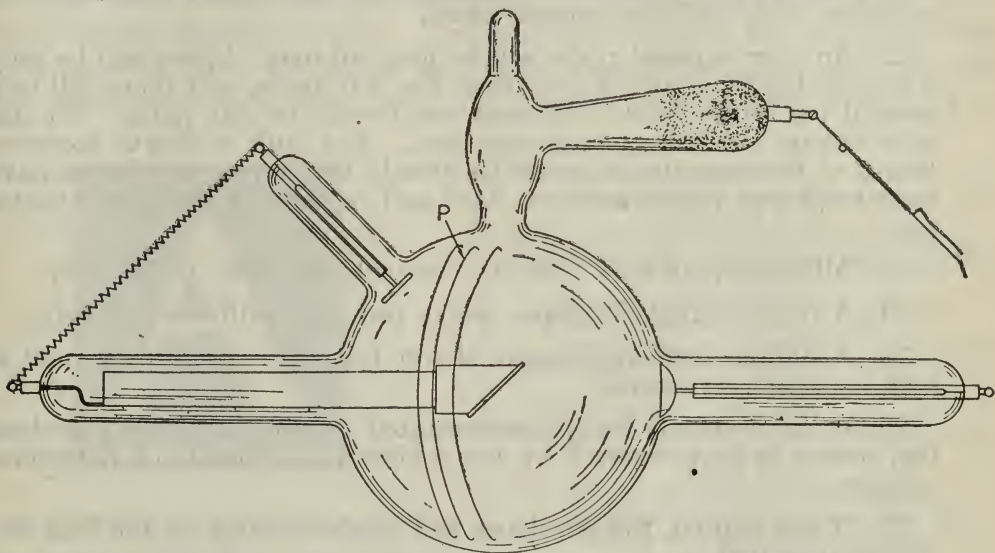
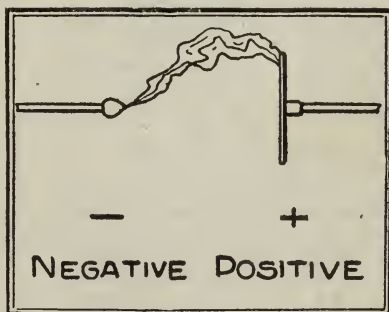
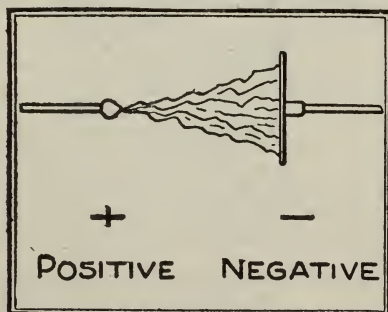


FIG. 4,709.—Suggestion for using X ray tubes: **Inverse**. At times, in addition to the hemisphere of brilliant green fluorescence there will be bands of green fluorescence on the bulb back of the anode, as shown in the illustration at P and parallel with cathode. This indicates, either that the tube is of low vacuum, or improper adjustment of the machine used for exciting it. In this case, go over the adjustment of the coil, or raise the vacuum of the tube. If only the green rings show and there is no hemisphere it indicates that the tube is incorrectly connected, and to remedy this reverse the connections.



FIGS. 4,710 and 4,711.—Suggestion for using X ray tubes: **Positive and negative poles**. This is determined by the action of the spark on the disc connected to the poles. If the sparks appear to come from the edge of the disc, the disc is positive and the point negative. If the sparks appear to come from the center of the disc, the disc is negative and the point positive. Do not use a flame or heavy spark while making this test,

19. Development is an art and considerable time should be given to this work to become proficient.

20. A correctly timed plate will show black during development in parts which have not been covered by the patient's body. Bones will appear fairly clear and the soft parts will show contrast and detail.

21. An under exposed plate will appear gray in portions not covered by the patient's body; the shadows of the bones will be white and the soft parts will show faint details. If the under exposure be excessive, they will also appear white.

22. An over exposed plate will be gray all over; bones will be only a slightly lighter shade of gray than the soft parts, and there will be a general fog with neither contrasts nor details in soft parts. To this type belong the majority of negatives. The fault is due to excessive length of the exposure, or more frequently to the fact that tubes have been employed which were too hard and required a relatively shorter time.

23. All developers work best at a temperature of 65° to 70° Fahr.

24. A concentrated developer works fast and with much density.

25. A diluted developer works slower but with finer details and is best for short exposures.

26. If the developer be too concentrated or too warm it will produce fog, unless it be restrained by the addition of bromide of potassium solution.

27. If too diluted, the developer will produce stains by the long immersion required.

28. Some developers, as for instance Eikonogen, Hydrochinone and Metol, when used fresh, require the addition of a few drops of bromide of potassium solution or some old developer to work perfectly clear. A small quantity of contrast developer may be added for the same purpose.



# INDEX

## HOW TO USE THIS INDEX

*NOTE.—This Index, containing over thirteen thousand five hundred items, covers all of Hawkins Electrical Guides. For convenience in using the Index, the Guide number is given last in heavy type, and the page number in light type. Thus the item: Alternating current arc, 2,441, #9, is found on page 2,441, Guide No. 9.*



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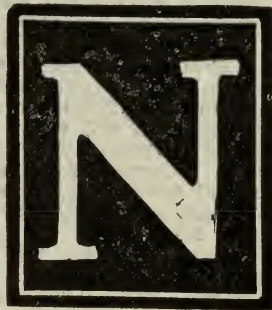
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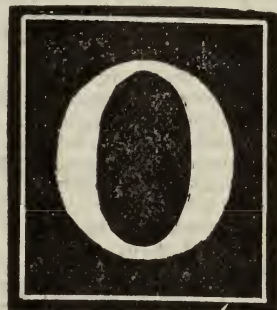


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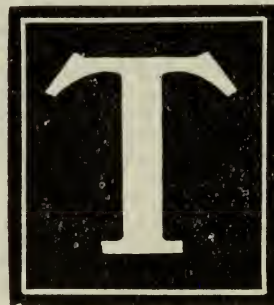
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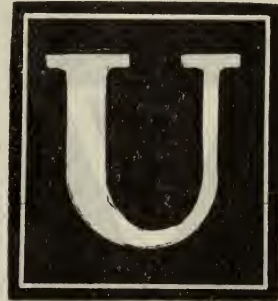


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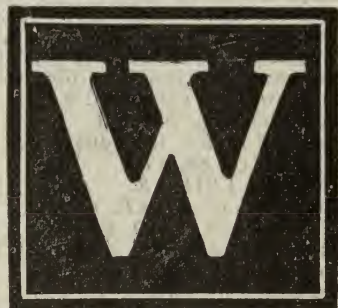
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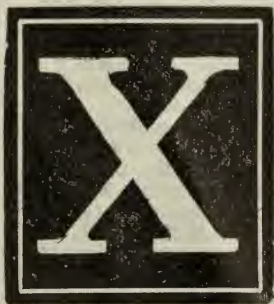
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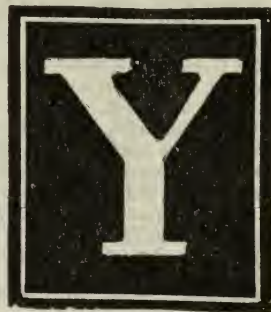
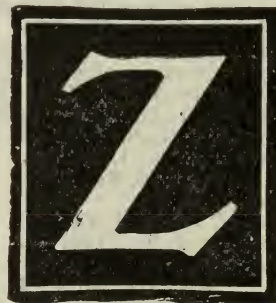
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# CAUTION.

*Quotation.—“Of nearly all accidents arising from contact with electric wires and electric machines it may be said it is more the want of care than the want of knowledge.”*

*This figure is a reminder of the necessity for constant care and watchfulness upon the part of all who have aught to do with electricity.*



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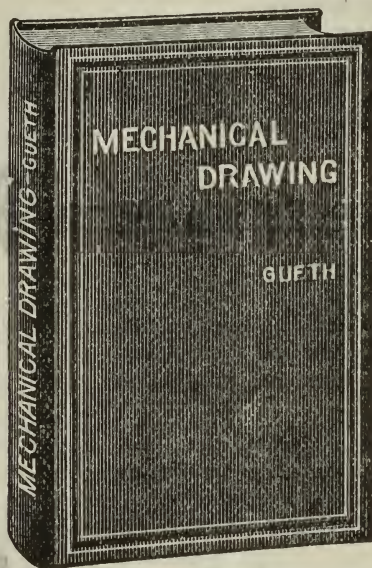
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